# 62. Generalized Hypergeometric Equations with Certain Finite Irreducible Monodromy Groups 

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In this paper we shall study the irreducibility condition for monodromy groups of generalized hypergeometric equations (say GHGE, for brevity) and determine, under a certain condition, their explicit forms when they are finite groups. Recently Beukers-Heckman [1] obtained independently the same condition ([1], Propositions 2.7 and 3.3) and determined the cases of finite monodromy groups generally by a method quite different from ours. So we shall state a remark about the latter from our standpoint.

Let us consider GHGE in the form of Okubo type (see [4]) ;

$$
(t I-B) \frac{d x}{d t}=A x
$$

where $t \in S$ (the Riemann sphere), $x={ }^{t}\left(x_{1}, \cdots, x_{n}\right)$ is a column $n$-vector, $I$ is the $n$ by $n$ unit matrix, $B$ is the $n$ by $n$ diagonal matrix $\operatorname{diag}(0, \cdots, 0,1)$ and $A$ is an $n$ by $n$ constant matrix;

$$
A=\left(\begin{array}{ccc|c}
-a_{1} & & 0 & 1 \\
0 & \ddots & 0 & \vdots \\
& -a_{n-1} & \dot{1} \\
\hline b_{1} \cdots & b_{n-1} & -a_{n}
\end{array}\right)
$$

with $n$ distinct eigenvalues $-\rho_{1},-\rho_{2}, \cdots,-\rho_{n}$. Moreover we assume the following;
(A) None of the quantities $a_{i}, a_{j}-a_{k}$ and $\rho_{l}-\rho_{m}(i, l, m=1, \cdots, n ; j$, $k=1,2, \cdots, n-1 ; j \neq k, l \neq m)$ is an integer. Moreover each $\rho_{j}$ is not a positive integer.

The equation (\#) is Fuchsian on $S$ with three regular singular points $t=0,1$ and $\infty$. From (A) there is no logarithmic solution.

Remark 1. Since (\#) is accessory parameter free, the coefficients $b_{i}$ are written in terms of $a_{j}$ and $\rho_{k}$ (see [4], §1). Eliminating $x_{1}, \cdots, x_{n-1}$ and setting $x=x_{n}$, we obtain

$$
\begin{equation*}
\left[\delta\left(\delta+a_{1}-1\right) \cdots\left(\delta+a_{n-1}-1\right)-t\left(\delta+\rho_{1}\right) \cdots\left(\delta+\rho_{n}\right)\right] x=0 \tag{b}
\end{equation*}
$$

where $\delta=t(d / d t)$. It is just the classical GHGE which has

$$
{ }_{n} F_{n-1}\binom{\rho_{1}, \cdots, \rho_{n} ; t}{a_{1}, \cdots, a_{n-1}}=\sum_{k=0}^{\infty} \frac{\left(\rho_{1}\right)_{k} \cdots\left(\rho_{n}\right)_{k}}{\left(a_{1}\right)_{k} \cdots\left(a_{n-1}\right)_{k} k!} t^{k}
$$

as its particular solution at $t=0$, where $(\alpha)_{k}=\alpha(\alpha+1) \cdots(\alpha+k-1)$ (for details, see [4], § 1 and § 5).

We first remind Theorem 2 in [4] which was originally obtained in [3].

Let $G$ be the monodromy group with respect to the specific fundamental system $X=\left(X_{1}, \cdots, X_{n}\right)$ of solutions of (\#) ([4], Theorem 1). It is a group representation of the fundamental group $\pi_{1}\left(S^{*}\right)\left(S^{*}=S \backslash\{0,1, \infty\}\right)$ into $G L(n, C)$ generated by the circuit matrices $\left\{M_{\lambda}\right\}_{\lambda=0,1}$ around 0 and 1. Let us denote $\exp \left(-2 \pi \sqrt{-1} a_{j}\right)$ and $\exp \left(-2 \pi \sqrt{-1} \rho_{j}\right)$ by $e_{j}$ and $f_{j}$, respectively. Then $M_{\lambda}$ is represented as
(1)

$$
M_{0}=\left(\begin{array}{cc|c}
e_{1} & & \left(e_{1}-1\right) p_{1} \\
0 & 0 & \vdots \\
& e_{n-1} & \left(e_{n-1}-1\right) p_{n-1} \\
\hline 0 \cdots 0 & \mathbf{1}
\end{array}\right)
$$

$$
M_{1}=\left(\begin{array}{cc|c}
1 & & 0 \\
0 & \cdot & \vdots \\
& 1 & \dot{0} \\
\hline\left(e_{n}-1\right) q_{1} \cdots\left(e_{n}-1\right) q-1 & e_{n}
\end{array}\right)
$$

