

A Note on the Differential of the Exponential Map and Jacobi Fields in a Symmetric Space

Hajime TANIGUCHI

Sophia University

It was remarked by Rauch [4] that the differential equation for Jacobi fields in a symmetric space has constant coefficients with respect to suitable moving frames along a geodesic. Using a slightly different method, we give here an explicit form of a Jacobi field in a coordinate free form.

We also give, in the Lemma in §1, a relationship between the differential of the exponential map and Jacobi fields. This provides an alternate proof of the well known formula (Helgason [1], Chap. IV, Theorem 4.1) on the differential of the exponential map in a symmetric space.

§1. Let M be a manifold with a torsion-free affine connection ∇ , and consider $\exp = \exp_x: T_x M \rightarrow M$, $x \in M$, and let $d \exp_X: T_x M \rightarrow T_{\exp X} M$, $X \in T_x M$, be its differential at X . Furthermore write $\gamma(t) = \exp tX$, and set

$$\mathcal{J} = \{J: \text{a Jacobi field along } \gamma, J(0) = 0\}.$$

Then we have the isomorphism:

$$\phi: T_x M \rightarrow \mathcal{J}$$

where, for $Y \in T_x M$, $\phi(Y) = J$ is defined by $J(0) = 0$ and $\nabla J/dt(0) = Y$.

LEMMA. *The following diagram is commutative:*

$$\begin{array}{ccc} T_x M & \xrightarrow{d \exp_{tX}} & T_{\exp tX} M \\ \phi \downarrow & & \downarrow t \\ \mathcal{J} & \xrightarrow{ev} & T_{\exp tX} M \end{array}$$

where the "bottom map" is the evaluation map sending J to $J(t)$ and

the "vertical map" on the right is the scalar multiplication by t .

PROOF. For $Y \in T_x M$, set

$$\alpha(u, t) = \exp t(X + uY).$$

We denote by $\partial\alpha/\partial u$ the tangent vector of " u -curves" and by $\nabla/\partial u$ the covariant differentiation along them, and similarly for " t -curves". Since, for a fixed t , $Y(u) = t(X + uY)$ defines a curve in $T_x M$ such that $Y(0) = tX$, $Y'(0) = tY$, we have

$$\frac{\partial\alpha}{\partial u}(0, t) = t d \exp_{tX}(Y).$$

On the other hand, writing

$$\left. \frac{\partial\alpha}{\partial u} \right|_{u=0} = J$$

we get, for the covariant derivative along γ ,

$$\begin{aligned} \left. \frac{\nabla}{dt} \right|_{t=0} J &= \left. \frac{\nabla}{\partial t} \frac{\partial\alpha}{\partial u} \right|_{t=0, u=0} \\ &= \left. \frac{\nabla}{\partial u} \frac{\partial\alpha}{\partial t} \right|_{t=0, u=0} \\ &= \left. \frac{\nabla}{du}(X + uY) \right|_{u=0} \\ &= Y. \end{aligned}$$

Note that the second equality holds because ∇ is assumed to be torsion free. q.e.d.

§2. Let $M = G/K$ be an affine symmetric space, σ the associated involutive automorphism of G , $\mathfrak{g} = \mathfrak{k} + \mathfrak{m}$ the decomposition of the Lie algebra into the eigenspaces of σ , $\pi: G \rightarrow G/K$ the natural projection, and let $\pi(e) = o$ (e is the unit of G). As usual we identify \mathfrak{m} with $T_o M$ via $d\pi: \mathfrak{m} \rightarrow T_o M$. Furthermore put $x_t = \exp tX$ ($X \in \mathfrak{m}$), and put $\gamma(t) = \tau_{x_t} o = \pi(\exp tX)$, where τ_x is the action of $x \in G$ on M . On the other hand M carries the canonical connection ∇ and it is well-known that the parallel translation τ'_t along γ is given by τ_{x_t} , i.e.,

$$\tau'_t = d\tau_{x_{-(t'-t)}}: T_{\gamma(t')} M \rightarrow T_{\gamma(t)} M$$

in particular

(*) $\gamma(t) = \pi(\exp tX)$ is a geodesic for $X \in \mathfrak{m}$.

PROPOSITION. The Jacobi field J along γ with the initial condition $J(0) = 0, \nabla J/dt(0) = Y \in \mathfrak{m}$ is given by

$$J(t) = \tau_{xt} \sum_{n=0}^{\infty} \frac{t^{2n+1}}{(2n+1)!} T_X^n(Y)$$

where $T_X = (\text{ad } X)^2: \mathfrak{m} \rightarrow \mathfrak{m}$.

