

## HOW A MINIMAL SURFACE LEAVES AN OBSTACLE<sup>1</sup>

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**ABSTRACT.** We announce that the function of least area among all functions defined in a convex domain, vanishing on its boundary, and constrained to lie above a concave analytic obstacle leaves the obstacle along an analytic curve.

We announce a result about the curve of separation determined by the solution to a variational inequality. A strictly convex domain  $\Omega$  with smooth boundary  $\partial\Omega$  is given in the  $z = x_1 + ix_2$  plane together with a smooth function  $\psi(z)$  which assumes a positive maximum in  $\Omega$  and is negative on  $\partial\Omega$ . Let  $K$  denote the closed convex set of Lipschitz functions  $v$  satisfying  $v \geq \psi$  in  $\Omega$  and  $v = 0$  on  $\partial\Omega$ . Let us denote by  $u$  the function of  $K$  which minimizes area among all functions of  $K$ ; that is

$$(1) \quad u \in K : \int_{\Omega} \frac{u_{x_j}}{(1 + |u_x|^2)^{1/2}} (v - u)_{x_j} dx \geq 0, \quad v \in K.$$

The existence of such  $u$ , actually satisfying  $u \in H^{2,q}(\Omega) \cap C^{1,\lambda}(\bar{\Omega})$ ,  $1 \leq q < \infty$ ,  $0 < \lambda < 1$ , was shown in the work of H. Lewy and G. Stampacchia [7] and also in M. Giaquinta and L. Pepe [1]. For  $u$  there is a set of coincidence  $I$  consisting of the points  $z \in \Omega$  where  $u(z) = \psi(z)$ . Let us call

$$(2) \quad \Gamma(u) = \Gamma = \{(x_1, x_2, x_3) : x_3 = u(z) = \psi(z), z \in \partial I\}$$

the "curve" of separation.

Up to this time it has only been known that when  $\psi$  is smooth and strictly concave,  $\Gamma$  is a Jordan curve [2]. On the other hand, the corresponding problem for the  $u \in K$  minimizing the Dirichlet integral has been thoroughly studied by H. Lewy and G. Stampacchia [6]. We wish to announce here the

**THEOREM.** *Let  $\psi$  be analytic and strictly concave. Let  $u$  be the solution of (1). Then  $\Gamma(u)$  is an analytic Jordan curve (as a function of its arc length parameter).*

The demonstration relies on the resolution of a system of differential equations and the utilization of the system to extend analytically a con-

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formal representation of the minimal surface which is the graph of  $u$  in the subset of  $\Omega$  where  $u > \psi$ . This is the idea of Hans Lewy (cf. for example [4], [5]). To derive the system of equations requires knowing that  $u$  has bounded second derivatives, which was shown in [3]. In order to identify the solution, we prove first that  $\Gamma$  is rectifiable.

In order to present a precise statement of this first step of the smoothness of  $\Gamma$ , let us introduce some notations. Set  $\Sigma = \{x \in \mathbb{R}^3 : x_3 = u(z), z \in \Omega\}$ ,  $S = \{x \in \mathbb{R}^3 : x_3 = u(z), z \in \Omega - I\} \subset \Sigma$ , and  $D = \{|\zeta| < 1\}$ . Let  $X : D \rightarrow \Sigma$  be a uniformization (conformal representation) of the  $C^{1,\alpha}$  surface  $\Sigma$  with  $X(0) = P \in \Gamma$ , a fixed point of  $\Gamma$ .

**THEOREM.** *Let  $f = f_\varepsilon$  be a conformal mapping of  $G = \{\text{Im } t > 0, |t| < 1\}$  onto a Jordan domain  $f_\varepsilon(G)$  containing  $\{\zeta : X(\zeta) \in S, |\zeta| < \varepsilon\}$  such that  $f_\varepsilon : (-1, 1) \rightarrow X^{-1}(\Gamma)$  and  $f_\varepsilon(0) = 0$ . Then there exists an  $\varepsilon > 0$  such that  $f_\varepsilon \in C^1(\bar{G})$ .*

From this it is clear that the conformal representation  $X\{f(t)\}$  provides, locally, a  $C^1$  representation of  $\Gamma$ . The proof of the theorem relies on the strict concavity of  $\psi$  and results of [2] to show that  $f' \in L^q(G)$  for a  $q > 2$ .

To prove the second theorem mentioned, we assume only that  $\psi \in C^3(\Omega)$  and is strictly concave. Hence we present a method to rectify curves determined by variational inequalities.

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