56. On the Number of Apparent Singularities

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§0. Introduction. Let M be a closed Riemann surface of genus g, S a finite subset of M and ρ a representation of the fundamental group $\pi_1(M-S)$ on C^n . The Riemann-Hilbert problem states as follows:

Find a Fuchsian linear differential equation of order n with singularities on S and having ρ as its monodromy representation.

When S consists of m distinct points, the set of Fuchsian linear differential equations of order n having their singuralities only on S has a structure of a complex manifold of dimension $2^{-1}n(n+1)m+n^2(g-1)$ (Kita [3]), whereas the totality of equivalence classes of complex n-dimensional irreducible representations of the fundamental group $\pi_1(M-S)$ forms a complex manifold of dimension $n^2(m+2g-2)+1$. So, in general, we must introduce apparent singulalities to solve the Riemann-Hilbert problem. On the number of apparent singulalities, the following result is known ([4]):

Theorem 1 (Ohtsuki). If the representation ρ is irreducible and if the local representation at a point of S induced by ρ is semi-simple, then there exists a Fuchsian linear equation of order n on M which has the given representation ρ as its monodromy representation and has at most

$$2^{-1}n(n-1)m+n^2(g-1)+1$$

apparent singularities.

In this paper, without assuming that the local representation at a point of S induced by ρ is semi-simple, we show the following theorem:

Main theorem. Let M, S and ρ be as above Let d be the greatest common divisor of complex dimensions of all invariant subspaces of the local representation induced by ρ at each point of S. Then there exists a Fuchsian linear equation of order n on M which has the given representation ρ as its monodromy representation and has at most

$$2^{-1}n(n-1)m+n^2(g-1)+d$$

apparent singularities.

Since d is at most n, we have easily the

Corollary. There exists a Fuchsian linear equation of order n on M which has the given representation ρ as its monodromy representation and has at most

$$2^{-1}n(n-1)m + n^2(g-1) + n$$

apparent singularities.

§1. The method of Deligne. To establish the main theorem, we recall the proof of Theorem 1 (Ohtsuki [4]). Deligne's method. 1) The representation ρ defines a local system V' of *n*-dimensional complex vector spaces over M-S.

2) V' determines canonically a holomorphic vector bundle V' over M-S with a holomorphic connection V' such that

$$V' = \{ \xi \in V' \mid \overline{V'} \xi = 0 \}.$$

3) Then the pair (V', ∇') extends to a pair (V, ∇) , where V is a holomorphic vector bundle over M and ∇ is a meromorphic connection on V such that the restriction $(V|_{M-S}, \nabla|_{V|M-S})$ is equivalent to (V', ∇') .

4) To obtain an ordinary linear differential equation, we take a holomorphic section ψ of the dual bundle V^* such that $\psi(V')$ is isomorphic to V' as local systems, where we consider $\psi(V')$ as a subsheaf of \mathcal{O}_{M-S} . Then a differential equation having $\psi(V')$ as the solution sheaf gives a solution of the Riemann-Hilbert problem.

(V, V) is not uniquely determined by (V', V'). We use this fact in the proof of the main theorem.

§ 2. Differential equation with the given solution sheaf. Let (V, \overline{V}) be an extension of the pair $(V', \overline{V'})$ with a non-zero holomorphic section $\psi \in \Gamma(M, \mathcal{O}(V^*))$ of the dual bundle V^* of V. It follows from the irreducibility of the given representation ρ that the local system $\psi(V')$ is isomorphic to V'. A differential equation having $\psi(V')$ as the solution sheaf is constructed as follows.