Theorem 2 (Okubo-Takano). The following relations hold:

$$
\begin{align*}
p_{j} q_{j} & =-\frac{\prod\left(e_{j}-f_{k}\right)}{e_{j}\left(e_{j}-1\right)\left(e_{n}-1\right) \prod_{k \neq j}^{\prime}\left(e_{j}-e_{k}\right)}  \tag{2}\\
& =-\frac{\prod \sin \pi\left(a_{j}-\rho_{k}\right)}{\sin \pi a_{j} \cdot \sin \pi a_{n} \cdot \prod_{k \neq j}^{\prime} \sin \pi\left(a_{j}-a_{k}\right)},
\end{align*}
$$

where $\prod_{\text {and }} \prod^{\prime}$ are $\prod_{k=1}^{n}$ and $\prod_{k=1}^{n-1}$, respectively.
Remark 3. K. Okubo [2] determined each connection coefficients $p_{j}$ and $q_{j}$ explicitly (see also [4], Theorem 3). It is sufficient for our purpose to know only Theorem 2 because of the following arguments: Let us assume $p_{j} q_{j} \neq 0$ for all $j$. Then, if we take $q_{j}$ to any preassigned non-zero values, $p_{j}$ are determined uniquely by (2). Substituting those values into (1), we obtain new matrices, say $\bar{M}_{\lambda}$, and non-singular diagonal matrix $D$ determined uniquely up to a scalar multiple which satisfy $\left\langle\bar{M}_{0}, \bar{M}_{1}\right\rangle=D^{-1} G D$, where $\langle$,$\rangle is the group generated by \bar{M}_{\lambda}$ in $G L(n, C)$. Namely preassigned non-zero $q_{j}$ 's determine a group representation equivalent to $G$.

Now we state the irreducibility conditions for $G$ which was obtained independently in [1].

Theorem 4. $G$ is irreducible if and only if $e_{j} \neq f_{k} \neq 1$ for all $j=1,2$, $\cdots, n-1$ and $k=1,2, \cdots, n$, i.e., none of the quantities $a_{j}-\rho_{k}$ and $\rho_{k}$ is an integer (cf., assumption (A)).

From now on we assume that $G$ is irreducible. Let $M_{0 j}$ be a generalized reflection

$$
M_{0 j}=\left(\begin{array}{cccc}
1 & & & 0 \\
& \cdot & & 0 \\
\\
& \cdot & e_{j} & \\
\\
& 0 & & \left(e_{j}-1\right) p_{j} \\
& & & \cdot \\
\hline
\end{array}\right) \quad(j=1,2, \cdots, n-1)
$$

i.e., all the diagonal elements are 1 except for the $j$-th element which is $e_{j}$ and all off-diagonal elements are 0 except for the ( $j, n$ )-th element which is $\left(e_{j}-1\right) p_{j}$. Obviously we have $M_{0}=M_{01} \cdots M_{0, n-1}$. Let us denote $\left\langle M_{01}, \cdots\right.$, $\left.M_{0, n-1}, M_{1}\right\rangle$ by $\tilde{G}$ which contains $G=\left\langle M_{0}, M_{1}\right\rangle$ as its subgroup. From the assumption on $G, \tilde{G}$ is irreducible. If $\tilde{G}$ is finite, so is $G$, and $\tilde{G}$ must be a finite unitary reflection group with $n$ reflections as its generators. Such groups were completely classified by Shephard-Todd [7]. Let us denote the number $k(1 \leq k \leq 37)$ of the group in table VII in [7] by STk.

In the following our purpose is to determine all cases where $\tilde{G}$ to be finite when $n \geq 3$. For the case $n=2$ it is equivalent to determine the same cases on $G$ which was done by H. A. Schwarz [6]. From the above arguments we obtain $a_{j}, \rho_{j} \in \boldsymbol{Q}$. The invariance of the trace of $A$ implies $\sum_{j} a_{j}=\sum_{j} \rho_{j}$. On the other hand all $M_{0 j}$ and $M_{1}$ are written in terms of $e_{j}$ and $f_{k}$. Thus we may assume, by (A) and Theorem 4,

$$
\begin{equation*}
0<a_{j}, \rho_{\sim}<1 \quad(j=1,2, \cdots, n-1 ; k=1,2, \cdots, n) . \tag{3}
\end{equation*}
$$

