

INFINITESIMAL DEFORMATION OF THE  
SKEW HELICOID.

BY DR. L. P. EISENHART.

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CONSIDER the skew helicoid  $S$ , defined by the equations

$$(1) \quad x = u \cos v, \quad y = u \sin v, \quad z = av.$$

We shall show that the problem of the infinitesimal deformation of this surface can be completely solved.

By direct calculation we find

$$(2) \quad E = \sum \left( \frac{\partial x}{\partial u} \right)^2 = 1, \quad F = \sum \frac{\partial x}{\partial u} \frac{\partial x}{\partial v} = 0,$$

$$G = \sum \left( \frac{\partial x}{\partial v} \right)^2 = u^2 + a^2,$$

and

$$(3) \quad X, Y, Z = \frac{a \sin v, -a \cos v, u}{\sqrt{u^2 + a^2}}$$

where  $Y, X, Z$  denote the direction cosines of the normal. Again we find

$$(4) \quad D = \sum X \frac{\partial^2 x}{\partial u^2} = 0, \quad D' = \sum X \frac{\partial^2 x}{\partial u \partial v} = \frac{-a}{\sqrt{u^2 + a^2}},$$

$$D'' = \sum X \frac{\partial^2 x}{\partial v^2} = 0.$$

The characteristic equation of the deformation reduces in this case to

$$\frac{\partial^2 \phi}{\partial u \partial v} + \frac{u}{u^2 + a^2} \frac{\partial \phi}{\partial v} = 0,$$

of which the general integral is

$$(5) \quad \phi = \frac{U + V}{\sqrt{u^2 + a^2}},$$

where  $U$  is a function of  $u$  alone and  $V$  is a function of  $v$  alone.

The cartesian cöordinates of the surface  $S_1$ , corresponding to  $S$  with orthogonality of linear elements, have the following expressions :\*

$$(6) \quad \begin{aligned} x_1 &= (U + V) \sin v - 2 \int \sin v \cdot V' dv, \\ y_1 &= -(U + V) \cos v + 2 \int \cos v \cdot V' dv, \\ z_1 &= -\frac{1}{a} [(U + V)u - 2 \int u \cdot U' du], \end{aligned}$$

where the accent denotes differentiation. From (6) we have that, when  $V$  is a constant,  $S_1$  is a surface of revolution. Moreover, since these formulæ involve an arbitrary function of  $u$ , it follows that any surface of revolution can be defined by them.

Conversely, *given a surface of revolution defined by*

$$x = u \cos v, \quad y = u \sin v, \quad z = U;$$

*the helicoid with plane director, whose equations are*

$$\bar{x} = U_1 \sin v, \quad \bar{y} = -U_1 \cos v, \quad \bar{z} = av,$$

*has the same axis and corresponds with orthogonality of linear elements, if*

$$U_1 = au \int \frac{U'}{u^2} du,$$

where the accent denotes differentiation with respect to  $u$ .

By direct calculation we find from (6),

$$(7) \quad F_1 = \sum \frac{\partial x_1}{\partial u} \frac{\partial x_1}{\partial v} = \frac{V'}{a^2} [u(U + V) - (u^2 + a^2)U].$$

From (4) we see that the lines  $u = \text{const.}$ ,  $v = \text{const.}$  on  $S$  are asymptotic, and consequently the corresponding lines on  $S_1$  form a conjugate system. Hence it follows from (7) that *the necessary and sufficient condition that asymptotic lines on  $S$  cor-*

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\* Bianchi, *Lezioni*, p. 276.

respond to lines of curvature on  $S_1$  is that  $V' = 0$ , that is,  $S_1$  must be a surface of revolution.

From (5) we see that in the latter case  $\phi$  is a function of  $u$  alone. This, however, is a general property of the infinitesimal deformation of minimal surfaces. For, from the following formula, which we have established elsewhere,\*

$$F_1 = F\phi^2 + \frac{1}{K^2(EG - F^2)} \left( D \frac{\partial \phi}{\partial v} - D' \frac{\partial \phi}{\partial u} \right) \left( D' \frac{\partial \phi}{\partial v} - D'' \frac{\partial \phi}{\partial u} \right),$$

it is seen that when  $S$  is a minimal surface referred to its asymptotic lines, the necessary and sufficient condition that the parametric lines on  $S_1$  be the lines of curvature is that  $\phi$  shall be a function of  $u$  alone or a function of  $v$  alone.

When in particular we take

$$(8) \quad U = \sqrt{u^2 + a^2}, \quad V = 0,$$

we get

$$\begin{aligned} x_1 &= \sqrt{u^2 + a^2} \cdot \sin v, & y_1 &= -\sqrt{u^2 + a^2} \cdot \cos v, \\ z_1 &= -a \log(u + \sqrt{u^2 + a^2}), \end{aligned}$$

which define the catenoid. From (5) we get  $\phi = 1$ , which is the case whenever, in the deformation of a minimal surface, the adjoint of the latter is taken for the surface  $S_1$ .†

Genty‡ has shown that the cartesian coördinates,  $x_0, y_0, z_0$ , of the associate surface §  $S_0$  in an infinitesimal deformation are given by the equations

$$\begin{aligned} dx_1 &= z_0 dy - y_0 dz, \\ dy_1 &= x_0 dz - z_0 dx, \\ dz_1 &= y_0 dx - x_0 dy. \end{aligned}$$

Substituting the expressions for  $x, y, \dots, z_1$ , from (1) and (6), and solving we find

$$(9) \quad \begin{aligned} x_0 &= \frac{1}{a} [(U + V - uU') \sin v + V' \cdot \cos v], \\ y_0 &= \frac{1}{a} [-(U + V - uU') \cos v + V' \cdot \sin v], \\ z_0 &= U'. \end{aligned}$$

\* *Amer. Jour. of Math.*, vol. 24, p. 177.

