# 48. The Application of Monodromy Preserving Deformation to the Gravitational Field Equation 

By Kimio Ueno<br>Research Institute for Mathematical Sciences, Kyoto University (Communicated by Kôsaku Yosida, M. J. A., April 13, 1981)

§0. In this note, we will show the new method for constructing exact solutions of the vacuum Einstein equation for stationary axisymmetric gravitational fields (VESA).

From a viewpoint of the inverse scattering theory, Belinsky-Zakharov (B-Z) [1], [2] gave an interesting method for integrating VESA, expressed by the metric form

$$
\text { (0.1) } \quad-d s^{2}=f\left(d \rho^{2}+d z^{2}\right)+g_{\alpha \beta} d x^{\alpha} d x^{\beta} \quad(\alpha, \beta=0,1)
$$

where $f$ and $g_{\alpha \beta}$ are functions in $\rho$ and $z$, and $x^{0}, x^{1}$ represent the coordinates $t$, $\phi$, respectively.

Under the supplementary condition
(0.2) $\quad \operatorname{det} g=-\rho^{2}, \quad g=\left(g_{\alpha \beta}\right)$,
the fields equation for the metric (0.1) can be written as follows:

$$
\begin{align*}
& \left\{\begin{array}{l}
U_{\rho}+V_{z}=0 \\
U_{z}-V_{\rho}+\rho^{-1} V+\rho^{-1}[U, V]=0
\end{array}\right.  \tag{0.3}\\
& \left\{\begin{array}{l}
(\log f)_{\rho}=-\rho^{-1}+(4 \rho)^{-1} \operatorname{trace}\left(U^{2}-V^{2}\right) \\
(\log f)_{z}=(2 \rho)^{-1} \operatorname{trace}(U V) .
\end{array}\right. \tag{0.4}
\end{align*}
$$

Here $U=\rho g_{\rho} g^{-1}$, and $V=\rho g_{z} g^{-1}$. We should note that the matrix $g$ is symmetric. $\mathrm{B}-\mathrm{Z}$ found that the equation ( 0.3 ) are equivalent to the compatibility conditions of the system of linear equations

$$
\left\{\begin{array}{l}
D_{1} Y=\frac{\rho V-\lambda U}{\lambda^{2}+\rho^{2}} Y  \tag{0.5}\\
D_{2} Y=\frac{\lambda V+\rho U}{\lambda^{2}+\rho^{2}} Y
\end{array}\right.
$$

where

$$
D_{1}=\frac{\partial}{\partial z}-\frac{2 \lambda^{2}}{\lambda^{2}+\rho^{2}} \frac{\partial}{\partial \lambda}, \quad D_{2}=\frac{\partial}{\partial \rho}+\frac{2 \lambda \rho}{\lambda^{2}+\rho^{2}} \frac{\partial}{\partial \lambda},
$$

and $\lambda$ is a complex parameter independent of $\rho$ and $z$.
If we find a solution $Y(\lambda)=Y(\lambda, \rho, z)$ to (0.4), and set

$$
\begin{equation*}
g=Y(0)=Y(0, \rho, z), \tag{0.6}
\end{equation*}
$$

the potentials $U$ and $V$ in (0.5) can be recovered as $U=\rho g_{\rho} g^{-1}, V$ $=\rho g_{z} g^{-1}$, so we obtain a solution of (0.3). But we should note that the function $g$ given by ( 0.6 ) is not always assured to be symmetric, real, and to satisfy the condition (0.2). We can easily find the conditions that $g$ is real and satisfies (0.2) (cf. [1], [2], [9]). Therefore one of the
crucial points to which we must make efforts is to find out the symmetric conditions for $g=Y(0)$.

By applying monodromy preserving deformation (MPD), we are succeed in construction of exact solutions of VESA. Namely, our main tool here is MPD of a certain Fuchsian equation

$$
\begin{equation*}
\frac{d Y}{d \lambda}=\sum_{j=1}^{n} \frac{A_{j}}{\lambda-\mu_{j}} Y . \tag{0.7}
\end{equation*}
$$

If the global monodromy of the normalized fundamental solution matrix (briefly, the normalized solution) $Y(\lambda)=Y(\lambda, \rho, z)$ is kept, and at the same time, satisfy appropriate conditions, then $Y$ solves the equation (0.3) with some potential $U, V$, and its 0 -value $Y(0)=Y(0, \rho, z)$ is symmetric.

