# AN EXAMPLE OF RIEMANNIAN MANIFOLDS SATISFYING $R(X, Y) \cdot R=0$ BUT NOT $\nabla R=0$ 

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If a Riemannian manifold $M$ is locally symmetric, then its curvature tensor $R$ satisfies

$$
\begin{equation*}
R(X, Y) \cdot R=0 \text { for all tangent vectors } X \text { and } Y \tag{*}
\end{equation*}
$$

where the endomorphism $R(X, Y)$ operates on $R$ as a derivation of the tensor algebra at each point of $M$. Conversely, does this algebraic condition ( ${ }^{*}$ ) on the curvature tensor field $R$ imply that $M$ is locally symmetric (i.e. $\nabla R=0$ )? For this problem, K. Nomizu conjectured that the answer is affirmative in the case where $M$ is irreducible and complete and $\operatorname{dim} M \geqq 3$.

In the present paper, we shall show that, in a 4 -dimensional Euclidean space $E^{4}$, there exists an irreducible and complete hypersurface $M$ which satisfies the condition ( ${ }^{*}$ ) but is not locally symmetric.

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1. Reduction of condition (*). Let $M$ be a 3 -dimensional Riemannian manifold which is isometrically immersed in a Euclidean space $E^{4}$. Let $U$ be a neighborhood of a point $p_{0} \in M$ on which we can choose a unit vector field $N$ normal to $M$. For any vector fields $X$ and $Y$ tangent to $M$, we have the formulas of Gauss and Weingarten:

$$
\begin{align*}
& D_{X} Y=\nabla_{X} Y+H(X, Y) N,  \tag{1.1}\\
& D_{X} N=-A X
\end{align*}
$$

where $D_{X}$ and $\nabla_{X}$ denote covariant differentiations for the Euclidean connection of $E^{4}$ and the Riemannian connection on $M$, respectively. $A$ is a field of symmetric endomorphisms which corresponds to the second fundamental form $H$, that is, $H(X, Y)=g(A X, Y)$ for tangent vectors $X$ and $Y, g$ being the Riemannian metric induced from $E^{4}$. The equation of Gauss expresses the curvature tensor $R$ of $M$ by means of $A$ :

$$
R(X, Y) Z=g(Z, A Y) A X-g(Z, A X) A Y
$$

The type number $t(p)$ at $p \in M$ is, by definition, the rank of $A$ at $p$. At a point $p \in M$, let $\left\{e_{1}, e_{2}, e_{3}\right\}$ be an orthonormal basis of the tangent
space $T_{p}(M)$ such that $A e_{i}=\lambda_{i} e_{i}(i=1,2,3)$.
Lemma 1.1. (cf. [2]) At a point $p$, the condition $\left({ }^{*}\right)$ is equivalent to $\lambda_{i} \lambda_{j} \lambda_{k}\left(\lambda_{i}-\lambda_{j}\right)=0$ for $k \neq i, j$ where $i \neq j$. Thus, the condition (*) is satisfied at $p$ if either
(a)

$$
t(p)=3 \text { and } \lambda_{1}=\lambda_{2}=\lambda_{3}
$$

or
(b)

$$
t(p) \leqq 2
$$

From now on, we shall assume that the type number $t(p)$ at $p$ is not greater than 2 for any point $p \in M$ and that there exists at least one point $p_{0} \in M$ such that $t\left(p_{0}\right)$ is equal to 2 . By continuity of the eigenvalues of $A$, there exists a neighborhood $W$ on $M$ at $p_{0}$ such that $t(p)=2$ for all $p \in W$.

We shall now define a 1-dimensional distribution on $W$ as follows:

$$
T_{0}(p)=\left\{X \in T_{p}(M): A X=0\right\}
$$

Lemma 1.2. (cf. [2]) $T_{0}$ is differentiable and totally geodesic.
Let $V \in T_{0}$ be a unit vector field on $W$, then we have $\nabla_{V} V=0$ by the above lemma and hence $D_{V} V=0$ by (1.1). This means that an integral curve of $V$ is a piece of a straight line in $E^{4}$.

Lemma 1.3. $T_{0}$ is parallel in $M$ if and only if the family of integral curves of $V$ is parallel in $E^{4}$.

Proof. From (1.1), we have $D_{X} V=\nabla_{X} V$ for all vector fields $X$ tangent to $M$.

Lemma 1.4. $T_{0}$ is parallel in $M$, if $M$ is either a locally symmetric space or a locally product space as a Riemannian manifold.

