# 8. On Conformal Diffeomorphisms between Product Riemannian Manifolds 

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In this note, a conformal diffeomorphism means a non-homothetic conformal one. Let $M=M_{1} \times M_{2}$ and $M^{*}=M_{1}^{*} \times M_{2}^{*}$ be connected product Riemannian manifolds of dimension $n \geqq 3$, and denote the metric product structures by $(M, g, F)$ and ( $M^{*}, g^{*}, G$ ) respectively. Several geometers [1]-[3], [5]-[8] proved non-existence of global conformal diffeomorphism between complete product Riemannian manifolds with certain properties. The purpose of this note is to announce the following

Theorem. If $M$ and $M^{*}$ are complete product Riemannian manifolds, then there is no global conformal diffeomorphism of $M$ onto $M^{*}$ such that it does not commute the product structures $F$ and $G, F G$ $\neq G F$, somewhere in $M$.

This is an improvement of the main theorem in a previous paper [5]. As the contraposition, a conformal diffeomorphism of $M$ onto $M^{*}$ has to commute the product structures $F$ and $G$ everywhere in $M$, and an example of such a conformal diffeomorphism was given in [5].

Outline of the proof. Let $M_{1}$ and $M_{2}$ be of dimension $n_{1}$ and $n_{2}$ respectively, $n_{1}+n_{2}=n$, and ( $x^{i}, x^{p}$ ) a separate coordinate system of $M$, ( $x^{i}$ ) belonging to $M_{1}$ and $\left(x^{p}\right)$ to $M_{2}$. Latin indices run on

$$
i, j, k=1,2, \cdots, n_{1} ; p, q, r=n_{1}+1, \cdots, n
$$

respectively, and Greek indices $\kappa, \lambda, \mu, \nu$ on the range 1 to $n$. The metric tensor $g=\left(g_{\mu \lambda}\right)$ of $M$ has pure components $g_{j i}$ and $g_{q p}$ only with respect to the separate coordinate system ( $x^{i}, x^{p}$ ).

A conformal diffeomorphism $f$ of $M$ to $M^{*}$ is characterized by a change of the metric tensors

$$
\begin{equation*}
g_{\mu \lambda}^{*}=\frac{1}{\rho^{2}} g_{\mu \lambda}, \tag{1}
\end{equation*}
$$

$\rho$ being a positive-valued scalar field. The integrability of the product structure $G$ with respect to $g^{*}$ in $M^{*}$ is equivalent to

$$
\begin{equation*}
\nabla_{\mu} G_{2 k}=-\frac{1}{\rho}\left(G_{\mu \lambda} \rho_{k}+G_{\mu \kappa k} \rho_{\lambda}-g_{\mu \lambda} G_{k \nu} \rho^{\nu}-g_{\mu s} G_{2 \nu} \rho^{\nu}\right) \tag{2}
\end{equation*}
$$

where $\nabla$ indicates covariant differentiation in $M$ and $\rho_{\lambda}=\nabla_{\lambda} \rho, \rho^{\nu}=\rho_{\lambda} g^{\lambda^{\nu}}$. Denote the gradient vector field ( $\rho^{2}$ ) by $Y$, the parts ( $\rho^{i}$ ) along to $M_{1}$ by $Y_{1}$ and $\left(\rho^{p}\right)$ to $M_{2}$ by $Y_{2}$. Put $\Phi=|Y|^{2}=\rho_{2} \rho^{2}=\left|Y_{1}\right|^{2}+\left|Y_{2}\right|^{2}$ and

$$
\begin{aligned}
& N_{1}=\left\{P \mid Y_{1}(P)=0\right\}, \quad N_{2}=\left\{P \mid Y_{2}(P)=0\right\}, \\
& U=\left\{P \mid Y_{1}(P) \neq 0, Y_{2}(P) \neq 0\right\}, \quad V=\{P \mid F G \neq G F \text { at } P\} .
\end{aligned}
$$

Starting from the equation (2), we have the inclusion relations

$$
U \subset V \subset M-N_{1} \cap N_{2}
$$

By definition, a special concircular scalar field $\rho$ satisfies (3)

$$
\nabla_{\mu} \rho_{\lambda}=(k \rho+b) g_{\mu \lambda},
$$

$k$ and $b$ being constants. The trajectories of $Y=\left(\rho^{\lambda}\right)$ are geodesics, called $\rho$-curves. In a neighborhood of an ordinary point $P$ of $\rho, Y(P)$ $\neq 0$, there is an adapted coordinate system $\left(u, u^{\alpha}\right), \alpha, \beta, \gamma=2, \cdots, n$, such that $u$ is the arc-length of $\rho$-curves, $\rho$ is a function of $u$ only, and the metric of $M$ is given in the form

