

THE PLATEAU PROBLEM FOR marginally OUTER TRAPPED SURFACES

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Abstract

We solve the Plateau problem for marginally outer trapped surfaces in general Cauchy data sets. We employ the Perron method and tools from geometric measure theory to force and control a blow-up of Jang's equation. Substantial new geometric insights regarding the lower order properties of marginally outer trapped surfaces are gained in the process. The techniques developed in this paper are flexible and can be adapted to other non-variational existence problems.

1. Introduction

Let (M^n, g) be a complete oriented Riemannian manifold and let p be a symmetric $(0, 2)$ -tensor field defined on M^n . In the context of general relativity, triples (M^n, g, p) of this form arise as spacelike hypersurfaces of time-oriented Lorentz manifolds (\bar{M}^{n+1}, \bar{g}) where g is the induced metric and p is the second fundamental form with respect to the future pointing normal of M^n in \bar{M}^{n+1} . We will refer to (M^n, g, p) as an initial data set of general relativity. The case classically studied by physicists is that of $n = 3$, the development of string theory however has greatly increased the interest in higher dimensional space-times. Since the methods presented in this paper are in no way limited to 3 dimensions and, we hope, interesting in their own right, we will keep the exposition general. The author is grateful to G. Galloway for suggesting that the case $n = 2$ should also be included in the discussion because of interest in quantum gravity.

We now fix the terminology used in this work and briefly indicate the physical significance of the surfaces whose existence and properties are studied in this paper. We refer to [HE73], [W84], the discussion in [AM07], and the survey article [CPG08] for further background and concise references. Given an initial data set (M^n, g, p) and an open subset $\Omega \subset M^n$ we say that a smooth embedded oriented hypersurface

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$\Sigma^{n-1} \subset \Omega$, possibly with boundary, is *marginally outer trapped* if it satisfies the prescribed mean curvature equation

$$(1) \quad H_\Sigma + \text{tr}_\Sigma(p) = 0.$$

Here, $\text{tr}_\Sigma(p)$ denotes the trace of the tensor p over the tangent space of Σ^{n-1} and H_Σ is the scalar mean curvature of Σ^{n-1} computed consistently with the orientation of Σ^{n-1} . If Σ^{n-1} is given specifically as a (relative) boundary in Ω we require that condition (1) holds for the mean curvature scalar H_Σ computed as the tangential divergence of the outward pointing unit normal of Σ^{n-1} . The conditions $H_\Sigma + \text{tr}_\Sigma(p) < 0$ and $H_\Sigma + \text{tr}_\Sigma(p) > 0$ for such a relative boundary Σ^{n-1} are called *outer trapped* and *outer untrapped* respectively. If a space-time (\bar{M}^{n+1}, \bar{g}) containing (M^n, g, p) as a Cauchy surface satisfies the null energy condition and is asymptotically predictable, then the singularity theorem of Hawking and Penrose implies that closed marginally outer trapped surfaces $\Sigma^{n-1} \subset M^n$ lie inside the black hole region of (\bar{M}^{n+1}, \bar{g}) . In this concrete sense, marginally outer trapped surfaces have been studied as a “quasi-local version of the event horizon” of \bar{M}^{n+1} traced out on M^n . If Σ^{n-1} is outermost with respect to inclusion in its homology class amongst all marginally outer trapped surfaces of (M^n, g, p) , then it is referred to as an *apparent horizon* in the literature, and the compact region bounded by Σ^{n-1} is called the *trapped region*.

The prescribed mean curvature condition $H_\Sigma + \text{tr}_\Sigma(p) = 0$ characterizing marginally outer trapped surfaces is not known to arise as the Euler-Lagrange equation of a variational problem on (M^n, g, p) , except for the cases where the data is totally geodesic (i.e. $p \equiv 0$) and Σ^{n-1} is a minimal surface, or, more generally, when p is a constant multiple of g and marginally outer trapped surfaces are those with constant mean curvature.

In their proof of the space-time positive mass theorem [SY81], R. Schoen and S.-T. Yau constructed solutions to a one parameter family of regularizations of Jang’s equation on an initial data set (M^n, g, p) . Using curvature estimates and the Harnack principle on the graphs of these solutions in $M^n \times \mathbb{R}$, they argued that they can be passed subsequentially in the regularization limit to complete embedded submanifolds of $M^n \times \mathbb{R}$ that are made up of graphical components, corresponding to actual solutions of Jang’s equation on open subsets of M^n , and cylindrical components, whose cross-sections are closed marginally outer trapped surfaces in M^n . It is useful to think of this limiting submanifold as a geometric solution of Jang’s equation. R. Schoen proposed to employ the observations from [SY81] to show that closed marginally outer trapped surfaces exist in bounded regions $\Omega \subset M^n$ of the form $\Omega := \Omega_1 - \bar{\Omega}_2$ for which $\partial\Omega_1$ is outer untrapped and $\partial\Omega_2$ is outer trapped, by using

these conditions on the boundary to construct appropriately divergent solutions of Jang's equation on Ω which would lead to 'marginally outer trapped cylinders' as in [SY81]. The technical difficulty with this program stems from the one-sidedness of the trapping assumptions, which by themselves are not sufficient to derive a priori boundary gradient estimates to solve the relevant Dirichlet problems for the regularization of Jang's equation. L. Andersson and J. Metzger were able to overcome this difficulty by performing a delicate modification of the data and geometry of Ω to reduce to the special case where $p \equiv 0$ near $\partial\Omega$, so that the boundary gradient estimate can be derived as for the capillary surface equation. This allowed the authors to prove existence of closed marginally outer trapped surfaces under physically suggestive conditions in [AM07].

In this paper we develop a direct and versatile technique to force and control a blow-up of Jang's equation on the original data set, and we use it to prove existence of marginally outer trapped surfaces spanning a given boundary (the Plateau problem). On the way we introduce concepts and low order methods from geometric measure theory to the context of marginally outer trapped surfaces. The robust global geometric features of marginally outer trapped surfaces that are exhibited in this work provide a very tight analogy with the variational aspects of minimal and constant mean curvature surfaces, with immediate applications (cf. Appendix B and [E08]). They also open the door to study existence and regularity of marginally outer trapped surfaces in arbitrary dimension.

Theorem 1.1 (Plateau problem for marginally outer trapped surfaces). *Let (M^n, g, p) be an initial data set and let $\Omega \subset M^n$ be a bounded open domain with smooth boundary $\partial\Omega$. Let $\Gamma^{n-2} \subset \partial\Omega$ be a non-empty, smooth, closed, embedded submanifold that separates this boundary in the sense that $\partial\Omega \setminus \Gamma^{n-2} = \partial_1\Omega \dot{\cup} \partial_2\Omega$ for disjoint, non-empty, and relatively open subsets $\partial_1\Omega, \partial_2\Omega$ of $\partial\Omega$. We assume that $H_{\partial\Omega} + \text{tr}_{\partial\Omega} p > 0$ near $\partial_1\Omega$ and that $H_{\partial\Omega} - \text{tr}_{\partial\Omega} p > 0$ near $\partial_2\Omega$ where the mean curvature scalar is computed as the tangential divergence of the unit normal pointing out of Ω . Then there exists an almost minimizing (relative) boundary $\Sigma^{n-1} \subset \Omega$, homologous to $\partial_1\Omega$, whose singular set is strictly contained in Ω and has Hausdorff dimension $\leq (n - 8)$, so that Σ^{n-1} satisfies the marginally outer trapped surface equation distributionally, and so that Σ^{n-1} is a smooth hypersurface near Γ^{n-2} with boundary Γ^{n-2} . In particular, if $2 \leq n \leq 7$, then Σ^{n-1} is a smooth embedded marginally outer trapped surface in Ω which spans Γ^{n-2} .*

The boundary conditions for the domain Ω in this theorem are physically natural and reduce to a standard assumption (see [HS79], [MY82]) for the Plateau problem for minimal surfaces in Riemannian manifolds

when $p \equiv 0$. We emphasize that Σ^{n-1} in this theorem arises as a relative boundary of a subset $E \subset \Omega$ with finite perimeter in Ω which has the property that

$$|\mathrm{D}\chi_E|(\Omega) \leq |\mathrm{D}\chi_F|(\Omega) + C\mathcal{L}^n(E\Delta F)$$

for every $F \subset \Omega$ with $E\Delta F \subset\subset \Omega$.

Here $E\Delta F := (E - F) \cup (F - E)$ is the symmetric difference of E and F , $|\mathrm{D}\chi_E|(\Omega)$ and $|\mathrm{D}\chi_F|(\Omega)$ denote the perimeters of E and F in Ω , \mathcal{L}^n is n -dimensional Lebesgue measure, and $C := n|p|_{C(\bar{\Omega})}$ is an explicit constant. For convenience we will say throughout that a boundary Σ^{n-1} satisfying the above condition is C -almost minimizing. This particular property is a special case of much more general notions of almost minimizing currents as pioneered by F. Almgren in [Alm76]. We review the classical regularity and compactness results for such boundaries, which in essence are those of area minimizing boundaries, and give precise references to the literature in Appendix A. Notions of almost minimizing boundaries are typical in the context of variational problems with obstacles and constraints. We find it surprising that the C -almost minimizing property appears quite naturally in our study of marginally outer trapped surfaces, despite the lack of a variational principle. Along with it, the apparatus of geometric measure theory enters the picture, allowing us to dispense with the use of curvature estimates and to prove existence results in all dimensions. Moreover, area bounds for marginally outer trapped surfaces and the existence and regularity of the apparent horizon which have been established in [AM07] in $n = 3$ by a delicate surgery procedure based on a priori curvature estimates for stable 2-dimensional surfaces can be deduced from this property and hold in higher dimensions, as we discuss in [E08]. Besides this ‘zero order’ almost minimizing feature, the marginally outer trapped surfaces in the theorem also have certain stability properties (cf. Remark 3.1): if for example the data set satisfies the dominant energy condition, then the first Dirichlet eigenvalue of the conformal Laplacian of Σ^{n-1} will be non-negative.

The method presented in this paper immediately adapts to prove analogous existence results for $C^{1,\alpha}$ -boundaries Σ^{n-1} with prescribed boundary manifolds Γ^{n-2} that solve $H_\Sigma = F(x, \vec{\nu})$ distributionally, provided F is a continuous function on the Grassmann manifold $G_{n-1}(\Omega)$. The minor modifications are carried out for the special case of generalized apparent horizons (i.e. surfaces Σ^{n-1} with $H_\Sigma = |\mathrm{tr}_\Sigma(p)|$, cf. [BK08]) in [E08].

For context and convenient reference we briefly explain some of the key insights of R. Schoen and S.-T. Yau in their analysis of divergent

limits of solutions of the regularized Jang’s equation in Proposition 4 of [SY81]:

Given a complete asymptotically flat initial data set (M^n, g, p) consider a new “initial data set” $(M^n \times \mathbb{R}, g + dx_{n+1}^2, p)$, where p is extended trivially to $M^n \times \mathbb{R}$ by zero in the vertical direction. For $u : M^n \rightarrow \mathbb{R}$ consider the condition

$$(2) \quad \left(g^{ij} - \frac{u^i u^j}{1 + |Du|^2} \right) \left(\frac{D_i D_j u}{\sqrt{1 + |Du|^2}} + p_{ij} \right) = 0.$$

This equation was introduced in [J78] and has become known as Jang’s equation. Note that

$$H(u) := \left(g^{ij} - \frac{u^i u^j}{1 + |Du|^2} \right) \frac{D_i D_j u}{\sqrt{1 + |Du|^2}}$$

expresses the mean curvature of the graph of u as a submanifold in $M^n \times \mathbb{R}$ when computed as the tangential divergence of the downward pointing unit normal. The expression

$$\text{tr}(p)(u) := \left(g^{ij} - \frac{u^i u^j}{1 + |Du|^2} \right) p_{ij}$$

is the trace of p over the tangent space of this graph. Put differently, the graph of a solution u of Jang’s equation (2) is a marginally outer trapped surface in $(M^n \times \mathbb{R}, g + dx_{n+1}^2, p)$. Proving existence of entire solutions $u : M^n \rightarrow \mathbb{R}$ of (2), say with decay to 0 on the asymptotically flat ends, is hampered by the lack of sub and super solutions for a priori estimates. To overcome this, for parameters $t > 0$ the regularized problems of finding $u_t : M^n \rightarrow \mathbb{R}$ with

$$(3) \quad (H + \text{tr}(p))u_t = tu_t \text{ with } u_t(x) \rightarrow 0 \text{ on the ends of } M^n$$

are introduced and studied in [SY81]. The constant functions $\pm n|p|_{C^0}/t$ are barriers for these problems. Together with interior estimates for the gradient, the a priori estimate $t|u_t| + t|Du_t| \leq C(|\text{Ric}_M|, |p|_{C^1})$ is obtained, and existence of solutions u_t of (3) follows from the continuity method. It is then shown in [SY81] that vertical translation is an ‘approximate Jacobi field’ on $\text{graph}(u_t)$, where ‘approximate’ is independent of $t > 0$. This leads to a uniform stability-like inequality for these graphs. The iteration method from [SSY75] provides geometric bounds for these hypersurfaces of $M^n \times \mathbb{R}$ provided that $n \leq 5$. It follows that in low dimensions one can pass $\text{graph}(u_t)$ to a smooth limiting hypersurface $G \subset M^n \times \mathbb{R}$ along a subsequence $t_i \searrow 0$. This submanifold G is then a marginally outer trapped surface in $(M^n \times \mathbb{R}, g + dx_{n+1}^2, p)$. The Harnack principle implies that every connected component of G is either itself a graph over some open subset $\Omega_0 \subset M^n$ (on which the defining function solves Jang’s equation), or else is a cylinder of the form

$\Sigma^{n-1} \times \mathbb{R}$ (in which case Σ^{n-1} is a closed marginally outer trapped surface). It also follows that the graphical components in this limit G must be asymptotic to such marginally outer trapped cylinders $\Sigma^{n-1} \times \mathbb{R}$ on approach to $\partial\Omega_0$. By the same token, the boundaries of the sets Ω_+ and $\Omega_- \subset M^n$ on which the functions $u_{t_i}(x)$ diverge to plus, respectively, minus infinity as $t_i \searrow 0$ consist of smooth closed embedded marginally outer trapped surfaces $\Sigma^{n-1} \subset M^n$. If no such surfaces are contained in the initial data set or if $|u_t|$ is bounded independently of $t > 0$, then this construction leads to an entire solution $u : M^n \rightarrow \mathbb{R}$ of Jang's equation. Importantly, these arguments of [SY81] show that if solutions u_t of the regularized Jang's equation (3) diverge to plus infinity in some places and stay finite or diverge to minus infinity in other places as $t \searrow 0$, then there must be a marginally outer trapped surface Σ^{n-1} in the base.

