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# A Compactness Result For An Equation with Holderian Condition 

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#### Abstract

We give blow-up behavior for a Brezis and Merle's problem with Dirichlet and Hölderian conditions. Also we derive a compactness criterion as in the work of Brezis and Merle.


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## 1 Introduction

We set $\Delta=-\left(\partial_{11}+\partial_{22}\right)$ on open set $\Omega$ of $\mathbb{R}^{2}$ with analytic boundary.
We consider the following equation:

$$
(P)\left\{\begin{aligned}
\Delta u & =V\left(1+|x|^{2 \beta}\right) e^{u} & & \text { in } \Omega \subset \mathbb{R}^{2} \\
u & =0 & & \text { in } \partial \Omega
\end{aligned}\right.
$$

Here, we assume that:

$$
0 \in \partial \Omega, \beta \in[0,1 / 2) .
$$

and,

$$
0 \leq V \leq b<+\infty, e^{u} \in L^{1}(\Omega) \text { and } u \in W_{0}^{1,1}(\Omega) .
$$

We can see in [8] a nice formulation of this problem $(P)$ in the sense of the distributions. This Problem arises from geometrical and physical problems, see for example [1, 3, $21,24]$. The above equation was studied by many authors, with or without the boundary condition, also for Riemannian surfaces, see [1-23], where one can find some existence and compactness results. In [7] we have the following important Theorem,

[^0]Theorem $\mathbf{A}$ (Brezis-Merle [7]).For $\left(u_{i}\right)_{i}$ and $\left(V_{i}\right)_{i}$ two sequences of functions relative to $(P)$ with,

$$
0<a \leq V_{i} \leq b<+\infty
$$

then it holds,

$$
\sup _{K} u_{i} \leq c,
$$

with $c$ depending on $a, b, \beta, K$ and $\Omega$.
One can find in [7] an interior estimate if we assume $a=0$, but we need an assumption on the integral of $e^{u_{i}}$, namely, we have:

Theorem $\mathbf{B}\left(\right.$ Brezis-Merle [7]).For $\left(u_{i}\right)_{i}$ and $\left(V_{i}\right)_{i}$ two sequences of functions relative to the problem $(P)$ with,

$$
0 \leq V_{i} \leq b<+\infty \text { and } \int_{\Omega} e^{u_{i}} d y \leq C
$$

then it holds;

$$
\sup _{K} u_{i} \leq c,
$$

with $c$ depending on $b, \beta, C, K$ and $\Omega$.
We look to the uniform boundedness in all $\bar{\Omega}$ of the solutions of the Problem $(P)$. When $a=0$, the boundedness of $\int_{\Omega} e^{u_{i}}$ is a necessary condition in the problem $(P)$ as showed in [7] by the following counterexample.

Theorem C(Brezis-Merle [7]).There are two sequences $\left(u_{i}\right)_{i}$ and $\left(V_{i}\right)_{i}$ of the problem $(P)$ with,

$$
0 \leq V_{i} \leq b<+\infty \text { and } \int_{\Omega} e^{u_{i}} d y \leq C
$$

such that,

$$
\sup _{0} u_{i} \rightarrow+\infty \text {. }
$$

To obtain the two first previous results (Theorems A and B) Brezis and Merle used an inequality (Theorem 1 of [7]) obtained by an approximation argument and used Fatou's lemma and applied the maximum principle in $W_{0}^{1,1}(\Omega)$ which arises from Kato's inequality. Also this weak form of the maximum principle is used to prove the local uniform boundedness result by comparing a certain function and the Newtonian potential. We refer to [6] for a topic about the weak form of the maximum principle.

When $\beta=0$, the above equation has many properties in the constant and the Lipschitzian cases:

Note that for the problem $(P)(\beta=0)$, by using the Pohozaev identity, we can prove that $\int_{\Omega} e^{u_{i}}$ is uniformly bounded when $0<a \leq V_{i} \leq b<+\infty$ and $\left\|\nabla V_{i}\right\|_{L^{\infty}} \leq A$ and $\Omega$ starshaped, when $a=0$ and $\nabla \log V_{i}$ is uniformly bounded, we can bound uniformly $\int_{\Omega} V_{i} e^{u_{i}}$. In [20], Ma-Wei have proved that those results stay true for all open sets not necessarily starshaped.

In [10] $(\beta=0)$ Chen-Li have proved that if $a=0, \nabla \log V_{i}$ is uniformly bounded and $u_{i}$ is locally uniformly bounded in $L^{1}$, then the functions are uniformly bounded near the boundary.

In [10] $(\beta=0)$ Chen-Li have proved that if $a=0$ and $\int_{\Omega} e^{u_{i}}$ is uniformly bounded and $\nabla \log V_{i}$ is uniformly bounded, then we have the compactness result directly. Ma-Wei in [20], extend this result in the case where $a>0$.

