

A rigid Calabi–Yau three-fold

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Abstract

The aim of this paper is to analyze some geometric properties of the rigid Calabi–Yau three-fold \mathcal{Z} obtained by a quotient of E^3 , where E is a specific elliptic curve. We describe the cohomology of \mathcal{Z} and give a simple formula for the trilinear form on $\text{Pic}(\mathcal{Z})$. We describe some projective models of \mathcal{Z} and relate these to its generalized mirror. A smoothing of a singular model is a Calabi–Yau three-fold with small Hodge numbers which was not known before.

1 Introduction

One of the most exciting mathematical implications of string theory is mirror symmetry, which finds its origin in the papers [13, 28]. A phenomenological verification of the conjecture that Calabi–Yau manifolds should appear in pairs was given in [11], and the first nontrivial examples of mirror pairs appeared in [20]. In [20], it was also discovered that mirror symmetry can be used to compute the instanton corrections to the Yukawa couplings (the

first explicit computations were carried out in [7]), which mathematically corresponds to determine the number of rational curves of given degree embedded in the Calabi–Yau manifold. This led to the notion of Gromov–Witten invariants and more generally to the one of Gopakumar–Vafa invariants [21, 22].

Curiously, in the seminal paper [10], where the relevance of Calabi–Yau manifolds in string theory was established, among the few explicit known examples of Calabi–Yau manifolds there was the manifold \mathcal{Z} , realized as the desingularization of the quotient E^3/φ_3 , with $\varphi_3 = \varphi \times \varphi \times \varphi$ and φ the generator of \mathbb{Z}_3 which acts on the elliptic curve E . As \mathcal{Z} is a rigid manifold, it cannot admit a Calabi–Yau three-fold as mirror partner. This created a puzzle in the general framework of mirror symmetry. However, physically, mirror symmetry arises as a complete equivalence between conformal field theories. In this respect, it should not be surprising that in certain exceptional cases the equivalence could involve more general spaces. Indeed, in [8] it was proposed that the mirror of \mathcal{Z} should be a cubic in \mathbb{P}^8 quotiented by a suitable finite group. By using the usual mirror methods, the authors were able to reproduce the right Yukawa couplings of \mathcal{Z} . The mirror symmetry generalized to rigid Calabi–Yau manifolds has been considered also in [32], where the mirror is presented as (embedded in) a higher dimensional Fano variety having the mirror diamond as an embedded sub-diamond and in [1], where it is related to toric geometry. However, a definitive understanding of the question is still open.

In this paper, as a preparation to further work on generalized mirror symmetry, we present a very detailed study of the rigid manifold \mathcal{Z} . Section 2 is devoted to an explicit description of the cohomology of \mathcal{Z} . The Hodge diamond of this three-fold is very well known, but here we identify a set of generators of $\text{Pic}(\mathcal{Z})$ made up of surfaces and a set of generators of $H^4(\mathcal{Z}, \mathbb{Q})$ made up of curves. Our goal is to describe the trilinear intersection form on the generators of $\text{Pic}(\mathcal{Z})$ relating it with the trilinear intersection form on $\text{Pic}(E^3)$. Indeed the generators of $\text{Pic}(\mathcal{Z})$ are of two types: the ones coming from the generators of $\text{Pic}(E^3)$ and the ones coming from the resolution of the singularities of E^3/φ_3 . The intersection between two divisors of different type is zero, and the trilinear form on the divisors coming from E^3 is, up to a constant, the trilinear form $\text{Pic}(E^3)$. For this reason it is important to give a good description of the trilinear form on $\text{Pic}(E^3)$: in (4) the cubic self-intersection form is given for each divisor in $\text{Pic}(E^3)$. In Section 3, Theorem 3.1, we prove that it can be given in terms of the determinant of a matrix in $\text{Mat}_{3,3}(\mathbb{Q}[\zeta])$, $\zeta^3 = 1$. The locus, where the determinant vanishes is a singular cubic in \mathbb{P}^8 . We recall that the Yukawa coupling on $H^{1,1}$ is strongly related with the cup product on $H^{1,1}$ and thus with the intersection form on $\text{Pic}(E^3)$. Moreover the locus

where the Yukawa coupling vanishes, corresponds to fermion mass generation points.

In the second part of the paper, in Section 4, we describe some projective models of \mathcal{Z} . Here we will limit ourselves to make some basic observation on mirror symmetry, deferring a systematic analysis to a future paper. We give a detailed description of the images of three maps (called m_0, m_1, m_2) defined from \mathcal{Z} to projective spaces and we relate these to earlier work. None of the maps $m_i, i = 0, 1, 2$, gives an embedding. For this reason, we also prove that a certain divisor on \mathcal{Z} is very ample (cf. Proposition 4.12), i.e., it defines a map m such that $m(\mathcal{Z}) \simeq \mathcal{Z}$.

The maps $m_i, i = 0, 1, 2$, allow us to describe some peculiarities of \mathcal{Z} . The map m_0 is $3 : 1$ and it gives a model of another rigid Calabi–Yau three-fold \mathcal{Y} , birational to \mathcal{Z}/\mathbb{Z}_3 . Moreover $m_0(\mathcal{Z})$ is contained in the Fermat cubic hypersurface in \mathbb{P}^8 and this could give a geometrical interpretation of the conjectures on the generalized mirrors of the rigid Calabi–Yau three-folds \mathcal{Z} and \mathcal{Y} presented in [8, 26]. The map m_1 contracts 27 rational curves on \mathcal{Z} , and gives a model of \mathcal{Z} embedded in \mathbb{P}^{11} . This model will be used in Section 6 to obtain other Calabi–Yau three-folds. The map m_2 was already defined by Kimura [25] to show that there exists a birational map between \mathcal{Z} and a particular complete intersection of two cubics in \mathbb{P}^5 , called $V_{3,3}$. Several models of the variety $V_{3,3}$ were analyzed previously (cf. [24, 37, 29]).

We already observed that the Calabi–Yau three-fold \mathcal{Z} is very well known, but it can be used to construct several other Calabi–Yau three-folds, which are not always rigid. In Section 5, we recall constructions which produce Calabi–Yau three-folds starting from a given one. In Section 6, we apply one of these constructions (described in [15]) to \mathcal{Z} and we obtain non rigid Calabi–Yau three-folds. The idea is to contract some curves on \mathcal{Z} and then to consider the smoothing of the singular three-fold obtained. One of the Calabi–Yau three-folds constructed in this section does not appear in the list of known Calabi–Yau three-fold with small Hodge numbers given in [4] and is a new Calabi–Yau variety.

2 The three-folds $E^3, \widetilde{E}^3, \mathcal{Z}$ and their cohomology

In this note, we will analyze the properties of the very well known Calabi–Yau three-fold \mathcal{Z} introduced independently in [3, Example 2] and [34]. In order to describe the trilinear form on $\text{Pic}(\mathcal{Z})$ (cf. (8)), which is strongly related to the Yukawa coupling, we will compute the cohomology of \mathcal{Z} (Section 2.3) and of the varieties involved in its construction (Sections 2.1 and 2.2).

To fix the notation, we recall some definitions and the construction of \mathcal{Z} .

Definition 2.1. A smooth compact complex variety, X , is called a Calabi–Yau variety if it is a Kähler variety, it has a trivial canonical bundle and $h^{i,0}(X) = 0$ for $0 < i < \dim(X)$.

To give the Hodge diamond of a Calabi–Yau three-fold X one has to find $h^{1,1}(X)$ and $h^{2,1}(X)$. We recall that $h^{2,1}(X)$ is the dimension of the family of deformations of X (which are indeed unobstructed by the Tian–Todorov theorem), so X has $h^{2,1}(X)$ complex moduli.

Let E be the Fermat elliptic curve $x^3 + y^3 + z^3 = 0$, i.e., the elliptic curve admitting a complex multiplication of order 3. We will denote by $\varphi : E \rightarrow E$ the automorphism of E given by $(x, y, z) \mapsto (x, y, \zeta z)$, where ζ is a primitive third root of unity. Let E^3 be the Abelian three-fold $E \times E \times E$ and φ_3 be the automorphism $\varphi \times \varphi \times \varphi$ acting as φ on each factor of E^3 . The automorphism φ has three fixed points on E , which are called $p_i := (-1 : \zeta^i : 0)$, $i = 1, 2, 3$. Hence φ_3 fixes 27 points on E^3 , $p_{i,j,k} := (p_i; p_j; p_k)$, $i, j, k = 1, 2, 3$. Let $\alpha : E^3 \rightarrow E^3/\varphi_3$ be the quotient map. The three-fold E^3/φ_3 is singular and its singular locus consists of the 27 points $\alpha(p_{i,j,k})$. Let $\beta : \widetilde{E^3} \rightarrow E^3$ be the blow up of E^3 in the 27 points fixed by φ_3 . The exceptional locus consists of 27 disjoint copies of \mathbb{P}^2 , and the exceptional divisor over the point $p_{i,j,k}$ will be denoted by $\widetilde{B_{i,j,k}}$. The automorphism φ_3 of E^3 induces the automorphism $\widetilde{\varphi}_3$ on $\widetilde{E^3}$. Let $\mathcal{Z} := \widetilde{E^3}/\widetilde{\varphi}_3$ and $\pi : \widetilde{E^3} \rightarrow \widetilde{E^3}/\widetilde{\varphi}_3$ be the quotient map. The following diagram commutes:

$$\begin{array}{ccccc}
 \varphi_3 \circlearrowleft & E^3 & \xleftarrow{\beta} & \widetilde{E^3} & \circlearrowright \widetilde{\varphi}_3 \\
 & \alpha \downarrow & & \downarrow \pi & \\
 & E^3/\varphi_3 & \xleftarrow{\gamma} & \mathcal{Z} &
 \end{array}$$

where γ is the contraction of the divisors $\pi(\widetilde{B_{i,j,k}})$ to the singular points $\alpha(p_{i,j,k})$ of E^3/φ_3 .

The three-fold \mathcal{Z} is smooth (indeed the fixed locus of $\widetilde{\varphi}_3$ on $\widetilde{E^3}$ is of codimension 1) and is a Calabi–Yau three-fold.

2.1 The cohomology of E^3

The three-fold E^3 is an Abelian variety. Its canonical bundle is trivial and

$$H^{p,q}(E^3) = \bigoplus_{\substack{a_1+a_2+a_3=p, \\ b_1+b_2+b_3=q}} (H^{a_1,b_1}(E) \otimes H^{a_2,b_2}(E) \otimes H^{a_3,b_3}(E)).$$

Hence, the Hodge diamond of E^3 is

$$\begin{array}{ccccc}
 & & & & 1 \\
 & & & 3 & 3 \\
 & & 3 & 9 & 3 \\
 1 & 9 & 9 & 9 & 1
 \end{array}$$

Let z_i be the complex local coordinate of the i th copy of E in E^3 . Then $H^{1,0}(E^3) = \langle dz_1, dz_2, dz_3 \rangle$, $H^{2,0} = \langle dz_1 \wedge dz_2, dz_1 \wedge dz_3, dz_2 \wedge dz_3 \rangle$ and $H^{3,0}(E^3) = \langle dz_1 \wedge dz_2 \wedge dz_3 \rangle$.

The Picard group is generated by:

- Three classes Φ_i , $i = 1, 2, 3$, which are the classes of the fiber of the projection $\rho_i : E^3 \rightarrow E$ on the i -th factor, e.g., $\Phi_1 = \bar{q} \times E \times E$ for a general point $\bar{q} \in E$;
- Three classes Δ_i , $i = 1, 2, 3$, which are the product of the i th factor of E^3 by the diagonal on the other two factors, e.g., $\Delta_1 = E \times \Delta = \{E \times q \times q | q \in E\}$;
- Three classes Γ_i , $i = 1, 2, 3$, which are the product of the i th factor of E^3 by the graph on the other two factors, i.e., $\Gamma_1 = E \times \Gamma = \{E \times q \times \varphi(q) | q \in E\}$, $\Gamma_2 = \{\varphi(q) \times E \times q | q \in E\}$, $\Gamma_3 = \{q \times \varphi(q) \times E | q \in E\}$.

By the definition of the divisor Φ_i it is clear that $\Phi_i = \rho_i^*(\bar{q})$, where \bar{q} is a general point on E .

A similar description can be given for the divisors Δ_i and Γ_i . Indeed let $\rho_i : E^3 \rightarrow E$, $\tau_i : E^3 \rightarrow E$ and $\eta_i : E^3 \rightarrow E$ be the maps defined below, then:

$$\begin{aligned}
 \Phi_i &= \rho_i^*(P), & \rho_i &: (q_1, q_2, q_3) \mapsto q_i, \\
 \Delta_i &= \tau_i^*(P), & \tau_i &: (q_1, q_2, q_3) \mapsto q_j - q_k, \quad \{i, j, k\} = \{1, 2, 3\}, \\
 \Gamma_i &= \eta_i^*(P), & \eta_i &: (q_1, q_2, q_3) \mapsto (\varphi(q_{i+1}) - q_{i+2}), \quad \{i, i+1, i+2\} \\
 & & &= \{1, 2, 3\}, \quad i, i+1, i+2 \in \mathbb{Z}_3.
 \end{aligned} \tag{1}$$

We recall that $E \simeq \mathbb{R}^2/\Lambda \simeq \mathbb{C}/\Lambda$, where Λ is the lattice generated by 1 and ζ . Let (x_{2j-1}, x_{2j}) be the real coordinates of \mathbb{R}^2 relative to the j th copy of E and let the isomorphism $\mathbb{R}^2 \rightarrow \mathbb{C}$ be $(x_{2j-1}, x_{2j}) \rightarrow x_{2j-i} + \zeta x_{2j}$, $j = 1, 2, 3$. Each divisor D on E^3 is a linear combination of surfaces on the three-fold and defines a two-form, $c_1(D)$, in $H^2(E^3, \mathbb{Z})$. The classes of the nine divisors defined above can be found by pulling back the class of a point in $H^2(E, \mathbb{Z})$. The form associated to a point $q = y_1 + \zeta y_2$ on E is $dy_1 \wedge dy_2$. We will denote with the same name both the divisor and the corresponding form.

So:

$$\begin{aligned}
\Phi_1 &= \rho_1^*(dy_1 \wedge dy_2) = dx_1 \wedge dx_2, \\
\Phi_2 &= dx_3 \wedge dx_4, \\
\Phi_3 &= dx_5 \wedge dx_6, \\
\Delta_1 &= \tau_1^*(dy_1 \wedge dy_2) = d(x_3 - x_5) \wedge d(x_4 - x_6), \\
\Delta_2 &= d(x_1 - x_5) \wedge d(x_2 - x_6), \\
\Delta_3 &= d(x_1 - x_3) \wedge d(x_2 - x_4), \\
\Gamma_1 &= \eta_1^*(dy_1 \wedge dy_2) = d(x_5 + x_4) \wedge d(x_6 - x_3 + x_4), \\
\Gamma_2 &= d(x_1 + x_6) \wedge d(x_2 - x_5 + x_6), \\
\Gamma_3 &= d(x_3 + x_2) \wedge d(x_4 - x_1 + x_2).
\end{aligned}$$

In the last three lines we used: $\varphi(q) = \zeta q$, hence $\varphi(x_{2i-1} + \zeta x_{2i}) = \zeta x_{2i-1} + (-\zeta - 1)x_{2i} = -x_{2i} + \zeta(x_{2i-1} - x_{2i})$.

