

### 35. Entropy of Random Dynamical Systems

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**1. Introduction.** Let  $(\Omega, \mathcal{F}, P)$  be a probability space and let  $\sigma$  be a  $P$ -preserving transformation. Given a non-atomic Lebesgue space  $(M, \mathcal{B}(M), \mu)$  and a standard measurable space  $(S, \mathcal{B}(S))$ , consider a  $\mathcal{B}(M) \times \mathcal{B}(S)$ -measurable map  $f: S \times M \ni (s, x) \rightarrow f_s x \in M$  and a stationary sequence of  $S$ -valued random variables  $\{\hat{\xi}_n\}_{n=1}^\infty$  defined by  $\hat{\xi}_n(\omega) = \xi \circ \sigma^{n-1}(\omega)$  for  $n \geq 1$ , where  $\xi$  is an  $S$ -valued random variable. The sequence  $X = \{X_n(\omega)\}_{n=0}^\infty$  of random maps which are defined by  $X_n(\omega) = f_{\hat{\xi}_n(\omega)} \circ X_{n-1}(\omega)$  ( $n \geq 1$ ) and  $X_0(\omega) = id_M$ , is called a random dynamical system. The purpose of this paper is to define the concept of the (metrical) entropy of such a random dynamical system under the hypothesis that the map  $f_s: M \rightarrow M$  preserves  $\mu$  for each  $s \in S$ .

**2. Preliminaries.** In what follows, we always identify two subsets of  $M$  which coincide with each other up to  $\mu$ -measure zero. Let  $\alpha$  be a countable measurable partition of  $M$  and  $\mathcal{B}$  be a sub- $\sigma$ -algebra of  $\mathcal{B}(M)$  (see [3, Ch. 1]).

Put  $I(\alpha | \mathcal{B}) = -\sum_{A \in \alpha} \log \mu(A | \mathcal{B})$  where  $\mu(A | \mathcal{B})$  denotes the conditional probability of an event  $A$  given  $\mathcal{B}$ , and put  $H(\alpha | \mathcal{B}) = \int_M I(\alpha | \mathcal{B})(x) \mu(dx)$ . They are called the conditional information of  $\alpha$  given  $\mathcal{B}$  and the conditional entropy of  $\alpha$  given  $\mathcal{B}$  respectively. If  $\mathcal{B} = \mathcal{N} = \{\phi, M\}$ ,  $I(\alpha | \mathcal{N}) = -\sum_{A \in \alpha} \mathbf{1}_A \log \mu(A)$  is denoted by  $I(\alpha)$  and  $H(\alpha | \mathcal{N}) = -\sum_{A \in \alpha} \mu(A) \log \mu(A)$  denoted by  $H(\alpha)$ . They are called the information of  $\alpha$  and the entropy of  $\alpha$  respectively. For a countable measurable partition  $\beta$  of  $M$ , let  $I(\alpha | \beta)$  denote  $I(\alpha | \mathcal{B}(\beta))$  and  $H(\alpha | \beta)$  denote  $H(\alpha | \mathcal{B}(\beta))$  where  $\mathcal{B}(\beta)$  is the sub- $\sigma$ -algebra of  $\mathcal{B}(M)$  generated by the elements of  $\beta$ . Let  $Z$  be the set of all countable measurable partition with finite entropy. It is well-known that  $Z$  becomes a complete separable metric space with metric  $\rho$  defined by  $\rho(\alpha, \beta) = H(\alpha | \beta) + H(\beta | \alpha)$  for  $\alpha, \beta \in Z$  (see [4]). For  $\alpha, \beta \in Z$  and a measurable map  $\tau: M \rightarrow M$ , let  $\alpha \vee \beta$  denote the measurable partition  $\{A \cap B; A \in \alpha, B \in \beta\}$  and  $\tau^{-1}\alpha$  denote the partition  $\{\tau^{-1}A; A \in \alpha\}$ .

