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STABILITY AND SENSITIVITY ANALYSIS OF NON-STATIONARY α -FRACTAL FUNCTIONS

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ABSTRACT. This article presents a comprehensive investigation of fractal interpolation functions associated with a sequence of iterated function systems (IFSs). By selecting a suitable sequence of IFS parameters, the resulting non-stationary fractal function becomes a better approximant for the non-smooth function. To achieve this, we first construct the non-stationary interpolant within the Lipschitz space and examine key topological properties of the associated non-linear fractal operator. Furthermore, we explore the stability of the interpolant under small perturbations and analyze the sensitivity to perturbations in the IFS parameters. We provide an upper bound for the errors encountered during the approximation process. Finally, we study the continuous dependence of the proposed interpolant on various IFS parameters.

1. Introduction

The representation of arbitrary functions or data sets using simple classical functions 22 like polynomials, trigonometric functions, or exponentials is a fundamental concept in 23 numerical analysis and approximation theory. While traditional approaches have been 24 successful in many cases, they often fall short in producing precise approximations for 25 irregular forms encountered in real-world signals such as time series, financial data, 26 climatic data, and bioelectric recordings. To address these irregularities, Barnsley [3] 27 introduced the concept of fractal interpolation functions (FIFs), which provide a powerful 28 framework for handling complex and irregular data. To further explore this field, interested 29 readers are encouraged to look at the books [4, 14], and the additional sources cited therein. 30 FIFs offer several advantages compared to traditional interpolation functions. They 31 are generally self-similar/affine, and their graph's Hausdorff-Besicovitch dimensions are 32 non-integers. For an analysis of the dimensional properties of stationary fractal functions, 33 readers can refer to [1, 2, 21, 25]. The primary advantage of fractal interpolants over classi-34 cal interpolants lies in their ability to generate both smooth and non-smooth interpolations, 35 depending on the chosen IFS parameters. It is worth noting that only a limited number of 36 techniques, including subdivision schemes-a popular method can produce nonsmooth 37 interpolants [9]. Recently, there have been attempts to establish a connection between 38 subdivision methods and fractal interpolation [10, 13]. 39

Motivated by the work of Barnsley, Navascués [17] explored a family of non-affine fractal functions, denoted as f^{α} or α -fractal functions. These functions correspond to a continuous function f defined on a closed and bounded interval I in \mathbb{R} . The function f^{α} approximates and interpolates f. The convergence analysis of the perturbation method was studied by Vijender, Chand, Navascués and Sebastian [27, 28]. This fractal perturbation

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2

approach gives rise to an operator that connects the theory of FIF with Operator Theory,
 Approximation Theory, Functional Analysis, and Harmonic Analysis.

Evidently, a lot of work has been done in the development of fractal approximations
(stationary) [5, 8, 6, 7, 19, 20, 23], and it is still a subject of very active research, with an
extensive list of connections and applications. But on the other hand, many questions
remain to be settled in the non-stationary case, and more specifically in the case of a
sequence of IFSs. The difficulty lies in the fact that the standard tools are not well developed
in the setting of a sequence of IFSs. Consequently, advances in non-stationary IFS are
required.
Using the fixed points of contractive operators for a specific type of IFS is a helpful

¹¹ way to build fractals [11, 22]. In the case of usual fractal functions, a common procedure ¹² of construction is to consider an operator on a complete space and define the fractal ¹³ function as the unique fixed point. However, if the operator is substituted by a sequence 14 of maps, then we face problems with similar construction. Levin, Dyn, Viswanathan ¹⁵ [13] investigate the trajectory of contraction mappings which produces limit attractors at ¹⁶ various scales with different features or shapes. It is known that various phenomena exhibit 17 complex multiscale over a wide range of scales. Analysis of the geometry of complex ¹⁸ phenomena has primarily been thought of constant fractal dimension. However, it has ¹⁹ been observed by Takayasu [24] that more general descriptions are possible in terms of a ²⁰ scale-dependent extension of the fractal framework (fractal dimension may be a function ²¹ of scale). As a consequence, the scale dependent behaviours can describe phenomena ²² whose geometry may vary with scale, like "random walk trajectories, topographic surfaces, ²³ the galaxy distribution in the universe", etc. The use of mixed contraction maps in the ²⁴ construction of the non-stationary FIFs gives the flexibility to incorporate the scale and ²⁵ location-dependent features. In [15], Massopust advanced fractal function to a new and ²⁶ more adaptive environment by utilising the concept of forward and backward trajectories ²⁷ to offer new forms of fractal functions with the variable local and global behaviours. Recently, we have studied the non-stationary α -fractal functions in different function 28 ²⁹ spaces [16].

In this article, we construct non-stationary α -fractal interpolation functions within the 30 space of all Lipschitz functions on a closed and bounded interval I in \mathbb{R} . Our aim in 31 presenting the non-stationary variant is not only to generalize the stationary situation 32 ³³ but also to expand the applicability of non-stationary fractal functions. The inherent self-34 similarity of FIFs created by IFSs with constant parameters may lead to a loss of flexibility 35 and noticeable inaccuracies when fitting and approximating complex curves and nonstationary data that exhibit less self-similarity. Non-stationary α -FIFs, on the other hand, 36 ³⁷ do not depend on local or global data points, enabling greater flexibility and accuracy. We examine the stability and sensitivity of the analytical characteristics of FIFs generated by 38 a class of IFSs with variable parameters. Furthermore, we calculate an upper bound for 39 ⁴⁰ the errors that arise when comparing our proposed interpolant with the non-stationary 41 interpolant derived from perturbed IFSs. The rest of the article is organized as follows: Section 2 reviews trajectories and 42 43 stationary/non-stationary iterated function systems (IFSs). Section 3 describes the construction of non-stationary α -fractal functions on the Lipschitz space $Lip_d(I)$, including the 44

⁴⁵ use of a sequence of IFSs for generating fractal functions. Section 4 explores a nonlinear

 $\frac{46}{47}$ fractal operator on $Lip_d(I)$ and discusses its topological properties. Section 5 investigates

1 stability analysis by perturbing the ordinates and examines the sensitivity of the IFS pa-

² rameters, providing an upper bound for approximation errors. Finally, Section 6 explores

- ³ the continuous dependence of non-stationary fractal interpolation functions on the IFS
- 4 parameters α and b.

2. Preparatory Results

5 6 7 8 In this section, we collect the necessary tools leading to the construction of non-stationary α -fractal functions in the Lipschitz space. For more details on this section, we invite the 9 reader to study the paper of Massopust [15] and the work by Barnsley [3] and Navascués 10 [17]. 11

12 **2.1.** Iterated Function System and Trajectories. Let (\mathbf{X}, d) be a complete metric space. $\frac{13}{2}$ Let $\mathscr{H}(\mathbf{X})$ denote the collection of all non-empty compact subsets of \mathbf{X} and define the 14 Hausdorff distance between sets *A* and *B* of $\mathscr{H}(\mathbf{X})$ as

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 $d_H(A,B) = \inf \{ \varepsilon \ge 0; A \subseteq B_{\varepsilon} \text{ and } B \subseteq A_{\varepsilon} \},\$

where $A_{\varepsilon} = \bigcup \{z \in \mathbf{X}; d(z, x) \leq \varepsilon \}$. The space $(\mathscr{H}(\mathbf{X}), d_H)$ is a complete metric space known 17 18 $x \in A$

as the space of fractals. 19

20 **Definition 2.1.** Let (\mathbf{X}, d) be a complete metric space and $w_i : \mathbf{X} \to \mathbf{X}$ be *N* continuous maps. 21 Then the system $\mathscr{I} = {\mathbf{X}; w_i : i = 1, 2, ..., N}$ is called an iterated function system (IFS). If 22 each map w_i in \mathscr{I} is a contraction, then the IFS \mathscr{I} is hyperbolic.

23 The attractor of the IFS is the fixed point of the set-valued Hutchinson map $\mathscr{W}:\mathscr{H}(\mathbf{X}) \rightarrow$ 24 $\mathscr{H}(\mathbf{X}),$ 25

26 27

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$$\mathscr{W}(E) = \bigcup_{i=1}^{N} w_i(E), \ E \in \mathscr{H}(\mathbf{X}).$$

28 W is a contraction map on $\mathscr{H}(\mathbf{X})$ with the Lipschitz constant $Lip(\mathscr{W}) := \max\{Lip(w_i) : i = 0\}$ 29 $1, 2, \ldots, N$. The uniqueness of the fixed point is guaranteed by the Banach fixed point 30 theorem. The limit of the iterative process $A_k = \mathcal{W}(A_{k-1}); k \in \mathbb{N}$, where $A_0 \in \mathcal{H}(\mathbf{X})$ is any 31 arbitrary set, also gives the attractor of the IFS. 32

Definition 2.2. Let $T : \mathbf{X} \to \mathbf{X}$ be a contraction map on a complete metric space (\mathbf{X}, d) . 33 The forward iterates of T are transformations $T^{\circ n}: \mathbf{X} \to \mathbf{X}$ defined by $T^{\circ 0}(x) = x$ and 34 $T^{\circ (n+1)}(x) = T(T^{\circ n}(x)) = T \circ T \circ \cdots \circ T(x) \text{ for } n \in \mathbb{N} \cup \{0\}.$ 35 36 (n+1 times)

37 **Definition 2.3.** (Forward and Backward Trajectories) Let **X** be a metric space and $\{T_r\}_{r \in \mathbb{N}}$ 38 be a sequence of Lipschitz maps on X. We define forward and backward trajectories 39 respectively 40

$$\phi_r := T_r \circ T_{r-1} \circ \ldots \circ T_1$$
 and $\psi_r := T_1 \circ T_2 \circ \ldots \circ T_r$

42 The subject now concerns the convergence of general trajectories, i.e., under what ⁴³ conditions the forward and backward trajectories will converge. In addition, we look for ⁴⁴ the trajectories producing new types of fractal sets. Recently, Levin et al. [13] observed ⁴⁵ that the backward trajectories converge under relatively mild conditions and may produce ⁴⁶ a new class of fractal sets. In [13], the authors use the assumption of compact invariant ⁴⁷ domain to guarantee the convergence of backward trajectories. In [18], Navascués and

Verma replace the compact invariant domain condition by a weaker condition. We now
 recall the result in the following.

³ **Proposition 2.4.** [18, Proposition 2.6] Let $\{T_r\}_{r\in\mathbb{N}}$ be a sequence of Lipschitz maps on a complete metric space (\mathbf{X},d) with Lipschitz constants $c_r, r \in \mathbb{N}$ respectively. If $\exists x^*$ in the space such that the sequence $\{d(x^*, T_r(x^*))\}$ is bounded, and $\sum_{r=1}^{\infty} \prod_{i=1}^{r} c_i < \infty$, then the sequence $\{\psi_r(x)\}$ converges for all $x \in \mathbf{X}$ to a unique limit \bar{x} .

