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## COADJOINT EQUIVARIANCY OF MOMENTUM MAPPING

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1. A coadjoint orbit of a Lie group G is a G-homogeneous symplectic manifold with the inclusion map as the coadjoint equivariant momentum mapping. If  $(M, \mathcal{Q})$  is a G-homogeneous symplectic manifold with the coadjoint equivariant momentum mapping, then the coadjoint equivariant momentum mapping gives a symplectic covering mapping onto a coadjoint orbit. And we have a result of B. Kostant which classifies the (simply connected) homogeneous symplectic manifolds with coadjoint equivariant momentum mappings (cf. [1], [2], [5]). An action with a fixed point may be considered to be antipodal with a homogeneous action. As explained in [4], we have some theorems concerning with the existence of (coadjoint equivariant) momentum mappings. In particular, the following three guarantee the coadjoint equivariancy of a momentum mapping:

(1)  $H^2(\mathfrak{g}, R)=0$ , where  $\mathfrak{g}$  is the Lie algebra of G (cf. [4], [5], [6]),

(2) the symplectic form is an exact form of a G-invariant 1-form (cf. [1]), and

(3) G is a semidirect product of  $G_1$  by  $G_2$ , where  $G_1$  and  $G_2$  have coadjoint equivariant momentum mappings,  $H^1(\mathfrak{g}_1, R)=0$  and  $G_1$  is connected (cf. [3], [4]).

In this paper, we give a condition for the coadjoint equivariancy of momentum mappings. The result is

**PROPOSITION.** Let  $(M, \Omega)$  be a connected symplectic manifold, and let G be a symplectic action on  $(M, \Omega)$  with a momentum mapping. If the action G has a fixed point, then G has a coadjoint equivariant momentum mapping.

2. Let  $(M, \Omega)$  be a connected symplectic manifold, that is, M is a connected smooth manifold with a non-degenerate closed 2-form  $\Omega$ .  $\Omega$  induces a bundle isomorphism  $\Omega^{\flat}: TM \to T^*M$  between the tangent bundle and the cotangent bundle of M defined by

$$\Omega^{\flat}(v) = v \sqcup \Omega$$
.

Denote the inverse of  $\Omega^{\flat}$  by  $\Omega^*$ .  $\Omega^*: T^*M \to TM$  is also a bundle isomorphism. Let  $C^{\infty}(M)$  (resp. aut $(M, \Omega)$ ) be the set of all real valued smooth functions (resp. Hamiltonian vector fields i.e., vector field X satisfying  $L_X \Omega = 0$ ) on M.

For each  $f \in C^{\infty}(M)$ , define  $\beta(f)$  by

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$$\beta(f) = \Omega^{*}(df)$$
, or equivalently,  $\Omega^{\flat}(\beta(f)) = df$ .

Since we have

$$\begin{split} L_{\beta(f)} \mathcal{Q} &= \beta(f) \, \sqcup \, d\mathcal{Q} + d(\beta(f) \, \sqcup \, \mathcal{Q}) \\ &= d(\mathcal{Q}^{\flat}(\beta(f))) = d(df) = 0 \,, \end{split}$$

 $\beta(f) \in \operatorname{aut}(M, \Omega)$  for each  $f \in C^{\infty}(M)$ . For each f, h in  $C^{\infty}(M)$ , the Poisson bracket  $\{f, h\}$  is defined by

$$\{f, h\} = -\Omega(\beta(f), \beta(h))$$
$$= \beta(f) \sqcup dh.$$

 $C^{\infty}(M)$  is a Lie algebra with the Poisson bracket  $\{,\}$ . For example, the Jacobi identity for  $\{,\}$  comes from  $d\Omega=0$ . It is clear that  $\operatorname{aut}(M, \Omega)$  is a Lie sub-algebra of the Lie algebra of all smooth vector fields on M. Since we have

$$d \{f, h\} = d(\beta(f) \sqcup dh)$$
$$= L_{\beta(f)} dh$$
$$= L_{\beta(f)}(\beta(h) \sqcup \Omega)$$
$$= [\beta(f), \beta(h)] \sqcup \Omega$$
$$= \Omega^{\flat} [\beta(f), \beta(h)],$$

 $\beta$  satisfies  $\beta\{f, h\} = [\beta(f), \beta(h)]$ , that is,  $\beta$  is a Lie algebra homomorphism from  $C^{\infty}(M)$  into aut $(M, \Omega)$ .

