

The proof of Theorem 10.3 is similar, but with obvious modifications.

REFERENCES

1. Tibor Radó, *On convex functions*, Trans. Amer. Math. Soc. vol. 37 (1935) pp. 266-285.
2. H. B. Dwight, *Tables of integrals and other mathematical data*, Macmillan, 1934.
3. G. Pólya and G. Szegő, *Aufgaben und Lehrsätze aus der Analysis*, vol. 2, Berlin, Springer, 1925.
4. G. H. Hardy, J. E. Littlewood, and G. Pólya, *Inequalities*, Cambridge, 1934.

EMMANUEL MISSIONARY COLLEGE

A SIMPLE SUFFICIENT CONDITION THAT A METHOD OF SUMMABILITY BE STRONGER THAN CONVERGENCE

RALPH PALMER AGNEW

1. **Introduction.** A matrix a_{nk} of real or complex constants determines a transformation

$$(1) \quad \sigma_n = \sum_{k=1}^{\infty} a_{nk} s_k$$

and a method A of summability by means of which a given sequence s_1, s_2, \dots is summable to σ if the series in (1) converge and define numbers $\sigma_1, \sigma_2, \dots$ such that $\sigma_n \rightarrow \sigma$ as $n \rightarrow \infty$. If a sequence s_n is summable A , we say that $A \{s_n\}$ exists and that s_n belongs to the summability field of A . If s_n is summable A to σ , we say that $A \{s_n\} = \sigma$. The method A is regular if $A \{s_n\} = \lim s_n$ whenever $\lim s_n$ exists.

Toeplitz [1911] (reference in bibliography at end of this paper) proved that A is regular if and only if the three conditions

$$(2) \quad \sum_{k=1}^{\infty} |a_{nk}| \leq M, \quad n = 1, 2, 3, \dots,$$

$$(3) \quad \lim_{n \rightarrow \infty} a_{nk} = 0, \quad k = 1, 2, 3, \dots,$$

$$(4) \quad \lim_{n \rightarrow \infty} \sum_{k=1}^{\infty} a_{nk} = 1$$

are satisfied, M being a constant depending on the matrix a_{nk} . Immediately thereafter, Steinhaus [1911] proved that no regular A has a summability field containing all sequences; in fact, to each A correspond sequences, whose elements are zeros and ones, which are non-summable A . Actually, Toeplitz and Steinhaus considered only row-finite transformations, but their methods give the facts stated.

An attempt to prove that each regular A has a summability field containing some divergent sequences cannot succeed, because there exist regular methods A whose summability fields are identical with the class of convergent sequences. Convergence is the simplest example. A classic theorem of Mercer [1907] and its generalizations, known as Mercerian Theorems, provide further examples. More examples of less special forms have been given by Agnew [1932], Sunouchi [1934] and Radó [1938]. It is the purpose of this paper to prove and discuss the following theorem and a generalization of it.

THEOREM 1. *If A is regular and satisfies the condition*

$$(5) \quad \lim_{n,k \rightarrow \infty} a_{nk} = 0$$

then some divergent sequences of zeros and ones are summable A .

This theorem and the result of Steinhaus given above combine to yield the following theorem.

THEOREM 2. *If A is regular and satisfies (5), then some but not all divergent sequences of zeros and ones are summable A .*

It is of course well known and obvious that if the matrix a_{nk} has an inverse α_{nk} , in the sense that (1) holds if and only if

$$s_n = \sum_{k=1}^{\infty} \alpha_{nk} \sigma_k,$$

then at least one divergent sequence s_n is summable A (such that σ_n converges) if and only if the matrix α_{nk} fails to be conservative. The more general case in which the transformation (1) is reversible (in the sense of Mazur and Banach) was treated by J. D. Hill [1942]. The virtue of the criterion (5) lies in the fact that it is a simple criterion involving the matrix a_{nk} itself; it may be used when a_{nk} has no inverse, and when the inverse exists but is so complicated that the test for conservatism is not easily applied.

2. The condition (5). Each of the conditions (2), (3), and (4) has an obvious interpretation involving the matrix

$$(6) \quad \begin{matrix} a_{11}a_{12}a_{13} \cdots a_{1k} \cdots \\ a_{21}a_{22}a_{23} \cdots a_{2k} \cdots \\ \cdots \cdots \cdots \cdots \cdots \end{matrix}$$

For example, (3) means that the elements of each column form a sequence converging to zero. The meaning of (5) is, roughly, that $|a_{nk}|$ is near zero whenever both n and k are large.

When a matrix satisfies (2), (3), and (4), there are several conditions which imply and are implied by (5). One is the condition (8) displayed below; it says, in other words, that the limit in (3) is uniform over the set $k=1, 2, 3, \dots$.

3. A generalization of Theorem 1. While proving Theorem 1, we can, without introducing complications, prove the following more general theorem.

THEOREM 3. *If the matrix a_{nk} of A is such that*

$$(7) \quad \sum_{k=1}^{\infty} |a_{nk}| < \infty, \quad n = 1, 2, 3, \dots,$$

and

$$(8) \quad \lim_{n \rightarrow \infty} \max_{k=1,2,\dots} |a_{nk}| = 0,$$

then there is at least one divergent sequence, whose elements are zeros and ones, which is summable A .

Actually, the proof will show clearly that there are “many” such sequences summable A .

