# ADJOINT FAMILIES IN TOPOLOGICAL VECTOR SPACES 

SADOON I. OTHMAN<br>Department of Mathematics, College of Science<br>King Saud University, P.O. Box 2455, Riyadh 11451, Saudi Arabia


#### Abstract

Given a linear partial differential operator $L$ of order $m$ with $c^{m}$-coefficients and a distribution $T$ on an open set $\Omega$ of $\boldsymbol{R}^{n}$, a necessary and sufficient condition is derived for the existence of a function $f \in L^{p}(\Omega), 1<$ $p<\infty$, such that $L f=T$ in the sense of distribution.


## 1. Introduction

Suppose $B$ is a reflexive Banach space, $E$ a locally convex space and $T: B \rightarrow E$ a linear map (continuous or not). We obtain a necessary and sufficient condition so that given $g \in E$, there exists $f \in B$ such that $T f=g$.

This result is applied to the problem of finding a solution of $f \in L^{p}(\Omega), \quad 1<$ $p<\infty$ and $\Omega$ open in $\mathbb{R}^{n}$, for the differential equation $L f=T$ where $L$ is a partial differential operator of order $m$ with $c^{m}$-coefficients and $T$ is a distribution defined on $\Omega$.

## 2. A Preliminary result in a Hilbert space

Proposition 1. Let $T$ be a bounded linear operator on a Hilbert space $H$. Then given $g \in H$, there exists an $f \in H$ such that $T f=g$ if and only if $\sup _{\|u\|=1} \frac{|(g, u)|}{\|T \star u\|}$ is finite.

[^0]
## Proof:

1) Suppose $T f=g$. Then for any $u \in H, \quad|(g, u)|=|(T f, u)|=\left|\left(f, T^{\star} u\right)\right| \leq$ $\|f\|\left\|T^{\star} u\right\|$.
2) Conversely, suppose $|(g, u)| \leq c\left\|T^{\star} u\right\|$ for every $u \in H$.

Consider now the linear functional $\lambda$ defined on $\operatorname{Ran} T^{\star}$ as follows:

For $v=T^{\star} u, \quad \lambda(v)=(g, u)$. This definition does not depend on the particular choice of $u$ and $|\lambda(v)| \leq c\left\|T^{\star} u\right\|=c\|v\|$.

Hence $\lambda$ is a bounded linear functional on Ran $T^{*}$ and it can be extended as a continuous linear functional on the whole of $H$. Let us denote this extension also by $\lambda$.

Consequently, there exists an $f \in H$ such that $\lambda(x)=(f, x)$ for every $x \in H$.
In particular, for every $u \in H, \lambda\left(T^{\star} u\right)=\left(f, T^{\star} u\right)=(T f, u)$. But $T^{\star} u \in \operatorname{Ran} T^{\star}$ and hence $\lambda\left(T^{\star} u\right)=(g, u)$.

Thus, $(T f, u)=(g, u)$ for every $u \in H$ and hence $T f=g$.

## 3. Adjoint family in topological vector spaces.

Definition 1: Let $E_{1}$ and $E_{2}$ be two topological vector spaces; $E_{1}^{\prime}$ and $E_{2}^{\prime}$ are their topological dual spaces. Let $T: E_{1} \rightarrow E_{2}$ and $S: E_{2}^{\prime} \rightarrow E_{1}^{\prime}$ be two linear operators (continuous or not) defined on some subspaces of $E_{1}$ and $E_{2}^{\prime}$ respectively, such that $(T x, y)=(x, S y)$ for $x \in \operatorname{Dom} T$ and $y \in \operatorname{Dom} S$. Then $\left(E_{1}, E_{2} ; T, S\right)$ is called an adjoint family.

Theorem 1. Let ( $B, E ; T, S$ ) be an adjoint family where $B$ is a reflexive Banach space and $E$ is a topological vector space whose topological dual $E^{\prime}$ separates points of $E$. (Examples: $E=l^{p}, 0<p<\infty$ or $E$ is any locally convex space). Suppose that $\operatorname{Dom} T$ is $B$ and $\operatorname{Dom} S$ is a $\sigma\left(E^{\prime}, E\right)$-dense subspace in $E^{\prime}$.

Then, given $g \in E$, there exists an $f \in B$ such that $T f=g$ if and only if $|(g, u)| \leq c\|S u\|$ for every $u \in \operatorname{Dom} S$.

When a solution to the equation $T f=g$ exists, it is unique if and only if Ran $S$ is dense in $B^{\prime}$.

## Proof:

1) Let $T f=g$

Then, for $u \in \operatorname{Dom} S,|(g, u)|=|(f, S u)| \leq\|f\|\|S u\|$.
2) Suppose now that $g \in E$ is given and $|(g, u)| \leq c\|S u\|$ for every $u \in \operatorname{Dom} S$.