<u>9</u> 2.2. *Stationary Fractal Interpolation Functions.* For a fixed $k \in \mathbb{N}$, we denote by \mathbb{N}_k the **<u>10</u>** first *k* natural numbers and $\mathbb{N}_k^0 = \mathbb{N}_k \cup \{0\}$. Let I = [a, b] and define a partition Δ on *I* by

$$\Delta = \{ (x_0, x_1, \dots, x_N) : a = x_0 < x_1 < \dots < x_N = b \}$$

For $i \in \mathbb{N}_N$, let $I_i = [x_{i-1}, x_i]$. Suppose the affine maps $l_i : I \to I_i$ are such that

$$l_{i}(x_{0}) = x_{i-1}, \ l_{i}(x_{N}) = x_{i}, \ \text{and} \ |l_{i}(z_{1}) - l_{i}(z_{2})| \le l|z_{1} - z_{2}| \ \forall z_{1}, \ z_{2} \in I,$$

¹⁶/₁₇ where 0 ≤ *l* < 1. Set $\mathcal{M} = I \times \mathbb{R}$. Let the *N* continuous maps $F_i : \mathcal{M} \to \mathbb{R}$, *i* ∈ \mathbb{N}_N be such that

(2.2)
$$F_i(x_0, y_0) = y_{i-1}, \quad F_i(x_N, y_N) = y_i,$$

¹⁹ and F_i is a contraction in the second variable for $i \in \mathbb{N}_N$. The following are the most chosen maps for the formation of IFS

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22
23
(2.3)
$$\begin{cases} l_i(x) = a_i x + e_i, \\ F_i(x, y) = \alpha_i(x) y + q_i(x), & i \in \mathbb{N}_N, \end{cases}$$

where a_i, e_i can be determined by conditions (2.1). $\alpha_i(x)$ are scaling functions satisfying $||\alpha_i||_{\infty} < 1$ and $q_i(x)$ are suitable continuous functions such that condition (2.2) is satisfied. For $i \in \mathbb{N}_N$, we define $W_i : \mathcal{M} \to I_i \times \mathbb{R}$ by

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$$W_i(x,y) = (l_i(x), F_i(x,y)) \quad \forall (x,y) \in \mathcal{M}.$$

The complete metric space (\mathcal{M}, d_H) with the above *N*-maps $\{W_i : i \in \mathbb{N}_N\}$ forms an IFS. The uniqueness of the attractor of the IFS is given by Barnsley; mentioned below.

³¹ **Theorem 2.5.** [3] *The IFS* $\mathscr{I} = {\mathscr{M}; W_i : i \in \mathbb{N}_N}$ *admits a unique attractor G, and G is the graph* ³² *of a continuous function f* : $I \to \mathbb{R}$ *which interpolates the given data.* ³³

2.3. Stationary α -fractal Functions. Let $\mathscr{C}(I)$ be the set of all continuous functions on a compact interval *I*. Let $f \in \mathscr{C}(I)$ be a prescribed function. Let us choose the function $q_i(x)$ in (2.3) as

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$$q_i(x) = f(l_i(x)) - \alpha_i(x)b(x), \ i \in \mathbb{N}_N,$$

³⁸ where $\alpha_i : I \to \mathbb{R}$ are continuous scaling functions satisfying $\|\alpha_i\|_{\infty} < 1$ and $b : I \to \mathbb{R}$ be ³⁹ continuous function such that $b \neq f$, $b(x_0) = f(x_0)$ and $b(x_N) = f(x_N)$. By Theorem 2.5, ⁴⁰ the corresponding IFS has a unique attractor *G*, which is the graph of a continuous map, ⁴¹ namely $f^{\alpha}_{\Delta,b} : I \to \mathbb{R}$ that interpolates the given data set. The map is known as the α -fractal ⁴² function. ⁴³ Though the stationary fractal interpolant approximates irregular functions very well.

Though the stationary fractal interpolant approximates irregular functions very well, it depends on local data points. To get a fractal interpolant that is independent of local

⁴⁵ data points and gets more flexibility, Massopust [15] introduced non-stationary fractal

⁴⁶ interpolation by taking a sequence of IFSs. In [18], the authors studied the parameterized

⁴⁷ non-stationary FIFs in $\mathscr{C}(I)$.

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1 2.4. *Non-stationary* α *-fractal Functions.* Let $f \in \mathscr{C}(I)$ and $r \in \mathbb{N}$. We use the following

 $\alpha_r := (\alpha_{1,r}, \alpha_{2,r}, \dots, \alpha_{N,r}), \ \alpha := \{\alpha_r\}_{r \in \mathbb{N}} \text{ and } b := \{b_r\}_{r \in \mathbb{N}}$ Let $\alpha_{i,r}$: $I \to \mathbb{R}$ be continuous functions such that $\|\alpha\|_{\infty} = \sup\{\|\alpha_r\|_{\infty} : r \in \mathbb{N}\} < 1, \text{ where } \|\alpha_r\|_{\infty} = \sup\{\|\alpha_{i,r}\|_{\infty} : i \in \mathbb{N}_N\},\$ and $b_r \in \mathscr{C}(I)$ such that $b_r \neq f$, $b_r(x_0) = f(x_0)$ and $b_r(x_N) = f(x_N)$. To define a sequence of IFSs, we use the following sequence of continuous maps $\begin{cases} l_i(x) = a_i x + e_i = \frac{x_i - x_{i-1}}{x_N - x_0} x + \frac{x_N x_{i-1} - x_0 x_i}{x_N - x_0}, \\ F_{i,r}(x, y) = \alpha_{i,r}(x) y + f(l_i(x)) - \alpha_{i,r}(x) b_r(x), \quad i \in \mathbb{N}_N. \end{cases}$ 14 15 For each $i \in \mathbb{N}_N$, we define 16 $W_{i,r}: \mathcal{M} \to I_i \times \mathbb{R}$ by $W_{i,r}(x, y) = (l_i(x), F_{i,r}(x, y)).$ 17 18 Now we have a sequence of IFSs $\mathscr{I}_r = \{\mathscr{M}; W_{i,r} : i \in \mathbb{N}_N\}$. Let 19 $\mathscr{C}_f(I) = \{g \in \mathscr{C}(I) : g(x_i) = f(x_i), i = 0, N\}.$ 20 Then $\mathscr{C}_{f}(I)$ is a complete metric space. For $r \in \mathbb{N}$, we define a sequence of Read-Bajraktarević 21 (RB) operators $T^{\alpha_r} : \mathscr{C}_f(I) \to \mathscr{C}_f(I)$ by 22 23 $(T^{\alpha_r}g)(x) = F_{ir}(l_i^{-1}(x), g(l_i^{-1}(x)))$ 24 (2.6) $= f(x) + \alpha_{i,r}(Q_i(x)) \cdot g(Q_i(x)) - \alpha_{i,r}(Q_i(x)) \cdot b_r(Q_i(x)),$ 25 26 for $x \in I_i$, $i \in \mathbb{N}_N$, where $Q_i(x) = l_i^{-1}(x)$. 27 The above operator is well defined and for any function $h \in \mathscr{C}_f(I)$, the sequence of backward 28 trajectories $\{T^{\alpha_1} \circ T^{\alpha_2} \circ \ldots \circ T^{\alpha_r}h\}$ converges to a map f^{α} of $C_f(I)$ [18]. The map f^{α} is the 29 unique map that satisfies the following equation 30 $f^{\alpha}(x) = f(x) + \lim_{r \to \infty} \sum_{i=1}^{r} \alpha_{i,1}(Q_i(x)) \dots \alpha_{i,j}(Q_i^j(x))(f - b_j)(Q_i^j(x)),$ 31 (2.7)32 33 where Q_i^j is a suitable finite composition of maps Q_i . The map f^{α} is called the non-34 stationary α -fractal interpolation function. 35 36 3. Non-stationary α -fractal function on Lipschitz Space 37 38 Let $g: I \to \mathbb{R}$ be a function. For $0 < d \le 1$, define 39 $Lip_d(g) = \sup \left\{ \frac{|g(x) - g(y)|}{|x - y|^d} : x, y \in I \text{ and } x \neq y \right\}.$ 40 41 The Lipschitz space is defined as $Lip_d(I) = \{g: I \to \mathbb{R} : Lip_d(g) < \infty\}$. Define $||g||_d =$ 42 $\max\{\|g\|_{\infty}, Lip_d(g)\}$. It is routine to show that $(Lip_d(I), \|.\|_d)$ is a Banach space. For more 43 details of the Lipschitz functions in an arbitrary Banach space, please refer to [12]. Let 44 45 $Lip_{d,f}(I) = \{g \in Lip_d(I) : g(x_0) = f(x_0), g(x_N) = f(x_N)\}.$ 46 ⁴⁷ Then $Lip_{d,f}(I)$ is a Banach space.

