

# Multiple periodic solutions of some Liénard equations with p-Laplacian

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## Abstract

The existence, non-existence and multiplicity of solutions to periodic boundary value problems of Liénard type

$$(|u'|^{p-2}u')' + f(u)u' + g(u) = e(t) + s, \quad u(0) - u(T) = 0 = u'(0) - u'(T),$$

is discussed, where  $p > 1$ ,  $f$  is arbitrary and  $g$  is assumed to be bounded, positive and  $g(\pm\infty) = 0$ . The function  $e$  is continuous on  $[0, T]$  with mean value 0 and  $s$  is a parameter.

## 1 Introduction and the main result

Consider periodic boundary value problems of the form

$$(\phi(u'))' + g(u) = e(t) + s, \quad u(0) - u(T) = 0 = u'(0) - u'(T), \quad (1)$$

where  $\phi : (-a, a) \rightarrow \mathbb{R}$  is an increasing homeomorphism such that  $\phi(0) = 0$  and  $0 < a \leq +\infty$ ,  $g : \mathbb{R} \rightarrow \mathbb{R}$ ,  $e : [0, T] \rightarrow \mathbb{R}$  are continuous functions and  $s \in \mathbb{R}$  is a parameter. Assume that the following assumptions are satisfied.

$$(H1) \quad \int_0^T e(t)dt = 0.$$

$$(H2) \quad g(u) > 0 \text{ for all } u \in \mathbb{R}.$$

$$(H3) \quad g(\pm\infty) = \lim_{u \rightarrow \pm\infty} g(u) = 0.$$

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By solution of (1) we mean a function  $u \in C^1([0, T])$  such that  $\phi \circ u' \in C^1([0, T])$  and which verifies (1). The main result in [1] is the following one.

**Theorem 1.** *If  $\phi : (-a, a) \rightarrow \mathbb{R}$  with  $0 < a \leq +\infty$  and conditions (H1)-(H3) hold, there exists  $s^*(e) \in (0, \sup_R g]$  such that problem (1) has zero, at least one or at least two solutions according to  $s \notin (0, s^*(e)]$ ,  $s = s^*(e)$  or  $s \in (0, s^*(e))$ .*

This type of result has been initiated by Ward [6] without multiplicity conclusion and  $\phi(v) = v$ . In the case  $\phi(v) = |v|^{p-2}v$  for some  $p > 1$ , we generalize the result above as follows.

Consider periodic boundary value problems of Liénard type

$$(|u'|^{p-2}u')' + f(u)u' + g(u) = e(t) + s, \quad u(0) - u(T) = 0 = u'(0) - u'(T), \quad (2)$$

where  $p > 1$ ,  $f : \mathbb{R} \rightarrow \mathbb{R}$  is a continuous function and  $g, e$  and  $s$  are as above. The main result of this paper is the following one.

**Theorem 2.** *If conditions (H1)-(H3) hold, there exists  $s^*(e) \in (0, \sup_R g]$  such that problem (2) has zero, at least one or at least two solutions according to  $s \notin (0, s^*(e)]$ ,  $s = s^*(e)$  or  $s \in (0, s^*(e))$ .*

To prove our main result, we use an approach similar to that in [1], but with technical differences due to the presence of  $f(u)u'$ . In what follows  $\phi : \mathbb{R} \rightarrow \mathbb{R}$  denotes the increasing homeomorphism defined by

$$\phi(v) = |v|^{p-2}v.$$

If  $\Omega \subset X$  is an open set of a normed space  $X$  and if  $S : \bar{\Omega} \rightarrow X$  is completely continuous and such that  $0 \notin (I - S)(\partial\Omega)$ , then  $d_{LS}[I - S, \Omega, 0]$  denotes the Leray-Schauder degree with respect to  $\Omega$  and 0. For the definition and properties of the Leray-Schauder degree see [3].

