# On reduction of finite-sample variance by extended Latin hypercube sampling 

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#### Abstract

McKay, Conover and Beckman introduced Latin hypercube sampling (LHS) for reducing the variance of Monte Carlo simulations. LHS is a method for stratifying a univariate margin. We consider an extension of LHS to stratify an $m$-variate margin with orthogonal arrays, after Owen and Tang. We define extended Latin hypercube sampling of strength $m$ (henceforth denoted by ELHS $(m)$ ), such that ELHS(1) reduces to LHS. Using the results obtained by Owen, we first derive an explicit formula for the finite-sample variance of $\operatorname{ELHS}(m)$. Based on this formula, we give a sufficient condition for variance reduction by $\operatorname{ELHS}(m)$, generalizing similar results from McKay et al. for $m=1$. Actually, our sufficient condition for $m=1$ contains the sufficient condition of McKay et al. and thus strengthens their result.


Keywords: computer experiments; Monte Carlo simulation; numerical integration; orthogonal arrays; variance reduction

## 1. Introduction

Monte Carlo simulation is often used to evaluate the expectation of a statistic $W=$ $g\left(X_{1}, \ldots, X_{K}\right)$, which is not analytically tractable. In most Monte Carlo simulations simple random sampling (SRS) is used to generate sample points. SRS is widely applicable because of its simplicity. However, its sampling variance is often large and many replications are needed to achieve the desired precision. Therefore methods for reducing the sampling variance of SRS are of great importance.

One way of reducing SRS variance is to scatter the sample points more uniformly than in SRS. This is the basic idea of various techniques known as quasi-Monte Carlo methods (for a review, see Niederreiter 1992). We can achieve uniformity by stratifying the sample space. Latin hypercube sampling (LHS) is a method for stratifying each univariate margin simultaneously. It is natural to define extended Latin hypercube sampling ELHS $(m)$ of strength $m, m \leqslant K$, by stratifying an $m$-variate margin simultaneously, such that ELHS (1) is equivalent to LHS. The desired stratification property can be achieved by sampling designs based on orthogonal arrays (OAs) proposed by Owen (1992a) and independently by Tang (1993). ELHS is a particular version of OA-based sampling.

The reduction of variance by LHS and ELHS is closely related to analysis of variance (ANOVA) decomposition of the statistic $W$. Stein (1987) showed that LHS asymptotically
filters out main effects of $W$. Therefore LHS asymptotically achieves variance reduction for any statistic $W$. Similarly, OA-based sampling asymptotically filters some higher-order interactions as well, and hence asymptotically achieves further variance reduction for any statistic. However, for the finite-sample case, LHS and its generalizations do not necessarily lead to variance reduction due to combinatorial complications.

In order to investigate the reduction of finite-sample variance, we first derive an explicit expression for the finite-sample variance of $\operatorname{ELHS}(m)$ based on the results obtained by Owen (1994a). Using this expression, we derive a sufficient condition for the variance reduction of $\operatorname{ELHS}(m)$ over SRS. Our sufficient condition is given in terms of $m$-variate monotonicity of the statistic $g\left(X_{1}, \ldots, X_{K}\right)$. For the case of $m=1$, our sufficient condition requires that $g$ is monotone in any $K-1$ out of $K$ variables $X_{1}, \ldots, X_{K}$. The sufficient condition given by McKay et al. (1979) requires that $g$ is monotone in each $X_{i}$, $i=1, \ldots, K$. Thus our result for $m=1$ strengthens the results of McKay et al. (1979).

The organization of this paper is as follows. In Section 2 we define $\operatorname{ELHS}(m)$ and introduce appropriate notational conventions. In Section 3 we derive explicit expression for the finite-sample variance of $\operatorname{ELHS}(m)$. Based on this expression, we give a sufficient condition for reduction of finite-sample variance of $\operatorname{ELHS}(m)$ over SRS in Section 4. In Section 5 we perform some numerical simulations to confirm our theoretical results. In Section 6 we make some additional comments on LHS and OA-based sampling.

## 2. Construction of extended Latin hypercube sampling

In this section we explicitly describe our $\operatorname{ELHS}(m)$, which is a particular version of Owen's generalization of LHS. We evaluate the expectation of a statistic $W=g\left(X_{1}, \ldots, X_{K}\right)$ :

$$
\mu=\mathrm{E}(W)=\mathrm{E}\left[g\left(X_{1}, \ldots, X_{K}\right)\right],
$$

where $\left(X_{1}, \ldots, X_{K}\right) \in \mathbb{R}^{K}$. We assume that $X_{1}, \ldots, X_{K}$ are independent continuous random variables with known distribution functions $F_{j}, j=1, \ldots, K$. The vector $\left(X_{1}, \ldots, X_{K}\right)=\mathbf{X}$ has the joint distribution function $F=F_{1} \cdots F_{K}$.

Suppose that the evaluation of this expectation is analytically intractable and we use a Monte Carlo method. In our extended Latin hypercube sampling defined below, the sample points are generated in two steps. For the first step, we partition the sample space $\mathbb{R}^{K}$ into $N^{K}$ cells of equal probability $1 / N^{K}$ and choose $N^{m}, m \leqslant K$, cells of $N^{K}$ cells using a random OA. For the second step the actual sample points are generated according to the conditional distribution on the chosen cells.

We now describe the first step. A $\lambda N^{m} \times K$ matrix $\mathbf{D}$, with elements taken from a set of $N$ symbols, is called an orthogonal array of strength $m(m \leqslant K)$, size $\lambda N^{m}, K$ constraints, $N$ levels and frequency $\lambda$, if in any $\lambda N^{m} \times m$ submatrix of $\mathbf{D}$ each of the possible $1 \times m$ row vectors occurs the same number $\lambda$ of times. Such an array is denoted by $\mathrm{OA}\left(\lambda N^{m}, K, N, m\right)$. Without essential loss of generality, we only consider the case $\lambda=1$ as in the original LHS of McKay et al. (1979).

The orthogonal array is a natural generalization of orthogonal Latin squares. Plackett and Burman (1946) generated OAs of strength 2 by combining mutually orthogonal Latin
squares. Rao (1947) formulated the concept of OAs in general form and gave a lower bound of $N$ for fixed $m, K$. Bose and Bush (1952) explained how to construct OAs and gave sufficient conditions for the existence of OAs, since they do not always exist.

