

## COMPLETE NONCOMPACT KÄHLER MANIFOLDS WITH POSITIVE HOLOMORPHIC BISECTIONAL CURVATURE

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In the theory of complex geometry and Kähler manifolds, one of the famous problems is the following conjecture:

**Conjecture.** Suppose  $M$  is a complete noncompact Kähler manifold with positive holomorphic bisectional curvature. Then  $M$  is biholomorphic to  $\mathbf{C}^n$ .

Several results concerning this conjecture were obtained in the past few years. In 1981 N. Mok, Y. T. Siu, and S. T. Yau [4] proved the following result:

**Theorem 1.** *Suppose  $M$  is a complete noncompact Kähler manifold of complex dimension  $n \geq 2$ . Suppose  $M$  is a Stein manifold and the holomorphic bisectional curvature is nonnegative. Suppose  $M$  satisfies the following assumptions:*

- (i)  $\text{Vol}(B(x_0, r)) \geq c_0 r^{2n}$ ,  $0 \leq r < +\infty$ ,
- (ii)  $0 \leq R(x) \leq c_1 / r(x, x_0)^{2+\varepsilon}$ ,  $x \in M$ ,

where  $0 < c_0, c_1, \varepsilon < +\infty$  are some constants,  $B(x_0, r)$  denotes the geodesic ball of radius  $r$  and centered at  $x_0$ ,  $\text{Vol}(B(x_0, r))$  denotes the volume of  $B(x_0, r)$ ,  $r(x_0, x)$  denotes the distance between  $x_0$  and  $x$ , and  $R(x)$  denotes the scalar curvature at  $x \in M$ . Then  $M$  is isometrically biholomorphic to  $\mathbf{C}^n$  with the flat metric.

Their result was improved by N. Mok [5] in 1984. In [5] N. Mok obtained the following result:

**Theorem 2.** *Suppose  $M$  is a complete noncompact  $n$ -dimensional Kähler manifold with positive holomorphic bisectional curvature and satisfies the following assumptions:*

- (i)  $\text{Vol}(B(x_0, r)) \geq c_0 r^{2n}$ ,  $0 \leq r < +\infty$ ,
- (ii)  $0 < R(x) \leq c_1 / r(x_0, x)^2$ ,  $x \in M$ ,

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where  $0 < c_0, c_1 < +\infty$  are some constants. Then  $M$  is biholomorphic to an affine algebraic variety.

In this note we announce the following result:

**Theorem 3.** *Suppose  $M$  is a complete noncompact Kähler manifold of complex dimension  $n$  with bounded and positive holomorphic bisectional curvature. Suppose  $M$  satisfies the following assumptions:*

- (i)  $\text{Vol}(B(x_0, r)) \geq c_0 r^{2n}, 0 \leq r < +\infty,$
- (ii)  $\int_{B(x_0, r)} R(x) dx \leq c_1 r^{2n-2}, x_0 \in M, 0 \leq r < +\infty,$

where  $0 < c_0, c_1 < +\infty$  are some constants. Then  $M$  is biholomorphic to  $\mathbb{C}^n$ .

The method we used to prove Theorem 3 is to study the following Ricci flow evolution equation on Riemannian manifolds:

$$(1) \quad \frac{\partial}{\partial t} g_{ij} = -2R_{ij},$$

where  $g_{ij}$  is the Riemannian metric on the manifold  $M$ ,  $R_{ij}$  denotes its Ricci curvature tensor. Evolution equation (1) was originally introduced by R. S. Hamilton [1] in 1982. In that paper Hamilton used (1) to classify all of the three-dimensional compact Riemannian manifolds with positive Ricci curvature. Since then many works dealing with or related to equation (1) have been published; for example, one can see [2, 3, and 6].

In the case where  $M$  is a complex Kähler manifold, evolution equation (1) is strongly related to complex Monge-Ampère equation. On Kähler manifolds Monge-Ampère equation is a nonlinear elliptic type equation and (1) is the corresponding parabolic equation of Monge-Ampère equation. Under this point of view, H. D. Cao generalized the arguments established by S. T. Yau for Monge-Ampère equation in the proof of Calabi's conjecture to the corresponding Ricci flow equation and obtained a different proof of Calabi's conjecture in 1985.