Let us now consider the space $H^{2,2}(E^3)$. We recall that $H^{2,2}(E^3)$ is the dual of $H^{1,1}(E^3)$ and in particular $H^{2,2}(E^3) \cap H^4(E^3, \mathbb{Z})$ is generated by nine four-forms, which are identified (via Poincaré duality) with nine one-cycles. A \mathbb{Q} -basis of $H^{2,2}(E^3) \cap H^4(E^3, \mathbb{Z})$ generated by classes of curves on E^3 , which are the pull back of the class of a general point $Q \in E \times E$ along certain maps $E^3 \rightarrow E \times E$, is:

$$\begin{aligned}
\phi_i &= \rho_{j,k}^*(Q), \quad \rho_{j,k} : (q_1, q_2, q_3) \mapsto (q_j, q_k), \quad i = 1, 2, 3, \quad \{i, j, k\} = \{1, 2, 3\} \\
\delta_i &= \tau_{j,k}^*(Q), \quad \tau_{j,k} : (q_1, q_2, q_3) \mapsto (q_i, q_j - q_k), \quad i = 1, 2, 3, \\
&\quad \{i, j, k\} = \{1, 2, 3\} \\
\gamma_i &= \eta_{j,k}^*(Q) \quad \eta_{j,k} : (q_1, q_2, q_3) \mapsto (q_i, \varphi(q_j) - q_k), \quad i = 1, 2, 3, \\
&\quad j = i + 1 \in \mathbb{Z}_3, k = i + 2 \in \mathbb{Z}_3.
\end{aligned}$$

One can directly check the following intersection products:

$$\begin{aligned}
\phi_i &= \Phi_j \Phi_k, \quad \{i, j, k\} = \{1, 2, 3\}, \quad i = 1, 2, 3, \delta_i = \Phi_i \Delta_i, \quad i = 1, 2, 3, \\
\gamma_i &= \Phi_i \Gamma_i, \quad i = 1, 2, 3.
\end{aligned} \tag{2}$$

As $\phi_i = \Phi_j \Phi_k$, its class in $H^4(E^3, \mathbb{Z})$ is the wedge product of the two-forms associated to Φ_j and Φ_k . The intersection between a divisor in $\text{Pic}(E^3)$ and a curve in $H^{2,2}(E^3)$ is the wedge product of a four-form and a two-form, hence it is an element in $H^6(E^3, \mathbb{Q}) \simeq \mathbb{Q}$, where the isomorphism is given by $dx_1 \wedge dx_2 \wedge dx_3 \wedge dx_4 \wedge dx_5 \wedge dx_6 \mapsto 1$. From this one finds the intersection numbers between the divisors generating $\text{Pic}(E^3)$ and the curves generating

$H^{2,2}(E^3)$:

	Φ_1	Φ_2	Φ_3	Δ_1	Δ_2	Δ_3	Γ_1	Γ_2	Γ_3
ϕ_1	1	0	0	0	1	1	0	1	1
ϕ_2	0	1	0	1	0	1	1	0	1
ϕ_3	0	0	1	1	1	0	1	1	0
δ_1	0	1	1	0	1	1	3	1	1
δ_2	1	0	1	1	0	1	1	3	1
δ_3	1	1	0	1	1	0	1	1	3
γ_1	0	1	1	3	1	1	0	1	1
γ_2	1	0	1	1	3	1	1	0	1
γ_3	1	1	0	1	1	3	1	1	0

(3)

Now (2) and (3) together give the cubic self-intersection form on $\text{Pic}(E^3)$:

$$\begin{aligned}
 \left(\sum_{i=1}^3 a_i \Phi_i + b_i \Delta_i + c_i \Gamma_i \right)^3 &= 6 \cdot \left(a_1 a_2 a_3 + \sum_{i < j} a_i a_j (b_i + b_j + c_i + c_j) \right. \\
 &+ \left(\sum_{i < j} b_i b_j \right) (a_1 + a_2 + a_3 + 3(c_1 + c_2 + c_3)) \\
 &+ \left(\sum_{i < j} c_i c_j \right) (a_1 + a_2 + a_3 + 3(b_1 + b_2 + b_3)) \\
 &\left. + (a_1 + a_2 + a_3)(b_1 + b_2 + b_3)(c_1 + c_2 + c_3) + 2 \sum_{i=1}^3 a_i b_i c_i - \sum_{i \neq j} a_i b_j c_j \right).
 \end{aligned}$$
(4)

From the cubic self-intersection form, one deduces the trilinear form on $\text{Pic}(E^3)$.

2.2 The cohomology of $\widetilde{E^3}$

The three-fold $\widetilde{E^3}$ is obtained by blowing up the 27 points $p_{i,j,k} := (p_i; p_j; p_k)$, $i, j, k = 1, 2, 3$, on E^3 and $\widetilde{B_{i,j,k}}$ are the exceptional divisors of this blow up. Hence, there is an isomorphism $\widetilde{E^3} - \bigcup \widetilde{B_{i,j,k}} \simeq E^3 - \bigcup p_{i,j,k}$. The numbers $h^{i,j}$ with i or j equal to zero are birational invariants, hence $h^{i,j}(\widetilde{E^3}) = h^{i,j}(E^3)$, if i or j are zero.

Let X be a projective manifold, S be a codimension r submanifold of X and \tilde{X} be a blow up of X in S . Then: $H^k(\tilde{X}, \mathbb{Z}) = H^k(X, \mathbb{Z}) \oplus \bigoplus_{i=0}^{r-2} H^{k-2i-2}(S, \mathbb{Z})$ ([35, Théorème 7.31]). Applying this result to $\widetilde{E^3}$, the blow up of E^3 in 27 points, we obtain the Hodge diamond of $\widetilde{E^3}$:

$$\begin{array}{cccc}
 & & 1 & \\
 & & 3 & 3 \\
 & 3 & 36 & 3 \\
 1 & 9 & 9 & 1
 \end{array}$$

Blowing up the 27 points, we introduced 27 exceptional divisors $\widetilde{B_{i,j,k}}$, hence $h^{1,1}(\widetilde{E^3}) = h^{1,1}(E^3) + 27$ and $H^{1,1}(\widetilde{E^3})$ is generated by the 36 classes:

$$\begin{aligned}
 \widetilde{F}_h &:= \beta^*(\Phi_h), \quad \widetilde{D}_h := \beta^*(\Delta_h), \quad \widetilde{G}_h := \beta^*(\Gamma_h), \quad h = 1, 2, 3, \\
 &\text{and by the classes } [\widetilde{B_{i,j,k}}], \quad i, j, k = 1, 2, 3.
 \end{aligned}$$

The divisors $\widetilde{F}_i, \widetilde{D}_i, \widetilde{G}_i$ are the classes of the strict transforms of $\Phi_i, \Delta_i, \Gamma_i$, indeed the Φ_i do not pass through the points $p_{i,j,k}$ and Δ_i, Γ_i are cohomologically equivalent to classes, which do not pass through $p_{i,j,k}$, for example Δ_1 is in the same class of $\{E \times q \times (q + q') \mid q \in E\}$ in $H^2(E^3, \mathbb{Z})$ for any $q' \in E$.

The intersection form on $H^{1,1}(\widetilde{E^3}) = \text{Pic}(\widetilde{E^3})$ is induced by the one on E^3 . More precisely:

- let L be a divisor in $\text{Pic}(E^3)$, then $\beta^*(L)\widetilde{B_{i,j,k}} = 0$, indeed all the divisors in $\text{Pic}(E^3)$ are linear combinations of Φ_i, Δ_i and Γ_i and all these divisors are equivalent to divisors, which do not pass through the points p_{ijk} and thus their strict transforms do not intersect the exceptional divisors;
- similarly, for $L_1, L_2, L_3 \in \text{Pic}(E^3)$ we have $\beta^*(L_1)\beta^*(L_2)\beta^*(L_3) = \widetilde{L_1 L_2 L_3}$;
- $\widetilde{B_{i,j,k}}\widetilde{B_{h,l,m}} = 0$, if $(i, j, k) \neq (h, l, m)$, because they are exceptional divisors over distinct points;
- $\widetilde{B_{i,j,k}}^3 = 1$ (see (5)).

Dually the space $H^{2,2}(\widetilde{E^3})$ is generated by 36 classes. We give a \mathbb{Q} -basis of $H^{2,2}(\widetilde{E^3}) \cap H^4(\widetilde{E^3}, \mathbb{Z})$ made up of curves. Nine of them are the pull-back via β of the classes of the curves generating $H^{2,2}(E^3)$ ($\widetilde{f}_i = \beta^*(\phi_i), \widetilde{d}_i = \beta^*(\delta_i), \widetilde{g}_i = \beta^*(\gamma_i)$) and the other 27 are the classes of the lines $\widetilde{l_{i,j,k}}$ which generate the Picard group of the exceptional divisors $\widetilde{B_{i,j,k}}$.

By the adjunction formula, the canonical divisor of $\widetilde{B}_{i,j,k}$ is

$$\begin{aligned} K_{\widetilde{B}_{i,j,k}} &= \left(\widetilde{B}_{i,j,k} + K_{\widetilde{E^3}} \right) \widetilde{B}_{i,j,k} \\ &= \left(\widetilde{B}_{i,j,k} + \beta^*(K_{E^3}) + 2 \sum_{i,j,k} \widetilde{B}_{i,j,k} \right) \widetilde{B}_{i,j,k} = 3\widetilde{B}_{i,j,k}^2. \end{aligned}$$

Since $\widetilde{B}_{i,j,k} \simeq \mathbb{P}^2$, $K_{\widetilde{B}_{i,j,k}} = -3\widetilde{l}_{i,j,k}$, and comparing the two expressions of $K_{\widetilde{B}_{i,j,k}}$, we obtain $\widetilde{l}_{i,j,k} = -\widetilde{B}_{i,j,k}^2$. Moreover

$$1 = (-\widetilde{l}_{i,j,k})^2 = \widetilde{B}_{i,j,k}|_{\widetilde{B}_{i,j,k}} \cdot \widetilde{B}_{i,j,k}|_{\widetilde{B}_{i,j,k}} = (\widetilde{B}_{i,j,k} \cdot \widetilde{B}_{i,j,k})|_{\widetilde{B}_{i,j,k}} = \widetilde{B}_{i,j,k}^3. \tag{5}$$

The intersection form between the curves generating $H^{2,2}(\widetilde{E^3})$ and the divisors generating $H^{1,1}(\widetilde{E^3})$ is induced by the one on E^3 : if $c \in H^{2,2}(E^3)$ and $L \in H^{1,1}(E^3)$ are chosen among the classes appearing in table (3), then: $c \cdot L = \beta^*(c) \cdot \beta^*(L)$; $\beta^*(c)\widetilde{B}_{i,j,k} = \widetilde{l}_{i,j,k}\beta^*(L) = 0$; $\widetilde{l}_{i,j,k}\widetilde{B}_{i,j,k} = -\widetilde{B}_{i,j,k}^3 = -1$; $\widetilde{l}_{h,m,n}\widetilde{B}_{i,j,k} = 0$ if $(h, m, n) \neq (i, j, k)$.

2.3 The cohomology of \mathcal{Z}

The map $\widetilde{\varphi}_3$ (induced by φ_3) fixes the divisors $\widetilde{B}_{i,j,k}$ and is without fixed points on $\widetilde{E^3} - \bigcup_{i,j,k=1,2,3} \widetilde{B}_{i,j,k}$. So the fixed locus $Fix_{\widetilde{\varphi}}(\widetilde{E^3}) = \bigcup_{i,j,k=1,2,3} \widetilde{B}_{i,j,k}$ has codimension 1 and hence the three-fold \mathcal{Z} , which is the quotient $\widetilde{E^3}/\widetilde{\varphi}_3$, is smooth. Moreover, $H^{p,q}(\mathcal{Z}) = H^{p,q}(\widetilde{E^3})^{\widetilde{\varphi}_3}$. We recall that $H^{i,0}(\widetilde{E^3}) = H^{i,0}(E^3)$ and that the action of $\widetilde{\varphi}_3$ is $(z_1, z_2, z_3) \mapsto (\zeta z_1, \zeta z_2, \zeta z_3)$ (where z_i are the local complex coordinates of the i th copy of E). Now it is clear that $\beta^*(dz_i)$ and $\beta^*(dz_i \wedge dz_j)$, $i \neq j$, $i, j = 1, 2, 3$, are not invariant under the action of $\widetilde{\varphi}_3$, but that $\beta^*(dz_1 \wedge dz_2 \wedge dz_3)$ is invariant under $\widetilde{\varphi}_3$. We conclude that $H^{1,0}(\mathcal{Z}) = H^{0,1}(\mathcal{Z}) = H^{2,0}(\mathcal{Z}) = H^{0,2}(\mathcal{Z}) = 0$ and $H^{3,0}(\mathcal{Z}) = \mathbb{C}\omega_{\mathcal{Z}}$ with $\pi^*\omega_{\mathcal{Z}} = \beta^*(dz_1 \wedge dz_2 \wedge dz_3)$.

Analogously one can compute $H^{2,1}(\mathcal{Z}) = H^{2,1}(\widetilde{E^3})^{\widetilde{\varphi}_3}$. Since $H^{2,1}(\widetilde{E^3})$ is generated by $\beta^*(dz_i \wedge dz_j \wedge \overline{dz}_k)$ for $\{i, j, k\} = \{1, 2, 3\}$, which are not invariant under $\widetilde{\varphi}_3$, we obtain $H^{2,1}(\mathcal{Z}) = H^{1,2}(\mathcal{Z}) = 0$.

The divisors on $\widetilde{E^3}$ induce divisors on \mathcal{Z} . Since the map $(\widetilde{\varphi}_3)^*$ acts as the identity on $\text{Pic}(\widetilde{E^3})$, the map $\pi_* : \text{Pic}(\widetilde{E^3}) \otimes \mathbb{Q} \rightarrow \text{Pic}(\mathcal{Z}) \otimes \mathbb{Q}$ is bijective,

and hence, as we will see, the Picard group of \mathcal{Z} is generated by the 36 classes $\pi_*(\widetilde{F}_i), \pi_*(\widetilde{D}_i), \pi_*(\widetilde{G}_i), \pi_*(\widetilde{B}_{i,j,k}), i, j, k = 1, 2, 3$, at least over \mathbb{Q} and we observe that $\text{Pic}(\mathcal{Z}) \otimes \mathbb{Q}$ is $H^2(\mathcal{Z}, \mathbb{Q})$. The divisors $\widetilde{F}_i, \widetilde{D}_i, \widetilde{G}_i, \widetilde{B}_{i,j,k}$ generating $\text{Pic}(\widetilde{E}^3)$ correspond to surfaces on \widetilde{E}^3 . Let us denote by \widetilde{L} one of them, then we define L to be

$$L := \pi(\widetilde{L}) \text{ as a set, with the reduced scheme structure.}$$

Thus, we get the classes $F_i, D_i, G_i, B_{i,j,k}$ which correspond to surfaces on \mathcal{Z} . By construction the quotient map $\pi : \widetilde{E}^3 \rightarrow \mathcal{Z}$ is a 3:1 cover branched over $\pi(\bigcup_{i,j,k=1,2,3} \widetilde{B}_{i,j,k}) = \bigcup_{i,j,k=1,2,3} B_{i,j,k}$. Hence the map $\pi : \widetilde{B}_{i,j,k} \rightarrow B_{i,j,k}$ is 1 : 1. Moreover, also $\pi : \widetilde{F}_i \rightarrow F_i, \pi : \widetilde{D}_i \rightarrow D_i, \pi : \widetilde{G}_i \rightarrow G_i$ are 1 : 1. Thus,

$$\pi_*(\widetilde{B}_{i,j,k}) = B_{i,j,k}, \quad \pi_*(\widetilde{F}_i) = F_i, \quad \pi_*(\widetilde{D}_i) = D_i, \quad \pi_*(\widetilde{G}_i) = G_i.$$

The set $\{F_h, D_h, G_h, B_{i,j,k}\}_{h,i,j,k=1,2,3}$ is a \mathbb{Q} -basis of $\text{Pic}(\mathcal{Z})$. However, it is known that this \mathbb{Q} -basis is not a \mathbb{Z} -basis. Indeed the class of the branch locus of an $n : 1$ cyclic cover is n -divisible in the Picard group (cf. [5, Lemma 17.1, Chapter I]), in particular there exists a divisor

$$M \in \text{Pic}(\mathcal{Z}) \text{ such that } 3M \simeq \sum_{i,j,k} B_{i,j,k} =: B, \tag{6}$$

where $C_1 \simeq C_2$, if the two cycles C_1 and C_2 have the same cohomology class. Of course, M is not a linear combination with integer coefficients of the $B_{i,j,k}$.

We recall that $\text{Pic}(\mathcal{Z}) = H^{1,1}(\mathcal{Z})$ and so the Hodge diamond of \mathcal{Z} is

$$\begin{array}{cccc} & & 1 & \\ & 0 & & 0 \\ & 0 & 36 & 0 \\ 1 & 0 & & 0 & 1 \end{array}$$

The intersection form on $\text{Pic}(\mathcal{Z})$ is induced by the one on $\text{Pic}(\widetilde{E}^3)$, but one has to recall that the map $\pi : \widetilde{E}^3 \rightarrow \mathcal{Z}$ is a 3 : 1 map away from the ramification locus, where it is a bijection. The map $\pi^* : H^*(\mathcal{Z}, \mathbb{C}) \rightarrow H^*(\widetilde{E}^3, \mathbb{C})$ is a homomorphism of rings and hence for each $D, D', D'' \in \text{Pic}(\mathcal{Z}) \subset H^*(\mathcal{Z})$:

$$\begin{aligned} \pi^*(D)\pi^*(D') &= \pi^*(D \cdot D'), \\ \pi^*(D)\pi^*(D')\pi^*(D'') &= \pi^*(D \cdot D' \cdot D'') = 3(D \cdot D' \cdot D''), \end{aligned} \tag{7}$$

where the last equality depends on the degree of π (cf. [12, Pag. 9]).

So to compute the intersection form on $\text{Pic}(\mathcal{Z})$, it suffices to divide the intersection form on $\pi^*(\text{Pic}(\mathcal{Z})) \subset \text{Pic}(\widetilde{E^3})$ by 3, here we sketch this computation:

- $\pi^*(B_{i,j,k}) = 3\widetilde{B_{i,j,k}}$, since $B_{i,j,k}$ are in the ramification locus;
- $\pi^*(F_i) = \widetilde{F_i} + \widetilde{\varphi_3^*}(F_i) + (\widetilde{\varphi_3^2})^*(F_i) \simeq 3\widetilde{F_i}$, in fact $\varphi_3^*(F_i)$ and F_i have the same cohomology class on E^3 (and hence $\widetilde{\varphi_3^*}(F_i)$ and $\widetilde{F_i}$ have the same cohomology class on $\widetilde{E^3}$);
- similarly $\pi^*(D_i) \simeq 3\widetilde{D_i}$, $\pi^*(G_i) \simeq 3\widetilde{G_i}$.