We arbitrarily choose and fix an orthogonal array $\mathrm{OA}\left(N^{m}, K, N, m\right)$ and denote it by $\mathbf{D}$. The $i j$ th element of $\mathbf{D}$ is denoted by $d_{i j}$. We call $\mathbf{D}$ a generator array. Actually we will show that the selection of $\mathbf{D}$ does not affect the variance of $\operatorname{ELHS}(m)$. We generate random OAs by random permutations of elements of $\mathbf{D}$. For simplicity of notation, we take the set of $N$ symbols as

$$
Z_{N}=\{1,2,3, \ldots, N\} .
$$

Let $\mathscr{S}_{N}$ denote the symmetric group of $Z_{N}$, that is, the set of permutations of $\{1, \ldots, N\}$. Let $\pi \in \mathscr{S}_{N}$; then $(\pi(1), \ldots, \pi(N))$ is a particular permutation of $(1, \ldots, N)$. We choose $K$ permutations $\pi_{j}, j=1, \ldots, K$, independently and uniformly from $\mathscr{S}_{N}$ and we apply $\pi_{j} \in \mathscr{S}_{N}$ to the $j$ th column of $\mathbf{D}, j=1, \ldots, K$. The resulting array is denoted by $\Pi(\mathbf{D})$, with $i j$ th element $\pi_{j}\left(d_{i j}\right)$. This constitutes the first step of generating the sample points.

Let $F_{j}^{-1}(u)=\inf \left\{x \mid F_{j}(x) \geqslant u\right\}, j=1, \ldots, K$, be the quantile functions, and for $\mathbf{z}=$ $\left(z_{1}, z_{2}, \ldots, z_{K}\right) \in Z_{N}^{K}$ let

$$
P^{(\mathrm{z})}=F_{1}^{-1}\left(\left(\frac{z_{1}-1}{N}, \frac{z_{1}}{N}\right]\right) \times \cdots \times F_{K}^{-1}\left(\left(\frac{z_{K}-1}{N}, \frac{z_{K}}{N}\right]\right) \subset \mathbb{R}^{K},
$$

which is a cell of $\mathbb{R}^{K}$ with probability $1 / N^{K}$. When $\pi_{j}, j=1, \ldots, K$, are given we denote the $i$ th row of $\Pi(\mathbf{D})$ by

$$
z_{i j}=\pi_{j}\left(d_{i j}\right), \quad z_{i}=\left(z_{i 1}, z_{i 2}, \ldots, z_{i K}\right) \in Z_{N}^{K} .
$$

For the second step we generate a random vector $\left(X_{i 1}, \ldots, X_{i K}\right)$ in the cell $P^{\left(z_{i}\right)}$ according to the conditional distribution of $F$ on the cell. Let $0<U_{i j} \leqslant 1, i=1, \ldots, N^{m}, j=1, \ldots, K$, be independent uniform random variables. Then $X_{i j}$ can be generated as

$$
X_{i j}=F_{j}^{-1}\left\{\left(z_{i j}-U_{i j}\right) / N\right\} .
$$

We now define our estimator $T_{\mathrm{EL}}$ of $\mu$ based on $\operatorname{ELHS}(m)$ by

$$
T_{\mathrm{EL}}=\frac{1}{N^{m}} \sum_{i=1}^{N^{m}} g\left(X_{i 1}, \ldots, X_{i K}\right) .
$$

Obviously $T_{\mathrm{EL}}$ is an unbiased estimator of $\mu$.
Furthermore we denote the usual estimator of $\mu$ based on SRS by $T_{\mathrm{R}}$. We are interested in the comparison of variances of $T_{\mathrm{EL}}$ and $T_{\mathrm{R}}$.

## 3. Finite-sample variance of ELHS

### 3.1. ANOVA decomposition of the cell mean function

In order to investigate the variance of $T_{\mathrm{EL}}$, we introduce the cell mean function and its ANOVA decomposition. The cell $P^{(\mathbf{z})}$ is indexed by $\mathbf{z}=\left(z_{1}, z_{2}, \ldots, z_{K}\right) \in Z_{N}^{K}$. In an abuse of
notation, we simply denote the cell as $\mathbf{z}=\left(z_{1}, z_{2}, \ldots, z_{K}\right) \in Z_{N}^{K}$. Suppose that a sample point $\mathbf{X}$ is obtained from a cell $\mathbf{z}$. We call the conditional expectation $\mathrm{E}[g(\mathbf{X}) \mid \mathbf{z}]$ the cell mean function and denote it by

$$
\mu_{\mathbf{z}}=\mathrm{E}[g(\mathbf{X}) \mid \mathbf{z}]=N^{K} \int_{P^{(z)}} g(\mathbf{X}) f(\mathbf{X}) \mathrm{d} \mathbf{X}
$$

where $f(\mathbf{X})$ is the density function of $\mathbf{X}$.
We denote the usual ANOVA decomposition of the cell mean function by

$$
\begin{aligned}
\mu_{z_{1} z_{2} \ldots z_{K}} & -\mu \\
& =\sum_{i=1}^{K} \alpha_{1}\left(z_{i}\right)+\sum_{i_{1}<i_{2}} \alpha_{2}\left(z_{i_{1}}, z_{i_{2}}\right)+\sum_{i_{1}<i_{2}<i_{3}} \alpha_{3}\left(z_{i_{1}}, z_{i_{2}}, z_{i_{3}}\right)+\ldots+\alpha_{K}\left(z_{i_{1}}, \ldots, z_{i_{K}}\right),
\end{aligned}
$$

where

$$
\begin{aligned}
\alpha_{1}\left(z_{i}\right) & =\frac{1}{N^{K-1}} \sum_{z_{1}=1}^{N} \cdots \sum_{z_{i-1}=1}^{N} \sum_{z_{i+1}=1}^{N} \cdots \sum_{z_{K}=1}^{N}\left(\mu_{z_{1} z_{2} \ldots z_{K}}-\mu\right), \\
\alpha_{2}\left(z_{i_{1}}, z_{i_{2}}\right) & =\frac{1}{N^{K-2}} \sum_{\substack{j=1 \\
j \neq i_{1}, i_{2}}}^{K} \sum_{z_{j}=1}^{N}\left(\mu_{z_{1} z_{2} \ldots z_{K}}-\mu-\alpha_{1}\left(z_{i_{1}}\right)-\alpha_{1}\left(z_{i_{2}}\right)\right),
\end{aligned}
$$

and we continue this process to $\alpha_{K}$. In each $\alpha_{s}\left(z_{i_{1}}, \ldots, z_{i_{s}}\right),\left(z_{1}, \ldots, z_{K}\right)$ is to be summed over all $K$-vectors in $Z_{N}^{K}$ with the values of $z_{i_{1}}, \ldots, z_{i_{s}}$ fixed and all other coordinates free. Summation over $z_{i}$ is always taken from 1 to $N$, and we henceforth omit the range $1 \leqslant z_{i} \leqslant N$ from the summation signs.