Let ξ_1, \dots, ξ_n be a local *C*-basis of $V'|_U$ on a local chart (U, z). Then $\langle \psi, \xi_1 \rangle, \dots, \langle \psi, \xi_n \rangle$ form a *C*-basis of $\psi(V')|_U$. The differential equation on (U, z) with the solution sheaf $\psi(V')$ is

$$\detegin{bmatrix} \langle\psi,\xi_1
angle&\cdots\langle\psi,\xi_n
angle&y\ D\langle\psi,\xi_1
angle&\cdots D\langle\psi,\xi_n
angle&Dy\ \dots&\dots&\dots\ D^n\langle\psi,\xi_n
angle&D^ny\end{bmatrix}=0,$$

where D = d/dz. On the other hand, the connection \mathcal{V} on the bundle \mathcal{V} defines the dual connection on the dual bundle \mathcal{V}^* of \mathcal{V} , which we denote also by \mathcal{V} . The covariant derivative $\mathcal{V}_D\psi$ of ψ by D with respect to the connection \mathcal{V} is a local meromorphic section of \mathcal{V}^* on U. We can define $(\mathcal{V}_D)^*\psi \in \Gamma(U, \mathcal{M}(\mathcal{V}^*))$ by

$$(\overline{V}_D)^k\psi=\overline{V}_D((\overline{V}_D)^{k-1}\psi).$$

We have

 $D^{k}\langle\psi,\xi_{j}\rangle = \langle (V_{D})^{k}\psi,\xi_{j}\rangle \qquad (j=1,\cdots,n),$

since, for any meromorphic section $\zeta \in \Gamma(U, \mathcal{M}(V^*))$,

$$D\langle\zeta,\xi_j
angle = \langle \nabla_D\zeta,\xi_j
angle + \langle\zeta,\nabla_D\xi_j
angle$$
 and $\nabla_D\xi_j = 0.$

Thus we obtain the differential equation:

(2.1)
$$\det \begin{bmatrix} \langle \psi, \xi_1 \rangle & \cdots \langle \psi, \xi_n \rangle & y \\ \langle \overline{\Gamma}_D \psi, \xi_1 \rangle & \cdots \langle \overline{\Gamma}_D \psi, \xi_n \rangle & Dy \\ & \cdots & & \\ \langle (\overline{\Gamma}_D)^n \psi, \xi_1 \rangle & \cdots \langle (\overline{\Gamma}_D)^n \psi, \xi_n \rangle & D^n y \end{bmatrix} = 0.$$

§ 3. The Wronskian and the number of apparent singularities. We define the Wronskian $W(\psi, \nabla)$ as follows:

First, we define $W(\psi, \nabla_{D})$ by

$$W(\psi, \nabla_D) = \psi \wedge \nabla_D \psi \wedge \cdots \wedge (\nabla_D)^{n-1} \psi.$$

For another local coordinate (U', z'), we have on $U \cap U' \neq \phi$:

 $W(\psi, \nabla_D) = K^{n(n-1)/2} W(\psi, \nabla_{D'}),$

where D'=d/dz' and K=dz'/dz. It follows that a global meromorphic section $W(\psi, V)$ of the line bundle det $(V^*)\otimes \Omega^{n(n-1)/2}$ is well-defined, Ω being the canonical line bundle of the Riemann surface M:

 $W(\psi, \nabla) \in \Gamma(M, \mathcal{M}(\det(V^*) \otimes \Omega^{n(n-1)/2})).$

We have from (2.1)

$$\alpha_0 D^n y + \alpha_1 D^{n-1} y + \cdots + \alpha_n y = 0,$$

where

Since $\xi_1 \wedge \cdots \wedge \xi_n \neq 0$, this differential equation has singularities only at the zeros and poles of the Wronskian $W = W(\psi, \nabla)$. We see ([4]) that W is holomorphic on M-S and has a pole of order at most n(n-1)/2 at $a \in S$. The zeros of W are apparent singularities of the differential equation. We have

$$\begin{aligned} & \#(\text{zeros of } W) - \#(\text{poles of } W) \\ &= c_1 (\det (V^*) \otimes \Omega^{n(n-1)/2}) \\ &= c_1 (V^*) + 2^{-1} n(n-1) c_1(\Omega) \\ &= c_1 (V^*) + 2^{-1} n(n-1)(2g-2), \end{aligned}$$

where we consider the first Chern classes as integers:

 $\mathbf{c}_{_1} (\det (V^*) \otimes \mathcal{Q}^{n(n-1)/2}), \quad \mathbf{c}_{_1} (V^*), \quad \mathbf{c}_{_1} (\mathcal{Q}) \in \mathrm{H}^2(M, Z) \simeq Z.$

It follows that

Thus we arrive at the

Lemma 3.1. Let (V, Γ) be an extension of (V', Γ') such that the dual bundle V^* of V has a non-zero global holomorphic section $\psi \in \Gamma(M, \mathcal{O}(V^*))$. Then there exists a solution of the Riemann-Hilbert problem which has at most

$$c_1(V^*)+2^{-1}n(n-1)(m+2g-2)$$

apparent singularities.