Together with the description of the map π_* this implies that for every divisor $\widetilde{L} \in \text{Pic}(\widetilde{E^3})$, $\pi^*(L) = \pi^*(\pi_*(\widetilde{L})) \simeq 3\widetilde{L}$.

By (7), we have $(3\widetilde{L})(3\widetilde{L}')(3\widetilde{L}'') = \pi^*(L) \cdot \pi^*(L') \cdot \pi^*(L'') = 3(L \cdot L' \cdot L'')$ and thus

$$LL'L'' = 9\widetilde{L}\widetilde{L}'\widetilde{L}''.$$

Hence we obtain that the trilinear form on $\pi_*(\text{Pic}(\widetilde{E^3})) \subset \text{Pic}(\mathcal{Z})$ is the trilinear form of $\text{Pic}(\widetilde{E^3})$ multiplied by nine. Since the divisors in $\pi_*(\text{Pic}(\widetilde{E^3}))$ define a \mathbb{Q} -basis for $\text{Pic}(\mathcal{Z})$, this determines the trilinear form on $\text{Pic}(\mathcal{Z})$ completely. To recap, we proved that each divisor $L \in \text{Pic}(\mathcal{Z})$ can be written as $L = L_E + L_B$, where $L_E = \sum_{i=1}^3 (a_i F_i + b_i D_i + c_i G_i)$, $L_B = \sum_{i,j,k=1}^3 \alpha_{i,j,k} B_{i,j,k}$ and its cubic self-intersection is

$$L^3 = L_E^3 + L_B^3 = 9 \left(\left(\sum_{i=1}^3 (a_i \Phi_i + b_i \Delta_i + c_i \Gamma_i) \right)^3 + \sum_{i,j,k=1}^3 \alpha_{i,j,k}^3 \right). \tag{8}$$

We found a \mathbb{Q} -basis of $H^{2,2}(\widetilde{E^3})$ and this induces, via π_* , a \mathbb{Q} -basis of $H^{2,2}(\mathcal{Z})$ (in analogy to what we did for $\text{Pic}(\mathcal{Z})$). Hence a \mathbb{Q} -basis for $H^{2,2}(\mathcal{Z})$ consists of the curves $f_i (= \pi_*(\beta^*(\phi_i)))$, $d_i (= \pi_*(\beta^*(\delta_i)))$, $g_i (= \pi_*(\beta^*(\gamma_i)))$, $l_{i,j,k} (= \pi_*(\widetilde{l_{i,j,k}}))$. The intersection number aL between $a =: \pi_*(\widetilde{a}) \in H^{2,2}(\mathcal{Z})$ and L , a divisor of the chosen \mathbb{Q} -basis of $\text{Pic}(\mathcal{Z})$, can be computed by the projection formula (cf. [12, pag. 9]):

$$aL = \pi_*(\widetilde{a})L = \widetilde{a}\pi^*L = 3\widetilde{a}\widetilde{L} \tag{9}$$

For example, choosing $a = l_{i,j,k}$ and $L = B_{i,j,k}$, we have $l_{i,j,k}B_{i,j,k} = -3$.

We will need the expression of certain curves and classes in $H^{2,2}(\mathcal{Z})$ as linear combinations of the classes generating $H^{2,2}(\mathcal{Z})$, so here we compute some of them as examples.

Example 2.2. The class M^2 . The space $H^{2,2}(\mathcal{Z})$ contains all the classes obtained as intersection of two divisors on \mathcal{Z} . In particular, the class $M^2 = \left(\frac{1}{3} \sum_{i,j,k} B_{i,j,k}\right)^2$ can be written as linear combination of $f_i, d_i, g_i, l_{i,j,k}$ with coefficients in \mathbb{Q} , i.e., $\frac{1}{9} \sum_{i,j,k} (B_{i,j,k}^2) = (\sum_{h=1}^3 (\lambda_h f_h + \mu_h d_h + \nu_h g_h) + \sum_{i,j,k} \alpha_{i,j,k} l_{i,j,k})$. To find the coefficients of this \mathbb{Q} -linear combination, it suffices to compute the intersection of the divisors $F_i, D_i, G_i, B_{i,j,k}$ with M^2 . The only non trivial intersections of M^2 with these divisors are $M^2 B_{i,j,k} = 1$. We know that $B_{i,j,k} l_{i,j,k} = -3, B_{i,j,k} l_{a,b,c} = 0$, if $(a, b, c) \neq (i, j, k), B_{i,j,k} f_h = B_{i,j,k} d_h = B_{i,j,k} g_h = 0$ (cf. (9)). This implies that $1 = M^2 B_{i,j,k} = -3\alpha_{i,j,k}$ and hence, $\alpha_{i,j,k} = -1/3$. Using (3) and (9), the intersections of M^2 with F_h, D_h and G_h give $\lambda_h = \mu_h = \nu_h = 0$.

Example 2.3. The curves $C_{i,j}^k \subset E^3$ and $A_{i,j}^k \subset \mathcal{Z}$. Let us consider the curve $C_{i,j}^1 = E \times \{p_i\} \times \{p_j\}$, where $i, j = 1, 2, 3$ and p_i are the points fixed by φ on E . This curve passes through three fixed points, $p_{a,i,j} \in E^3, a = 1, 2, 3$. The curve $C_{i,j}^1 \subset E^3$ has the same cohomology class as $E \times \{q\} \times \{r\}$ for two general points $q, r \in E$. In particular, the class of the curve $C_{i,j}^1$ is the class ϕ_1 for each i, j . Let $\widetilde{C}_{i,j}^1 := \overline{\beta^{-1}(C_{i,j}^1) - \cup_{a=1,2,3} \{p_{a,i,j}\}}$, it is the strict transform of $C_{i,j}^1$. The curve $\widetilde{C}_{i,j}^1$ intersects the exceptional divisors $\widetilde{B}_{a,b,c}$ in one point, if and only if $(b, c) = (i, j)$. Hence, $\widetilde{C}_{i,j}^1 = \beta^*(\phi_1) - \sum_{a=1}^3 \widetilde{l}_{a,i,j}$. So, $\pi_*(\widetilde{C}_{i,j}^1) = \pi_*(\beta^*(\phi_1) - \sum_{a=1}^3 \widetilde{l}_{a,i,j}) = f_1 - \sum_{a=1}^3 l_{a,i,j}$. Let us consider $A_{i,j}^1 = \pi(C_{i,j}^1)$ as set with the reduced scheme structure. The map $\pi : \widetilde{C}_{j,k}^1 \rightarrow A_{i,j}^1$ is $3 : 1$, hence $A_{i,j}^1 = \frac{1}{3}(\pi_*(\beta^*(C_{i,j}^1)))$. More generally, define $C_{i,j}^2 = \{p_i\} \times E \times \{p_j\}, C_{i,j}^3 = \{p_i\} \times \{p_j\} \times E, A_{i,j}^h = \pi(\widetilde{C}_{i,j}^h)$ as a set with the reduced scheme structure, then:

$$\begin{aligned} A_{i,j}^1 &= \frac{1}{3} \left(f_1 - \sum_{a=1}^3 l_{a,i,j} \right), & A_{i,j}^2 &= \frac{1}{3} \left(f_2 - \sum_{a=1}^3 l_{i,a,j} \right), \\ A_{i,j}^3 &= \frac{1}{3} \left(f_3 - \sum_{a=1}^3 l_{i,j,a} \right). \end{aligned} \tag{10}$$

2.4 The Chern classes and the Riemann–Roch theorem on \mathcal{Z}

The i th Chern class of a variety is the i th Chern class of its tangent bundle. For a smooth projective variety $X, c_i(X) \in H^{2i}(X, \mathbb{Z})$ and, by convention, $c_0(X) = 1$.

If X is a Calabi–Yau variety, then $c_1(X) = 0$, indeed $c_1(\mathcal{T}_X) = c_1(\bigwedge^3 \mathcal{T}_X) = c_1(-K_X) = 0$.

The third Chern class of a smooth projective variety of dimension three satisfies $\chi(X) = c_3(X)$ (Gauss–Bonnet formula, [19, 416]).

Here, we compute the Chern classes of \mathcal{Z} . From the previous considerations it follows immediately that:

$$c_0(\mathcal{Z}) = 1, \quad c_1(\mathcal{Z}) = 0, \quad c_2(\mathcal{Z}) = \sum_{h=1}^3 (\lambda_h f_h + \mu_h d_h + \nu_h g_h) + \sum_{i,j,k=1}^3 \alpha_{i,j,k} l_{i,j,k},$$

$$c_3(\mathcal{Z}) = \chi(\mathcal{Z}) = 72,$$

where $\lambda_h, \mu_h, \nu_h, \alpha_{i,j,k} \in \mathbb{Q}$. It remains to determine the coefficients of the linear combination defining c_2 . To do this we need the following result:

Lemma 2.4 ([15, Lemma 4.4]). *If X is a complex three-fold with trivial canonical bundle and S is a smooth complex surface in X , then $c_2(X)[S] = -c_1(S)^2 + c_2(S)$.*

We now apply this result to each generator of $\text{Pic}(\mathcal{Z})$. As the divisors $B_{i,j,k}$ are isomorphic to \mathbb{P}^2 , one has $c_1(B_{i,j,k}) = 3l_{i,j,k}$ and $c_2(B_{i,j,k}) = \chi(\mathbb{P}^2) = 3$. The divisors F_i, D_i, G_i are isomorphic to the Abelian surface $E \times E$ (indeed the map π is $1 : 1$ between the Abelian surface $\tilde{F}_i \simeq E \times E$ and F_i are isomorphic to $E \times E$, similarly D_i and G_i). Hence, their first Chern class is zero (since their canonical bundle is trivial) and their second Chern class is zero (since it is equal to their Euler characteristic).

Now we compute the coefficients in $c_2(\mathcal{Z})$ as in Example 2.2. Indeed using (3) and (9) one has:

$$\begin{aligned} -6 &= -c_1(B_{x,y,z})^2 + c_2(B_{x,y,z}) = c_2(\mathcal{Z})[B_{x,y,z}] \\ &= \left(\sum_{h=1}^3 (\lambda_h f_h + \mu_h d_h + \nu_h g_h) + \sum_{i,j,k} \alpha_{i,j,k} l_{i,j,k} \right) [B_{x,y,z}] = -3\alpha_{x,y,z}, \end{aligned}$$

and

$$\begin{aligned} 0 &= -c_1(F_1)^2 + c_2(F_1) = c_2(\mathcal{Z})[F_1] \\ &= \left(\sum_{h=1}^3 (\lambda_h f_h + \mu_h d_h + \nu_h g_h) + \sum_{i,j,k} \alpha_{i,j,k} l_{i,j,k} \right) [F_1] \\ &= 3(\lambda_1 + \mu_2 + \mu_3 + \nu_2 + \nu_3) \end{aligned}$$

Doing this for all divisors, we obtain $\lambda_h = \mu_h = \nu_h = 0$, thus:

$$c_2(\mathcal{Z}) = 2 \sum_{i,j,k=1}^3 l_{i,j,k}.$$

Remark 2.5. Considering Example 2.2, it is immediate to see that the second Chern class $c_2(\mathcal{Z})$ is divisible by 6 in $H^4(\mathcal{Z}, \mathbb{Z})$, indeed $c_2(\mathcal{Z})/6 = \sum_{i,j,k=1,2,3} l_{i,j,k}/3 = -M^2 \in H^4(\mathcal{Z}, \mathbb{Z})$. The divisibility of this class was already obtained in a different and more involved way by Lee and Oguiso, [27].

The computation of the second Chern class of \mathcal{Z} allows also to write down explicitly the Riemann–Roch theorem for the divisors on \mathcal{Z} . Indeed it is well known (cf. [23]) that the Riemann–Roch theorem for a three-fold is:

$$\chi(\mathcal{L}(D)) = \frac{1}{12} D \cdot (D - K_X)(2D - K_X) + \frac{1}{12} c_2 \cdot D + 1 - p_a.$$

In case $X = \mathcal{Z}$, we have $K_{\mathcal{Z}} = 0$ and $p_a = 1$ (since \mathcal{Z} is a Calabi–Yau variety), so we obtain:

$$\chi(\mathcal{L}(D)) = \frac{1}{6} D^3 + \frac{1}{6} \sum_{i,j,k=1,2,3} l_{i,j,k} D. \quad (11)$$

3 More on the trilinear form on $\text{Pic}(E^3)$

To compute the Yukawa coupling on \mathcal{Z} it is necessary to describe the trilinear form on $\text{Pic}(\mathcal{Z})$. We proved in the previous section that the trilinear form on $\text{Pic}(\mathcal{Z})$ depends on the trilinear form on $\text{Pic}(E^3)$ (cf. (8), (14)). For this reason, we now give a different description of the trilinear form on $\text{Pic}(E^3)$: we reduce the computation of this trilinear form to the computation of the determinant of a matrix in $\text{Mat}_{3,3}(\mathbb{Q}[\zeta])$ (cf. (13)). More precisely in this section, we give a way to associate to each divisor L on E^3 a matrix Ω_L in $\text{Mat}_{3,3}(\mathbb{Q}[\zeta])$ and we prove the following theorem:

Theorem 3.1. *There exists a homomorphism of groups $\mu : \text{Pic}(E^3) \rightarrow \{H \in \text{Mat}_{3,3}(\mathbb{Q}[\zeta]) \mid {}^t \overline{H} = -H\} \subset \text{Mat}_{3,3}(\mathbb{Q}[\zeta])$ such that, for each divisor $L \in \text{Pic}(E^3)$, $L^3 = \frac{1}{12} \sqrt{-3} \det(\mu(L))$.*

We already said (Section 2.1) that a divisor D on an Abelian variety $A \simeq \mathbb{R}^n/\Lambda$ corresponds to a two-form $c_1(D)$ and hence to a skew-symmetric form E_D on the lattice Λ taking values in \mathbb{Z} .

The elliptic curve E is obtained as $\mathbb{C}/\mathbb{Z}[\zeta]$. Since, we are considering the Abelian variety E^3 , in this context $\Lambda \simeq \mathbb{Z}[\zeta]^3$, and we are saying that each divisor D in $\text{Pic}(E^3)$ defines a skew-symmetric form $E_D : \mathbb{Z}[\zeta]^3 \times \mathbb{Z}[\zeta]^3 \rightarrow \mathbb{Z}$.

First of all, we prove that for each $L \in \text{Pic}(E^3)$ there exists a matrix Ω_L , such that for each $x, y \in \mathbb{Z}[\zeta]^3$, $E_L(x, y) = \text{Tr}({}^t x \Omega_L \bar{y})$, where Tr is the trace of an element in $\mathbb{Q}[\zeta]$ over \mathbb{Q} defined as $\text{Tr}(a + \zeta b) = (a + \zeta b) + \overline{(a + \zeta b)} = 2a - b$ for $a, b \in \mathbb{Q}$. Since $E_L(x, y) = -E_L(y, x)$, ${}^t \overline{\Omega_L} = -\Omega_L$.

To compute the matrix Ω_L for each of the nine divisors L , which generate the Picard group of E^3 , we use the same technique considered in Section 2.1, i.e., we consider divisors which generate $\text{Pic}(E^3)$ as pull-back of divisors on an elliptic curve E . Indeed, since the map $c_1 : \text{Pic}(X) \rightarrow H^2(X, \mathbb{Z})$ commutes with the pull-back, we have that, if $L \in \text{Pic}(E^3)$ is $\alpha^*(l)$ for a certain map $\alpha : E^3 \rightarrow E$ and a certain divisor $l \in \text{Pic}(E)$, then $E_L(x, y) = E_l(\alpha(x), \alpha(y))$.

Let us consider the elliptic curve $E = \mathbb{C}/\mathbb{Z}[\zeta]$ and a general point $P \in E$. Then, $c_1(P)$ is the skew-form $E_P = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$ (the unique, up to a constant, skew-form on Λ). So $E_P(a + \zeta b, c + \bar{\zeta} d) = ad - bc$. The matrix Ω_P is a 1×1 matrix with entries in $\mathbb{Q}[\zeta]$ (i.e., $\Omega_P \in \mathbb{Q}[\zeta]$) such that

$$\text{Tr}((a + \zeta b)\Omega_L(c + \bar{\zeta} d)) = (a, b) \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \begin{pmatrix} c \\ d \end{pmatrix} = ad - bc.$$

This gives $\Omega_P = \rho (= -{}^t \overline{\Omega_P})$ where $\rho := (\zeta - \bar{\zeta})/3$.