Note the analogy of this blow-up analysis of [SY81] with M. Miranda's notion of "quasi-solutions" of the minimal surface equations (see §4.1 in [MM84]), which provides an appropriate and convenient framework in which to pass possibly divergent minimal graphs and more generally graphs of functions that solve a variational problem to subsequential limits.

R. Schoen suggested to use the features of [SY81] to prove existence of marginally outer trapped surfaces in domains Ω by forcing a blow-up of Jang's equation from trapping conditions imposed on the boundary. The existence of closed marginally outer trapped surfaces between an outer trapped and an outer untrapped boundary in [AM07] was obtained as a corollary of the analysis in Proposition 4 of [SY81] explained above by constructing appropriately divergent solutions of certain Dirichlet problems for the regularized Jang's equation on a modified data set. To tackle the Plateau problem from this direction, we are interested in finding solutions $u_t \in \mathcal{C}^{2,\mu}(\bar{\Omega})$ of

$$(4) \quad \begin{array}{lll} (\mathbb{H} + \text{tr}(p))u_t & = tu_t & \text{on } \Omega \\ u_t & = \varphi_t & \text{on } \partial\Omega \end{array}$$

for choices of boundary data φ_t that, loosely speaking, diverge to plus infinity as $t \searrow 0$ on $\partial_1\Omega$, and to minus infinity on $\partial_2\Omega$. From [SY81] one expects that if such solutions u_t exist and if their graphs can be passed to a smooth subsequential limit in $\Omega \times \mathbb{R}$, then this limit either contains a marginally outer trapped cylinder $\Sigma^{n-1} \times \mathbb{R}$, or contains a graphical component asymptotic to such a cylinder, whose cross-section $\Sigma^{n-1} \subset \Omega$ spans the boundary $\Gamma^{n-2} \subset \partial\Omega$. Note that if (M^n, g) is flat and $p \equiv 0$, then (4) is just the Dirichlet problem for the ordinary capillary surface equation. In this case the Dirichlet problem is well-posed provided that $t|\varphi_t(x)| \leq H_{\partial\Omega}(x)$ at every boundary point $x \in \partial\Omega$, by §20 in [Se69]. When $p \not\equiv 0$, the methodology of J. Serrin in [Se69] provides sub and super solutions for the boundary gradient estimate

for solutions u_t of (4) provided that $-H_{\partial\Omega}(x) + \text{tr}_{\partial\Omega}(p)(x) < t\varphi_t(x) < H_{\partial\Omega}(x) + \text{tr}_{\partial\Omega}(p)(x)$ at every boundary point $x \in \Omega$. These barriers are constructed as inward perturbations of the cylinders $\partial\Omega \times \mathbb{R}$ below, respectively above, the boundary values φ_t . In addition to the one-sided trapping assumption for $\partial\Omega$ at hand this would require the boundary to satisfy the much stronger condition $H_{\partial\Omega} > |\text{tr}_{\partial\Omega}(p)|$, or at least to be mean-convex in addition to the original assumption. The original proof of the boundaryless case of the Plateau problem in [AM07] is precisely by deforming the geometry and data carefully to reduce to this special case (in fact to the case where $p \equiv 0$ near $\partial\Omega$).

Our method of constructing appropriately divergent solutions of the regularized Jang's equation takes place on the original data set. However, we will not find exact solutions of the Dirichlet problems. Instead, we are going to use the Perron method, suitably adapted to this context, to obtain maximal interior solutions u_t of the equations $L_t u_t := (H + \text{tr}(p) - t)u_t = 0$ subject to the condition that $\underline{u}_t \leq u_t \leq \bar{u}_t$. Here, \underline{u}_t and \bar{u}_t are viscosity sub and super solutions for the monotone operators L_t which coincide with standard barriers obtained from the one-sided trapping assumptions $H_{\partial_1\Omega} + \text{tr}_{\partial_1\Omega}(p) > 0$ and $H_{\partial_2\Omega} - \text{tr}_{\partial_2\Omega}(p) > 0$ near the respective portions of $\partial\Omega$, and which are suitably extended to the interior by the constant barriers $\pm n|p|_{C(\bar{\Omega})}/t$. In general these sub and super solutions will only match up in a small neighborhood of $\Gamma^{n-2} \subset \partial\Omega$ (where the trapping assumptions are two-sided), hence forcing u_t to assume prescribed values there. Besides this, we will not be able to say anything precise about the boundary behavior of the u_t 's other than to assert their divergence in the regularization limit $t \searrow 0$. Along with the geometric compactness of the graphs of these solutions (which have their mean curvature bounded independently of $t > 0$ and hence are almost minimizing) this is fortunately all we need. We note in Lemma A.1 that the almost minimizing property of $\text{graph}(u_t) \subset \Omega \times \mathbb{R}$ descends to the cross-sections of cylinders contained in limits and limits of vertical translations of such surfaces. We can conclude the boundary regularity of Σ^{n-1} from an application of [All75].

The use of the Perron method in conjunction with the minimal surface operator goes back to the study of Dirichlet problems for minimal and constant mean curvature graphs in [JS66] and [Se70]: maximal interior solutions to these problems exist provided the domain admits sub and super solutions, and these Perron solutions assume continuous boundary values where the boundary is sufficiently mean-convex so that two-sided barriers can be constructed. The analysis described above shares important features with the classical construction of Scherk-type (i.e. infinite boundary value) minimal graphs in polygonal regions in \mathbb{R}^2 in [JS68] and its obstructions expressed by the Jenkins-Serrin conditions,

and variants of it in [Sp72], [M77], and [HRS08]. The elegant reflection method of [Sp72] to deal with boundary arcs of constant negative curvature does not seem to generalize to our setting.

In [SY83], R. Schoen and S.-T. Yau used their work on Jang's equation to show that if the boundary of a compact domain Ω is trapped both ways, i.e. if $H_{\partial\Omega} > |\text{tr}_{\partial\Omega}(p)|$, and if enough matter is concentrated in Ω compared to its homological filling radius $\text{Rad}(\Omega)$, then Ω must contain a marginally outer trapped surface, see also [Y97]. This important result about the geometry of initial data sets has been sharpened and generalized by S.-T. Yau in [Y01].

In the next section, we collect several technical lemmas on the regularized Jang's equation. In Section 3 we employ the Perron method to construct maximal interior solutions of these equations when only one-sided boundary barriers are available. As an application we present a new proof of the existence of closed marginally outer trapped surfaces between oppositely trapped surfaces, and we record the uniform almost minimizing property of the surfaces that are found. This sets the stage for our main application, the solution of the Plateau problem, in Section 4. Standard results from geometric measure theory regarding the compactness and regularity theory for the classes \mathcal{F}_C of C -almost minimizing boundaries, which will be used throughout this paper, are reviewed in Appendix A. We conclude with a brief remark on outermost marginally outer trapped surfaces in Appendix B.

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2. Interior gradient estimate, the regularized Jang's equation on small balls, and the Harnack principle

In this section we give three routine lemmas that will be needed later in this paper.

First, we apply the maximum principle method of Korevaar-Simon (see [K86], [KS88], and [Sp07] for the method on Riemannian manifolds) to obtain interior gradient estimates from one-sided oscillation bounds for solutions of the regularized Jang's equation. The derivation of the required estimate is well-known and straightforward from these

references but not quite contained in their presentation, so we include the proof for completeness. In [Si76a] interior gradient estimates for very general PDE's of prescribed mean curvature type, including those considered in this section, have been obtained by iteration techniques. The author is grateful to Leon Simon for very helpful discussions regarding these estimates.

We begin by introducing relevant notation. Let (M^n, g, p) be an initial data set and let u be a real valued function defined on an open subset of M^n on which it solves $(H + \text{tr}(p))u = tu$ for some $t \geq 0$. Let $\Sigma^n := \text{graph}(u) \subset M^n \times \mathbb{R}$ and endow this hypersurface with the induced metric \bar{g} from $(M^n \times \mathbb{R}, g + dx_{n+1}^2)$. If x_1, \dots, x_n are local coordinates on M^n , we agree on the following notation and sign convention, cf. [SY81] and [Sp07]:

$$\begin{aligned}
 \bar{g}_{ij} &= g_{ij} + u_i u_j && \text{induced metric in base coordinates} \\
 \bar{g}^{ij} &= g^{ij} - \frac{u^i u^j}{1 + |Du|^2} && \text{inverse of the induced metric} \\
 v &= \sqrt{1 + |Du|^2} && \text{area element (really area stretch factor)} \\
 \vec{\nu} &= \nu^i \frac{\partial}{\partial x_i} - \frac{1}{v} \frac{\partial}{\partial t} \text{ where } \nu^i = \frac{u^i}{v} && \text{(downward pointing) unit normal} \\
 h_{ij} &= v^{-1} D_i D_j u && \text{second fundamental form} \\
 H_\Sigma &= H(u) = \bar{g}^{ij} h_{ij} = D_i \nu^i && \text{mean curvature} \\
 \text{tr}_\Sigma(p) &= \text{tr}(p)(u) = \bar{g}^{ij} p_{ij} && \text{trace of } p \text{ over the tangent space of } \Sigma^n \\
 \Delta_\Sigma u &= v^{-1} H_\Sigma
 \end{aligned}$$

Here, all covariant derivatives are taken with respect to the g metric on the base, and indices are raised with respect to g , unless indicated otherwise.

The following identity for the hypersurface Laplacian of the area element of a graph (see (2.18) in [SY81] for a derivation) is well-known as the Jacobi equation (corresponding to the Killing field coming from vertical translation):

$$(5) \quad \Delta_\Sigma \left(\frac{1}{v} \right) + (\bar{g}(h, h) + \text{Ric}_{M \times \mathbb{R}}(\vec{\nu}, \vec{\nu}) + \underbrace{\vec{\nu}(tu - \text{tr}(p)(u))}_{H_\Sigma}) \frac{1}{v} = 0$$

where $H_\Sigma = H(u)$ is thought of as a function on $M^n \times \mathbb{R}$ (independent of the vertical coordinate x_{n+1}). We compute in coordinates on the base that

$$\begin{aligned}
 &\vec{\nu}(tu - \text{tr}(p)(u)) \\
 &= \nu^i (tu - \bar{g}^{mn} p_{mn})_i \\
 &= \nu^i (tu - p_m^m + \nu^m \nu^n p_{mn})_i \\
 &= \frac{t|Du|^2}{v} - \nu^i D_i p_m^m + 2p_{mn} h_{ip} \bar{g}^{pn} \nu^i \nu^m + D_i p_{mn} \nu^m \nu^n \nu^i
 \end{aligned}$$

(all covariant derivatives on M^n) so that for a constant $\beta \geq 0$ depending only on the size of the Ricci tensor and $|p|_{\mathcal{C}^1}$ we have that

$$(6) \quad \bar{g}(h, h) + \text{Ric}_{M \times \mathbb{R}}(\bar{v}, \bar{v}) + \bar{v}(tu - \text{tr}(p)(u)) \geq \frac{t|Du|^2}{v} - \beta \geq -\beta.$$

Note that no assumption on the size of $t|Du|$ is necessary here, since it enters the computation with a favorable sign. In view of the ensuing differential inequality $\Delta_\Sigma \left(\frac{1}{v}\right) \leq \frac{\beta}{v}$, the use of the maximum principle to derive an interior gradient estimate from a one-sided oscillation bound is now exactly as in [KS88] or [Sp07]:

