

MINIMAL REALIZATION OF MACHINES IN CLOSED CATEGORIES

BY J. A. GOGUEN

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There has been recent interest in extending automaton theory to encompass aspects of machine, language, and control theories [1], [2]. This paper presents a minimal realization theory for discrete-time machines in suitable categories with such applications, but assuming no background outside pure mathematics except perhaps as motivation. Minimal realization is proved in the strong form of an adjunction between behavior and a realization construction generalizing Nerode's [8]. We wish to thank Michael Arbib, Lee Carlson, Saunders Mac Lane, and Lotfi Zadeh for their encouragement and/or technical assistance.

If C is a category, $|C|$ denotes its class of objects; and the composite of $A \xrightarrow{f} B \xrightarrow{g} C$ is written $A \xrightarrow{fg} C$. Functors are written after their arguments.

1. *X-automata*. In the first four sections C is a fixed *suitable* category, i.e., closed symmetric monoidal [7] with countable coproducts and canonical cofactorizations [6]. Let \mathbf{Mon} be the category of *monoids* [7] in C . For $X \in |C|$, let $X^* = \coprod_r \otimes^r X$, the coproduct over the nonnegative integers of iterated "tensor" powers \otimes^r of X , where \otimes is the multiplication in C . Let $i_0: I \rightarrow X^*$ be the zeroth injection, from $\otimes^0 X = I$, the identity for \otimes in C . Finally, define $\mu: X^* \otimes X^* \rightarrow X^*$ to be the composite

$$\left(\coprod_r \otimes^r X \right) \otimes \left(\coprod_s \otimes^s X \right) \cong \coprod_{r,s} (\otimes^r X) \otimes (\otimes^s X) \cong \coprod_{r,s} \otimes^{r+s} X \rightarrow X^*$$

where the first isomorphism uses the distributivity of \otimes over \coprod which arises from the adjointness of \otimes , the second isomorphism is a generalized associative law in C , and the third morphism is defined by letting its $\langle r, s \rangle$ -component be the $r + s$ injection $\otimes^{r+s} X \rightarrow X^*$. Then [7], $\langle X^*, \mu, i_0 \rangle \in |\mathbf{Mon}|$.

For $M \in |\mathbf{Mon}|$, let \mathbf{Act}^M be the category of right M -actions in C , that is, $\alpha: S \otimes M \rightarrow S$ satisfying appropriate identities [7]. For $X \in |C|$, an *X-monadic algebra* in C is $\delta: S \otimes X \rightarrow S$; and a morphism $h: \delta \rightarrow \delta'$ of such algebras is $h: S \rightarrow S'$ such that $(h \otimes X)\delta' = \delta h$. Let \mathbf{Mond}^X be the resulting category. δ is often called a *transition* morphism.

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THEOREM 1. $Act^{X^*} \cong Mond^X$.

A *point* for an M -action or X -monadic algebra is $\sigma: I \rightarrow S$ in C . Denote the categories of pointed actions and algebras, with morphisms preserving the points, by Act^M and Aut^X respectively, the latter for X -automata. These generalize Kalman's modules in [5].

COROLLARY 2. $Act^{X^*} \cong Aut^X$.

Let $\langle X^*, \hat{\mu}, i_0 \rangle$ with $\hat{\mu}: X^* \otimes X \rightarrow X^*$ be the X -automaton corresponding by this corollary to the action $\mu: X^* \otimes X^* \rightarrow X^*$ of X^* on itself.

THEOREM 3. $\langle X^*, \hat{\mu}, i_0 \rangle$ is an initial X -automaton.

If $\langle S, \delta, \sigma \rangle$ is an X -automaton, let $\delta^+: X^* \rightarrow S$ denote the unique X -automaton morphism. Call $\langle S, \delta, \sigma \rangle$ *reachable* iff δ^+ is epic in C .

THEOREM 4. Aut^X has co-images.

This preliminary material works for somewhat less than suitable categories, since the internal hom is not used. Only Theorem 4 uses canonical cofactorization.

2. Machines. A *machine* M in C is $\langle X, S, Y, \delta, \lambda, \sigma \rangle$ such that $\langle S, \delta, \sigma \rangle$ is an X -automaton and $\lambda: S \rightarrow Y$ is a morphism in C . We also fix X and speak of the X -machine $\langle S, Y, \delta, \lambda, \sigma \rangle$. M is *reachable* iff its X -automaton is. A *morphism* of X -machines is a pair $\langle a, b \rangle$ with $a: S \rightarrow S'$, $b: Y \rightarrow Y'$ such that a is an X -automaton morphism and $\lambda b = a\lambda'$. Denote the category of reachable X -machines and morphisms in C by M^X . S, Y (resp. a, b) are the *state* and *output objects* (resp. *components*) of M (resp. $\langle a, b \rangle$). X is the *input* object.