The matrix Ω_L for a certain divisor $L \in \text{Pic}(E^3)$ was identified by the property $E_L(v, w) = \text{Tr}({}^t v \Omega_L \bar{w})$, hence to compute it, we consider $\alpha : E^3 \rightarrow E$, $\alpha : (z_1, z_2, z_3) \mapsto \sum_{i=1}^3 a_i z_i$, where z_i are the complex coordinates on the i th copy of E . Let $a := (a_1, a_2, a_3)$ and analogously $v := (v_1, v_2, v_3)$, $w := (w_1, w_2, w_3)$. Let $L = \alpha^*(P)$, $\alpha(v) = \sum_i a_i v_i = a^t v$, $\alpha(w) = \sum_i a_i w_i = a^t w$ (where ${}^t b$ is the transpose of the vector b). Then

$$\begin{aligned} E_L(v, w) &= E_P(\alpha(v), \alpha(w)) = E_P(a^t v, a^t w) = \text{Tr}({}^t (a^t v) \overline{\rho a^t w}) \\ &= \text{Tr}(v^t a \overline{\rho a^t w}), \end{aligned}$$

which implies that the matrix Ω_L associated to $L = \alpha^*(P)$ is

$$\Omega_L := \rho \begin{pmatrix} a_1 \\ a_2 \\ a_3 \end{pmatrix} (\overline{a_1}, \overline{a_2}, \overline{a_3}). \tag{12}$$

Thus to find, for example, Ω_{Γ_1} , it suffices to apply (12) to the map $\eta_1 : (z_1, z_2, z_3) \mapsto \zeta z_2 - z_3$:

$$\Omega_{\Gamma_1} = \rho \begin{pmatrix} 0 \\ \zeta \\ -1 \end{pmatrix} (0, \bar{\zeta}, -1) = \rho \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & -\zeta \\ 0 & -\bar{\zeta} & 1 \end{bmatrix}.$$

Similarly, one finds Ω_{Φ_i} , Ω_{Δ_i} and Ω_{Γ_i} (the map associated to each of these divisors is given in (1)). In this way one finds that if $L = \sum_{i=1}^3 (a_i \Phi_i + b_i \Delta_i + c_i \Gamma_i)$, then $\Omega_L = a_i \Omega_{\Phi_i} + b_i \Omega_{\Delta_i} + c_i \Omega_{\Gamma_i}$ is given by

$$\Omega_L = \rho \begin{bmatrix} a_1 + b_2 + b_3 + c_2 + c_3 & -b_3 - \zeta c_3 & -b_2 - \bar{\zeta} c_2 \\ -b_3 - \bar{\zeta} c_3 & a_2 + b_1 + b_3 + c_1 + c_3 & -b_1 - \zeta c_1 \\ -b_2 - \zeta c_2 & -b_1 - \bar{\zeta} c_1 & a_3 + b_1 + b_2 + c_1 + c_2 \end{bmatrix}. \tag{13}$$

Now an explicit computation shows that for each divisor $L \in \text{Pic}(E^3)$, the determinant of Ω_L is, up to a constant, the intersection form computed in (4),

$$L^3 = \frac{1}{12} \sqrt{-3} \det \left(\sum_{i=1}^3 (a_i \Omega_{\Phi_i} + b_i \Omega_{\Delta_i} + c_i \Omega_{\Gamma_i}) \right) \tag{14}$$

and this concludes the proof of Theorem 3.1.

Remark 3.2. The compatibility between the group structures of $\text{Pic}(E^3)$ and $\text{Mat}_{3,3}(\mathbb{Q}[\zeta])$ is because of the properties of the skew-symmetric form E_L defined by a divisor L and of the trace Tr . Indeed $E_{L \otimes M}(x) = E_L(x) + E_M(x) = \text{Tr}({}^t x \Omega_L \bar{x}) + \text{Tr}({}^t x \Omega_M \bar{x}) = \text{Tr}({}^t x (\Omega_L + \Omega_M) \bar{x})$, and so to the line bundle $L \otimes M$, we associate the matrix $\Omega_L + \Omega_M$.

We observe that the Picard group of the singular quotient E^3/φ_3 has rank 9 and is induced by the one on $\text{Pic}(E^3)$. The Picard group of E^3/φ_3 can be identified with the subgroup of $\text{Pic}(\mathcal{Z})$ generated by F_i, D_i, G_i . In Section 2.3, we proved that the trilinear intersection form on $\langle F_i, D_i, G_i \rangle_{i=1,2,3} \subset \text{Pic}(\mathcal{Z})$ is, up to a constant (multiplication by 9), the trilinear form on $\text{Pic}(E^3)$. We deduce that the trilinear form on $\text{Pic}(E^3/\varphi_3)$ is, up to a constant, the determinant of the matrix as in (13). Since $H^{2,0}(E^3/\varphi_3) = 0$, $\text{Pic}(E^3/\varphi_3) \otimes \mathbb{C} \simeq H^{1,1}(E^3/\varphi_3)$ and the cup product on $H^{1,1}(E^3/\varphi_3)$ coincides with the \mathbb{C} -linear extension of the trilinear form. So the cup product on $H^{1,1}(E^3/\varphi_3)$ can be represented as determinant of a matrix in $\text{Mat}_{3,3}(\mathbb{Q}[\zeta])$. This is of a certain interest because of its relation with the Yukawa coupling on $H^{1,1}(E^3/\varphi_3)$, obtained as the sum of the cup

product and another addend, involving the Gromov–Witten invariants. The values of a_i, b_i, c_i , where the determinant of the matrix (13) is zero correspond to $(1, 1)$ forms, where the cup product is zero. The set of such values is described by the cubic $\mathcal{C}_3 := V(\det(\sum_{i=1}^3 (a_i \Omega_{\Phi_i} + b_i \Omega_{\Delta_i} + c_i \Omega_{\Gamma_i})))$ in \mathbb{P}^8 (projective space with coordinates $(a_1 : a_2 : a_3 : b_1 : b_2 : b_3 : c_1 : c_2 : c_3)$). This cubic is singular, where the matrix $\sum_{i=1}^3 (a_i \Omega_{\Phi_i} + b_i \Omega_{\Delta_i} + c_i \Omega_{\Gamma_i})$ has rank 1, hence along the intersection of the nine quadrics in \mathbb{P}^8 defined by requiring that the nine 2×2 minors of the matrix are zero. The matrices of rank 1 are of type $\rho({}^t a)(\bar{a})$ for a certain vector $a = (a_1, a_2, a_3)$. We already showed that the matrix associated to the divisors $\Phi_i, \Delta_i, \Gamma_i$ are of this type and hence, they correspond to singular points of the cubic. We notice that these divisors define a fibration on the three-fold.

Remark 3.3. Let Y be a Calabi–Yau three-fold. In [36], the cubic hypersurface W in $\mathbb{P}(\text{Pic}(Y) \otimes \mathbb{C})$, consisting of the points representing divisors L with $L^3 = 0$, is analyzed. Here, we are considering the cubic \mathcal{C}_3 defined in the same way as W , but in the case of the Abelian variety E^3 . By the relations between $\text{Pic}(E^3)$ and $\text{Pic}(\mathcal{Z})$ given in Section 2.3, the cubic \mathcal{C}_3 is also related to the cubic W in case $Y = \mathcal{Z}$.

4 Projective models of \mathcal{Z}

The aim of this section is to give explicit relations and equations for \mathcal{Z} . To do this we describe some (singular) projective models of the three-fold \mathcal{Z} and more in general maps $f : \mathcal{Z} \rightarrow \mathbb{P}^N$. Each of these maps is associated to a line bundle $L := f^*(\mathcal{O}_{\mathbb{P}^N}(1))$, and hence f is given by global sections $s_0, \dots, s_N \in H^0(\mathcal{Z}, L)$, i.e., $f : z \mapsto (s_0(z) : \dots : s_N(z))$.

Our strategy will be to construct line bundles L (and maps m_L associated to L) on E^3 and use these to induce line bundles (and hence maps) on \mathcal{Z} . Let L be a line bundle on E^3 such that $\varphi_3^* L \simeq L$. Then, φ_3^* acts on $H^0(E^3, L)$ and hence the space $H^0(E^3, L)$ is naturally decomposed in three eigenspaces $H^0(E^3, L)_0, H^0(E^3, L)_1, H^0(E^3, L)_2$. By construction the maps $(m_L)_0 : E^3 \rightarrow \mathbb{P}(H^0(E^3, L)_0), (m_L)_1 : E^3 \rightarrow \mathbb{P}(H^0(E^3, L)_1), (m_L)_2 : E^3 \rightarrow \mathbb{P}(H^0(E^3, L)_2)$ identify points on E^3 which are in the same orbit for φ_3 . This implies that these maps (or better the maps induced by these maps on $\widetilde{E^3}$) are well defined on \mathcal{Z} and thus are associated to line bundles on \mathcal{Z} . It is moreover clear that the map $(m_L)_\epsilon, \epsilon = 0, 1, 2$, is the composition of $E^3 \rightarrow m_L(E^3)$ followed by the projection of $m_L(E^3)$ on the subspace $\mathbb{P}(H^0(E^3, L))_\epsilon$. First of all, we point out the relations between the line bundle and its global sections on E^3 and on \mathcal{Z} and then we focus our attention on a specific case.

Remark 4.1. We said that the space $H^0(E^3, L)$ is naturally decomposed in eigenspaces by the action of φ_3^* , and indeed there are three subspaces of $H^0(E^3, L)$, such that the action of φ_3 is the same on all the elements in the same subspace and is different on two elements chosen in two different subspaces. However, the choice of the eigenvalue of each eigenspace is not canonical, but depends on the lift of φ_3^* on $H^0(E^3, L)$ chosen.

Lemma 4.2 ([5, Lemma I.17.2]). *Let $\pi : X \rightarrow Y$ be an n -cyclic covering of Y branched along a smooth divisor C and determined by $\mathcal{O}_Y(L)$, where L is a divisor such that $\mathcal{O}_Y(nL) \simeq \mathcal{O}_Y(C)$. Then $\pi_*(\mathcal{O}_X) = \bigoplus_{k=0}^{n-1} \mathcal{O}_Y(-kL)$.*

Since $\widetilde{\varphi}_3$ acts as a multiplication by ζ on the local equation of each ramification divisor $\widetilde{B}_{i,j,k}$, we can apply the previous lemma to $X = \widetilde{E}^3$, $Y = \mathcal{Z}$, $C = B$, $L = M$ (cf. (6)), obtaining

$$\pi_*(\mathcal{O}_{\widetilde{E}^3}) = \mathcal{O}_{\mathcal{Z}} \oplus \mathcal{O}_{\mathcal{Z}}(-M) \oplus \mathcal{O}_{\mathcal{Z}}(-2M). \tag{15}$$

Indeed $\mathcal{O}_{\mathcal{Z}}$, $\mathcal{O}_{\mathcal{Z}}(-M)$, $\mathcal{O}_{\mathcal{Z}}(-2M)$ correspond to the subbundles of $\pi_*(\mathcal{O}_{\widetilde{E}^3})$, which are stable with respect to the action of $\widetilde{\varphi}_3$. In particular, $\mathcal{O}_{\mathcal{Z}}$ corresponds to the subbundle of the eigenvalue 1.

Let $\widetilde{L} \in \text{Pic}(\widetilde{E}^3)$ be such that there exists $L \in \text{Pic}(\mathcal{Z})$ satisfying $\widetilde{L} = \pi^*(L)$. Then

$$\pi_*(\widetilde{L}) = \pi_*(\pi^*(L) \otimes \mathcal{O}_{\widetilde{E}^3}) = L \otimes \pi_*\mathcal{O}_{\widetilde{E}^3} = L \oplus L(-M) \oplus L(-2M), \tag{16}$$

where the last equality follows from (15). This implies that

$$H^0(\widetilde{E}^3, \widetilde{L}) = H^0(\mathcal{Z}, \pi_*(\widetilde{L})) = H^0(\mathcal{Z}, L) \oplus H^0(\mathcal{Z}, L - M) \oplus H^0(\mathcal{Z}, L - 2M) \tag{17}$$

where in the first equality we used, viewing \widetilde{L} as invertible sheaf, $H^0(\mathcal{Z}, \pi_*(\widetilde{L})) = (\pi_*(\widetilde{L}))(\mathcal{Z}) = \widetilde{L}(\pi^{-1}(\mathcal{Z})) = \widetilde{L}(\widetilde{E}^3) = H^0(\widetilde{E}^3, \widetilde{L})$ and in the last (16).

Now, we concentrate on a specific choice of divisors on E^3 and \mathcal{Z} : let $\Phi := \Phi_1 + \Phi_2 + \Phi_3 \in \text{Pic}(E^3)$ and $F := F_1 + F_2 + F_3 \in \text{Pic}(\mathcal{Z})$.

Proposition 4.3. *The map $m_{3\Phi} : E^3 \rightarrow \mathbb{P}^{26}$ is an embedding. The automorphism φ_3 of E^3 extends to an automorphism, called again φ_3 , on \mathbb{P}^{26} . Let $(\mathbb{P}^{26})_\epsilon$ be the eigenspace for the eigenvalue ζ^ϵ , $\epsilon = 0, 1, 2$, for φ_3 . The composition of $m_{3\Phi}$ with projection $\mathbb{P}^{26} \rightarrow \mathbb{P}_0^{26}$ (resp. \mathbb{P}_1^{26} , \mathbb{P}_2^{26}) is the map defined on \mathcal{Z} , which is associated to the divisor F (resp. $F - M$, $F - 2M$).*

Proof. The diagram:

$$\begin{array}{ccc}
 E^3 & \xleftarrow{\beta} & \widetilde{E^3} & & H^0(E^3, 3\Phi) & \xrightarrow{\beta^*} & H^0(\widetilde{E^3}, 3\beta^*(\Phi)) \\
 & & \downarrow \pi & \text{induces} & & & \uparrow \pi^* \\
 & & \mathcal{Z} & & & & H^0(\mathcal{Z}, F)
 \end{array}$$

The map β^* is an isomorphism. A section $s \in H^0(E^3, 3\Phi)$ with divisor D , which has multiplicity $\alpha_{i,j,k}$ in the point $p_{i,j,k}$ pulls back to a section β^*s with divisor $\beta^*D = \widetilde{D} + \sum_{i,j,k} \alpha_{i,j,k} \widetilde{B_{i,j,k}}$, where \widetilde{D} is the strict transform of D . Since $3\beta^*(\Phi) = \pi^*(F)$, using (16) and (17), we have $\pi_*(3\beta^*(\Phi)) = F \otimes \pi_*\mathcal{O}_{\widetilde{E^3}}$ and

$$\begin{aligned}
 H^0(\widetilde{E^3}, 3\beta^*(\Phi)) &= H^0(\mathcal{Z}, F \otimes \pi_*\mathcal{O}_{\widetilde{E^3}}) \\
 &= H^0(\mathcal{Z}, F) \oplus H^0(\mathcal{Z}, F(-M)) \oplus H^0(\mathcal{Z}, F(-2M)).
 \end{aligned}$$

Thus

$$\begin{aligned}
 H^0(E^3, 3\Phi) &\stackrel{\beta^*}{\simeq} H^0(\widetilde{E^3}, 3\beta^*\Phi) \simeq H^0(\mathcal{Z}, F) \oplus H^0(\mathcal{Z}, F - M) \\
 &\quad \oplus H^0(\mathcal{Z}, F - 2M)
 \end{aligned} \tag{18}$$

and the last decomposition is a decomposition in eigenspaces of $H^0(E^3, 3\Phi)$. So $H^0(\mathcal{Z}, F - aM) \subset H^0(E^3, 3\Phi)$ corresponds to the space of the sections of 3Φ on E^3 with zeros with multiplicity at least a in the points $p_{i,j,k}$ and which are in the same eigenspace for φ_3 . The map associated to 3Φ is very explicit: Every elliptic curve is embedded in \mathbb{P}^2 as a cubic, by the linear system associated to the divisor $3P$. In particular, the curve E has the curve $x^3 + y^3 + z^3 = 0$ as image in $\mathbb{P}^2_{x,y,z}$. So we can embed E^3 in $\mathbb{P}^2_{x_1,y_1,z_1} \times \mathbb{P}^2_{x_2,y_2,z_2} \times \mathbb{P}^2_{x_3,y_3,z_3}$ (embedding each factor of E^3 in the correspondent copy of \mathbb{P}^2). Now, it is well known that there exists an embedding of $\mathbb{P}^2 \times \mathbb{P}^2 \times \mathbb{P}^2$ in \mathbb{P}^{26} given by the Segre map

$$\begin{aligned}
 s : ((x_1 : y_1 : z_1), (x_2 : y_2 : z_2), (x_3 : y_3 : z_3)) \\
 \rightarrow (x_1x_2x_3 : x_1x_2y_3 : x_1x_2z_3 : x_1y_2x_3 : \dots : z_1z_2z_3).
 \end{aligned}$$

Hence, there is an embedding of E^3 in \mathbb{P}^{26} , which is the restriction of s to E^3 . By construction, this map is associated to the very ample divisor 3Φ on E^3 . This map extends to a map defined on $\widetilde{E^3}$, which contracts the exceptional divisors $\widetilde{B_{i,j,k}}$ (which are in fact orthogonal to the divisor $\beta^*(3\Phi)$ defining the map).