We denote the sum of squares of $s$ th-order interaction effects by

$$
\varphi_{s}^{2}=\frac{1}{N^{s}} \sum_{i_{1}<\ldots<i_{s}} \sum_{z_{i_{1}}} \cdots \sum_{z_{i_{s}}} \alpha_{s}\left(z_{i_{1}}, \ldots, z_{i_{s}}\right)^{2} .
$$

Then $\operatorname{var}\left(T_{\mathrm{R}}\right)$ can be written as

$$
\begin{align*}
\operatorname{var}\left(T_{\mathrm{R}}\right) & =\frac{1}{N^{m}}\left\{\operatorname{var}\left(\mu_{\mathbf{z}}\right)+\mathrm{E}_{\mathbf{z}}[\operatorname{var}(g(\mathbf{X}) \mid \mathbf{z})]\right\} \\
& =\frac{1}{N^{m}} \sum_{s=1}^{K} \varphi_{s}^{2}+\nabla \tag{1}
\end{align*}
$$

where

$$
\nabla=\frac{1}{N^{m}} \mathrm{E}_{\mathbf{z}}[\operatorname{var}(g(\mathbf{X}) \mid \mathbf{z})]
$$

(see Serfling 1980, Section 5.2).

### 3.2. The variance of estimators using ELHS

For any $N^{m} \times s$ subarray $\mathbf{A}=\left\{a_{i j}\right\}, i=1, \ldots, N^{m}, j=1, \ldots, s$, of the generator array $\mathbf{D}$, define

$$
L(s, h)=\sum_{i=1}^{N^{m}} \sum_{l=1}^{N^{m}} I\left(\sum_{j=1}^{s} I\left(a_{i j}=a_{l j}\right)=h\right), \quad 0 \leqslant h \leqslant s
$$

where $I$ is an indicator function. We can interpret $L(s, h)$ as the number of pairs of rows of $\mathbf{A}$ with exactly $h$ common elements. By symmetry among the columns of $\mathbf{D}, L(s, h)$ is common to all $N^{m} \times s$ subarrays $\mathbf{A}$. Theorem 1 of Owen (1994a) implies that

$$
\begin{equation*}
\operatorname{var}\left(T_{\mathrm{EL}}\right)=\frac{1}{N^{2 m}} \sum_{s=m+1}^{K} \sum_{h=0}^{s} L(s, h)(1-N)^{h-s} \varphi_{s}^{2}+\nabla \tag{2}
\end{equation*}
$$

Owen (1994a) does not give an explicit form for $L(s, h)$. We obtain an explicit form of $L(s, h)$, which leads to Theorem 1 below. We have given an alternative proof of (3) in the preprint form of this paper (Hoshino and Takemura 1997) available from us.

## Theorem 1.

$$
\begin{equation*}
\operatorname{var}\left(T_{\mathrm{EL}}\right)=\frac{1}{N^{m}} \sum_{s=m+1}^{K} \varphi_{s}^{2}\left\{1-(1-N)^{1-s} \sum_{u=0}^{m-1}(-N)^{u}\binom{s-1}{u}\right\}+\nabla \tag{3}
\end{equation*}
$$

Note that in (3) interaction effects up to order $m$, that is, $\varphi_{s}^{2}, s=1, \ldots, m$, are cancelled out. This has to be the case for $\operatorname{ELHS}(m)$. In $\operatorname{ELHS}(m)$ we stratify an $m$-variate margin, such that for $s \leqslant m$ all elements of $Z_{N}^{S}$ appear an equal number of times in each combination of $s$ axes. In view of $\sum_{z_{i_{1}}} \cdots \sum_{z_{i_{s}}} \alpha_{s}\left(z_{i_{1}}, \ldots, z_{i_{s}}\right)=0$, interaction effects of the cell mean function up to order $m$ vanish for each realization of $T_{\mathrm{EL}}$. Expression (3) may also be written as

$$
\operatorname{var}\left(T_{\mathrm{EL}}\right)=\frac{1}{N^{m}} \sum_{s=m+1}^{K} \varphi_{s}^{2}\left\{\left(1-N^{-1}\right)^{1-s} \sum_{u=0}^{s-m-1}\binom{s-1}{u}(-N)^{-u}\right\}+\nabla
$$

using the fact that $1=(1-N)^{1-s} \sum_{u=0}^{s-1}(-N)^{u}\binom{s-1}{u}$. This expression was suggested to us by a referee.

Theorem 1 is an immediate consequence of the following two lemmas, whose proofs are given in Appendix A.

Lemma 1. Let $m<s \leqslant K$. For $0 \leqslant h \leqslant m-1$,

$$
\begin{equation*}
L(s, h)=\binom{s}{h} \sum_{t=0}^{m-h-1}(-1)^{t}\left(N^{m-h-t}-1\right)\binom{s-h}{t} N^{m} \tag{4}
\end{equation*}
$$

$L(s, h)=0$ for $m \leqslant h \leqslant s-1$, and $L(s, s)=N^{m}$.

Combining Lemma 1 and (2),

$$
\begin{equation*}
\operatorname{var}\left(T_{\mathrm{EL}}\right)=\frac{1}{N^{m}} \sum_{s>m}\left(\sum_{h=0}^{m-1}(1-N)^{h-s}\binom{s}{h} \sum_{t=0}^{m-h-1}(-1)^{t}\left(N^{m-h-t}-1\right)\binom{s-h}{t}+1\right) \varphi_{s}^{2} \tag{5}
\end{equation*}
$$

The coefficients of $\varphi_{s}^{2}$ in (5) can be simplified as follows.
Lemma 2. For $m<s \leqslant K$,

$$
\begin{align*}
& \sum_{h=0}^{m-1}(1-N)^{h-s}\binom{s}{h} \sum_{t=0}^{m-h-1}(-1)^{t}\left(N^{m-h-t}-1\right)\binom{s-h}{t}+1 \\
& \quad=1-(1-N)^{1-s} \sum_{u=0}^{m-1}(-N)^{u}\binom{s-1}{u} \tag{6}
\end{align*}
$$

## 4. A sufficient condition for variance reduction

In this section we obtain a sufficient condition for the variance reduction $\operatorname{var}\left(T_{\mathrm{EL}}\right) \leqslant \operatorname{var}\left(T_{\mathrm{R}}\right)$. McKay et al. (1979) showed that monotonicity of $g\left(X_{1}, \ldots, X_{K}\right)$ in each argument $X_{i}$, $i=1, \ldots, K$, is a sufficient condition for the variance reduction at $m=1$. Here $g(\mathbf{X})$ is monotone in $X_{i}$ if $g(\mathbf{X})$, regarded as a function of the $i$ th argument (with all other arguments arbitrarily held fixed), is monotone in the usual sense. The direction of the monotonicity (increasing or decreasing) must not depend on the values of the other arguments. Their proof of the variance reduction depends on the results of Lehmann (1966). Our proof is completely different and we use the monotonicity in a different way. In the following, we clarify their condition and generalize the condition to $m>1$.