## 2 Notation and auxiliary results

Let  $C$  denote the Banach space of continuous functions on  $[0, T]$  endowed with the uniform norm  $\|\cdot\|_\infty$ ,  $C^1$  denotes the Banach space of continuously differentiable functions on  $[0, T]$ , equipped with the norm  $\|u\| = \|u\|_\infty + \|u'\|_\infty$ . We consider its closed subspace

$$C^1_\# = \{u \in C^1 : u(0) = u(T), u'(0) = u'(T)\},$$

and denote corresponding open balls of center 0 and radius  $r$  by  $B_r$ . We denote by  $P, Q : C \rightarrow C$  the continuous projectors defined by

$$P, Q : C \rightarrow C, \quad Pu(t) = u(0), \quad Qu(t) = \frac{1}{T} \int_0^T u(\tau) d\tau \quad (t \in [0, T]),$$

and define the continuous linear operator  $H : C \rightarrow C^1$  by

$$Hu(t) = \int_0^t u(\tau) d\tau \quad (t \in [0, T]).$$

A technical result from [4] is needed for the construction of the equivalent fixed point problems.

**Proposition 1.** *For each  $h \in C$ , there exists a unique  $\alpha := Q_\phi(h) \in \text{Range } h$  such that*

$$\int_0^T \phi^{-1}(h(t) - \alpha) dt = 0.$$

Moreover, the function  $Q_\phi : C \rightarrow \mathbb{R}$  is continuous.

The following fixed point reformulation of periodic boundary value problems like (2) is taken from [4].

**Proposition 2.** *Assume that  $F : C^1 \rightarrow C$  is continuous and takes bounded sets into bounded sets. Then  $u$  is a solution of the abstract periodic problem*

$$(\phi(u'))' = F(u), \quad u(0) - u(T) = 0 = u'(0) - u'(T)$$

if and only if  $u \in C^1_\#$  is a fixed point of the operator  $M^F_\#$  defined on  $C^1_\#$  by

$$M^F_\#(u) = Pu + QF(u) + H \circ \phi^{-1} \circ (I - Q_\phi) \circ [H(I - Q)F](u).$$

Furthermore,  $M^F_\#$  is completely continuous on  $C^1_\#$ .

The following result is a continuation theorem due to Manásevich and Mawhin [4].

**Proposition 3.** *Let  $h : [0, T] \times \mathbb{R}^2 \rightarrow \mathbb{R}$  be a continuous function and assume that there exists  $R > 0$  such that the following conditions hold.*

(i) *For each  $\lambda \in (0, 1]$  the problem*

$$(\phi(u'))' = \lambda h(t, u, u'), \quad u(0) - u(T) = 0 = u'(0) - u'(T),$$

*has no solution on  $\partial B_R$ .*

(ii) *The continuous function  $\eta : \mathbb{R} \rightarrow \mathbb{R}$*

$$\eta(d) := \frac{1}{T} \int_0^T h(t, d, 0) dt = 0,$$

*is such that  $\eta(-R)\eta(R) < 0$ .*

Then problem

$$(\phi(u'))' = h(t, u, u'), \quad u(0) - u(T) = 0 = u'(0) - u'(T), \tag{3}$$

has a least one solution in  $B_R$ , and

$$|d_{LS}[I - M^h_\#, B_R, 0]| = 1,$$

where  $M^h_\#$  denotes the fixed point operator associated to (3).

Let us decompose any  $u \in C^1_\#$  in the form

$$u = \bar{u} + \tilde{u} \quad (\bar{u} = u(0), \quad \tilde{u}(0) = 0),$$

and let

$$\widetilde{C^1_\#} = \{u \in C^1_\# : u(0) = 0\}.$$

The following inequality will be very useful in the sequel:

$$\|\tilde{u}\|_\infty \leq T^{1/q} \|u'\|_p \quad \forall u \in C^1_\#, \quad (\text{Sobolev}),$$

where  $1/p + 1/q = 1$  and  $\|u\|_p = (\int_0^T u(t) dt)^{1/p}$  for all  $u \in C$ .