The action of the automorphism φ_3 on E^3 is given by $\varphi : ((x_1 : y_1 : z_1), (x_2 : y_2 : z_2), (x_3 : y_3 : z_3)) \rightarrow ((x_1 : y_1 : \zeta z_1), (x_2 : y_2 : \zeta z_2), (x_3 : y_3 : \zeta z_3))$ and this

automorphism extends to an automorphism on \mathbb{P}^{26} . The eigenspaces with eigenvalue $1, \zeta, \zeta^2$ for φ_3 on \mathbb{P}^{26} are

$$\begin{aligned} & (x_1x_2x_3 : x_1x_2y_3 : x_1y_2x_3 : x_1y_2y_3 : y_1x_2x_3 : y_1x_2y_3 : y_1y_2x_3 : y_1y_2y_3 : z_1z_2z_3) \\ & (z_1x_2x_3 : z_1x_2y_3 : z_1y_2x_3 : z_1y_2y_3 : x_1z_2x_3 : x_1z_2y_3 : y_1z_2x_3 : y_1z_2y_3 : x_1x_2z_3 : \\ & \quad x_1y_2z_3 : y_1x_2z_3 : y_1y_2z_3) \\ & (x_1z_2z_3 : y_1z_2z_3 : z_1x_2z_3 : z_1y_2z_3 : z_1z_2x_3 : z_1z_2y_3) \end{aligned}$$

respectively. We observe that the first eigenspace is defined by sections of 3Φ , which are not necessarily zero in the points $p_{i,j,k}$ (for example the monomial $x_1x_2x_3$ is not zero in the points $p_{i,j,k}$), the second is defined by sections passing through $p_{i,j,k}$ with multiplicity 1 and the third by sections passing through the points $p_{i,j,k}$ with multiplicity 2. Hence, the first eigenspace is identified (under the isomorphisms (18)) with $H^0(\mathcal{Z}, F)$, the second with $H^0(\mathcal{Z}, F - M)$ and the third with $H^0(\mathcal{Z}, F - 2M)$. \square

Remark 4.4. From this description of $H^0(\mathcal{Z}, F - kM)$ we obtain:

$$\dim(H^0(\mathcal{Z}, F)) = 9, \quad \dim(H^0(\mathcal{Z}, F - M)) = 12, \quad \dim(H^0(\mathcal{Z}, F - 2M)) = 6.$$

If we apply the Riemann–Roch theorem (cf. (11)) to the divisor $F, F - M, F - 2M$, we find $\chi(F) = 9, \chi(F - M) = 12, \chi(F - 2M) = 6$. This in particular implies that for a divisor L among $F, F - M, F - 2M, h^2(\mathcal{Z}, L) - h^1(\mathcal{Z}, L) = 0$, indeed by Serre duality we have $h^3(\mathcal{Z}, L) = 0$. For the divisors F and $F - M$ this is a trivial consequence of the fact that they are big and nef, as we will see in Propositions 4.6 and 4.8, and of the Kawamata–Viehweg vanishing theorem.

Remark 4.5. Analogously, we can consider the sections of the line bundles $hF - kM, h, k \geq 0$, over \mathcal{Z} . These correspond (as showed for $F - kM$) to sections of $3h\Phi$ over E^3 , which vanish at least of degree k in the points $p_{i,j,k}$. We denote by $N_{h,k}$ the space of such a sections. In case $k = 0, 1, 2$, this gives a decomposition in eigenspaces of $H^0(E^3, h\Phi)$ relative to the eigenvalue ζ^k .

Let $k = 0, 1, 2$. We denote by $(\text{Sym}^h(E))_k := (\text{Sym}^h \langle x, y, z \rangle)_k$ the monomials of degree h in the coordinates of E , which belong to the eigenspace of the eigenvalue ζ^k . Now $(\text{Sym}^h(E))_k$ is generated by the monomials of the form $x^\alpha y^\beta z^\gamma$, such that $\alpha + \beta + \gamma = h$ and $\gamma \equiv k \pmod 3$. Since $z^3 = -x^3 - y^3$ on E , we can assume that $\gamma = k$. Thus the eigenspaces have the following dimensions: $\dim(\text{Sym}^h(E))_k = h + 1, h, h - 1$ for $k = 0, 1, 2$, respectively. The sections of $3h\Phi$ on E^3 are given by $\text{Sym}^h(E) \times \text{Sym}^h(E) \times \text{Sym}^h(E)$ and hence $N_{h,k} = \text{Sym}^h(E)_a \times \text{Sym}^h(E)_b \times \text{Sym}^h(E)_c$ with

$a, b, c = 0, 1, 2$ and $a + b + c \equiv k \pmod 3$. After direct computation, we obtain the following dimensions

$$\dim(N_{h,k}) = \begin{cases} 9h^3 & k = 0, \\ 9h^3 + 3 & k = 1, \\ 9h^3 - 3 & k = 2, \end{cases}$$

which add up to $H^0(E^3, 3h\Phi) = (3h)^3$.

Now $\chi(hF - kM) = 9h^3 + \frac{3}{2}k(3 - k^2)$ by the Riemann–Roch theorem (cf. (11)): we notice that $\dim(N_{h,k})$ equals $\chi(hF - kM)$ for $k = 0, 1, 2$, $h > 0$. This generalizes the result of Remark 4.4 and allows one to describe projective models of \mathcal{Z} obtained from the maps associated to the divisors $hF - kM$, for each $h > 0$, $k = 0, 1, 2$.

4.1 The first eigenspace

We now analyze the projection to the eigenspace relative to the eigenvalue 1, i.e., the map m_0 on E^3 given by $(x_1x_2x_3 : x_1x_2y_3 : x_1y_2x_3 : x_1y_2y_3 : y_1x_2x_3 : y_1x_2y_3 : y_1y_2x_3 : y_1y_2y_3 : z_1z_2z_3)$.

Considering the coordinate functions of m_0 , we observe that they are invariant not only under the action of φ_3 , but also under the action of $\phi : ((x_1 : y_1 : z_1), (x_2 : y_2 : z_2), (x_3 : y_3 : z_3)) \rightarrow ((x_1 : y_1 : \zeta z_1), (x_2 : y_2 : \zeta^2 z_2), (x_3 : y_3 : z_3))$. It is easy to see that the map is 9 : 1 on E^3 , and hence the image gives a model of the Calabi–Yau variety \mathcal{Y} , which desingularizes $E^3 / \langle \phi, \varphi_3 \rangle$. So \mathcal{Z} is a 3 : 1 cover of $m_0(E^3)$. The Calabi–Yau \mathcal{Y} , of which $m_0(E^3)$ is a birational model, is still interesting, so we describe the map m_0 in some details. In this section we prove the following:

Proposition 4.6. *The map $m_0 : E^3 \rightarrow \mathbb{P}^8$ is well defined on E^3 , and is a 9 : 1 map on its image. Its differential fails to be injective only on the curves $C_{j,k}^i$ (cf. Example 2.3).*

The variety $m_0(E^3)$ is a 3 : 1 cover of $\sigma(\mathbb{P}^1 \times \mathbb{P}^1 \times \mathbb{P}^1)$ where $\sigma : \mathbb{P}^1 \times \mathbb{P}^1 \times \mathbb{P}^1 \rightarrow \mathbb{P}^7$ is the Segre embedding. Moreover, $m_0(E^3)$ is contained in the Fermat cubic hypersurface in \mathbb{P}^8 .

The map m_0 induces the 3 : 1 map $m_F : \mathcal{Z} \rightarrow \mathbb{P}^8$ associated to the nef and big divisor F .

It is immediate to check that the map m_0 is 9 : 1. To analyze its differential, we first consider m_0 as defined on $\mathbb{P}^2 \times \mathbb{P}^2 \times \mathbb{P}^2$ and then we will restrict it to

E^3 . We recall that \mathbb{P}^2 is covered by its open subsets $U_x := \{(x : y : z) | x \neq 0\}$, U_y and U_z . Since the point $(0 : 0 : 1) \notin E$, it suffices to consider the open sets U_x and U_y , but the map is totally symmetric in the x_i and y_i , so it is enough to study the map on the open set $U_x \times U_x \times U_x$ of $\mathbb{P}^2 \times \mathbb{P}^2 \times \mathbb{P}^2$:

$$\begin{aligned} U_x \times U_x \times U_x &\longrightarrow U \subset \mathbb{C}^8 \\ (y_1, z_1) \times (y_2, z_2) \times (y_3, z_3) &\longmapsto (y_3, y_2, y_2y_3, y_1, y_1y_3, y_1y_2, \\ &\quad y_1y_2y_3, z_1z_2z_3). \end{aligned}$$

The Jacobian is given by

$$J_{m_0} = \begin{pmatrix} 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & y_3 & 0 & y_2 & 0 \\ 1 & 0 & 0 & 0 & 0 & 0 \\ y_3 & 0 & 0 & 0 & y_1 & 0 \\ y_2 & 0 & y_1 & 0 & 0 & 0 \\ y_2y_3 & 0 & y_1y_3 & 0 & y_1y_2 & 0 \\ 0 & z_2z_3 & 0 & z_1z_3 & 0 & z_1z_2 \end{pmatrix}.$$

Now we restrict our attention to the tangent space to E^3 : the tangent vectors (u, v) to E in (y, z) satisfy $u \frac{\partial f}{\partial y} + v \frac{\partial f}{\partial z} = 0$, where $f = 1 + y^3 + z^3$ is the equation of E in U_x , thus $(u, v) = \lambda(-\frac{\partial f}{\partial z}, \frac{\partial f}{\partial y}) = \lambda(-3z^2, 3y^2)$, $\lambda \in \mathbb{C}$. Hence the tangent vectors of E^3 in the point $q := (y_1, z_1, y_2, z_2, y_3, z_3)$ are $(u_1, v_1, u_2, v_2, u_3, v_3) = (-\frac{\partial f_1}{\partial z_1} \lambda, \frac{\partial f_1}{\partial y_1} \lambda, -\frac{\partial f_2}{\partial z_2} \mu, \frac{\partial f_2}{\partial y_2} \mu, -\frac{\partial f_3}{\partial z_3} \rho, \frac{\partial f_3}{\partial y_3} \rho)$, where $(\lambda, \mu, \rho) \in \mathbb{C}^3 \simeq T_q E^3$.

The Jacobian fails to be injective, where $J_{m_0}(u_1, v_1, u_2, v_2, u_3, v_3)^t = 0$, which gives the following equations:

$$\begin{cases} -\frac{\partial f_3}{\partial z_3} \rho = 0 \\ -\frac{\partial f_2}{\partial z_2} \mu = 0 \\ -\frac{\partial f_1}{\partial z_1} \lambda = 0 \\ z_2z_3 \frac{\partial f_1}{\partial y_1} \lambda + z_1z_3 \frac{\partial f_2}{\partial y_2} \mu + z_1z_2 \frac{\partial f_3}{\partial y_3} \rho = 0 \end{cases} \Rightarrow \begin{cases} z_3 = 0 \ (\Rightarrow y_3 = \zeta^c \neq 0) & \text{or } \rho = 0 \\ z_2 = 0 \ (\Rightarrow y_2 = \zeta^b \neq 0) & \text{or } \mu = 0 \\ z_1 = 0 \ (\Rightarrow y_1 = \zeta^a \neq 0) & \text{or } \lambda = 0 \end{cases}$$

Thus, if either $z_i \neq 0 \forall i$ or $z_i = 0, z_j, z_k \neq 0$ for $\{i, j, k\} = \{1, 2, 3\}$, then $\lambda = \mu = \rho = 0$, which gives no points where $(J_{m_0})|_{E^3}$ is not injective. On the other hand, the condition $z_1 \neq 0, z_j = 0$ for $j \neq 1$ (resp. $z_i = 0 \forall i$) implies $\lambda = 0$, but does not give conditions on μ, ρ (resp. λ, μ, ρ). We recall that the condition $z_i = 0$ gives exactly the fixed points p_i on the i th copy of E in E^3 . Therefore the map $(J_{m_0})|_{E^3}$, and also m_0 , fails to be injective on the curves $C_{i,j}^k$ (and in particular at the fixed points $p_i \times p_j \times p_k$). The reason is that these curves are invariant not only under the action of φ_3 , but also under ϕ .

The map m_0 can also be described in a different way, which exhibits $m_0(E^3)$ as $3 : 1$ cover of a subvariety in \mathbb{P}^7 . Consider the composition γ of the projection $\alpha : E^3 \rightarrow \mathbb{P}^1$ of each elliptic curve $E \subset \mathbb{P}^2$ on the first two coordinates and the Segre embedding $\sigma : (\mathbb{P}^1)^3 \rightarrow \mathbb{P}^7$

$$\begin{aligned} \gamma : \quad E^3 & \xrightarrow{\alpha} \mathbb{P}^1 \times \mathbb{P}^1 \times \mathbb{P}^1 \\ x_i^3 + y_i^3 + z_i^3 = 0 & \mapsto ((x_1 : y_1), (x_2 : y_2), (x_3 : y_3)) \\ \sigma & \xrightarrow{\quad} \mathbb{P}^7 \\ \mapsto & (x_1x_2x_3 : x_1x_2y_3 : \dots : y_1y_2y_3) \end{aligned}$$

The Segre map σ is well known to be an embedding and the map α is clearly $3^3 : 1$, hence, γ is $3^3 : 1$.

Let us denote by X_0, \dots, X_8 the coordinates on the target projective space of the map m_0 . The map γ is the composition of projection of m_0 with the projection on the hyperplane $\mathbb{P}^7 \subset \mathbb{P}^8$ with coordinates X_0, \dots, X_7 . Thanks to this description one can show that $m_0(E^3)$ is contained in certain quadrics and a cubic hypersurface. Indeed the variety $\sigma(\mathbb{P}^1 \times \mathbb{P}^1 \times \mathbb{P}^1)$ is contained in the quadrics

$$\begin{aligned} X_0X_3 &= X_1X_2, & X_0X_5 &= X_1X_4, & X_0X_7 &= X_2X_5, & X_0X_7 &= X_1X_6, \\ X_0X_6 &= X_2X_4, & X_0X_7 &= X_3X_4, & X_1X_7 &= X_3X_5, & X_2X_7 &= X_3X_6, \\ X_4X_7 &= X_5X_6 \end{aligned}$$

and since $x_i^3 + y_i^3 + z_i^3 = 0$, we have $-(X_8)^3 = -(z_1z_2z_3)^3 = -(-x_1^3 - y_1^3)(-x_2^3 - y_2^3)(-x_3^3 - y_3^3) = X_0^3 + X_1^3 + X_2^3 + X_3^3 + X_4^3 + X_5^3 + X_6^3 + X_7^3$, so $m_0(E^3)$ is contained in the Fermat cubic in \mathbb{P}^8 , $F_8 := V(\sum_{i=0}^8 X_i^3)$.

It is now clear that the projection $(X_0 : \dots : X_8) \rightarrow (X_0 : \dots : X_7)$ restricted to F_8 and to $m_0(E^3)$ is a cyclic $3 : 1$ map with cover transformation $(X_0 : \dots : X_7 : X_8) \rightarrow (X_0 : \dots : X_7 : \zeta X_8)$.

Remark 4.7. The map m_F induced by m_0 on \mathcal{Z} does not contract curves. This guarantees that F is a big and nef divisor, indeed $F^3 > 0$ (i.e., F is big) and for each curve $C \in \mathcal{Z}$, $FC = 3\text{deg}(m_F(C)) > 0$, and by [12, Theorem 1.26] this suffices to conclude that F is nef.

The inclusion $m_0(E^3) \subset F_8$ is interesting in view of the paper [8], where the authors suggest that a generalized mirror for the Calabi–Yau three-fold \mathcal{Z} is a quotient of the Fermat cubic in \mathbb{P}^8 by an automorphism of order 3. Here, we proved that there exists a 3 : 1 map from \mathcal{Z} to a singular model of the Calabi–Yau variety $\mathcal{Y} = \widetilde{\mathcal{Z}/\mathbb{Z}_3}$, which is contained in this cubic in \mathbb{P}^8 . The Hodge numbers of \mathcal{Y} are $h^{1,1} = 84$ and $h^{2,1} = 0$.

In [8], the authors observe that the middle cohomology of the desingularization $\widetilde{F_8/G}$ of the quotient of F_8 by certain groups G has the following Hodge numbers:

$$H^7 : \quad 0 \ 0 \ 1 \ \beta \ \beta \ 1 \ 0 \ 0. \tag{19}$$

For a certain choice of the action of the group $G \simeq \mathbb{Z}_3$, the value of β is 36 and hence $h^{4,3}(\widetilde{F_8/G}) = h^{1,1}(\mathcal{Z})$. The space $H^{4,3}(\widetilde{F_8/G})$ is the complex moduli space of $\widetilde{F_8/G}$ and has the same dimension of the Kähler moduli space of \mathcal{Z} . Requiring that the dimension of the complex moduli space of a variety coincides with the dimension of the Kähler moduli space of another variety is one of the necessary conditions for the two varieties to be mirrors. In [8], deeper relations between the complex moduli of $\widetilde{F_8/G}$ and the Kähler moduli of \mathcal{Z} are found using the Yukawa coupling. Because of this, the authors suggest that $\widetilde{F_8/G}$ could be a “generalized mirror” of \mathcal{Z} .

Now we observe that, if G is trivial, then β in (19) is 84 and $h^{4,3}(F_8) = h^{1,1}(\mathcal{Y})$. Thus, we observe that F_8 has the Hodge numbers of the generalized mirror of \mathcal{Y} (a desingularization of \mathcal{Z}/\mathbb{Z}_3). This was already noticed in [26, Section 6.1.3], where the authors analyze a deeper relation between \mathcal{Y} and F_8 based on their L -functions (cf. [26, Theorem 2]).