This is our main result in this article.
The author would like to thank Prof. E. Date of Kyoto University and Drs. M. Jimbo and T. Miwa of RIMS for many valuable suggestions and stimulating discussions.
§1. MPD and VESA. In order to construct special solutions of ( 0.3 ), instead of (0.5), we start from a $2 \times 2$ Fuchsian equation in the complex domain

$$
\begin{equation*}
\frac{d Y}{d \lambda}=\sum_{j=1}^{m} \frac{A_{j}}{\lambda-\mu_{j}} Y \tag{1.1}
\end{equation*}
$$

where each singular point $\mu_{j}$ is a root of the quadratic equation

$$
\begin{equation*}
\mu^{2}-2\left(w_{j}-z\right) \mu-\rho^{2}=0, \quad w_{j} \in C, \tag{1.2}
\end{equation*}
$$

namely $\mu_{j}$ is a solution of non-linear equations of first order

$$
\begin{equation*}
\frac{\partial \mu}{\partial z}=\frac{-2 \mu^{2}}{\mu^{2}+\rho^{2}}, \quad \frac{\partial \mu}{\partial \rho}=\frac{2 \rho \mu}{\mu^{2}+\rho^{2}} . \tag{1.3}
\end{equation*}
$$

We assume that, in this equation, the exponents at each singular point are distinct modulo integers, and that there exists the solution normalized at the infinity $Y^{(\infty)}(\lambda)=Y^{(\infty)}(\lambda, \rho, z)$, which has a local expansion at the infinity

$$
\begin{equation*}
Y^{(\infty)}=\left(1+\hat{Y}_{1}^{(\infty)} \lambda^{-1}+\cdots\right)\left(\lambda^{-1}\right)^{L^{(\infty)}}, \quad \text { as } \lambda \rightarrow \infty, \tag{1.4}
\end{equation*}
$$

where $L^{(\infty)}$ is a diagonal matrix.
First we obtain the following fundamental theorem.
Theorem 1.1. If the global monodromy of $Y^{(\infty)}(\lambda)$ is independent of $\rho$ and $z$ (i.e. isomonodromic), $Y^{(\infty)}(\lambda)$ solves the equation of (0.5), where the potentials $U$ and $V$ are given by

$$
\begin{equation*}
U=\sum_{j=1}^{n} \frac{2 \rho^{2} A_{j}}{\mu_{j}^{2}+\rho^{2}}, \quad V=-\sum_{j=1}^{n} \frac{2 \rho \mu_{j} A_{j}}{\mu_{j}^{2}+\rho^{2}} . \tag{1.5}
\end{equation*}
$$

This theorem is very important, and plays a central role in our scheme. However we should note that the symmetry of $Y^{(\infty)}(0)$ is not always assured. In order to describe the symmetric condition for $Y^{(\infty)}(0)$ as that of the global monodromy, we need the following prop-
osition, which was suggested by Prof. E. Date (cf. [3]).
Proposition 1.2 (Date). Let $Y(\lambda)=Y(\lambda, \rho, z)$ be a solution of (0.5). If $Y(0)$ is symmetric, there exists an invertible matrix $S(\lambda, \rho, z)$ such that

$$
\begin{equation*}
D_{1} S=D_{2} S=0 \tag{1.9}
\end{equation*}
$$

and

$$
\begin{equation*}
Y(0)=Y\left(-\frac{\rho^{2}}{\lambda}\right) S(\lambda)^{t} Y(\lambda) \tag{1.10}
\end{equation*}
$$

Here ${ }^{t} Y(\lambda)$ denotes the transposed matrix of $Y(\lambda)$.
For the purpose of the interpretation to the feature of $S(\lambda)$, we introduce a variable $w$ through

$$
\begin{equation*}
w=2^{-1}\left(\lambda+2 z-\lambda^{-1} \rho^{2}\right) \tag{1.11}
\end{equation*}
$$

$S(\lambda)$ is a function of $w$, and if $\mu$ is a root of (1.2), $S(\mu)$ is constant. $S(\lambda)$ has also a symmetric property

$$
\begin{equation*}
S(\lambda)={ }^{t} S\left(-\frac{\rho^{2}}{\lambda}\right) \tag{1.12}
\end{equation*}
$$

Let $Y_{0}(\lambda)$ be a solution of (0.5) with potentials $U_{0}$ and $V_{0}$. Suppose that $Y_{0}(0)$ is symmetric. We define a function $S_{0}(\lambda)$ by (1.10), where $Y(\lambda)$ is replaced by $Y_{0}(\lambda)$. Furthermore, let $Y(\lambda)$ be a solution of (0.5) with new potentials $U$ and $V$. Then we consider the condition that $Y\left(-\left(\rho^{2} / \lambda\right)\right) S_{0}(\lambda)^{t} Y(\lambda)$ just gives $Y(0)$.

