75. Structural Operators for Linear Delay-differential Equations in Hilbert Space

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Let H and V be complex Hilbert spaces such that V is a dense subspace of H and the inclusion mapping of V into H is continuous. The norms of H and V are denoted by | | and || || respectively. Identifying H with its antidual we may write $V \subset H \subset V^*$. We use the notation $(\ ,\)$ to denote both the innerproduct of H and the pairing between V^* and V. For a couple of Hilbert spaces X and Y the notation B(X,Y) denotes the totality of bounded linear mappings of X into Y, and B(X) = B(X,X).

Let a(u, v) be a sesquilinear form defined on $V \times V$. Suppose that there exist positive constants C and c such that

$$|a(u, v)| \le C \|u\| \|v\|, \quad \text{Re } a(u, u) \ge c \|u\|^2$$

for any $u, v \in V$. Let $-A_0 \in B(V, V^*)$ be the operator associated with this sesquilinear form: $(-A_0u, v) = a(u, v)$, $u, v \in V$. The realization of A_0 in H which is the restriction of A_0 to $D(A_0) = \{u \in V : A_0u \in H\}$ is also denoted by the same letter A_0 . It is known that A_0 generates an analytic semigroup in both H and V^* .

Let A_i , i=1,2, be operators in $B(V,V^*)$. Then, $A_iA_0^{-1} \in B(V^*)$ for i=1,2. We assume that these two operators map H to itself and $A_iA_0^{-1} \in B(H)$, i=1,2. We assume also that $A_i^*(A_0^*)^{-1} \in B(H)$, i=1,2, where A_0^* , $A_i^* \in B(V,V^*)$ are the adjoint operators of A_0 , A_i .

Let a(s) be a real valued Hölder continuous function in the interval [-h,0], where h is some positive number. We consider the following delay-differential equation

(1)
$$du(t)/dt = A_0 u(t) + A_1 u(t-h) + \int_{-h}^{0} a(s) A_2 u(t+s) ds$$

which is considered as an equation in both H and V^* . According to [3] the fundamental solution W(t) of (1) can be constructed.

It is easily seen that the space

$$\left\{ f \in V^* : \int_0^\infty \|A_0 \exp(tA_0) f\|_*^2 dt < \infty \right\}$$

coincides with H, where $\| \|_*$ is the norm of V^* . Hence, in view of [1] the semigroup S(t) in $Z=H\times L^2(-h,0;V)$ is defined by

$$S(t)g = (u(t; g), u(t + \cdot; g)), \qquad g = (g^0, g^1) \in Z$$

where u(t; g) is the mild solution of (1) (cf. [2]) satisfying the initial condition

$$u(0; q) = q^0$$
, $u(s; q) = q^1(s)$, $-h \le s < 0$.

Similarly, the semigroup $S_T(t)$ in the same space Z is defined for the adjoint equation

$$dv(t)/dt = A_0^*v(t) + A_1^*v(t-h) + \int_{-h}^0 a(s)A_2^*v(t+s) ds.$$

The first structural operator F is defined by

$$Fg\!=\!([Fg]^{\scriptscriptstyle 0},[Fg]^{\scriptscriptstyle 1}), \qquad g\!=\!(g^{\scriptscriptstyle 0},g^{\scriptscriptstyle 1})\in \!Z, \ [Fg]^{\scriptscriptstyle 0}\!=\!g^{\scriptscriptstyle 0}, \qquad [Fg]^{\scriptscriptstyle 1}\!=\!A_{\scriptscriptstyle 1}g^{\scriptscriptstyle 1}(-h\!-\!s)\!+\!\int_{-h}^s\!a(au)A_{\scriptscriptstyle 2}g^{\scriptscriptstyle 1}(au\!-\!s)d au$$

(cf. [2]). As is easily seen $F \in B(Z, Z^*)$, where $Z^* = H \times L^2(-h, 0; V^*)$.

Theorem 1. $FS(t) = S_T^*(t)F$, $S^*(t)F^* = F^*S_T(t)$, $t \ge 0$.

The above theorem can be established as Theorem 4.2 of [2] with the aid of Theorem 2 below. Let G be the second structural operator (cf. [2]):

$$Gg = ([Gg]^0, [Gg]^1), \qquad g = (g^0, g^1) \in Z^*,$$

$$[Gg]^{1}(s) = W(s+h)g^{0} + \int_{-h}^{0} W(s+h+\tau)g^{1}(\tau)d\tau, \qquad [Gg]^{0} = [Gg]^{1}(0),$$

where W(t) is the fundamental solution of (1). It is easy to see that $G \in B(Z^*, Z)$.

Theorem 2. $S(t)G = GS_T^*(t), G^*S^*(t) = S_T(t)G^*.$

Example. Let A_0 be a strongly elliptic linear partial differential operator with the Dirichlet boundary condition, and A_i , i=1,2, be linear differential operators of the same order as A_0 . Then, the hypothesis of the above theorems are satisfied if their coefficients are sufficiently smooth.

References

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