

A note on Newton's method for stochastic differential equations and its error estimate

By Kazuo AMANO

Department of Mathematics, Faculty of Engineering, Gunma University, Kiryu 376-8515, Japan

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Abstract: Kawabata and Yamada [3] proposed an *implicit* Newton method for stochastic differential equations and proved its convergence. They proved an error estimate in a sufficiently small time interval and extended it to a global convergence theorem by using open-closed method. In this note, the author gives an *explicit* Newton scheme which is equivalent to Kawabata-Yamada's *implicit* formulation (Remark 1) and prove its direct error estimate (Theorem 2.1). His result could provide a key to solve the open problem of second order convergence (see Remark of Theorem 2.1 and [2]).

Key words: Newton's method for stochastic differential equations; error estimate.

1. Preliminaries. Let $a(t, x)$ and $b(t, x)$ be real-valued bounded C^1 smooth functions defined in \mathbf{R}^2 . For the sake of simplicity, we assume that there exist nonnegative constants A_1 and B_1 satisfying

$$\left| \frac{\partial a}{\partial x}(t, x) \right| \leq A_1, \quad \left| \frac{\partial b}{\partial x}(t, x) \right| \leq B_1$$

in \mathbf{R}^2 . Let $\xi(t)$, $t \geq 0$ be a solution of the initial value problem for stochastic differential equation

$$(1) \quad d\xi(t) = a(t, \xi(t)) dt + b(t, \xi(t)) dw(t), \quad \xi(0) = \xi_0,$$

where $w(t)$ denotes a standard Brownian motion and ξ_0 is a bounded random variable independent of $\mathcal{F}(w(s), s \geq 0)$. Without loss of generality, we assume that $\xi(t)$ is continuous with respect to $t \geq 0$. Our explicit Newton scheme for the problem (1) is formulated as follows: We define a sequence $\{\xi_n(t)\}$ by $\xi_0(t) = \xi_0$ and

$$\begin{aligned} & \xi_{n+1}(t) \\ &= e^{\eta_n(t)} \left(\xi_0 + \int_0^t (a_{0,n}(s) - b_{0,n}(s) b_{1,n}(s)) e^{-\eta_n(s)} ds \right. \\ & \quad \left. + \int_0^t b_{0,n}(s) e^{-\eta_n(s)} dw(s) \right) \end{aligned}$$

for $n = 0, 1, 2, \dots$, where

$$\eta_n(t) = \int_0^t \left(a_{1,n}(s) - \frac{1}{2} (b_{1,n}(s))^2 \right) ds$$

$$\begin{aligned} & + \int_0^t b_{1,n}(s) dw(s), \\ a_{0,n}(t) &= a(t, \xi_n(t)) - \frac{\partial a}{\partial x}(t, \xi_n(t)) \xi_n(t), \\ a_{1,n}(t) &= \frac{\partial a}{\partial x}(t, \xi_n(t)), \\ b_{0,n}(t) &= b(t, \xi_n(t)) - \frac{\partial b}{\partial x}(t, \xi_n(t)) \xi_n(t), \\ b_{1,n}(t) &= \frac{\partial b}{\partial x}(t, \xi_n(t)). \end{aligned}$$

Though the above definition of $\{\xi_n(t)\}$ may look strange, it is actually a natural fomulation of Newton's method. In fact, each $\xi_n(t)$ is a solution of the linearized equation of (1) (see Lemma 1.1 and Remark 1).

Lemma 1.1. *Assume that $a_i(t)$, $b_i(t)$, $i = 0, 1$ are bounded continuous nonanticipative functions defined in $[0, \infty)$. Then, the initial value problem for linear stochastic differential equation*

$$\begin{aligned} d\xi(t) &= (a_0(t) + a_1(t) \xi(t)) dt \\ & \quad + (b_0(t) + b_1(t) \xi(t)) dw(t), \quad \xi(0) = \xi_0 \end{aligned}$$

has an explicit solution

$$\begin{aligned} \xi(t) &= e^{\eta(t)} \left(\xi_0 + \int_0^t (a_0(s) - b_0(s) b_1(s)) e^{-\eta(s)} ds \right. \\ & \quad \left. + \int_0^t b_0(s) e^{-\eta(s)} dw(s) \right), \end{aligned}$$

where

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$$\eta(t) = \int_0^t \left(a_1(s) - \frac{1}{2} b_1^2(s) \right) ds + \int_0^t b_1(s) dw(s).$$

Lemma 1.1 follows immediately from Itô's formula.

Remark 1. It follows immediately from the definition of $\xi_{n+1}(t)$ and Lemma 1.1 that $\xi_{n+1}(0) = \xi_0$ and

$$d\xi_{n+1}(t) = (a_{0,n}(t) + a_{1,n}(t) \xi_{n+1}(t)) dt + (b_{0,n}(t) + b_{1,n}(t) \xi_{n+1}(t)) dw(t)$$

for $n = 0, 1, 2, \dots$. Therefore, $\{\xi_n(t)\}$ is exactly the same sequence introduced by Kawabata and Yamada [3].