We observe that in these two generalized mirrors the desingularization of a quotient by \mathbb{Z}_3 is involved:

CY	Conjectured generalized mirror
\mathcal{Z}	$\widetilde{F_8/\mathbb{Z}_3}$
$\mathcal{Y} = \widetilde{\mathcal{Z}/\mathbb{Z}_3}$	F_8

The fact that the Calabi–Yau variety \mathcal{Y} admits a birational model inside the variety $\sum_{i=0}^8 X_i^3 = 0$ (and \mathcal{Z} a 3 : 1 map to a subvariety of $\sum_{i=0}^8 X_i^3 = 0$) could be useful to give a geometric explanation of the relations between \mathcal{Z} and its generalized mirror and between \mathcal{Y} and F_8 .

4.2 The second eigenspace

We now analyze the projection on the eigenspace of the eigenvalue ζ , i.e the map m_1 on E^3 given by $(z_1x_2x_3 : z_1x_2y_3 : z_1y_2x_3 : z_1y_2y_3 : x_1z_2x_3 : x_1z_2y_3 : y_1z_2x_3 : y_1z_2y_3 : x_1x_2z_3 : x_1y_2z_3 : y_1x_2z_3 : y_1y_2z_3)$. We summarize the properties of this map in the following Proposition, which is proved in this section:

Proposition 4.8. *The base locus of the map $m_1 : E^3 \rightarrow \mathbb{P}^{11}$ consists of the 27 points $p_{i,j,k}$. The map m_1 contracts the 27 curves $C_{j,k}^i$ and is 3 : 1 on E^3 away from these curves. Its differential is injective away from the 27 contracted curves. The image $m_1(E^3)$ has 27 singular points, the images of the curves $C_{j,k}^i$, which are ordinary double points.*

The map m_1 induces a well defined map over $\widetilde{E^3}$, which sends the 27 exceptional divisors $\widetilde{B}_{i,j,k}$ to 27 copies of \mathbb{P}^2 and whose differential is injective away from the contracted curves.

The map m_1 induces the map f_{F-M} on \mathcal{Z} associated to the nef and big divisor $F - M$. It contracts the curves $A_{j,k}^i$ and is the isomorphism $\mathcal{Z} - \bigcup_{i,j,k=1}^3 A_{j,k}^i \rightarrow f_{F-M}(\mathcal{Z} - \bigcup_{i,j,k=1}^3 A_{j,k}^i)$ away from the contracted curves.

By the definition of m_1 , it is clear that the base locus is given by the condition $z_1 = z_2 = z_3 = 0$ and hence the base locus consists of the 27 points $p_{i,j,k}$. Let q be one of the following 27 points $(0 : \dots : 0 : 1 : -\zeta^b : -\zeta^a : \zeta^{a+b})$, $(0 : \dots : 0 : 1 : -\zeta^c : -\zeta^a : \zeta^{a+c} : 0 : \dots : 0)$ and $(1 : -\zeta^c : -\zeta^b : \zeta^{b+c} : 0 : \dots : 0)$. Then the inverse image of q is a curve $C_{j,k}^i$ (for example $C_{1,1}^1$ is sent to $(1 : -\zeta : -\zeta : \zeta^2 : 0 : \dots : 0)$). The inverse image of all the other points in $m_1(E^3)$ consists of 3 points, so the map is generically 3 : 1.

To study the Jacobian, we consider the open subset $U_z \times U_x \times U_x$ (where the map is surely defined, because the base locus is defined by $z_1 = z_2 = z_3 = 0$). Since the tangent vectors to E^3 in $(x_1, y_1, y_2, z_2, y_3, z_3)$ are $(u_1, v_1, u_2, v_2, u_3, v_3) = (-\frac{\partial f_1}{\partial y_1} \lambda, \frac{\partial f_1}{\partial x_1} \lambda, -\frac{\partial f_2}{\partial z_2} \mu, \frac{\partial f_2}{\partial y_2} \mu, -\frac{\partial f_3}{\partial z_3} \rho, \frac{\partial f_3}{\partial y_3} \rho)$, where $(\lambda, \mu, \rho) \in \mathbb{C}^3 \simeq T_p E^3$, the restriction of the differential of m_1 to the tangent space of E^3

has kernel:

$$\left\{ \begin{array}{l} -\frac{\partial f_3}{\partial z_3} \rho = 0 \\ -\frac{\partial f_2}{\partial z_2} \mu = 0 \\ -z_2 \frac{\partial f_1}{\partial y_1} \lambda + x_1 \frac{\partial f_2}{\partial y_2} \mu = 0 \\ -z_2 \frac{\partial f_1}{\partial x_1} \lambda + y_1 \frac{\partial f_2}{\partial y_2} \mu = 0 \\ -z_3 \frac{\partial f_1}{\partial y_1} \lambda + x_1 \frac{\partial f_3}{\partial y_3} \rho = 0 \\ -z_3 \frac{\partial f_1}{\partial x_1} \lambda + y_1 \frac{\partial f_3}{\partial y_3} \rho = 0 \end{array} \right. \Rightarrow \left\{ \begin{array}{l} z_3 = 0 (\Rightarrow y_3 = \zeta^c \neq 0) \quad \text{or } \rho = 0 \\ z_2 = 0 (\Rightarrow y_2 = \zeta^b \neq 0) \quad \text{or } \mu = 0 \\ -z_2 y_1^2 \lambda + x_1 y_2^2 \mu = 0 \\ -z_2 x_1^2 \lambda + y_1 y_2^2 \mu = 0 \\ -z_3 y_1^2 \lambda + x_1 y_3^2 \rho = 0 \\ -z_3 x_1^2 \lambda + y_1 y_3^2 \rho = 0 \end{array} \right.$$

Thus, for $z_2, z_3 \neq 0 \Rightarrow \mu = \rho = 0$ and, considering for example the third and the fourth equation, we obtain

$$\left\{ \begin{array}{l} -z_2 y_1^2 \lambda = 0 \\ -z_2 x_1^2 \lambda = 0 \end{array} \right. \Rightarrow \lambda = 0 \text{ (since } x_1, y_1 \text{ cannot be both zero),}$$

which implies $\lambda = \rho = \mu = 0$. This condition gives no points, where the differential is not injective. Similarly, if $z_2 = 0, z_3 \neq 0$, then $\rho = 0$ and (by the previous argument) $\lambda = \mu = 0$. On the contrary, in case $z_2 = z_3 = 0$ one obtains $\mu = \rho = 0$, but no conditions on λ , which corresponds to curves where the differential is not injective. The curves $C_{j,k}^i$ are contracted to 27 singular points of $m_1(E^3)$, which are the only singular points of the image.

In order to prove that these singular points are ordinary double points, we consider some relations among the coordinate functions N_i , for $i = 0, \dots, 11$, of m_1 . There are 15 quadratic relations involving these monomials, which are induced by the Segre embedding:

$$\begin{array}{ll} \mathcal{Q}_i := V(N_0 N_{2i+1} - N_1 N_{2i}), \quad i = 1, 2, 3 & | \quad \mathcal{Q}_i := V(N_0 N_{2i+1} - N_2 N_{2i}), \quad i = 4, 5 \\ \mathcal{Q}_i := V(N_1 N_{2i-3} - N_3 N_{2(i-2)}), \quad i = 6, 7 & | \quad \mathcal{Q}_i := V(N_2 N_{2i-11} - N_3 N_{2(i-6)}), \quad i = 8, 9 \\ \mathcal{Q}_{10} := V(N_4 N_7 - N_5 N_6) & | \quad \mathcal{Q}_i := V(N_4 N_{i-1} - N_6 N_{i-3}), \quad i = 11, 12 \\ \mathcal{Q}_i := V(N_5 N_{i-3} - N_7 N_{i-5}), \quad i = 13, 14 & | \quad \mathcal{Q}_{15} := V(N_8 N_{11} - N_9 N_{10}) \end{array}$$

We observe that, due to $x_i^3 + y_i^3 + z_i^3 = 0$, $i = 1, 2, 3$, we obtain also 6 cubic equations relating the monomials:

$$\begin{aligned} \mathcal{C}_1 &:= V(N_0^3 + N_1^3 - (N_8^3 + N_{10}^3)) \mid \mathcal{C}_2 := V(N_2^3 + N_3^3 - (N_9^3 + N_{11}^3)) \\ \mathcal{C}_3 &:= V(N_0^3 + N_2^3 - (N_4^3 + N_6^3)) \mid \mathcal{C}_4 := V(N_1^3 + N_3^3 - (N_5^3 + N_7^3)) \\ \mathcal{C}_5 &:= V(N_4^3 + N_5^3 - (N_8^3 + N_9^3)) \mid \mathcal{C}_6 := V(N_6^3 + N_7^3 - (N_{10}^3 + N_{11}^3)) \end{aligned}$$

So $m_1(E^3)$ is contained in the intersection of all the varieties defined by these equations. As done before one can compute the Jacobian of these relations and analyze it at the singular points (for example at the point $p := (0 : \dots : 0 : 1 : -1 : -1 : 1)$, which is image of the curve $C_{3,3}^3$). We get seven independent relations among the 12 variables N_i , for example choosing $\mathcal{Q}_4, \mathcal{Q}_6, \mathcal{Q}_{10}, \mathcal{Q}_{13}, \mathcal{C}_1, \mathcal{C}_2$ and \mathcal{C}_3 . Hence $\dim(\ker J_p) = 12 - 7 = 5$ and $\ker J_p = \langle (a : b : -a : -b : c : d : -c : -d : e : -e : -e : e) \rangle$, $a, b, c, d, e \in \mathbb{C}$. Once we projectivize this yields $T_p(\mathcal{Q}_4, \mathcal{Q}_6, \mathcal{Q}_{10}, \mathcal{Q}_{13}, \mathcal{C}_1, \mathcal{C}_2, \mathcal{C}_3) \simeq \mathbb{P}^4_{(a:b:c:d:e)}$. In the affine coordinate chart $N_{11} = 1$ the tangent vectors are given by (a, b, c, d) . Considering the quadric \mathcal{Q}_2 , we obtain that $ab - cd = 0$. Thus, the points we obtain by contracting one of the 27 curves are ordinary double points.

We already said that the map m_1 is not defined in the 27 points $p_{i,j,k}$, $i, j, k = 1, 2, 3$, and hence we consider the blow up, $\widetilde{E^3}$, of E^3 in the base locus of m_1 . As in Section 4.1 we consider the map m_1 extended to $(\mathbb{P}^2)^3$ and we restrict it to the open subset $U_x \times U_x \times U_x$, which obviously contains the 27 points we wish to examine:

$$\begin{array}{ccccccc} U_x & \times & U_x & \times & U_x & \xrightarrow{m_1} & \mathbb{P}^{11} \\ (y_1, z_1) & \times & (y_2, z_2) & \times & (y_3, z_3) & \longmapsto & (z_1 : z_1 y_3 : z_1 y_2 : z_1 y_2 y_3 : z_2 : \\ & & & & & & z_2 y_3 : z_2 y_1 : z_2 y_1 y_3 : \\ & & & & & & z_3 : z_3 y_2 : z_3 y_1 : z_3 y_1 y_2). \end{array}$$

In $U_x \times U_x \times U_x$ the fixed points are given by $p_{i,j,k} = ((-\zeta^i, 0), (-\zeta^j, 0), (-\zeta^k, 0))$. We study what happens locally when we approach the point $p_{i,j,k}$. We consider the parametrized line through $p = p(0)$, $p(t) = ((-\zeta^i + tu_1, tv_1), (-\zeta^j + tu_2, tv_2), (-\zeta^k + tu_3, tv_3))$, where $((u_1, v_1), (u_2, v_2), (u_3, v_3)) \in (\mathbb{C}^2)^3$ and $t \in \mathbb{C}$. Under m_1 the point $p(t)$ is mapped to

$$\begin{aligned} m_1(p(t)) &= (tv_1 : tv_1(-\zeta^k + tu_3) : tv_1(-\zeta^2 + tu_2) : tv_1(-\zeta^j + tu_2)(-\zeta^k + tu_3) : \\ &tv_2 : tv_2(-\zeta^k + tu_3) : tv_2(-\zeta^i + tu_1) : tv_2(-\zeta^i + tu_1)(-\zeta^k + tu_3) : \\ &tv_3 : tv_3(-\zeta^j + tu_2) : tv_3(-\zeta^i + tu_1) : tv_3(-\zeta^i + tu_1)(-\zeta^j + tu_2)). \end{aligned}$$

Let $E_x := E \cap U_x$. The coordinates on $\mathcal{T}_p(E_x \times E_x \times E_x)$ are v_1, v_2, v_3 , since $u_1 = u_2 = u_3 = 0$, and thus the exceptional divisor of $\widetilde{E^3}$ over p is mapped to a $\mathbb{P}^2 = \mathbb{P}(\mathcal{T}_p E^3) = \mathbb{P}^2_{(v_1:v_2:v_3)}$ linearly embedded in \mathbb{P}^{11} . It remains to prove that the differential of the map $m_1 : \widetilde{E^3} \rightarrow \mathbb{P}^{11}$ is injective on the exceptional divisors. To do this, let us choose the complex coordinates of E^3 on $E_x \times E_x \times E_x$, the coordinates z_i . So E^3 is locally isomorphic to $\mathbb{C}^3_{(z_1, z_2, z_3)}$ and $z_i = \sqrt[3]{-1 - y_i^3}$. Blowing up $\mathbb{C}^3_{(z_1, z_2, z_3)}$ in $(0, 0, 0)$, we obtain a variety locally isomorphic to $\mathbb{C}_{(z_1, b, c)}$, where $z_2 = bz_1$ and $z_3 = cz_1$. The action of $\widetilde{\varphi}_3$ on the coordinates (z_1, b, c) is $(z_1, b, c) \mapsto (\zeta z_1, b, c)$. Hence, the quotient $\mathbb{C}^3_{(z_1, b, c)}/\varphi_3$ is locally isomorphic to a copy of \mathbb{C}^3 with coordinates (z_1^3, b, c) . Computing the Jacobian of the map induced by m_1 on this quotient, one finds that the rank of the Jacobian is 3 (i.e., is maximal), hence the map induced by m_1 on $\widetilde{E^3}$ has an injective differential (except on the contracted curves).

Remark 4.9. As in the case of m_0 , one proves that $F - M$ is big and nef. Indeed m_1 contracts the curves $A_{i,j}^k$ and $(F - M)A_{i,j}^k = 0$. All the non contracted curves have positive intersection with $F - M$ (cf. Remark 4.7). Hence for each curve C in \mathcal{Z} , $(F - M)C \geq 0$, so $F - M$ is nef. Since $(F - M)^3 > 0$, it is also big. In particular $h^i(F - M) = 0$, $i > 0$.

We observe that using the intersection form on $\text{Pic}(\mathcal{Z})$ one immediately finds that the image of the divisor $B_{i,j,k}$ under m_1 is a linear subspace (we computed explicitly this result on the blow up), indeed $(F - M)^2 B_{i,j,k} = 1$.

4.3 The third eigenspace

We now analyze the projection on the eigenspace of the eigenvalue ζ^2 , i.e., the map m_2 on E^3 given by $(x_1 z_2 z_3 : y_1 z_2 z_3 : z_1 z_2 x_3 : z_1 z_2 y_3 : z_1 x_2 z_3 : z_1 y_2 z_3)$. We summarize the properties of this map in the following proposition, which is proved in this section. Let us denote by S_j^1 (resp. S_j^2, S_j^3) the surface $p_j \times E \times E$ (resp. $E \times p_j \times E, E \times E \times p_j$).

Proposition 4.10. *The base locus of the map $m_2 : E^3 \rightarrow \mathbb{P}^5$ consists of the 27 curves $C_{j,k}^i$. The map m_2 contracts the nine surfaces S_j^i and is 3 : 1 on E^3 away from these surfaces. Its differential is injective away from the nine contracted surfaces. The map m_2 is a 3 : 1 dominant rational map between E^3 and the desingularization $\widetilde{V}_{3,3}$ of the three-fold*

$$V_{3,3} := \begin{cases} -X_0^3 & -X_1^3 & +X_2^3 & +X_3^3 & & & = 0 \\ & & X_2^3 & +X_3^3 & -X_4^3 & -X_5^3 & = 0 \end{cases} \quad (\text{cf. [25]}). \quad (20)$$

Let $\widetilde{E^3}$ be the blow up of E^3 along the curves $\widetilde{C_{j,k}^i}$. The map m_2 induces a map $\widetilde{E^3} \rightarrow V_{3,3}$, defined everywhere, which sends the strict transform of the exceptional divisors $\widetilde{B_{i,j,k}}$ to the 27 linear subspaces $\mathbb{P}_{(s:t:u)}^2 \simeq (-s : \zeta^i s : -t : \zeta^j t : -u : \zeta^k u) \subset V_{3,3}$ and the strict transform of the curves $\widetilde{C_{j,k}^i}$ to the 27 rational curves $(0 : 0 : -\lambda : \zeta^i \lambda : -\mu : \mu \zeta^j)$, $(-\lambda : \zeta^i \lambda : 0 : 0 : -\mu : \mu \zeta^j)$, $(-\lambda : \zeta^i \lambda : -\mu : \mu \zeta^j : 0 : 0)$.

The variety $V_{3,3}$ has 9 singular points of type $(3, 3, 3, 3)$, which are the contractions of the strict transforms of the surfaces S_j^i and whose tangent cone is the cone over the Fermat cubic Del Pezzo surface.

