

CONTRACTIVE PROJECTIONS AND PREDICTION OPERATORS¹

BY M. M. RAO

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1. Introduction. The purpose of this note is to present some results on characterizations of subspaces of a general class of Banach function spaces (BFS) admitting contractive projections onto them, and to include an application to nonlinear prediction (and approximation) theory.

Let L^ρ be the subspace of all measurable scalar functions f on (Ω, Σ, μ) with $\rho(f) = \rho(|f|) < \infty$, where $\rho(\cdot)$ is a function norm, i.e., a norm with the additional properties

(i) $0 \leq f_n \uparrow \Rightarrow \rho(f_n) \uparrow$, and

(ii) $\rho(\cdot)$ verifies the triangle inequality for infinite sums. Then L^ρ is also complete, called a BFS, (cf. [6] and [4]). It will also be assumed, for convenience, that $0 \leq f_n \uparrow f \Rightarrow \rho(f_n) \uparrow \rho(f)$, the Fatou property. $\rho(\cdot)$ is an absolutely continuous norm (a.c.n.) if for each $f \in L^\rho$, $\rho(f\chi_{A_n}) \rightarrow 0$ for any A_n in Σ , $A_n \downarrow \emptyset$. If \mathfrak{X} is a B -space, $L_{\mathfrak{X}}^\rho$ is the space of \mathfrak{X} -valued strongly measurable functions f on Ω , with $\rho(|f|_{\mathfrak{X}}) < \infty$, where $\rho(\cdot)$ is as above. Then $L_{\mathfrak{X}}^\rho$ is also complete. Finally let $\mathfrak{M}_{\mathfrak{X}}^\rho = \overline{\text{sp}}\{fx : f \in L^\rho, x \in \mathfrak{X}\} \subset L_{\mathfrak{X}}^\rho$. A projection is a linear idempotent operator.

The projection problem, stated at the outset, has been first treated for $L^\rho = L^1$ in [5], and a more detailed consideration of the same case, with $\mu(\Omega) < \infty$, has been given in [2]. If $L^\rho = L^p$, also with $\mu(\Omega) < \infty$, it was then considered in [1], and these results were extended for $L^\rho = L^\Phi$, the Orlicz spaces, with a.c.n. and μ σ -finite, in [10]. The general solution of the problem in the scalar case, and a less general one in the vector case, will be given below.

2. Contractive projections. Let $\mathfrak{S} \subset L^\rho$ be a closed subspace. If $L^\rho \neq L^2$, then, as is well known, not every \mathfrak{S} is the range of a bounded projection. The positive solution is given by the following result for L^ρ -spaces. (An operator T is positive if $Tf \geq 0$ for $f \geq 0$.)

THEOREM 1. *If (Ω, Σ, μ) is a measure space, let $L^\rho(\Sigma)$ be the BFS defined above. Consider the statements:*

- (a) \mathfrak{S} is the range of a (positive) contractive projection in $L^\rho(\Sigma)$.
- (b) there is an isometric isomorphism $\Psi: L^\rho(\Sigma) \rightarrow L^\rho(\Sigma)$, ($\Psi = \text{identity}$) such that

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(i) $\Psi(\mathcal{S})$ is a B -lattice, i.e., a selfadjoint space with real functions forming a lattice, and

(ii) $0 \leq f_n \in \Psi(\mathcal{S}), f_n \uparrow f, f \in L^p(\Sigma) \Rightarrow f \in \Psi(\mathcal{S})$.

(c) there is a (positive) isometric isomorphism between some $L^p(\mathcal{B})$ on some measure space (S, \mathcal{B}, μ_1) and \mathcal{S} .

(d) same as (c) except "topological equivalence" replaces "isometric isomorphism."

Then one has (c) \Rightarrow (a) \Leftrightarrow (b) \Rightarrow (d). In case $\rho(\cdot)$ also verifies, $\chi_A \in L^p(\Sigma)$ for each $A \in \Sigma$ with $\mu(A) < \infty$, then (a) \Leftrightarrow (c) also holds.

REMARK. If $\rho(f) = \int_0^1 |f| d\mu/x$, with $\Omega = [0, 1]$, $\mu = \text{Leb. meas.}$, then $\rho(\cdot)$ is a function norm, but $\rho(\chi_\Omega) = \infty$. Thus the last condition of the theorem is a restriction on ρ . It can be shown easily that $b(ii)$ automatically holds if ρ is an a.c.n., but will be needed otherwise.

