

18. On some Schrödinger Type Equations

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1. Introduction. We are concerned with the following evolution equation defined for $(x, t) \in R^n \times R^1$:

$$(1.1) \quad L(u) = i\partial_t u + \sum_{j,k} \partial_j (a_{jk}(x) \partial_k u) + \sum_j b_j(x) \partial_j u + c(x)u = f(x, t),$$

with initial data $u_0(x) \in L^2(R^n)$ at $t=0$, where $\partial_j = \partial/\partial x_j$ and $a_{jk}(x)$ are real-valued and bounded with all their derivatives with $a_{jk}(x) = a_{kj}(x)$. Moreover we assume the uniform ellipticity: $\sum a_{jk}(x) \xi_j \xi_k \geq \delta |\xi|^2$ ($\delta > 0$).

Recently J. Takeuchi treated this type problem for more general equations ([3]). He proposes a (sufficient) condition for the equation (1.1) to be L^2 -wellposed. This terminology means the following: For any initial data $u_0(x) \in L^2(R^n)$, and any continuous function $t \mapsto f(\cdot, t)$ in L^2 , the equation (1.1) has a unique solution $u(\cdot, t)$, continuous in L^2 , so that by Banach's closed graph theorem there exists a constant C such that for any $t \in [-1, 1]$, it holds

$$(1.2) \quad \|u(t)\| \leq C \left(\|u(0)\| + \left| \int_0^t \|f(s)\| ds \right| \right).$$

The purpose of this note is to investigate the necessary condition for this problem. Let

$$a(x, \xi) = \sum a_{jk}(x) \xi_j \xi_k.$$

We consider the integral curves, called bicharacteristic strips, of the corresponding Hamilton-Jacobi equation

$$(1.3) \quad \begin{cases} \frac{dx}{dt} = a_\xi(x, \xi) \\ \frac{d\xi}{dt} = -a_x(x, \xi). \end{cases}$$

Denote its integral curve issuing from (x_0, ξ^0) at $t=0$ by $(x(x_0, t, \xi^0), \xi(x_0, t, \xi^0))$. Then the condition that we propose is:

(B) $\operatorname{Re} \int_0^t \sum_j b_j(x(x_0, s, \xi^0)) \xi_j(x_0, s, \xi^0) ds$ remain bounded for all $(x_0, \xi^0) \in R^n \times R^n \setminus \{0\}$ and $t \in R^1$.

We assume here the following:

(A) For any $(\xi^0, t) \in R^n \setminus \{0\} \times R^1$ fixed, the mapping $x_0 \mapsto x(x_0, t, \xi^0)$ is a diffeomorphism from R^n onto R^n .

Let us note that, under this assumption, there exists the global phase function $S(x, t, \xi^0)$, which is defined as the solution of Hamilton-Jacobi's equation

$$(1.4) \quad S_t + a(x, S_x) = 0,$$

with $S(x, 0, \xi^0) = x\xi^0$. Then we have

Theorem. *Under the assumption (A), the condition (B) is necessary for the L^2 -wellposedness of (1.1).*

Remark. We assume $b_j(x) \in C^1$ and $c(x)$ is locally bounded. If we are concerned only with forward Cauchy problem, the condition (B) should be replaced by

(B)₊ $\operatorname{Re} \int_0^t b(x(x_0, s, \xi^0)) \xi(x_0, s, \xi^0) ds$ remain bounded from below for all $(x_0, \xi^0) \in R^n \times R^n \setminus \{0\}$ and $t \geq 0$.

For the proof, we use asymptotic solutions which are fairly familiar (see [1], [2]). In other words, we look at wave packets moving along classical trajectories corresponding to Hamiltonian $a(x, \xi)$.

2. Approximate solutions. We show the necessity of (B)₊. Let us suppose (B)₊ is violated. Then there exist $x_0^0 (= (x_{0,1}, \dots, x_{0,n}))$ and $\xi^0 \in R^n \setminus \{0\}$ and $t_1 > 0$, such that

$$(2.1) \quad \operatorname{Re} \int_0^{t_1} b(x(x_0^0, s, \xi^0)) \xi(x_0^0, s, \xi^0) ds \leq -\log(2C),$$

where C is the constant in (1.2). We seek an approximate solution of the form

$$\begin{aligned} u(x, t) &= e^{iS(x,t,\xi^0)} v(x, t; \xi^0). \\ e^{-iS} [i\partial_t + \sum \partial_j a_{jk}(x) \partial_k + \sum b_j(x) \partial_j] (e^{iS} v) \\ &= [-S_t + i\partial_t + \sum (\partial_j + iS_{x_j}) a_{jk}(x) (\partial_k + iS_{x_k}) + \sum b_j (iS_{x_j} + \partial_j)] v(x, t, \xi^0). \end{aligned}$$

Taking account of (1.4), [...] becomes

$$\begin{aligned} i[\partial_t + 2 \sum_{j,k} a_{jk}(x) S_{x_j} \partial_k + \sum \partial_j (\sum_k a_{jk}(x) S_{x_k}) + \sum b_j(x) S_{x_j}] v \\ + \sum_{j,k} \partial_j (a_{jk}(x) \partial_k v) + \sum b_j(x) \partial_j v. \end{aligned}$$

We define v as a solution of the transport equation

$$(E) \quad \{\partial_t + \sum_j a_{tj}(x, S_x) \partial_j\} v + \{\sum_j \partial_j (\sum_k a_{jk}(x) S_{x_k}) + \sum_j b_j(x) S_{x_j}\} v = 0.$$