If we assume $V$ more regular, we can have another type of estimates, a sup +inf type inequalities. It was proved by Shafrir see [23], that, if $\left(u_{i}\right)_{i},\left(V_{i}\right)_{i}$ are two sequences of functions solutions of the previous equation without assumption on the boundary and, $0<$ $a \leq V_{i} \leq b<+\infty$, then we have the following interior estimate:

$$
C\left(\frac{a}{b}\right) \sup _{K} u_{i}+\inf _{\Omega} u_{i} \leq c=c(a, b, K, \Omega)
$$

One can see in [11] an explicit value of $C\left(\frac{a}{b}\right)=\sqrt{\frac{a}{b}}$. In his proof, Shafrir has used a blowup function, the Stokes formula and an isoperimetric inequality, see [3]. For Chen-Lin, they have used the blow-up analysis combined with some geometric type inequality for the integral curvature.

Now, if we suppose $\left(V_{i}\right)_{i}$ uniformly Lipschitzian with $A$ the Lipschitz constant, then, $C(a / b)=1$ and $c=c(a, b, A, K, \Omega)$, see Brezis-Li-Shafrir [5]. This result was extended for Hölderian sequences $\left(V_{i}\right)_{i}$ by Chen-Lin, see [11]. Also, one can see in [18], an extension of the Brezis-Li-Shafrir result to compact Riemannian surfaces without boundary. One can see in [19] explicit form, $\left(8 \pi m, m \in \mathbb{N}^{*}\right.$ exactly), for the numbers in front of the Dirac masses when the solutions blow-up. Here, the notion of isolated blow-up point is used.

In [9] we have some a priori estimates on the 2 and 3 -spheres $\mathbb{S}_{2}, \mathbb{S}_{3}$.
Here we give the behavior of the blow-up points on the boundary and a proof of BrezisMerle Problem when $\beta \geq 0$.

The Brezis-Merle Problem (see [7]) is:
Problem. Suppose that $V_{i} \rightarrow V$ in $C^{0}(\bar{\Omega})$ with $0 \leq V_{i} \leq b$ for some positive constant $b$. Also, we consider a sequence of solutions $\left(u_{i}\right)$ of $(P)$ relative to $\left(V_{i}\right)$ such that,

$$
\int_{\Omega} e^{u_{i}} d x \leq C
$$

is it possible to have:

$$
\left\|u_{i}\right\|_{L^{\infty}} \leq C=C(b, \beta, C, V, \Omega) ?
$$

Here we give a blow-up analysis for a sequence of solutions of the Problem $(P)$ and a proof of compactness result for the Brezis-Merle's Problem when $\beta \geq 0$. We extend the result of Chen-Li [10]. For the blow-up analysis we assume that:

$$
0 \leq V_{i} \leq b
$$

The condition $V_{i} \rightarrow V$ in $C^{0}(\bar{\Omega})$ is not necessary, but for the proof of the compactness result we assume that:

$$
\left\|\nabla V_{i}\right\|_{L^{\infty}} \leq A
$$

Our mains results are:

## 2 Main Results

Theorem 2.1. Assume that $\max _{\Omega} u_{i} \rightarrow+\infty$, where $\left(u_{i}\right)$ are solutions of the problem ( $P$ ) with:

$$
\beta \in[0,1 / 2), 0 \leq V_{i} \leq b \text { and } \int_{\Omega} e^{u_{i}} d x \leq C, \forall i,
$$

then, after passing to a subsequence, there is a finction $u$, there is a number $N \in \mathbb{N}$ and $N$ points $x_{1}, \ldots, x_{N} \in \partial \Omega$, such that,

$$
\begin{gathered}
\partial_{\nu} u_{i} \rightarrow \partial_{\nu} u+\sum_{j=1}^{N} \alpha_{j} \delta_{x_{j}}, \alpha_{j} \geq 4 \pi, \text { weakly in the sens of measures on } \partial \Omega . \\
u_{i} \rightarrow u \text { in } C_{l o c}^{1}\left(\bar{\Omega}-\left\{x_{1}, \ldots, x_{N}\right\}\right) .
\end{gathered}
$$

Theorem 2.2. Assume that $\left(u_{i}\right)$ are solutions of $(P)$ relative to $\left(V_{i}\right)$ with the following conditions:

$$
0 \in \partial \Omega, \beta \in[0,1 / 2),
$$

and,

$$
0 \leq V_{i} \leq b,\left\|\nabla V_{i}\right\|_{L^{\infty}} \leq A \text { and } \int_{\Omega} e^{u_{i}} \leq C
$$

we have,

$$
\left\|u_{i}\right\|_{L^{\infty}} \leq c(b, \beta, A, C, \Omega)
$$

In the last theorem we extend the result of Chen-Li $(\beta=0)$. The proof of Chen-Li and Ma-Wei $[10,20]$, use the moving-plane method $(\beta=0)$.

