

19. Certain Quadratic First Integral and Elliptic Orbits of Linear Hamiltonian System

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1. Introduction. This paper deals with a close relation between a hyperplane filled with elliptic orbits of a linear Hamiltonian system and a certain quadratic first integral. To be more precise, it is proved that when a linear Hamiltonian system admits an invariant hyperplane filled with closed orbits, it leaves a quadratic form invariant, and conversely, when a certain quadratic first integral is admitted, there exists such an invariant hyperplane.

By the way, the phase portrait drawn by a discrete-time system which approximates a continuous Hamiltonian system is often different from that of the original system. For example, a closed orbit of the original system is usually destroyed by a discrete system, even when the original one is linear. It seems that the result of this paper is of use for the purpose of reproducing the original elliptic orbit by a discrete system when a certain kind of first integrals is inherited.

2. Elliptic orbit of linear system. Let us think of a linear Hamiltonian system with N degrees of freedom given by

$$(1) \quad \frac{dx}{dt} = Hx, \quad H \in sp(N, R), \quad x \in R^{2N}.$$

We introduce into the phase space R^{2N} both a Euclidean inner product $(x, y) = {}^t xy$ and a symplectic inner product $\langle x, y \rangle = {}^t x J y$, where $J = \begin{bmatrix} 0 & I \\ -I & 0 \end{bmatrix}$ and the superfix t denotes matrix transpose. An orbit of (1) which starts from x_0 is closed, it and only if $e^{\varepsilon H} x_0 = x_0$ holds for a positive constant ε . This condition is equivalent to that H has pure imaginary eigenvalues, in other words, H^2 has a negative eigenvalue. Then, we define a linear subspace by

$$(2) \quad \Gamma_\beta = \{x \in R^{2N} \mid H^2 x = -\beta^2 x\} \quad (\beta > 0),$$

and assume that $\Gamma_\beta \neq \{0\}$ from now on. Let us pay attention to the solution curves of (1) which are contained in Γ_β . Choose an arbitrary $q \in \Gamma_\beta$, $q \neq 0$, and put

$$(3) \quad p = -\frac{1}{\beta} H q.$$

Then, q and p are linearly independent and spans a two-dimensional hyperplane Γ included by Γ_β .

Proposition 1. *The orbit of (1) starting from $q \in \Gamma$ is an ellipse with the period $2\pi/\beta$, and lies in Γ . Furthermore, all elliptic orbits in Γ are*

similar to each other.

Proof. Denote by $q(t)$ and $p(t)$ the solutions of (1) starting from q and p , respectively. Since it holds that

$$(4) \quad Hq = -\beta p, \quad Hp = \beta q,$$

we have $(q(t), p(t)) = e^{tH}(q, p) = (q, p) \begin{bmatrix} \cos(\beta t) & \sin(\beta t) \\ -\sin(\beta t) & \cos(\beta t) \end{bmatrix}$. This shows that the curve $q(t)$ is a closed quadratic one in Γ .

The result means that Γ_β is full of ellipses with the period $2\pi/\beta$. A similar circumstance holds true in any other eigenspace Γ_γ of H^2 when the eigenvalue is negative. In general, an orbit starting from a point in the sum $\Gamma_\beta + \Gamma_\gamma$ is, however, like a Lissajous figure, and may not be closed.

We have not used the assumption that H belongs to $sp(N, R)$, and the result holds good in every linear system. In case of linear Hamiltonian systems, the above plane Γ is characterized by a certain quadratic first integral, which is the theme of the next section.

3. Certain quadratic first integral. In this section, we show a close relation between a certain first integral and the hyperplane Γ . Let Γ, Γ_β, q and p be as in § 1. Furthermore, we remark that

$$(5) \quad {}^tHJ + JH = 0$$

holds, for H belongs to $sp(N, R)$.

Theorem 2. For an arbitrary $q \in \Gamma$ ($q \neq 0$), define p by (3). Then, the following quadratic form is a first integral of (1)

$$(6) \quad I(x) = \frac{1}{2} {}^t x^t J (q^t q + p^t p) J x.$$

Proof. Put

$$(7.a) \quad S = q^t q + p^t p, \quad (7.b) \quad \tilde{S} = {}^t J S J,$$

and use (5), and we have $dI/dt = {}^t x J (HS + S^t H) J x / 2$. Since $HS = -\beta p^t q + \beta q^t p = -(p^t(Hp) + q^t(Hq)) = -S^t H$, then dI/dt vanishes.

Remark. The first integral (6) is independent of the choice of $q \in \Gamma$. In fact, a quadratic form constructed from another $\tilde{q} \in \Gamma$ in the same way becomes (6) multiplied by a constant.