First, let us introduce the difference operator $\Delta_{x_{i}, x_{i}^{\prime}}$, defined by the formula

$$
\Delta_{x_{i}, x_{i}^{\prime}} g(\mathbf{X})=g\left(X_{1}, \ldots, X_{i-1}, x_{i}, X_{i+1}, \ldots, X_{K}\right)-g\left(X_{1}, \ldots, X_{i-1}, x_{i}^{\prime}, X_{i+1}, \ldots, X_{K}\right)
$$

Then

$$
\begin{equation*}
\Delta_{x_{1}, x_{1}^{\prime}} \Delta_{x_{2}, x_{2}^{\prime}} \cdots \Delta_{x_{1}, x_{i}^{\prime}} g(\mathbf{X}) \tag{7}
\end{equation*}
$$

corresponds to the mixed partial derivative with respect to $X_{1}, \ldots, X_{t}$. We make the following definitions. Monotonicity of $g(\mathbf{X})$ in $\left(X_{1}, \ldots, X_{t}\right)$ holds if the sign of (7) remains the same, when (7) is regarded as a function of the $t$ arguments with all other arguments arbitrarily held fixed. Also th-order monotonicity of $g(\mathbf{X})$ in $X_{1}$ holds if $g(\mathbf{X})$ is monotone in $\left(X_{1}, X_{i_{2}}, \ldots, X_{i_{t}}\right)$ for all $\left(\begin{array}{c}K-1\end{array}\right)$ combinations $\left(1, i_{2}, \ldots, i_{t}\right), 1<i_{2}<\ldots<i_{t} \leqslant K$. The monotonicity in other arguments is similarly defined. Our generalized monotonicity implies that for differentiable functions the sign of the partial mixed derivative remains the same regardless of the values of the variables.

Now we state our main theorem.
Theorem 2. If th-order monotonicity holds in $K-t$ arguments of $g\left(X_{1}, \ldots, X_{K}\right)$ for all $t$ such that $1 \leqslant t \leqslant m$, then $\operatorname{var}\left(T_{\mathrm{EL}}\right) \leqslant \operatorname{var}\left(T_{\mathrm{R}}\right)$.

We denote $T_{\mathrm{EL}}$ under LHS, that is, $m=1$, simply by $T_{\mathrm{L}}$.
Corollary 1. If $g\left(X_{1}, \ldots, X_{K}\right)$ is monotone in $K-1$ arguments, then $\operatorname{var}\left(T_{\mathrm{L}}\right) \leqslant \operatorname{var}\left(T_{\mathrm{R}}\right)$.
The sufficient condition given by McKay et al. (1979) for LHS requires that $g$ be monotone in all $K$ arguments for variance reduction. Actually $K-1$ monotonicities are sufficient.

Since (3) can alternatively be written as

$$
\begin{align*}
\operatorname{var}\left(T_{\mathrm{EL}}\right) & =\frac{1}{N^{m}} \sum_{s=1}^{K} \varphi_{s}^{2}\left\{1-(1-N)^{1-s} \sum_{u=0}^{m-1}(-N)^{u}\binom{s-1}{u}\right\}+\nabla \\
& =\operatorname{var}\left(T_{\mathrm{R}}\right)+\frac{1}{N^{m}} \sum_{s=1}^{K} \varphi_{s}^{2}\left\{-(1-N)^{1-s} \sum_{u=0}^{m-1}(-N)^{u}\binom{s-1}{u}\right\}, \tag{8}
\end{align*}
$$

the variance reduction holds if and only if

$$
\begin{equation*}
\sum_{s=1}^{K} \varphi_{s}^{2}\left\{(-1)^{s}(N-1)^{1-s} \sum_{u=0}^{m-1}(-N)^{u}\binom{s-1}{u}\right\} \leqslant 0 \tag{9}
\end{equation*}
$$

We rewrite (9) as

$$
\begin{equation*}
\sum_{u=0}^{m-1} N^{u} \sum_{s=1+u}^{K} \varphi_{s}^{2}(-1)^{s+u}(N-1)^{1-s}\binom{s-1}{u} \leqslant 0 \tag{10}
\end{equation*}
$$

Our objective is to obtain a sufficient condition for (10). If, for $0 \leqslant u \leqslant m-1$,

$$
\begin{equation*}
\sum_{s=1+u}^{K} \varphi_{s}^{2}(-1)^{s+u}(N-1)^{1-s}\binom{s-1}{u} \leqslant 0 \tag{11}
\end{equation*}
$$

then (10) holds. Let $t=1+u$. In Appendix B, we show that $t$ th-order monotonicity in $K-t$ axes is a sufficient condition for (11).

The monotonicity condition of Theorem 2 may be difficult to check in practice. If we can assume that higher-order interaction effects are small, then variance reduction holds without the full monotonicity condition of Theorem 2 . For example, assume that $\varphi_{1}^{2} \geqslant \varphi_{i}^{2}$ holds for all $i$. Then $\operatorname{var}\left(T_{\mathrm{L}}\right) \leqslant \operatorname{var}\left(T_{\mathrm{R}}\right)$ for $N \geqslant 3$ by

$$
\varphi_{1}^{2} \geqslant \varphi_{1}^{2} \frac{N-1}{(N-1)^{2}-1}=\varphi_{1}^{2} \sum_{i=0}^{\infty}(N-1)^{-2 i-1} \geqslant \sum_{s=2}^{K} \varphi_{s}^{2}(-1)^{s}(N-1)^{1-s} .
$$

Hence LHS gives the variance reduction in quite a number of situations. Similarly, if we assume that $\varphi_{2}^{2} \geqslant \varphi_{i}^{2}$ for $i \geqslant 2$, then (11) holds for $N \geqslant 4$ with $u=1$ by

$$
\frac{\varphi_{2}^{2}}{N-1} \geqslant \varphi_{2}^{2} \frac{2(N-1)^{2}}{\left(N^{2}-2 N\right)^{2}}=\varphi_{2}^{2} \sum_{i=0}^{\infty} \frac{2+2 i}{(N-1)^{2 i+2}} \geqslant \sum_{s=3}^{K} \varphi_{s}^{2}(-1)^{s+1}(N-1)^{1-s}\binom{s-1}{1} .
$$

We summarize these simple sufficient conditions for variance reduction in the following proposition.

Proposition 1. If $\varphi_{1}^{2} \geqslant \varphi_{i}^{2}$ for all $i$, then the variance reduction of LHS holds for $N \geqslant 3$. If $\varphi_{1}^{2} \geqslant \varphi_{2}^{2} \geqslant \varphi_{i}^{2}$ for $i \geqslant 2$, then the variance reduction of $\operatorname{ELHS}(2)$ holds for $N \geqslant 4$.