4. Proof of Theorem 3. Let a_{nk} be a matrix satisfying (7) and (8). We establish Theorem 3 by exhibiting a divergent sequence s_n , whose elements are all zeros and ones, which is summable A to zero. To simplify typography, we sometimes write $a(n, k)$ and $s(k)$ for a_{nk} and s_k . Let $\alpha(1), \alpha(2), \dots$ be a sequence, of positive numbers, which converges to 0 so rapidly that $n\alpha(n) \rightarrow 0$; for example, let $\alpha(n) = n^{-2}$. Let $\beta(1), \beta(2), \dots$ be a sequence, of positive numbers, which converges to 0. The hypothesis (8) implies existence of an increasing sequence $n(1) < n(2) < \dots$ of positive integers such that, for each $p=1, 2, \dots$,

$$(9) \quad |a_{n,k}| \leq \alpha(p), \quad n \geq n_p, k = 1, 2, \dots$$

Such a sequence $n(p)$ being fixed, the hypothesis (7) implies that if

$k(1), k(2), \dots$ is a sequence of integers which becomes infinite sufficiently rapidly, then, for each $p=1, 2, 3, \dots$,

$$(10) \quad \sum_{k=k(p)+1}^{\infty} |a_{n,k}| \leq \beta(p), \quad n_p \leq n < n_{p+1}.$$

Let a sequence $k(p)$ be fixed such that (10) holds and $k(p+1) > k(p) + 1$ for each $p=1, 2, \dots$. Let s_1, s_2, \dots be the particular sequence of zeros and ones defined by

$$(11) \quad \begin{array}{ll} s_k = 1, & k = k_1, k_2, k_3, \dots, \\ s_k = 0 & \text{otherwise.} \end{array}$$

Then $s_k = 1$ for an infinite set of k 's and $s_k = 0$ for an infinite set of k 's; hence the sequence is divergent. Moreover the transform $\sigma_1, \sigma_2, \dots$ of this sequence is such that, when $p=1, 2, 3, \dots$ and $n_p \leq n < n_{p+1}$,

$$\begin{aligned} |\sigma_n| &= \left| \sum_{k=1}^{\infty} a(n, k) s(k) \right| = \left| \sum_{j=1}^{\infty} a(n, k_j) \right| \\ &\leq \sum_{j=1}^p |a(n, k_j)| + \sum_{j=p+1}^{\infty} |a(n, k_j)| \\ &\leq \sum_{j=1}^p \alpha(p) + \sum_{k=k(p)+1}^{\infty} |a(n, k)| < p\alpha(p) + \beta(p). \end{aligned}$$

Therefore, since $p\alpha(p) \rightarrow 0$ and $\beta(p) \rightarrow 0$, $\sigma_n \rightarrow 0$. Thus the particular divergent sequence of zeros and ones is summable A to 0 and Theorem 3 is proved.

5. Relations between two methods of summability. Let B and C be two matrix methods of summability regular or not, of the form (1). It is the purpose of this section to discuss standard general procedures for determining relations between B and C , and to show how Theorems 1 and 3 may be used. One says that B includes C , or $B \supset C$, if $B\{s_n\} = C\{s_n\}$ whenever $C\{s_n\}$ exists; and that B is stronger than C if $B\{s_n\}$ exists whenever $C\{s_n\}$ exists, while $B\{s_n\}$ exists for at least one sequence for which $C\{s_n\}$ fails to exist. Two methods B and C are consistent if $B\{s_n\} = C\{s_n\}$ whenever both $B\{s_n\}$ and $C\{s_n\}$ exist, and are equivalent if $B\{s_n\} = C\{s_n\}$ whenever at least one of $B\{s_n\}$ and $C\{s_n\}$ exist.

For simplicity, we assume that C is triangular and has an inverse; this means that $c_{nk} = 0$ when $k > n$ and that $c_{nn} \neq 0$ for each $n=1, 2, \dots$. Let a_{nk} be the matrix of the transformation A defined by $A = BC^{-1}$. It is standard practice to use the fact that $B \supset C$

if and only if A is regular, that is, if and only if (2), (3), and (4) hold. If, in a particular case, one shows that (2), (3), and (4) hold, one knows that $B \supset C$; the methods must then be consistent, but it remains unknown whether (i) B and C are equivalent or (ii) B is stronger than C . If, in addition to (2), (3), and (4), one shows that (5) holds, then, by Theorem 1, B must be stronger than C .

There are cases in which, by reason of algebraic difficulties or by reason of actual failure of the conditions, one is unable to show that (2), (3), and (4) hold. (Those who work in the field know that the "norm condition" (2) is frequently the troublesome one.) It may nevertheless be possible to show that (7) and (8) hold. In such cases, Theorem 3 implies existence of sequences summable B but nonsummable C .

BIBLIOGRAPHY

Agnew, R. P., 1932. *On equivalence of methods of evaluation of sequences*, Tôhoku Math. J. vol. 35 (1932) pp. 244-252.

Hill, J. D., 1942. *Some properties of summability*, Duke Math. J. vol. 9 (1942) pp. 373-381.

Mercer, J., 1907. *On the limits of real variants*, Proc. London Math. Soc. (2) vol. 5 (1907) pp. 206-224.

Radó, R., 1938. *Some elementary Tauberian Theorems. I*, Quart. J. Math. Oxford Ser. vol. 9 (1938) pp. 274-282.

Steinhaus, H., 1911. *Quelques remarques sur la généralisation de la notion de limite* (in Polish), Prace Matematyczno-fizyczne vol. 22 (1911) pp. 121-134.

Sunouchi, G., 1934. *On a linear transformation of infinite sequences*, Proceedings of the Physico-Mathematical Society of Japan (3) vol. 16 (1934) pp. 161-163.

Toeplitz, O., 1911. *Über allgemeine lineare Mittelbildungen*, Prace Matematyczno-fizyczne vol. 22 (1911) pp. 113-119.

CORNELL UNIVERSITY