**3. The main theorems.** Unless otherwise stated we use the same notations as before and we assume that  $f_s$  preserves the measure  $\mu$  for each  $s \in S$ . First, we prove the following:

**Theorem 1.** *There is a  $C(Z)$ -valued random variable  $h(\alpha, \omega)$  such that*

$$h(\alpha, \omega) = \lim_{n \rightarrow \infty} \frac{1}{n} H\left(\bigvee_{i=0}^{n-1} X_i^{-1}(\omega)\alpha\right) \quad P\text{-a.e.}$$

and

$$|h(\alpha, \omega) - h(\beta, \omega)| \leq \rho(\alpha, \beta) \quad P\text{-a.e.}$$

for any  $\alpha, \beta \in Z$ , where  $C(Z)$  denotes the space of all real valued continuous functions on  $Z$ .

*Proof.* For fixed  $\alpha \in Z$ , it is easy to see that

$$H\left(\bigvee_{i=0}^{n+m-1} X_i^{-1}(\omega)\alpha\right) \leq H\left(\bigvee_{i=0}^{n-1} X_i^{-1}(\omega)\alpha\right) + H\left(\bigvee_{i=0}^{m-1} X_i^{-1}(\sigma^n(\omega))\alpha\right).$$

Therefore the limit  $\bar{h}(\alpha, \omega) = \lim_{n \rightarrow \infty} (1/n) H(\bigvee_{i=0}^{n-1} X_i^{-1}(\omega)\alpha)$  exists  $P$ -a.e. in virtue of the subadditive ergodic theorem (see Theorem 10. 1 in [5, p. 231]). On the other hand, in the same way as Corollary 4.12.1 in [5, p. 91] we can prove that  $|\bar{h}(\alpha, \omega) - \bar{h}(\beta, \omega)| \leq \rho(\alpha, \beta)$   $P$ -a.e. for fixed  $\alpha, \beta \in Z$ . If we notice that  $Z$  is separable, we can take a continuous version  $h(\alpha, \omega)$  of  $\bar{h}(\alpha, \omega)$ . This completes the proof.

This theorem enables us to define the following :

**Definition.** The (metrical) entropy of the random dynamical system  $X = \{X_n\}_{n=0}^\infty$  is the random variable which is given by

$$h(\omega) = \sup_{\alpha \in Z} h(\alpha, \omega).$$

**Remark.** If the transformation  $\sigma$  is ergodic then  $h(\alpha, \omega)$  is constant  $P$ -a.e. since it is  $\sigma$ -invariant. In this case we write  $h(\alpha)$  and  $h$  instead of  $h(\alpha, \omega)$  and  $h(\omega)$  respectively.

Next we give some properties of the entropy defined above.

**Theorem 2** (A Kolmogolov-Sinai type theorem). Assume that the smallest sub  $\sigma$ -algebra which contains all  $\mathcal{B}(\bigvee_{i=0}^n X_i^{-1}(\omega)\alpha)$  coincides with  $\mathcal{B}(M)$   $P$ -a.e. for some  $\alpha \in Z$ . Then we have  $h(\omega) = h(\alpha, \omega)$   $P$ -a.e.

*Proof.* For any positive integer  $m$  and any  $\beta \in Z$ , we have

$$\begin{aligned} H\left(\bigvee_{i=0}^{k-1} X_i^{-1}(\omega)\beta\right) &\leq H\left(\bigvee_{i=0}^{k-1} X_i^{-1}(\omega)\bigvee_{j=0}^{m-1} X_j^{-1}(\sigma^i\omega)\alpha\right) \\ &\quad + H\left(\bigvee_{i=0}^{k-1} X_i^{-1}(\omega)\beta \middle| \bigvee_{i=0}^{k-1} X_i^{-1}(\omega)\bigvee_{j=0}^{m-1} X_j^{-1}(\sigma^i\omega)\alpha\right) \\ &\leq H\left(\bigvee_{i=0}^{m+k-2} X_i^{-1}(\omega)\alpha\right) + \sum_{i=0}^{k-1} H\left(\beta \middle| \bigvee_{j=0}^{m-1} X_j^{-1}(\sigma^j\omega)\alpha\right). \end{aligned}$$