Lemma 2.1 (Interior gradient estimate). *Fix a point $x_0 \in M^n$, a radius $\rho \in (0, \text{inj}_{x_0}(M^n, g))$ and $t \geq 0$. Suppose that $u \in \mathcal{C}^3(\mathbb{B}(x_0, \rho)) \cap \mathcal{C}(\bar{\mathbb{B}}(x_0, \rho))$ solves $(H + \text{tr}(p))u = tu$ on $\mathbb{B}(x_0, \rho)$ and that for some $T > 0$ either $u(x) \leq u(x_0) + T$ for all $x \in \mathbb{B}(x_0, \rho)$ or $u(x) \geq u(x_0) - T$ for all $x \in \mathbb{B}(x_0, \rho)$. Then $|Du|(x_0)$ is bounded explicitly by an expression in this one-sided oscillation T , the radius ρ , and bounds on $\mathbb{B}(x_0, \rho)$ for $|p|$, $|Dp|$, $t|u|$ and the sectional curvatures of g .*

Proof. We only consider $u(x) \leq u(x_0) + T$. The other case follows from this by considering the equation satisfied by $-u$. By decreasing ρ slightly if necessary we can assume that $u \in \mathcal{C}^3(\bar{\mathbb{B}}(x_0, \rho))$. Define on $\bar{\mathbb{B}}(x_0, \rho)$ the function $\phi(x) := -u(x_0) + u(x) + \rho - \frac{T+\rho}{\rho^2} \text{dist}(x_0, x)^2$ where $\text{dist}(x_0, x)$ is geodesic distance on M^n . Define the open set $\Omega = \{x \in \mathbb{B}(x_0, \rho) : \phi > 0\}$ and observe that $\phi = 0$ on the boundary of Ω , and that $x_0 \in \Omega$. For a number $K \geq 1$ to be chosen later, consider the cut-off function $\eta := e^{K\phi} - 1$. At a point where ηv achieves its maximum in Ω , one computes that

$$\begin{aligned} 0 &\geq \frac{1}{v} \Delta_\Sigma(\eta v) = \frac{\eta}{v} \Delta_\Sigma v + \frac{2}{v} \bar{g}(\bar{D}v, \bar{D}\eta) + \Delta_\Sigma \eta \\ &\geq \frac{2\eta}{v^2} |\bar{D}v|^2 - \beta \eta + \frac{2}{v} \bar{g}(\bar{D}v, \bar{D}\eta) + \Delta_\Sigma \eta = -\beta \eta + \Delta_\Sigma \eta \\ &= \beta + \{K \Delta_\Sigma \phi + K^2 |\bar{D}\phi|^2 - \beta\} e^{K\phi} \\ &\geq K \underbrace{\left\{ v^{-1} H_\Sigma - \frac{T+\rho}{\rho^2} \Delta_\Sigma \text{dist}^2(x_0, \cdot) - \beta \right\}}_{=: (I)} e^{K\phi} + K^2 \\ &\underbrace{\left\{ \left| Du - \frac{T+\rho}{\rho^2} D \text{dist}^2(x_0, \cdot) \right|^2 - \frac{(Du - \frac{T+\rho}{\rho^2} D \text{dist}^2(x_0, \cdot), Du)^2}{1 + |Du|^2} \right\}}_{=: (II)} e^{K\phi}. \end{aligned}$$

Recall that $\Delta_\Sigma f = \bar{g}^{ij} D_{ij}^2 f - H_\Sigma \frac{u^j}{v} \frac{\partial f}{\partial x_j}$ for functions f defined on the base, so that by the Hessian comparison theorem $\Delta_\Sigma \text{dist}^2(x_0, \cdot)$ is estimated in terms of ρ , a bound on the sectional curvatures of g on

$B(x_0, \rho)$, and a bound on H_Σ (which in turn is bounded by $n|p|$ and $t|u|$ from the equation that u satisfies). It follows that (I) , the term multiplying K , is a priori bounded, while $\liminf_{|Du| \rightarrow \infty} (II) \geq 1$. By fixing the constant K to be on the order of an absolute bound for (I) , it follows that $|Du|$ must lie below a definite threshold at points in Ω where $\eta v = (e^{K\phi} - 1)\sqrt{1 + |Du|^2}$ is largest. Since the auxiliary function ϕ is bounded on Ω by $T + \rho$, this implies an upper bound for $\eta v(x_0) = (e^{K\rho} - 1)\sqrt{1 + |Du|^2(x_0)}$ and hence for $|Du|(x_0)$. q.e.d.

Remark 2.1. This method of Korevaar-Simon provides interior gradient estimates from one-sided oscillation bounds for \mathcal{C}^3 -solutions u of $H(u) = F\left(x, \frac{Du}{\sqrt{1+|Du|^2}}, u\right)$, provided F is a \mathcal{C}^1 -function that is non-decreasing in its last argument.

In the introduction we discussed how boundary gradient estimates and hence existence for the Dirichlet problem for the regularized Jang’s equation (4) follow from standard barriers [Se70] provided the Dirichlet data φ and the geometry of $\partial\Omega$ are such that $H_{\partial\Omega}(x) > |\text{tr}_{\partial\Omega}(p) - t\varphi|(x)$ at every $x \in \partial\Omega$. In the construction of solutions to the exact Jang’s equation (possibly with interior blow-up) with boundary data φ this condition needs to be verified only for sufficiently small $t > 0$, so the requirement is that $H_{\partial\Omega} > |\text{tr}_{\partial\Omega}(p)|$. The sufficiency of this condition was pointed out by R. Schoen and S.-T. Yau. The following general lemma is a straightforward consequence of the continuity method in [SY81]. The case $t = 0$ in this lemma was discussed in [Y01], [WY08], and the case where φ is constant and $p \equiv 0$ near $\partial\Omega$ in [AM07].

Lemma 2.2. (*Dirichlet problem for regularized Jang’s equation*) *Let $\Omega \subset (M^n, g, p)$ be a bounded domain with smooth boundary, let $t \in (0, 1)$, and assume that $\varphi \in \mathcal{C}(\partial\Omega)$ is such that $H_{\partial\Omega} > |\text{tr}_{\partial\Omega}(p) - t\varphi|$. Then there exists $u \in \mathcal{C}^3(\Omega) \cap \mathcal{C}(\bar{\Omega})$ with $(H + \text{tr}(p))(u) = tu$ in Ω and such that $u = \varphi$ on $\partial\Omega$.*

Proof. First, note that interior extrema of a solution u are a priori bounded by $n|p|_{\mathcal{C}(\bar{\Omega})}/t$. As in the proof of Theorem 16.8 in [GT98], successive application of the interior gradient estimates in Lemma 2.1, Hölder estimates for the gradient (§13 in [GT98]), Schauder theory, and the Arzela-Ascoli theorem readily reduces to the case where $\varphi \in \mathcal{C}^{2,\mu}(\partial\Omega)$. Let $I = \{s \in [0, 1] : \exists w \in \mathcal{C}^{2,\mu}(\bar{\Omega}) \text{ s.t. } (H + s \text{tr}(p))w = tw \text{ in } \Omega \text{ and } w = s\varphi \text{ on } \partial\Omega\}$. Obviously, $0 \in I$ and the implicit function theorem (see the proof of Lemma 3 in [SY81] for the linearized operator) shows that I is relatively open. To see that I is closed (and hence all of $[0, 1]$) one requires an a priori estimate for solutions $w \in \mathcal{C}^{2,\mu}$ as in the definition of I that is independent of $s \in I$. By standard elliptic theory (notably the ‘Bernstein trick’ used at the beginning of Section 4 in [SY81], Hölder estimates for the gradient as

in Theorem 13.8 in [GT98], and Schauder estimates) it is sufficient to derive a boundary gradient estimate for w . Observe that by assumption, $H_{\partial\Omega} \geq \chi + |s \operatorname{tr}_{\partial\Omega}(p) - ts\varphi|$ for all $s \in [0, 1]$ for some constant $\chi > 0$, and that by continuity we may assume that this inequality not only holds for $\partial\Omega$, but also for all surfaces $\partial_\gamma\Omega$ parallel to $\partial\Omega$ at distances $\gamma \in (0, \delta)$ for some $\delta > 0$. This is precisely the hypothesis (14.60) of Serrin’s boundary gradient estimate as described in Theorem 14.9 in [GT98] (with Euclidean metric replaced by g): in local coordinates x_1, \dots, x_n near a point in $\partial\Omega$ the decomposition $a^{ij} = \Lambda a_\infty^{ij} + a_0^{ij}$ and $b = |p|\Lambda b_\infty + b_0$ of (14.43) in [GT98] is given by $\Lambda = (1 + |p|^2)$, $a_\infty^{ij} = g^{ij} - \frac{p^i p^j}{|p|^2}$, $a_0^{ij} = \frac{p^i p^j}{|p|^2}$, $b_\infty = (g^{ij} - \frac{p^i p^j}{|p|^2})(sp_{ij} - \Gamma_{ij}^k \frac{p_k}{|p|}) - tz$, $b_0 = -tz \frac{\Lambda}{\Lambda^{1/2} + |p|} - \frac{p^i p^j}{|p|^2} \Gamma_{ij}^k p_k + sp_{ij} \left(g^{ij} \frac{\Lambda}{\Lambda^{1/2} + |p|} + \frac{p^i p^j}{|p|} \frac{\Lambda^{1/2}}{\Lambda^{1/2} + |p|} \right)$. The metric g is used to raise indices and compute lengths here. Both b_0 and b_∞ are non-increasing in z , and the structural conditions (14.59) in [GT98] are also clearly satisfied. As for the boundary curvature conditions (14.60), note that $\mathcal{K}^- + b_\infty(x, s\varphi, -\vec{\nu}) = H_{\partial\Omega} + s \operatorname{tr}_{\partial\Omega}(p) - ts\varphi \geq \chi > 0$ (here $\vec{\nu}$ is the inward unit normal of $\partial\Omega$) leads to a sub solution of the form $\underline{w} = s\varphi - k \operatorname{dist}_{\partial\Omega}$, where $\operatorname{dist}_{\partial\Omega}(x)$ measures geodesic distance to $\partial\Omega$, φ is extended to Ω independently of $\operatorname{dist}_{\partial\Omega}$ through nearest point projection, and where $k \gg 1$ is sufficiently large depending on the (uniform) upper bound for w . Analogously, the condition $\mathcal{K}^+ - b_\infty(x, s\varphi, \vec{\nu}) = H_{\partial\Omega} - s \operatorname{tr}_{\partial\Omega}(p) + ts\varphi \geq \chi > 0$ leads to a super solution of the form $\overline{w} = s\varphi + k \operatorname{dist}_{\partial\Omega}$. In fact, if we extend $\vec{\nu}$ to a neighborhood of $\partial\Omega$ in Ω as the gradient of the distance function $\operatorname{dist}_{\partial\Omega}$, then $a_\infty^{ij}(x, d \operatorname{dist}_{\partial\Omega})(\operatorname{dist}_{\partial\Omega})_{ij} + b_\infty(x, \overline{w}, d \operatorname{dist}_{\partial\Omega}) \leq a_\infty^{ij}(x, d \operatorname{dist}_{\partial\Omega})(\operatorname{dist}_{\partial\Omega})_{ij} + b_\infty(x, \varphi(x), d \operatorname{dist}_{\partial\Omega}) = (g^{ij} - \nu^i \nu^j)(\nu_{i,j} + sp_{ij})(x) - ts\varphi(x) = (-H_{\partial_\gamma\Omega} + s \operatorname{tr}_{\partial_\gamma\Omega}(p))(x) - ts\varphi(x) \leq -\chi$ provided that $\operatorname{dist}_{\partial\Omega}(x) = \gamma < \delta$. This gives the boundary gradient estimate from Theorem 14.9 in [GT98]. Note also that by (6) an interior maximum value of $|Dw|$ in Ω must be bounded above by $\frac{\beta}{t}$ where $\beta = \beta(s|p|_{C^1(\overline{\Omega})}, |\operatorname{Ric}_M|_{C(\overline{\Omega})})$ (cf. (4.3) in [SY81]). q.e.d.

Corollary 2.1. *Let $\Omega \subset M^n$ and $t \in (0, 1)$. Fix a constant $C > n|p|_{C(\overline{\Omega})}$ where $|p|_{C(\overline{\Omega})}$ measures the largest eigenvalue of p with respect to g across $\overline{\Omega}$. For $x \in \Omega$ define $r_D(x) := \frac{1}{2} \min\{\operatorname{inj}_x(M^n, g), \operatorname{dist}(x, \partial\Omega), r_0(x)\}$ where $r_0(x) > 0$ is so small that $H_{\partial B(x,r)} > 3C$ for all $r \in (0, r_0(x))$. Then for every $r \in (0, r_D(x))$ and every $\varphi \in \mathcal{C}(\partial B(x, r))$ with $|\varphi|_{\mathcal{C}(\partial B(x,r))} \leq 2C/t$ the Dirichlet problem $(H + \operatorname{tr}(p))u = tu$ in $B(x, r)$ with $u = \varphi$ on $\partial B(x, r)$ has a unique solution $u \in \mathcal{C}^3(B(x, r)) \cap \mathcal{C}(B(x, r))$.*

We will frequently apply the following well-known Harnack argument for limits of graphs. For minimal graphs, this argument was devised in

[BG72] (see also §1 in [Si76b]). In the context of Jang’s equation a more sophisticated version was derived in Proposition 2 in [SY81].