### 3 Proof of the main result

For  $s \in \mathbb{R}$ , we define the continuous nonlinear operator  $N_s : C^1 \rightarrow C$  by

$$N_s(u)(t) = e(t) + s - g(u(t)) - f(u(t))u'(t) \quad (t \in [0, T]).$$

Using Proposition 2, it follows that  $u \in C_{\#}^1$  is a solution of (2) if and only if

$$u = Pu + QN_s(u) + H \circ \phi^{-1} \circ (I - Q_\phi) \circ [H(I - Q)N_s](u) =: \mathcal{G}(s, u),$$

and the nonlinear operator  $\mathcal{G}(s, \cdot) : C_{\#}^1 \rightarrow C_{\#}^1$  is completely continuous.

A *strict lower solution*  $\alpha$  (resp. *strict upper solution*  $\beta$ ) of (2) is a function  $\alpha \in C^1$  such that  $\phi(\alpha') \in C^1$ ,  $\alpha(0) = \alpha(T)$ ,  $\alpha'(0) \geq \alpha'(T)$  (resp.  $\beta \in C^1$ ,  $\phi(\beta') \in C^1$ ,  $\beta(0) = \beta(T)$ ,  $\beta'(0) \leq \beta'(T)$ ) and

$$(\phi(\alpha'(t)))' + f(\alpha(t))\alpha'(t) + g(\alpha(t)) > e(t) + s$$

(resp.

$$(\phi(\beta'(t)))' + f(\beta(t))\beta'(t) + g(\beta(t)) < e(t) + s)$$

for all  $t \in [0, T]$ .

**Lemma 1.** *If  $f, g : \mathbb{R} \rightarrow \mathbb{R}$  are continuous functions,  $e \in C$  and if (2) has a strict lower solution  $\alpha$  and a strict upper solution  $\beta$  such that  $\alpha(t) \leq \beta(t)$  for all  $t \in [0, T]$ , then problem (2) has a solution  $u$  such that  $\alpha(t) < u(t) < \beta(t)$  for all  $t \in [0, T]$ . Moreover,*

$$|d_{LS}[I - \mathcal{G}(s, \cdot), \Omega_{\alpha, \beta}^r, 0]| = 1,$$

where

$$\Omega_{\alpha, \beta}^r = \{u \in C_{\#}^1 : \alpha(t) < u(t) < \beta(t) \text{ for all } t \in [0, T], \quad \|u'\|_{\infty} < r\},$$

and  $r$  is sufficiently large.

*Proof. I. A modified problem.*

Let  $\gamma : [0, T] \times \mathbb{R} \rightarrow \mathbb{R}$  be the continuous function defined by

$$\gamma(t, u) = \begin{cases} \beta(t), & u > \beta(t) \\ u, & \alpha(t) \leq u \leq \beta(t) \\ \alpha(t), & u < \alpha(t). \end{cases}$$

We consider the modified problem

$$\begin{aligned} (|u'|^{p-2}u')' - [u - \gamma(t, u)] + f(\gamma(t, u))u' + g(\gamma(t, u)) &= e(t) + s, \\ u(0) - u(T) = 0 = u'(0) - u'(T). \end{aligned} \quad (4)$$

It is not difficult to show that if  $u$  is a solution of (4), then  $\alpha(t) < u(t) < \beta(t)$  for all  $t \in [0, T]$  and hence  $u$  is a solution of (2) (see [5], [2]).

*II. A priori estimations.*

In order to apply Manásevich-Mawhin continuation theorem to problem (4), we consider the family of problems

$$\begin{aligned} (|u'|^{p-2}u')' - \lambda[u - \gamma(t, u)] + \lambda f(\gamma(t, u))u' + \lambda g(\gamma(t, u)) &= \lambda(e(t) + s), \\ u(0) - u(T) = 0 = u'(0) - u'(T), \end{aligned} \tag{5}$$

where  $\lambda \in (0, 1]$ . Let  $u$  be a possible solution of (5). Let  $\tau \in [0, T]$  be such that  $u(\tau) = \max_{[0, T]} u$ . This implies that  $(\phi(u'(\tau)))' \leq 0$  and  $u'(\tau) = 0$ . Hence, using (5), it follows that

