

38. Note on Certain Nonlinear Evolution Equations of Second Order

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1. Introduction. In this note we consider nonlinear evolution equations of the form

$$(1.1) \quad u''(t) + Au(t) + B(t)u'(t) = f(t), \quad 0 \leq t \leq T,$$

with initial conditions

$$(1.2) \quad u(0) = u_0 \quad \text{and} \quad u'(0) = u_1,$$

($u'(t) = du(t)/dt$, $u''(t) = d^2u(t)/dt^2$), where A is a nonlinear operator and each $B(t)$ is a formally self-adjoint positive operator.

When $B(t) \equiv 0$, there are a great number of results on non-existence of global weak solutions of (1.1) (see e.g. Knops-Straughan [4] and the cited papers therein). However, as for the existence of a global weak solution for an abstract Cauchy problems (1.1) and (1.2), where A is a genuinely nonlinear operator, it seems that there are few results except for Tsutsumi's [8]. He obtained sufficient conditions for the global existence under the presence of the dissipative term $B(t)u'(t)$.

The purpose of the present note is to show the existence of a global weak solution of (1.1) and (1.2) satisfying a certain inequality of energy type. Especially, we intend to weaken the assumptions of Tsutsumi [8] so that the result can be applied to a wider class of nonlinear partial differential equations.

2. Assumptions and result. Let H be a real separable Hilbert space with inner product (\cdot, \cdot) and norm $|\cdot|_H$. Let W be a second real separable Hilbert space with norm $|\cdot|_W$ and let V be a real separable reflexive Banach space with norm $|\cdot|_V$. Suppose that

$$V \subset W \subset H,$$

where each injection is dense and continuous. Furthermore, the injection of W into H is compact. As usual, we identify H with its own dual and denote by V^* and W^* the dual spaces of V and W , respectively. Then the following inclusion relation holds:

$$V \subset W \subset H \subset W^* \subset V^*.$$

The pairing between $x^* \in V^*$ (resp. $x^* \in W^*$) and $x \in V$ (resp. $x \in W$) is simply denoted by (x^*, x) ; if $x, x^* \in H$, this is the ordinary inner product in H .

Throughout this note we put the following assumptions on the nonlinear operator $A: V \rightarrow V^*$.

(A. 1) For each $u \in V$, $Au \in V^*$ is the Gâteaux differential of a convex functional F_A at u , which is lower semicontinuous on V .

(A. 2) For each $c > 0$, $\{u \in V; F_A(u) \leq c\}$ is bounded in V .

(A. 3) A maps every bounded set of V into a bounded set of V^* .

For the linear operator $B(t) : W \rightarrow W^*$, we assume the following.

(B. 1) For each $t \in [0, T]$, $B(t)$ is a linear operator associated with a symmetric bilinear form $b(t; \cdot, \cdot)$ on W , which satisfies

$$|b(t; u, v)| \leq b_1 |u|_W |v|_W \quad \text{and} \quad b(t; u, u) \geq b_2 |u|_W^2$$

for $\forall u, v \in W$,

where b_1 and b_2 are some positive constants independent of t .

(B. 2) For each $u, v \in W$, $t \mapsto b(t; u, v)$ is continuously differentiable on $[0, T]$ and $\dot{b}(t; u, v) (\equiv db(t; u, v)/dt)$ has the following property: If $u_n \rightarrow u$ weakly in W as $n \rightarrow \infty$, then $\limsup_{n \rightarrow \infty} \dot{b}(t; u_n, u_n) \leq \dot{b}(t; u, u)$ for every $t \in [0, T]$.

Under these assumptions we have the main result.

Theorem 2.1. *Let $u_0 \in V$, $u_1 \in H$ and $f \in L^2(0, T; H)$. Then there exists a function u such that*

(2.1) $u \in L^\infty(0, T; V),$

(2.2) $u' \in L^\infty(0, T; H) \cap L^2(0, T; W),$

(2.3) $u'' \in L^2(0, T; V^*),$

and satisfies (1.1), (1.2) and the following inequality; for any positive function $\psi \in C^1[0, T]$

$$(2.4) \quad \begin{aligned} & \psi(t)E(u(t)) + \int_s^t \psi(r)b(r; u'(r), u'(r))dr \\ & \leq \psi(s)E(u(s)) + \int_s^t \psi'(r)E(u(r))dr + \int_s^t \psi(r)(f(r), u'(r))dr, \end{aligned}$$

a.e. $0 \leq s \leq t \leq T$,

where

$$E(u(t)) = \frac{1}{2} |u'(t)|_H^2 + F_A(u(t)).$$

Remark 2.2. If the injection of V into W is also compact, then the conclusion of Theorem 2.1 holds true with (B. 2) replaced by the following weaker assumption:

(B. 2)' For each $u, v \in W$, $t \mapsto b(t; u, v)$ is continuous on $[0, T]$.