An X -*behavior* in C is a morphism $f: X^* \rightarrow Y$, and a morphism $f \rightarrow f'$ of X -behaviors is $b: Y \rightarrow Y'$ such that $fb = f'$. Let B^X denote the category. Given an X -machine M , let $ME = \delta^+\lambda: X^* \rightarrow Y$, where δ^+ arises from the X -automaton of M ; given $\langle a, b \rangle: M \rightarrow M'$ in M^X , let $\langle a, b \rangle E = b$. Then $E: M^X \rightarrow B^X$ is a functor, called the *external behavior* functor. Say that M *realizes* f iff $ME = f$.

Given $f: X^* \rightarrow Y$, let fA be the X -automaton $\langle [X^*, Y], \alpha_f, \sigma_f \rangle$, where $\alpha_f: [X^*, Y] \otimes X \rightarrow [X^*, Y]$ and $\sigma_f: I \rightarrow [X^*, Y]$ are the adjoint transforms of the composites

$$([X^*, Y] \otimes X) \otimes X^* \cong [X^*, Y] \otimes (X^* \otimes X) \xrightarrow{[X^*, Y] \otimes ((X^* \otimes i_1)\mu)} [X^*, Y] \otimes X^* \xrightarrow{\nu} Y$$

and $I \otimes X^* \cong X^* \xrightarrow{f} Y$ where $i_1: X \rightarrow X^*$ is the coproduct injection and v is the "evaluation" morphism or co-unit arising from the adjunction $\otimes \dashv [\ , \]$. Given $b: f \rightarrow f'$ in \mathbf{B}^X , let $bA = [X^*, b]$. Then $A: \mathbf{B}^X \rightarrow \mathbf{Aut}^X$ is a functor. Given $f \in |\mathbf{B}^X|$, let $\bar{f}: X^* \rightarrow [X^*, Y]$ be the unique X -automaton morphism $\langle X^*, \hat{\mu}, i_0 \rangle \rightarrow fA$. Let e_0 denote the composite $[X^*, Y] \cong [X^*, Y] \otimes I \xrightarrow{[X^*, Y] \otimes i_0} [X^*, Y] \otimes X^* \xrightarrow{v} Y$.

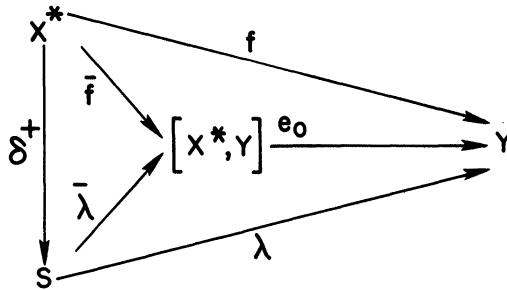
LEMMA 5. $\bar{f}e_0 = f$.

Now let M be an X -machine, and define $\bar{\lambda}: S \rightarrow [X^*, Y]$ to be the adjoint transform of the composite $S \otimes X^* \xrightarrow{\delta^+} S \xrightarrow{\lambda} Y$.

LEMMA 6. $\bar{\lambda}: S \rightarrow fA$ is an X -automaton morphism, and $\bar{\lambda}e_0 = \lambda$.

Note that by the uniqueness of X -automaton morphisms from $\langle X^*, \hat{\mu}, i_0 \rangle$, we must have $\delta^+ \bar{\lambda} = \overline{ME}$. These results are summarized as follows.

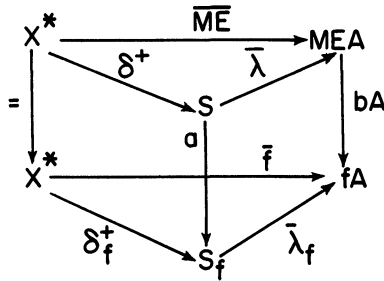
THEOREM 7 (INTRINSIC FACTORIZATION). *Given an X -machine M with behavior $f = ME$, the following commutes in \mathbf{C} :*