Proposition 1.3. Suppose that $g=Y\left(-\left(\rho^{2} / \lambda\right)\right) S_{0}(\lambda)^{t} Y(\lambda)$ is independent of $\lambda$. Then the 0 -value of $Y(\lambda)$ is given by (1.13)

$$
Y(0)=g
$$

moreover $Y(0)$ is symmetric.
According to this proposition, we search for the condition that the normalized solution $Y^{(\infty)}(\lambda)$ of a $2 \times 2$ Fuchsian equation

$$
\begin{equation*}
\frac{d Y}{d \lambda}=\sum_{j=1}^{n}\left(\frac{A_{j}}{\lambda-a_{j}}+\frac{B_{j}}{\lambda-b_{j}}\right) Y \tag{1.14}
\end{equation*}
$$

has the symmetric 0 -value $Y^{(\infty)}(0)$. In (1.14), $a_{j}, b_{j}$ are two roots of a quadratic equation of (1.2). We fix a function $y_{0}(\lambda)$,

$$
\begin{equation*}
y_{0}(\lambda)=\prod_{j=1}^{n}\left(\lambda-a_{j}\right)^{\alpha_{j}}\left(\lambda-b_{j}\right)^{\beta_{j}}, \quad \alpha_{j}, \beta_{j} \in C \tag{1.15}
\end{equation*}
$$

associated with (1.14), and set

$$
\begin{equation*}
S_{0}(\lambda)=y_{0}\left(-\frac{\rho^{2}}{\lambda}\right)^{-1} y_{0}(0) y_{0}(\lambda)^{-1} \tag{1.16}
\end{equation*}
$$

The normalized solution $Y^{(\infty)}(\lambda)$ is assumed to have a local expansion at each singular point

$$
\begin{align*}
& \left.y_{0}(\lambda) Y^{(\infty)}(\lambda)^{-1}\right|_{\lambda=\infty}=1  \tag{1.17}\\
& Y^{(\infty)}(\lambda)=G^{(\mu)} \hat{Y}^{(\mu)}(\lambda)(\lambda-\mu)^{L^{(\mu)}} C^{(\mu)},  \tag{1.18}\\
& \hat{Y}^{(\mu)}(\lambda)=\sum_{l=1}^{\infty} Y_{l}^{(\mu)}(\lambda-\mu)^{l}, \quad Y_{0}^{(\mu)}=1, \quad \mu=a_{j}, b_{j} \\
& \quad(j=1, \cdots, n),
\end{align*}
$$

(1.19) $\quad L^{(\mu)}=\operatorname{diag}\left(l_{1}^{(\mu)}, l_{2}^{(\mu)}\right)$ and $C^{(\mu)}$ is constant, invertible.

Namely the global monodromy of $Y^{(\infty)}(\lambda)$ is preserved.
We state our main result.
Theorem 1.4. Suppose that the entries of any $L^{(\mu)}$ are distinct modulo integers. Then, $g=Y^{(\infty)}\left(-\left(\rho^{2} / \lambda\right)\right) S_{0}(\lambda)^{t} Y^{(\infty)}(\lambda)$ is independent of $\lambda$, if and only if either of the following conditions is always valid for any $j$ :

$$
\begin{equation*}
l_{s}^{\left(b_{j}\right)}+l_{s}^{\left(a_{j}\right)}=\beta_{j}+\alpha_{j}, \quad \text { for } s=1,2, \tag{1.20}
\end{equation*}
$$

and $C^{\left(b_{j}, a_{j}\right)}$ is a diagonal matrix,
(1.21) $\quad l_{s}^{\left(b_{j}\right)}+l_{s^{\prime}}^{\left(a_{j}\right)}=\beta_{j}+\alpha_{j}, \quad$ for $s \neq s^{\prime}, \quad s, s^{\prime}=1,2$
and $C^{\left(b_{j}, a_{j}\right)}$ is a diagonal free matrix, where $C^{\left(b_{j}, a_{j}\right)}=C^{\left(b_{j}\right)^{t}} C^{\left(a_{j}\right)}$.
For the proof, the reader should be referred to [9].
Using this theorem, together with Theorem 1.1 and Proposition 1.3, we can find out the symmetric solution $g$ of ( 0.3 ).
§2. Schlesinger transformations and symmetry. In this section, we will discuss Schlesinger transformations which preserve the symmetry of $Y^{(\infty)}(0)$.