Remark 2.3. Our assumptions (A. 1)–(A. 3) generalize the corresponding ones of Tsutsumi [8]; in particular, it is unnecessary to assume the homogeneity condition of A.

3. Outline of the proof. First we shall prepare some lemmas to prove Theorem 2.1.

Lemma 3.1. *A is a maximal monotone and demicontinuous operator from V to V^* .*

Proof. By (A. 1), it is easily shown that A is a maximal monotone operator from V to V^* (see e.g. Barbu [1, Chap. 2, § 2]). So the demi-

continuity of A follows from the result of Rockafellar [7, Cor. 1.1].

Lemma 3.2. *Let $u \in C^1([0, T]; V)$. Then*

$$\frac{d}{dt}F_A(u(t)) = \left(Au(t), \frac{d}{dt}u(t) \right) \quad \text{for every } t \in [0, T].$$

Proof. By the definition of the subdifferential (see e.g. [1]),

$$(3.1) \quad \begin{aligned} (Au(t+h), u(t+h) - u(t)) &\geq F_A(u(t+h)) - F_A(u(t)) \\ &\geq (Au(t), u(t+h) - u(t)). \end{aligned}$$

Dividing (3.1) by h and letting $h \rightarrow 0$, we obtain the conclusion. (Note that $t \mapsto Au(t)$ is weakly continuous in V^* by Lemma 3.1.)

Let $1 \leq p \leq \infty$. We recall the fact that, for any $u \in L^p(0, T; V)$, $t \mapsto Au(t)$ is strongly measurable in V^* by Lemma 3.1 and the result of Brezis [2, Appendice IV]. Define the operator $\mathcal{A}: L^p(0, T; V) \rightarrow L^{p'}(0, T; V^*)$ ($1/p + 1/p' = 1$) with the domain $D(\mathcal{A})$ as follows:

$$\begin{aligned} D(\mathcal{A}) &= \{u \in L^p(0, T; V); Au \in L^{p'}(0, T; V^*)\} \\ (\mathcal{A}u)(t) &= Au(t) \quad \text{for a.e. } t \in [0, T]. \end{aligned}$$

Then we have the following lemma whose proof can be found in [2, Appendice I].

Lemma 3.3. *\mathcal{A} is a maximal monotone operator from $L^p(0, T; V)$ to $L^{p'}(0, T; V^*)$.*

Now we shall begin the proof of Theorem 2.1. It is very standard, so we only sketch it here. For details, see Tsutsumi [8].

We employ the Galerkin's method and take $\{w_j\}$ as the basis. Define approximate functions $u_m(t)$ as follows;

$$u_m(t) = \sum_{j=1}^m \alpha_{jm}(t)w_j,$$

where unknown functions α_{jm} are determined by the following ordinary differential equations

$$(u_m''(t), w_j) + (Au_m(t), w_j) + b(t; u_m'(t), w_j) = (f(t), w_j),$$

$$j = 1, 2, \dots, m,$$

with initial conditions

$$\begin{aligned} u_m(0) &= u_{0,m}, & u_{0,m} &= \sum_{j=1}^m \alpha_{jm} w_j \rightarrow u_0 \\ & & & \text{strongly in } V \text{ as } m \rightarrow \infty, \\ u_m'(0) &= u_{1,m}, & u_{1,m} &= \sum_{j=1}^m \beta_{jm} w_j \rightarrow u_1 \\ & & & \text{strongly in } H \text{ as } m \rightarrow \infty. \end{aligned}$$

Having proved Lemmas 3.2 and 3.3, we can repeat the same procedure as in [8] with an obvious modification. We can, therefore, extract a subsequence $\{u_{\mu}\}$ of $\{u_m\}$, which converges (in the sense of [8]) to a weak solution u of (1.1) and (1.2) satisfying (2.1)–(2.3). Note that the convergence properties of $\{u_{\mu}\}$ in [8, (2.14)–(2.23)] still remain true.

To prove that the weak solution u satisfies (2.4), we use the following lemma which is obtained as a consequence of the above proof (cf. [9, 4.2]).

