## SYMMETRY IN NONSELFADJOINT STURM-LIOUVILLE SYSTEMS

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Suppose that a < b and C is the inner product space of all continuous real-valued functions on [a, b] such that  $||f|| = (\int_a^b f^2)^{1/2}$  if f is in C. Denote by each of p and q a member of C such that p(x) > 0 for all x in [a, b]. Denote by each of W and Q a real  $2 \times 2$  matrix and denote by C' the subspace of C consisting of all f in C such that (pf')' - qf is in C and

$$W\begin{bmatrix} f'(a) \\ p(a)f'(a) \end{bmatrix} + Q\begin{bmatrix} f'(b) \\ p(b)f'(b) \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}.$$

Denote by L the transformation from C' to C such that if f is in C', then Lf = (pf')' - qf. Assume for the remainder of this note that L has an inverse T. The purpose of this note is to point out that if  $T \neq T^*$  it is nevertheless true that T is very closely related to a symmetric operator. Specifically T is a dilation (via the two-dimensional space of solutions to the homogeneous equation) of a symmetric operator. This fact permits an analysis of T using the theory of completely continuous symmetric operators. This suggests a worthwhile alternative to the approach taken in [1, Chapter 12], in which the general theory of completely continuous operators is used.

Denote by S' the subspace of C consisting of all f so that (pf')' - qf = 0 and denote by S the orthogonal complement in C of S'. Denote by P the orthogonal projection of C onto S'.

THEOREM 1. If  $T \neq T^*$ , then  $Tg = T^*g$  if and only if g is in S.

THEOREM 2. If V is the restriction of (I-P)T to S, then  $V^* = V$ .

INDICATION OF PROOF OF THEOREM 1. From [2] one has that if g is in C, then the member f of C' so that Lf = g is such that

$$\begin{bmatrix} f(t) \\ p(t)f'(t) \end{bmatrix} = \int_{a}^{b} \begin{bmatrix} K_{11}(t,j)K_{12}(t,j) \\ K_{21}(t,j)K_{22}(t,j) \end{bmatrix} \begin{bmatrix} 0 \\ g \end{bmatrix}$$

for all t in [a, b] (j(x) = x if x is in [a, b]) where

$$\begin{bmatrix}
K_{11}(t, u) K_{12}(t, u) \\
K_{21}(t, u) K_{22}(t, u)
\end{bmatrix} = K(t, u)$$

$$= \begin{cases}
M(t, a) [W + QM(b, a)]^{-1} W M(a, u) & \text{if } a \leq u \leq t, \\
-M(t, a) [W + QM(b, a)]^{-1} Q M(b, a) M(a, u) & \text{if } t < u \leq b
\end{cases}$$

and M is such that

$$\begin{split} M(t,u) &= \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} + \int_{u}^{t} \begin{bmatrix} 0 & 1/p \\ q & 0 \end{bmatrix} M(j,u) \quad \text{for all } t,u \text{ in } [a,b]. \\ M \text{ is denoted by } \begin{bmatrix} A & B \\ C & D \end{bmatrix}, \end{split}$$

QM(b, a) by Z and det [W+Z] by  $\Delta$ . Straightforward computation gives that

$$\Delta K_{12}(t, u)$$

$$= \begin{cases} A(t, a) \left[ \det W + (\hat{Z}W)_{11} \right] B(a, u) + B(t, a) (\hat{Z}W)_{21} B(a, u) \\ + A(t, a) (\hat{Z}W)_{12} D(a, u) + B(t, a) \left[ \det W + (\hat{Z}W)_{22} \right] D(a, u) \\ & \text{if } a \leq u \leq t \\ - \left\{ A(t, a) \left[ \det Z + (\hat{W}Z)_{11} \right] B(a, u) + B(t, a) (\hat{W}Z)_{21} B(a, u) \\ + A(t, a) (\hat{W}Z)_{12} D(a, u) + B(t, a) \left[ \det Z + (\hat{W}Z)_{22} \right] D(a, u) \right\} \\ & \text{if } t < u \leq b \end{cases}$$

$$= \begin{cases} B(t, u) \det W - A(t, a) B(u, a) (\hat{Z}W)_{11} + A(t, a) A(u, a) (\hat{Z}W)_{12} \\ - B(t, a) B(u, a) (\hat{Z}W)_{21} + B(t, a) A(u, a) (\hat{Z}W)_{22} \end{cases}$$

$$= \begin{cases} B(t, u) \det Z + A(t, a) B(u, a) (\hat{W}Z)_{11} - A(t, a) A(u, a) (\hat{W}Z)_{12} \\ + B(t, a) B(u, a) (\hat{W}Z)_{21} - B(t, a) A(u, a) (\hat{W}Z)_{22} \end{cases}$$

$$= \begin{cases} B(t, u) \det Z + A(t, a) B(u, a) (\hat{W}Z)_{11} - A(t, a) A(u, a) (\hat{W}Z)_{12} \\ + B(t, a) B(u, a) (\hat{W}Z)_{21} - B(t, a) A(u, a) (\hat{W}Z)_{22} \end{cases}$$

$$= \begin{cases} B(t, u) \det Z + A(t, a) B(u, a) (\hat{W}Z)_{11} - A(t, a) A(u, a) (\hat{W}Z)_{12} \\ + B(t, a) B(u, a) (\hat{W}Z)_{21} - B(t, a) A(u, a) (\hat{W}Z)_{22} \end{cases}$$

since A(x, y) = D(y, x), B(x, y) = -B(y, x) and C(x, y) = -C(y, x) if x, y are in [a, b].

From this it follows that

$$K_{12}(y, x) - K_{12}(x, y) = (\det W - \det Q)B(y, x)/\Delta$$

for all x, y in [a, b]. Noting that if g is in C, then the member f of C' so that Lf = g is given by  $f(t) = \int_a^b K_{12}(t, j)g$  for all t in [a, b], one sees that  $(Tg)(t) = \int_a^b K_{12}(t, j)g$  for all t in [a, b] and g in C. Hence if g is in C and t is in [a, b],  $(T^*g)(t) = \int_a^b K_{12}(j, t)g$  and  $(Tg)(t) - (T^*g)(t) = \Delta^{-1}(\det W - \det Q) \int_a^b B(t, j)g$ . Hence if g is in S and t is

in [a, b], (Tg)(t) - (T\*g)(t) = 0 since B(t, j) is in S' inasmuch as B(j, t) = -A(j, a)B(t, a) + B(j, a)A(t, a).

Suppose  $T \neq T^*$ . Then det  $W - \det Q \neq 0$ . Hence if g is in C and  $Tg = T^*g$ , then  $0 = \int_a^b B(t,j)g = -A(t,a) \int_a^b B(j,a)g + B(t,a) \int_a^b A(j,a)g$  for all t in [a, b] and hence  $\int_a^b B(j,a)g = 0 = \int_a^b A(j,a)g$ . Therefore g is in S.

PROOF of THEOREM 2. If each of h and g is in S, (Vh, g) = ((I-P)Th, g) = (Th, (I-P)g) = (h, T\*g) = (h, Tg) = ((I-P)h, Tg) = (h, (I-P)Tg) = (h, Vg) and so V\* = V.

## REFERENCES

- 1. E. A. Coddington and N. Levinson, Theory of ordinary differential equations, McGraw-Hill, New York, 1955.
- 2. J. W. Neuberger, Concerning boundary value problems, Pacific J. Math. 10 (1960), 1385-1392.

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