Let $\varphi(x_0)$ be a smooth function with small compact support around $x_0 = x_0^0$. Let the inverse mapping of $x_0 \mapsto x(x_0, t, \xi^0)$ be $x_0(x, t, \xi^0)$ then the integration of the relation (E) along the bicharacteristic curve Γ through the point (x, t) gives

$$\begin{aligned} v(x, t; \xi^0) &= \exp \left[- \sum_j \int_0^t b_j(x(x_0, s, \xi^0)) \xi_j(x_0, s, \xi^0) ds \right] \\ &\quad \times \exp \left[- \int_0^t \sum_j \partial_j (\sum_k a_{jk}(x) S_{x_k}) |_{\Gamma} ds \right] \varphi(x_0(x, t, \xi^0)). \end{aligned}$$

Now it is easy to see that the second factor of the right-hand side is equal to $|dx/dx_0|_{t=\xi^0}^{-1/2}$ where dx/dx_0 is Jacobian. Hence the above expression is

$$(2.2) \quad v(x, t; \xi^0) = \exp \left[- \int_0^t \sum_j b_j(x) \xi_j |_{\Gamma} ds \right] \left| \frac{dx}{dx_0} \right|_{t=\xi^0}^{-1/2} \varphi(x_0(x, t, \xi^0)).$$

3. Proof of Theorem. Up to now we fixed ξ^0 . Now we replace

ξ^0 by $\lambda\xi^0$, λ being positive parameter tending to ∞ . Denote the corresponding solution by $v_\lambda(x, t)$. To see clearly the dependence of $v_\lambda(x, t)$ on λ , first we observe

$$(3.1) \quad \begin{cases} x(x_0, t, \lambda\xi^0) = x(x_0, \lambda t, \xi^0) \\ \xi(x_0, t, \lambda\xi^0) = \lambda\xi(x_0, \lambda t, \xi^0). \end{cases}$$

In fact, the function $t \mapsto (x(x_0, \lambda t, \xi^0), \lambda\xi(x_0, \lambda t, \xi^0))$ satisfies Hamilton-Jacobi's equation (1.3) with initial data $(x_0, \lambda\xi^0)$ at $t=0$. Then by uniqueness, (3.1) follows. This shows in particular the projection on the x -space of the bicharacteristic strip is unchanged. Next, since in the expression of (2.2) (in view of (3.1)), we have

$$\int_0^t b(x(x_0, s, \lambda\xi^0))\xi(x_0, s, \lambda\xi^0)ds = \int_0^{\lambda t} b(x(x_0, s, \xi^0))\xi(x_0, s, \xi^0)ds.$$

Put

$$w(x, t, \xi^0) = \left| \frac{dx}{dx_0} \right|^{-1/2} \varphi(x_0(x, t, \xi^0)).$$

Recalling the relation $x_0(x, t, \lambda\xi^0) = x_0(x, \lambda t, \xi^0)$, we see easily that $w(x, t, \lambda\xi^0) = w(x, \lambda t, \xi^0)$. Thus,

$$(3.2) \quad v_\lambda(x, t) \equiv v(x, t; \lambda\xi^0) = v(x, \lambda t; \xi^0).$$

Another important property is that the mapping $\varphi(x) \mapsto w(\cdot, t, \xi^0)$ is unitary, namely L^2 -norm is preserved. Now v_λ satisfies

$$(3.3) \quad L(e^{iS_\lambda} v_\lambda) = f_\lambda(x, t),$$

$$(3.4) \quad \begin{cases} S_\lambda(x, t) = S(x, t, \lambda\xi^0) \\ f_\lambda(x, t) = ie^{iS_\lambda} \left[\sum_{j,k} \partial_j \cdot a_{jk}(x) \partial_k + \sum_j b_j(x) \partial_j + ic(x) \right] v_\lambda(x, t). \end{cases}$$

An important property of $f_\lambda(x, t)$ is that, in view of its form, we have $|f_\lambda(x, t)| = |f_1(x, \lambda t)|$, f_1 being defined by (3.4) replacing there v_λ by $v(x, t, \xi^0)$. Thus

$$(3.5) \quad \int_0^t \|f_\lambda(\cdot, s)\| ds = \int_0^{\lambda t} \|f_1(\cdot, \lambda s)\| ds = \frac{1}{\lambda} \int_0^{\lambda t} \|f_1(\cdot, s)\| ds.$$

Now we apply (1.2) to the relation (3.3). Since S_λ is real, we have

$$(3.6) \quad \|v_\lambda(\cdot, t)\| \leq C \left(\|\varphi\| + \int_0^t \|f_\lambda(\cdot, s)\| ds \right).$$

First we put here $t = t_1/\lambda$. Then by (3.5), the integral term is $\frac{1}{\lambda} \int_0^{t_1} \|f_1(\cdot, s)\| ds$. Next, remark that the support of $w(x, t_1, \xi^0)$ is concentrated around $x^{(1)} = x(x_0^0, t_1, \xi^0)$, moreover its diameter can be made as small as we desire by shrinking the support of φ to x_0^0 . Thus by (2.1) we can assume, in the expression (2.2) replaced t by t_1 , exponential term is greater than $3C/2$ in absolute value. Thus, for $t = t_1/\lambda$, we have

$$\|v_\lambda(\cdot, t)\| \geq \frac{3C}{2} \|\varphi\|.$$

Thus (3.6) implies the following inequality

$$\frac{3C}{2}\|\varphi\|\leq C\left(\|\varphi\|+\frac{1}{\lambda}\int_0^{t_1}\|f_1(\cdot, s)\|ds\right),$$

which is impossible when $\lambda\rightarrow\infty$. Thus we proved Theorem.

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References

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