Lemma 3.4. For any function $\phi \in C[0, T]$ and $t \in [0, T]$,

$$(3.2) \quad \lim_{\mu \rightarrow \infty} \int_0^t \phi(s) (Au_\mu(s), u_\mu(s)) ds = \int_0^t \phi(s) (Au(s), u(s)) ds.$$

Now we note that the following inequality holds by (A. 1):

$$(3.3) \quad F_A(u(t)) - F_A(u_\mu(t)) \geq (Au_\mu(t), u(t) - u_\mu(t)), \quad \forall t \in [0, T].$$

Hence, with the help of (3.3) and the lower semicontinuity of F_A , (3.3) leads to the following: For any function $\phi \in C[0, T]$ and $t \in [0, T]$,

$$(3.4) \quad \lim_{\mu \rightarrow \infty} \int_0^t \phi(s) F_A(u_\mu(s)) ds = \int_0^t \phi(s) F_A(u(s)) ds,$$

which, in particular, implies that

$$(3.5) \quad \liminf_{\mu \rightarrow \infty} F_A(u_\mu(t)) = F_A(u(t)) \quad \text{for a.e. } t \in [0, T].$$

Recall that the equality in (2.4) holds true for $0 \leq s \leq t \leq T$ if u is replaced by u_μ (use Lemma 3.2). Hence taking the inferior limit of the both sides of the resulting expression and using the convergence properties (3.4), (3.5) and [8, (2.15), (2.23)], we see that u satisfies (2.4).

4. Applications. Let Ω be a bounded domain in R_x^n with smooth boundary Γ . We consider the following two examples.

Example 4.1. Let $J(\xi)$ be a convex $C^1(R_\xi^n)$ -function satisfying

$$\begin{aligned} \alpha_1 |\xi|^p \leq J(\xi) \leq \alpha_2 (|\xi|^p + 1), & \quad \forall \xi \in R_\xi^n, \\ |\partial J(\xi) / \partial \xi_i| \leq \alpha_3 (|\xi|^{p-1} + 1), & \quad \forall \xi \in R_\xi^n, \quad i = 1, 2, \dots, n, \end{aligned}$$

with

$$p \geq 2, \alpha_1, \alpha_2, \alpha_3 > 0 \quad \text{and} \quad |\xi|^2 = \sum_{i=1}^n \xi_i^2.$$

Set

$$a_i(\xi) = \partial J(\xi) / \partial \xi_i, \quad i = 1, 2, \dots, n.$$

We consider the following initial boundary value problem

$$\begin{cases} \frac{\partial^2 u}{\partial t^2} - \sum_{i=1}^n \frac{\partial}{\partial x_i} (a_i(\text{grad } u)) - b(t) \Delta \frac{\partial u}{\partial t} = f & \text{in } \Omega \times [0, T], \\ u(x, t) = 0 & \text{on } \Gamma \times [0, T], \\ u(x, 0) = u_0(x), \quad \frac{\partial u}{\partial t}(x, 0) = u_1(x) & \text{in } \Omega, \end{cases}$$

where f, u_0 and u_1 are given functions and $b \in C^1[0, T]$ is a monotone non-increasing positive function (cf. Tsutsumi [8]).

Take $H = L^2(\Omega)$, $V = W_0^{1,p}(\Omega)$ and $W = H_0^1(\Omega)$. If we put

$$F_A(u) = \int_\Omega J(\text{grad } u(x)) dx,$$

we easily see that our hypotheses are satisfied. Thus we can apply Theorem 2.1 to the above problem.

Example 4.2. Next we consider nonlinear partial integro-differential equations of the form

$$\frac{\partial^2 u}{\partial t^2} - M \left(\int_\Omega |\text{grad } u(x)|^p dx \right) \Delta u - b(t) \Delta \frac{\partial u}{\partial t} = f \quad \text{in } \Omega \times [0, T],$$

with the same initial and boundary conditions as Example 4.1 (cf.

Dickey [3], Medeiros [5] and Pohozaev [6]). Suppose that M is a continuous and monotone non-decreasing function on $[0, \infty)$ satisfying

$$M(0) \geq 0 \quad \text{and} \quad \int_0^\infty M(r) dr = \infty.$$

Take $H = L^2(\Omega)$ and $V = W = H_0^1(\Omega)$ and define

$$\Phi(r) = \int_0^r M(s) ds.$$

Then putting

$$F_A(u) = \frac{1}{2} \Phi \left(\int_\Omega |\text{grad } u(x)|^2 dx \right),$$

we can apply Theorem 2.1. In this example, it is easily seen that the equality in (2.4) holds true. Furthermore, if M is a $C^1[0, \infty)$ -function satisfying $M(0) > 0$, we can derive the uniqueness of weak solutions.

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