Lemma 5. If $\tilde{G}(n \geq 3)$ is finite, then the dimension $n$ must be 3.
Let $H$ be the inverse matrix of $h$;

$$
h=\left[\begin{array}{lll}
1 & 0 & p_{1} \\
0 & 1 & p_{2} \\
q_{1} & q_{2} & 1
\end{array}\right]
$$

The existenece of $H$ follows from (3) and $a_{3} \notin \boldsymbol{Z}$, for $\operatorname{det} h=\Pi\left(\sin \pi \rho_{j} / \sin \pi a_{j}\right)$. We may assume $a_{1}<a_{2}$ and $\rho_{1}<\rho_{2}<\rho_{3}$.

Lemma 6. $H$ is taken to be hermitian by an appropriate choice of a diagonal matrix $D$ (Remark 3) if and only if $\rho_{1}<a_{1}<\rho_{2}<a_{2}<\rho_{3}$.

This condition leads $0<a_{3}<1$. The transformed groups of $G$ and $\tilde{G}$ by $D$ are written again, for simplicity, by $G$ and $\tilde{G}$, respectively,

Lemma 7. If $H$ is hermitian, then it is $G$ - and $\tilde{G}$-invariant. Moreover it is positive definite from (3).

Noting these facts in addition to the result ([8], 3.4) due to T. A. Springer we obtain

Theorem 8. $\tilde{G}$ is finite if and only if the set $\left(a_{1}, a_{2}, a_{3} ; \rho_{1}, \rho_{2}, \rho_{3}\right)$ under the condition (3) takes one of the following values up to the complex conjugate:
( I ) $\left(\frac{1}{3}, \frac{2}{3}, \frac{2}{3}, \frac{1}{9}, \frac{4}{9}, \frac{7}{9}\right) ; \tilde{G} \simeq S T 25$ and imprimitive $G \simeq(Z / 3 Z \times \boldsymbol{Z} / 3 Z$ $\times Z / 3 Z) \rtimes(Z / 3 Z)$.

$$
\begin{equation*}
\left(\frac{1}{2}, \frac{2}{3}, \frac{1}{3} ; \frac{1}{12}, \frac{7}{12}, \frac{5}{6}\right) ; G=\tilde{G} \simeq S T 26 . \tag{II}
\end{equation*}
$$

$$
\begin{equation*}
\left(\frac{1}{3}, \frac{1}{2}, \frac{1}{3} ; \frac{1}{18}, \frac{7}{18}, \frac{13}{18}\right) ; G=\tilde{G} \simeq S T 26 \tag{III}
\end{equation*}
$$

(IV) $\left(\frac{n}{m}, \frac{1}{2}, \frac{1}{2} ; \frac{n}{3 m}, \frac{m+n}{3 m}, \frac{2 m+n}{3 m}\right)$ for any $m, n \in N$ with $m \geq 3,1 \leq n$

$$
<m,(n, m)=1 ; \tilde{G} \simeq G(m, 1,3) \text { and }
$$

$$
\begin{equation*}
G \simeq\left\langle G\left(\frac{m}{2}, 1,3\right), \zeta_{m} I\right\rangle, \text { where } \zeta_{m}=\exp (2 \pi \sqrt{-1} / m), \text { if } m \text { is even } \tag{i}
\end{equation*}
$$

(ii) $G=\tilde{G}$ if $m$ is odd.

Remark 9. The following had been presumed from a differential equational point of view; if $G$ is a finite group, then so is $\tilde{G}$. However. the groups $\tilde{G}$, for examples, corresponding to the cases on the list 8.3 in [1] are all infinite from Theorem 8.

Remark 10. We found the above case (IV) intuitively and checked that there is no other finite imprimitive $\tilde{G}$ when $m \leq 6$ by using MACSYMA on DEC VAX-11/750. The same fact for any $m$ follows from Theorem 5.8 in [1] which is the only one result of [1] we used. Moreover, in the case (I), the natural reflection subgroup of $G$ acts reducibly on $C^{3}$ ([1], Theorem 5.3). We also note that (II) and (III) are (5/6)-shift of No. 9 and the complex conjugate of (1/2)-shift of No. 10 on the table 8.3 in [1], respectively.

Remark 11. Finally we have to point out that the condition stated in Lemma 6 leads $H$ to be Hermitian and that, in [1], the same implies the positive definiteness of invariant forms.

Almost all results in this paper were announced in the symposium at RIMS, October 1988 [5]. Details will appear in elsewhere.

## References

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