Since  $L_X \Omega = dX \sqcup \Omega = d(\Omega^{\mathfrak{b}}(X))$ , for each Hamiltonian vector field X we have a closed 1-form  $\Omega^{\mathfrak{b}}(X)$ . Let  $\gamma(X)$  be the de Rham cohomology class of  $\Omega^{\mathfrak{b}}(X)$  for each X in  $\operatorname{aut}(M, \Omega)$ . We have

$$\begin{aligned} \mathcal{Q}^{\flat}([X, Y]) &= [X, Y] \, \lrcorner \, \mathcal{Q} \\ &= L_X(Y \, \lrcorner \, \mathcal{Q}) \\ &= d(X \, \lrcorner \, Y \, \lrcorner \, \mathcal{Q}) \quad \text{for each } X, Y \text{ in } \operatorname{aut}(M, \, \mathcal{Q}). \end{aligned}$$

This implies  $\gamma[X, Y]=0$ . Thus  $\gamma$  is a Lie algebra homomorphism from aut $(M, \Omega)$  into  $H^1(M, \mathbb{R})$  if we introduce the trivial Lie algebra structure in  $H^1(M, \mathbb{R})$ . We have the following short exact sequence of Lie algebra homomorphisms

$$0 \longrightarrow R \longrightarrow C^{\infty}(M) \xrightarrow{\beta} \operatorname{aut}(M, \Omega) \xrightarrow{\gamma} H^{1}(M, \mathbb{R}) \longrightarrow 0.$$

Let G be a Lie group. A smooth left action  $\phi: G \times M \to M$  is called a symplectic action of a Lie group G on a symplectic manifold  $(M, \mathcal{Q})$  if for each g in G the map  $\phi_g: M \to M: m \mapsto \phi(g, m)$  is a symplectomorphism, that is,  $\phi_g^* \mathcal{Q} = \mathcal{Q}$ . A symplectic action  $(G, \phi)$  on  $(M, \mathcal{Q})$  induces a Lie algebra homomorphism

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$$\begin{split} \rho: \mathfrak{g} &\longrightarrow \operatorname{aut}(M, \ \mathcal{Q}) \\ \rho(\xi)_m = (\psi_m)_{*e}(-\xi) \,, \end{split}$$

defined by

where g is the Lie algebra of G consisting of all left-invariant vector fields on G,  $\phi_m$  is the orbit map of  $(G, \phi)$  through m, that is,  $\phi_m(g) = \phi(g, m)$  and e is the unit of G.

A momentum mapping for the symplectic action  $(G, \phi)$  is a mapping  $J: M \to \mathfrak{g}^*$  (=the dual space of  $\mathfrak{g}$ ) such that

$$d\langle J, \xi \rangle = 
ho(\xi) ot \Omega$$
 .

This condition is equivalent to

$$d\hat{J}(\xi)\!=\!\varOmega^\flat(\rho(\xi))$$

or

$$\Omega^* d\hat{J}(\xi) = \rho(\xi) \quad \text{i.e.,} \quad \beta(\hat{J}(\xi)) = \rho(\xi) ,$$

where  $\hat{J}(\xi)$  in  $C^{\infty}(M)$  is defined by

$$\hat{J}(\xi)(m) = \langle J(m), \xi \rangle$$
.

A momentum mapping  $J: M \rightarrow g^*$  for the symplectic action  $(G, \phi)$  is coadjoint equivariant if and only if J satisfies

$$J(\phi_g(m)) = Ad(g^{-1})^* J(m)$$

for each g, m in G and M. This condition is equivalent to

$$\int Ad(g^{-1}) = \phi_g^* \int$$
 for each g in G.

Differentiating the above, we have

$$\hat{f}[\xi, \eta] = \{\hat{f}(\xi), \hat{f}(\eta)\}$$
 for each  $\xi, \eta$  in g,

that is,  $\hat{f}$  is a Lie algebra homomorphism of g into  $C^{\infty}(M)$ . We know that if the Lie group G is connected and if  $\hat{f}$  is a Lie algebra homomorphism, then J is coadjoint equivariant.

## 3. At first, we prove

LEMMA (cf. [1]). For a symplectic action  $(G, \phi)$  on a symplectic manifold  $(M, \Omega)$  we have

- (1)  $\phi_g^* \Omega^\flat \phi_{g*} = \Omega^\flat$
- (2)  $\phi_{g*}\Omega^{*}\phi_{g}^{*}=\Omega^{*}$
- (3)  $\phi_{g*}\beta(f) = \beta(\phi_{g-1}^*f)$
- (4)  $\phi_g^* \{f, h\} = \{\phi_g^* f, \phi_g^* h\}$
- (5)  $\phi_{g*}\rho(\xi) = \rho(Ad(g)\xi)$

for each g in G, f, h in  $C^{\infty}(M)$  and  $\xi$  in g. These mean that the diagrams below are commutative.