## 3 Proof of theorem 2.1

We have:

$$
u_{i} \in W_{0}^{1,1}(\Omega)
$$

Since $e^{u_{i}} \in L^{1}(\Omega)$ by the corollary 1 of Brezis-Merle's paper (see [7]) we have $e^{u_{i}} \in$ $L^{k}(\Omega)$ for all $k>2$ and the elliptic estimates of Agmon and the Sobolev embedding (see [1]) imply that:

$$
u_{i} \in W^{2, k}(\Omega) \cap C^{1, \epsilon}(\bar{\Omega}) .
$$

We denote by $\partial_{\nu} u_{i}$ the inner normal derivative. By the maximum principle we have, $\partial_{\nu} u_{i} \geq 0$.

By the Stokes formula we have,

$$
\int_{\partial \Omega} \partial_{\nu} u_{i} d \sigma \leq C
$$

We use the weak convergence in the space of Radon measures to have the existence of a nonnegative Radon measure $\mu$ such that,

$$
\int_{\partial \Omega} \partial_{\nu} u_{i} \phi d \sigma \rightarrow \mu(\phi), \forall \phi \in C^{0}(\partial \Omega) .
$$

We take an $x_{0} \in \partial \Omega$ such that, $\mu\left(x_{0}\right)<4 \pi$. For $\epsilon>0$ small enough set $I_{\epsilon}=B\left(x_{0}, \epsilon\right) \cap \partial \Omega$ on the unit disk or one can assume it as an interval. We choose a function $\eta_{\epsilon}$ such that,

$$
\left\{\begin{array}{l}
\eta_{\epsilon} \equiv 1, \text { on } I_{\epsilon}, 0<\epsilon<\delta / 2, \\
\eta_{\epsilon} \equiv 0, \text { outside } I_{2 \epsilon}, \\
0 \leq \eta_{\epsilon} \leq 1, \\
\left\|\nabla \eta_{\epsilon}\right\|_{L^{\infty}\left(I_{2 \epsilon}\right)} \leq \frac{C_{0}\left(\Omega, x_{0}\right)}{\epsilon} .
\end{array}\right.
$$

We take a $\tilde{\eta}_{\epsilon}$ such that,

$$
\left\{\begin{aligned}
\Delta \tilde{\eta}_{\epsilon}=0 & \text { in } \Omega \subset \mathbb{R}^{2}, \\
\tilde{\eta}_{\epsilon}=\eta_{\epsilon} & \text { in } \partial \Omega .
\end{aligned}\right.
$$

Remark: We use the following steps in the construction of $\tilde{\eta}_{\epsilon}$ :
We take a cutoff function $\eta_{0}$ in $B(0,2)$ or $B\left(x_{0}, 2\right)$ :
1- We set $\eta_{\epsilon}(x)=\eta_{0}\left(\left|x-x_{0}\right| / \epsilon\right)$ in the case of the unit disk it is sufficient.
2- Or, in the general case: we use a chart $(f, \tilde{\Omega})$ with $f(0)=x_{0}$ and we take $\mu_{\epsilon}(x)=$ $\eta_{0}(f(|x| / \epsilon))$ to have connected sets $I_{\epsilon}$ and we take $\eta_{\epsilon}(y)=\mu_{\epsilon}\left(f^{-1}(y)\right)$. Because $f, f^{-1}$ are Lipschitz, $\left|f(x)-x_{0}\right| \leq k_{2}|x| \leq 1$ for $|x| \leq 1 / k_{2}$ and $\left|f(x)-x_{0}\right| \geq k_{1}|x| \geq 2$ for $|x| \geq 2 / k_{1}>1 / k_{2}$, the support of $\eta$ is in $I_{\left(2 / k_{1}\right) \epsilon}$.

$$
\left\{\begin{array}{l}
\eta_{\epsilon} \equiv 1, \text { on } f\left(I_{\left(1 / k_{2}\right) \epsilon}\right), 0<\epsilon<\delta / 2, \\
\eta_{\epsilon} \equiv 0, \text { outside } f\left(I_{\left(2 / k_{1}\right) \epsilon},\right. \\
0 \leq \eta_{\epsilon} \leq 1, \\
\left\|\nabla \eta_{\epsilon}\right\|_{L^{\infty}\left(I_{\left(2 / k_{1}\right) \epsilon}\right)} \leq \frac{C_{0}\left(\Omega, x_{0}\right)}{\epsilon} .
\end{array}\right.
$$

3- Also, we can take: $\mu_{\epsilon}(x)=\eta_{0}(|x| / \epsilon)$ and $\eta_{\epsilon}(y)=\mu_{\epsilon}\left(f^{-1}(y)\right)$, we extend it by 0 outside $f\left(B_{1}(0)\right)$. We have $f\left(B_{1}(0)\right)=D_{1}\left(x_{0}\right), f\left(B_{\epsilon}(0)\right)=D_{\epsilon}\left(x_{0}\right)$ and $f\left(B_{\epsilon}^{+}\right)=D_{\epsilon}^{+}\left(x_{0}\right)$ with $f$ and $f^{-1}$ smooth diffeomorphism.

$$
\left\{\begin{array}{l}
\eta_{\epsilon} \equiv 1, \text { on athe connected set } J_{\epsilon}=f\left(I_{\epsilon}\right), 0<\epsilon<\delta / 2, \\
\eta_{\epsilon} \equiv 0, \text { outside } J_{\epsilon}^{\prime}=f\left(I_{2 \epsilon}\right), \\
0 \leq \eta_{\epsilon} \leq 1, \\
\left\|\nabla \eta_{\epsilon}\right\|_{L^{\infty}\left(J_{\epsilon}\right)} \leq \frac{C_{0}\left(\Omega, x_{0}\right)}{\epsilon} .
\end{array}\right.
$$

And, $H_{1}\left(J_{\epsilon}^{\prime}\right) \leq C_{1} H_{1}\left(I_{2 \epsilon}\right)=C_{1} 4 \epsilon$, since $f$ is Lipschitz. Here $H_{1}$ is the Hausdorff measure.