The map m_2 induces a generically $1 : 1$ map on \mathcal{Z} associated to the divisor $F - 2M$. It is not defined on the curves $A_{j,k}^i$ and contracts the surfaces $\pi(\widetilde{S_j^i})$, where $\widetilde{S_j^i}$ is the strict transform of S_j^i over $\widetilde{E^3}$.

By the definition of m_2 , it is clear that the base locus is given by the condition $z_i = z_j = 0$, $i, j = 1, 2, 3$, $i \neq j$ and hence the base locus consists of the 27 curves $C_{j,k}^i$. Moreover, one immediately sees that the surfaces with $z_i = 0$, $i = 1, 2, 3$, are contracted to points by the map m_2 . Under the condition $z_i \neq 0$, for each $i \in \{1, 2, 3\}$, m_2 is $3 : 1$. As in Sections 4.1, 4.2 one can prove that the Jacobian J_{m_2} restricted to E^3 is injective away from the contracted surfaces S_j^i .

In [25], a dominant rational map of degree three between E^3 and the three-fold $V_{3,3}$ is given. Comparing the map described in [25] with m_2 , one observes that they coincide, up to a choice of the signs of the coordinate functions of \mathbb{P}^5 . In [25], Kimura observes that the existence of this map is predicted by the Tate conjecture. The variety $V_{3,3}$ has nine singularities of type $(3, 3, 3, 3)$ at the points $(1 : -\zeta^a : 0 : 0 : 0 : 0)$, $(0 : 0 : 0 : 0 : 1 : -\zeta^b)$ and $(0 : 0 : 1 : -\zeta^c : 0 : 0)$ ($a, b, c = 0, 1, 2$), which can be resolved by a simultaneous blow up. By a direct computation, one shows that the tangent cone over the singularity is a Del Pezzo cubic in \mathbb{P}^3 and more precisely the Fermat cubic in \mathbb{P}^3 . We also observe that there are 27 curves $(-s : \zeta^a s : -t : \zeta^b t : 0 : 0)$, $(0 : 0 : -t : \zeta^b t : -u : \zeta^c u)$, $(-s : \zeta^a s : 0 : 0 : -u : \zeta^c u)$ and 27 surfaces $(-s : \zeta^a s : -t : \zeta^b t : -u : \zeta^c u)$, $a, b, c = 1, 2, 3$, on $V_{3,3}$, which contain the singular points and which do not appear in the image $m_2(E^3)$. We will show that these curves and surfaces are contained in the image of $\widetilde{E^3}$.

It suffices to consider the problem locally: locally E^3 is isomorphic to a copy of $\mathbb{C}_{(z_1, z_2, z_3)}^3$. Blowing up the origin, one obtains the variety

$V(bz_1 - az_2) \cap V(cz_1 - az_3) \cap V(cz_2 - bz_3) \subset \mathbb{C}^3_{(z_1, z_2, z_3)} \times \mathbb{P}^2_{(a:b:c)}$, which is isomorphic to a copy of \mathbb{C}^3 with coordinates (z_1, b, c) , in the affine set $a = 1$. Applying the map m_2 to these new coordinates $((x_1, y_1, z_1); (x_2, y_2, bz_1); (x_3, y_3, cz_1))$, one obtains $(x_1bc : y_1bc : x_3b : y_3b : x_2c : y_2c)$. It is clear that, in the affine set $a = 1$, the map is not defined on the curve $b = c = 0$ and that the exceptional divisor $\mathbb{P}^2_{(a:b:c)}$ over the point $p_{i,j,k}$ identified by $x_h = 1, h = 1, 2, 3, y_1 = -\zeta^i, y_2 = -\zeta^j, y_3 = \zeta^k$ is sent to $(-bc : \zeta^i bc : -ab : \zeta^j ab : -ac : \zeta^j ac) \simeq \mathbb{P}^2_{(ab:ac:bc)}$. The map restricted to the exceptional divisor $\mathbb{P}^2_{(a:b:c)}$ is $(a : b : c) \rightarrow (bc : ac : ab)$, so it is a Cremona transformation.

Blowing up $\mathbb{C}^3_{(z_1, b, c)}$ along the curve $b = c = 0$ one finds, as an open subset, a third copy of \mathbb{C}^3 with coordinates (z_1, b, γ) , related to the previous ones by $c = \gamma b$. Applying the map induced by m_2 one obtains the everywhere defined map on \widetilde{E}^3 , locally given by $(x_1b : y_1b : x_2\gamma : y_2\gamma : x_3 : y_3)$. Now one can directly check that the images of the strict transforms of $\widetilde{B_{i,j,k}}$ and of $\widetilde{C_{j,k}^i}$ are the ones given in the statement. The intersection of the contracted surface S_h^l with the strict transform of $\widetilde{B_{i,j,k}}$ is given by the lines contracted by the Cremona transformation induced by m_2 on $\widetilde{B_{i,j,k}}$.

Remark 4.11. The divisor $F - 2M$, associated to m_2 , is a big divisor, but it is not nef, indeed $(F - 2M)A_{i,j}^k < 0$.

The three-fold $V_{3,3}$ is studied by several authors, who give different models and descriptions of this three-folds. In [37], it is proved that this Calabi–Yau is isomorphic to a $3^5 : 1$ cover of \mathbb{P}^3 branched along the configuration of six planes which was constructed in [24]. The map associated to this cover is $\varsigma : (X_0 : X_1 : X_2 : X_3 : X_4 : X_5) \rightarrow (X_0^3 - X_1^3 : X_2^3 - X_3^3 : X_4^3 - X_5^3 : X_2^3 + X_3^3)$, hence there exists a $3^6 : 1$ rational dominant map between E^3 and \mathbb{P}^3 , obtained by the composition $\varsigma \circ m_3$, defined by $((z_2z_3)^3(-x_1^3 + y_1^3) : (z_1z_2)^3(x_3^3 - y_3^3) : (z_1z_3)^3(-x_2^3 + y_2^3) : (z_1z_2)^3(x_3^3 + y_3^3))$.

Another construction of the same Calabi–Yau is given in [29], where it is shown that the $3^5 : 1$ map $V_{3,3} \dashrightarrow \mathbb{P}^3$ is the composition of a $3^4 : 1$ map $V_{3,3} \dashrightarrow T$ and a $3 : 1$ map $T \rightarrow \mathbb{P}^3$, the last map being a $3 : 1$ cover of \mathbb{P}^3 branched along the six planes which are the faces of a cube.

4.4 Other maps

In the previous sections, we analyzed the maps defined on \mathcal{Z} associated to the divisors $F, F - M$ and $F - 2M$. These divisors give $3 : 1$ or $1 : 1$ maps,

but they do not give an image which is isomorphic to \mathcal{Z} . Indeed, the divisors F and $F - M$ are big and nef, but not ample and $F - 2M$ is not nef. In particular, none of them is very ample. Here, we want to prove that the divisor $2F - M$ is a very ample divisor and hence $f_{2F-M}(\mathcal{Z})$ is isomorphic to \mathcal{Z} , where f_{2F-M} is the map defined by the divisor $2F - M$. In general, it is not easy to find criteria which assure that a given divisor is very ample, and indeed we will prefer to consider explicitly the map associated to $2F - M$ and prove that it is an isomorphism on the image. However, it is clear that since F and $F - M$ are both nef and big, the sum of these divisors $2F - M$ is nef and big.

Let $m : E^3 \rightarrow \mathbb{P}^N$ be the composition of the map $f_{2(3\Phi)}$ defined on E^3 and the projection on the eigenspace of the eigenvalue ζ (with respect to the action of φ_3). By Remark 4.5, we know that the map induced by m on \mathcal{Z} is the map f_{2F-M} .

Proposition 4.12. *The base locus of the map m consists of the 27 points $p_{i,j,k}$. It induces an everywhere defined $3 : 1$ map over $\widetilde{E^3}$, whose differential is injective. The map induced on \mathcal{Z} is an isomorphism on the image and is associated to the divisor $2F - M$ which is very ample.*

Proof. By Remark 4.5 we have

$$m : E^3 \longrightarrow \mathbb{P}^{74} = \mathbb{P}(N_{2,1}),$$

and we are considering monomials contained in the eigenspace relative to ζ .

We consider only the monomials with one z , namely of the form

$$v_i v_j v_k \text{ with } v_i \in \{z_i x_i, z_i y_i\}, v_j \in \{x_j^2, x_j y_j, y_j^2\} \text{ and } v_k \in \{x_k^2, x_k y_k, y_k^2\},$$

where $\{i, j, k\} = \{1, 2, 3\}$. We restrict ourselves to the open subset defined by $x_h = 1$ for $h = 1, 2, 3$. The rank of the Jacobian of m is 3. Thus the differential is injective, where the map is defined.

We recall that $F - M$ defines an isomorphism on \mathcal{Z} except on the curves $A_{j,k}^i$, which are contracted, so $2F - M$ is an isomorphism outside the curves $A_{j,k}^i$ and thus it suffices to prove that $2F - M = F + F - M$ has an injective differential on these curves. The blow up of E^3 in the points $p_{i,j,k}$ is locally the blow up of $\mathbb{C}_{(z_1, z_2, z_3)}^3$ in the origin and is isomorphic to $\mathbb{C}_{(z_1, b, c)}^3$ on an open subset (cf. Subsection 4.3). The quotient by the map φ_3 is locally isomorphic to $\mathbb{C}_{(z_1^3, b, c)}^3$. Applying the map induced by m to $\mathbb{C}_{(z_1^3, b, c)}^3$ and computing the differential one obtains that it has rank 3 everywhere, in

particular where $b = c = 0$ (which is the curve corresponding to $A_{j,k}^1$). So the map m induces on \mathcal{Z} a map which is an isomorphism everywhere, thus divisor $2F - M$ is very ample. \square

Remark 4.13. The divisor $F - M + F_1$ is a nef and big divisor on \mathcal{Z} . It is easy to check that it contracts the curves $A_{j,k}^2$ and $A_{j,k}^3$ (indeed it acts essentially as $F - M$ on these curves), but is an isomorphism on $A_{j,k}^1$ (indeed it acts on these curves as $2F - M$) and away from the curves $A_{j,k}^i$ (again because $F - M$ has the same property). One can also check that $(F - M + F_1)^2 A_{j,k}^1 = 1$ and $(F - M + F_1)^2 A_{j,k}^i = 0$ if $i = 2, 3$. Analogously we have that $F - M + F_i$, $i = 1, 2, 3$, contracts 18 curves among $A_{j,k}^h$ and is an isomorphism away from the contracted curves.

Similarly, the map associated to the divisor $F - M + F_i + F_j$, $i \neq j$, $i, j \in \{1, 2, 3\}$, contracts nine curves among $A_{k,l}^h$ and is an isomorphism away from these curves.

5 Other Calabi–Yau three-folds

Until now, we considered the well known Calabi–Yau three-fold \mathcal{Z} . The aim of this section is to recall that, starting from the Abelian three-fold E^3 or from the Calabi–Yau three-fold \mathcal{Z} , one can construct other Calabi–Yau three-folds with different Hodge numbers and properties. We will describe some already known constructions and results. In Section 6, we present two Calabi–Yau three-folds obtained from a singular model of \mathcal{Z} by a smoothing. One of these was unknown until now.

5.1 Quotient by automorphisms

To construct \mathcal{Z} , we considered the desingularization of the quotient of the Abelian variety E^3 by the automorphism φ_3 . Similarly, we can consider quotients of E^3 by other automorphisms, or quotients of \mathcal{Z} by automorphisms induced by the ones of E^3 .

Example 5.1. We already saw an example of this construction in 4.1. Indeed the group $G \simeq (\mathbb{Z}_3)^2 = \langle \varphi_3, \phi \rangle = \langle \zeta \times \zeta \times \zeta, \zeta \times \zeta^2 \times 1 \rangle$ acts on E^3 and E^3/G is a singular three-fold which admits a desingularization \mathcal{Y} which is a Calabi–Yau. This three-fold is already known [9, 18, 33], and its Hodge numbers are computed in [33]: $h^{2,1} = 0$, $h^{1,1} = 84$. The automorphisms φ_3 and ϕ commute on E^3 , this implies that ϕ induces an automorphism α of order 3 on E^3/φ_3 and also on \mathcal{Z} . Thus the three-fold \mathcal{Y} can be

obtained also as desingularization of the quotient \mathcal{Z} by the automorphism α . The automorphism α preserves the three-holomorphic form on \mathcal{Z} , and this guarantees that the quotient \mathcal{Z}/α has a desingularization, which is a Calabi–Yau three-fold.

As in the previous example, one can construct automorphisms on \mathcal{Z} considering the automorphisms of E^3 , which commute with φ_3 . These automorphisms induce automorphisms on \mathcal{Z} .

On each Abelian variety A , and in particular on E^3 , the translations by points are defined, indeed for each point $r \in A$, the map $t_r : A \rightarrow A$ such that $t_r(q) = q + r$ for each $q \in A$ is an automorphism of A . Let us assume that the order of t_r is finite. The quotient E^3/t_r does not have the Hodge numbers of a Calabi–Yau variety, indeed translations preserve all the holomorphic forms on E^3 , thus $h^{1,0}(E^3/t_r) = h^{2,0}(E^3/t_r) = 3$. However the translation t_r commutes with the automorphism φ_3 , if and only if $\varphi_3(r) = r$. In this case, the translation t_r defines an automorphism on E^3/φ_3 and a desingularization of $E^3/\langle\varphi_3, t_r\rangle$ has the Hodge numbers of a Calabi–Yau three-fold.

The Abelian variety E^3 admits a larger group of automorphisms: $GL_3(\mathbb{Z}[\zeta]) \subset Aut(E^3)$. In particular, the automorphism $\varphi_3 \in GL_3(\mathbb{Z}[\zeta])$ is the diagonal matrix (ζ, ζ, ζ) . Since all the matrices $M \in GL_3(\mathbb{Z}[\zeta])$ commute with the diagonal matrix (and in particular with φ_3), the automorphisms of E^3 given by the matrices M induce automorphisms on \mathcal{Z} . Thus, $GL_3(\mathbb{Z}[\zeta]) \subset Aut(\mathcal{Z})$. If $\sigma \in SL_3(\mathbb{Z}[\zeta])$ is of finite order, then \mathcal{Z}/σ has a desingularization, which is a Calabi–Yau three-fold. It is in general an open (and non trivial) problem to find explicitly such a desingularization and to compute its Hodge numbers $h^{1,1}$, $h^{2,1}$.

In [31], some quotients of E^3 by subgroups of $SL_3(\mathbb{Z}[\zeta])$ and their crepant resolutions are analyzed ([31, Theorem 3.4]). We notice that the definition of Calabi–Yau variety in [31] is slightly different from our definition, indeed in [31], it is not required that $h^{2,0} = 0$ and some particular singularities are admitted. Anyway, the three-folds $X_{3,1}$ and $X_{3,2}$ in [31, Theorem 3.4] have $h^{2,0} = 0$.

In [14], the finite subgroups of $SL_3(\mathbb{Z})$ are classified and the action of some of these subgroups on the product of three elliptic curves is studied.

In [2], certain Calabi–Yau varieties obtained as desingularization of quotients of an Abelian variety by a group of automorphisms are presented and their cohomology is computed.

5.2 Elementary modifications

In [15], two constructions are considered, both of them are related to the presence of rational curves C on a Calabi–Yau three-fold X such that the normal bundle of C in X is $\mathcal{N}_{C/X} \simeq \mathcal{O}_{\mathbb{P}^1}(-1) \oplus \mathcal{O}_{\mathbb{P}^1}(-1)$. The curves that satisfy this property are said to be of type $(-1, -1)$. The first construction is the elementary modification with respect to one of these curves, the second one is the smoothing of the three-fold obtained by contracting these curves. We will see later that the curves $A_{i,j}^h$ on \mathcal{Z} are rational curves of type $(-1, -1)$ and hence can be used for these constructions.

The elementary modification on a rational curve $C \subset X$ of type $(-1, -1)$ consists of a blow up of C and a blow down: blowing up the curve C on X , one obtains a variety \hat{X} with an exceptional divisor D , which is isomorphic to $\mathbb{P}^1 \times \mathbb{P}^1$ (which is a \mathbb{P}^1 -bundle over the curve $C \simeq \mathbb{P}^1$). Now one can contract the first or the second copy of \mathbb{P}^1 in the exceptional divisor $\mathbb{P}^1 \times \mathbb{P}^1$. One of these contractions is the opposite of the blow up $\hat{X} \rightarrow X$, gives exactly X and sends D to $C \subset X$, the other one gives a new 3-fold X' (in this case D is sent to a rational curve $C' \subset X'$), which is said to be obtained by X by an elementary modification (or a flop) on the curve C :

$$\begin{array}{ccccc} X & \leftarrow & \hat{X} & \rightarrow & X' \\ C & \leftarrow & D & \rightarrow & C' \end{array} .$$

If X is projective, X' is not necessarily a projective variety, (see for example [15, Examples 7.6, 7.7]). In fact X' may not even be Kähler.