Proof of Lemma. For each g in G,  $\phi_g^* \Omega = \Omega$  implies

 $\Omega(\phi_{g*}v, \phi_{g*}w) = \Omega(v, w) \quad \text{for any } v, w \text{ in } T_m M.$ 

This means

$$(\phi_g^* \Omega^{\flat}(\phi_g * v))(w) = (\Omega^{\flat}(v))(w)$$

and proves (1). (2) is only another expression of (1). (2) implies (3), since

$$\begin{split} \phi_{g*}\beta(f) &= \phi_{g*}\Omega^*(df) = \Omega^*(\phi_{g-1}^*df) = \Omega^*(d\phi_{g-1}^*f) \\ &= \beta(\phi_{g-1}^*f) \,. \end{split}$$

The proof of (4) is

$$\phi_{g}^{*}\{f, h\} = \phi_{g}^{*}(\beta(f) \sqcup dh) = (\phi_{g^{-1}*}\beta(f)) \sqcup \phi_{g}^{*}dh$$
$$= \beta(\phi_{g}^{*}f) \sqcup d(\phi_{g}^{*}h) = \{\phi_{g}^{*}f, \phi_{g}^{*}h\}$$

using (3). (5) comes from

$$\begin{split} \phi_{g*}(\rho(\xi)_m) &= \phi_{g*}(\psi_m)_{*e}(-\xi) = (\phi_g \psi_m)_{*e}(-\xi) \\ &= (\phi_{\phi(g,m)}I_g)_{*e}(-\xi) = (\psi_{\phi(g,m)})_{*e}(-Ad(g)\xi) \\ &= \rho(Ad(g)\xi)_{\phi(g,m)}, \end{split}$$

where  $I_g$  is the inner automorphism of G induced by g and  $(I_g)_{*e} = Ad(g)$ .

Now we prove our Proposition. Let J be a given momentum mapping for the symplectic action  $(G, \phi)$ , that is,  $\hat{J}$  is linear and satisfies  $\beta \hat{J} = \rho$ . Using Lemma, we have

$$\begin{split} \beta(\phi_{g}^{*}\hat{f}(\xi)) &= \phi_{g^{-1}}^{*}\beta\hat{f}(\xi) = \phi_{g^{-1}}^{*}\rho(\xi) = \rho(Ad(g^{-1})\xi) \\ &= \beta\hat{f}(Ad(g^{-1})\xi) \quad \text{for each } g \text{ in } G. \end{split}$$

Therefore

$$\phi_{g}^{*}\hat{J}(\xi) - \hat{J}(Ad(g^{-1})\xi)$$

is a constant function on M, and so

$$\phi_{g}^{*}\hat{J}(\xi) - \hat{J}(Ad(g^{-1})\xi) = (\phi_{g}^{*}\hat{J}(\xi))(m_{0}) - \hat{J}(Ad(g^{-1})\xi)(m_{0})$$

for any given point  $m_0$  in M. Let  $m_0$  be a fixed point for the symplectic action  $(G, \phi)$ , that is,  $\phi_g(m_0) = m_0$  for each g in G. Then we have

$$\phi_g^* \hat{J}(\xi) - \hat{J}(Ad(g^{-1})\xi) = \hat{J}(\xi)(m_0) - \hat{J}(Ad(g^{-1})\xi)(m_0)$$

for each g in G. Define  $\lambda: g \to C^{\infty}(M)$  by

$$\lambda(\xi) = \hat{J}(\xi) - \hat{J}(\xi)(m_0).$$

Then  $\lambda$  is linear and satisfies  $\beta \lambda = \rho$ . Moreover we have

$$\begin{split} \phi_{g}^{*}\lambda(\xi) &= \phi_{g}^{*}\hat{J}(\xi) - \hat{J}(\xi)(m_{0}) \\ &= \hat{J}(Ad(g^{-1})\xi) - \hat{J}(Ad(g^{-1})\xi)(m_{0}) \\ &= \lambda(Ad(g^{-1})\xi) \; . \end{split}$$

Thus  $\lambda$  defines a coadjoint equivariant momentum mapping for the symplectic action  $(G, \phi)$ . This completes the proof of our Proposition.

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