$$\lambda u(\tau) \leq \lambda[\gamma(\tau, u(\tau)) + g(\gamma(\tau, u(\tau))) - e(\tau) - s],$$

and there exists a constant  $C_1 > 0$  which not depends upon  $\lambda$  and  $u$  such that  $u(\tau) < C_1$ . Analogously, we can prove that there exists a constant  $C_2$  which not depends upon  $\lambda$  and  $u$  such that  $\min_{[0, T]} u > C_2$ . So, there exists  $C_3 > 0$  such that

$$\|u\|_\infty < C_3. \tag{6}$$

Multiplying both members of (5) by  $u$ , integrating over  $[0, T]$  and using (6), we deduce that there exists  $C_4, C_5 > 0$  such that

$$\|u'\|_p^p < C_4 + C_5\|u'\|_p,$$

which implies that there exists a constant  $C_6 > 0$  such that

$$\|u'\|_p < C_6. \tag{7}$$

Using (5), (6) and (7) it follows easily that there exists  $R > 0$  such that  $\|u\| < R$ , and because, in this case, the function  $\eta$  is given by

$$\eta(d) = d - \frac{1}{T} \int_0^T [\gamma(t, d) + g(\gamma(t, d))]dt + \frac{1}{T} \int_0^T e(t)dt + s,$$

we deduce that  $R$  can be chosen such that  $\eta(-R)\eta(R) < 0$ .

*III. End of the proof.*

Using II and Manásevich-Mawhin continuation theorem, we deduce that

$$|d_{LS}[I - \mathcal{H}(s, \cdot), B_R, 0]| = 1,$$

where  $\mathcal{H}(s, \cdot)$  is the fixed point operator associated to (4). On the other hand, using I, II and Proposition 2, it follows that every fixed point of the nonlinear operator  $\mathcal{H}(s, \cdot)$  belongs to  $\Omega_{\alpha, \beta}^r$  for  $r$  sufficiently large, and by excision property of the Leray-Schauder degree, we deduce that

$$|d_{LS}[I - \mathcal{H}(s, \cdot), \Omega_{\alpha, \beta}^r, 0]| = 1.$$

Because  $\mathcal{G}(s, \cdot) = \mathcal{H}(s, \cdot)$  on  $\overline{\Omega_{\alpha, \beta}^r}$ , it follows that

$$|d_{LS}[I - \mathcal{G}(s, \cdot), \Omega_{\alpha, \beta}^r, 0]| = 1,$$

and by existence property of the Leray-Schauder degree,  $\mathcal{G}(s, \cdot)$  has a fixed point in  $\Omega_{\alpha, \beta}^r$ , which is a solution of (2). ■

Let  $M : C^1 \rightarrow C$  be the continuous nonlinear operator defined by

$$M(u)(t) = e(t) - g(u(t)) - f(u(t))u'(t) \quad (t \in [0, T]),$$

and  $\widetilde{M} : \mathbb{R} \times \widetilde{C}_{\#}^1 \rightarrow \widetilde{C}_{\#}^1$  be the completely continuous operator defined by

$$\widetilde{M}(\bar{u}, \tilde{u}) = H \circ \phi^{-1} \circ (I - Q_{\phi}) \circ [H(I - Q)M](\bar{u} + \tilde{u}).$$

If  $u$  is a solution of (2), then

$$\frac{1}{T} \int_0^T g(u(t))dt = s, \tag{8}$$

and  $\tilde{u} = \widetilde{M}(\bar{u}, \tilde{u})$ . Reciprocally, if  $(\bar{u}, \tilde{u}) \in \mathbb{R} \times \widetilde{C}_{\#}^1$  is such that  $\tilde{u} = \widetilde{M}(\bar{u}, \tilde{u})$ , then  $u = \bar{u} + \tilde{u}$  is a solution of (2) with  $s = \frac{1}{T} \int_0^T g(u(t))dt$ . In other words,  $(\bar{u}, \tilde{u}) \in \mathbb{R} \times \widetilde{C}_{\#}^1$  satisfies  $\tilde{u} = \widetilde{M}(\bar{u}, \tilde{u})$  if and only if

$$(|\tilde{u}'|^{p-2}\tilde{u}')' + f(\bar{u} + \tilde{u})\tilde{u}' + g(\bar{u} + \tilde{u}) = e(t) + \frac{1}{T} \int_0^T g(\bar{u} + \tilde{u}(t))dt$$