† *Ibid.*, p. 192.

‡ *Toulouse Annales*, vol. 9.

§ Bianchi, *l. c.*, p. 279.

The linear element of  $S_0$  is readily found to be

$$(10) \quad ds_0^2 = \frac{U''^2}{a^2} (u^2 + a^2) du^2 + \frac{1}{a^2} (V'' + V - uU' + U)^2 dv^2.$$

It is well known that the lines upon any associate surface corresponding to the asymptotic lines on  $S$  form a conjugate system. From (10) we see that the conjugate system on  $S_0$  corresponding to asymptotic lines on  $S$  are the lines of curvature. Furthermore, the lines of curvature  $v = \text{const.}$  are geodesics and consequently  $S_0$  is a surface of Monge.\* From the form of the coefficient of  $dv^2$  in (10) we have that the generating developable is a cylinder.† Hence

*In any infinitesimal deformation of a skew helicoid the associate surface is a moulure surface.*

Conversely, given any moulure surface; its equations can be put in the form (9) and then can be taken for the associate surface in the deformation of the helicoid (1), corresponding to the value  $(U + V)(u^2 + a^2)^{-\frac{1}{2}}$  of the characteristic function.

From (6) and (9) we get the

**THEOREM:** *When the surface  $S_1$  in an infinitesimal deformation of a skew helicoid is a surface of revolution, the associate surface  $S_0$  also is a surface of revolution, and their lines of curvature correspond.*

And conversely,

*When the associate surface  $S_0$  is a surface of revolution, the characteristic surface  $S_1$  is a surface of revolution.*

When in particular  $S_1$  is the catenoid,  $S_0$  is the sphere of radius unity and center at the origin.

If we put

$$U = a \sqrt{u^2 + a^2} - au \log(u + \sqrt{u^2 + a^2}), \quad V = 0,$$

the formulæ (9) define the catenoid. We have shown‡ that the necessary and sufficient condition that the lines of curvature be unaltered in the deformation of  $S$  is that  $S_0$  be the adjoint minimal surface of  $S$ . Hence, when

$$\phi = a \left[ 1 - \frac{u}{\sqrt{u^2 + a^2}} \log(u + \sqrt{u^2 + a^2}) \right],$$

\* Monge, *Applic. de l'Analyse à la Géométrie* 5 ed., chap. 25.

† Darboux, *Leçons*, vol. 1, p. 105.

‡ L. c., p. 199.

the corresponding deformation of  $S$  leaves the lines of curvature unaltered and only in this case.

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## ON INTEGRABILITY BY QUADRATURES.

BY DR. SAUL EPSTEEN.

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THE object of this note is to show that Vessiot's noted theorem that: "the necessary and sufficient condition that a linear differential equation shall be integrable by quadratures is that its group of rationality shall be integrable,"\* is a special case of the Jordan-Beke † theorem on reducibility of differential equations.

The Jordan-Beke theorem is to the effect that "if a linear differential equation is reducible in the sense of Frobenius ‡ then its group of rationality will transform a certain linear manifoldness of the solutions (which does not include the total  $n$ -dimensional manifoldness) into itself."

Analytically interpreted § this says that the group

$$\begin{aligned}
 y_1 &= a_{11}y_1 + \cdots + a_{1k}y_k \\
 &\cdot \quad \cdot \quad \cdot \quad \cdot \quad \cdot \quad \cdot \\
 y_k &= a_{k1}y_1 + \cdots + a_{kk}y_k, \\
 (1) \quad y_{k+1} &= a_{k+1,1}y_1 + \cdots + a_{k+1,k}y_k + a_{k+1,k+1}y_{k+1} + \cdots + a_{k+1,n}y_n, \\
 &\cdot \quad \cdot \quad \cdot \quad \cdot \quad \cdot \quad \cdot \quad \cdot \quad \cdot \quad \cdot \quad \cdot \quad \cdot \quad \cdot \\
 y_n &= a_{n1}y_1 + \cdots + a_{nk}y_k + a_{n,k+1}y_{k+1} + \cdots + a_{nn}y_n,
 \end{aligned}$$

is isomorphic with the group of rationality. For convenience it is well to adopt Loewy's notation, writing for (1) simply the coefficients

\* Vessiot: *Ann. de l'Ec. nor. sup.*, 1892.

† C. Jordan. *Bull. de la Soc. Math. de France*, vol. 2; Beke: *Math. Annalen*, vol. 45, p. 279.

‡ Frobenius: *Crelle*, vol. 76.

§ A. Loewy: "Ueber die irreduciblen Factoren," etc., *Berichte der math.-phy. Classe der Königl. Sächs. Gesellschaft der Wissenschaften zu Leipzig*, vol. 54 (1902), pp. 1-13.