Lemma 2.3 (Harnack principle). *Let $f_k : \Omega \rightarrow \mathbb{R}$, $k = 1, 2, \dots$, be a family of \mathcal{C}^3 -functions so that for some constant $\beta > 0$ it is true that $\Delta_{G_k} \frac{1}{v_k} \leq \frac{\beta}{v_k}$, where Δ_{G_k} is the (non-positive) Laplace-Beltrami operator of $G_k := \text{graph}(f_k, \Omega) \subset \Omega \times \mathbb{R}$, and where $\frac{1}{v_k} = (1 + |\nabla f_k|^2)^{-\frac{1}{2}}$ is the vertical component of the upward unit normal of G_k . If in some open subset $U \subset \Omega \times \mathbb{R}$ such graphs G_k converge (in \mathcal{C}^3 , as normal graphs) to a submanifold $G \subset U$ as $k \nearrow \infty$, then every connected component of G is either a vertical cylinder (i.e. of the form $\Sigma^{n-1} \times \mathbb{R}$), or is itself a graph over an open subset of Ω .*

Proof. Observe that G inherits an orientation from G_k , and we take its unit normal to be ‘upward’ in this sense. Since $G_k \rightarrow G$ in U it follows that $1/v_k$ converges to the vertical component of the unit normal vector of G (call it w). Clearly, $w \geq 0$ and $\Delta_G w - \beta w \leq 0$. By the Hopf maximum principle, either w vanishes identically on each connected component, or else is everywhere positive on it. In the first case, the connected component is evidently cylindrical, in the second alternative it is a graph. q.e.d.

3. The Perron method for Jang’s equation

In this section we invoke the Perron method to prove existence of certain maximal interior solutions u_t of the regularized Jang’s equations $L_t u_t := (H + \text{tr}(p) - t)u_t = 0$ on domains $\Omega \subset M^n$ whose boundary components satisfy certain one-sided trapping conditions. As a first application, and in preparation for the next section, we supply a new proof of the following theorem proposed by R. Schoen (with existence proven first in [AM07] in those dimensions where stability based curvature estimates are available):

Theorem 3.1. *Let (M^n, g, p) be an initial data set and let $\Omega \subset M^n$ be a connected bounded open subset with smooth embedded boundary $\partial\Omega$. Assume this boundary consists of two non-empty closed hypersurfaces $\partial_1\Omega$ and $\partial_2\Omega$ so that*

$$(7) \quad H_{\partial_1\Omega} + \text{tr}_{\partial_1\Omega} p > 0 \text{ and } H_{\partial_2\Omega} - \text{tr}_{\partial_2\Omega} p > 0,$$

where the mean curvature scalar is computed as the tangential divergence of the unit normal vector field that is pointing out of Ω . Then there exists a closed boundary $\Sigma^{n-1} \subset \Omega$ homologous to $\partial_1\Omega$ that is C -almost minimizing in Ω for an explicit constant $C = C(|p|_{\mathcal{C}(\bar{\Omega})})$ (and hence has singular set of Hausdorff dimension $\leq n - 8$) and which satisfies the marginally outer trapped surface equation $H_\Sigma + \text{tr}_\Sigma(p) = 0$ distributionally. In particular, if $2 \leq n \leq 7$, then Σ^{n-1} is a non-empty smooth

embedded closed marginally outer trapped surface in Ω . If $3 \leq n \leq 7$ and if the initial data set satisfies the dominant energy condition, then Σ^{n-1} has non-negative Yamabe type.

Remark 3.1. The fact that the dominant energy condition restricts the Yamabe type of hypersurfaces arising in a blow-up of Jang's equation was recognized and employed in [SY81]. In [AM07], the authors prove that a closed marginally outer trapped surface arising in the regularization limit of Jang's equation as in [SY81] satisfies the stronger 'non-symmetric' stability condition of [AMS05] that implies the non-negativity of its Yamabe type, as was proven in [GS06].

Note that if Ω arises as $\Omega := \Omega_1 - \bar{\Omega}_2$ with $\partial_1\Omega = \partial\Omega_1$ and $\partial_2\Omega = \partial\Omega_2$, then condition (7) asks that $\partial\Omega_2$ is outer trapped and $\partial\Omega_1$ is outer untrapped, and the theorem asserts that there exists a closed marginally outer trapped surface Σ^{n-1} in between.

As in [AM07], the existence of the marginally outer trapped surface Σ^{n-1} in Theorem 3.1 here will be an immediate corollary to Proposition 4 in [SY81], once appropriately divergent solutions u_t of the regularized Jang's equations $L_t u_t = 0$ are constructed. R. Schoen pointed out that the trapping assumptions (7) provide one-sided boundary barriers for Jang's equation but are by themselves not sufficient to solve the relevant Dirichlet problems (4). However, these one-sided boundary barriers together with the constant sub and super solutions coming from the capillarity regularization of Jang's equation do lead to *maximal interior solutions* u_t of $L_t u_t = 0$ which have the *required blow-up* behavior. The goal of this section is to make this statement precise and to prove it. Unlike with more typical Dirichlet problems, the solutions u_t here will not in general assume particular boundary values anywhere. Importantly though, we retain uniform and explicit control on $|tu_t|$ in our construction and hence on the mean curvature of $\text{graph}(u_t) \subset M^n \times \mathbb{R}$, so that we are able to pass these hypersurfaces to a subsequential limit in the class of C -almost minimizing boundaries. This also means that we can dispense with the curvature estimates used in [SY81] and [AM07] which are limited to low dimensions.

The original proof of Theorem 3.1 in [AM07] approaches the construction of 'solutions' u_t of the approximate Jang's equation by reduction to a special case. The authors first bend Ω along its boundary towards its 'lightcone' in the Lorentzian manifold $(M^n \times (-\epsilon, \epsilon), -dt^2 + g + tp)$ (where $\epsilon > 0$ is small), carefully, so that the altered data has everywhere positive mean curvature $\tilde{H}_{\partial\Omega} > \delta$, and so that (after a further modification through a cut-off) \tilde{p} vanishes near the boundary. After this change of the boundary geometry and data, the regularized Jang's equations coincide with capillary surface equations in a neighborhood of $\partial\Omega$. At

this point the authors can use standard, two-sided boundary barriers for boundary values $\pm \frac{\delta}{2t}$, arising as in Theorem 14.9 in [GT98] from linear inward perturbations of the cylinder $\partial\Omega \times \mathbb{R}$ above and below the boundary values, to obtain the a priori estimates for solving the relevant Dirichlet problems classically. (The same linear barriers apply under one-sided trapping assumptions in the general case, and we will use them in Lemma 3.3.) The authors then apply the maximum principle to argue that the marginally outer trapped surface they construct from this modified data actually lies in the unchanged part of Ω , and hence is a solution to the original problem.

Our construction of appropriately divergent solutions u_t of the regularized Jang's equation will occupy the rest of this section and will at the same time set the stage for the more delicate existence results of Section 4. To set up the appropriate definition of Perron sub and super solutions, we fix a constant $C > n|p|_{\mathcal{C}(\bar{\Omega})}$ and let $r_D : \Omega \rightarrow \mathbb{R}^+$ be the function from Corollary 2.1. The subscript D here will remind us that the Dirichlet problem $L_t u_t = 0$ on $B(x, r)$ for the regularized Jang's equation can be solved for arbitrary continuous boundary data φ on $\partial B(x, r)$ with $|\varphi| \leq \frac{2C}{t}$, for any $x \in \Omega$ and $r \in (0, r_D(x))$. For convenience we will adjust the definition of r_D slightly just before the statement of Lemma 3.3. With this preparation, the definition of Perron sub and super solutions and their elementary properties in the next few lemmas are standard. We refer to §2.8 in [GT98] for the classical case of harmonic functions, and to [JS66], [JS68], [Se70], [Sp72], [HRS08] for variants of the Perron method in conjunction with Dirichlet problems for constant mean curvature graphs.

Definition 3.1. A Perron sub solution of L_t on Ω is a function $\underline{u} \in \mathcal{C}(\bar{\Omega})$ with $|\underline{u}| \leq \frac{C}{t}$ and the following property: if $x \in \Omega$, $r \in (0, r_D(x))$ and $u \in \mathcal{C}(\bar{B}(x, r)) \cap \mathcal{C}^{2,\mu}(B(x, r))$ is the unique solution of the Dirichlet problem

$$(8) \quad \begin{aligned} L_t u &= 0 && \text{on } B(x, r) \\ u &= \underline{u} && \text{on } \partial B(x, r) \end{aligned}$$

whose existence is guaranteed by Theorem 2.2, then $u \geq \underline{u}$ on $\bar{B}(x, r)$. A function $\bar{u} \in \mathcal{C}(\bar{\Omega})$ with $|\bar{u}| \leq \frac{C}{t}$ is a Perron super solution if for every $x \in \Omega$ and every $r \in (0, r_D(x))$ the unique solution u of the Dirichlet problem

$$(9) \quad \begin{aligned} L_t u &= 0 && \text{on } B(x, r) \\ u &= \bar{u} && \text{on } \partial B(x, r) \end{aligned}$$

lies below \bar{u} on $B(x, r)$. Observe that by the maximum principle and the choice of $C \geq n|p|_{C(\bar{\Omega})}$, the constant functions $-\frac{C}{t}$ and $\frac{C}{t}$ are, respectively, Perron sub and super solutions of L_t on Ω .

Definition 3.2 (L_t lift of a Perron sub solution, cf. §2.8 in [GT98]). Let \underline{u} be a Perron sub solution of L_t on Ω , and fix $x \in \Omega$ and $r \in (0, r_D(x))$. Let $u \in \mathcal{C}(\bar{B}(x, r)) \cap C^{2,\mu}(B(x, r))$ be the unique solution of $L_t u = 0$ on $B(x, r)$ with $u = \underline{u}$ on $\partial B(x, r)$. The function \hat{u} defined by

$$\hat{u} := \begin{cases} u & \text{on } B(x, r) \\ \underline{u} & \text{on } \bar{\Omega} \setminus B(x, r) \end{cases}$$

is called the L_t lift of \underline{u} with respect to $B(x, r)$.

Definition 3.3. Let \bar{u}_t be a Perron super solution of L_t on Ω . We denote by $\mathcal{S}_{\bar{u}_t} := \{\underline{u} \in \mathcal{C}(\bar{\Omega}) : \underline{u} \text{ is a sub solution of } L_t \text{ on } \Omega \text{ with } \underline{u} \leq \bar{u}_t\}$ the class of all Perron sub solutions of L_t lying below \bar{u}_t .

Lemma 3.1 (Basic properties of Perron sub solutions, cf. §2.8 in [GT98]). Let \bar{u}_t be a Perron super solution of L_t on Ω . We have the following two basic properties of the class $\mathcal{S}_{\bar{u}_t}$:

- 1) If $\underline{u}, \underline{v} \in \mathcal{S}_{\bar{u}_t}$, then $\max\{\underline{u}, \underline{v}\} \in \mathcal{S}_{\bar{u}_t}$.
- 2) If $\underline{u} \in \mathcal{S}_{\bar{u}_t}$, $x \in \Omega$, $r \in (0, r_D(x))$ and \hat{u} is the L_t lift of \underline{u} with respect to $B(x, r)$, then $\hat{u} \in \mathcal{S}_{\bar{u}_t}$.

Proof. If $t > 0$, U is a smooth bounded domain, and if $f, g \in C^2(U) \cap C(\bar{U})$ satisfy $L_t f \leq L_t g$ and $f \geq g$ on ∂U , then $f \geq g$ on \bar{U} , by the maximum principle. Both properties are immediate consequences of this. q.e.d.

Definition 3.4 (cf. §2.8 in [GT98]). Let \bar{u}_t be a Perron super solution of L_t on Ω such that $\mathcal{S}_{\bar{u}_t} \neq \emptyset$. Define the Perron solution u_t^P of L_t on Ω with respect to \bar{u}_t pointwise for $x \in \Omega$ by $u_t^P(x) := \sup\{\underline{u}(x) : \underline{u} \in \mathcal{S}_{\bar{u}_t}\}$.

The interior gradient estimates from Section 2 and the resulting compactness of bounded solutions (cf. [Se70] and Corollary 16.7 in [GT98]) now imply the interior regularity of the Perron solution in a standard way:

Lemma 3.2 (cf. §2.8 in [GT98] and [Se70]). Let u_t^P be the Perron solution constructed under the assumptions of Definition 3.4. Then $u_t^P \in C_{loc}^{2,\mu}(\Omega)$ and $L_t u_t^P = 0$ holds classically.

