## AN EXAMPLE OF RIEMANNIAN MANIFOLDS SATISFYING $R(X, Y) \cdot R = 0$ BUT NOT $\nabla R = 0$

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If a Riemannian manifold M is locally symmetric, then its curvature tensor R satisfies

(\*)  $R(X, Y) \cdot R = 0$  for all tangent vectors X and Y,

where the endomorphism R(X, Y) operates on R as a derivation of the tensor algebra at each point of M. Conversely, does this algebraic condition (\*) on the curvature tensor field R imply that M is locally symmetric (i.e.  $\nabla R = 0$ )? For this problem, K. Nomizu conjectured that the answer is affirmative in the case where M is irreducible and complete and dim  $M \ge 3$ .

In the present paper, we shall show that, in a 4-dimensional Euclidean space  $E^*$ , there exists an irreducible and complete hypersurface M which satisfies the condition (\*) but is not locally symmetric.

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1. Reduction of condition (\*). Let M be a 3-dimensional Riemannian manifold which is isometrically immersed in a Euclidean space  $E^4$ . Let U be a neighborhood of a point  $p_0 \in M$  on which we can choose a unit vector field N normal to M. For any vector fields X and Y tangent to M, we have the formulas of Gauss and Weingarten:

(1.1) 
$$D_X Y = \nabla_X Y + H(X, Y)N,$$
$$D_X N = -AX,$$

where  $D_X$  and  $\nabla_X$  denote covariant differentiations for the Euclidean connection of  $E^4$  and the Riemannian connection on M, respectively. A is a field of symmetric endomorphisms which corresponds to the second fundamental form H, that is, H(X, Y) = g(AX, Y) for tangent vectors X and Y, g being the Riemannian metric induced from  $E^4$ . The equation of Gauss expresses the curvature tensor R of M by means of A:

$$R(X, Y)Z = g(Z, AY)AX - g(Z, AX)AY$$
.

The type number t(p) at  $p \in M$  is, by definition, the rank of A at p. At a point  $p \in M$ , let  $\{e_1, e_2, e_3\}$  be an orthonormal basis of the tangent space  $T_p(M)$  such that  $Ae_i = \lambda_i e_i$  (i = 1, 2, 3).

LEMMA 1.1. (cf. [2]) At a point p, the condition (\*) is equivalent to  $\lambda_i \lambda_j \lambda_k (\lambda_i - \lambda_j) = 0$  for  $k \neq i, j$  where  $i \neq j$ . Thus, the condition (\*) is satisfied at p if either

(a) 
$$t(p) = 3 and \lambda_1 = \lambda_2 = \lambda_3$$

or

(b) 
$$t(p) \leq 2$$
.

From now on, we shall assume that the type number t(p) at p is not greater than 2 for any point  $p \in M$  and that there exists at least one point  $p_0 \in M$  such that  $t(p_0)$  is equal to 2. By continuity of the eigenvalues of A, there exists a neighborhood W on M at  $p_0$  such that t(p) = 2 for all  $p \in W$ .

We shall now define a 1-dimensional distribution on W as follows:

$$T_0(p) = \{X \in T_p(M) : AX = 0\}$$

LEMMA 1.2. (cf. [2])  $T_0$  is differentiable and totally geodesic.

Let  $V \in T_0$  be a unit vector field on W, then we have  $\nabla_V V = 0$  by the above lemma and hence  $D_V V = 0$  by (1.1). This means that an integral curve of V is a piece of a straight line in  $E^4$ .

**LEMMA 1.3.**  $T_0$  is parallel in M if and only if the family of integral curves of V is parallel in  $E^4$ .

PROOF. From (1.1), we have  $D_X V = \nabla_X V$  for all vector fields X tangent to M.

LEMMA 1.4.  $T_0$  is parallel in M, if M is either a locally symmetric space or a locally product space as a Riemannian manifold.