This result is proved through several isomorphisms using equivalent measure spaces and the results of [13]. However, for an application of the latter, a first reduction is needed and is provided by the following result which has independent interest.

THEOREM 2. *If $L^p(\Sigma)$ is a BFS on (Ω, Σ, μ) , then there exists a measure space (S, \mathcal{B}, ν) where S is a locally compact space, \mathcal{B} is a σ -field generated by the compact subsets of S and ν is a measure assigning finite measure for compacts, in terms of which $L^p(S, \mathcal{B}, \nu)$, or $L^p(\mathcal{B})$, is isometrically (and lattice) isomorphic to $L^p(\Sigma)$. Moreover each f in $L^p(\mathcal{B})$ has a σ compact support. If there exists a strictly positive element in $L^p(\Sigma)$, then S can be chosen compact, so that (S, \mathcal{B}, ν) is a finite measure space.*

If μ is σ -finite then a strictly positive element always exists in $L^p(\Sigma)$ (e.g., a weak unit, cf. [6, p. 153]) and the last part contains this case. This result is proved using a method of proof of ([8, Theorem 2.1]) and some results of [13]. (See also [3] for the L^1 -case.) With this reduction, the problem of Theorem 1 can be transferred to $L^p(\mathcal{B})$. Then it can be isometrically embedded in $L^p(\tilde{\mathcal{B}})$ on a localizable measure space $(\tilde{S}, \tilde{\mathcal{B}}, \tilde{\nu})$ where \mathcal{B} goes, under an algebraic isomorphism, into a subring of $\tilde{\mathcal{B}}$, [13, Theorem 3.4]. Then the proof is successively reduced to the case of finite measure space where the methods and ideas of [2] and [10] can be generalized and used. In this way the full result of Theorem 1 is established.

In general there will be many contractive projections onto \mathcal{S} , when one exists. The following gives a uniqueness result.

PROPOSITION 3. *Suppose $L^p(\Sigma)$ is a rotund (= strictly convex) and smooth (= norm is Gâteaux differentiable) reflexive space on (Ω, Σ, μ) . Then a closed subspace $\mathcal{S} \subset L^p(\Sigma)$ can be the range of at most one contrac-*

tive projection. If in particular $\mathcal{S} = L^p(\mathcal{B})$, $\mathcal{B} \subset \Sigma$, a σ -field, then there exists a unique positive contractive projection onto \mathcal{S} , namely the (generalized) conditional expectation $E^{\mathcal{B}}: L^p(\Sigma) \rightarrow L^p(\mathcal{B})$.

The case of $L^p = L^p$, $1 < p < \infty$, $\mu(\Omega) < \infty$, of the above result was obtained in ([1, p. 392]). The general form of P is not-simple. The following case is illustrative.

PROPOSITION 4. *Let $P: L^p(\Sigma) \rightarrow L^p(\mathcal{B})$ be a contractive projection (which exists by Theorem 1), where $\mathcal{B} \subset \Sigma$ is a σ -field with $\mu_{\mathcal{B}}$ σ -finite, and $L^p(\Sigma)$ is a BFS. Then there exists a locally integrable function g such that*

- (i) $P(\cdot) = E^{\mathcal{B}}(g \cdot)$, and
- (ii) $E^{\mathcal{B}}(g) = 1$ a.e., where $E^{\mathcal{B}}$ is the conditional expectation relative to \mathcal{B} .

This shows that while $E^{\mathcal{B}}$ itself is a contractive projection onto $L^p(\mathcal{B})$, it is not the general form of the operator. If ρ is an a.c.n., then it can be shown that $g = 1$ a.e. here, and this is not necessarily true in the general case. The above two results are proved by an extension of the methods of [10]. A special case of the above proposition for L^{Φ} -spaces, with $\mu(\Omega) < \infty$, was discussed in [11].

For the case of $\mathfrak{M}_{\mathfrak{X}}^{\mathfrak{L}}$ spaces, the following result holds.

