62. Generalized Hypergeometric Equations with Certain Finite Irreducible Monodromy Groups

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In this paper we shall study the irreducibility condition for monodromy groups of generalized hypergeometric equations (say GHGE, for brevity) and determine, under a certain condition, their explicit forms when they are finite groups. Recently Beukers-Heckman [1] obtained independently the same condition ([1], Propositions 2.7 and 3.3) and determined the cases of finite monodromy groups generally by a method quite different from ours. So we shall state a remark about the latter from our standpoint.

Let us consider GHGE in the form of Okubo type (see [4]);

$$(\ddagger) \qquad (tI-B)\frac{dx}{dt} = Ax,$$

where $t \in S$ (the Riemann sphere), $x = {}^{\iota}(x_1, \dots, x_n)$ is a column *n*-vector, *I* is the *n* by *n* unit matrix, *B* is the *n* by *n* diagonal matrix diag $(0, \dots, 0, 1)$ and *A* is an *n* by *n* constant matrix;

$$A \!=\! egin{pmatrix} -a_1 & & 1 & \ & \cdot & 0 & \ & 0 & \cdot & \ & -a_{n-1} & 1 & \ & & 1 & \ & & -a_n & \ & & 1 & \ & & b_1 \cdot \cdot \cdot b_{n-1} & -a_n \end{pmatrix}$$

with *n* distinct eigenvalues $-\rho_1, -\rho_2, \cdots, -\rho_n$. Moreover we assume the following;

(A) None of the quantities a_i , $a_j - a_k$ and $\rho_l - \rho_m$ $(i, l, m=1, \dots, n; j, k=1, 2, \dots, n-1; j \neq k, l \neq m)$ is an integer. Moreover each ρ_j is not a positive integer.

The equation (\ddagger) is Fuchsian on S with three regular singular points t=0, 1 and ∞ . From (A) there is no logarithmic solution.

Remark 1. Since (\ddagger) is accessory parameter free, the coefficients b_i are written in terms of a_j and ρ_k (see [4], § 1). Eliminating x_1, \dots, x_{n-1} and setting $x = x_n$, we obtain

(b) $[\delta(\delta+a_1-1)\cdots(\delta+a_{n-1}-1)-t(\delta+\rho_1)\cdots(\delta+\rho_n)]x=0$, where $\delta=t(d/dt)$. It is just the classical GHGE which has

$${}_{n}F_{n-1}\left(\begin{matrix}\rho_{1}, \cdots, \rho_{n}; t\\a_{1}, \cdots, a_{n-1}\end{matrix}\right) = \sum_{k=0}^{\infty} \frac{(\rho_{1})_{k} \cdots (\rho_{n})_{k}}{(a_{1})_{k} \cdots (a_{n-1})_{k}k!} t^{k}$$

as its particular solution at t=0, where $(\alpha)_k = \alpha(\alpha+1)\cdots(\alpha+k-1)$ (for details, see [4], §1 and §5).

We first remind Theorem 2 in [4] which was originally obtained in [3].

Let G be the monodromy group with respect to the specific fundamental system $X = (X_1, \dots, X_n)$ of solutions of (\ddagger) ([4], Theorem 1). It is a group representation of the fundamental group $\pi_1(S^*)$ ($S^* = S \setminus \{0, 1, \infty\}$) into GL(n, C) generated by the *circuit matrices* $\{M_i\}_{i=0,1}$ around 0 and 1. Let us denote $\exp(-2\pi\sqrt{-1}a_j)$ and $\exp(-2\pi\sqrt{-1}\rho_j)$ by e_j and f_j , respectively. Then M_i is represented as