We solve the Dirichlet Problem:

$$
\left\{\begin{array}{clrl}
\Delta \bar{\eta}_{\epsilon} & =\Delta \eta_{\epsilon} & & \text { in } \Omega \subset \mathbb{R}^{2}, \\
\bar{\eta}_{\epsilon}=0 & & \text { in } \partial \Omega .
\end{array}\right.
$$

and finaly we set $\tilde{\eta}_{\epsilon}=-\bar{\eta}_{\epsilon}+\eta_{\epsilon}$. Also, by the maximum principle and the elliptic estimates we have :

$$
\left\|\nabla \tilde{\eta}_{\epsilon}\right\|_{L^{\infty}} \leq C\left(\left\|\eta_{\epsilon}\right\|_{L^{\infty}}+\left\|\nabla \eta_{\epsilon}\right\|_{L^{\infty}}+\left\|\Delta \eta_{\epsilon}\right\|_{L^{\infty}}\right) \leq \frac{C_{1}}{\epsilon^{2}},
$$

with $C_{1}$ depends on $\Omega$.
We use the following estimate, see $[4,8,14,25]$,

$$
\left\|\nabla u_{i}\right\|_{L^{q}} \leq C_{q}, \forall i \text { and } 1<q<2
$$

We deduce from the last estimate that, $\left(u_{i}\right)$ converge weakly in $W_{0}^{1, q}(\Omega)$, almost everywhere to a function $u \geq 0$ and $\int_{\Omega} e^{u}<+\infty$ (by Fatou lemma). Also, $V_{i}$ weakly converge to a nonnegative function $V$ in $L^{\infty}$. The function $u$ is in $W_{0}^{1, q}(\Omega)$ solution of :

$$
\left\{\begin{aligned}
\Delta u & =V\left(1+|x|^{2 \beta}\right) e^{u} \in L^{1}(\Omega) & & \text { in } \Omega \subset \mathbb{R}^{2}, \\
u & =0 & & \text { in } \partial \Omega .
\end{aligned}\right.
$$

According to the corollary 1 of Brezis-Merle's result, see [7], we have $e^{k u} \in L^{1}(\Omega), k>1$. By the elliptic estimates, we have $u \in C^{1}(\bar{\Omega})$.

For two vectors $f$ and $g$ we denote by $f \cdot g$ the inner product of $f$ and $g$.
We can write:

$$
\begin{equation*}
\Delta\left(\left(u_{i}-u\right) \tilde{\eta}_{\epsilon}\right)=\left(1+|x|^{2 \beta}\right)\left(V_{i} e^{u_{i}}-V e^{u}\right) \tilde{\eta}_{\epsilon}-2 \nabla\left(u_{i}-u\right) \cdot \nabla \tilde{\eta}_{\epsilon} . \tag{3.1}
\end{equation*}
$$

We use the interior esimate of Brezis-Merle, see [7],
Step 1: Estimate of the integral of the first term of the right hand side of (3.1).
We use the Green formula between $\tilde{\eta}_{\epsilon}$ and $u$, we obtain,

$$
\begin{equation*}
\int_{\Omega}\left(1+|x|^{2 \beta}\right) V e^{u} \tilde{\eta}_{\epsilon} d x=\int_{\partial \Omega} \partial_{\nu} u \eta_{\epsilon} \leq C^{\prime} \epsilon\left\|\partial_{\nu} u\right\|_{L^{\infty}}=C \epsilon \tag{3.2}
\end{equation*}
$$

We have,

$$
\left\{\begin{aligned}
\Delta u_{i} & =\left(1+|x|^{2 \beta}\right) V_{i} e^{u_{i}} & & \text { in } \Omega \subset \mathbb{R}^{2}, \\
u_{i} & =0 & & \text { in } \partial \Omega .
\end{aligned}\right.
$$

We use the Green formula between $u_{i}$ and $\tilde{\eta}_{\epsilon}$ to have:

$$
\begin{equation*}
\int_{\Omega}\left(1+|x|^{2 \beta}\right) V_{i} e^{u_{i}} \tilde{\eta}_{\epsilon} d x=\int_{\partial \Omega} \partial_{\nu} u_{i} \eta_{\epsilon} d \sigma \rightarrow \mu\left(\eta_{\epsilon}\right) \leq \mu\left(J_{\epsilon}^{\prime}\right) \leq 4 \pi-\epsilon_{0}, \epsilon_{0}>0 . \tag{3.3}
\end{equation*}
$$