## 5. Some simulation results

In this section we confirm our theoretical results by simulation. We choose a rather simple situation where the exact variance of $\operatorname{ELHS}(m)$ can be computed. Note that this is not a realistic situation in which simulations are actually used.

Let $K=4$, and consider

$$
\begin{equation*}
W=\exp \left(X_{1}+X_{2}+X_{3}+X_{4}\right), \tag{12}
\end{equation*}
$$

where $X_{i}, i=1, \ldots, 4$, are independently and identically distributed as $U[0,1]$. In this example all mixed derivatives are positive and hence monotonicities of all orders hold.

We obtained the simulation variance with 1000000 replications for each $T_{\mathrm{R}}, T_{\mathrm{L}}$ and $T_{\mathrm{EL}}$ of $m=2$. The sample size was 25 . Thus $N=25$ for LHS and $N=5$ for ELHS(2). The simulated sampling distributions of SRS, LHS and ELHS(2) are plotted in Figure 1. We see


Figure 1. Simulated distributions of $T_{\mathrm{R}}, T_{\mathrm{L}}$ and $T_{\mathrm{EL}}$ (Section 5).
that $T_{\mathrm{EL}}$ is much more concentrated around the true value $\mu$. The numerical results of our simulation are summarized in Table 1. Observe that the true values and the simulated values in Table 1 are in close agreement, and this confirms our theoretical results.

In this example $\varphi_{1}^{2}=23.825679, \varphi_{2}^{2}=2.801345, \varphi_{3}^{2}=0.146388, \varphi_{4}^{2}=0.002869$ for $\operatorname{ELHS}(2)$ with $N=5$. For LHS with $N=25, \varphi_{1}^{2}=24.873724, \varphi_{2}^{2}=3.053217, \varphi_{3}^{2}=$ $0.166568, \varphi_{4}^{2}=0.003408$ and these are different from those for $\operatorname{ELHS}(2)$ with $N=5$. Our choice of $m=2$ seems to be appropriate in this example.

## 6. Further discussion

It is desirable to compare $\operatorname{ELHS}(m)$ schemes for different $m$ under the same sample size. In the example (12) of the preceding section, ELHS(2) dominates ELHS(1). However, general monotone variance reduction in $m$ might not hold for small sample size. The difficulty lies in the fact that $\varphi_{s} s$ depend on $N$ and signs in the summation of (3) are alternating. For large sample size $\varphi_{s}$ becomes stable with respect to $N$, but the monotone variance reduction in $m$ obviously holds asymptotically.

The method of mapping $z_{i j}$ into $X_{i j}$ is a controversial point. Although it produces bias, we can make $\nabla=0$ by choosing $x_{i j}$ deterministically given $z_{i j}$. Hence one needs to consider the trade-off between bias and variance. Owen (1992a) discusses the midpoint rule and rectangular rule, and Tang (1993) introduces a Latin hypercube structure to the cells, that is, the sample points in the given cells are generated by using a method like LHS. Under this stratification, $\nabla$ is reduced when $W$ is additive.
To achieve specific objectives some authors impose restrictions on the Latin hypercube design. Handcock (1991) proposed a 'cascading' Latin hypercube design. Sample points were obtained by using modified LHS with midpoint rule, and a few points from the same cells are added with LHS. In the literature of experimental design, optimality of permuted generator arrays is discussed. Uniformity of the sample points is improved by restricting permutations. Tang (1994) introduced a criterion for comparing design arrays. Shaw (1988) reviewed the criteria of uniformity.

Table 1. Simulation results (1000 000 replications)

|  | SRS | LHS | ELHS(2) |
| :--- | :---: | :---: | ---: |
| True E[ $W$ ] | 8.717212 | 8.717212 | 8.717212 |
| Sample mean | 8.716336 | 8.716541 | 8.717124 |
| True variance of $\mu_{\mathbf{z}}$ | - | 0.134005 | 0.009239 |
| True $\nabla$ | - | 0.002221 | 0.055047 |
| True variance of $T$ | 1.126098 | 0.136226 | 0.064286 |
| Sample variance of $T$ | 1.123594 | 0.136028 | 0.064175 |
| Minimum $T$ | 4.991916 | 7.612060 | 7.613056 |
| Maximum $T$ | 15.304256 | 10.909609 | 10.060986 |

In our assumption, each axis is independently distributed. Iman and Conover (1982) treated dependency in LHS, and Owen (1994b) proposed another algorithm for controlling correlations. Stein (1987) discussed the central limit theorem for LHS and Owen (1992b) gave a proof of the central limit theorem using the method of moments. Loh (1996) established a Berry-Esseen-type bound for LHS. It is natural to expect that the central limit theorem holds for $T_{\text {EL }}$ under appropriate regularity conditions (see Figure 1).

## Appendix A. Proofs of lemmas in Section 3

Proof of Lemma 1. We first show that $L(s, h)=0$ for $m \leqslant h \leqslant s-1<K$. Note that any $N^{m} \times s$ submatrix of $\mathrm{OA}\left(N^{m}, K, N, m\right)$ becomes $\mathrm{OA}\left(N^{m}, s, N, m\right)$. In an orthogonal array $\mathrm{OA}\left(N^{m}, s, N, m\right)$, the rows of each $N^{m} \times m$ submatrix are all distinct. This implies that two rows of $\mathrm{OA}\left(N^{m}, s, N, m\right)$ can only have less than $m$ elements in common. Therefore $L(s, h)=0$ for $m \leqslant h \leqslant s-1$, and $L(s, s)=N^{m}$.

Now let $h<m$. We consider a particular $\operatorname{OA}\left(N^{m}, s, N, m\right)$, say $\mathbf{A}$, whose first row is assumed for the moment to be $\mathbf{y}=(1,1, \ldots, 1)$. With the remaining $N^{m}-1$ rows of $\mathbf{A}$, we want to know the number of rows that have just $h$ axes indexed as 1 . There are $N^{m-h}-1$ rows $\mathbf{z}$ of $\mathbf{A}$ such that $z_{1}=z_{2}=\cdots=z_{h}=1$. Using an inclusion-exclusion formula, we can count the number of rows that satisfy $z_{1}=\cdots=z_{h}=1, z_{h+1} \neq 1$, $\ldots, z_{K} \neq 1$ among these. Note that the first row $(1,1, \ldots, 1)$ has to be subtracted from the count. Therefore the number is

$$
\begin{equation*}
\sum_{t=0}^{m-h-1}(-1)^{t}\left(N^{m-h-t}-1\right)\binom{s-h}{t} \tag{13}
\end{equation*}
$$

This times $\binom{s}{h}$ yields the total number of rows that have just $h$ axes indexed as 1 .
Note that the above argument does not depend on the assumption $\mathbf{y}=(1,1, \ldots, 1)$. Therefore, multiplying (13) by $N^{m}\binom{s}{h}$, we obtain the lemma.