$$
d s^{2}=d u^{2}+\left\{\rho^{\prime}(u)\right\}^{2} \overline{d s^{2}},
$$

where $\overline{d s^{2}}=f_{\gamma \beta} d u^{\gamma} d u^{\beta}$ is the metric form of an ( $n-1$ )-dimensional Riemannian manifold $\bar{M}$. If $M$ is complete and $k<0$, then $M$ is a sphere and $\bar{M}$ is the equatorial hypersphere of $M$. The equation (3) reduces to the ordinary differential equation

$$
\rho^{\prime \prime}(u)=k \rho+b
$$

along the $\rho$-curves, see [4].
The assumption of the theorem means $V \neq \phi$.
Case (I) of $U=\phi$. Then $M=N_{1} \cup N_{2}$, and we suppose $N_{2} \neq \phi$. In a connected component $V_{0}$ of $V \cap N_{2}$, we have the equation

$$
\begin{equation*}
\nabla_{j} \rho_{i}=c^{2} \rho g_{j i} \tag{4}
\end{equation*}
$$

$c$ being a positive constant, and

$$
\begin{equation*}
\Phi=\rho_{i} \rho^{i}=c^{2} \rho^{2} . \tag{5}
\end{equation*}
$$

In an adapted coordinate system in $V_{0}, \rho$ is given by $\rho=a e^{c u}, a$ being a constant. It follows from this expression and the differentiability of $\rho$ that $M=N_{2}$ and the equation (4) is valid on the whole manifold $M$.

If $U \neq \phi$, then it is proved that $\Phi$ is the sum
(6)

$$
\Phi=\rho_{\lambda} \rho^{2}=\Phi_{1}+\Phi_{2}
$$

of functions $\Phi_{1}$ of $\left(x^{i}\right)$ and $\Phi_{2}$ of $\left(x^{p}\right)$, and the parts $\Phi_{1}$ and $\Phi_{2}$ satisfy the equations

$$
\begin{equation*}
\nabla_{j} \nabla_{i}\left(\Phi_{1}-k \rho^{2}\right)=\Omega g_{j i}, \quad \nabla_{q} \nabla_{p}\left(\Phi_{2}+k \rho^{2}\right)=\Omega g_{q p}, \tag{7}
\end{equation*}
$$

where we have put

$$
\Omega=k\left(\Phi_{1}-\Phi_{2}-k \rho^{2}\right)+b,
$$

$b$ being a constant. Moreover we have the equations

$$
\begin{align*}
& \left\{\begin{array}{l}
\nabla_{p} \nabla_{j} \nabla_{i} \rho^{2}=\nabla_{p}\left(\Phi_{2}+k \rho^{2}\right) g_{j i}, \\
\nabla_{i} \nabla_{q} \nabla_{p} \rho^{2}=\nabla_{i}\left(\Phi_{1}-k \rho^{2}\right) g_{q p},
\end{array}\right.  \tag{8}\\
& \left\{\begin{array}{l}
\nabla_{k} \nabla_{j} \nabla_{i} \rho^{2}=\nabla_{k}\left(\Phi_{1}+k \rho^{2}\right) g_{j i}+g_{k j} \nabla_{i} \Phi_{1}+g_{k i} \nabla_{j} \Phi_{1}, \\
\nabla_{r} \nabla_{q} \nabla_{p} \rho^{2}=\nabla_{r}\left(\Phi_{2}-k \rho^{2}\right) g_{q p}+g_{r q} \nabla_{p} \Phi_{2}+g_{r p} \nabla_{q} \Phi_{2},
\end{array}\right. \tag{9}
\end{align*}
$$

and

$$
\left\{\begin{array}{l}
\nabla_{k} \nabla_{j} \nabla_{i} \Phi_{1}=k\left(2 g_{j i} \nabla_{k} \Phi_{1}+g_{k j} \nabla_{i} \Phi_{1}+g_{k i} \nabla_{j} \Phi_{1}\right),  \tag{10}\\
\nabla_{r} \nabla_{q} \nabla_{p} \Phi_{2}=-k\left(2 g_{q p} \nabla_{r} \Phi_{2}+g_{r q} \nabla_{p} \Phi_{2}+g_{r p} \nabla_{q} \Phi_{2}\right) .
\end{array}\right.
$$

Case (II) where $k=0$ in $U$. The equations (8) and (9) together make the tensor equation
(11)

$$
\nabla_{\nu} \nabla_{\mu} \nabla_{\lambda} \rho^{2}=g_{\nu \mu} \nabla_{\lambda} \Phi+g_{\nu \lambda} \nabla_{\mu} \Phi+g_{\mu \lambda} \nabla_{\nu} \Phi
$$

and the equations (7) do
(12)

$$
\nabla_{\mu} \nabla_{\lambda} \Phi=b g_{\mu \lambda} .
$$

This case splits into three cases.
( a ) $b=0$ and $\Phi$ is constant in $U$. Noting (6), we can obtain the equation