Proof. We will make repeated use of the properties of $\mathcal{S}_{\bar{u}_t}$ stated in Lemma 3.1. Fix $x \in \Omega$, $r \in (0, r_D(x))$, and let $\underline{u}_i \in \mathcal{S}_{\bar{u}_t}$ be a sequence of sub solutions such that $\lim_{i \rightarrow \infty} \underline{u}_i(x) = u_t^P(x)$. By Lemma 3.1 we may assume that \underline{u}_i are pointwise non-decreasing on Ω and that they solve $L_t \underline{u}_i = 0$ classically on $B(x, r)$. Since $|\underline{u}_i| \leq \frac{C}{t}$ on Ω we can use the

interior gradient estimate in Lemma 2.1 together with Hölder estimates for the gradient (§13 in [GT98]) and Schauder estimates to show that on $B(x, r)$ the limit $\lim_{i \rightarrow \infty} \underline{u}_i(y) =: \tilde{u}_t^P(y)$ exists in $\mathcal{C}_{\text{loc}}^{2,\mu}$ and that $L_t \tilde{u}_t^P = 0$ there. By our choices and the definition of the Perron solution u_t^P we also see that $\tilde{u}_t^P(y) \leq u_t^P(y)$ for all $y \in B(x, r)$ with equality at x . If for some $y \in B(x, r)$ we had $\tilde{u}_t^P(y) < u_t^P(y)$ there would exist a pointwise non-decreasing sequence of functions $\underline{v}_i \in \mathcal{S}_{\tilde{u}_t}$ with $\underline{v}_i \geq \underline{u}_i$ on Ω such that $L_t \underline{v}_i = 0$ on $B(x, r)$ and with $\lim_{i \rightarrow \infty} \underline{v}_i(y) = u_t^P(y) > \tilde{u}_t^P(y)$. Applying the same reasoning as above we could then pass \underline{v}_i on $B(x, r)$ to a $\mathcal{C}_{\text{loc}}^{2,\mu}$ limit v with $L_t v = 0$ and $v \geq \tilde{u}_t^P$ with equality at x and strict inequality at y . Since $v - \tilde{u}_t^P \geq 0$ solves a linear elliptic equation on $B(x, r)$ this is in contradiction with the strong maximum principle. Hence $\tilde{u}_t^P = u_t^P$ on $B(x, r)$ so that $u_t^P \in \mathcal{C}_{\text{loc}}^{2,\mu}$ is a classical solution on Ω , as asserted. q.e.d.

Recall that we chose $C > n|p|_{\mathcal{C}(\bar{\Omega})}$. We now fix constants $\chi \in (0, C)$ and $\delta \in (0, \frac{1}{5} \text{dist}(\partial_1 \Omega, \partial_2 \Omega))$ so that the distance surfaces $\partial_{1,\gamma} \Omega := \{x \in \Omega : \text{dist}(x, \partial_1 \Omega) = \gamma\}$ and analogously $\partial_{2,\gamma} \Omega$ are smooth, disjoint, and embedded for all $\gamma \in [0, 2\delta]$, and so that $H_{\partial_{1,\gamma} \Omega} + \text{tr}_{\partial_{1,\gamma} \Omega}(p) \geq 2\chi$ and $H_{\partial_{2,\gamma} \Omega} - \text{tr}_{\partial_{2,\gamma} \Omega}(p) \geq 2\chi$. The methodology of J. Serrin [Se69] applies here and relates the trapping assumptions on the boundary to the existence of sub and super solutions for the operator L_t in a natural and geometric way. In particular, the proof of Theorem 14.9 in [GT98] (or the computation in §5 of [Y01]) shows that $(H + \text{tr}(p))(-k \text{dist}_{\partial_1 \Omega}(x)) \geq \chi$ on $\Omega' := \{x \in \Omega : \text{dist}(x, \partial_1 \Omega) \leq 2\delta\}$ provided k is sufficiently large. By translation invariance it follows that the function $\underline{u}'_t(x) := \frac{\chi}{t} - k \text{dist}_{\partial_1 \Omega}(x)$ with $k := \frac{\chi + C}{\delta t}$ satisfies $L_t \underline{u}'_t \geq 0$ on Ω' provided $t > 0$ is sufficiently small. As in [AM07] we choose the boundary value of \underline{u}'_t on $\partial_1 \Omega$ essentially as large as condition (14.60) in [GT98] warrants, so as to achieve a blow-up as $t \searrow 0$. Geometrically, the graph of \underline{u}'_t is a linear inward perturbation of the boundary cylinder $\partial_1 \Omega \times \mathbb{R}$ below height $\frac{\chi}{t}$. We briefly pursue this geometric point of view to elucidate and justify the choice of \underline{u}'_t here:

First, our choice of the outward unit normal for the computation of the mean curvature of $\partial_1 \Omega \times \mathbb{R}$ corresponds to the downward unit normal of the graph of \underline{u}'_t . If $\gamma \in [0, 2\delta]$ and if $N^n = \partial_{1,\gamma} \Omega \times \mathbb{R}$, then $H_N + \text{tr}_N(p) - tx_{n+1}$, as a function on N^n , is $\geq \chi$ on the part of N^n that lies below $\{x_{n+1} = \frac{\chi}{t}\}$. More generally, consider the local geometric operator $\mathcal{L}_t : N^n \rightarrow H_N + \text{tr}_N(p) - tx_{n+1}$ which takes an oriented hypersurface N^n to a scalar functions on N^n . If \tilde{N}^n is a normal graph above some hypersurface N^n with defining function ϕ , and if we identify functions on N^n and \tilde{N}^n via this parametrization, then $|\mathcal{L}_t N - \mathcal{L}_t \tilde{N}| \leq c(\{\text{spt}(\phi) \subset N\})|\phi|_{\mathcal{C}^2(N)}$. Now $\mathcal{L}_t(\text{graph}(\underline{u}'_t, \Omega'))(x, \underline{u}'_t(x)) = (L_t \underline{u}'_t)(x)$

at every point $x \in \Omega'$. Note that if $\text{dist}(x, \partial_1\Omega) = \gamma$ and if $t > 0$ is sufficiently small, then $\text{graph}(\underline{u}'_t, \Omega')$ can be expressed as a normal graph over the cylinder $\partial_{1,\gamma}\Omega \times \mathbb{R}$ on a ball of radius 1 with center at $(x, \underline{u}'_t(x))$ in $M^n \times \mathbb{R}$, and that the \mathcal{C}^2 -norm of the defining function is on the order of t . Since $\text{graph}(\underline{u}'_t, \Omega')$ lies below $\{x_{n+1} = \frac{\chi}{t}\}$, it follows that if $t > 0$ is sufficiently small then certainly $L_t \underline{u}'_t(x) \geq 0$, as needed.

Finally, we let $\underline{u}_t := \min\{\underline{u}'_t, -\frac{C}{t}\}$ on Ω' . Note that this extends to a continuous function on all of Ω with constant value $-\frac{C}{t}$ away from the boundary. At this point, it is convenient to re-define $r_D(x)$ from Corollary 2.1 slightly as $\min\{r_D(x), \delta\}$. To see that \underline{u}_t is a Perron sub solution, note that the condition in Definition 3.1 only needs to be verified on small balls $B(x, r)$ where $r \in (0, r_D(x))$. It follows that on any such ball $B(x, r)$, either $\underline{u}_t \equiv -\frac{C}{t}$ or else $B(x, r) \subset \Omega'$. From this it follows as in Lemma 3.1 that \underline{u}_t is a Perron sub solution. The argument for the construction of the super solution \bar{u}_t is completely analogous. In conclusion we have the following lemma, which provides divergent one-sided Perron sub and super solutions from one-sided trapping assumptions on the boundary (cf. the proofs of Theorem 14.9 in [GT98] and of Proposition 3.5 and Lemma 3.7 in [AM07]).

Lemma 3.3 (Existence of special Perron sub and super solutions). *For all $t > 0$ sufficiently small the following $\mathcal{C}(\bar{\Omega})$ functions*

$$\underline{u}_t(x) := \begin{cases} \frac{\chi}{t} - \frac{\chi+C}{t\delta} \text{dist}_{\partial\Omega}(x) & \text{if } \text{dist}(\partial_1\Omega, x) \leq \delta \\ -\frac{C}{t} & \text{if } \text{dist}(\partial_1\Omega, x) > \delta \end{cases}$$

and

$$\bar{u}_t(x) := \begin{cases} -\frac{\chi}{t} + \frac{\chi+C}{t\delta} \text{dist}_{\partial\Omega}(x) & \text{if } \text{dist}(\partial_2\Omega, x) \leq \delta \\ +\frac{C}{t} & \text{if } \text{dist}(\partial_2\Omega, x) > \delta \end{cases}$$

are, respectively, Perron sub and super solutions of L_t on Ω . We have that $\underline{u}_t < \bar{u}_t$ on Ω and that $\underline{u}_t \geq \frac{\chi}{2t}$ on the collar of width $\frac{\chi\delta}{2(\chi+C)}$ about $\partial_1\Omega$ and that $\bar{u}_t \leq -\frac{\chi}{2t}$ on the collar of width $\frac{\chi\delta}{2(\chi+C)}$ about $\partial_2\Omega$.

We now finish the proof of Theorem 3.1. For all $t > 0$ small enough for Lemma 3.3 to apply, we let $u_t^P \in \mathcal{C}_{\text{loc}}^{2,\mu}(\Omega)$ be the Perron solution $L_t u_t^P = 0$ from Lemma 3.2 for the (non-empty) class $\mathcal{S}_{\bar{u}_t}$. The relative boundary of the region $\{(x, x_{n+1}) : x_{n+1} > u_t(x)\}$ in $\Omega \times \mathbb{R}$ is the graph $G_t := \text{graph}(u_t^P, \Omega) \subset \Omega \times \mathbb{R}$ whose mean curvature is clearly bounded by $2C$. Restricting to the open region $U = \{x \in \Omega : \text{dist}(x, \partial\Omega) > \frac{\chi\delta}{3(\chi+C)}\} \times \mathbb{R}$, we can use the compactness and regularity theory discussed in Appendix A to show that in dimensions $2 \leq n \leq 6$, the graphs G_t pass to a smooth subsequential limit G in the class \mathcal{F}_{2C} as $t \searrow 0$, and that this limit G has distance at least $\frac{\chi\delta}{2(\chi+C)}$ from $\partial\Omega \times \mathbb{R}$. We explain in

Remark 4.1 why we get smooth convergence also if $n = 7$. If $n \geq 8$, this convergence is in the sense of Lemma A.2 (i.e. current *and* varifold convergence) and $\dim \text{sing } G \leq n - 8$. The limit G is $2C$ -almost minimizing. Note that G is non-empty: the mean-value theorem and the monotonicity formula show that G must have non-empty intersection with every horizontal plane. The remainder of the blow-up analysis is now identical to Proposition 4 in [SY81]: if G_0 is a connected component of the regular set of G , then there is a canonical choice of orientation on G_0 (the ‘downwards’ orientation that G_0 inherits from being a geometric limit of graphs; note that Allard’s theorem applies to ensure smooth convergence towards G_0) so that $H_{G_0} + \text{tr}_{G_0}(p) = 0$ holds. This holds distributionally on all of G because the singular set of G is small. By the Harnack principle for limits of graphs in Lemma 2.3, each G_0 is either cylindrical or a graph of a smooth function $u : \Omega_0 \rightarrow \mathbb{R}$ defined on some open subset $\Omega_0 \subset \Omega$ where u solves Jang’s equation $(H + \text{tr}(p))u = 0$. The same discussion applies to any (necessarily non-vanishing) subsequential limit in \mathcal{F}_{2C} obtained from G by a divergent sequence of downward translations. Such a limit is bound to be a marginally outer trapped cylinder $\Sigma^{n-1} \times \mathbb{R}$ where Σ^{n-1} is a relative boundary in Ω homologous to $\partial_1 \Omega$. By Lemma A.1 the cross-section Σ^{n-1} is a $2C$ -almost minimizing boundary, and clearly it is itself marginally outer trapped.

Finally, the statement about the Yamabe type of $\Sigma^{n-1} \subset \Omega$ in dimensions $3 \leq n \leq 7$ follows, exactly as in [SY81], from the inequality

$$\begin{aligned} 0 \leq & \bar{R} - \sum_{i,j=1}^n (h_{ij} + p_{ij})^2 - 2 \sum_{i=1}^n (h_{in+1} + p_{in+1})^2 \\ & + 2 \sum_{i=1}^n \bar{D}_i (h_{in+1} + p_{in+1}) + \left(\sum_{i=1}^n p_{ii} \right)^2 - H^2 \\ & + 2 \left(\sum_{i=1}^n p_{ii} + H \right) p_{n+1n+1} - 2e_{n+1} \left(\sum_{i=1}^n p_{ii} + H \right) \end{aligned}$$

(derived as (2.15) in [SY81]) which is a consequence of the Jacobi equation (5), the Codazzi and Gauss equations, and the dominant energy condition. The indices $\{i, j\}$ here are with respect to a local orthonormal frame $\{e_1, \dots, e_{n+1}\}$ for $\Omega \times \mathbb{R}$ which is parallel in the vertical direction and such that e_{n+1} restricts to the downward pointing unit normal field on G_t . The function H on G_t is also extended vertically here; \bar{R} and \bar{D} are used to denote the scalar curvature and covariant differentiation on G_t (making the third term on the right the divergence of the tangential vector field whose length is computed in the second term), h_{ij} is the second fundamental form of G_t , and $h_{in+1} = -\bar{D}_i \log \sqrt{1 + |Du_t|^2}$. We point out that it is important here

that $e_{n+1}(\sum_i p_{ii} + H) = e_{n+1}(tu_t) = \frac{t|Du_t|^2}{\sqrt{1+|Du_t|^2}}$ enters the inequality with a favorable sign.