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Theorem 3.1. Let $f \in Lip_d(I)$. Let $r \in \mathbb{N}$, $b_r \in Lip_{d,f}(I)$ be such that $||b||_d := \sup ||b_r||_d < \infty$ and 1 2 3 4 5 6 7 8 9 10 11 12 the scaling functions $\alpha_{i,r} \in Lip_d(I)$ are chosen such that $\max_{i \in \mathbb{N}_N} \left(\frac{\|\alpha_{i,r}\|_d}{a_i^d} \right) < \frac{1}{2}$. We define a sequence of RB operators T^{α_r} : $Lip_{d,f}(I) \rightarrow Lip_{d,f}(I)$ by $(T^{\alpha_r}g)(x) = f(x) + \alpha_{i,r}(Q_i(x)) \cdot g(Q_i(x)) - \alpha_{i,r}(Q_i(x)) \cdot b_r(Q_i(x)),$ (3.1)for $x \in I_i$, $i \in \mathbb{N}_N$. Then the following hold. (1) The RB operator T^{α_r} defined in equation (3.1) is well defined on $Lip_{d,f}(I)$. (2) In fact, T^{α_r} : $Lip_{d,f}(I) \rightarrow Lip_{d,f}(I) \subset Lip_d(I)$ is a contraction map. (3) There exists a unique function $f_{b,Lip_d}^{\alpha} \in Lip_{d,f}(I)$ such that the sequence $\{T^{\alpha_1} \circ T^{\alpha_2} \circ \ldots \circ T^{\alpha_r}g\}$ converges to the map f_{b,Lip_d}^{α} for every $g \in Lip_{d,f}(I)$. 13 14 15 16 17 18 Proof. (1) The norm defined on $Lip_{d,f}(I)$ is $||f||_d = \max\{||f||_{\infty}, Lip_d(f)\}$ so that, $||T^{\alpha_r}f||_d =$ $\max\{\|T^{\alpha_r}f\|_{\infty}, Lip_d(T^{\alpha_r}f)\}$. From the definition of RB operators, we have $(T^{\alpha_r}g)(x) = f(x) + \alpha_{i,r}(Q_i(x)) \cdot (g - b_r)(Q_i(x)).$ Now, 19 20 $Lip_d(T^{\alpha_r}g) = \max_{i \in \mathbb{N}_N} \sup_{x, y \in I_i} \frac{|T^{\alpha_r}g(x) - T^{\alpha_r}g(y)|}{|x - y|^d}$ 21 $= \max_{i \in \mathbb{N}_N} \sup_{x,y \in I_i} \frac{|f(x) - f(y) + \alpha_{i,r}(Q_i(x)).(g - b_r)(Q_i(x)) - \alpha_{i,r}(Q_i(y)).(g - b_r)(Q_i(y))|}{|x - y|^d}$ 22 23 24 $\leq \max_{i \in \mathbb{N}_N} \sup_{x,y \in I_i} \left[\frac{|f(x) - f(y)|}{|x - y|^d} + \frac{|\alpha_{i,r}(Q_i(x)).[(g - b_r)(Q_i(x)) - (g - b_r)(Q_i(y))]|}{|x - y|^d} \right]$ 25 26 27 $+\frac{|(g-b_r)(Q_i(y))[\alpha_{i,r}(Q_i(x))-\alpha_{i,r}(Q_i(y))]|}{|x-y|^d}\Bigg]$ 28 29 $\leq Lip_{d}(f) + \max_{i \in \mathbb{N}_{N}} \|\alpha_{i,r}\|_{\infty} \sup_{\substack{x,y \in I_{i} \\ x \neq y}} \frac{|(g(Q_{i}(x)) - g(Q_{i}(y)))| + |(b_{r}(Q_{i}(x)) - b_{r}(Q_{i}(y)))|}{|x - y|^{d}}$ 30 31 32 33 $+ \|g - b_r\|_{\infty} \max_{\substack{i \in \mathbb{N}_N}} \sup_{\substack{x, y \in I_i \\ x \neq y}} \frac{|(\alpha_{i,r}(Q_i(x)) - \alpha_{i,r}(Q_i(y)))|}{|x - y|^d}$ 34 35 $= Lip_d(f) + \max_{i \in \mathbb{N}_N} \|\alpha_{i,r}\|_{\infty} \sup_{\substack{x, y \in I_i \\ x \neq y}} \frac{|(g(Q_i(x)) - g(Q_i(y)))| + |(b_r(Q_i(x)) - b_r(Q_i(y)))|}{a_i^d |Q_i(x) - Q_i(y)|^d}$ 36 37 38 39 + $||g - b_r||_{\infty} \max_{\substack{i \in \mathbb{N}_N}} \sup_{\substack{x,y \in I_i \\ x \neq y}} \frac{|(\alpha_{i,r}(Q_i(x)) - \alpha_{i,r}(Q_i(y)))|}{a_i^d |Q_i(x) - Q_i(y)|^d}$ 40 41 $=Lip_d(f) + \max_{i \in \mathbb{N}_N} \left(\frac{\|\boldsymbol{\alpha}_{i,r}\|_{\infty}}{a_i^d}\right) \sup_{\substack{\tilde{x}, \tilde{y} \in I\\ \tilde{x} \neq \tilde{y}}} \frac{|g(\tilde{x}) - g(\tilde{y})| + |b_r(\tilde{x}) - b_r(\tilde{y}))|}{|\tilde{x} - \tilde{y}|^d}$ 42 43 44 $+ \|g - b_r\|_{\infty} \max_{i \in \mathbb{N}_N} \sup_{\substack{\tilde{x}, \tilde{y} \in I \\ \tilde{x} \neq i}} \frac{|(\alpha_{i,r}(\tilde{x}) - \alpha_{i,r}(\tilde{y}))|}{a_i^d |\tilde{x} - \tilde{y}|^d}$ 45 46 47

As $f, g, b_r \in Lip_{d,f}(I)$, the above estimation ensures that $Lip_d(T^{\alpha_r}g) < \infty$ and so that $T^{\alpha_r}g \in Lip_d(I)$. Also $T^{\alpha_r}g(x_0) = f(x_0)$ and $T^{\alpha_r}g(x_N) = f(x_N)$. Hence $T^{\alpha_r}g \in Lip_{d,f}(I)$ and the RB operator T^{α_r} defined in equation (2.6) is well defined on $Lip_{d,f}(I)$.

 $|(T^{\alpha_r}g_1 - T^{\alpha_r}g_2)(x)| = |\alpha_{i,r}(Q_i(x))||(g_1 - g_2)(Q_i(x))|$

 $\leq Lip_d(f) + \max_{i \in \mathbb{N}_N} \left(\frac{\|\boldsymbol{\alpha}_{i,r}\|_d}{a^d_i} \right) (Lip_d(g) + Lip_d(b_r) + \|g\|_{\infty} + \|b_r\|_{\infty}).$

 $\leq Lip_d(f) + \max_{i \in \mathbb{N}_N} \left(\frac{\|\boldsymbol{\alpha}_{i,r}\|_{\infty}}{a_i^d} \right) \left(Lip_d(g) + Lip_d(b_r) \right) + \max_{i \in \mathbb{N}_N} \left(\frac{Lip_d(\boldsymbol{\alpha}_{i,r})}{a_i^d} \right) \left(\|g\|_{\infty} + \|b_r\|_{\infty} \right)$

36

(2) For $x \in I_i$,

 $\leq \max_{i\in\mathbb{N}_N}(\|\alpha_{i,r}\|_{\infty})\|g_1-g_2\|_{\infty},$ and hence $\|(T^{\alpha_r}g_1 - T^{\alpha_r}g_2)\|_{\infty} \le \max_{i \in \mathbb{N}_N} (\|\alpha_{i,r}\|_{\infty}) \|g_1 - g_2\|_{\infty}.$ - (3.2) Using similar steps in the estimation of $Lip_d(T^{\alpha_r}g)$, we obtain $Lip_d(T^{\alpha_r}g_1 - T^{\alpha_r}g_2) \le \max_{i\in\mathbb{N}_N} \left(\frac{\|\alpha_{i,r}\|_d}{a^d_i}\right) (Lip_d(g_1 - g_2) + \|g_1 - g_2\|_{\infty}).$ (3.3)Combining (3.2) and (3.3), we get $||(T^{\alpha_r}g_1 - T^{\alpha_r}g_2)||_d$ $= \max \{ \| (T^{\alpha_r} g_1 - T^{\alpha_r} g_2) \|_{\infty}, Lip_d (T^{\alpha_r} g_1 - T^{\alpha_r} g_2) \}$ $\leq \max\left\{\max_{i\in\mathbb{N}_{N}}(\|\alpha_{i,r}\|_{\infty})\|g_{1}-g_{2}\|_{\infty},\max_{i\in\mathbb{N}_{N}}\left(\frac{\|\alpha_{i,r}\|_{d}}{a_{:}^{d}}\right)(Lip_{d}(g_{1}-g_{2})+\|g_{1}-g_{2}\|_{\infty})\right\}$ $\leq \max_{i \in \mathbb{N}_{N}} \left(\frac{\|\boldsymbol{\alpha}_{i,r}\|_{d}}{a^{d}} \right) \max \left\{ \|g_{1} - g_{2}\|_{d}, 2\|g_{1} - g_{2}\|_{d} \right\}$ $= 2 \max_{i \in \mathbb{N}_N} \left(\frac{\|\alpha_{i,r}\|_d}{a_i^d} \right) \|g_1 - g_2\|_d.$

By assumptions on the sequence of scaling functions, we can ensure that T^{α_r} is a contraction.

(3) Let $g \in Lip_d(I)$ be an arbitrary function. We have to check if the sequence $\{ \| T^{\alpha_r}g$ $g||_d$ is bounded. Now, by a similar calculation as in item (1), we get

$$\begin{split} Lip_{d}(T^{\alpha_{r}}g-g) &\leq Lip_{d}(T^{\alpha_{r}}g) + Lip_{d}(g) \\ &\leq Lip_{d}(f) + \max_{i \in \mathbb{N}_{N}} \left(\frac{\|\alpha_{i,r}\|_{d}}{a_{i}^{d}}\right) (Lip_{d}(g) + Lip_{d}(b_{r}) + \|g\|_{\infty} + \|b_{r}\|_{\infty}) + Lip_{d}(g) \\ &\leq Lip_{d}(f) + \left(1 + \max_{i \in \mathbb{N}_{N}} \left(\frac{\|\alpha_{i}\|_{d}}{a_{i}^{d}}\right)\right) Lip_{d}(g) + 2\max_{i \in \mathbb{N}_{N}} \left(\frac{\|\alpha_{i}\|_{d}}{a_{i}^{d}}\right) \|b_{r}\|_{d} \\ &\leq Lip_{d}(f) + \left(1 + \max_{i \in \mathbb{N}_{N}} \left(\frac{\|\alpha_{i}\|_{d}}{a_{i}^{d}}\right)\right) Lip_{d}(g) + 2\max_{i \in \mathbb{N}_{N}} \left(\frac{\|\alpha_{i}\|_{d}}{a_{i}^{d}}\right) \|b\|_{d}, \\ &\text{where } \|\alpha_{i}\|_{d} := \sup_{\mathbb{N}} \|\alpha_{i,r}\|_{d}. \text{ Also,} \end{split}$$

37 38 39 40 41 42 43 44 45 46 $|(T^{\alpha_r}g - g)(x)| = |(f - g)(x)| + |\alpha_{i,r}(Q_i(x))| \cdot |(g - b_r)(Q_i(x))|$ $\leq \|f-g\|_{\infty}+\|\alpha\|_{\infty}\|g-b_r\|_{\infty}$ 47

11 Mar 2024 05:29:00 PDT

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STABILITY AND SENSITIVITY ANALYSIS OF NON-STATIONARY α -FRACTAL FUNCTIONS

$$\frac{1}{\frac{2}{3}} \leq \|f - g\|_{\infty} + \|\alpha\|_{\infty}(\|g\|_{\infty} + \|b_r\|_{\infty}) \\ \leq \|f - g\|_d + \|\alpha\|_{\infty}(\|g\|_d + \|b_r\|_d).$$

Hence,

$$||T^{\alpha_r}g - g||_{\infty} \le ||f - g||_d + ||\alpha||_{\infty} (||g||_d + ||b||_d).$$

Combining (i) and (ii), we get that the bound of $||T^{\alpha_r}g - g||_d$ is independent of r. Using Proposition 2.4, \exists a unique $f^{\alpha}_{b,Lip_d} \in Lip_{d,f}(I)$ such that $f^{\alpha}_{b,Lip_d} = \lim_{r \to \infty} T^{\alpha_1} \circ T^{\alpha_2} \circ \ldots \circ T^{\alpha_r}g$ for any $g \in Lip_{d,f}(I)$. This completes the proof of the theorem.