We make a Schlesinger transformation of type

$$
\begin{cases}a_{n+1}, \cdots, a_{n+N} & b_{n+1}, \cdots, b_{n+N}  \tag{2.1}\\ -E_{1} \cdots,-E_{1} & E_{1}, \cdots, E_{1} \\ & E_{1}=\operatorname{diag}(1,0), \quad E_{2}=\operatorname{diag}(0,1)\end{cases}
$$

to the normalized solution $Y^{(\infty)}(\lambda)$ of (1.1) (cf. [8]). Here $a_{j}$ and $b_{j}$ $(j=n+1, \cdots, n+N)$ are two roots of the quadratic equation

$$
\begin{gather*}
\mu^{2}-2\left(w_{j}-z\right) \mu-\rho^{2}=0, \quad w_{j} \in C, \quad w_{j} \neq w_{k}, \quad(j \neq k)  \tag{2.2}\\
j=n+1, \cdots, n+N,
\end{gather*}
$$

and assumed to be regular points of (1.1). At these regular points, a gauge matrix $G^{(\mu)}$ and a connection matrix $C^{(\mu)}\left(\mu=a_{j}, b_{j}\right)$ are introduced through

$$
\begin{align*}
& C^{(\mu)} ; \text { an arbitrary constant invertible matrix, }  \tag{2.3}\\
& G^{(\mu)}=Y^{(\infty)}(\mu) C^{(\mu)-1} .
\end{align*}
$$

The multiplier $R(\lambda)$ for the transformation (2.1) is given by

$$
\begin{equation*}
R(\lambda)=1+\sum_{j=n+1}^{n+N} \frac{R_{j}}{\lambda-a_{j}} \tag{2.4}
\end{equation*}
$$

$$
=1+\left[\vec{G}^{\left(b_{n+1}\right)}, \cdots, \vec{G}^{\left(b_{n+N}\right)}\right] W^{-1}\binom{1 \quad{ }^{t}\left(\vec{G}^{\left(a_{n+1}\right)-1}\right.}{\left.\frac{a_{n+1}}{1} \begin{array}{c}
1 \\
\frac{1}{\lambda-a_{n+N}}
\end{array}\right) \text {, } \vec{G}^{\left(a_{n+N}\right)-1}}
$$

$$
\begin{equation*}
W=\left[\frac{\left(G^{\left(a_{n+i}\right)-1} G^{\left(b_{n+j}\right)}\right)_{11}}{a_{n+i}-b_{n+j}}\right]_{i, j=1, \ldots, N}, \tag{2.5}
\end{equation*}
$$

$$
\begin{align*}
& { }^{t} \vec{G}^{\left(b_{n+j}\right)}=\left[G_{11}^{\left(b_{n+j}\right)}, G_{21}^{\left(b_{n+j}\right)}\right],  \tag{2.6}\\
& { }^{t} \vec{G}^{\left(a_{n+j}\right)-1}=\left[G_{11}^{\left(a_{n+j}\right)-1}, G_{12}^{\left(a_{n+j}-1\right.}\right] .
\end{align*}
$$

Throughout the following discussion, $Y^{(\infty)}(0)$ is assumed to be symmetric. We define $S(\lambda)$ by (1.10), replacing $Y(\lambda)$ by $Y^{(\infty)}(\lambda)$, and set (2.7)

$$
Y_{1}^{(\infty)}(\lambda)=R(\lambda) Y^{(\infty)}(\lambda)
$$

Then $Y_{1}^{(\infty)}(\lambda)$ is a solution normalized at the infinity of a certain Fuchsian equation with singular points as $\mu_{1}, \cdots, \mu_{m}, a_{n+1}, \cdots, b_{n+N}$, and if the global monodromy of $Y_{1}^{(\infty)}(\lambda)$ is kept, that of $Y_{1}^{(\infty)}(\lambda)$ is so. Therefore $Y_{1}^{(\infty)}(\lambda)$ solves the equation (0.5), whose potentials are replaced by, say, $U_{1}$ and $V_{1}$. But we should note that $Y_{1}^{(\infty)}(0)$ is not always symmetric even if $Y^{(\infty)}(0)$ is so. Along the scheme stated in $\S 1$, we consider $g_{1}=Y_{1}^{(\infty)}\left(-\left(\rho^{2} / \lambda\right)\right) S(\lambda)^{t} Y_{1}^{(\infty)}(\lambda)$. By Proposition 1.3, if $g_{1}$ does not depend on $\lambda, g_{1}=Y_{1}(0)$, and $g_{1}$ is symmetric. In a similar way as Theorem 1.4, we obtain the following