Remark 3.2. In the smooth case $2 \leq n \leq 7$, the marginally trapped cylinder $\Sigma^{n-1} \times \mathbb{R}$, obtained above as a limit of graphs of solutions u_{t_i} of the regularized Jang’s equations with $t_i|u_{t_i}| \leq C$ followed by a sequence of divergent downward translations, is always $n|p|_{\mathcal{C}(\bar{\Omega})}$ -almost minimizing. To see this, consider the relatively open sets $\Omega_+, \Omega_-, \Omega_0$ where, respectively, the u_{t_i} either diverge to $+\infty$, to $-\infty$, or converge. By the analysis in Proposition 4 in [SY81], the whole domain $\bar{\Omega}$ is the union of the closures of these sets. Recall that $H(u_{t_i})$ is the divergence of the unit normal vector field of $\text{graph}(u_{t_i})$ that leads to the almost minimizing property in Example A.1. If $\Omega'_+ \subset\subset \Omega_+$ then $\liminf_{i \rightarrow \infty} \inf_{x \in \Omega'_+} H(u_{t_i})(x) \geq -n|p|_{\mathcal{C}(\bar{\Omega})}$, and similar statements hold for the other regions. A careful analysis of signs in Example A.1 then establishes the asserted $n|p|_{\mathcal{C}(\bar{\Omega})}$ -almost minimizing property of $\Sigma^{n-1} \subset (\partial\Omega_+ \cup \partial\Omega_- \cup \partial\Omega_0) \cap \Omega$.

4. The Plateau problem for marginally outer trapped surfaces

In this section we establish the existence of marginally outer trapped surfaces spanning a given boundary (Theorem 1.1). For the duration of the proof we fix a constant $C > n|p|_{\mathcal{C}(\bar{\Omega})}$. Let dist_Γ measure oriented geodesic distance in $\partial\Omega$ to Γ^{n-2} (say positive on $\partial_1\Omega$). Let $\delta > 0$ and $\chi \in (0, C)$ be positive constants such that dist_Γ is smooth on $\{x \in \partial\Omega : -2\delta < \text{dist}_\Gamma(x) < 2\delta\}$ and such that

$$(10) \quad \begin{aligned} H_{\partial\Omega} + \text{tr}_{\partial\Omega} p &\geq 2\chi && \text{on } \partial_1\Omega \cup \{x \in \partial\Omega : -2\delta < \text{dist}_\Gamma(x) < 2\delta\}, \\ H_{\partial\Omega} - \text{tr}_{\partial\Omega} p &\geq 2\chi && \text{on } \partial_2\Omega \cup \{x \in \partial\Omega : -2\delta < \text{dist}_\Gamma(x) < 2\delta\}. \end{aligned}$$

Lemma 4.1. *For every $t \in (0, 1)$ there exists a Perron sub solution $\underline{u}_t \in \mathcal{C}(\bar{\Omega})$ of L_t on Ω (in the sense of Definition 3.1) such that for $x \in \partial\Omega$ we have*

$$\underline{u}_t(x) = \text{smooth version of } \begin{cases} -\frac{C}{t} & \text{dist}_\Gamma(x) < -\delta t \\ \frac{C}{\delta t^2} \text{dist}_\Gamma(x) & \text{if } -\delta t < \text{dist}_\Gamma(x) < \frac{\chi\delta t}{C} \\ \frac{\chi}{t} & \frac{\chi\delta t}{C} < \text{dist}_\Gamma(x). \end{cases}$$

Analogously there exists a Perron super solution $\bar{u}_t \in \mathcal{C}(\bar{\Omega})$ with

$$\bar{u}_t(x) = \text{smooth version of } \begin{cases} -\frac{\chi}{t} & \text{dist}_\Gamma(x) < -\frac{\chi\delta t}{C} \\ \frac{C}{\delta t^2} \text{dist}_\Gamma(x) & \text{if } -\frac{\chi\delta t}{C} < \text{dist}_\Gamma(x) < \delta t \\ \frac{C}{t} & \delta t < \text{dist}_\Gamma(x). \end{cases}$$

We can arrange so that $-\frac{C}{t} \leq \underline{u}_t \leq \bar{u}_t \leq \frac{C}{t}$ on $\bar{\Omega}$.

Proof. The sub solution \underline{u}_t can be obtained in a standard way [GT98] from linear inward perturbation of $\partial_1\Omega \times \mathbb{R}$ beneath the required boundary values. We argue this geometrically here. First, note that from the trapping assumptions we know that $\mathcal{L}_t(\partial\Omega \times \mathbb{R}) \geq \chi$ holds on $(U \cap \bar{\Omega}) \times (-\infty, \frac{\chi}{t})$, where U is an open neighborhood of $\partial_1\Omega \cup \{x \in \partial\Omega : -\delta < \text{dist}_\Gamma(x) < \delta\}$ in M^n . \mathcal{L}_t is the geometric regularized Jang’s operator that was introduced in the proof of Lemma 3.3. Let $h_{\partial\Omega} : \partial\Omega \rightarrow \mathbb{R}$ denote the intended boundary values of the sought-after sub solution \underline{u}_t . Extend the inward pointing unit normal $\vec{\nu}(x)$ of $\partial\Omega$ to a normal vector field of $\partial\Omega \times \mathbb{R}$ by vertical translation. For large constants $k \gg 1$ consider the function $d : \partial\Omega \times \mathbb{R} \rightarrow \mathbb{R}$ defined by $d(x, x_{n+1}) = \frac{1}{k}(h_{\partial\Omega}(x) - x_{n+1})$. For k sufficiently large (depending on $t > 0$) the normal graph $N^n := \{\exp_{(x, x_{n+1})}(d(x, x_{n+1})\vec{\nu}(x)) : (x, x_{n+1}) \in \partial\Omega \times (-\frac{C+1}{t}, \frac{\chi}{t})\} \cap ((U \cap \bar{\Omega}) \times \mathbb{R})$ coincides with the vertical graph of a function \underline{u}'_t that is defined on a subset $U' \subset U \cap \bar{\Omega}$, because d is monotone in x_{n+1} . Since $|d|_{C^2} = O(\frac{1}{k})$, it follows that $\mathcal{L}_t(N^n) = H_N + \text{tr}_N(p) - tx_{n+1} \geq 0$ on $U' \times \mathbb{R}$ if k is sufficiently large (again depending on $t > 0$). Hence $L_t(\underline{u}'_t) \geq 0$ on U' . By increasing k further if necessary we can arrange for $\underline{u}_t := \max(-\frac{C}{t}, \underline{u}'_t)$ to extend to a continuous function on all of $\bar{\Omega}$. This will be the required sub solution. The construction of the super solution is identical. q.e.d.

The sub and super solutions of the preceding lemma are not optimal for our purposes away from Γ^{n-2} in that they wouldn’t prevent the graphs of the corresponding Perron solutions u_t^P from converging towards $(\partial\Omega \setminus \Gamma^{n-2}) \times \mathbb{R}$ at fixed bounded heights as $t \searrow 0$. In order to get this shielding effect from the initial barriers we could improve the construction in Lemma 4.1 by allowing the inward slope (respectively the normal slope k of the perturbation) of \bar{u}_t and \underline{u}_t to vary as a function of $\text{dist}_\Gamma(\cdot)$. Alternatively, one can construct for every $x \in \partial_1\Omega$ a local sub solution whose graph is a cone with vertex at $(x, \frac{\chi}{t})$ and base a small inward perturbation (depending on $\text{dist}_\Gamma(x)$ but not on $t > 0$) of $\partial\Omega \times \{-\frac{C}{t}\}$ near $(x, -\frac{C}{t})$, continued by the horizontal plane at height $-\frac{C}{t}$ to all of Ω . Local super solutions can be constructed analogously. Either way we conclude the following property of the Perron solutions u_t^P corresponding to the class $\mathcal{S}_{\bar{u}_t}$ (but cf. Remark 4.2).

Lemma 4.2. *For every $x \in \partial_1\Omega$ there exists $r(x) > 0$ such that for all sufficiently small $t > 0$, $(\Omega \cap B(x, r)) \times (-\infty, \frac{\chi}{2t})$ lies below the graph of the Perron solution u_t^P corresponding to the class $\mathcal{S}_{\bar{u}_t}$, where \bar{u}_t is as in Lemma 4.1. Similarly, for every $x \in \partial_2\Omega$ there exists $r = r(x) > 0$ such that the half-infinite cylinder $(\Omega \cap B(x, r)) \times (-\frac{\chi}{2t}, \infty)$ lies above this graph for all $t > 0$ sufficiently small.*

Note that the Perron sub and super solutions described in Lemma 4.1 match up along $B_t := \{(x, \frac{C}{\delta t^2} \text{dist}_\Gamma(x)) : x \in \partial\Omega \text{ and } -\frac{\chi\delta t}{2C} \leq \text{dist}_\Gamma(x) \leq \frac{\chi\delta t}{2C}\}$. It follows that the functions u_t^P extend continuously from Ω to $\Omega \cup \{x \in \partial\Omega : -\frac{\chi\delta t}{2C} \leq \text{dist}_\Gamma(x) \leq \frac{\chi\delta t}{2C}\}$. Let $G_t := \{(x, u_t^P(x)) : x \in \Omega\}$ denote the graph of the Perron solution u_t^P and observe that its mean curvature is pointwise bounded by $t|u_t^P| + |\text{tr}(p)(u_t^P)| \leq 2C$. It follows that $G_t \in \mathcal{F}_{2C}$ on the open cylinder $\Omega \times \mathbb{R}$. From Example A.1 in Appendix A we obtain bounds for the \mathcal{H}^n -measure of G_t . It follows readily that the G_t are integer rectifiable n -varifolds in $M^n \times \mathbb{R}$. We summarize their basic distributional properties in the next lemma.

Lemma 4.3. *Let u_t^P be the Perron solution for L_t on Ω constructed from the class $\mathcal{S}_{\bar{u}_t}$ where \bar{u}_t is as in Lemma 4.1, and let $G_t := \{(x, u_t^P(x)) : x \in \Omega\}$ denote its graph. Then G_t is an n -dimensional integer multiplicity varifold in $M^n \times \mathbb{R}$. In the open cylinder $\Omega \times \mathbb{R}$, G_t is a $\mathcal{C}_{loc}^{2,\mu}$ -graph with mean curvature uniformly bounded by $2C$. We have locally uniform mass bounds $\sup_{t \in (0,1)} \|G_t\|(W) \leq C(W) < \infty$ for every precompact set $W \subset M^n \times (-\frac{\chi}{2t}, \frac{\chi}{2t})$. Denoting $B_t := \{(x, \frac{C}{\delta t^2} \text{dist}_\Gamma(x)) : x \in \partial\Omega \text{ and } -\frac{\chi\delta t}{2C} \leq \text{dist}_\Gamma(x) \leq \frac{\chi\delta t}{2C}\}$ we have that $\|G_t\|(B_t) = 0$, $B_t \subset \text{spt}(G_t)$, and $\text{spt}(G_t) \setminus B_t$ is relatively closed in $(M^n \times (-\frac{\chi}{2t}, \frac{\chi}{2t})) \setminus B_t$.*

The regularity of G_t up to and including B_t is immediate from Allard's boundary regularity theorem [All75] once we establish that, as a varifold, G_t has density $\frac{1}{2}$ along B_t . This is an elementary consequence of the fact that G_t is a graph in $\Omega \times \mathbb{R}$, and that B_t is never vertical for $t > 0$. Since we are interested in the limit as $t \searrow 0$ we will supply a second, more portable argument to get boundary density $\frac{1}{2}$ below. We mention the abstract boundary regularity theory for almost minimizing currents in [DS93b] where some of the standard arguments below are discussed in great generality. In our concrete context we can argue directly following Lemma 5.2 in the paper [All75], whose notation we use and which all references in the proof of the following lemma are to. For ease of notation, we will assume that $(M^n, g) = (\mathbb{R}^n, \delta)$. The author is grateful to Theodora Bourne for helping with some of the statements in [All75]. Her recent work [B09] is relevant for relaxing the regularity of the boundary Γ^{n-2} needed in the proof.