PROOF. Assume that M is a locally product space, then it is locally of the form  $M^2 \times M^1$ , where  $M^2$  and  $M^1$  are a 2-dimensional space and a 1-dimensional space, respectively. Then, the Ricci tensor field S of M is recurrent (i.e.  $\nabla_X S = \alpha(X)S$  for a certain 1-form  $\alpha$  and for all vector fields X on M). On the other hand, since S is given by

$$S(Z, Y) = g(AZ, Y)$$
 trace  $A - g(A^2Z, Y)$ 

for vector fields Y and Z, we have S(V, X) = 0 for any X. It is easy to show that the rank of S is 2 on W, that is, S(Z, X) = 0 for any X implies that  $Z = \beta V$  for a certain scalar field  $\beta$ . Since

$$\alpha(Y)S(V, X) = (\nabla_Y S)(V, X) = \nabla_Y (S(V, X)) - S(\nabla_Y V, X) - S(V, \nabla_Y X) ,$$

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we have  $S(\nabla_Y V, X) = 0$  and hence  $D_Y V = \nabla_Y V = 0$  because V is unit. The proof for a locally symmetric case is similar.

2. An example of Riemannian manifolds satisfying  $R(X, Y) \cdot R = 0$ but not  $\nabla R = 0$ . In this section, the hypersurface M in consideration will be one defined by the form w = f(x, y, z) where (x, y, z, w) is a Cartesian coordinate system in  $E^4$  and f is a  $C^{\infty}$  real valued function defined on  $E^3$ . Of course, M is defined on  $E^3$  and (x, y, z) is a coordinate system globally defined on M.

M is represented by a position vector P as follows:

$$P = (x, y, z, f(x, y, z))$$
.

Since  $P_x = (1, 0, 0, f_x)$ ,  $P_y = (0, 1, 0, f_y)$  and  $P_z = (0, 0, 1, f_z)$  are tangent to M, the unit normal vector field on M is represented by

$$N = 1/h(-f_x, -f_y, -f_z, 1)$$
,

where  $h = (1 + f_x^2 + f_y^2 + f_z^2)^{1/2}$ . Using the formula of Gauss, the second fundamental form H is represented by the coordinates x, y, z as follows:

(2.1) 
$$H = 1/h \begin{bmatrix} f_{xx} & f_{zy} & f_{zz} \\ f_{yx} & f_{yy} & f_{yz} \\ f_{zx} & f_{zy} & f_{zz} \end{bmatrix}.$$

Then,

$$\det \begin{bmatrix} f_{xx} & f_{xy} & f_{xz} \\ f_{yx} & f_{yy} & f_{yz} \\ f_{zx} & f_{zy} & f_{zz} \end{bmatrix} = 0 \text{ for each } (x, y, z) \in E^{3}$$

is a condition of the type number  $t(p) \leq 2$  for each point  $p \in M$ . Using a theory of implicit functions, we have the following

LEMMA 2.1. Let  $F(\xi, \eta, \zeta)$  be a real valued  $C^{\infty}$  function defined on  $E^{3}$ which has no singular point (i.e.  $F_{\xi}^{2} + F_{\eta}^{2} + F_{\zeta}^{2} \neq 0$  anywhere in  $E^{3}$ ). If f satisfies a partial differential equation

$$F(f_x, f_y, f_z) = 0 ,$$

then  $t(p) \leq 2$  for each point  $p \in M$ .

PROOF. It is obvious.

LEMMA 2.2. Let W be a neighborhood on M such that for each  $p \in W$ , t(p) = 2. Then,  $T_0$  is parallel if and only if there exist real constants a, b, c and  $d(a^2 + b^2 + c^2 + d^2 = 1)$  such that  $af_x + bf_x + cf_z = d$  on W.

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**PROOF.** The condition  $af_x + bf_y + cf_z = d$  is equivalent to  $N \cdot V = 0$  for the parallel vector field V = (a, b, c, d) in  $E^4$ , which means that V is tangent to M. And moreover,  $V \in T_0$  (i.e. AV = 0) is easily seen from (2.1). Then, by lemma 1.3,  $T_0$  is parallel. The converse is clear.

Now, let us consider the hypersurface M defined by

$$w = (x^2 z - y^2 z - 2xy)/2(z^2 + 1)$$

or

$$2z^2w - x^2z + y^2z + 2w + 2xy = 0$$
 ,

which satisfies the non-linear partial differential equation

$$w_x^2 - w_y^2 + 2w_z = 0$$
.

By lemma 2.1, the type number  $t(p) \leq 2$  at each point of M. In fact, t(p) = 2 almost everywhere on M. Then the condition (\*) is satisfied by lemma 1.1. And there exists a neighborhood W such that t(p) = 2 for each  $p \in W$ . But, by lemma 2.2,  $T_0$  is not parallel on W and hence M is irreducible and not locally symmetric by lemma 1.4. Since M is isometrically immersed and closed in  $E^4$ , M is complete.

## References

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