Theorem 2.1. $g_{1}=Y_{1}^{(\infty)}\left(-\left(\rho^{2} / \lambda\right)\right) S(\lambda)^{t} Y_{1}^{(\infty)}(\lambda)$ does not depend on $\lambda$, hence $g_{1}=Y_{1}^{(\infty)}(0)$ is symmetric, if and only if the following condition holds for each $j=n+1, \cdots, n+N$.

$$
\begin{equation*}
E_{2} C^{\left(b_{j}\right)} S\left(a_{j}\right)^{t} C^{\left(a_{j}\right)} E_{1}=0 . \tag{2.8}
\end{equation*}
$$

Remark. The Schlesinger transformations considered in Theorem 2.1 are equal to those constructed in [1], [2], because the following fact holds:
" $g_{1}=Y_{1}^{(\infty)}\left(-\left(\rho^{2} / \lambda\right)\right) S(\lambda)^{t} Y_{1}^{(\infty)}(\lambda)$ is independent of $\lambda$ " is equivalent to " $g_{1}=R\left(-\left(\rho^{2} / \lambda\right)\right) Y^{(\infty)}(0)^{t} R(\lambda)$ is independent of $\lambda$ ".

In [1], [2], B-Z determines the coefficients of $R(\lambda)$, by the latter condition.
$\S 3$. The $\tau$-function and the metric coefficient $f$. In this section, we will show that the $\tau$-function for the Schlesinger equation is essentially the metric coefficient $f$, defined by (0.4). Throughout this section, the equation (1.1) and its normalized solution $Y^{(\infty)}(\lambda)$ satisfy the condition in the situation of Theorem 1.1.

First we interpret the $\tau$-function for the Schlesinger equation (cf. [4], [7]). The Schlesinger equation is a deformation equation for Fuchsian system (1.1), and a completely integrable system, given by

$$
\begin{equation*}
d A_{j}=\sum_{k(\neq j)}\left[A_{k}, A_{j}\right] \frac{d\left(\mu_{k}-\mu_{j}\right)}{\mu_{k}-\mu_{j}}, \quad j=1, \cdots, m \tag{3.1}
\end{equation*}
$$

The $\tau$-function for (3.1) is defined by

$$
\begin{equation*}
d \log \tau=\frac{1}{2} \sum_{j \neq k} \operatorname{trace} A_{j} A_{k} \frac{d\left(\mu_{j}-\mu_{k}\right)}{\mu_{j}-\mu_{k}} \tag{3.2}
\end{equation*}
$$

which is a closed 1-form under (3.1). The metric coefficient $f$ is introduced through (0.4), where the potentials $U$ and $V$ are given by (1.5).

By a direct computation, we can prove our first assertion.
Theorem 3.1. Under the condition of Theorem 1.1, we have

$$
\begin{equation*}
\rho f=\text { const } \prod_{j=1}^{m}\left(\frac{\mu_{j}^{2}}{\mu_{j}^{2}+\rho^{2}}\right)^{1 / 2 \operatorname{trace} L^{\left(\mu_{j}\right) 2}} \tau \tag{3.3}
\end{equation*}
$$

where $L^{\left(\mu_{j}\right)}$ is an exponent matrix of the monodromy of $Y^{(\infty)}(\lambda)$ around $\mu_{j}$.

Next we consider how $f$ changes under the Schlesinger transformation of type (2.1). Let $Y_{1}^{(\infty)}(\lambda)$ be given by (5.1), and $f, f_{1}$ the metric coefficient corresponding to $Y^{(\infty)}(\lambda), Y_{1}^{(\infty)}(\lambda)$, respectively. By Theorem 3.1, together with Theorem 4.1 in Jimbo-Miwa [8], we obtain the following

Theorem 3.2. Let $W$ be an $N \times N$ matrix given by (2.5). Then we have

$$
\begin{equation*}
f_{1}=\operatorname{const} f \rho^{N} \prod_{j=1}^{N}\left(\frac{a_{n+j}}{a_{n+j}^{2}+\rho^{2}}\right) \operatorname{det} W \text {. } \tag{3.4}
\end{equation*}
$$

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