From (3.2) and (3.3) we have for all $\epsilon>0$ there is $i_{0}=i_{0}(\epsilon)$ such that, for $i \geq i_{0}$,

$$
\begin{equation*}
\int_{\Omega}\left|\left(1+|x|^{2 \beta}\right)\left(V_{i} e^{u_{i}}-V e^{u}\right) \tilde{\eta}_{\epsilon}\right| d x \leq 4 \pi-\epsilon_{0}+C \epsilon . \tag{3.4}
\end{equation*}
$$

Step 2: Estimate of integral of the second term of the right hand side of (3.1).

Let $\Sigma_{\epsilon}=\left\{x \in \Omega, d(x, \partial \Omega)=\epsilon^{3}\right\}$ and $\Omega_{\epsilon^{3}}=\left\{x \in \Omega, d(x, \partial \Omega) \geq \epsilon^{3}\right\}, \epsilon>0$. Then, for $\epsilon$ small enough, $\Sigma_{\epsilon}$ is hypersurface.

The measure of $\Omega-\Omega_{\epsilon^{3}}$ is $k_{2} \epsilon^{3} \leq \operatorname{meas}\left(\Omega-\Omega_{\epsilon^{3}}\right)=\mu_{L}\left(\Omega-\Omega_{\epsilon^{3}}\right) \leq k_{1} \epsilon^{3}$.
Remark: For the unit ball $\bar{B}(0,1)$, our new manifold is $\bar{B}\left(0,1-\epsilon^{3}\right)$.
(Proof of this fact; let's consider $d(x, \partial \Omega)=d\left(x, z_{0}\right), z_{0} \in \partial \Omega$, this imply that $\left(d\left(x, z_{0}\right)\right)^{2} \leq$ $(d(x, z))^{2}$ for all $z \in \partial \Omega$ which it is equivalent to $\left(z-z_{0}\right) \cdot\left(2 x-z-z_{0}\right) \leq 0$ for all $z \in \partial \Omega$, let's consider a chart around $z_{0}$ and $\gamma(t)$ a curve in $\partial \Omega$, we have;
$\left(\gamma(t)-\gamma\left(t_{0}\right) \cdot\left(2 x-\gamma(t)-\gamma\left(t_{0}\right)\right) \leq 0\right.$ if we divide by $\left(t-t_{0}\right)$ (with the sign and tend $t$ to $\left.t_{0}\right)$, we have $\gamma^{\prime}\left(t_{0}\right) \cdot\left(x-\gamma\left(t_{0}\right)\right)=0$, this imply that $x=z_{0}-s v_{0}$ where $v_{0}$ is the outward normal of $\partial \Omega$ at $\left.z_{0}\right)$ ).

With this fact, we can say that $S=\{x, d(x, \partial \Omega) \leq \epsilon\}=\left\{x=z_{0}-s v_{z_{0}}, z_{0} \in \partial \Omega,-\epsilon \leq s \leq \epsilon\right\}$. It is sufficient to work on $\partial \Omega$. Let's consider a charts $\left(z, D=B\left(z, 4 \epsilon_{z}\right), \gamma_{z}\right)$ with $z \in \partial \Omega$ such that $\cup_{z} B\left(z, \epsilon_{z}\right)$ is cover of $\partial \Omega$. One can extract a finite $\operatorname{cover}\left(B\left(z_{k}, \epsilon_{k}\right)\right), k=1, \ldots, m$, by the area formula the measure of $S \cap B\left(z_{k}, \epsilon_{k}\right)$ is less than a $k \epsilon$ (a $\epsilon$-rectangle). For the reverse inequality, it is sufficient to consider one chart around one point of the boundary).

We write,

$$
\begin{equation*}
\int_{\Omega}\left|\nabla\left(u_{i}-u\right) \cdot \nabla \tilde{\eta}_{\epsilon}\right| d x=\int_{\Omega_{\epsilon^{3}}}\left|\nabla\left(u_{i}-u\right) \cdot \nabla \tilde{\eta}_{\epsilon}\right| d x+\int_{\Omega-\Omega_{\epsilon^{3}}}\left|\nabla\left(u_{i}-u\right) \cdot \nabla \tilde{\eta}_{\epsilon}\right| d x . \tag{3.5}
\end{equation*}
$$

Step 2.1: Estimate of $\int_{\Omega-\Omega_{\epsilon^{3}}}\left|\nabla\left(u_{i}-u\right) \cdot \nabla \tilde{\eta}_{\epsilon}\right| d x$.
First, we know from the elliptic estimates that $\left\|\nabla \tilde{\eta}_{\epsilon}\right\|_{L^{\infty}} \leq C_{1} / \epsilon^{2}, C_{1}$ depends on $\Omega$
We know that $\left(\mid \nabla u_{i}\right)_{i}$ is bounded in $L^{q}, 1<q<2$, we can extract from this sequence a subsequence which converge weakly to $h \in L^{q}$. But, we know that we have locally the uniform convergence to $|\nabla u|$ (by Brezis-Merle's theorem), then, $h=|\nabla u|$ a.e. Let $q^{\prime}$ be the conjugate of $q$.