The approximation errors

$$\varepsilon_n(t) = \xi_n(t) - \xi(t), \quad n = 0, 1, 2, \dots$$

satisfy the following linear stochastic differential equations.

Lemma 1.2. For any $n = 0, 1, 2, \dots$, $\varepsilon_{n+1}(t)$ is a solution of the linear stochastic differential equation

$$d\varepsilon_{n+1}(t) = (\alpha_{0,n}(t) + a_{1,n}(t) \varepsilon_{n+1}(t)) dt + (\beta_{0,n}(t) + b_{1,n}(t) \varepsilon_{n+1}(t)) dw(t)$$

satisfying the initial condition $\varepsilon_{n+1}(0) = 0$, where

$$\begin{aligned} \alpha_{0,n}(t) &= a(t, \xi_n(t)) - \frac{\partial a}{\partial x}(t, \xi_n(t)) \varepsilon_n(t) \\ &\quad - a(t, \xi_n(t) - \varepsilon_n(t)), \\ \beta_{0,n}(t) &= b(t, \xi_n(t)) - \frac{\partial b}{\partial x}(t, \xi_n(t)) \varepsilon_n(t) \\ &\quad - b(t, \xi_n(t) - \varepsilon_n(t)). \end{aligned}$$

Proof. Since, by Remark 1, $\xi_{n+1}(t)$ is a solution of the linear stochastic differential equation

$$d\xi_{n+1}(t) = (a_{0,n}(t) + a_{1,n}(t) \xi_{n+1}(t)) dt + (b_{0,n}(t) + b_{1,n}(t) \xi_{n+1}(t)) dw(t),$$

we have

$$\begin{aligned} d\varepsilon_{n+1}(t) &= d\xi_{n+1}(t) - d\xi(t) \\ &= \left(a(t, \xi_n(t)) - \frac{\partial a}{\partial x}(t, \xi_n(t)) \xi_n(t) \right. \\ &\quad \left. - a(t, \xi(t)) + a_{1,n}(t) \xi_{n+1}(t) \right) dt \\ &\quad + \left(b(t, \xi_n(t)) - \frac{\partial b}{\partial x}(t, \xi_n(t)) \xi_n(t) \right. \\ &\quad \left. - b(t, \xi(t)) + b_{1,n}(t) \xi_{n+1}(t) \right) dw(t) \end{aligned}$$

$$\begin{aligned} &\quad - b(t, \xi(t)) + b_{1,n}(t) \xi_{n+1}(t) \Big) dw(t) \\ &= \left(a(t, \xi_n(t)) - \frac{\partial a}{\partial x}(t, \xi_n(t)) \varepsilon_n(t) \right. \\ &\quad \left. - a(t, \xi_n(t) - \varepsilon_n(t)) + a_{1,n}(t) \varepsilon_{n+1}(t) \right) dt \\ &\quad + \left(b(t, \xi_n(t)) - \frac{\partial b}{\partial x}(t, \xi_n(t)) \varepsilon_n(t) \right. \\ &\quad \left. - b(t, \xi_n(t) - \varepsilon_n(t)) + b_{1,n}(t) \varepsilon_{n+1}(t) \right) dw(t) \\ &= (\alpha_{0,n}(t) + a_{1,n}(t) \varepsilon_{n+1}(t)) dt \\ &\quad + (\beta_{0,n}(t) + b_{1,n}(t) \varepsilon_{n+1}(t)) dw(t). \end{aligned}$$

□

A version of Gronwall's inequality plays an important role to estimate the error $\varepsilon_{n+1}(t)$ (see also [1]).

Lemma 1.3. For any constant $T > 0$, if $f(t)$ and $g(t)$ are continuous nonnegative functions defined in a closed interval $[0, T]$ and if there exist nonnegative constants C_1 and C_2 such that

$$f(t) \leq C_1 \int_0^t g(s) ds + C_2 \int_0^t f(s) ds$$

for any $0 \leq t \leq T$, then we have

$$f(t) \leq C_1 e^{C_2 t} \int_0^t g(s) ds$$

for all $0 \leq t \leq T$.

2. Theorem and its proof.

Theorem 2.1. For any $T > 0$, there exists a nonnegative constant C depending only on T , A_1 and B_1 such that

$$(2) \quad \sup_{0 \leq t \leq T} E \varepsilon_n^2(t) \leq \frac{C^m}{n!} \sup_{0 \leq t \leq T} E \varepsilon_0^2(t)$$

for $n = 1, 2, 3, \dots$.