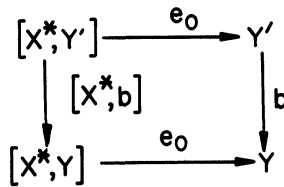
3. **Minimal realization.** Given a behavior $f: X^* \rightarrow Y$, let $\langle S_f, \delta_f, \sigma_f \rangle$ be the X -automaton coimage of the automaton morphism $\bar{f}: X^* \rightarrow [X^*, Y]$ (using Theorem 4). The automaton morphism $X^* \rightarrow S_f$ is epic in \mathbf{C} , and must be δ_f^+ by Theorem 3, so that this X -automaton is reachable. Let λ_f be the composite $S_f \rightarrow [X^*, Y] \xrightarrow{e_0} Y$, where the first map is the other part of the co-image factorization of \bar{f} (and incidentally is a strong monic in \mathbf{C}). Then $fN = \langle S_f, Y, \delta_f, \lambda_f, \sigma_f \rangle$ is the Nerode [8] realization of f . That $fNE = f$ follows from Lemma 5. That N is a functor $\mathbf{B}^X \rightarrow \mathbf{M}^X$ follows automatically from our main result, the universal property for fN . We sketch a proof, much of the work being contained in the previous results.

THEOREM 8. *Given a suitable category \mathbf{C} , $X \in |\mathbf{C}|$, and an X -behavior f , each morphism $ME \rightarrow f$ in \mathbf{B}^X with $M \in |\mathbf{M}^X|$ is gE for a unique $g: M \rightarrow fN$ in \mathbf{M}^X . Moreover, the state component of g is epic in \mathbf{C} .*

PROOF. Let $b: ME \rightarrow f$ in \mathbf{B}^X , and consider in \mathbf{Aut}^X the diagram



There is a unique $a: S \rightarrow S_f$ such that everything commutes, because δ^+ is epic, $\delta^+ \bar{\lambda}(bA) = \bar{f}$, and δ_f^+ is the co-image of \bar{f} . Because a is an automaton morphism $\langle a, b \rangle: M \rightarrow fN$ is in \mathbf{M}^X if $\lambda b = a \lambda_f$; but this follows from Lemma 6 by composing the right front square above with



the above square which commutes by naturality of the constructions involved. Now $\langle a, b \rangle E = b: ME \rightarrow fNE = f$ as required, and it remains to show $\langle a, b \rangle$ is the only X -automaton morphism such that $gE = b$, which follows since δ^+ is epic. \square

General lore [7] about adjoints now gives a number of results.

THEOREM 9. *The functor $E: \mathbf{M}^X \rightarrow \mathbf{B}^X$ has the Nerode functor $N: \mathbf{B}^X \rightarrow \mathbf{M}^X$ as a right adjoint left inverse.*

We say a machine M is *minimal* iff it is reachable and satisfies the following condition for some $f \in |\mathbf{B}^X|$: For any reachable X -machine M' and any morphism $h: M'E \rightarrow f$ in \mathbf{B}^X , there is a unique $g: M' \rightarrow M$ in \mathbf{M}^X such that $gE = h$. Then any two minimal realizations of f are isomorphic. We also say M is *reduced* iff the morphism $\bar{\lambda}: X \rightarrow [X^*, Y]$ is strong monic [6] in \mathbf{C} .

THEOREM 10. *fN is a minimal realization of $f \in |\mathbf{B}^X|$.*

THEOREM 11. *The full subcategory \mathbf{R}^X of \mathbf{M}^X with reduced machines as objects is reflective.*

THEOREM 12. *A machine is minimal iff reduced and reachable.*

Thus, M is a minimal realization of f iff M is reduced, reachable, and realizes f . This suggests the following globalization: *A minimal realization functor* is a right adjoint left inverse to the behavior functor. The Nerode function is one by Theorem 9, the proof of which also shows that N is a minimal realization functor iff each fN is reduced (or equivalently by Theorem 12, minimal, since it is already reachable) and realizes f . Moreover, since it is a right adjoint, a minimal realization functor preserves all (inverse) limits, for example products, and also monics. The adjunction $E \dashv N$ has a unit natural transformation $\eta: M^X \rightarrow EN$, called the *reduction transform* since $\eta_M: M \rightarrow MEN$ takes a machine to its reduced form; and $N: B^X \rightarrow M^X$ is a minimal realization functor iff $NE = B^X$ and there is a natural transformation $\eta: M^X \rightarrow EN$ such that $\eta E = E$ and $N\eta = N$. Moreover, in this case each η_M has epic state component.