Proof. Assume that $M$ is a locally product space, then it is locally of the form $M^{2} \times M^{1}$, where $M^{2}$ and $M^{1}$ are a 2-dimensional space and a 1-dimensional space, respectively. Then, the Ricci tensor field $S$ of $M$ is recurrent (i.e. $\nabla_{X} S=\alpha(X) S$ for a certain 1-form $\alpha$ and for all vector fields $X$ on $M$ ). On the other hand, since $S$ is given by

$$
S(Z, Y)=g(A Z, Y) \text { trace } A-g\left(A^{2} Z, Y\right)
$$

for vector fields $Y$ and $Z$, we have $S(V, X)=0$ for any $X$. It is easy to show that the rank of $S$ is 2 on $W$, that is, $S(Z, X)=0$ for any $X$ implies that $Z=\beta V$ for a certain scalar field $\beta$. Since

$$
\alpha(Y) S(V, X)=\left(\nabla_{Y} S\right)(V, X)=\nabla_{Y}(S(V, X))-S\left(\nabla_{Y} V, X\right)-S\left(V, \nabla_{Y} X\right)
$$

we have $S\left(\nabla_{Y} V, X\right)=0$ and hence $D_{Y} V=\nabla_{Y} V=0$ because $V$ is unit. The proof for a locally symmetric case is similar.
2. An example of Riemannian manifolds satisfying $R(X, Y) \cdot R=0$ but not $\nabla R=0$. In this section, the hypersurface $M$ in consideration will be one defined by the form $w=f(x, y, z)$ where $(x, y, z, w)$ is a Cartesian coordinate system in $E^{4}$ and $f$ is a $C^{\infty}$ real valued function defined on $E^{3}$. Of course, $M$ is deffeomorphic to $E^{3}$ and $(x, y, z)$ is a coordinate system globally defined on $M$.
$M$ is represented by a position vector $P$ as follows:

$$
P=(x, y, z, f(x, y, z))
$$

Since $P_{x}=\left(1,0,0, f_{x}\right), P_{y}=\left(0,1,0, f_{y}\right)$ and $P_{z}=\left(0,0,1, f_{z}\right)$ are tangent to $M$, the unit normal vector field on $M$ is represented by

$$
N=1 / h\left(-f_{x},-f_{y},-f_{z}, 1\right)
$$

where $h=\left(1+f_{x}^{2}+f_{y}^{2}+f_{z}^{2}\right)^{1 / 2}$. Using the formula of Gauss, the second fundamental form $H$ is represented by the coordinates $x, y, z$ as follows:

$$
H=1 / h\left[\begin{array}{lll}
f_{x x} & f_{x y} & f_{x z}  \tag{2.1}\\
f_{y x} & f_{y y} & f_{y z} \\
f_{z x} & f_{z y} & f_{z z}
\end{array}\right]
$$

Then,

$$
\operatorname{det}\left[\begin{array}{lll}
f_{x x} & f_{x y} & f_{x z} \\
f_{y x} & f_{y y} & f_{y z} \\
f_{z x} & f_{z y} & f_{z z}
\end{array}\right]=0 \text { for } \operatorname{each}(x, y, z) \in E^{3}
$$

is a condition of the type number $t(p) \leqq 2$ for each point $p \in M$.
Using a theory of implicit functions, we have the following
Lemma 2.1. Let $F(\xi, \eta, \zeta)$ be a real valued $C^{\infty}$ function defined on $E^{3}$ which has no singular point (i.e. $F_{\xi}^{2}+F_{\eta}^{2}+F_{\xi}^{2} \neq 0$ anywhere in $E^{3}$ ). If $f$ satisfies a partial differential equation

$$
F\left(f_{x}, f_{y}, f_{z}\right)=0,
$$

then $t(p) \leqq 2$ for each point $p \in M$.
Proof. It is obvious.
Lemma 2.2. Let $W$ be a neighborhood on $M$ such that for each $p \in W$, $t(p)=2$. Then, $T_{0}$ is parallel if and only if there exist real constants $a, b, c$ and $d\left(a^{2}+b^{2}+c^{2}+d^{2}=1\right)$ such that $a f_{x}+b f_{x}+c f_{z}=d$ on $W$.

Proof. The condition $a f_{x}+b f_{y}+c f_{z}=d$ is equivalent to $N \cdot V=0$ for the parallel vector field $V=(a, b, c, d)$ in $E^{4}$, which means that $V$ is tangent to $M$. And moreover, $V \in T_{0}$ (i.e. $A V=0$ ) is easily seen from (2.1). Then, by lemma $1.3, T_{0}$ is parallel. The converse is clear.

Now, let us consider the hypersurface $M$ defined by

$$
w=\left(x^{2} z-y^{2} z-2 x y\right) / 2\left(z^{2}+1\right)
$$

or

$$
2 z^{2} w-x^{2} z+y^{2} z+2 w+2 x y=0
$$

which satisfies the non-linear partial differential equation

$$
w_{x}^{2}-w_{y}^{2}+2 w_{z}=0
$$

By lemma 2.1, the type number $t(p) \leqq 2$ at each point of $M$. In fact, $t(p)=2$ almost everywhere on $M$. Then the condition $\left(^{*}\right)$ is satisfied by lemma 1.1. And there exists a neighborhood $W$ such that $t(p)=2$ for each $p \in W$. But, by lemma $2.2, T_{0}$ is not parallel on $W$ and hence $M$ is irreducible and not locally symmetric by lemma 1.4. Since $M$ is isometrically immersed and closed in $E^{4}, M$ is complete.

## References

[1] S. Kobayashi and K. Nomizu, Foundations of Differential Geometry, Vol. I, Interscience Publisher, New York, 1963.
[2] K. Nomizu, On hypersurfaces satisfying a certain condition on the curvature tensor, Tôhoku Math. J., 20 (1968), 46-59.

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