Proof. For any $n = 0, 1, 2, \dots$ and $0 \leq t \leq T$, Lemma 1.2 shows, by Minkowsky's and Hölder's inequalities and a fundamental property of stochastic integrals, that

$$\begin{aligned} &\{E \varepsilon_{n+1}^2(t)\}^{1/2} \\ &\leq \left\{ E \left(\int_0^t (\alpha_{0,n}(s) + a_{1,n}(s) \varepsilon_{n+1}(s)) ds \right)^2 \right\}^{1/2} \\ &\quad + \left\{ E \left(\int_0^t (\beta_{0,n}(s) + b_{1,n}(s) \varepsilon_{n+1}(s)) dw(s) \right)^2 \right\}^{1/2} \end{aligned}$$

$$\begin{aligned}
&\leq \left\{ 2E \left(\int_0^t \alpha_{0,n}(s) ds \right)^2 \right. \\
&\quad \left. + 2E \left(\int_0^t a_{1,n}(s) \varepsilon_{n+1}(s) ds \right)^2 \right\}^{1/2} \\
&\quad + \left\{ 2E \left(\int_0^t \beta_{0,n}^2(s) ds \right) \right. \\
&\quad \left. + 2E \left(\int_0^t b_{1,n}^2(s) \varepsilon_{n+1}^2(s) ds \right) \right\}^{1/2} \\
&\leq \left\{ 2TE \left(\int_0^t \alpha_{0,n}^2(s) ds \right) \right. \\
&\quad \left. + 2E \left(\left(\int_0^t a_{1,n}^2(s) ds \right) \left(\int_0^t \varepsilon_{n+1}^2(s) ds \right) \right) \right\}^{1/2} \\
&\quad + \left\{ 2E \left(\int_0^t \beta_{0,n}^2(s) ds \right) \right. \\
&\quad \left. + 2E \left(\int_0^t b_{1,n}^2(s) \varepsilon_{n+1}^2(s) ds \right) \right\}^{1/2}.
\end{aligned}$$

Since

$$(3) \quad |\alpha_{0,n}(t)| \leq 2A_1|\varepsilon_n(t)|, \quad |\beta_{0,n}(t)| \leq 2B_1|\varepsilon_n(t)|,$$

the above result gives

$$\begin{aligned}
&\{E\varepsilon_{n+1}^2(t)\}^{1/2} \\
&\leq \left\{ 8A_1^2TE \left(\int_0^t \varepsilon_n^2(s) ds \right) \right. \\
&\quad \left. + 2A_1^2TE \left(\int_0^t \varepsilon_{n+1}^2(s) ds \right) \right\}^{1/2} \\
&\quad + \left\{ 8B_1^2E \left(\int_0^t \varepsilon_n^2(s) ds \right) \right. \\
&\quad \left. + 2B_1^2E \left(\int_0^t \varepsilon_{n+1}^2(s) ds \right) \right\}^{1/2} \\
&\leq 2\sqrt{2}(A_1\sqrt{T} + B_1) \left(\int_0^t E\varepsilon_n^2(s) ds \right)^{1/2} \\
&\quad + \sqrt{2}(A_1\sqrt{T} + B_1) \left(\int_0^t E\varepsilon_{n+1}^2(s) ds \right)^{1/2}.
\end{aligned}$$

Consequently, we obtain

$$\begin{aligned}
E\varepsilon_{n+1}^2(t) &\leq 16(A_1\sqrt{T} + B_1)^2 \int_0^t E\varepsilon_n^2(s) ds \\
&\quad + 4(A_1\sqrt{T} + B_1)^2 \int_0^t E\varepsilon_{n+1}^2(s) ds;
\end{aligned}$$

this shows, by Lemma 1.3,

$$\begin{aligned}
E\varepsilon_{n+1}^2(t) &\leq 16(A_1\sqrt{T} + B_1)^2 e^{4(A_1\sqrt{T} + B_1)^2 T} \int_0^t E\varepsilon_n^2(s) ds
\end{aligned}$$

for all $0 \leq t \leq T$ and every $n = 0, 1, 2, \dots$. The recursive use of the above estimate completes the proof. \square

Remark 2. Since (2) implies

$$\lim_{n \rightarrow \infty} \sup_{0 \leq t \leq T} E\varepsilon_n^2(t) = 0,$$

Theorem 2.1 gives a simple proof of Kawabata and Yamada's convergence theorem. We easily have

$$(4) \quad |\alpha_{0,n}(t)| \leq A_2|\varepsilon_n(t)|^2, \quad |\beta_{0,n}(t)| \leq B_2|\varepsilon_n(t)|^2$$

instead of (3) if $|a_{xx}| \leq A_2$ and $|b_{xx}| \leq B_2$ for some constants A_2 and B_2 , however we cannot prove the second order error estimate in the present note. For this purpose, our explicit formulation and a new type of approach would be necessary [2].

References

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