Using evolution equation (1) to deform the metric  $g_{ij}$  on Riemannian manifold  $M$ , the first thing one has to consider is the short time existence for the solution of (1). In the case where  $M$  is compact, evolution equation (1) always has a smooth solution for at least a short time interval. This fact was proved by R. S. Hamilton in [1]. In the case where  $M$  is complete and noncompact, the similar statement in general is not true. One can easily find a counterexample when the curvature tensor is unbounded on the whole

manifold. If we assume that  $M$  is a complete noncompact Riemannian manifold with bounded curvature tensor, then we have the following short time existence theorem which was proved in [7]:

**Theorem 4.** *Let  $(M, g_{ij}(x))$  be an  $n$ -dimensional complete noncompact Riemannian manifold with its Riemannian curvature tensor  $\{R_{ijkl}\}$  satisfying*

$$(2) \quad |R_{ijkl}(x)|^2 \leq k_0, \quad \forall x \in M,$$

where  $0 < k_0 < +\infty$  is a constant. Then there exists a constant  $T(n, k_0) > 0$  depending only on  $n$  and  $k_0$  such that the evolution equation

$$(3) \quad \begin{cases} \frac{\partial}{\partial t} g_{ij}(x, t) = -2R_{ij}(x, t) \\ g_{ij}(x, 0) = g_{ij}(x) \end{cases}$$

has a smooth solution  $g_{ij}(x, t) > 0$  for a short time  $0 \leq t \leq T(n, k_0)$ , and satisfies the following estimates: For any integers  $m \geq 0$ , there exist constants  $c_m > 0$  depending only on  $n, m$ , and  $k_0$  such that

$$(4) \quad \sup_{x \in M} |\nabla^m R_{ijkl}(x, t)|^2 \leq c_m/t^m, \quad 0 \leq t \leq T(n, k_0),$$

where  $\nabla^m R_{ijkl}$  denote the  $m$ th order covariant derivatives of  $R_{ijkl}$ .

*Sketch of the proof of Theorem 3.* Now we suppose  $M$  is a complex  $n$ -dimensional complete noncompact Kähler manifold which satisfies the hypothesis in Theorem 3. Since the holomorphic bisectional curvature on  $M$  is positive and bounded, we know that the curvature tensor  $\{R_{ijkl}\}$  of  $M$  satisfies condition (2) in Theorem 4 with some constant  $k_0 < +\infty$ . Thus from Theorem 4, we know that evolution equation (1) has a solution  $g_{ij}(x, t) > 0$  on  $M$  for a short time interval.

In the next step, we want to show that the solution  $g_{ij}(x, t)$  of evolution equation (1) actually exists for all time  $0 \leq t < +\infty$ . To prove the long time existence for the solution of (1), what we need to prove is that the curvature of  $g_{ij}(x, t)$  would not tend to infinity on any finite time interval. This kind of fact and the techniques used to prove it were originally established by author in [8] under some more restricted curvature pinching and decay assumptions. Modifying and generalizing the arguments developed

in [8], we can show that on any finite time interval  $0 \leq t < T$ , the curvature of the solution  $g_{ij}(x, t)$  is bounded uniformly on  $M \times [0, T)$  under the hypotheses of Theorem 3. Thus we know that the solution  $g_{ij}(x, t)$  of (1) actually exists for all time  $0 \leq t < +\infty$  under the hypotheses of Theorem 3.

Suppose  $g_{ij}(x, t) > 0$  defined on  $M \times [0, \infty)$  is the solution of evolution equation (1) for all time  $0 \leq t < +\infty$ . By the assumption in Theorem 3, we know that  $g_{ij}(x, t)$  is Kähler metric at time  $t = 0$ . Using the maximum principles for the solutions of heat equations on complete noncompact Riemannian manifolds which were developed in [8], it is easy to show that  $g_{ij}(x, t)$  are Kähler metrics for all  $0 \leq t < +\infty$ . Similar to what we did in [8], we can show that the curvature  $\{R_{ijkl}(x, t)\}$  of  $g_{ij}(x, t)$  and its covariant derivatives tend to zero as time  $t \rightarrow +\infty$ . Thus finally we obtained a flat Kähler metric on  $M$ , hence we know that  $M$  is isometrically biholomorphic to  $\mathbf{C}^n$  with the new metric. The proof of Theorem 3 is complete.

The details of the proof of Theorem 3 will appear elsewhere.

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