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(ii)

Definition 3.2. The function f_{b,Lip_d}^{α} is called a Lipschitz non-stationary α -fractal function with respect to f, α, b and the partition Δ .

 $\frac{13}{14}$ Remark 3.3. As each T^{α_r} is a contraction, there exists a unique stationary α -fractal function $f_r^{\alpha_r}(f_r^{\alpha}) = f_r^{\alpha}$ and it satisfies the functional equation:

$$f_r^{\alpha}(x) = F_{i,r} \left(Q_i(x), f_r^{\alpha}(Q_i(x)) \right) \quad \forall \ x \in I_i,$$

 $\frac{17}{18}$ where $Q_i(x) := l_i^{-1}(x)$. That is,

$$f_{r}^{\alpha}(x) = f(x) + \alpha_{i,r}(Q_{i}(x)) \cdot f_{r}^{\alpha}(Q_{i}(x)) - \alpha_{i,r}(Q_{i}(x))b_{r}(Q_{i}(x)).$$

4. A Nonlinear Fractal Operator on $Lip_d(I)$

²² Suppose $L_r : Lip_d(I) \to Lip_d(I)$ is a sequence of operators such that $||L||_{\infty} := \sup_{r \in \mathbb{N}} ||L_r||_{\infty} < \infty$ ²³ and satisfy $(L_r(f))(x_0) = f(x_0)$ and $(L_r(f))(x_N) = f(x_N)$. We set $b_r = L_r f$. The corresponding ²⁴ non-stationary α -fractal function will be denoted by f_b^{α} .

Definition 4.1. Let $f \in Lip_d(I)$ and Δ be fixed. We define the α -fractal operator $\mathfrak{F}_b^{\alpha} \equiv \mathfrak{F}_{\Delta,b}^{\alpha}$ as

$$\mathfrak{F}_{h}^{\alpha}: Lip_{d}(I) \subset \mathscr{C}(I) \to \mathscr{C}(I), \ \mathfrak{F}_{h}^{\alpha}(f) = f_{h}^{\alpha}.$$

Remark 4.2. In the case of a stationary fractal function, a similar construction is well studied in literature [17]. If we take $\alpha_{i,r} = \alpha_i \forall r \in \mathbb{N}, i \in \mathbb{N}_N$ and $b_r = Lf \forall r \in \mathbb{N}$, where $L : Lip_d(I) \rightarrow Lip_d(I)$ is an operator such that $(L(f))(x_0) = f(x_0)$ and $(L(f))(x_N) = f(x_N)$. Then the non-stationary α -fractal function will coincide with the stationary one.

Our next concern is to study the error approximation in the non-stationary perturbation process. The error bound in the different fractal approximations is well-studied in the stationary case [17].

Proposition 4.3. Let f_b^{α} be the non-stationary FIF corresponding to the seed function $f \in Lip_d(I)$. Then we have the following error bound

$$\|f_b^{a} - f\|_{\infty} \le \frac{\|\alpha\|_{\infty}}{1 - \|\alpha\|_{\infty}} \sup_{r \in \mathbb{N}} \{\|f - L_r(f)\|_{\infty}\}$$

 $\frac{42}{43}$ *Proof.* The proof is similar to that given in Theorem 4.1. of [18].

Corollary 4.4. Let $f \in Lip_d(I)$ be the germ function and f_b^{α} be the corresponding nonstationary FIF. Then for any $j \in \mathbb{N}$, we have the following inequality

$$\|f_b^{\alpha} - L_j(f)\|_{\infty} \le \frac{1}{1 - \|\alpha\|_{\infty}} \sup_{r \in \mathbb{N}} \{\|f - L_r(f)\|_{\infty}\}.$$

11 Mar 2024 05:29:00 PDT

240101-JhaSangita Version 2 - Submitted to Rocky Mountain J. Math.

8

1 Proof. Let $j \in \mathbb{N}$. Using inequality (4.1), we get $\|f_b^{\alpha} - L_j(f)\|_{\infty} = \|f_b^{\alpha} - f + f - L_j(f)\|_{\infty} = \|f_b^{\alpha} - f + f - L_j(f)\|_{\infty} = \|f_b^{\alpha} - f\|_{\infty} + \|f_j^{\alpha}\|_{\infty} \leq \|g_b^{\alpha} - f\|_{\infty} + \|f_j^{\alpha}\|_{\infty} \leq \frac{\|\alpha\|_{\infty}}{1 - \|\alpha\|_{\infty}} \sup_{r \in \mathbb{N}} \{\|g_b^{\alpha}\|_{\infty} \leq \frac{1}{1 - \|g_b^{\alpha}\|_{\infty}}$ $||f_{b}^{\alpha} - L_{i}(f)||_{\infty} = ||f_{b}^{\alpha} - f + f - L_{i}(f)||_{\infty}$ $\leq \|f_h^{\alpha} - f\|_{\infty} + \|f - L_i(f)\|_{\infty}$ $\leq \frac{\|\boldsymbol{\alpha}\|_{\infty}}{1-\|\boldsymbol{\alpha}\|_{\infty}} \sup_{r \in \mathbb{N}} \{\|f - L_r(f)\|_{\infty}\} + \|f - L_j(f)\|_{\infty}$ $\leq \frac{1}{1 - \|\boldsymbol{\alpha}\|_{\infty}} \sup_{r \in \mathbb{N}} \{ \|f - L_r(f)\|_{\infty} \}.$ Based on the same arguments used in [18], we know if L_r is linear, then \mathfrak{F}_b^{α} is a linear operator. In order to keep track of this, let us write it down in the next proposition: 13

Proposition 4.5. The fractal operator $\mathfrak{F}_{b}^{\alpha}$ is a linear operator, provided that the sequence of 14 operators $L_r: Lip_d(I) \to Lip_d(I)$ are linear for each $r \in \mathbb{N}$.

16 Unless otherwise specified, note that we do not assume that L_r is linear. As a result, 17 the fractal operator is typically nonlinear (not necessarily linear). With regard to the 18 conventional setting of fractal operators spread throughout the literature, the present 19 findings abandon the general assumption of linearity and boundedness of the map L_r . 20 Consequently, the research presented here may uncover possible applications of the fractal 21 operator within the theory of unbounded and nonlinear operators. 22

Let us now collect some standard definitions of operators of interest in nonlinear func-23 tional analysis and perturbation theory. Let $(A, \|.\|_A)$ and $(B, \|.\|_B)$ be two normed linear 24 spaces. 25

26 **Definition 4.6.** If an operator $\mathcal{T} : A \to B$ maps bounded sets to bounded sets, then it is 27 said to be topologically bounded.

28 **Definition 4.7.** Let $\mathscr{T}_1 : D(\mathscr{T}_1) \subset A \to B$ and $\mathscr{T}_2 : D(\mathscr{T}_2) \subset A \to B$ be two operators such that 29 $D(\mathscr{T}_2) \subset D(\mathscr{T}_1)$. If $\mathscr{T}_1, \mathscr{T}_2$ satisfy the following inequality 30

 $\|\mathscr{T}_1(u)\|_B \leq t_1 \|u\|_A + t_2 \|\mathscr{T}_2(u)\|_B \ \forall u \in D(\mathscr{T}_2),$

32 where t_1 and t_2 are some non-negative constants, then \mathcal{T}_1 is said to be relatively (norm) 33 bounded with respect to \mathscr{T}_2 or simply \mathscr{T}_2 -bounded. The \mathscr{T}_2 -bound of \mathscr{T}_1 is defined as the 34 infimum of all possible values of t_2 satisfying the aforementioned inequality. 35

36 **Definition 4.8.** An operator $\mathscr{T} : A \to B$ is said to be Lipschitz if there exists a constant q > 037 such that 38

$$\|\mathscr{T}(u) - \mathscr{T}(v)\|_B \le q \|u - v\|_A \ \forall \ u, v \in A$$

39 For a Lipschitz operator $\mathscr{T}: A \to B$, the Lipschitz constant of \mathscr{T} is denoted by $|\mathscr{T}|$. 40

41 **Definition 4.9.** Let $\mathscr{T}_1 : D(\mathscr{T}_1) \subset A \to B$ and $\mathscr{T}_2 : D(\mathscr{T}_2) \subset A \to B$ be two operators such that $D(\mathscr{T}_2) \subset D(\mathscr{T}_1)$. If $\mathscr{T}_1, \mathscr{T}_2$ satisfies the following inequality 42

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$$\|\mathscr{T}_1(u) - \mathscr{T}_1(v)\|_B \le M_1 \|u - v\|_A + M_2 \|\mathscr{T}_2(u) - \mathscr{T}_2(v)\|_B \,\forall u, v \in D(\mathscr{T}_1),$$

⁴⁵ where M_1 and M_2 are non-negative constants, then we say that \mathcal{T}_1 is relatively Lipschitz $\overline{46}$ with respect to \mathscr{T}_2 or simply \mathscr{T}_2 -Lipschitz. The infimum of all such values of M_2 is called ⁴⁷ the \mathscr{T}_2 -Lipschitz constant of \mathscr{T}_1 .