§4. Proof of the theorem. We estimate the $c_1(V^*)$, show the existence of (V, V) with a non-zero global section $\psi \in \Gamma(M, \mathcal{O}(V^*))$ and then complete the proof. We construct an extension (V, V) of (V', V') in the following manner. Let (U, z) be a simply connected coordinate neighbourhood of $a \in S$ such that z(a)=0 and $U \cap S=\{a\}$. Let γ be a generator of the fundamental group $\pi_1(U-a)$ and $A_a \in GL(n, C)$ the image of γ by the local representation induced by ρ at a. Let B_a be a matrix such that

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(4.1)
$$A_a = \exp(-2\pi i B_a).$$

We define a meromorphic connection ∇^U on the trivial bundle $U \times C^n$ by $\nabla^U = d + z^{-1}B_a dz.$

By (4.1), we can patch $(V', \overline{V'})$ and $(U \times C^n, \overline{V'})$ together. In this way, we obtain an extension (V, \overline{V}) of $(V', \overline{V'})$ to M. By a straight computation, we have an important lemma.

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Lemma 4.2. The first Chern class $c_1(V)$ ($\in H^2(M, Z) \simeq Z$) is given by $c_1(V) = -\Sigma_{a \in S} \operatorname{tr}(B_a).$

If the Jordan normal form J_a of A_a is of the following form :

$$J_{a} = \begin{bmatrix} A_{1} & 0 \\ A_{2} & \\ & \ddots & \\ 0 & & A_{\mu} \end{bmatrix} \qquad A_{k} = \begin{bmatrix} \alpha_{k} & 1 & \\ & \ddots & \\ & & \ddots & 1 \\ & & \alpha_{k} \end{bmatrix} \in GL(\delta_{k}, C)$$
$$\delta_{1} + \cdots + \delta_{\mu} = n$$

then the Jordan normal form L_a of B_a can be written as:

$$L_{a} = egin{bmatrix} B_{1} & 0 \ B_{2} & \ & \ddots & \ & 0 & B_{\mu} \end{bmatrix} \qquad B_{k} = egin{bmatrix} eta_{k} & & * \ & \ddots & \ & 0 & & eta_{k} \end{bmatrix}.$$

Note that for each $\beta_k \in C$,

$$\alpha_k = \exp\left(-2\pi i\beta_k\right).$$

We can choose for each β_k an arbitray branch of the logarithm. If B'_a is another matrix such that

(4.3) $A_a = \exp(-2\pi i B'_a),$

then for some $\nu \in \mathbb{Z}$,

(4.4) $\operatorname{tr}(B_a') - \operatorname{tr}(B_a) = \nu d_a,$

where d_a is the greatest common divisor of $\delta_1, \dots, \delta_{\mu}$. Conversely, for any $\nu \in \mathbb{Z}$, there exists a matrix B'_a satisfying (4.3) and (4.4). From (4.2), we have the following lemma.

Lemma 4.5. For some $c \in \mathbb{Z}$, $c_1(V)$ can take any value in

$$\{c+\nu d\,|\,\nu\in Z\},\$$

where d is the greatest common divisor of the set $\{d_a | a \in S\}$. On the other hand, from the Riemann-Roch theorem, we deduce the following:

Lemma 4.6. If

$$c_1(V^*) \ge n(g-1)+1,$$

then there exists a non-zero section $\psi \in \Gamma(M, \mathcal{O}(V^*))$.

By (4.5), we can choose a pair (V, \overline{V}) such that

$$n(g-1)+1 \le c_1(V^*) \le n(g-1)+d.$$

By (3.1), (4.6) and this fact, we complete the proof. If the local representation at some point of S induced by ρ is semi-simple, then d=1 and we have Theorem 1. No. 7]

References

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