THEOREM 5. *Let $L^p(\Sigma)$ and $\mathfrak{M}_{\mathfrak{X}}^{\mathfrak{L}}$ be as defined in §1. If $\mathcal{S} \subset L^p(\Sigma)$ is a closed subspace, let $\mathcal{S}_{\mathfrak{X}} = \overline{\text{sp}} \{fx: f \in \mathcal{S}, x \in \mathfrak{X}\} \subset \mathfrak{M}_{\mathfrak{X}}^{\mathfrak{L}}$. Also let $\chi_A \in L^p(\Sigma)$ for each $A \in \Sigma$ with $\mu(A) < \infty$. Then the following four statements are equivalent:*

- (i) \exists contractive projection $P: L^p(\Sigma) \rightarrow \mathcal{S}$.
- (ii) \exists contractive projection $P: \mathfrak{M}_{\mathfrak{X}}^{\mathfrak{L}} \rightarrow \mathcal{S}_{\mathfrak{X}}$.
- (iii) $\exists L^p(\mathcal{B}_1, \mu_1)$, on some measure space $(S_1, \mathcal{B}_1, \mu_1)$ and \mathcal{S} is isometrically isomorphic to $L^p(\mathcal{B}_1, \mu_1)$.
- (iv) $\mathcal{S}_{\mathfrak{X}}$ is isometrically isomorphic to $\mathfrak{M}_{\mathfrak{X}}^{\mathfrak{L}}(\mathcal{B}_1, \mu_1)$.

This result is proved on using Theorem 1, and the fact that $L^p \otimes_{\gamma} \mathfrak{X} \subset \mathfrak{M}_{\mathfrak{X}}^{\mathfrak{L}}$ and is dense in the latter (see [9]). Here \otimes_{γ} is the greatest cross-norm, and one then uses a result on projections in cross-spaces [12, p. 58]. The general case of $L_{\mathfrak{X}}^p$ itself does not seem to follow in this way. The above one already includes the $L_{\mathfrak{X}}^p$, $1 \leq p \leq \infty$ case.

3. Prediction operators. A subspace $M \subset L^p$ is said to be a *Tshebyshev subspace* if for each $x \in L^p$ there is a unique $x_0 \in M$ with $\rho(x - x_0) = \min \{\rho(x - y): y \in M\}$. The operator $P_M: x \rightarrow x_0 \in M$, is

called a *prediction operator* in nonlinear prediction theory. Though $P_M^2 = P_M$, it is not linear in general. If it is linear, the powerful methods of linear analysis will be available in their study. So this is a natural question to treat. If P_M is linear, then $Q = I - P_M$ is a contractive projection with M as its null space (and the converse also holds). This is the connection between projections and predictions, and a solution can be presented as follows.

THEOREM 6. *Let $M \subset L^p$ be a Tshebyshev subspace, and P_M be the prediction operator for M . If P_M is linear then the quotient space L^p/M is topologically equivalent to $L^p(\mathfrak{B})$ on some measure space (S, \mathfrak{B}, μ_1) . Conversely, if L^p/M is isometrically isomorphic to $L^p(\mathfrak{B})$ on some (S, \mathfrak{B}, μ_1) then P_M is linear.*

In case $\chi_A \in L^p$ for each $A \in \Sigma$, $\mu(A) < \infty$, then the above can be stated as: P_M is linear $\Leftrightarrow L^p/M$ is isometrically isomorphic to an $L^p(\mathfrak{B})$. If $L^p = L^p$, $1 < p < \infty$, $\mu(\Omega) < \infty$, the latter has been obtained in [1]. The general case can be proved quickly with the results of the preceding section. However, it was noted in [10], that for the case $L^p \neq L^2$, M must be relatively complicated since P_M will not be linear if M is of the form $L^p(\Sigma_1)$, $\Sigma_1 \subset \Sigma$, a σ -field.

The proofs of all the results above involve first a characterization of the adjoint space $(L^p)^*$ of L^p . This is involved. It is obtained by generalizing the work of ([7] and [4]) appropriately. With these results (and those of [9]), and of [13], the above bare sketch is completed. The details and related results will be published separately.

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MATHEMATISCHE INSTITUT DER UNIVERSITÄT, WIEN, AND
CARNEGIE-MELLON UNIVERSITY, PITTSBURGH, PENNSYLVANIA 15213