PROOF. For a vector field J along γ set

$$\bar{J}(t) = \tau_t^* J(t) \in \mathfrak{m}$$

so that \bar{J} is an \mathfrak{m} -valued function in t , and we have

$$\frac{\nabla J}{dt} = \tau_t^* \frac{d\bar{J}}{dt}.$$

Now the Jacobi equation for J is given by

$$\frac{\nabla^2 J}{dt^2} + R\left(J, \frac{d\gamma}{dt}\right) \frac{d\gamma}{dt} = 0.$$

Since R is parallel, applying τ_t^* to the above equation we get

$$\frac{d^2 \bar{J}}{dt^2} + R_0(\bar{J}, X)X = 0.$$

But it is well-known that

$$R_0(X, Y) = -\text{ad}[X, Y] \quad X, Y \in \mathfrak{m}.$$

Hence

(#)
$$\frac{d^2 \bar{J}}{dt^2} - T_X(\bar{J}) = 0 \quad \text{or}$$

$$\frac{d}{dt} \begin{pmatrix} \bar{J} \\ \bar{J}' \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ T_X & 0 \end{pmatrix} \begin{pmatrix} \bar{J} \\ \bar{J}' \end{pmatrix} \quad \text{with} \quad \bar{J}' = \frac{d\bar{J}}{dt}.$$

Thus, setting $S_X = \begin{pmatrix} 0 & 1 \\ T_X & 0 \end{pmatrix}$ we get

$$\begin{pmatrix} \bar{J} \\ \bar{J}' \end{pmatrix} = \exp tS_X \begin{pmatrix} 0 \\ Y \end{pmatrix}. \quad \text{q.e.d.}$$

In view of the Lemma, the following theorem is an immediate consequence of the Proposition:

THEOREM. For $X \in T_o(M) = \mathfrak{m}$ and $\exp: \mathfrak{m} \rightarrow G/K$ we have

$$d \exp_X = \tau_{\exp X} \circ \sum_{n=0}^{\infty} \frac{T_X^n}{(2n+1)!}$$

COROLLARY. For a Lie group G , $X \in \mathfrak{g}$, and $\exp: \mathfrak{g} \rightarrow G$, we have

$$d \exp_X = dL_{\exp X} \circ \frac{1 - e^{-\text{ad} X}}{\text{ad} X}$$

where L_x is the left translation by $x \in G$.

PROOF. We put, as usual, $G^* = G \times G$, $\sigma(x, y) = (y, x)$, $K^* = \{(x, x) : x \in G\}$ and apply the Theorem to the pair (G^*, K^*) . We have the following identifications:

$$\theta: M^* = G^*/K^* \longrightarrow G \quad (x, y)K^* \longmapsto xy^{-1}$$

and setting $\mathfrak{m}^* = \{(X, -X) : X \in \mathfrak{g}\}$

$$\theta: T_o M^* = \mathfrak{m}^* \longrightarrow \mathfrak{g} \quad X^* = (X, -X) \longmapsto 2X.$$

The diagram below is commutative because of (*),

$$\begin{array}{ccc} T_o M^* = \mathfrak{m}^* & \xrightarrow{\exp} & G^*/K^* \\ \theta \downarrow & & \downarrow \theta \\ \mathfrak{g} & \xrightarrow{\exp} & G \end{array}$$

thus, so is the left square of the following diagram.

$$\begin{array}{ccccc} \mathfrak{m}^* & \xrightarrow{d \exp_{X^*}} & T_{\exp X^*}(G^*/K^*) & \xleftarrow{d \tau_{\exp X^*}} & \mathfrak{m}^* \\ \theta \downarrow & & \theta \downarrow & & \theta \downarrow \\ \mathfrak{g} & \xrightarrow{d \exp_{2X}} & T_{\exp 2X} G & \xleftarrow{d L_{\exp X} \circ d R_{\exp X}} & \mathfrak{g} \end{array}$$

The right half is also commutative, because the action of $(a, b) \in G^*$ on G^*/K^* corresponds, via θ , to $L_a \circ R_b^{-1}$. (R_x is the right multiplication by x .) Writing $\Phi = d\tau_{\exp X^*}^{-1} \circ d \exp_{X^*}$ and $\Psi = (dL_{\exp X} \circ dR_{\exp X})^{-1} \circ d \exp_{2X} = e^{\text{ad} X} \circ dL_{\exp 2X}^{-1} \circ d \exp_{2X}$, we have shown that, for $Y^* = (Y, -Y) \in \mathfrak{m}^*$,

$$\Phi(Y^*) = \sum_{n=0}^{\infty} \frac{\text{ad}(X, -X)^{2n}}{(2n+1)!} (Y, -Y).$$

Hence,

$$\begin{aligned}
dL_{\exp(-2X)} \circ d \exp_{2X}(2Y) &= e^{-\text{ad}X} \circ \Psi(2Y) \\
&= e^{-\text{ad}X} \left(2 \sum_{n=0}^{\infty} \frac{(\text{ad} X)^{2n}}{(2n+1)!} (Y) \right) \\
&= e^{-\text{ad}X} \frac{e^{\text{ad}X} - e^{-\text{ad}X}}{\text{ad} X} (Y) \\
&= \frac{1}{\text{ad}(2X)} (1 - e^{-\text{ad}(2X)})(2Y) .
\end{aligned}$$

q.e.d.

References

- [1] S. HELGASON, Differential Geometry and Symmetric Spaces, Academic Press, New York, 1962.
- [2] S. KOBAYASHI and K. NOMIZU, Foundations of Differential Geometry, Interscience, New York, 1963.
- [3] J. MILNOR, Morse Theory, Ann. Math. Studies 51, Princeton University Press, 1963.
- [4] H. RAUCH, The global study of geodesics in symmetric and nearly symmetric Riemannian manifolds, Proc. U.S.-Japan Seminar in Differential Geometry, Kyoto, Japan, 1965, 115-127.

Present Address:
DEPARTMENT OF MATHEMATICS
SOPHIA UNIVERSITY
KIOI-CHO, CHIYODA-KU, TOKYO 102