Proposition 4.10. The non-stationary fractal operator $\mathfrak{F}_{b}^{\alpha}$: $Lip_{d}(I) \to \mathscr{C}(I)$ is continuous

Proof. Let $(f_n)_{n \in \mathbb{N}}$ be a convergent sequence in $Lip_d(I)$, converges to $f \in Lip_d(I)$. We have,

$$f_b^{\alpha}(x) = f(x) + \lim_{r \to \infty} \sum_{j=1}^r \alpha_{i,1}(Q_i(x)) \dots \alpha_{i,j}(Q_i^j(x))(f - L_j f)(Q_i^j(x)).$$

Proposition 4.10. The non-stationary fractal operator
$$\mathfrak{F}_{b}^{\alpha} : Lip_{d}(I) \to \mathscr{C}(I)$$
 is continuous for each $r \in \mathbb{N}$.
whenever $L_{r} : Lip_{d}(I) \to Lip_{d}(I)$ is continuous for each $r \in \mathbb{N}$.
Proof. Let $(f_{n})_{n \in \mathbb{N}}$ be a convergent sequence in $Lip_{d}(I)$, converges to $f \in Lip_{d}(I)$. We $f_{b}^{\alpha}(x) = f(x) + \lim_{r \to \infty} \sum_{j=1}^{r} \alpha_{i,1}(Q_{i}(x)) \dots \alpha_{i,j}(Q_{i}^{j}(x))(f - L_{j}f)(Q_{i}^{j}(x))$.
Now,
 $|(f_{n})_{b}^{\alpha}(x) - f_{b}^{\alpha}(x)|$
 $\leq |f_{n}(x) - f(x)| + |\lim_{r \to \infty} \sum_{j=1}^{r} \alpha_{i,1}(Q_{i}(x)) \dots \alpha_{i,j}(Q_{i}^{j}(x))(f_{n} - f - L_{j}f_{n} + L_{j}f)(Q_{i}^{j}(x))|$
 $\leq |f_{n} - f||_{\infty} + \lim_{r \to \infty} \sum_{j=1}^{r} ||\alpha||_{\infty}^{j}(||f_{n} - f||_{\infty} + ||L_{j}f_{n} - L_{j}f||_{\infty})$
 $\leq ||f_{n} - f||_{d} + \lim_{r \to \infty} \sum_{j=1}^{r} ||\alpha||_{\infty}^{j}(||f_{n} - f||_{d} + ||L_{j}f_{n} - L_{j}f||_{d}).$

19 Since the inequality holds for all $x \in I$, we have

$$\|(f_n)_b^{\alpha} - f_b^{\alpha}\|_{\infty} \leq \|f_n - f\|_d + \lim_{r \to \infty} \sum_{j=1}^r \|\alpha\|_{\infty}^j (\|f_n - f\|_d + \|L_j f_n - L_j f\|_d).$$

As the sequence (f_n) converges to f, we get our desired result using continuity of $L_i, j \in$ $\mathbb{N}.$

Proposition 4.11. If for each $r \in \mathbb{N}$, the operator $L_r : Lip_d(I) \to Lip_d(I)$ is a Lipschitz operator with Lipschitz constant $|L_r|$, then the non-stationary fractal operator $\mathfrak{F}_b^{\alpha} : Lip_d(I) \to \mathscr{C}(I)$ is also a Lipschitz operator, and $|\mathfrak{F}_b^{\alpha}| \leq \frac{1+|L|\|\alpha\|_{\infty}}{1-\|\alpha\|_{\infty}}$, where $|L| := \sup_{r \in \mathbb{N}} |L_r| < \infty$.

Proof. Let $f, g \in Lip_d(I)$. Then

$$f_b^{\alpha}(x) = f(x) + \lim_{r \to \infty} \sum_{j=1}^r \alpha_{i,1}(Q_i(x)) \dots \alpha_{i,j}(Q_i^j(x))(f - L_j f)(Q_i^j(x)),$$
$$g_b^{\alpha}(x) = g(x) + \lim_{r \to \infty} \sum_{j=1}^r \alpha_{i,1}(Q_i(x)) \dots \alpha_{i,j}(Q_i^j(x))(g - L_j g)(Q_i^j(x)).$$

Therefore,

$$\begin{aligned} \frac{38}{39} & |f_b^{\alpha}(x) - g_b^{\alpha}(x)| = |f(x) + \lim_{r \to \infty} \sum_{j=1}^r \alpha_{i,1}(Q_i(x)) \dots \alpha_{i,j}(Q_i^j(x))(f - L_j f)(Q_i^j(x))) \\ & -g(x) - \lim_{r \to \infty} \sum_{j=1}^r \alpha_{i,1}(Q_i(x)) \dots \alpha_{i,j}(Q_i^j(x))(g - L_j g)(Q_i^j(x)))| \\ & \leq |f(x) - g(x)| + |\lim_{r \to \infty} \sum_{j=1}^r \alpha_{i,1}(Q_i(x)) \dots \alpha_{i,j}(Q_i^j(x))(f - g - L_j f + L_j g)(Q_i^j(x))| \\ & \leq ||f - g||_{\infty} + \lim_{r \to \infty} \sum_{j=1}^r ||\alpha||_{\infty}^j (||f - g||_{\infty} + ||L_j f - L_j g||_{\infty}) \end{aligned}$$

$$\leq \|f - g\|_{\infty} + \lim_{r \to \infty} \sum_{j=1}^{r} \|\alpha\|_{\infty}^{j} (\|f - g\|_{\infty} + |L_{j}| \cdot \|f - g\|_{\infty})$$
$$\leq \left(1 + \sum_{j=1}^{\infty} \|\alpha\|_{\infty}^{j} (1 + |L|)\right) \cdot \|f - g\|_{\infty}$$

$$= \left(1 + \frac{\|\boldsymbol{\alpha}\|_{\infty}}{1 - \|\boldsymbol{\alpha}\|_{\infty}}(1 + |L|)\right) \cdot \|f - g\|_{\infty}$$
$$\leq \frac{1 + |L| \cdot \|\boldsymbol{\alpha}\|_{\infty}}{1 - \|\boldsymbol{\alpha}\|_{\infty}} \cdot \|f - g\|_{d}.$$

 $\frac{3}{4} \\
 \frac{5}{6} \\
 \frac{7}{8} \\
 \frac{9}{10} \\
 11$ This holds for every $x \in I$, hence

$$\|\mathfrak{F}^{\boldsymbol{\alpha}}_{b}(f) - \mathfrak{F}^{\boldsymbol{\alpha}}_{b}(g)\|_{\infty} = \|f^{\boldsymbol{\alpha}}_{b} - g^{\boldsymbol{\alpha}}_{b}\|_{\infty} \leq \frac{1 + |L| \cdot \|\boldsymbol{\alpha}\|_{\infty}}{1 - \|\boldsymbol{\alpha}\|_{\infty}} \|f - g\|_{d}.$$

15 This concludes the proof.

Proposition 4.12. The non-stationary fractal operator \mathfrak{F}_b^{α} : $Lip_d(I) \to \mathscr{C}(I)$ is topologically bounded provided that $L_r: Lip_d(I) \to Lip_d(I)$ is uniformly bounded.

19 *Proof.* Let *f* be a function in $Lip_d(I)$. We have,

$$\begin{split} |f_{b}^{\alpha}(x)| &\leq |f(x)| + |\lim_{r \to \infty} \sum_{j=1}^{r} \alpha_{i,1}(Q_{i}(x)) \dots \alpha_{i,j}(Q_{i}^{j}(x))(f - L_{j}f)(Q_{i}^{j}(x)) \\ &\leq \|f\|_{\infty} + \lim_{r \to \infty} \sum_{j=1}^{r} \|\alpha\|_{\infty}^{j} \|f - L_{j}f\|_{\infty} \\ &\leq \|f\|_{\infty} + \lim_{r \to \infty} \sum_{j=1}^{r} \|\alpha\|_{\infty}^{j} (\|f\|_{\infty} + \|L_{j}f\|_{\infty}) \\ &\leq (1 + \sum_{j=1}^{\infty} \|\alpha\|_{\infty}^{j}) \|f\|_{\infty} + \sum_{j=1}^{\infty} \|\alpha\|_{\infty}^{j} \|L_{j}f\|_{\infty} \\ &= \frac{1}{1 - \|\alpha\|_{\infty}} \|f\|_{\infty} + \sum_{j=1}^{\infty} \|\alpha\|_{\infty}^{j} \|L_{j}f\|_{\infty} \\ &\leq \frac{1}{1 - \|\alpha\|_{\infty}} \|f\|_{d} + \sum_{j=1}^{\infty} \|\alpha\|_{\infty}^{j} \|L_{j}f\|_{\infty}. \end{split}$$

Hence

$$\|\mathfrak{F}_{b}^{\alpha}(f)\|_{\infty} = \|f_{b}^{\alpha}\|_{\infty} \leq \frac{1}{1-\|\alpha\|_{\infty}}\|f\|_{d} + \sum_{j=1}^{\infty} \|\alpha\|_{\infty}^{j}\|L_{j}f\|_{\infty}.$$

Since $L_j (j \in \mathbb{N})$ is uniformly bounded, it follows from the above inequality that the operator $\mathfrak{F}_{h}^{\alpha}$ is topologically bounded.

In the following propositions of this section, we assume that L_r be a sequence of linear operators such that there exists a linear operator *L* satisfying $||Lf||_{\infty} = \sup ||L_rf||_{\infty}$. Let us $r \in \mathbb{N}$ move on to the following proposition using this presumption.

Proposition 4.13. The non-stationary fractal operator \mathfrak{F}_b^{α} : $Lip_d(I) \to \mathscr{C}(I)$ is relatively Lipschitz with respect to *L* with *L*-Lispchitz constant of \mathfrak{F}_b^{α} not exceeding $\frac{\|\alpha\|_{\infty}}{1-\|\alpha\|_{\infty}}$

11 Mar 2024 05:29:00 PDT

240101-JhaSangita Version 2 - Submitted to Rocky Mountain J. Math.