(1)
$$M_{0} = \begin{pmatrix} e_{1} & (e_{1}-1)p_{1} \\ \vdots & 0 & \vdots \\ 0 & \vdots & \vdots \\ e_{n-1} & (e_{n-1}-1)p_{n-1} \\ \hline 0 & \cdots & 0 & 1 \\ \end{pmatrix},$$
$$M_{1} = \begin{pmatrix} 1 & 0 & 0 \\ \vdots & 0 & 0 \\ 0 & \ddots & 0 & 0 \\ \hline 1 & 0 & 0 & \vdots \\ 0 & \ddots & 1 & 0 \\ \hline (e_{n}-1)q_{1} \cdots (e_{n}-1)q_{n}-1 & e_{n} \\ \end{pmatrix}.$$

Theorem 2 (Okubo-Takano). The following relations hold:

(2)
$$p_{j}q_{j} = -\frac{\prod (e_{j} - f_{k})}{e_{j}(e_{j} - 1)(e_{n} - 1) \prod'_{k \neq j}(e_{j} - e_{k})} = -\frac{\prod \sin \pi(a_{j} - \rho_{k})}{\sin \pi a_{j} \cdot \sin \pi a_{n} \cdot \prod'_{k \neq j} \sin \pi(a_{j} - a_{k})},$$

where \prod and \prod' are $\prod_{k=1}^{n}$ and $\prod_{k=1}^{n-1}$, respectively.

Remark 3. K. Okubo [2] determined each connection coefficients p_j and q_j explicitly (see also [4], Theorem 3). It is sufficient for our purpose to know only Theorem 2 because of the following arguments: Let us assume $p_j q_j \neq 0$ for all j. Then, if we take q_j to any preassigned non-zero values, p_j are determined uniquely by (2). Substituting those values into (1), we obtain new matrices, say \overline{M}_{λ} , and non-singular diagonal matrix Ddetermined uniquely up to a scalar multiple which satisfy $\langle \overline{M}_0, \overline{M}_1 \rangle = D^{-1}GD$, where \langle , \rangle is the group generated by \overline{M}_{λ} in GL(n, C). Namely preassigned non-zero q_j 's determine a group representation equivalent to G.

Now we state the irreducibility conditions for G which was obtained independently in [1].

Theorem 4. G is irreducible if and only if $e_j \neq f_k \neq 1$ for all $j=1, 2, \dots, n-1$ and $k=1, 2, \dots, n$, i.e., none of the quantities $a_j - \rho_k$ and ρ_k is an integer (cf., assumption (A)).

From now on we assume that G is *irreducible*. Let M_{0j} be a generalized reflection

$$M_{0j} = \begin{pmatrix} 1 & & 0 \\ \cdot & 0 & \vdots \\ & e_j & (e_j - 1)p_j \\ 0 & \cdot & \vdots \\ & & \cdot & 1 \end{pmatrix} \qquad (j = 1, 2, \dots, n-1),$$

i.e., all the diagonal elements are 1 except for the *j*-th element which is e_j and all off-diagonal elements are 0 except for the (j, n)-th element which is $(e_j-1)p_j$. Obviously we have $M_0 = M_{01} \cdots M_{0,n-1}$. Let us denote $\langle M_{01}, \cdots, M_{0,n-1}, M_1 \rangle$ by \tilde{G} which contains $G = \langle M_0, M_1 \rangle$ as its subgroup. From the assumption on G, \tilde{G} is irreducible. If \tilde{G} is finite, so is G, and \tilde{G} must be a finite unitary reflection group with n reflections as its generators. Such groups were completely classified by Shephard-Todd [7]. Let us denote the number $k(1 \leq k \leq 37)$ of the group in table VII in [7] by STk.

In the following our purpose is to determine all cases where \tilde{G} to be finite when $n \ge 3$. For the case n=2 it is equivalent to determine the same cases on G which was done by H. A. Schwarz [6]. From the above arguments we obtain a_j , $\rho_j \in Q$. The invariance of the trace of A implies $\sum_j a_j = \sum_j \rho_j$. On the other hand all M_{0j} and M_1 are written in terms of e_j and f_k . Thus we may assume, by (A) and Theorem 4,

(3) $0 < a_j, \rho_k < 1$ $(j=1, 2, \dots, n-1; k=1, 2, \dots, n).$

Lemma 5. If \tilde{G} $(n \ge 3)$ is finite, then the dimension n must be 3.