Here the first inequality follows from the fact that  $H(\beta_1 \vee \beta_2) = H(\beta_1) + H(\beta_2 | \beta_1)$  and the second inequality follows from the fact that

$$\bigvee_{i=0}^{m+k-2} X_i^{-1}(\omega)\alpha = \bigvee_{i=0}^{k-1} X_i^{-1}(\omega)\bigvee_{j=0}^{m-1} X_j^{-1}(\sigma^i\omega)\alpha$$

and  $H(\bigvee_{i=1}^n \alpha_i | \bigvee_{i=1}^n \beta_i) \leq \sum_{i=1}^n H(\alpha_i | \beta_i)$  for any  $\{\alpha_i\}_{i=1}^n, \{\beta_i\}_{i=1}^n \subset Z$ . Putting  $f_m(\omega) = H(\beta | \bigvee_{j=0}^{m-1} X_j^{-1}(\omega)\alpha)$ , we have

$$H\left(\bigvee_{i=0}^{k-1} X_i^{-1}(\omega)\beta\right) \leq H\left(\bigvee_{i=0}^{m+k-2} X_i^{-1}(\omega)\alpha\right) + \sum_{i=0}^{k-1} f_m(\sigma^i\omega).$$

Therefore in virtue of the ergodic theorem, we have

$$h(\beta, \omega) \leq h(\alpha, \omega) + \bar{f}_m(\omega) \quad P\text{-a.e.},$$

where  $\bar{f}_m(\omega) = \lim_{n \rightarrow \infty} (1/n) \sum_{j=0}^{n-1} f_m(\sigma^j\omega)$ . From the assumption, we can show that  $f_m \rightarrow 0$  ( $m \rightarrow \infty$ )  $P$ -a.e. Thus we have  $E\bar{f}_m = Ef_m \rightarrow 0$  ( $m \rightarrow \infty$ ). Since  $\bar{f}_m \geq 0$ , we may assume that  $\bar{f}_m \rightarrow 0$   $P$ -a.e. ( $m \rightarrow \infty$ ). This implies that  $h(\alpha, \omega) = h(\omega)$   $P$ -a.e.

For a random dynamical system we introduce a transformation  $T : M \times \Omega \rightarrow M \times \Omega$  defined by

$$T(x, \omega) = (X_1(\omega)x, \sigma\omega) \quad \text{for } (x, \omega) \in M \times \Omega.$$

It is easy to see that the product measure  $\mu \times P$  is  $T$ -invariant. For  $\alpha \in Z$ , put  $f(x, \omega) = \lim_{n \rightarrow \infty} I(\alpha | \bigvee_{i=1}^n X_i^{-1}(\omega)\alpha)(x)$  if the limit exists,  $= \infty$  otherwise and  $f_\alpha(x, \omega) = \lim_{n \rightarrow \infty} (1/n) \sum_{i=0}^{n-1} f \circ T^i(x, \omega)$  if the limit exists,  $= \infty$  otherwise. In particular, these limits exist  $\mu \times P$ -a.e. and in  $L^1(\mu \times P)$  in virtue of Doob's theorem and the ergodic theorem. Then we have the following random version of the Shannon-McMillan Theorem.

**Theorem 3.**  $(1/n) I(\bigvee_{i=0}^n X_i^{-1}(\omega)\alpha) \rightarrow f_\alpha(x, \omega)$   $\mu \times P$ -a.e. and in  $L^1(\mu \times P)$  as  $n \rightarrow \infty$ .

**Corollary.** *If the transformation  $T$  is ergodic then  $-(1/n) \log \mu(A_n(x, \omega)) \rightarrow h(\alpha)$   $P$ -a.e., where  $A_n(x, \omega)$  is the element of  $\bigvee_{i=0}^{n-1} X_i^{-1}(\omega)\alpha$  which contains  $x \in M$ .*

**Remarks.** 1) Since the measure theoretical dynamical system  $(\sigma, P)$  is a factor of  $(T, \mu \times P)$ ,  $\sigma$  is ergodic if  $T$  is ergodic (see [4]). This is the reason why we use the notation  $h(\alpha)$  in the Corollary.

2) Consider the case  $\{\xi_n\}_{n=1}^\infty$  are mutually independent and the  $\sigma$ -algebra  $\mathcal{F}$  is generated by them. Then,  $T$  is ergodic if the measure theoretical dynamical system  $(f_{\xi(\omega)}, \mu)$  is ergodic with positive  $P$ -measure.