In [30], some fibrations on the three-fold \mathcal{Z} are described. They are induced by the projection of E^3 on $E \times E$, the product of two factors of E^3 , and the general fiber is an elliptic curve. Thanks to the results in Section 2.3 we conclude that these elliptic fibrations are associated to the divisors $F_i + F_j$ on \mathcal{Z} . These elliptic fibrations have some singular fibers which, are the fibers over the points of $E \times E$ (the base of the fibration) which are fixed by φ_3 . These fibers consist of a rational curve and three planes. From this geometric description it is immediate that the rational curve is one of the curves $A_{i,j}^h$ and the planes are three of the $B_{i,j,k}$'s. More precisely, if the fibration considered is obtained from the projection $E^3 \rightarrow E \times E$ on the second and the third factors, then the rational curves over the points $(p_i, p_j) \in E \times E$ are $A_{i,j}^1$ and the planes in the fibers are $B_{a,i,j}$, $a = 1, 2, 3$. Once one fixes the projection $E^3 \rightarrow E \times E$, the rational curves in the exceptional fibers depend only on i, j and these curves are denoted by $l_{i,j}$ in [30]. In [30, Proposition 2.2] it is proved that the curves $A_{i,j}^k$ (denoted by $l_{i,j}$ by Oguiso) are of type $(-1, -1)$. Moreover in [30, Proposition 2.4] the

three-folds X_T , obtained by elementary modifications on certain subsets T of curves $A_{i,j}^k$, are proved to be Calabi–Yau varieties with $h^{2,1} = 0$. By construction, the three-folds \mathcal{Z} and X_T are birational, but in [27, Theorem 3.1] it is proved that they are not homeomorphic, i.e., they are not equivalent from a topological point of view.

6 The smoothings

In this Section, we construct a new Calabi–Yau three-fold obtained by smoothing a singular model of \mathcal{Z} .

In [15, Section 8] the smoothing of a singular variety obtained by the contraction of certain curves on a three-fold with trivial canonical bundle is analyzed. Let V be a three-fold with trivial canonical bundle and let C_i be rational curves on it. Let \bar{V} be the three-fold obtained contracting the C_i and let us assume that the C_i contract to singular ordinary double points, p_i , on \bar{V} . Let $r : V \rightarrow \bar{V}$ be the contraction. Let V_t be the three-fold obtained by smoothing \bar{V} , i.e., V_t is the fiber over t of a proper flat map $f : \mathcal{V} \rightarrow \Delta$, where Δ is the unit disc of \mathbb{C} , such that $f^{-1}(0) = \bar{V}$ and $f^{-1}(s) = V_s$ is smooth for each $s \in \Delta$, $s \neq 0$. Friedman proves the following results:

Lemma 6.1 ([15, Lemma 8.7]). *Let \bar{V} be a compact complex three-fold with only ordinary double point singularities and let $\pi : V \rightarrow \bar{V}$ be a small resolution such that the canonical bundle of V is trivial. Let p_i be the singularities of \bar{V} and C_i be the curve $\pi^{-1}(p_i)$. Then there exists a first order deformation of \bar{V} which is nontrivial for the p_i (i.e., smooths them to first order) if and only if the fundamental classes $[C_i]$ in $H^2(V, \Omega_V^2)$ satisfy a relation $\sum_i \lambda_i [C_i] = 0$ such that for every i , $\lambda_i \neq 0$.*

This Lemma gives a condition to assure that there exists a smoothing of the three-fold \bar{V} . The following two lemmas describe the properties of this smoothing, if it exists.

Lemma 6.2 ([15, Lemma 8.1]). *With the previous notations, let $e : \oplus_i \mathbb{Z}C_i \rightarrow H_2(V, \mathbb{Z})$ be the map which associates to each curve its class, then $H_2(V_t, \mathbb{Z})$ is isomorphic to the cokernel of e and $b_3(V_t) = b_3(V) + 2s$, where s is the rank of the kernel of e .*

Lemma 6.3 ([15, Lemma 8.2]). *With the previous notations: 1) if $h^{i,0}(V) = 0$ for a certain i , then $h^{i,0}(V_t) = 0$ for any small t .*

2) If the canonical bundle of V is trivial and $h^{1,0}(V) = 0$, then the canonical bundle of V_t is trivial.

The previous lemma implies that, if V is a Calabi–Yau variety, then V_t is a Calabi–Yau variety. Moreover, if one can describe the map e , its kernel and its cokernel, one immediately deduces $b_2(V_t)$ and $b_3(V_t)$. For a Calabi–Yau variety, we have $b_2 = h^{1,1}$ and $b_3 = 2 + h^{2,1} + h^{1,2} = 2 + 2h^{2,1}$. Thus knowing e , one determines the Hodge diamond of the Calabi–Yau variety V_t .

Now the idea is to apply these results to $V = \mathcal{Z}$ and to the contraction m_1 of the 27 curves $A_{i,j}^k$, $i, j, k = 1, 2, 3$. Indeed $\overline{\mathcal{Z}} := m_1(\mathcal{Z})$ is a three-fold with only ordinary double points (this was proved in Proposition 4.8, but is also the consequence of the cited result by Oguiso, [30, Proposition 2.2], who proved that the curves $A_{i,j}^k$ are of type $(-1, -1)$) and $m_1 : \mathcal{Z} \rightarrow \overline{\mathcal{Z}}$ is the small resolution required by Lemma 6.1. Now it suffices to show that there exists a relation in $H_2(\mathcal{Z}, \mathbb{Z}) \simeq H^4(\mathcal{Z}, \mathbb{Z})$

$$\sum_{i,j,k=1,2,3} \lambda_{i,j,k} A_{i,j}^k = 0, \quad \lambda_{i,j,k} \neq 0, \text{ for each } i, j, k = 1, 2, 3, \quad (21)$$

to prove that there exists a smoothing of $\overline{\mathcal{Z}}$. If this smoothing exists, then its fibers are Calabi–Yau three-folds, by Lemma 6.3. We described $A_{i,j}^k$ as linear combination of a basis of $H^{2,2}(\mathcal{Z})$ in (10). Hence, it suffices to substitute each $A_{i,j}^k$ with its expression in (21) and to determine $\lambda_{i,j,k}$ such that all the coefficients of the basis of $H^{2,2}(\mathcal{Z})$ are equal to zero. The following choice for the $\lambda_{i,j,k}$, all nonzero, gives the relation:

$$4A_{1,1}^1 + \sum_{i=2}^3 A_{1,i}^1 + A_{2,1}^1 - 2 \sum_{i=2}^3 A_{2,i}^1 + A_{3,1}^1 - 2 \sum_{i=1}^3 A_{3,i}^1 - 2 \sum_{i=1}^3 A_{1,i}^2 + \sum_{i=1}^3 A_{2,i}^2 + \sum_{i=1}^3 A_{3,i}^2 - 2 \sum_{i=1}^3 A_{1,i}^3 + \sum_{i=1}^3 A_{2,i}^3 + \sum_{i=1}^3 A_{3,i}^3 = 0.$$

Hence, there exists a smoothing of $\overline{\mathcal{Z}}$ and its fibers are Calabi–Yau varieties. We compute the Hodge numbers of these Calabi–Yau three-folds, using Lemma 6.2. Indeed the map e in this lemma is exactly the one described by the relations (10). It is a trivial computation to show that its kernel has dimension six and hence we have that $b_3(V_t) = 2 + 12 = 14$ and $b_2(V_t) = 36 - 21 = 15$. Thus, the Hodge diamond of the Calabi–Yau varieties which are smooth fibers of the smoothing of $\overline{\mathcal{Z}}$ is the following:

$$\begin{matrix} & & & & 1 & & & & \\ & & & & 0 & & 0 & & \\ & & & & 0 & & 15 & & 0 \\ & & & & 1 & & 6 & & 6 & & 1 \end{matrix} \quad (22)$$

and Euler characteristic equal to 18.

Remark 6.4. In [4, figure 1], the known Calabi–Yau three-folds with small Hodge numbers are listed. The Calabi–Yau three-fold obtained as smoothing of $\overline{\mathcal{Z}}$ with Hodge diamond (22) is unknown.

In a similar way, one can consider the map f_{F-M+F_3} associated to the divisor $F - M + F_3$. As proved in Section 4.4, this map contracts the 18 curves $A_{i,j}^k$, $i, j = 1, 2, 3$, $k = 1, 2$ and is injective with an injective differential away from these curves. The map $f_{F-M+F_3} : \mathcal{Z} \rightarrow f_{F-M+F_3}(\mathcal{Z})$ contracts the curves $A_{i,j}^k$, $i, j = 1, 2, 3$, $k = 1, 2$ to ordinary double points (indeed all these curves are of type $(-1, -1)$). Among these curves there exists the following relation:

$$2 \sum_{i=1}^3 A_{1,i}^1 - \sum_{i=1}^3 (A_{2,i}^1 + A_{3,1}^1) - 2 \sum_{i=1}^3 A_{1,i}^2 + \sum_{i=1}^3 (A_{2,i}^2 + A_{3,1}^2) = 0$$

thus one can smooth $f_{F-M+F_3}(\mathcal{Z})$ to Calabi–Yau varieties. By Lemma 6.2, we compute the Hodge numbers of such a smooth Calabi–Yau: $b_3 = 2 + 4 = 6$, $b_2 = 36 - 16 = 20$. Thus, the Hodge diamond is

$$\begin{array}{ccccccc}
 & & & & 1 & & & & \\
 & & & & 0 & & 0 & & \\
 & & & 0 & 20 & & 0 & & \\
 & & 1 & & 2 & & 2 & & 1
 \end{array} \tag{23}$$

and Euler characteristic equal to 36.

The situation is essentially the same considering the maps induced by $F - M + F_1$ and $F - M + F_2$.

Remark 6.5. In [6, Pag. 25, line 1 and Section 3.4.2] a Calabi–Yau three-fold with the Hodge diamond mirror of the one in (23) is given. In particular this Calabi–Yau is constructed as smooth quotient of a complete intersection. We do not know if this Calabi–Yau manifold is the mirror of the one constructed as smoothing of $f_{F-M+F_3}(\mathcal{Z})$ or if they only have specular Hodge numbers.

In Section 4.4 we noticed that the map associated to $F - M + F_1 + F_2$ contracts the nine curves $A_{i,j}^3$, $i, j = 1, 2, 3$, but we cannot use the map $f_{F-M+F_1+F_2}$ to construct a smoothing of $f_{F-M+F_1+F_2}(\mathcal{Z})$. Indeed, it is immediate to check that the curves $A_{i,j}^3$, $i, j = 1, 2, 3$, are linearly independent and hence there exists no relation among them as required by Lemma 6.1, i.e., there exists no smoothing of $f_{F-M+F_1+F_2}(\mathcal{Z})$.

7 Conclusions

In this paper, we analyzed the geometry of the rigid Calabi–Yau three-fold \mathcal{Z} . This Calabi–Yau is well known, but the careful description of its geometry allows us to give a different interpretation of known results (for example of the generalized mirror) and to construct other Calabi–Yau three-folds.

The mirror conjecture says that two families of Calabi–Yau three-folds are mirror if the complex moduli space of one of them is locally isomorphic to the Kähler moduli space of the other one. The definition of the isomorphism among these two moduli spaces implies that the instanton corrections defined on $H^{1,1}$ of one of them can be reconstructed by the superpotential of the complex moduli defined on $H^{2,1}$ of the other Calabi–Yau three-fold and thus involve the Yukawa coupling on the Calabi–Yau three-folds. The mirror conjecture is stated, and in particular cases proved, under two hypotheses on the families of Calabi–Yau three-folds: the families have to be at least one-dimensional and have to admit a point with maximal unipotent monodromy. Families of Calabi–Yau three-folds without a point with maximal unipotent monodromy are described for example in [17, 18, 33]. An extension of the mirror conjecture to these families is until now unknown. On the contrary, there are some ideas to extend the mirror conjecture to rigid Calabi–Yau three-folds (see [1, 7, 32]). In particular in [7] a generalized mirror for the three-fold \mathcal{Z} is proposed. In the classical mirror symmetry there often is a geometric link among families of Calabi–Yau three-folds and their mirrors and this link is very useful in the mirror construction: the most famous example is the mirror of the quintic in \mathbb{P}^4 , which is the desingularization of the quotient of a particular quintic by a group of automorphisms. In this paper we have analyzed a lot of properties of the well known rigid Calabi–Yau three-fold \mathcal{Z} and we gave a geometric relation between it and its generalized mirror.

The other problem we analyzed is the construction of families of Calabi–Yau three-folds with given Hodge numbers. In [4] there is a list of the pairs of small numbers which can be the Hodge numbers of Calabi–Yau three-folds. Not all these pairs correspond to known Calabi–Yau three-folds. Here, we constructed a new family with given Hodge numbers, starting from the Calabi–Yau three-fold \mathcal{Z} .

In this paper, we have obtained essentially three types of results: in Sections 2.1 and 3, we described the trilinear form on $\text{Pic}(\mathcal{Z})$ and hence we gave information on the Yukawa coupling of \mathcal{Z} ; in Section 4 we gave very explicit equations of projective models of \mathcal{Z} , related one of them with the

generalized mirror of \mathcal{Z} and suggested how to construct other models; in Section 6 we constructed other Calabi–Yau three-folds starting from \mathcal{Z} .

In Section 2, the trilinear form on $\text{Pic}(\mathcal{Z})$ is computed. As we already said this gives information on the Yukawa coupling of \mathcal{Z} , but it is also important in view of the construction of the projective models of \mathcal{Z} . The computation of this form is very explicit and we essentially proved that the Picard group of \mathcal{Z} splits in two parts, one of them comes from $\text{Pic}(E^3)$, the other one from the resolution of the singularities of the quotient E^3/φ_3 . The trilinear form on the second part is very elementary, the one on the first part depends only on the properties of the Abelian variety E^3 . We proved that the trilinear form on $\text{Pic}(E^3)$ can be expressed in terms of determinants of certain matrices in $\text{Mat}_{3,3}(\mathbb{Q}[\zeta])$. This is useful because, of course, makes the computation easier, but could also have a deeper meaning, indeed this creates a strong relation between a significative part of the Yukawa coupling of \mathcal{Z} and a group of matrices. This could help in clarifying the relation between string theory and exceptional supergravities, cf. [16].

The three-fold \mathcal{Z} is well known in the literature as desingularization of the quotient of an Abelian variety by a group of automorphisms, but there are not many explicit descriptions of its projective models. Here, we provided three very explicit descriptions and suggested a strategy to obtain many others: We wrote down the equations of maps from E^3 to projective spaces and related them with divisors on E^3 . Thanks to the strong relation between \mathcal{Z} and E^3 these maps give (singular) models of \mathcal{Z} . In particular, we analyzed three maps: the first one exhibits \mathcal{Z} as a $3 : 1$ cover of another Calabi–Yau three-fold \mathcal{Y} , which is contained in the cubic hypersurface F_8 in \mathbb{P}^8 . This is interesting in view of the study of the mirror conjecture of rigid Calabi–Yau three-folds, indeed in [7], a quotient of the cubic Fermat hypersurface F_8 is proved to be a generalized mirror of \mathcal{Z} and the hypersurface F_8 is conjectured to be the generalized mirror of \mathcal{Y} (see [26]). Here, we have provided a geometric relation between these two rigid Calabi–Yau three-folds (\mathcal{Z} , \mathcal{Y}) and their generalized mirrors. The second map gave a singular birational model of \mathcal{Z} . It is embedded in \mathbb{P}^{11} and its singular locus consists of 27 ordinary double points. This model is used in Section 6 to construct other Calabi–Yau three-folds. The third map was already considered by Kimura in [25] and exhibits the birationality of \mathcal{Z} and the variety $V_{3,3}$, a complete intersection of two particular cubics in \mathbb{P}^5 .

The richness of the results obtained from the study of these three maps (such as the geometric relation between rigid Calabi–Yau three-folds and their generalized mirrors or the possibility to construct other Calabi–Yau varieties) suggests it might be interesting to analyze also other models, constructed in a similar way (i.e., writing the explicit maps defined on E^3).

For this reason we introduced maps associated to other divisors (see Remark 4.5 and Section 4.4) and in particular we proved that one of these divisors is very ample (and thus gives an isomorphism between \mathcal{Z} and its image under the induced map).

We think that our results on the connection between $\text{Pic}(\mathcal{Z})$ and a group of matrices and on the geometric relation between \mathcal{Z} and its generalized mirror could lead to a deeper understanding of the generalization of the mirror conjecture to rigid Calabi–Yau three-folds.

The construction of several projective models is important to better understand the geometry of \mathcal{Z} , but also because from singular models of \mathcal{Z} we have constructed new Calabi–Yau three-folds. In Sections 5 and 6, we presented some constructions that can be used to obtain Calabi–Yau three-folds from a given one, in particular from \mathcal{Z} . One of these constructions is the smoothing of a singular model of \mathcal{Z} . Considering singular models constructed in Section 4 and applying the smoothing to these models, we obtained two distinct Calabi–Yau three-folds with different Hodge numbers. One of these Calabi–Yau three-folds was unknown until now. It is now clear that the analysis of other singular projective models of \mathcal{Z} (for example associated to the divisors proposed in Section 4) could give other unknown Calabi–Yau three-folds. As we said, one can obtain other models considering the maps presented in Section 4.4, but one can also apply the techniques of Section 4 to other varieties, which are desingularizations of quotients of known varieties. This should give a lot of Calabi–Yau three-folds and we hope to find new Calabi–Yau varieties in this way.

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