$$
\nabla_{\mu} \nabla_{\lambda} \rho^{2}=2 \Phi g_{\mu \lambda} .
$$

Referring this equation to an adapted coordinate system ( $u, u^{\alpha}$ ) for $\rho^{2}$, and choosing suitably the arc-length $u$, we obtain the expression

$$
\begin{equation*}
\rho^{2}=\Phi u^{2} . \tag{13}
\end{equation*}
$$

(b) $b=0$ and $\Phi$ is not constant. Then we have $\nabla_{\mu} \nabla_{\lambda} \Phi=0$. Integrating the equation (11) in an adapted one for $\Phi$, we can see that this case does not occur locally.
( c ) $b \neq 0$ in some connected component of $U$. In an adapted coordinate system ( $u, u^{\alpha}$ ) for $\Phi, \rho^{2}$ is expressed as

$$
\begin{equation*}
\rho^{2}=\frac{1}{8 b}\left[\left(b u^{2}+4 \gamma\right)^{2}+4 f^{\alpha \beta} \gamma_{\beta} \gamma_{\alpha}\right], \tag{14}
\end{equation*}
$$

where $\gamma$ is a solution of the equation

$$
\begin{equation*}
\overline{\bar{V}}_{\gamma} \overline{\overline{ }}_{\beta} \bar{\nabla}_{\alpha} \gamma=-\left(2 f_{\beta \alpha} \overline{\bar{\sigma}}_{\gamma} \gamma+f_{\gamma \beta} \bar{\nabla}_{\alpha} \gamma+f_{r \alpha} \bar{\nabla}_{\beta \gamma} \gamma\right) \tag{15}
\end{equation*}
$$

in an (n-1)-dimensional manifold $\bar{M}$ with metric tensor $f_{\beta \alpha}$.
Case (III) where $k \neq 0$ in some component $U_{0}$ of $U$. By means of (7), $\Phi_{1}-k \rho^{2}$ and $\Phi_{2}+k \rho^{2}$ are special concircular scalar fields in $M_{1} \cap U_{0}$ and $M_{2} \cap U_{0}$. We may put $k=c^{2}, c>0$. Referring (7)-(9) to adapted coordinate systems ( $u, u^{\alpha}$ ) in $M_{1} \cap U_{0}$ and ( $v, v^{\xi}$ ) in $M_{2} \cap U_{0}, \alpha=2, \cdots$, $n_{1}, \xi=n_{1}+2, \cdots, n$, and noting (6), we obtain the expressions of $\rho^{2}$ in the forms

$$
\rho^{2}=\left\{\begin{array}{l}
\text { ( a ) } \frac{1}{c^{2}}\left(\omega_{1} e^{2 c u}-\omega_{2} \sin ^{2} c v+\frac{A}{c^{2}} e^{c u} \cos c v+B\right),  \tag{16}\\
\text { (b) } \frac{1}{c^{2}}\left(\omega_{1} \cosh ^{2} c u-\omega_{2} \sin ^{2} c v+\frac{A}{c^{2}} \sinh c u \cos c v+B\right), \\
\text { (c) } \frac{1}{c^{2}}\left(\omega_{1} \sinh ^{2} c u-\omega_{2} \sin ^{2} c v+\frac{A}{c^{2}} \cosh c u \cos c v+B\right),
\end{array}\right.
$$

according to the forms of solution of (7), where $A, B$ are constants, $\omega_{1}$ is a function of $u^{\alpha}$ and $\omega_{2}$ a function of $v^{\xi}$ satisfying certain equations similar to (15).

By means of the expressions (16), we see that, in any case of the above, the sets $N_{1}$ and $N_{2}$ are border sets in $M$, the constants appearing in (16) are common with all components of $U$ and the expressions are valid over the whole manifold $M$.

If $M$ is complete, then so are the parts $M_{1}$ and $M_{2}$, in particular,
$M_{2}$ is 1-dimensional or an $n_{2}$-sphere, and $\gamma$ in Case (I, c) and $\omega_{2}$ in Case (III) are constant or bounded.

For example, we treat Case (III, a). Let $P$ be a point of $U, M_{1}(P)$ the part passing through $P, \Gamma$ a $\rho$-curve of the restriction $\left(\Phi_{1}-c^{2} \rho^{2}\right) \mid$ $M_{1}(P), \Gamma^{*}=f(\Gamma)$, and $s^{*}$ the arc-length of $\Gamma^{*}$. Then $\omega_{1}$ on $\Gamma$ should be positive and we put $\omega_{1}=2 a^{2}$. We take a value $u_{0}$ so large that $\rho>(a / c) e^{c u}$ for $u>u_{0}$, and $s_{0}^{*}$ the value corresponding to $u_{0}$. Then we obtain the inequality

$$
s^{*}-s_{0}^{*}<\frac{1}{a} e^{-c u_{0}} .
$$

Hence the length of $\Gamma^{*}$ is bounded as $u \rightarrow \infty$. This contradicts to the globalness of the conformal diffeomorphism $f: M \rightarrow M^{*}$.

## References

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