We have, $\forall f \in L^{q^{\prime}}(\Omega)$

$$
\int_{\Omega}\left|\nabla u_{i}\right| f d x \rightarrow \int_{\Omega}|\nabla u| f d x
$$

If we take $f=1_{\Omega-\Omega_{\epsilon^{3}}}$, we have:

$$
\text { for } \epsilon>0 \exists i_{1}=i_{1}(\epsilon) \in \mathbb{N}, i \geq i_{1}, \int_{\Omega-\Omega_{\epsilon^{3}}}\left|\nabla u_{i}\right| \leq \int_{\Omega-\Omega_{\epsilon^{3}}}|\nabla u|+\epsilon^{3} .
$$

Then, for $i \geq i_{1}(\epsilon)$,

$$
\int_{\Omega-\Omega_{\epsilon^{3}}}\left|\nabla u_{i}\right| \leq \operatorname{meas}\left(\Omega-\Omega_{\epsilon^{3}}\right)\|\nabla u\|_{L^{\infty}}+\epsilon^{3}=\epsilon^{3}\left(k_{1}\|\nabla u\|_{L^{\infty}}+1\right) .
$$

Thus, we obtain,

$$
\begin{equation*}
\int_{\Omega-\Omega_{\epsilon^{3}}}\left|\nabla\left(u_{i}-u\right) \cdot \nabla \tilde{\eta}_{\epsilon}\right| d x \leq \epsilon C_{1}\left(2 k_{1}\|\nabla u\|_{L^{\infty}}+1\right) \tag{3.6}
\end{equation*}
$$

The constant $C_{1}$ does not depend on $\epsilon$ but on $\Omega$.
Step 2.2: Estimate of $\int_{\Omega_{\epsilon^{3}}}\left|\nabla\left(u_{i}-u\right) \cdot \nabla \tilde{\eta}_{\epsilon}\right| d x$.
We know that, $\Omega_{\epsilon} \subset \subset \Omega$, and ( because of Brezis-Merle's interior estimates) $u_{i} \rightarrow u$ in $C^{1}\left(\Omega_{\epsilon^{3}}\right)$. We have,

$$
\left\|\nabla\left(u_{i}-u\right)\right\|_{L^{\infty}\left(\Omega_{\epsilon^{3}}\right)} \leq \epsilon^{3}, \text { for } i \geq i_{3}=i_{3}(\epsilon) .
$$

We write,

$$
\int_{\Omega_{\epsilon^{3}}}\left|\nabla\left(u_{i}-u\right) \cdot \nabla \tilde{\eta}_{\epsilon}\right| d x \leq\left\|\nabla\left(u_{i}-u\right)\right\|_{L^{\infty}\left(\Omega_{\epsilon^{3}}\right)}\left\|\nabla \tilde{\eta}_{\epsilon}\right\|_{L^{\infty}} \leq C_{1} \epsilon \text { for } i \geq i_{3},
$$

For $\epsilon>0$, we have for $i \in \mathbb{N}, i \geq \max \left\{i_{1}, i_{2}, i_{3}\right\}$,

$$
\begin{equation*}
\int_{\Omega}\left|\nabla\left(u_{i}-u\right) \cdot \nabla \tilde{\eta}_{\epsilon}\right| d x \leq \epsilon C_{1}\left(2 k_{1}\|\nabla u\|_{L^{\infty}}+2\right) \tag{3.7}
\end{equation*}
$$

From (3.4) and (3.7), we have, for $\epsilon>0$, there is $i_{3}=i_{3}(\epsilon) \in \mathbb{N}, i_{3}=\max \left\{i_{0}, i_{1}, i_{2}\right\}$ such that,

$$
\begin{equation*}
\int_{\Omega}\left|\Delta\left[\left(u_{i}-u\right) \tilde{\eta}_{\epsilon}\right]\right| d x \leq 4 \pi-\epsilon_{0}+\epsilon 2 C_{1}\left(2 k_{1}\|\nabla u\|_{L^{\infty}}+2+C\right) \tag{3.8}
\end{equation*}
$$