4. Realization in subcategories. A pair M_1, B_1 of subcategories of M^X, B^X is *appropriate* iff the restrictions of N and E to B_1 and M_1 factor through M_1 and B_1 (respectively) giving $N_1: B_1 \rightarrow M_1$ right adjoint left inverse to $E_1: B_1 \rightarrow M_1$. Since E_1 is a right inverse, it is surjective, so that $B_1 = M_1 E$. Clearly all results of §3 hold for an appropriate pair of subcategories: fN_1 is minimal and reduced; N_1 preserves limits and monics; the adjunction's unit η^1 satisfies $\eta^1 E_1 = E_1$ and $N_1 \eta^1 = N_1$; and each η_M^1 has epic state component.

PROPOSITION 13. *Let C_1, C_2 be subcategories of C , let $X \in |C|$, and let $M_1 = M^X(C_1, C_2)$ be the subcategory of M^X with state components (of machines and morphisms) in C_1 and output components in C_2 . If C_1 is closed under quotients (i.e., all epics of C with domain in C_1 lie in C_1), then $M_1^X, B_1^X = M_1^X E$ is an appropriate pair.*

For $X, Y \in |C|$ and C_1 a subcategory of C , let $M^{X,Y}(C_1) = M^X(C_1, \{Y\})$, where $\{Y\}$ is the subcategory of C with only the object Y and its identity. Write $M^{X,Y}$ for $M^{X,Y}(C)$.

COROLLARY 14. *$M^{X,Y}, M^{X,Y} E$ is an appropriate pair; and if C_1 is closed under quotients, so is $M^{X,Y}(C_1), M^{X,Y}(C_1) E$.*

5. Applications. The category of sets is suitable with binary Cartesian product, giving a minimal realization theory for discrete (possibly infinite) machines. The full subcategory of finite sets is closed under quotients, so Proposition 13 gives the theory for standard finite automata. In this case, a realization M of f is minimal in our sense iff its state set has minimal cardinality among all finite realizations of f . Most results in §3

are new even for this well-studied case; see [4] for further discussion.

If Y is the two point set $\{0, 1\}$ and X is finite, then Corollary 14 gives an adjunction between finite state (or regular) languages and minimal acceptors.

The category of modules over a commutative ring K with unit is suitable with tensor product \otimes_K , and its full subcategory of finitely generated modules is closed under quotients. Because $\delta: S \otimes_K X \rightarrow S$ linear corresponds to $\delta: S \times X \rightarrow S$ bilinear, we call the machines in this theory *bilinear transition machines*. Actually, it is better for concrete applications to let C be the full subcategory with all K^S as objects, where S is a set giving a distinguished basis for the free module K^S . This is also suitable. The special case where $K = Y = 2$, the two point field, gives an adjunction between bilinear transition acceptors and (arbitrary) languages having the basis for X as alphabet, since these correspond naturally to linear $f: X^* \rightarrow 2$.

An *affine morphism* $A \rightarrow B$ between modules is a function of the form $f + b$, where $f: A \rightarrow B$ is linear and $b \in B$. The category Aff_K of modules over K with affine morphisms is suitable with *affine tensor product* $A \textcircled{A}_K B = A \otimes_K B + A + B$. We call the machines and behaviors: *affine* since $\delta: S \textcircled{A}_K X \rightarrow S$ affine corresponds to $\delta: S \times X \rightarrow S$ biaffine. The subcategory of finitely generated modules is closed under quotients. Again, it is better for applications to use the suitable subcategory with objects K^S . Indeed, these machines seem to give a better and richer model for physical systems than the usual linear systems. Because any linear $\delta: X \times X \rightarrow S$ is biaffine, the linear machines form a subcategory. But a minimal affine realization of a linear behavior can be simpler than any linear realization. Moreover, affine machines are richer in (loosely speaking) allowing multiplications between inputs and states. This type of machine and its minimal realization theory seem to be new.

The category *Kell* of all Kelley (often called compactly generated T_2) spaces [3] with binary Cartesian product is suitable. This gives a new minimal realization theory for continuous (generally nonlinear) machines. Here minimality cannot be expressed the traditional way, that some numerical characteristic of the state space is least, because Kelley spaces admit no such convenient number.

Finally we remark that the restriction to a fixed input object X can be removed; see [4].

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COMMITTEE ON INFORMATION SCIENCES, UNIVERSITY OF CHICAGO, CHICAGO, ILLINOIS 60637

MATHEMATICAL SCIENCE DEPARTMENT, THOMAS J. WATSON RESEARCH CENTER, I.B.M., YORKTOWN HEIGHTS, NEW YORK 10598 (current address)