The following identity is easily shown by induction on $c \geqslant 0$ :

$$
\begin{equation*}
\sum_{b=0}^{c}(-1)^{b}\binom{a}{b}=(-1)^{c}\binom{a-1}{c} \tag{14}
\end{equation*}
$$

Now we need the following lemma to prove Lemma 2.
Lemma 3. For $0 \leqslant l<m-q, q \geqslant 1, s \geqslant m$,

$$
\sum_{h=l}^{m-q}(-1)^{m-h-q}\binom{s-h-1}{m-h-q}\binom{s-l}{h-l}=1
$$

Proof. Note that $s-l \geqslant 0, s-m+q \geqslant 0$. Consider the series expansion of

$$
\frac{(1+x)^{s-l}}{(1+x)^{s-m+q}}=(1+x)^{m-q-l} .
$$

We obtain the lemma by comparing the coefficients of $x^{m-q-l}$.
Proof of Lemma 2. The left-hand side of (6) equals

$$
1-(1-N)^{1-s} \sum_{h=0}^{m-1}(1-N)^{h}\binom{s}{h} \sum_{t=0}^{m-h-1}(-1)^{t} \frac{N^{m-h-t}-1}{N-1}\binom{s-h}{t} .
$$

Thus we need to show that

$$
\begin{equation*}
\sum_{h=0}^{m-1}(1-N)^{h}\binom{s}{h} \sum_{t=0}^{m-h-1}(-1)^{t} \frac{N^{m-h-t}-1}{N-1}\binom{s-h}{t}=\sum_{u=0}^{m-1}(-N)^{u}\binom{s-1}{u} . \tag{15}
\end{equation*}
$$

The left-hand side of (15) reduces to

$$
\begin{align*}
& \sum_{h=0}^{m-1}(1-N)^{h}\binom{s}{h} \sum_{t=0}^{m-h-1}(-1)^{t} \sum_{j=0}^{m-h-t-1} N^{j}\binom{s-h}{t} \\
& \quad=\sum_{h=0}^{m-1} \sum_{u=0}^{h}\binom{h}{u}(-N)^{u}\binom{s}{h} \sum_{j=0}^{m-h-1} N^{j}(-1)^{m-h-1-j}\binom{s-h-1}{m-h-1-j} \tag{16}
\end{align*}
$$

by (14). Furthermore, (16) equals

$$
\begin{gather*}
\sum_{h=0}^{m-1} \sum_{l=0}^{h}(-N)^{l}\binom{s}{l}\binom{s-l}{h-l} \sum_{j=0}^{m-h-1} N^{j}(-1)^{m-h-1-j}\binom{s-h-1}{m-h-1-j} \\
\quad=\sum_{u=0}^{m-1} \sum_{l=0}^{u} \sum_{h=l}^{m-q}\binom{s}{l}\binom{s-l}{h-l}\binom{s-h-1}{m-h-q}(-1)^{m-h-q}(-1)^{l} N^{u}, \tag{17}
\end{gather*}
$$

where $q=1+u-l$. Using Lemma 3, (17) equals

$$
\sum_{u=0}^{m-1} \sum_{l=0}^{u}\binom{s}{l}(-1)^{l} N^{u}=\sum_{u=0}^{m-1}(-N)^{u}\binom{s-1}{u}
$$

by (14). This is the right-hand side of (15).

## Appendix B. Proofs of results required for section 4

It is straightforward to show that

$$
\operatorname{var}\left(T_{\mathrm{EL}}\right)=\operatorname{var}\left(T_{\mathrm{R}}\right)+\frac{N^{m}-1}{N^{m}} \operatorname{cov}\left(\mu_{\mathbf{y}}, \mu_{\mathbf{z}}\right),
$$

where $\operatorname{cov}\left(\mu_{\mathbf{y}}, \mu_{\mathrm{z}}\right)=\mathrm{E}\left[\left(\mu_{\mathrm{y}}-\mu\right)\left(\mu_{\mathrm{z}}-\mu\right)\right]$ is the covariance of two cell mean functions under the cell selection. Comparing this with (8), we have

$$
\left(N^{m}-1\right) \operatorname{cov}\left(\mu_{\mathbf{y}}, \mu_{\mathbf{z}}\right)=\sum_{s=1}^{K} \varphi_{s}^{2}\left\{(-1)^{s}(N-1)^{1-s} \sum_{u=0}^{m-1}(-N)^{u}\binom{s-1}{u}\right\} .
$$

We are interested in a sufficient condition for this covariance term to be non-positive: $\left(N^{m}-1\right) \operatorname{cov}\left(\mu_{\mathrm{y}}, \mu_{\mathrm{z}}\right) \leqslant 0$.

Here we prefer to examine the case $m=1$ first and generalizing the result to $m>1$ later.

## B.1. LHS

For the case $m=1$, we can rewrite $(N-1) \operatorname{cov}\left(\mu_{\mathbf{y}}, \mu_{\mathbf{z}}\right)$ to be non-positive as

$$
\begin{aligned}
0 \geqslant & -\sum_{i=1}^{K} \sum_{z_{i}} \alpha_{1}\left(z_{i}\right)^{2} N^{-1}(N-1)^{0}+\sum_{i_{1}<i_{2}} \sum_{z_{i_{1}}} \sum_{z_{i_{2}}} \alpha_{2}\left(z_{i_{1}}, z_{i_{2}}\right)^{2} N^{-2}(N-1)^{-1} \\
& -\sum_{i_{1}<i_{2}<i_{3}} \sum_{z_{i_{1}}} \sum_{z_{i_{2}}} \sum_{z_{i_{3}}} \alpha_{3}\left(z_{i_{1}}, z_{i_{2}}, z_{i_{3}}\right)^{2} N^{-3}(N-1)^{-2} \\
& +\ldots+(-1)^{K} \sum_{z_{1}} \cdots \sum_{z_{K}} \alpha_{K}\left(z_{1}, \ldots, z_{K}\right)^{2} N^{-K}(N-1)^{1-K} .
\end{aligned}
$$

Lemma 4. If $\mu_{\mathrm{z}}$ is monotone in $z_{1}$, then

$$
\begin{aligned}
0 \leqslant & \sum_{z_{1}} \alpha_{1}\left(z_{1}\right)^{2} N^{-1}(N-1)^{0}(-1)^{0}+\sum_{1<i} \sum_{z_{1}} \sum_{z_{i}} \alpha_{2}\left(z_{1}, z_{i}\right)^{2} N^{-2}(N-1)^{-1}(-1)^{1} \\
& +\sum_{1<i_{1}<i_{2}} \sum_{z_{1}} \sum_{z_{i_{1}}} \sum_{z_{i_{2}}} \alpha_{3}\left(z_{1}, z_{i_{1}}, z_{i_{2}}\right)^{2} N^{-3}(N-1)^{-2}(-1)^{2} \\
& +\ldots+\sum_{z_{1}} \cdots \sum_{z_{K}} \alpha_{K}\left(z_{1}, \ldots, z_{K}\right)^{2} N^{-K}(N-1)^{1-K}(-1)^{K-1} .
\end{aligned}
$$