*Proof of Theorem 3.* It is not hard to see that

$$\begin{aligned} I\left(\bigvee_{i=0}^{n-1} X_i^{-1}(\omega)\alpha\right)(x) &= I\left(\alpha \left| \bigvee_{i=1}^{n-1} X_i^{-1}(\omega)\alpha\right.\right)(x) + \dots \\ &+ I\left(\alpha \left| \bigvee_{i=1}^{n-2} X_i^{-1}(\sigma\omega)\alpha\right.\right)(X_1(\omega)x) + \dots + I(\alpha)(X_{n-1}(\omega)x). \end{aligned}$$

Put  $f_k(x, \omega) = I(\alpha | \bigvee_{i=1}^{k-1} X_i^{-1}(\omega)\alpha)(x)$ . Clearly, we have

$$\begin{aligned} \left| \frac{1}{n} I\left(\bigvee_{i=0}^{n-1} X_i^{-1}(\omega)\alpha\right) - f_\alpha(x, \omega) \right| &\leq \frac{1}{n} \sum_{i=0}^{n-1} |f_{n-1} \circ T^i(x, \omega) - f(x, \omega)| \\ &+ \left| \frac{1}{n} \sum_{i=0}^{n-1} f \circ T^i(x, \omega) - f_\alpha(x, \omega) \right|. \end{aligned}$$

The last term goes to 0  $\mu \times P$ -a.e. and in  $L^1(\mu \times P)$  as  $n \rightarrow \infty$ . We must prove that

$$\limsup_{n \rightarrow \infty} \frac{1}{n} \sum_{i=0}^{n-1} g_{n-i} \circ T^i(x, \omega) = 0$$

and

$$\limsup_{n \rightarrow \infty} \frac{1}{n} \sum_{i=0}^{n-1} \int g_{n-i} \circ T^i(x, \omega) \mu(dx) P(d\omega) = 0,$$

where  $g_k = f_k - f$ . But this can be done in the same way as the proof of Theorem 2.5 in [3, p. 21].

**4. Other results.** If  $M$  has a topologically rich structure we can obtain the following :

**Theorem 4** (A random version of Katok's theorem [2]). *We assume that  $M$  is a compact metric space with metric  $d$  and  $f_s$  is a continuous map on  $M$  for each  $s \in S$ . We further assume that the transformation  $T$ , which*

is introduced in the previous section, is ergodic. Then we have, for  $\delta > 0$ ,

$$h = \lim_{\varepsilon \downarrow 0} \limsup_{n \rightarrow \infty} \frac{1}{n} \log N(n, \varepsilon, \delta, \omega) = \lim_{\varepsilon \downarrow 0} \liminf_{n \rightarrow \infty} \frac{1}{n} \log N(n, \varepsilon, \delta, \omega).$$

Here  $N(n, \varepsilon, \delta, \omega)$  stands for the minimal number of  $\varepsilon$ -balls in the  $d_{n,\omega}$ -metric which cover the set of  $\mu$ -measure more than or equal to  $1 - \delta$ , where  $d_{n,\omega}$ -metric is defined by

$$d_{n,\omega}(x, y) = \max_{0 \leq i \leq n-1} d(X_i(\omega)x, X_i(\omega)y) \quad \text{for } x, y \in M.$$

**Theorem 5** (A random version of Kushnirenko's theorem). Assume that  $M$  is a compact smooth manifold without boundary and  $f_s$  is a  $C^1$ -differentiable map on  $M$  for each  $s \in S$ . If

$$E \log^+ \|f_{\xi(\cdot)}\|_{C^1} = \int \log^+ \|f_{\xi(\omega)}\|_{C^1} P(d\omega) < \infty,$$

then we have  $h(\omega) < \infty$   $P$ -a.e., where  $\|\cdot\|_{C^1}$  denotes the  $C^1$ -norm of a  $C^1$ -differential map  $\cdot$ .

The proofs of Theorem 4, and Theorem 5 are not difficult but complicated and quite long because we must modify the proofs of deterministic cases. For example, for the proof of Theorem 4, we need a modification of the proof of Theorem 1.1 in [2] and for the proof of Theorem 5, we need modifications of the proof of Corollary to Lemma 18.2 in [1] and the proof of Theorem 7.5 in [5, p. 181]. Detailed proofs of theorems in this paper will be given elsewhere.

## References

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