

## A FUBINI THEOREM FOR ITERATED STOCHASTIC INTEGRALS

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Let  $x(t)$  and  $y(t)$  be continuous martingales on the probability space  $(\Omega, \mathcal{F}, \mathbf{P})$ . Consider a bounded region  $\mathcal{D}$  in  $\mathbf{R}_+^2$  with smooth boundary  $\Gamma$ . Define  $\Gamma_i$  to be the portion of  $\Gamma$  along which the outward normal points in the direction of quadrant  $i$  ( $i = 1, 2, 3, 4$ ). Let  $f(t, s)$  be a smooth function on  $\bar{\mathcal{D}}$ . It is desired to evaluate

$$\iint_{\mathcal{D}} f(t, s) dx(s)dy(t) \quad \text{and} \quad \iint_{\mathcal{D}} f(t, s) dy(t)dx(s)$$

by Riemann sums in an Ito-related fashion. The difference between these sums is then of the form

$$\pm \Sigma f(t'_i, s'_i)[x(s'_{i+1}) - x(s'_i)] [y(t'_{i+1}) - y(t'_i)]$$

where  $(t'_i, s'_i)$  are points near  $\Gamma_2$  and  $\Gamma_4$ . Under suitable conditions on  $\mathcal{D}$  this sum tends to an integral of  $f$  along these portions of  $\Gamma$ . These considerations lead to the following

**THEOREM (THE CORRECTION FORMULA).** *Let  $(x(t), y(t))$  be a joint martingale. Then*

$$\begin{aligned} \iint_{\mathcal{D}} f(t, s) dx(s)dy(t) + \int_{\Gamma_2 \cap l} f(t, t) d\langle x, y \rangle(t) \\ = \iint_{\mathcal{D}} f(t, s) dy(t)dx(s) + \int_{\Gamma_4 \cap l} f(t, t) d\langle x, y \rangle(t) \end{aligned}$$

where  $\langle x, y \rangle$  is the quadratic covariation process of  $x$  and  $y$ , and  $l$  is the line  $s = t$ .

It is to be noted that the rigorous justification of the Correction Formula entails the development of a new type of stochastic integral  $I(t) = \int_{t_0}^t g(t, s) dx(s)$  where  $g(t, s)$  is measurable with respect to the sigma-field generated by  $\{x(u) - x(s) : s \leq u \leq t\}$ . Conditions are given which insure the existence of  $I(t)$  as a limit of Ito-related Riemann sums. The following result concerning the moments of  $I(t)$  is presented.

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THEOREM. Suppose  $E(g(t, s)/F_s) = 0$ , a.s. where  $F_s$  is the sigma-field generated by  $\{x(u): t_0 \leq u \leq s\}$ . Then

$$EI(t) = -\int_{t_0}^t E\partial_s g(t, s) dx(s)$$

$$E|I(t)|^2 = \int_{t_0}^t E|g(t, s)|^2 ds + \int_{t_0}^t \int_{t_0}^t E\partial_s g(t, s)\partial_r g(t, r) dx(s)dx(r)$$

where  $\partial_s$  represents the  $s$ -stochastic differential.

As an application of the Correction Formula, consider the linear Ito-Volterra equation (see Berger [1])

$$\xi(t) - \int_{t_0}^t a(t, s)\xi(s) dw(s) - \int_{t_0}^t b(t, s)\xi(s) ds = F(t).$$

Here  $w(t)$  is a Brownian motion. Using the Correction Formula the solution can be obtained by a Neumann series, and takes the form

$$\xi(t) = F(t) + \int_{t_0}^t r_a(t, s)F(s) dv(s) + \int_{t_0}^t r_b(t, s)F(s) ds$$

where  $v(t) = w(t) - \int_{t_0}^t a(s, s) ds$  and

$$r_a(t, s) = \sum_{n=1}^{\infty} a_n(t, s), \quad r_b(t, s) = \sum_{n=1}^{\infty} b_n(t, s),$$

$$a_1(t, s) = a(t, s), \quad b_1(t, s) = b(t, s),$$

$$a_{n+1}(t, s) = \int_s^t a(t, r)a_n(r, s) dw(r) + \int_s^t b(t, r)a_n(r, s) dr,$$

$$b_{n+1}(t, s) = \int_s^t a(t, r)b_n(r, s) dw(r) + \int_s^t b(t, r)b_n(r, s) dr; \quad n = 1, 2, \dots$$

Corollaries of the Correction Formula include a differentiation rule for  $z(t) = h(t, x(t))$  where  $h(t, a) = \int_{t_0}^t \psi(s, x(s), t, a) dx(s)$ ; and a formula for evaluating  $\int_{t_0}^t \varphi(s)H_n(\int_s^t \varphi^2(r) dr, \int_s^t \varphi(r) dw(r)) dw(s)$  where  $H_n(t, x)$  is the Hermite polynomial of degree  $n$ . There is also included a discussion of stochastic integrals  $\int_{t_0}^t x(\lambda(s)) dx(s)$  where  $\lambda(s) \geq s$ .

#### REFERENCES

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