Proof. By the monotonicity in $z_{1}$,

$$
\left(\mu_{z_{1} z_{2} \ldots z_{K}}-\mu_{i z_{2} \ldots z_{K}}\right)\left(\mu_{z_{1} y_{2} \ldots y_{K}}-\mu_{i} y_{2} \ldots y_{K}\right) \geqslant 0, \quad \forall z_{1}, z_{1}^{\prime}, z_{2}, \ldots, z_{K}, y_{2} \neq z_{2}, \ldots, y_{K} \neq z_{K} .
$$

Therefore

$$
\begin{equation*}
\sum_{z_{1}} \sum_{z_{1}^{\prime}} \sum_{z_{2}} \cdots \sum_{z_{K}} \sum_{y_{2} \neq z_{2}} \cdots \sum_{y_{K} \neq z_{K}}\left(\mu_{z_{1} z_{2} \ldots z_{K}}-\mu_{z_{1}^{\prime} z_{2} \ldots z_{K}}\right)\left(\mu_{z_{1} y_{2} \ldots y_{K}}-\mu_{z_{1}^{\prime} y_{2} \ldots y_{K}}\right) \geqslant 0 . \tag{18}
\end{equation*}
$$

For $2 \leqslant t \leqslant s$,

$$
\begin{aligned}
& \sum_{y_{t} \neq z_{t}}\left(\alpha_{s}\left(z_{1}, y_{2}, \ldots, y_{s}\right)-\alpha_{s}\left(z_{1}^{\prime}, y_{2}, \ldots, y_{s}\right)\right) \\
& \quad=(-1)\left(\alpha_{s}\left(z_{1}, y_{2}, \ldots, z_{t}, \ldots, y_{s}\right)-\alpha_{s}\left(z_{1}^{\prime}, y_{2}, \ldots, z_{t}, \ldots, y_{s}\right)\right)
\end{aligned}
$$

Further,

$$
\sum_{z_{1}} \sum_{z_{1}^{\prime}}\left(\alpha_{s}\left(z_{1}, \ldots\right)-\alpha_{s}\left(z_{1}^{\prime}, \ldots\right)\right)^{2}=2 N \sum_{z_{1}}\left(\alpha_{s}\left(z_{1}, \ldots\right)\right)^{2} .
$$

Using these facts, (18) divided by $2 N$ is

$$
\begin{align*}
0 \leqslant & N^{K-1}(N-1)^{K-1} \sum_{z_{1}} \alpha_{1}\left(z_{1}\right)^{2}+N^{K-2}(N-1)^{K-2} \sum_{2 \leqslant i \leqslant K} \sum_{z_{1}} \sum_{z_{i}} \alpha_{2}\left(z_{1}, z_{i}\right)^{2}(-1) \\
& +N^{K-3}(N-1)^{K-3} \sum_{2 \leqslant i_{1}<i_{2} \leqslant K} \sum_{z_{1}} \sum_{z_{i_{1}}} \sum_{z_{i_{2}}} \alpha_{3}\left(z_{1}, z_{i_{1}}, z_{i_{2}}\right)^{2}(-1)^{2} \\
& +\cdots+N^{0}(N-1)^{0} \sum_{z_{1}} \cdots \sum_{z_{K}} \alpha_{K}\left(z_{1}, \ldots, z_{K}\right)^{2}(-1)^{K-1} . \tag{19}
\end{align*}
$$

Multiplying by $N^{-K}(N-1)^{1-K}$ proves the lemma.
By Lemma 4, under the monotonicity of $\mu_{\mathbf{z}}$ in $z_{1}$, our new sufficient condition for the variance reduction of LHS is given by

$$
\begin{align*}
0 \leqslant & \sum_{1<i} \sum_{z_{i}} \alpha_{1}\left(z_{i}\right)^{2} \cdot N^{-1}(N-1)^{0}(-1)^{0}+\sum_{1<i_{1}<i_{2}} \sum_{z_{i_{1}}} \sum_{z_{i_{2}}} \alpha_{2}\left(z_{i_{1}}, z_{i_{2}}\right)^{2} \cdot N^{-2}(N-1)^{-1}(-1)^{1} \\
& +\sum_{1<i_{1}<i_{2}<i_{3}} \sum_{z_{i_{1}}} \sum_{z_{i_{2}}} \sum_{z_{i_{3}}} \alpha_{3}\left(z_{i_{1}}, z_{i_{2}}, z_{i_{3}}\right)^{2} \cdot N^{-3}(N-1)^{-2}(-1)^{2} \\
& +\ldots+\sum_{z_{2}} \cdots \sum_{z_{K}} \alpha_{K-1}\left(z_{2}, \ldots, z_{K}\right)^{2} \cdot N^{1-K}(N-1)^{2-K}(-1)^{K-2} . \tag{20}
\end{align*}
$$

Note that -1 times the right-hand side of this inequality corresponds to the covariance of partially averaged cell mean function:

$$
\mu_{\cdot \cdot_{2} z_{3} \ldots z_{K}}=\frac{1}{N} \sum_{z_{1}=1}^{N} \mu_{z_{1} z_{2} \ldots z_{K}}
$$

which can be regarded as a function with $K-1$ arguments. In fact (20) is equivalent to $\operatorname{cov}\left(\mu_{\cdot z_{2} \ldots z_{K}}, \mu_{\cdot y_{2} \ldots y_{K}}\right) \leqslant 0$ under LHS.

Therefore by assuming the monotonicity in any one axis, we have reduced our problem from $K$ arguments to $K-1$ arguments. Employing the monotonicity in $z_{2}$, we can further reduce the number of arguments. To complete this inductive argument we need the following initial condition.