We choose $\epsilon>0$ small enough to have a good estimate of (3.1).
Indeed, we have:

$$
\left\{\begin{array}{cl}
\Delta\left[\left(u_{i}-u\right) \tilde{\eta}_{\epsilon}\right]=g_{i, \epsilon} & \text { in } \Omega \subset \mathbb{R}^{2}, \\
\left(u_{i}-u\right) \tilde{\eta}_{\epsilon}=0 & \\
\text { in } \partial \Omega .
\end{array}\right.
$$

with $\left\|g_{i, \epsilon}\right\|_{L^{1}(\Omega)} \leq 4 \pi-\frac{\epsilon_{0}}{2}$.
We can use Theorem 1 of [7] to conclude that there are $q \geq \tilde{q}>1$ such that:

$$
\int_{V_{\epsilon}\left(x_{0}\right)} e^{\tilde{\tilde{q}\left|u_{i}-u\right|}} d x \leq \int_{\Omega} e^{q\left|u_{i}-u\right| \tilde{\eta}_{\epsilon}} d x \leq C(\epsilon, \Omega) .
$$

where, $V_{\epsilon}\left(x_{0}\right)$ is a neighberhood of $x_{0}$ in $\bar{\Omega}$. Here we have used that in a neighborhood of $x_{0}$ by the elliptic estimates, $1-C \epsilon \leq \tilde{\eta}_{\epsilon} \leq 1$. (We can take $B\left(x_{0}, \epsilon^{3}\right)$ ).

Thus, for each $x_{0} \in \partial \Omega-\left\{\bar{x}_{1}, \ldots, \bar{x}_{m}\right\}$ there is $\epsilon_{x_{0}}>0, q_{x_{0}}>1$ such that:

$$
\begin{equation*}
\int_{B\left(x_{0}, \epsilon_{x_{0}}\right)} e^{q_{x_{0}} u_{i}} d x \leq C, \forall i . \tag{3.9}
\end{equation*}
$$

Now, we consider a cutoff function $\eta \in C^{\infty}\left(\mathbb{R}^{2}\right)$ such that

$$
\eta \equiv 1 \text { on } B\left(x_{0}, \epsilon_{x_{0}} / 2\right) \text { and } \eta \equiv 0 \text { on } \mathbb{R}^{2}-B\left(x_{0}, 2 \epsilon_{x_{0}} / 3\right) .
$$

We write

$$
\Delta\left(u_{i} \eta\right)=\left(1+|x|^{2 \beta}\right) V_{i} e^{u_{i}} \eta-2 \nabla u_{i} \cdot \nabla \eta+u_{i} \Delta \eta .
$$

By the elliptic estimates (see [15]) $\left(u_{i}\right)_{i}$ is uniformly bounded in $W^{2, q_{1}}\left(V_{\epsilon}\left(x_{0}\right)\right)$ and also, in $C^{1}\left(V_{\epsilon}\left(x_{0}\right)\right)$. Finaly, we have, for some $\epsilon>0$ small enough,

$$
\left\|u_{i}\right\|_{C^{1, \theta}\left[B\left(x_{0}, \epsilon\right)\right]} \leq c_{3} \forall i .
$$

We have proved that, there is a finite number of points $\bar{x}_{1}, \ldots, \bar{x}_{m}$ such that the squence $\left(u_{i}\right)_{i}$ is locally uniformly bounded (in $C^{1, \theta}, \theta>0$ ) in $\bar{\Omega}-\left\{\bar{x}_{1}, \ldots, \bar{x}_{m}\right\}$.

## 4 Proof of theorem 2.2.

Without loss of generality, we can assume that 0 is a blow-up point. Since the boundary is an analytic curve $\gamma(t)$, there is a neighborhood of 0 such that the curve $\gamma$ can be extend to a holomorphic map such that $\gamma^{\prime}(0) \neq 0$ (series) and by the inverse mapping one can assume that this map is univalent around 0 . In the case when the boundary is a simple Jordan curve the domain is simply connected, see [24]. In the case that the domains has a finite number of holes it is conformally equivalent to a disk with a finite number of disks removed, see [17]. Here we consider a general domain. Without loss of generality one can assume that $\gamma\left(B_{1}^{+}\right) \subset \Omega$ and also $\gamma\left(B_{1}^{-}\right) \subset(\bar{\Omega})^{c}$ and $\gamma(-1,1) \subset \partial \Omega$ and $\gamma$ is univalent. This means that $\left(B_{1}, \gamma\right)$ is a local chart around 0 for $\Omega$ and $\gamma$ univalent. (This fact holds if we assume that we have an analytic domain, in the sense of Hofmann see [16], (below a graph of an analytic function), we have necessary the condition $\partial \bar{\Omega}=\partial \Omega$ and the graph is analytic, in this case $\gamma(t)=(t, \phi(t))$ with $\phi$ real analytic and an example of this fact is the unit disk around the point $(0,1)$ for example).

By this conformal transformation, we can assume that $\Omega=B_{1}^{+}$, the half ball, and $\partial^{+} B_{1}^{+}$ is the exterior part, a part which not contain 0 and on which $u_{i}$ converge in the $C^{1}$ norm to $u$. Let us consider $B_{\epsilon}^{+}$, the half ball with radius $\epsilon>0$. Also, one can consider a $C^{1}$ domain (a rectangle between two half disks) and by charts its image is a $C^{1}$ domain).