Lemma 4.4 (Smoothness up to the boundary). *$G_t \cap (M^n \times (-\frac{\chi}{2t}, \frac{\chi}{2t}))$ is a smooth manifold with boundary B_t . For every precompact open set $W \subset M^n \times (-\frac{\chi}{2t}, \frac{\chi}{2t})$ we have that $\sup_{t \in (0,1)} \|G_t\|(W) + \|\delta G_t\|(W) \leq C(W) < \infty$.*

Proof. Note that the first variation measure δG_t of G_t is a Radon measure on the complement of B_t that is absolutely continuous with respect to $\|G_t\| = \mathcal{H}^n \llcorner G_t$ with density bounded by $2C$. Since $\|G_t\|(B_t) = 0$,

it follows from Allard's Lemma 3.1 that δG_t extends to a Radon measure on $\mathbb{R}^n \times (-\frac{\chi}{2t}, \frac{\chi}{2t})$ such that $(\delta G_t)_{\text{sing}} = \vec{\nu}_t d\|\delta G_t\|$, where $\vec{\nu}_t$ is a $\|\delta G_t\|$ -measurable \mathbb{R}^{n+1} -valued function supported on B_t and normal to B_t at $\|\delta G_t\|$ almost every point of B_t . By Allard's Theorem 3.5 the density function $\Theta^n(\|G_t\|, \cdot)$ is everywhere defined and is bounded below by $\frac{1}{2}$ at points in B_t . By Allard's integral compactness theorem the collection of varifold tangents at a boundary point $b \in B_t$ is non-empty and consists of integer multiplicity varifolds C supported in the closed halfspace associated to $\text{Tan}(\partial(\Omega \times \mathbb{R}), b)$ to the side of $\Omega \times \mathbb{R}$ with the following properties:

- 1.) $\frac{1}{2} \leq \Theta^n(G_t, b) = \Theta^n(\|C\|, 0) = \frac{\|C\|(\mathbb{B}(0,r))}{\omega_n r^n}$ for every $r > 0$
- 2.) $\|C\|(W^\perp) = 0$
- 3.) $\Theta^n(\|C\|, x) \geq 1$ for $\|C\|$ - a.e. $x \in \mathbb{R}^{n+1} \setminus W^\perp$
- 4.) $\|\delta C\|(\mathbb{R}^{n+1} \setminus W^\perp) = 0$ and δC extends to a Radon measure on \mathbb{R}^{n+1}
- 5.) $\delta C = \vec{\nu}_C d\|\delta C\|$ where $\vec{\nu}_C$ is $\|\delta C\|$ - a.e. perpendicular to W^\perp .

Here, W denotes the (2-dimensional) orthonormal complement of $\text{Tan}(B_t, b)$ in \mathbb{R}^{n+1} . Combining these properties with a standard monotonicity argument for varifolds of bounded first variation (as in §17 of [Si83]), it follows that any such C is invariant under homotheties and hence is indeed a tangent cone. In fact, by Allard's Lemma 5.1, the Constancy Theorem for stationary varifolds, and the fact that the support of C lies in a halfspace, it follows that any such tangent cone C must be a finite union of integer multiplicity halfplanes through W^\perp . Allard's Theorem implies boundary regularity if C consists of a single multiplicity one halfplane, or equivalently, if $\Theta^n(\|G_t\|, b) = \frac{1}{2}$. Note that by Lemma A.2 and the fact that C is a relative boundary in Ω , the sheets composing C all have multiplicity one. Away from W^\perp the halfplanes constituting C are a smooth limit of graphs of bounded mean curvature (by Allard's interior regularity theorem [Al172]). Since W^\perp is not vertical, this rules out the possibility of multiple sheets. A slightly more robust argument to argue that $\Theta^n(\|G_t\|, b) = \frac{1}{2}$, which also works when we analyze the boundary regularity in the limit as $t \searrow 0$, goes as follows: on compact subsets away from W^\perp , the tangent cone C is a smooth limit of graphs whose mean curvature tends to zero. By the mean value theorem, it follows that the sheets of C have to alternate in orientation (if we consider their trace in W) and that there must be an odd number of them. If there were three or more of them, then two consecutive oppositely oriented halfplanes would meet at an angle $< \pi$ in W^\perp . This would contradict the almost minimizing property of the approaching graphs (essentially by the triangle inequality and an argument as in Lemma A.1). Hence C consists of a single, multiplicity one halfplane, as required. The other statement in the lemma follows easily now. q.e.d.

Theorem 4.1. *The family $\{G_t \lfloor (M^n \times (-\frac{\chi}{2t}, \frac{\chi}{2t}))\}_{t \in (0,1)}$ is precompact in the class of integer multiplicity varifolds with locally uniformly bounded mass and first variation in $M^n \times \mathbb{R}$, and also in the class of $2C$ -almost minimizing boundaries in $\Omega \times \mathbb{R}$. In dimensions $2 \leq n \leq 7$ the possible limiting varifolds G as $t \searrow 0$ are smooth oriented hypersurfaces in $M^n \times \mathbb{R}$ with boundary $B := \Gamma^{n-2} \times \mathbb{R}$. If $n \geq 8$ then possible limits G are smooth near B and have closed singular set $\text{sing}(G) \subset \Omega$ of Hausdorff dimension $\leq n - 8$. Every connected component G_0 of the regular set of G satisfies the marginally outer trapped surface equation $H_{G_0} + \text{tr}_{G_0} p = 0$ for one of the two possible choices for the sign of the mean curvature of G_0 , and G_0 is either a vertical cylinder or entirely graphical. By passing to a subsequential limit of vertical translates of G one obtains a cylinder $\Sigma^{n-1} \times \mathbb{R}$ with all of the above properties. Its cross-section Σ^{n-1} is a solution of the Plateau problem for Γ^{n-2} in Ω .*

Proof. For the relevant compactness theorem see §42 in [Si83] or [All72]. On $\Omega \times \mathbb{R}$ the varifolds $G_t \lfloor (M^n \times (-\frac{\chi}{2t}, \frac{\chi}{2t}))$ satisfy the $2C$ -almost minimizing property. The interior regularity of a subsequential limit G follows from the discussion in Appendix A and Remark 4.1. The boundary regularity of G follows from the ‘alternative argument’ in the proof of Lemma 4.4. Lemma 4.2 shows that away from $\Gamma^{n-2} \times \mathbb{R}$ the limit G stays away from $\partial\Omega$. Every connected component G_0 of the regular set of G is a smooth limit of graphs whose defining functions u_t satisfy $(H + \text{tr}(p))u_t = tu_t$. The assertion about G_0 follows from this and the Harnack principle in Lemma 2.3. q.e.d.

Remark 4.1 (Better regularity for limits of graphs). The interior regularity in dimension $n = 7$ claimed in Theorem 1.1 is a consequence of the following well-known argument (see [BG72], [Si76b], [Si87]): the submanifolds we are considering here are the graphs G_t of (smooth) solutions u_t of the approximate Jang’s equation $(H + \text{tr}(p))u_t = tu_t$ and (varifold) limits thereof. From Section 2 we know that the functions $\frac{1}{v_t} = (1 + |Du_t|^2)^{-\frac{1}{2}} > 0$ satisfy a geometric differential inequality of the form $\Delta_{G_t} \frac{1}{v_t} - \frac{\beta}{v_t} \leq 0$, where β is a constant independent of $t > 0$. Observe that $\frac{1}{v_t}$ is just the vertical component of the upward pointing unit normal of G_t . Suppose now that $n = 7$, and that a limit G of G_t has interior singular points. The tangent cone analysis of Appendix A in [Si83] shows that we can then obtain an oriented tangent cone C of G that is area minimizing and has an isolated non-removable singular point at the origin. By the result of §2 in [BG72] we have that $\text{reg}(C) = C \setminus \{0\}$ is connected; by Allard’s theorem, it is a smooth limit of rescalings of the G_t . It hence makes sense to talk about the upward pointing unit normal of C , and we conclude that its vertical component is non-negative and superharmonic (the linear part scales away as we pass to the cone). Hence by the Hopf maximum principle, it is either

strictly positive or vanishes identically. In the former case, $C \setminus \{0\}$ is a minimal graph with an isolated singularity at the origin which would then be removable by a result of Finn's (see [F53] and also the remark in [Si76b] at the end of §1), while in the latter case, C is cylindrical and hence its singular set is a vertical line. In both cases we arrive at a contradiction to the assumption that C has a non-removable isolated singularity at the origin.

Remark 4.2. Using a simple modification of these arguments (involving an application of the half-space lemmas in 36.5 and 37.6 of [Si83] to establish regularity) we could have avoided the use of Lemma 4.2 here entirely, and concluded that $\partial\Omega \cap \text{spt } \Sigma^{n-1} = \Gamma^{n-2}$ a posteriori from the strong maximum principle.

Appendix A. Review of geometric measure theory

In this appendix we review several classical and well-known results from geometric measure theory that are used freely in this paper. The regularity theory for the classes \mathcal{F}_C of ' C -almost minimizing boundaries' is an immediate consequence of Allard's regularity theorem [All72] and dimension reduction as in §23 of [Si83]. For convenient reference we give an indication of the proofs here, following [Si83] closely. We confine the presentation to Euclidean space for simplicity. However, the results stated in this appendix carry over to general Riemannian manifolds and also localize, see Remark A.3.

The concept of C -almost minimizing boundaries below arises naturally in the context of this paper and is convenient and appropriate for our applications. Extensively studied and significantly more general notions include Almgren's (ϵ, δ) -minimal sets, see [Alm76], and Bombieri's (Ψ, ω, δ) -currents, see [Bo82], and allow a more general lower order term in (11) (typically of the form $r^{n+\alpha}$ where $r = \text{diam spt}(X)$). The papers [Ta82], [Ta84] develop the regularity theory for almost minimizing boundaries from De Giorgi's method. After this work was finished the author has learnt that the particular almost minimizing notion we used here has been investigated systematically as that of " λ -minimizing currents" in [DS93a]. We refer the reader to that paper for complete proofs and several more general results than those stated here, but we choose to keep the terminology ' C -almost minimizing' here to emphasize that these boundaries do not come from a variational principle in our work.

Definition A.1 (C -almost minimizing property, [DS93a]). A boundary $T = \partial E$ of a set $E \subset \mathbb{R}^{n+1}$ of locally finite perimeter is said to have the C -almost minimizing property if for every open $W \subset \subset \mathbb{R}^{n+1}$ and every integer multiplicity current $X \in \mathcal{D}_{n+1}(\mathbb{R}^{n+1})$ with support in W

we have that

$$(11) \quad M_W(T) \leq M_W(T + \partial X) + CM_W(X).$$

The collection of all such boundaries is denoted by \mathcal{F}_C .

Remark A.1. Let $T \in \mathcal{F}_C$, $W \subset\subset \mathbb{R}^{n+1}$ convex open, and let $Y \in \mathcal{D}_n(\mathbb{R}^{n+1})$ be integer multiplicity with $\partial Y = 0$ and $\text{spt}(Y) \subset W$. Then it follows from the above definition and the sharp isoperimetric inequality (see [Alm86]) that

$$M_W(T) \leq M_W(T + Y) + I_{n+1}CM_W(Y)^{\frac{n+1}{n}}$$

where I_{n+1} is the isoperimetric constant of \mathbb{R}^{n+1} . Hence the C -almost minimizing property is more stringent than the notion studied in [Ta82].

Remark A.2 (Bounded absolutely continuous mean curvature, cf. §2 in [DS93a]). Definition A.1 implies that the first variation δT corresponding to the varifold underlying $T \in \mathcal{F}_C$ is absolutely continuous with respect to the total variation measure μ_T associated with T , and $\delta T = \vec{H}_T d\mu_T$ for some \mathbb{R}^{n+1} -valued μ_T -measurable function \vec{H}_T that is pointwise bounded by the constant C . To see this, choose a variation vector field $X \in C_c^1(W, \mathbb{R}^{n+1})$ where $W \subset \mathbb{R}^{n+1}$ is open and bounded, and let $\phi : [0, 1] \times \mathbb{R}^{n+1} \rightarrow \mathbb{R}^{n+1}$ denote the flow generated by X . Let $U \subset W$ be an open set containing the support of X such that $T|_U$ is a regular slice. Using the homotopy formula (see [Si83], page 139) it follows that for t small $\phi_{\#}^t(T) - \phi_{\#}^0(T) = \phi_{\#}^t(T) - T = \partial\phi_{\#}([0, t] \times T) = \partial\phi_{\#}([0, t] \times T|_U)$ and a computation as in 26.23 in [Si83] shows that $\limsup_{t \rightarrow 0} t^{-1}M_W(\phi_{\#}([0, t] \times T|_U)) \leq M_W(T) \sup |X|$. Together with the C -almost minimizing property, the claim follows.

The standard calibration argument for graphs of bounded mean curvature in the following example was used in Section 3 of [SY81] to derive local volume bounds for graphs of approximate solutions to Jang's equation by comparison with extrinsic balls.