Let H be the inverse matrix of h;

$$h = \begin{bmatrix} 1 & 0 & p_1 \\ 0 & 1 & p_2 \\ q_1 & q_2 & 1 \end{bmatrix}.$$

The existence of *H* follows from (3) and $a_3 \notin \mathbb{Z}$, for det $h = \prod (\sin \pi \rho_j / \sin \pi a_j)$. We may assume $a_1 < a_2$ and $\rho_1 < \rho_2 < \rho_3$.

Lemma 6. *H* is taken to be hermitian by an appropriate choice of a diagonal matrix D (Remark 3) if and only if $\rho_1 < a_1 < \rho_2 < a_2 < \rho_3$.

This condition leads $0 < a_3 < 1$. The transformed groups of G and \tilde{G} by D are written again, for simplicity, by G and \tilde{G} , respectively,

Lemma 7. If H is hermitian, then it is G- and \tilde{G} -invariant. Moreover it is positive definite from (3).

Noting these facts in addition to the result ([8], 3.4) due to T.A. Springer we obtain

Theorem 8. \tilde{G} is finite if and only if the set $(a_1, a_2, a_3; \rho_1, \rho_2, \rho_3)$ under the condition (3) takes one of the following values up to the complex conjugate:

- (I) $\left(\frac{1}{3}, \frac{2}{3}, \frac{2}{3}; \frac{1}{9}, \frac{4}{9}, \frac{7}{9}\right); \tilde{G} \simeq ST25 \text{ and imprimitive } G \simeq (Z/3Z \times Z/3Z) \times (Z/3Z).$
- (II) $\left(\frac{1}{2}, \frac{2}{3}, \frac{1}{3}; \frac{1}{12}, \frac{7}{12}, \frac{5}{6}\right); G = \tilde{G} \simeq ST26.$
- (III) $\left(\frac{1}{3}, \frac{1}{2}, \frac{1}{3}; \frac{1}{18}, \frac{7}{18}, \frac{13}{18}\right); G = \tilde{G} \simeq ST26.$
- (IV) $\left(\frac{n}{m}, \frac{1}{2}, \frac{1}{2}; \frac{n}{3m}, \frac{m+n}{3m}, \frac{2m+n}{3m}\right)$ for any $m, n \in \mathbb{N}$ with $m \ge 3, 1 \le n$ $< m, (n, m) = 1; \tilde{G} \simeq G(m, 1, 3)$ and

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- (i) $G \simeq \langle G(\frac{m}{2}, 1, 3), \zeta_m I \rangle$, where $\zeta_m = \exp(2\pi\sqrt{-1}/m)$, if m is even,
- (ii) $G = \tilde{G}$ if m is odd.

Remark 9. The following had been presumed from a differential equational point of view; if G is a finite group, then so is \tilde{G} . However, the groups \tilde{G} , for examples, corresponding to the cases on the list 8.3 in [1] are all infinite from Theorem 8.

Remark 10. We found the above case (IV) intuitively and checked that there is no other finite imprimitive \tilde{G} when $m \leq 6$ by using MACSYMA on DEC VAX-11/750. The same fact for any m follows from Theorem 5.8 in [1] which is the only one result of [1] we used. Moreover, in the case (I), the natural reflection subgroup of G acts reducibly on C^3 ([1], Theorem 5.3). We also note that (II) and (III) are (5/6)-shift of No. 9 and the complex conjugate of (1/2)-shift of No. 10 on the table 8.3 in [1], respectively.

Remark 11. Finally we have to point out that the condition stated in Lemma 6 leads H to be Hermitian and that, in [1], the same implies the positive definiteness of invariant forms.

Almost all results in this paper were announced in the symposium at RIMS, October 1988 [5]. Details will appear in elsewhere.

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