We know that:

$$
u_{i} \in C^{2, \epsilon}(\bar{\Omega})
$$

Thus we can use integrations by parts (Gauss-Green-Riemann-Stokes formula). The second Pohozaev identity applied around the blow-up 0 see for example [2, 20, 22] gives :

$$
\begin{equation*}
\int_{B_{\epsilon}^{+}} \Delta u_{i}\left(x \cdot \nabla u_{i}\right) d x=-\int_{\partial^{+} B_{\epsilon}^{+}} g\left(\nabla u_{i}\right) d \sigma \tag{4.1}
\end{equation*}
$$

with,

$$
g\left(\nabla u_{i}\right)=\left(v \cdot \nabla u_{i}\right)\left(x \cdot \nabla u_{i}\right)-x \cdot v \frac{\left|\nabla u_{i}\right|^{2}}{2}
$$

Thus,

$$
\begin{equation*}
\int_{B_{\epsilon}^{+}} V_{i}\left(1+|x|^{2 \beta}\right) e^{u_{i}}\left(x \cdot \nabla u_{i}\right) d x=-\int_{\partial^{+} B_{\epsilon}^{+}} g\left(\nabla u_{i}\right) d \sigma \tag{4.2}
\end{equation*}
$$

After integration by parts, we obtain:

$$
\begin{gather*}
\int_{B_{\epsilon}^{+}} 2 V_{i}\left(1+(1+\beta)|x|^{2 \beta}\right) e^{u_{i}} d x+\int_{B_{\epsilon}^{+}} x \cdot \nabla V_{i}\left(1+|x|^{2 \beta}\right) e^{u_{i}} d x-\int_{\partial B_{\epsilon}^{+}} v \cdot x\left(1+|x|^{2 \beta}\right) V_{i} e^{u_{i}} d \sigma= \\
=\int_{\partial^{+} B_{\epsilon}^{+}} g\left(\nabla u_{i}\right) d \sigma \tag{4.3}
\end{gather*}
$$

Also, for $u$ we have:

$$
\begin{gather*}
\int_{B_{\epsilon}^{+}} 2 V\left(1+(1+\beta)|x|^{2 \beta}\right) e^{u} d x+\int_{B_{\epsilon}^{+}} x \cdot \nabla V\left(1+|x|^{2 \beta}\right) e^{u} d x-\int_{\partial B_{\epsilon}^{+}} v \cdot x\left(1+|x|^{2 \beta}\right) V e^{u} d \sigma= \\
=\int_{\partial^{+} B_{\epsilon}^{+}} g(\nabla u) d \sigma \tag{4.4}
\end{gather*}
$$

We use the fact that $u_{i}=u=0$ on $\left\{x_{1}=0\right\}$ and $u_{i}, u$ are bounded in the $C^{1}$ norm outside a neighborhood of 0 and we tend $i$ to $+\infty$ and then $\epsilon$ to 0 to obtain:

$$
\begin{equation*}
\int_{B_{\epsilon}^{+}} V_{i}\left(1+|x|^{2 \beta}\right) e^{u_{i}} d x=o(1)+O(\epsilon) \tag{4.5}
\end{equation*}
$$

however

$$
\begin{equation*}
\int_{\gamma\left(B_{\epsilon}^{+}\right)} V_{i}\left(1+|x|^{2 \beta}\right) e^{u_{i}} d x=\int_{\partial \gamma\left(B_{\epsilon}^{+}\right)} \partial_{\nu} u_{i} d \sigma=\alpha_{1}+O(\epsilon)+o(1)>0, \tag{4.6}
\end{equation*}
$$

which is a contradiction.
Here we have used a theorem of Hofmann see [16], which gives the fact that $\gamma\left(B_{\epsilon}^{+}\right)$is a Lipschitz domain. Also, we can see that $\gamma((-\epsilon, \epsilon))$ and $\gamma\left(\partial^{+} B_{\epsilon}^{+}\right)$are submanifolds.

We start with a Lipschitz domain $B_{\epsilon}^{+}$because it is convex and by the univalent and conformal map $\gamma$ the image of this domain $\gamma\left(B_{\epsilon}^{+}\right)$is a Lipschitz domain and thus we can apply the integration by part and here we know the explicit formula of the unit outward normal it is the usual unit outward normal (normal to the tangent space of the boundary which we know explicitly because we have two submanifolds).

In the case of the disk $D=\Omega$, it is sufficient to consider $B(0, \epsilon) \cap D$ which is a Lipschitz domain because it is convex (and not necessarily $\gamma\left(B_{\epsilon}^{+}\right)$).

There is a version of the integration by part which is the Green-Riemann formula in dimension 2 on a domain $\Omega$. This formula holds if we assume that there is a finite number of points $y_{1}, \ldots, y_{m}$ such that $\partial \Omega-\left(y_{1}, \ldots, y_{m}\right)$ is a $C^{1}$ manifold and for $C^{1}$ tests functions, see [2], for the Gauss-Green-Riemann-Stokes formula, for $C^{1}$ domains with singular points (here a finite number of singular points).

Remark: Note that a monograph of Droniou contain a proof of all fact about Sobolev spaces (with Strong Lipschitz property) with only weak Lipschitz property (LipschitzCharts), we start with Strong Lipschitz property and by $\gamma$ we have weak Lipschtz property.

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