**Lemma 2.** *If  $f, g : \mathbb{R} \rightarrow \mathbb{R}$  are continuous functions such that  $g$  is bounded and if  $e \in C$  satisfies (H1), then the set  $\mathcal{S}$  of solutions  $(\bar{u}, \tilde{u}) \in \mathbb{R} \times \widetilde{C}_{\#}^1$  of problem*

$$\tilde{u} = \widetilde{M}(\bar{u}, \tilde{u})$$

*contains a subset  $\mathcal{C}$  whose projection on  $\mathbb{R}$  is  $\mathbb{R}$ . Moreover, there exists  $\rho_1 > 0$  such that*

$$\|\tilde{u}\|_{\infty} \leq \rho_1 \quad \forall (\bar{u}, \tilde{u}) \in \mathcal{S} \tag{9}$$

*and for all  $\epsilon > 0$ , there exists  $r_{\epsilon} > 0$  such that*

$$\|\tilde{u}'\|_{\infty} \leq r_{\epsilon} \quad \forall (\bar{u}, \tilde{u}) \in \mathcal{S}, |\bar{u}| \leq \epsilon. \tag{10}$$

*Proof.* For each  $\lambda \in [0, 1]$  consider the problem

$$(|\tilde{u}'|^{p-2}\tilde{u}')' + \lambda f(\bar{u} + \tilde{u})\tilde{u}' + \lambda g(\bar{u} + \tilde{u}) = \lambda e(t) + \frac{\lambda}{T} \int_0^T g(\bar{u} + \tilde{u}(t))dt, \tag{11}$$

and assume that  $(\bar{u}, \tilde{u}) \in \mathbb{R} \times \widetilde{C}_{\#}^1$  is a solution of (11). Integrating (11) over  $[0, T]$  after multiplication by  $\tilde{u}$ , we get, after integration by parts

$$\|\tilde{u}'\|_p^p = \lambda \int_0^T [g(\bar{u} + \tilde{u}(t)) - e(t)]\tilde{u}dt - \frac{\lambda}{T} \int_0^T g(\bar{u} + \tilde{u}(t))dt \int_0^T \tilde{u}(t)dt.$$

Hence, using Sobolev inequality it follows that

$$\|\tilde{u}\|_{\infty}^p \leq T^{p/q} \|\tilde{u}'\|_p^p \leq T^{p/q} [2T \sup_{\mathbb{R}} |g| + \|e\|_1] \|\tilde{u}\|_{\infty},$$

and hence

$$\|\tilde{u}\|_{\infty} \leq \{T^{p/q} [2T \sup_{\mathbb{R}} |g| + \|e\|_1]\}^{1/p-1} =: \rho_1 \tag{12}$$

and

$$\|\tilde{u}'\|_p \leq \{[2T \sup_{\mathbb{R}} |g| + \|e\|_1] \rho_1\}^{1/p}. \tag{13}$$

Let  $\epsilon > 0$  be fixed and assume that  $|\bar{u}| \leq \epsilon$ . Using (11), (12) and (13) it follows that

$$\|(|\tilde{u}'|^{p-2} \tilde{u}')\|_1 \leq C_\epsilon,$$

where  $C_\epsilon$  depends only on  $e, \sup_{\mathbb{R}} |g|$  and  $\sup_{[-(\rho_1+\epsilon), \rho_1+\epsilon]} |f|$ . As  $\tilde{u}'$  necessarily vanishes at one point, this gives

$$\|\tilde{u}'\|_\infty \leq \phi^{-1}(C_\epsilon) =: r_\epsilon. \tag{14}$$

Taking  $\lambda = 1$  in (11) and using (12) and (14) we deduce (9) and (10).