12 STABILITY AND SENSITIVITY ANALYSIS OF NON-STATIONARY α -fractal functions

Proof. Let $f, g \in Lip_d(I)$. Then the functions satisfy the following equations: $f_b^{\alpha}(x) = f(x) + \lim_{r \to \infty} \sum_{i=1}^{r} \alpha_{i,1}(Q_i(x)) \dots \alpha_{i,j}(Q_i^j(x))(f - L_j f)(Q_i^j(x)),$ and $g_b^{\alpha}(x) = g(x) + \lim_{r \to \infty} \sum_{i=1}^{r} \alpha_{i,1}(Q_i(x)) \dots \alpha_{i,j}(Q_i^j(x))(g - L_j g)(Q_i^j(x)).$ Now, $|f_{h}^{\alpha}(x)-g_{h}^{\alpha}(x)|$ $= |f(x) + \lim_{r \to \infty} \sum_{i=1}^{r} \alpha_{i,1}(Q_i(x)) \dots \alpha_{i,j}(Q_i^j(x))(f - L_j f)(Q_i^j(x)))$ $-g(x) - \lim_{r \to \infty} \sum_{i=1}^{r} \alpha_{i,1}(Q_i(x)) \dots \alpha_{i,j}(Q_i^j(x))(g - L_j g)(Q_i^j(x))|$ $\leq |f(x) - g(x)| + |\lim_{r \to \infty} \sum_{i=1}^{r} \alpha_{i,1}(Q_i(x)) \dots \alpha_{i,j}(Q_i^j(x))(f - g - L_j f + L_j g)(Q_i^j(x))|$ $\leq \|f-g\|_{\infty} + \lim_{r \to \infty} \sum_{i=1}^{r} \|m{lpha}\|_{\infty}^{j} (\|f-g\|_{\infty} + \|L_{j}f-L_{j}g\|_{\infty})$ $\leq \|f - g\|_{\infty} + \lim_{r \to \infty} \sum_{i=1}^{r} \|\alpha\|_{\infty}^{j} (\|f - g\|_{\infty} + \|L_{j}(f - g)\|_{\infty})$ $\leq \left(1+\sum_{j=1}^{\infty}\|lpha\|_{\infty}^{j}
ight)\|f-g\|_{\infty}+\left(\sum_{j=1}^{\infty}\|lpha\|_{\infty}^{j}
ight)\|L(f-g)\|_{\infty}$ $\leq \left(\frac{1}{1-\|\boldsymbol{\alpha}\|_{\infty}}\right)\|f-g\|_{d}+\left(\frac{\|\boldsymbol{\alpha}\|_{\infty}}{1-\|\boldsymbol{\alpha}\|_{\infty}}\right)\|Lf-Lg\|_{\infty}.$ 27 28 29 For all *x*, the above mentioned inequality is true, hence 30 $\|\mathfrak{F}_b^{\alpha}(f) - \mathfrak{F}_b^{\alpha}(g)\|_{\infty} = \|f_b^{\alpha} - g_b^{\alpha}\|_{\infty} \le \left(\frac{1}{1 - \|\alpha\|_{\infty}}\right) \|f - g\|_d + \left(\frac{\|\alpha\|_{\infty}}{1 - \|\alpha\|_{\infty}}\right) \|Lf - Lg\|_{\infty}.$ 31 32 This completes the proof. 33 34 35 **Proposition 4.14.** The non-stationary fractal operator $\mathfrak{F}_b^{\alpha} : Lip_d(I) \to \mathscr{C}(I)$ is relatively bounded with respect to *L* with *L*-bound is less than or equal to $\frac{\|\alpha\|_{\infty}}{1-\|\alpha\|}$ 36 37 *Proof.* Let *f* be an arbitrary function in $Lip_d(I)$. From (2.6), we have 38 39 $f_b^{\alpha}(x) = f(x) + \lim_{r \to \infty} \sum_{i=1}^r \alpha_{i,1}(Q_i(x)) \dots \alpha_{i,j}(Q_i^j(x))(f - L_j f)(Q_i^j(x)).$ 40 41 42 Therefore, 43 $|f_b^{\alpha}(x)| = |f(x)| + |\lim_{r \to \infty} \sum_{i=1}^{\prime} \alpha_{i,1}(Q_i(x)) \dots \alpha_{i,j}(Q_i^j(x))(f - L_j f)(Q_i^j(x))|$ 44 45 46 $\leq \|f\|_{\infty} + \lim_{r \to \infty} \sum_{i=1}^{r} \|\alpha\|_{\infty}^{j} \|f - L_{j}f\|_{\infty}$

11 Mar 2024 05:29:00 PDT

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 $\leq \|f\|_{\infty} + \lim_{r \to \infty} \sum_{j=1}^{\prime} \|\alpha\|_{\infty}^{j} (\|f\|_{\infty} + \|L_{j}f\|_{\infty})$ $\begin{array}{c}
1\\
2\\
3\\
4\\
5\\
6\\
7\\
8\\
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10\\
11\\
12
\end{array}$

$$\leq \|f\|_{\infty} + \lim_{r
ightarrow \infty} \sum_{i=1}^r \|oldsymbollpha\|_\infty^j (\|f\|_\infty + \|Lf\|_\infty)$$

$$= \|f\|_{\infty} + \frac{\|\boldsymbol{\alpha}\|_{\infty}}{1 - \|\boldsymbol{\alpha}\|_{\infty}} (\|f\|_{\infty} + \|Lf\|_{\infty})$$

$$= \frac{1}{1 - \|\boldsymbol{\alpha}\|_{\infty}} \|f\|_{\infty} + \frac{\|\boldsymbol{\alpha}\|_{\infty}}{1 - \|\boldsymbol{\alpha}\|_{\infty}} \|Lf\|_{\infty}$$

$$\leq rac{1}{1-\|oldsymbollpha\|_{d}}\|f\|_{d}+rac{\|oldsymbollpha\|_{\infty}}{1-\|oldsymbollpha\|_{\infty}}\|Lf\|_{\infty}$$

13 The aforementioned inequality holds for all *x*, hence 14

$$\|\mathfrak{F}_{b}^{\alpha}(f)\|_{\infty} = \|f_{b}^{\alpha}\|_{\infty} \leq \frac{1}{1 - \|\alpha\|_{\infty}} \|f\|_{d} + \frac{\|\alpha\|_{\infty}}{1 - \|\alpha\|_{\infty}} \|Lf\|_{\infty}.$$

This proves our claim. 18

5. Stability and sensitivity analysis

21 Let us now investigate the stability of the FIF with changeable parameters produced by 22 IFS $\mathscr{I}_r = {\mathscr{M}; W_{i,r}(x,y) = (l_i(x), F_{i,r}(x,y)), i \in \mathbb{N}_N}$, where the maps are defined in (2.5) and 23 $\mathcal{M} = I \times [k_1, k_2] \subset \mathbb{R}^2$. The similar results for the stationary case can be observed in [29]. Let 24 $\mathbf{\bar{D}} := \{(x_i, \bar{y}_i) : i \in \mathbb{N}_N^0\}$ be another set of interpolation points in \mathcal{M} which can be considered 25 as the perturbations of ordinates of the points in $\mathbf{D} := \{(x_i, y_i) \in I \times [k_1, k_2] : i \in \mathbb{N}_N^0\}$. For the 26 data set $\mathbf{\bar{D}}$, an IFS can be defined by $\bar{\mathscr{I}}_r = \{\mathscr{M}; \bar{W}_{i,r}(x,y) = (l_i(x), \bar{F}_{i,r}(x,y)), i \in \mathbb{N}_N\}$, where 27 $l_i(x)$, $i \in \mathbb{N}_N$, are the maps defined in (2.5), and $\overline{F}_{i,r}$ are defined as 28

$$\bar{F}_{i,r} = \alpha_{i,r}(x)y + \hat{f}(l_i(x)) - \alpha_{i,r}(x)\hat{b}_r(x), \ i \in \mathbb{N}_N, \ r \in \mathbb{N}_N$$

31 Here we consider the base functions b_r and perturbed base functions \bar{b}_r in $\mathscr{C}_f(I)$ such that 32 $\sup \|b_r\|_{\infty} < \infty$ and $\sup \|\bar{b}_r\|_{\infty} < \infty$. 33 $r \in \mathbb{N}$ $r \in \mathbb{N}$

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Theorem 5.1. Let $\mathbf{D} := \{(x_i, y_i) : i \in \mathbb{N}_N^0\}$ and $\mathbf{\overline{D}} := \{(x_i, \overline{y}_i) : i \in \mathbb{N}_N^0\}$ be two data sets in \mathcal{M} . 35 Let f_b^{α} be the non-stationary FIF for **D** generated by the sequence of IFSs $\mathscr{I}_r = \{\mathscr{M}; W_{i,r}(x, y) = \}$ $(l_i(x), F_{i,r}(x, y)), i \in \mathbb{N}_N$ defined in (2.5) and \bar{f}_b^{α} be the non-stationary FIF for $\mathbf{\bar{D}}$ generated by the 37 sequence of IFSs $\bar{\mathscr{I}}_r = \{\mathscr{M}; \bar{W}_{i,r}(x,y) = (l_i(x), \bar{F}_{i,r}(x,y)), i \in \mathbb{N}_N\}$ defined through (5.1). Then we have, 39

$$\|f_{b}^{40} - \bar{f}_{b}^{\alpha}\|_{\infty} \leq \frac{\|f - \hat{f}\|_{\infty} + \|\alpha\|_{\infty} \cdot \sup_{r \in \mathbb{N}} \{\|b_{r} - \hat{b}_{r}\|_{\infty}\}}{1 - \|\alpha\|_{\infty}}$$

44 *Proof.* From (2.7), we have 45

$$f_b^{\alpha}(x) = f(x) + \lim_{r \to \infty} \sum_{j=1}^r \alpha_{i,1}(Q_i(x)) \dots \alpha_{i,j}(Q_i^j(x))(f - b_j)(Q_i^j(x)).$$

11 Mar 2024 05:29:00 PDT

240101-JhaSangita Version 2 - Submitted to Rocky Mountain J. Math.

STABILITY AND SENSITIVITY ANALYSIS OF NON-STATIONARY α -fractal functions 14

 $|f_h^{\alpha}(x) - \hat{f}_h^{\alpha}(x)|$

$$\begin{split} &-\lim_{r \to \infty} \sum_{j=1}^{r} \alpha_{i,1}(\mathcal{Q}_{i}(x)) \dots \alpha_{i,j}(\mathcal{Q}_{i}^{j}(x))(\hat{f} - \hat{b}_{j})(\mathcal{Q}_{i}^{j}(x))| \\ &\leq |f(x) - \hat{f}(x)| + |\lim_{r \to \infty} \sum_{j=1}^{r} \alpha_{i,1}(\mathcal{Q}_{i}(x)) \dots \alpha_{i,j}(\mathcal{Q}_{i}^{j}(x))(f - \hat{f} - b_{j} + \hat{b}_{j})(\mathcal{Q}_{i}^{j}(x))| \\ &\leq \|f - \hat{f}\|_{\infty} + \lim_{r \to \infty} \sum_{j=1}^{r} \|\alpha\|_{\infty}^{j} (\|f - \hat{f}\|_{\infty} + \|b_{j} - \hat{b}_{j}\|_{\infty}) \end{split}$$

 $= |f(x) + \lim_{r \to \infty} \sum_{j=1}^{r} \alpha_{i,1}(Q_i(x)) \dots \alpha_{i,j}(Q_i^j(x))(f - b_j)(Q_i^j(x)) - \hat{f}(x)$

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$$\leq \left(1 + \sum_{j=1}^{\infty} \|\alpha\|_{\infty}^{j}\right) \|f - \hat{f}\|_{\infty} + \left(\lim_{r \to \infty} \sum_{j=1}^{r} \|\alpha\|_{\infty}^{j}\right) \sup_{r \in \mathbb{N}} \{\|b_{r} - \hat{b}_{r}\|_{\infty}\}$$

$$= \left(1 + \frac{\|\alpha\|_{\infty}}{1 - \|\alpha\|_{\infty}}\right) \|f - \hat{f}\|_{\infty} + \left(\frac{\|\alpha\|_{\infty}}{1 - \|\alpha\|_{\infty}}\right) \sup_{r \in \mathbb{N}} \{\|b_{r} - \hat{b}_{r}\|_{\infty}\}$$

$$= \frac{\|f - \hat{f}\|_{\infty} + \|\alpha\|_{\infty} \cdot \sup_{r \in \mathbb{N}} \{\|b_{r} - \hat{b}_{r}\|_{\infty}\}}{1 - \|\alpha\|_{\infty}}.$$