Let $F=\left\{v \in B^{\prime}\right.$, where $v=S u$ for some $\left.u \in E^{\prime}\right\}$.
Then, as in the proof of Proposition 1, we note that the linear functional $L(v)=$ $(g, u)$ defined on $F$ extends as a bounded linear functional $L$ on the whole of $B^{\prime}$ (using Hahn-Banach theorem, see Schaefer [1]).

Thus $L \in B^{\prime \prime}=B$ since $B$ is reflexive. Identify $L$ with an $f \in B$ to write $L(x)=(f, x)$ for every $x \in B^{\prime}$.

But, if $u \in \operatorname{Dom} S, L(S u)=(g, u)$ since $S u \in F$.
Thus, for every $u \in \operatorname{Dom} S,(g, u)=(f, S u)=(T f, u)$. Since $T f-g \in E$ vanishes on a dense set of $E^{\prime},(T f-g, y)=0$ for every $y \in E^{\prime}$ and since $E^{\prime}$ separates points of $E, T f-g=0$ in $E$.

Uniqueness: Let us suppose now that $T f=g$ has a solution $f \in B$ for a given $g \in E$. We'll show that the solution is unique if and only if $\operatorname{Ran} S$ is dense in $B^{\prime}$.

1) Suppose Ran $S$ is not dense in $B^{\prime}$.

Then, by Hahn-Banach theorem, there exists $h \in B, \quad h \neq 0$ and $h(\operatorname{Ran} S)=$ 0 , i.e. $(h, S u)=0$ for $u \in \operatorname{Dom} S$. This means that $(T h, u)=0$ and then as shown earlier $T h=0$.

Hence, $T(f+h)=T f=g$ which means that the solution is not unique.
2) Conversely, suppose $\operatorname{Ran} S$ is dense in $B^{\prime}$.

Suppose $T f_{1}=g=T f_{2}$.
Then $\left(T\left(f_{1}-f_{2}\right), u\right)=0$ for every $u \in \operatorname{Dom} S$. i.e. $\left(f_{1}-f_{2}, S u\right)=0$. Since Ran $S$ is dense in $B^{\prime}$, this implies that $f_{1}-f_{2}=0$ in $B$.

## 4. An application

Let $\Omega$ be an open set in $\boldsymbol{R}^{n}, n \geq 1$. Let $L=\sum_{|k| \leq m} a_{k}(x) \partial^{k}$ be a linear partial differential operator of order $m$, with $a_{k}(x) \in c^{m}(\Omega)$.

Let $\mathcal{D}(\Omega)$ be the family of $c^{\infty}$-functions with compact support in $\Omega$ and $\mathcal{D}^{\prime}(\Omega)$ the space of distributions in $\Omega . \mathcal{D}(\Omega)$ is a locally convex space (see Treves [2] ).

Let $L^{\star} u=\sum_{|k| \leq m}(-1)^{|k|} \partial^{k}\left(a_{k}(x) u\right)$ be the adjoint operator; this satisfies the condition $(L T, \varphi)=\left(T, L^{\star} \varphi\right)$ for $T \in \mathcal{D}^{\prime}(\Omega)$ and $\varphi \in \mathcal{D}(\Omega)$.

For the reflexive Banach space $L^{p}(\Omega), \quad 1<p<\infty$, denote the norm by $\|\cdot\|_{p}$ and let $\frac{1}{p}+\frac{1}{q}=1$.

Recall that for $f \in L^{p}(\Omega), L f \in \mathcal{D}^{\prime}(\Omega)$ and that two distributions $T$ and $S$ are said to be equal if and only if $(T, \varphi)=(S, \varphi)$ for every $\varphi \in \mathcal{D}(\Omega)$.

With these notations, the following theorem is an immediate consequence of Theorem 1.

Theorem 2: Let $L$ be a linear partial differential operator of order $m$ with $c^{m}$ coefficients defined on an open set $\Omega$ in $\mathbb{R}^{n}$. Then given $T \in \mathcal{D}^{\prime}(\Omega)$ there exists an $f \in L^{p}(\Omega), 1<p<\infty$, such that $L f=T$ if and only if $|T(\varphi)| \leq\left\|L^{\star} \varphi\right\|_{q}$ for every $\varphi \in \mathcal{D}(\Omega)$.

When such a solution exists, it is unique if and only if $L^{\star}(\mathcal{D}(\Omega))$ is dense in $L^{q}(\Omega)$.

## References

[1] H.H. Schaefer: Topological Vector Spaces. Springer-Verlag, Berlin, 1980.
[2] F. Treves: Basic Linear Partial Differential Equations. Academic Press, New York, 1975.

Received February 6, 1995


[^0]:    AMS Subject Classification: Primary 47F05, Secondary 47N20
    Keywords and phrases: Locally convex spaces, Distributions.