Let  $\bar{u} \in \mathbb{R}$  be fixed and  $\mathcal{M}_{\bar{u}} : [0, 1] \times \widetilde{C}_{\#}^1 \rightarrow \widetilde{C}_{\#}^1$  be the completely continuous operator defined by

$$\mathcal{M}_{\bar{u}}(\lambda, \tilde{u}) = H \circ \phi^{-1} \circ (I - Q_\phi) \circ [\lambda H(I - Q)M](\bar{u} + \tilde{u}).$$

For  $(\lambda, \tilde{u}) \in [0, 1] \times \widetilde{C}_{\#}^1$ , we have that  $\mathcal{M}_{\bar{u}}(\lambda, \tilde{u}) = \tilde{u}$  if and only if  $(\bar{u}, \tilde{u})$  is a solution of (11). Hence, using (12), (14) and the homotopy invariance property of the Leray-Schauder degree, it follows that

$$\begin{aligned} d_{LS}[I - \mathcal{M}_{\bar{u}}(1, \cdot), B_r, 0] &= d_{LS}[I - \mathcal{M}_{\bar{u}}(0, \cdot), B_r, 0] \\ &= d_{LS}[I, B_r, 0] = 1, \end{aligned}$$

for some  $r$  sufficiently large. This, together with the existence property of the Leray-Schauder degree give the existence of some  $\tilde{u} \in \widetilde{C}_{\#}^1$  such that  $\widetilde{M}(\bar{u}, \tilde{u}) = \mathcal{M}_{\bar{u}}(1, \tilde{u}) = \tilde{u}$ . This completes the proof. ■

*In what follows we assume that (H1)-(H3) hold.*

Let us define

$$S_j = \{s \in \mathbb{R} : (2) \text{ has at least } j \text{ solutions} \} \quad (j \geq 1).$$

**Lemma 3.** *If  $s \in S_1$ , then  $0 < s \leq \sup_{\mathbb{R}} |g|$ .*

*Proof.* Assumptions (H2) and (H3) imply that  $g$  is bounded and  $0 < g(u) \leq \sup_{\mathbb{R}} |g|$  for all  $u \in \mathbb{R}$ . Hence, if  $u$  is a solution of (2) then, using (H1), it follows that (8) holds and  $0 < s \leq \sup_{\mathbb{R}} |g|$ . ■

Let  $\gamma : \mathbb{R} \times \widetilde{C}_{\#}^1 \rightarrow \mathbb{R}$  be the continuous function defined by

$$\gamma(\bar{u}, \tilde{u}) = \frac{1}{T} \int_0^T g(\bar{u} + \tilde{u}(t)) dt.$$

**Lemma 4.**  $S_1 \neq \emptyset$ .

*Proof.* Let  $(\bar{u}, \tilde{u}) \in \mathcal{C}$ , where  $\mathcal{C}$  is given in Lemma 2. Then  $u = \bar{u} + \tilde{u}$  is a solution of (2) with  $s = \gamma(\bar{u}, \tilde{u})$ . ■

Let us consider

$$s^*(e) = \sup S_1.$$

**Lemma 5.** *We have that  $0 < s^*(e) \leq \sup_{\mathbb{R}} |g|$  and  $s^*(e) \in S_1$ .*

*Proof.* The first assertion follows from Lemma 3. Let  $\{s_n\}$  be a sequence belonging to  $S_1$  which converges to  $s^*(e)$ . Let  $u_n = \bar{u}_n + \tilde{u}_n$  be a solution of (2) with  $s = s_n = \gamma(\bar{u}_n, \tilde{u}_n)$ . It follows that  $\tilde{u}_n = \widetilde{M}(\bar{u}_n, \tilde{u}_n)$ . Hence, if up to a subsequence  $\bar{u}_n \rightarrow \pm\infty$ , then using (9) and (H3), it follows that  $\gamma(\bar{u}_n, \tilde{u}_n) \rightarrow 0$ , which means that  $s^*(e) = 0$ , contradiction. We have proved that  $\{\bar{u}_n\}$  is a bounded sequence in  $\mathbb{R}$  and using (9) and (10) it follows that  $\{(\bar{u}_n, \tilde{u}_n)\}$  is a bounded sequence in  $\mathbb{R} \times \widetilde{C}_{\#}^1$ . Because  $\widetilde{M}$  is completely continuous, we can assume, passing to a subsequence, that  $\widetilde{M}(\bar{u}_n, \tilde{u}_n) \rightarrow \tilde{u}$  and  $\bar{u}_n \rightarrow \bar{u}$ . We deduce that  $\tilde{u} = \widetilde{M}(\bar{u}, \tilde{u})$ ,  $\gamma(\bar{u}, \tilde{u}) = s^*(e)$  and  $u$  is a solution of (2) with  $s = s^*(e)$ . ■