22 The above inequality holds for all $x \in I$; hence inequality (5.2) follows. 23

²⁴ *Remark* 5.2. Let f, \hat{f} be two piecewise linear functions through the interpolation data sets **D** and $\mathbf{\bar{D}}$ respectively. Also assume that $b_r = \hat{b}_r = b$ is a linear function passing through the 25 points (x_0, y_0) and (x_N, y_N) . Then we have 26

$$\|f_b^{\boldsymbol{\alpha}} - \bar{f}_b^{\boldsymbol{\alpha}}\|_{\infty} \leq \frac{1 + \|\boldsymbol{\alpha}\|_{\infty}}{1 - \|\boldsymbol{\alpha}\|_{\infty}} \max_{i \in \mathbb{N}_N^0} \{|y_i - \bar{y}_i|\},$$

which is the same result for stationary FIF given in [29]. So, our result can be treated as a 31 generalisation of the existing result. 32

Remark 5.3. Perturbations of abscissas of interpolation points can be taken to affect the 33 values of the non-stationary FIFs associated with the interpolation points. Also, perturbations of both abscissas and ordinates may be considered to examine the stability of the 35 non-stationary FIF. For more details, the reader is invited to read the paper of Wang and 36 Yu [29]. 37

38 Next, we discuss the sensitivity of the non-stationary α -FIF defined by the IFS \mathscr{I}_r . Let 39 $f, b_r, \alpha_{i,r}$ be as defined before and $T_{i,r}: \mathcal{M} \to \mathbb{R}, i \in \mathbb{N}_N, r \in \mathbb{N}$, be a sequence of continuous 40 functions on \mathcal{M} such that for all $(x, y) \in \mathcal{M}$, 41

$$T_{i,r}(x,y) = f(x) + [\alpha_{i,r}(Q_i(x)) + t_{i,r}\theta_{i,r}(Q_i(x))](g - b_r)(Q_i(x)) + s_{i,r}\phi_{i,r}(Q_i(x))$$

where $t_{i,r}$, $s_{i,r}$ are parameters of perturbation satisfying $0 < t_{i,r} < 1$ and $0 < s_{i,r} < 1$, $\phi_{i,r}$, $\theta_{i,r}$, 0) $\in Lip_d(I)$ satisfying sup $\max_i \|\alpha_{i,r}\|_{\infty} + \sup_i \max_i \|t_{i,r}\theta_{i,r}\|_{\infty} < 1$ and $\phi_{i,r}(x_0) = \phi_{i,r}(x_N) = 0$. The 45 46 function $T_{i,r}$ is a perturbation of the function $F_{i,r}$ for each $i \in \mathbb{N}_N, r \in \mathbb{N}$. Thus the IFS 47 $\mathscr{I}'_r = \{\mathscr{M}; (l_i(x), T_{i,r}(x, y)), i \in \mathbb{N}_N\}$ may be treated as the perturbation IFS of the IFS $\mathscr{I}_r =$

1 { \mathcal{M} ; $(l_i(x), F_{i,r}(x, y)), i \in \mathbb{N}_N$ }. For each $r \in \mathbb{N}, i \in \mathbb{N}_N, T_{i,r}$ is also contractive in the second $T_{i,r}(x_0, y_0) = y_{i-1}, \ T_{i,r}(x_N, y_N) = y_i.$ Therefore the IFS $\mathscr{I}'_r = \{\mathscr{M}; (l_i(x), T_{i,r}(x, y)), i \in \mathbb{N}_N\}$ determines a unique non-stationary **Theorem 5.4.** Let $\mathbf{D} := \{(x_i, y_i) : i \in \mathbb{N}_N^0\}$ be a data set in \mathcal{M} . Let f_b^{α} be the non-stationary FIFs corresponding to the sequence of IFSs $\mathscr{I}_r = \{\mathscr{M}; (l_i(x), F_{i,r}(x, y)), i \in \mathbb{N}_N\}$ defined in (2.5) and $f_{b,s}^{\alpha, t}$ be the non-stationary FIF generated by the sequence of IFSs $\mathscr{I}'_r = \{\mathscr{M}; (l_i(x), T_{i,r}(x, y)), i \in \mathbb{N}_N\}$. 11 12 Then 13 14 15 $\|f_{b,s}^{\alpha,t} - f_b^{\alpha}\|_{\infty} \leq \frac{\|\phi\|_{\infty}}{1 - \|\alpha\|_{\infty} - |t|_{\infty}\|\theta\|_{\infty}} |s|_{\infty} + \frac{\|\theta\|_{\infty} \sup\{\|f - b_r\|_{\infty}\}}{(1 - \|\alpha\|_{\infty})(1 - \|\alpha\|_{\infty} - |t|_{\infty}\|\theta\|_{\infty})} |t|_{\infty},$ (5.3)16 17 18 where
$$\begin{split} \|\phi\|_{\infty} &= \sup_{r \in \mathbb{N}} \{\max_{i \in \mathbb{N}_N} \|\phi_{i,r}\|_{\infty}\}, \ \|\theta\|_{\infty} = \sup_{r \in \mathbb{N}} \{\max_{i \in \mathbb{N}_N} \|\theta_{i,r}\|_{\infty}\}, \\ |s|_{\infty} &= \sup_{r \in \mathbb{N}} \{\max_{i \in \mathbb{N}_N} s_{i,r}\}, \ |t|_{\infty} = \sup_{r \in \mathbb{N}} \{\max_{i \in \mathbb{N}_N} t_{i,r}\}. \end{split}$$
19 20 21 22 *Proof.* From (2.7), we have 23 24 25 $f_b^{\alpha}(x) - f(x) = \lim_{r \to \infty} \sum_{i=1}^r \alpha_{i,1}(Q_i(x)) \dots \alpha_{i,j}(Q_i^j(x))(f - b_j)(Q_i^j(x)).$ (5.4)26 27 28 For $r \in \mathbb{N}$, let us define an RB operator V^{α_r} on \mathscr{M} by 29 $(V^{\alpha_r}g)(x) = T_{ir}(l_i^{-1}(x), g(l_i^{-1}(x)))$ 30 $= f(x) + [\alpha_{i,r}(Q_i(x)) + t_{i,r}\theta_{i,r}(Q_i(x))](g - b_r)(Q_i(x)) + s_{i,r}\phi_{i,r}(Q_i(x))$ 31 $= f(x) + [\mathbf{a}_{r}(x) + \mathbf{c}_{r}(x)](g - b_{r})(Q_{i}(x)) + s_{i,r}\phi_{i,r}(Q_{i}(x)),$ 32 33 where $\mathbf{a}_r(x) = \alpha_{i,r}(Q_i(x))$ and $\mathbf{c}_r(x) = t_{i,r}\theta_{i,r}(Q_i(x))$. 34 35 $V^{\alpha_1} \circ V^{\alpha_2} \circ \cdots \circ V^{\alpha_r} f(x) - f(x)$ 36 37 $= \Big[\mathbf{a}_1(x) + \mathbf{c}_1(x)\Big]\Big(V^{\alpha_2} \circ V^{\alpha_3} \circ \cdots \circ V^{\alpha_r} f - b_1\Big)(Q_i(x)) + s_{i,1}\phi_{i,1}(Q_i(x))\Big]$ 38 39 40 Using induction, we obtain 41 $V^{\alpha_1} \circ V^{\alpha_2} \circ \cdots \circ V^{\alpha_r} f(x) - f(x)$ 42 43 $=\sum_{i=1}^{r} \left[\mathbf{a}_{1}(x) + \mathbf{c}_{1}(x) \right] \left[\mathbf{a}_{2}(x) + \mathbf{c}_{2}(x) \right] \dots \left[\mathbf{a}_{j}(x) + \mathbf{c}_{j}(x) \right] (f - b_{j}) (Q_{i}^{j}(x))$ 44 45 + $\sum_{i=1}^{r} s_{i,j} \phi_{i,j}(Q_i^j(x)) \Big[\mathbf{a}_1(x) + \mathbf{c}_1(x) \Big] \Big[\mathbf{a}_2(x) + \mathbf{c}_2(x) \Big] \dots \Big[\mathbf{a}_{j-1}(x) + \mathbf{c}_{j-1}(x) \Big],$ 46 47

+ $\lim_{r \to \infty} \sum_{i=1}^{r} s_{i,j} \phi_{i,j}(Q_i^j(x)) \Big[\mathbf{a}_1(x) + \mathbf{c}_1(x) \Big] \Big[\mathbf{a}_2(x) + \mathbf{c}_2(x) \Big] \dots \Big[\mathbf{a}_{j-1}(x) + \mathbf{c}_{j-1}(x) \Big].$

¹ where Q_i^j is a suitable finite composition of mappings Q_i . Now, taking the limit as $r \to \infty$, 2 we get 3 4

 $= \lim_{r \to \infty} \sum_{i=1}^{r} \left[\mathbf{a}_1(x) + \mathbf{c}_1(x) \right] \left[\mathbf{a}_2(x) + \mathbf{c}_2(x) \right] \dots \left[\mathbf{a}_j(x) + \mathbf{c}_j(x) \right] (f - b_j) (Q_i^j(x))$

$$\frac{5}{6}$$
 (5.5)
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Subtracting (5.4) from (5.5), we get $\begin{array}{c} 11 \\ 12 \\ 13 \\ 14 \\ 15 \\ 16 \\ 17 \\ 18 \\ 19 \\ 20 \\ 21 \\ 22 \\ 23 \\ 24 \\ 25 \\ 26 \\ 27 \\ 28 \\ 29 \end{array}$