We show several properties of S :

$$(8.a) \quad \text{rank}(S) = 2, \quad (8.b) \quad S \geq 0,$$

$\text{range}(S) = \Gamma$, and $\text{ker}(S) = \Gamma^\perp$, where Γ^\perp denotes the orthogonal complement of Γ with respect to $(,)$ and $S \geq 0$ means that S is non-negative definite. These are restated in terms of \tilde{S} as follows: $\text{rank}(\tilde{S}) = 2, \tilde{S} \geq 0, \text{range}(\tilde{S}) = J(\Gamma)$, and $\text{ker}(\tilde{S}) = J(\Gamma^\perp)$. Now, the next step is to show that the converse of the theorem is true if a slight condition is added. We give a definition concerning the condition.

Definition 1. A linear subspace \mathcal{E} is called *null* [1], if and only if $\langle q, p \rangle$ vanishes for all vectors q and p in \mathcal{E} .

As for Γ in the above, when the eigenvalues $\pm i\beta$ of H are simple, it is not null. When Γ is not null, $\langle q, p \rangle$ is not zero for arbitrary linearly independent elements q and p . Furthermore, Γ is null if and only if $\Gamma \subset J(\Gamma^\perp)$.

Theorem 3. *Suppose that (1) has a quadratic first integral given by $I(x) = {}^t x \tilde{S} x / 2$ subject to ${}^t \tilde{S} = \tilde{S}$, $\text{rank}(\tilde{S}) = 2$, and $\tilde{S} \geq 0$. If $\Gamma = \text{range}(J\tilde{S})$ is not null and $H(\Gamma) \neq \{0\}$, then Γ is filled with elliptic orbits of (1) with a single period.*

Proof. If we define S by (7.b), then S satisfies (8). Therefore, S is expressed as (7.a) in terms of two non-zero vectors q and p subject to $(q, p) = 0$. Put $\Gamma = \{(q, p)\}$, and Γ is nothing but $\text{range}(J\tilde{S})$. Since Γ is not null by supposition, $\langle q, p \rangle$ does not vanish. Now, since $I(x)$ is a first integral, it must hold that

$$(9) \quad H \cdot SJ = SJ \cdot H.$$

Multiplying (9) by q and p from the right and using $\langle q, p \rangle \neq 0$, we can see that Hq and Hp are expressed as linear combinations of q and p . Then, we put

$$(10) \quad Hq = \alpha q + \beta p, \quad Hp = \gamma q + \delta p,$$

where α , β , γ , and δ are constants. Next, multiplying (9) by ${}^t q$ and ${}^t p$ from the left and using (10) and $(q, p) = 0$, we have $(\alpha {}^t q + \gamma {}^t p)J = -(\alpha {}^t q + \beta {}^t p)J$, and $(\beta {}^t q + \delta {}^t p)J = -(\gamma {}^t q + \delta {}^t p)J$. Then, it holds that $\alpha = \delta = 0$ and $\beta + \gamma = 0$, and accordingly, that $Hq = -\beta p$ and $Hp = \beta q$. Due to the supposition $H(\Gamma) \neq \{0\}$, β is not equal to zero. Thus, the conclusion is obtained from Proposition 1.

The next corollary follows directly from the above proof.

Corollary 4. *In Γ there exists a nonzero vector q which is orthogonal to Hq with respect to $(,)$.*

Now, when Γ is null, the value of $I(x)$ on Γ remains zero. Otherwise, $I(x)$ gives a positive definite form when restricted to Γ , and its level curve on Γ is nothing but an integral curve of (1). Furthermore, the Hamiltonian vector field with the Hamiltonian $I(x)$ is given by $H_1 x = SJx$. Then, it follows from (4) and (7.a) that $H_1 x$ is equal to $\langle p, q \rangle / \beta \cdot Hx$ for every $x \in \Gamma$. That is, as far as we are restricted to Γ , the symmetry generated by $I(x)$ produces the elliptic orbit of the original system (1). Moreover, $\ker(H_1)$ is equal to $J(\Gamma^\perp)$, and this symmetry yields no action in any direction in $J(\Gamma^\perp)$.

We close this paper by stressing again that an integral curve on Γ is nothing but a level curve of $I(x)$ if Γ is not null. If a discrete-time system which approximates (1) inherits the first integral given by (6) and leaves Γ invariant, the discrete orbit starting from a point in Γ , namely, a point sequence, lies on the solution curve of (1) itself. In addition, if the discrete system is sufficiently near the identity mapping, it results that at least in every Γ_β the phase portrait of (1) is reproduced accurately by the discrete-time system.

Reference

- [1] V. I. Arnold: *Mathematical Methods of Classical Mechanics* (Engl. Trans. by K. Vogtman and A. Weinstein). Springer (1978).