Lemma 5. Let $m=1, K=2$. Then monotonicity in one axis implies

$$
\operatorname{cov}\left(\mu_{z}, \mu_{\mathbf{y}}\right) \leqslant 0
$$

## Proof.

$(N-1) \operatorname{cov}\left(\mu_{\mathbf{z}}, \mu_{\mathbf{y}}\right)=-N^{-1}\left\{\sum_{z_{1}} \alpha_{1}\left(z_{1}\right)^{2}+\sum_{z_{2}} \alpha_{1}\left(z_{2}\right)^{2}\right\}+N^{-2}(N-1)^{-1} \sum_{z_{1}} \sum_{z_{2}} \alpha_{2}\left(z_{1}, z_{2}\right)^{2}$.
As in (19) the monotonicity in $z_{1}$ implies

$$
0 \geqslant-N^{-1}\left\{\sum_{z_{1}} \alpha_{1}\left(z_{1}\right)^{2}\right\}+N^{-2}(N-1)^{-1} \sum_{z_{1}} \sum_{z_{2}} \alpha_{2}\left(z_{1}, z_{2}\right)^{2}
$$

Now the lemma follows from $\sum_{z_{2}} \alpha_{1}\left(z_{2}\right)^{2} \geqslant 0$.
Summarizing the above arguments we have established the following Proposition.
Proposition 2. If the cell mean function $\mu_{\mathrm{z}}$ is monotone in any $K-1$ of the $K$ axes, then $\operatorname{var}\left(T_{\mathrm{L}}\right) \leqslant \operatorname{var}\left(T_{\mathrm{R}}\right)$.

Since the ranges of $F_{i}^{-1}\left(\left(\left(z_{i}-1\right) / N, z_{i} / N\right]\right), i=1, \ldots, K$, are monotone in $z_{i}$ 's, if $g$ is monotone in the $i$-th axis then the cell mean function is also monotone in the $i$-th axis. Hence Corollary 1 holds as a consequence of Proposition 2.

## B.2. ELHS

For general $m$ we establish the proposition below.
Proposition 3. Suppose that for all $1 \leqslant t \leqslant m$, th-order monotonicities of $\mu_{\mathrm{z}}$ concerning $K-t$ axes hold, then $\operatorname{var}\left(T_{\mathrm{EL}}\right) \leqslant \operatorname{var}\left(T_{\mathrm{R}}\right)$.

Proof. In view of (11) the variance reduction holds if

$$
c_{t}=(-1)^{t-1} \sum_{s=t}^{K} \varphi_{s}^{2}(-1)^{s}(N-1)^{1-s}\binom{s-1}{t-1} \leqslant 0
$$

for $1 \leqslant t \leqslant m$. We claim that $t$ th-order monotonicity in any $K-t$ axes implies $c_{t} \leqslant 0$. The monotonicity in ( $z_{1}, z_{2}, \ldots, z_{t}$ ) implies

$$
\left(\Delta_{z_{1}, z_{1}^{\prime}} \ldots \Delta_{z_{t}, z_{i}^{\prime}} \mu_{\mathbf{z}}\right)\left(\Delta_{z_{1}, z_{1}^{\prime}} \ldots \Delta_{z_{t}, z_{t}^{\prime}} \mu_{\mathbf{y}}\right) \geqslant 0
$$

for all $\mathbf{z}, z_{1}^{\prime}, \ldots, z_{t}^{\prime}, y_{t+1}, \ldots, y_{K}$. Summing these as in Lemma 4 yields

$$
\begin{aligned}
0 \leqslant & \sum_{z_{1}} \sum_{z_{2}} \cdots \sum_{z_{t}} \alpha_{t}\left(z_{1}, z_{2}, \ldots, z_{t}\right)^{2}(N(N-1))^{-1} \\
& -\sum_{t<i} \sum_{z_{1}} \cdots \sum_{z_{t}} \sum_{z_{i}} \alpha_{t+1}\left(z_{1}, \ldots, z_{t}, z_{i}\right)^{2}(N(N-1))^{-2} \\
& +\sum_{t<i_{1}<i_{2}} \sum_{z_{1}} \cdots \sum_{z_{t}} \sum_{z_{i_{1}}} \sum_{z_{i_{2}}} \alpha_{t+2}\left(z_{1}, \ldots, z_{t}, z_{i_{1}}, z_{i_{2}}\right)^{2}(N(N-1))^{-3} \\
& +\ldots+(-1)^{K-t} \sum_{z_{1}} \cdots \sum_{z_{K}} \alpha_{K}\left(z_{1}, \ldots, z_{K}\right)^{2}(N(N-1))^{-(K-t+1)} .
\end{aligned}
$$

In order to use induction on $z_{1}$, we utilize $\binom{K-1}{t-1}$ monotonicities concerning $z_{1}$. By symmetry and

$$
\frac{\binom{K-1}{t-1}\binom{K-t}{s-t}}{\binom{K-1}{s-1}}=\binom{s-1}{t-1},
$$

$t$ th-order of the monotonicity in $z_{1}$ implies

$$
\begin{aligned}
0 \leqslant & \sum_{1<i_{1}<\ldots<i_{t-1}} \sum_{z_{1}} \sum_{z_{i_{1}}} \cdots \sum_{z_{i_{t-1}}} \alpha_{t}\left(z_{1}, z_{i_{1}}, \ldots, z_{i_{t-1}}\right)^{2}(N(N-1))^{-1}\binom{t-1}{t-1} \\
& -\sum_{1<i_{1}<\ldots<i_{t}} \sum_{z_{1}} \sum_{z_{i 1}} \cdots \sum_{z_{i_{t}}} \alpha_{t+1}\left(z_{1}, z_{i_{1}}, \ldots, z_{i_{t}}\right)^{2}(N(N-1))^{-2}\binom{t}{t-1} \\
& +\sum_{1<i_{1}<\ldots<i_{t+1}} \sum_{z_{1}} \sum_{z_{i 1}} \cdots \sum_{z_{i_{t+1}}} \alpha_{t+2}\left(z_{1}, z_{i_{1}}, \ldots, z_{i_{t+1}}\right)^{2}(N(N-1))^{-3}\binom{t+1}{t-1} \\
& +\ldots+(-1)^{K-t} \sum_{z_{1}} \cdots \sum_{z_{K}} \alpha_{K}\left(z_{1}, \ldots, z_{K}\right)^{2}(N(N-1))^{-(K-t+1)}\binom{K-1}{t-1} .
\end{aligned}
$$

We see that the monotonicity leads to the reduction of one argument by $N^{t-1}(N-1)^{t-2} \geqslant 0$. By induction $K-(t+1) t$ th-order monotonicities lead to the initial condition

$$
\begin{aligned}
0 \leqslant & \sum_{i_{1}<\ldots<i_{t}} \sum_{z_{i 1}} \cdots \sum_{z_{i_{t}}} \alpha_{t}\left(z_{i_{1}}, \ldots, z_{i_{t}}\right)^{2}(N(N-1))^{-1}\binom{t-1}{t-1} \\
& -\sum_{z_{1}} \cdots \sum_{z_{t+1}} \alpha_{t+1}\left(z_{1}, \ldots, z_{t+1}\right)^{2}(N(N-1))^{-2}\binom{t}{t-1},
\end{aligned}
$$

which is implied by $t$ th-order monotonicity in $z_{1}$. This proves the proposition.
Then, as in Corollary 1, Theorem 2 is an immediate consequence of Proposition 3.

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