Example A.1 (Graphs of bounded mean curvature). Let $u : \mathbb{R}^n \rightarrow \mathbb{R}$ be a C^2 -function with mean curvature $|\mathbb{H}_{\text{graph}(u)}(\mathbf{x}, u(\mathbf{x}))| \leq C$ for every $\mathbf{x} = (x_1, \dots, x_n) \in \mathbb{R}^n$. Then $T := \partial\{(\mathbf{x}, x_{n+1}) : x_{n+1} \geq u(\mathbf{x})\}$ (= $\text{graph}(u)$) has the C -almost minimizing property. To see this, let $W \subset\subset \mathbb{R}^{n+1}$ open and $X \in \mathcal{D}_{n+1}(\mathbb{R}^{n+1})$ with $\text{spt}(X) \subset W$ as in Definition A.1. Denote by $\vec{\nu} := (1 + |Du|^2)^{-\frac{1}{2}}(Du, -1)$ the downward pointing unit normal of $\text{graph}(u)$ at $(\mathbf{x}, u(\mathbf{x}))$ thought of as a vector field on all of \mathbb{R}^{n+1} (parallel in the vertical direction). Observe that $(\text{div}_{\mathbb{R}^{n+1}} \vec{\nu})(\mathbf{x}, x_{n+1}) = \mathbb{H}_{\text{graph}(u)}(\mathbf{x}, u(\mathbf{x}))$. Let $\sigma = dx_1 \wedge \dots \wedge dx_{n+1}|_{\vec{\nu}}$ denote the area form of T and note that $(d\sigma)(\mathbf{x}, x_{n+1}) = \mathbb{H}_{\text{graph}(u)}(\mathbf{x}, u(\mathbf{x}))dx_1 \wedge \dots \wedge dx_{n+1}$.

Then

$$\begin{aligned}
 M_W(T + \partial X) &= \sup_{\omega \in \mathcal{D}^n(W), |\omega| \leq 1} (T + \partial X)\omega \\
 &\geq \sup_{\phi \in \mathcal{D}(W, X), |\phi| \leq 1} (T + \partial X)(\phi\sigma) \\
 &\geq \sup_{\phi \in \mathcal{D}(W, X), |\phi| \leq 1} T(\phi\sigma) - \sup_{\phi \in \mathcal{D}(W, X), |\phi| \leq 1} \partial X(\phi\sigma) \\
 &= M_W(T) - |X(d\sigma)| \\
 &\geq M_W(T) - CM_W(X).
 \end{aligned}$$

In this computation, we use $\mathcal{D}(W, X)$ to denote the collection of all smooth functions ϕ on \mathbb{R}^{n+1} with support in W which are identically equal to one in a neighbourhood of the support of X . We see that $T \in \mathcal{F}_C$, as asserted.

The following elementary consequence of Definition A.1 is needed in the paper:

Lemma A.1. *Suppose that $T = \partial E$ is C -almost minimizing in \mathbb{R}^{n+1} , and suppose that $E = E_0 \times \mathbb{R}$. Then $T_0 = \partial E_0$ is C -almost minimizing in \mathbb{R}^n .*

Proof. Let $W_0 \subset\subset \mathbb{R}^n$ be open and let $X \in \mathcal{D}_n(\mathbb{R}^n)$ have support in W_0 . Let $L \gg 1$ and consider the open set $W_L = W_0 \times (-L - 1, L + 1)$ and the current $X_L = X \times [-L, L] \in \mathcal{D}_{n+1}(\mathbb{R}^{n+1})$, which has support in W_L . Note that $\partial X_L = \partial X \times [-L, L] + X \times \{L\} - X \times \{-L\}$, that $M_{W_L}(X_L) = 2LM_{W_0}(X)$, $M_{W_L}(T) = 2(L + 1)M_{W_0}(T_0)$ and that $M_{W_L}(T + \partial X_L) \geq 2LM_{W_0}(T_0 + \partial X)$. The claim follows when dividing by L and passing $L \rightarrow \infty$. q.e.d.

Lemma A.2. *Let $T_j = \partial E_j \in \mathcal{F}_C$ be such that $T_j \rightarrow T$ as currents. Then $T = \partial E \in \mathcal{F}_C$ where $\chi_{E_j} \rightarrow \chi_E$ in BV_{loc} . In fact the underlying varifolds converge as Radon measures on $G_n(\mathbb{R}^{n+1})$.*

Proof. The proof is by a minor modification of the proofs of Theorems 34.5 and 37.2 in [Si83], cf. also Proposition 5.1 in [DS93a]. We reproduce the argument with the necessary changes for clarity and ease of reference: it is clear from Definition A.1 that $\sup_{j \geq 1} M_W(T_j) < \infty$ for every bounded open set W . It follows that the χ_{E_j} subconverge as BV_{loc} functions to some χ_E . We continue to denote the converging subsequence by $\{j\}$. In particular, $\chi_{E_j} \rightarrow \chi_E$ in \mathcal{L}^1_{loc} and hence $T = \partial E$ as currents. Next let $K \subset \mathbb{R}^{n+1}$ be compact, and let $\phi : \mathbb{R}^{n+1} \rightarrow [0, 1]$ be a smooth function identically equal to one near K and vanishing outside an ε -neighborhood of K . For $\lambda \in [0, 1)$ denote by $W_\lambda := \{x : \phi(x) > \lambda\}$ the corresponding super level set of ϕ . Let $R_j := E - E_j$ and note that $M_{W_0}(R_j) \rightarrow 0$ as $j \rightarrow \infty$. Slicing these currents with respect to ϕ (see

§28 of [Si83]), for almost every $\alpha \in (0, 1)$ one can pass to a further subsequence (which we continue to denote by $\{j\}$) so that

$$\begin{aligned} \partial(R_j \llcorner W_\alpha) &= (\partial R_j) \llcorner W_\alpha + P_j \\ M_{W_0}(T_j \llcorner \partial W_\alpha) &= 0 \text{ for all } j \text{ and } M_{W_0}(T \llcorner \partial W_\alpha) = 0. \end{aligned}$$

where $P_j \in \mathcal{D}_n(\mathbb{R}^{n+1})$ are integer multiplicity with support in ∂W_α and $M_{W_0}(P_j) \rightarrow 0$. Hence $T \llcorner W_\alpha = T_j \llcorner W_\alpha + \partial \tilde{R}_j + P_j$ where $\tilde{R}_j := R_j \llcorner W_\alpha$ and P_j are integer multiplicity with support in \bar{W}_α and whose total mass tends to zero. For a given integer multiplicity current $X \in \mathcal{D}_{n+1}(\mathbb{R}^{n+1})$ with $\text{spt}(X) \subset K$ the C -almost minimizing property of the T_j 's implies that for every $\lambda \in (0, \alpha)$ one has

$$\begin{aligned} M_{W_\lambda}(T + \partial X) &= M_{W_\lambda}(T_j + \partial X + \partial \tilde{R}_j + P_j) \\ (12) \quad &\geq M_{W_\lambda}(T_j) - M_{W_\lambda}(P_j) - C(M_{W_\lambda}(X) + M_{W_\lambda}(\tilde{R}_j)). \end{aligned}$$

Letting $j \rightarrow \infty$ in (12) and using the lower semi-continuity of mass under weak convergence one has

$$M_{W_\lambda}(T + \partial X) \geq M_{W_\lambda}(T) - CM_{W_\lambda}(X)$$

and hence $T \in \mathcal{F}_C$ (since K was arbitrary). From inequality (12) with $X = 0$ it follows that

$$\limsup_j \mu_{T_j}(K) \leq \limsup_j M_{W_\lambda}(T_j) \leq M_{\{x:d(K,x)<\varepsilon\}}(T).$$

Upon taking ε to zero (more subsequences!) this gives

$$\limsup_j \mu_{T_j}(K) \leq \mu_T(K)$$

and hence $\mu_{T_j} \rightarrow \mu_T$ as Radon measures on \mathbb{R}^{n+1} . As in [Si83], this argument can be repeated verbatim to show that every subsequence of the original sequence $\{T_j\}$ has a further subsequence which converges to T as in the statement of the lemma. The convergence of the original sequence follows. The first variation of the varifolds underlying the currents $\{T_j\}$ is uniformly bounded, see Remark A.2. By Allard's compactness theorem for integer rectifiable varifolds, see §42 of [Si83], these varifolds subconverge as Radon measures on the full Grassmann manifold $G_n(\mathbb{R}^{n+1})$ to an integer rectifiable varifold. We have already seen that their total variation measures converge to that of ∂E on \mathbb{R}^{n+1} . Hence the varifold limit equals the boundary ∂E with its usual (multiplicity one almost everywhere) structure. q.e.d.

Lemma A.3 (cf. Proposition 5.1 in [DS93a]). *The class \mathcal{F}_C is closed under translation and dilation by $\lambda \geq 1$. If $T \in \mathcal{F}_C$ then $\Theta^n(\mu_T, x) = 1$ for μ_T -almost every $x \in \text{spt}(T)$. \mathcal{F}_C is sequentially compact with respect to current convergence which - for this class - is the same as varifold convergence. The tangent varifolds of T are stationary and homogeneous*

of degree zero (and hence are tangent cones); viewed as currents, they are area minimizing.

Proof. Note that if $T \in \mathcal{F}_C$ then $\lambda(T - x) \in \mathcal{F}_{C/\lambda}$ for every $x \in \mathbb{R}^{n+1}$ and $\lambda > 0$. The result is immediate from Remark A.2, Lemma A.2, and a standard application of the monotonicity identity as in §17 of [Si83].
 q.e.d.

The definition of the singular and regular sets and the study of their size by dimension reduction, tangent cone analysis, and Allard’s regularity theorem is exactly as in §36, §37 of [Si83]:

Definition A.2. For $T \in \mathcal{F}_C$ define the regular set $\text{reg}(T) := \{x \in \text{spt}(T) : \exists \rho > 0 \text{ with } T|_{B(x, \rho)} \text{ is a connected } \mathcal{C}^{1,\alpha}\text{-graph}\}$, and the singular set as its complement: $\text{sing}(T) := \text{spt}(T) - \text{reg}(T)$.

Theorem A.1 (Regularity, cf. Theorem 1 in [Ta82] and Theorem 5.6 in [DS93a]). *Let $T \in \mathcal{F}_C$. Then $\dim(\text{sing}(T)) \leq n - 7$. If $n = 7$ the singular set consists of isolated points.*

Proof. By Allard’s theorem and the uniform bound on the mean curvature for members of \mathcal{F}_C , see Remark A.2, there exists $\delta > 0$ such that $\text{sing}(T) = \{x \in \text{spt}(T) : \Theta^n(\mu_T, x) \geq 1 + \delta\}$. It is not difficult to see that Leon Simon’s abstract dimension reduction argument (see Appendix A in [Si83]) applies in the present context: one only has to verify that if $T_i \rightharpoonup T$ and $x_i \in \text{spt}(T_i)$ converges to $x \in \text{spt}(T)$ then $\Theta^n(T, x) \geq \limsup_{i \rightarrow \infty} \Theta^n(T_i, x_i)$. This follows easily because no mass is lost under weak convergence (i.e. $\mu_{T_i} \rightarrow \mu_T$) and because there is an approximate monotonicity formula (see 17.4 in [Si83]) for the members of \mathcal{F}_C because of the uniform bound $|\vec{H}_T| \leq C$. Observe also that since \mathcal{F}_C consists of boundaries, the multiplicity on the regular set is always equal to 1.
 q.e.d.

Remark A.3. The notion of being C -almost minimizing localizes and Theorem A.1 pertains: if $\mathcal{O} \subset \mathbb{R}^{n+1}$ is an open set, then the arguments sketched here carry over verbatim to the class of boundaries $T = \partial E$ (in \mathcal{O}) for which (11) holds for all currents X as described in Definition A.1 but whose support also lies in \mathcal{O} . The results stated here and their proofs carry over to Riemannian manifolds as in §37 of [Si83], by isometrically embedding into some high dimensional Euclidean space.

Appendix B. Remark on the outermost marginally outer trapped surface

In [AM07] the existence, regularity, and uniqueness of the outermost marginally outer trapped surface Σ^2 (i.e. the apparent horizon) of a complete asymptotically flat 3-dimensional initial data set (M^3, g, p) is proven. It is shown that Σ^2 appears as the boundary of the total

outer trapped region $T \subset M^3$. J. Metzger pointed out in [M07] that one can force Jang's equation to blow up along Σ^2 . We remark that the method of the present paper can be used directly to conclude from such a blow-up that the apparent horizon Σ^2 has the $3|p|_{C(\bar{\Omega})}$ -almost minimizing property on the set $\{x \in M^3 : \text{dist}(x, \Sigma^2) < \epsilon\} \cup M^3 \setminus T$ for some $\epsilon > 0$. It follows that Σ^2 is *outer* $3|p|_{C(\bar{\Omega})}$ -almost minimizing, i.e. the defining property (11) holds for all top dimensional currents $X \in \mathcal{D}_3(M^3)$ with compact support contained in the (closed) complement of T .

In the construction of the outermost marginally outer trapped surface in [AM07] a delicate surgery procedure is used to derive an estimate on the “outer injectivity radius” for a certain class of marginally outer trapped surfaces $\Sigma^2 \subset M^3$ and, as a consequence, area estimates for these surfaces. The a priori curvature estimates used in this surgery procedure come from the Pogorelov-type estimate in [AM05], which relies on the Gauss-Bonnet formula. The area estimate which arises from the C -almost minimizing property observed in the present paper implies the area estimate in Theorem 1.2 of [AM07] (the assumptions there can be used to bound the area of a comparison surface) and is available in all dimensions. In [E08] we explain how the low order property of marginally outer trapped surfaces in this work brings in many classical techniques from the calculus of variations and readily leads to the existence and regularity of the apparent horizon in dimensions $n \leq 7$, without recourse to the delicate surgery procedure and stability based estimates of [AM07].

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