Arguing as in the proof of Lemma 5 we deduce the following a priori estimate result.

**Lemma 6.** *Let  $0 < s_1 < s^*(e)$ . Then, there is  $\rho' > 0$  such that any possible solution  $u$  of (2) with  $s \in [s_1, s^*(e)]$  belongs to  $B_{\rho'}$ .*

**Lemma 7.** *We have  $(0, s^*(e)) \subset S_2$ .*

*Proof.* Let  $s_1, s_2 \in \mathbb{R}$  such that  $0 < s_1 < s^*(e) < s_2$ . Using Lemma 3, Lemma 6 and the invariance property of the Leray-Schauder degree, it follows that there is  $\rho' > 0$  sufficiently large such that  $d_{LS}[I - \mathcal{G}(s, \cdot), B_{\rho'}, 0]$  is well defined and independent of  $s \in [s_1, s_2]$ . However, using Lemma 3 we deduce that  $u - \mathcal{G}(s_2, u) \neq 0$  for all  $u \in C_{\#}^1$ . This implies that  $d_{LS}[I - \mathcal{G}(s_2, \cdot), B_{\rho'}, 0] = 0$ , so that  $d_{LS}[I - \mathcal{G}(s_1, \cdot), B_{\rho'}, 0] = 0$  and, by excision property of the Leray-Schauder degree,

$$d_{LS}[I - \mathcal{G}(s_1, \cdot), B_{\rho''}, 0] = 0 \quad \text{if } \rho'' \geq \rho'. \tag{15}$$

Let  $u_*$  be a solution of (2) with  $s = s^*(e)$  given by Lemma 5. Then,  $u_*$  is a strict lower solution of (2) with  $s = s_1$ . Using Lemma 2 and (H3), there is  $(\bar{u}^*, \tilde{u}^*) \in \mathcal{C}$  such that  $u^* = \bar{u}^* + \tilde{u}^* > u_*$  on  $[0, T]$  and  $\gamma(\bar{u}^*, \tilde{u}^*) < s_1$ . It follows that  $u^*$  is a strict upper solution of (2) with  $s = s_1$ . So, using Lemma 1, we have that

$$|d_{LS}[I - \mathcal{G}(s_1, \cdot), \Omega_{u_*, u^*}^r, 0]| = 1, \tag{16}$$

for some  $r > 0$ , and (1) has a solution in  $\Omega_{u_*, u^*}^r$ . Taking  $\rho''$  sufficiently large and using (15) and (16), we deduce from the additivity property of the Leray-Schauder degree that

$$\begin{aligned} |d_{LS}[I - \mathcal{G}(s_1, \cdot), B_{\rho''} \setminus \overline{\Omega}_{u_*, u^*}^r, 0]| &= |d_{LS}[I - \mathcal{G}(s_1, \cdot), B_{\rho''}, 0]| \\ -d_{LS}[I - \mathcal{G}(s_1, \cdot), \Omega_{u_*, u^*}^r, 0] &= |d_{LS}[I - \mathcal{G}(s_1, \cdot), \Omega_{u_*, u^*}^r, 0]| = 1, \end{aligned}$$

and (2) with  $s = s_1$  has a second solution in  $B_{\rho''} \setminus \overline{\Omega}_{u_*, u^*}^r$ . ■

**End of the proof of Theorem 2.** The conclusion of Theorem 2 follows from Lemmas 3, 5 and 7. ■

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