 $f_{b,s}^{\alpha,t}(x) - f(x)$

$$\begin{aligned} f_{b,s}^{\alpha,i}(x) &- f_b^{\alpha}(x) \\ &= \lim_{r \to \infty} \sum_{j=1}^r s_{i,j} \phi_{i,j}(Q_i^j(x)) \left[\mathbf{a}_1(x) + \mathbf{c}_1(x) \right] \left[\mathbf{a}_2(x) + \mathbf{c}_2(x) \right] \dots \left[\mathbf{a}_{j-1}(x) + \mathbf{c}_{j-1}(x) \right] \\ &+ \lim_{r \to \infty} \sum_{j=1}^r \left[\left[\left[\mathbf{a}_1(x) + \mathbf{c}_1(x) \right] \left[\mathbf{a}_2(x) + \mathbf{c}_2(x) \right] \dots \left[\mathbf{a}_j(x) + \mathbf{c}_j(x) \right] \right] \\ &- \mathbf{a}_1(x) \mathbf{a}_2(x) \dots \mathbf{a}_j(x) \right] (f - b_j) (Q_i^j(x)) \end{aligned}$$

$$= \lim_{r \to \infty} \sum_{j=1}^{r} s_{i,j} \phi_{i,j}(Q_i^j(x)) \left[\mathbf{a}_1(x) + \mathbf{c}_1(x) \right] \left[\mathbf{a}_2(x) + \mathbf{c}_2(x) \right] \dots \left[\mathbf{a}_{j-1}(x) + \mathbf{c}_{j-1}(x) \right] \\ + \lim_{r \to \infty} \sum_{i=1}^{r} \left[\mathbf{a}_1(x) \cdot \mathbf{a}_2(x) \dots \mathbf{a}_{j-1}(x) \cdot \mathbf{c}_j(x) + \mathbf{a}_1(x) \cdot \mathbf{a}_2(x) \dots \mathbf{a}_{j-2}(x) \cdot \mathbf{c}_{j-1}(x) \right]$$

$$\times [\mathbf{a}_{j}(x) + \mathbf{c}_{j}(x)] + \mathbf{a}_{1}(x) \cdot \mathbf{a}_{2}(x) \dots \mathbf{a}_{j-3}(x) \cdot \mathbf{c}_{j-2}(x) [\mathbf{a}_{j-1}(x) + \mathbf{c}_{j-1}(x)] [\mathbf{a}_{j}(x) + \mathbf{c}_{j}(x)] + \dots + \mathbf{c}_{1}(x) [\mathbf{a}_{2}(x) + \mathbf{c}_{2}(x)] [\mathbf{a}_{3}(x) + \mathbf{c}_{3}(x)] \dots [\mathbf{a}_{j}(x) + \mathbf{c}_{j}(x)] (f - b_{j}) (Q_{i}^{j}(x)) \bigg]$$

30 31 Let $\mathbf{a} = \sup_{r \in \mathbb{N}} \{ \|\mathbf{a}_r\|_{\infty} \} = \|\alpha\|_{\infty}$ and $\mathbf{c} = \sup_{r \in \mathbb{N}} \{ \|\mathbf{c}_r\|_{\infty} \} = |t|_{\infty} \|\theta\|_{\infty}$. Therefore, 32 $|f_{l}^{\alpha,t}(x) - f_{l}^{\alpha}(x)|$

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$$\begin{split} &= \frac{\|\phi\|_{\infty}|s|_{\infty}}{1-\mathbf{a}-\mathbf{c}} + \sup\{\|f-b_r\|_{\infty}\}\mathbf{c}\sum_{j=1}^{\infty}(\mathbf{a}+\mathbf{c})^{j-1} \times \left(\frac{1-\left(\frac{\mathbf{a}}{\mathbf{a}+\mathbf{c}}\right)^{j}}{1-\left(\frac{\mathbf{a}}{\mathbf{a}+\mathbf{c}}\right)^{j}}\right) \\ &= \frac{\|\phi\|_{\infty}|s|_{\infty}}{1-\mathbf{a}-\mathbf{c}} + \sup\{\|f-b_r\|_{\infty}\}\sum_{j=1}^{\infty}\left((\mathbf{a}+\mathbf{c})^{j}-(\mathbf{a})^{j}\right) \\ &= \frac{\|\phi\|_{\infty}|s|_{\infty}}{1-\mathbf{a}-\mathbf{c}} + \sup\{\|f-b_r\|_{\infty}\}\left(\frac{\mathbf{a}+\mathbf{c}}{1-\mathbf{a}-\mathbf{c}}-\frac{\mathbf{a}}{1-\mathbf{a}}\right) \\ &= \frac{\|\phi\|_{\infty}}{1-\mathbf{a}-\mathbf{c}}|s|_{\infty} + \frac{\|\theta\|_{\infty}\sup\{\|f-b_r\|_{\infty}\}}{(1-\mathbf{a})(1-\mathbf{a}-\mathbf{c})}|t|_{\infty}. \end{split}$$

The above inequality holds for each $x \in \mathcal{M}$, hence

$$\begin{split} \|f_{b,s}^{\alpha,t} - f_b^{\alpha}\|_{\infty} &\leq \frac{\|\phi\|_{\infty}}{1 - \|\alpha\|_{\infty} - |t|_{\infty}\|\theta\|_{\infty}} |s|_{\infty} \\ &+ \frac{\|\theta\|_{\infty} \sup\{\|f - b_r\|_{\infty}\}}{(1 - \|\alpha\|_{\infty})(1 - \|\alpha\|_{\infty} - |t|_{\infty}\|\theta\|_{\infty})} |t|_{\infty}. \end{split}$$

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6. Continuous dependence on parameters b, α .

In this section, we will investigate the continuous dependence of the non-stationary α fractal function on different IFS parameters. The reader can refer to [26] for the same study in the stationary case. We will start with the continuous dependence of $f_{\Delta,b}^{\alpha}$ on the sequence of base functions $b := \{b_r\}$.

Theorem 6.1. Let $f \in \mathscr{C}(I)$, and the partition \triangle , sequence of scale functions $\alpha_r \in \mathscr{C}(I)$, $r \in \mathbb{N}$ with $\|\alpha\|_{\infty} < 1$ be fixed. Let $A = \{b_r \in \mathscr{C}(I) : b_r(x) = f(x) \ \forall \ x = x_0, x_N\}$. Then, the map $\mathscr{A} : A \to \mathscr{C}(I)$ defined by

$$\mathscr{A}(b) = f^{\alpha}_{\triangle, k}$$

 $\frac{32}{2}$ is Lipschitz continuous.

Proof. From Section 2.4, we obtain that $f_{\triangle,b}^{\alpha}$ is unique for a fixed sequence of scale function α_r , a partition \triangle , and a suitable sequence of base function $b_r \in \mathscr{C}(I)$. Further, $f_{\triangle,b}^{\alpha}$ satisfies the functional equation: for all $x \in I_i$, $i \in \mathbb{N}_N$, we have

$$f_{\Delta,b}^{\alpha}(x) = f(x) + \lim_{r \to \infty} \sum_{j=1}^{r} \alpha_{i,1}(Q_i(x)) \dots \alpha_{i,j}(Q_i^j(x))(f - b_j)(Q_i^j(x)).$$

 $\frac{40}{41}$ Let $b_r, c_r \in A$, for $r \in \mathbb{N}$. Then

$$\mathscr{A}(b)(x) = f^{\alpha}_{\Delta,b}(x) = f(x) + \lim_{r \to \infty} \sum_{j=1}^r \alpha_{i,1}(Q_i(x)) \dots \alpha_{i,j}(Q_i^j(x))(f-b_j)(Q_i^j(x)),$$

$$\frac{44}{45}$$
 and

$$\mathscr{A}(c)(x) = f^{\alpha}_{\Delta,c}(x) = f(x) + \lim_{r \to \infty} \sum_{j=1}^{r} \alpha_{i,1}(Q_i(x)) \dots \alpha_{i,j}(Q_i^j(x))(f-c_j)(Q_i^j(x)).$$

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1 To show that \mathscr{B} is continuous at α , we subtract one from the other of the above two

To show that
$$\mathscr{B}$$
 is continuous at α , we subtract one from the other of the above equations, for $x \in I_i$, $i \in \mathbb{N}_N$, we have

$$\begin{array}{l} \mathscr{B}(\alpha)(x) - \mathscr{B}(\beta)(x) \\ = \lim_{r \to \infty} \sum_{j=1}^r \alpha_{i,1}(Q_i(x)) \dots \alpha_{i,j}(Q_i^j(x))(f - b_j)(Q_i^j(x)) \\ -\lim_{r \to \infty} \sum_{j=1}^r \beta_{i,1}(Q_i(x)) \dots \beta_{i,j}(Q_i^j(x))(f - b_j)(Q_i^j(x)) \\ = \lim_{r \to \infty} \sum_{j=1}^r \left(\alpha_{i,1}(Q_i(x)) \dots \alpha_{i,j}(Q_i^j(x)) - \beta_{i,1}(Q_i(x)) \dots \beta_{i,j}(Q_i^j(x)) \right) (f - b_j)(Q_i^j(x)) \\ = \lim_{r \to \infty} \sum_{j=1}^r \left((\alpha_{i,1} - \beta_{i,1})(Q_i(x))\beta_{i,2}(Q_i^2(x)) \dots \beta_{i,j}(Q_i^j(x)) \\ + \alpha_{i,1}(Q_i(x))(\alpha_{i,2} - \beta_{i,2})(Q_i^2(x))\beta_{i,3}(Q_i^3(x)) \dots \beta_{i,j}(Q_i^j(x)) \\ + \dots + \alpha_{i,1}(Q_i(x))\alpha_{i,2}(Q_i^2(x)) \dots \alpha_{i,j-1}(Q_i^{j-1}(x))(\alpha_{i,j} - \beta_{i,j})(Q_i^j(x)) \right) (f - b_j)(Q_i^j(x)). \end{array}$$

20 Therefore,

Without loss of generality, let $0 < \|\beta\|_{\infty} < \|\alpha\|_{\infty} < 1$. Then

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$$= \|f - b\|_{\infty} \frac{\|\alpha - \beta\|_{\infty}}{\|\alpha\|_{\infty} - \|\beta\|_{\infty}} \sum_{j=1}^{\infty} \left(\|\alpha\|_{\infty}^{j} - \|\beta\|_{\infty}^{j} \right)$$
$$= \|f - b\|_{\infty} \frac{\|\alpha - \beta\|_{\infty}}{(1 - \|\alpha\|_{\infty}) \cdot (1 - \|\beta\|_{\infty})}$$
$$\leq \|\alpha - \beta\|_{\infty} \frac{\|f - b\|_{\infty}}{(1 - s)^{2}}.$$

The aforementioned inequality holds for all $x \in I$, therefore

$$\left|\left|\mathscr{B}(\alpha) - \mathscr{B}(\beta)\right|\right|_{\infty} \leq \|\alpha - \beta\|_{\infty} \frac{\|f - b\|_{\infty}}{(1 - s)^2}.$$

¹¹
₁₂ Since $f, b \in \mathscr{C}(I)$ and α is fixed, we have \mathscr{B} is continuous at α . As α was taken arbitrarily, ₁₃ \mathscr{B} is continuous on B.

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²² *Availability of data and material.* Not applicable $\frac{23}{23}$

24 *Code availability*. Not applicable

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