## ANALYSIS \& PDE

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## NONEXISTENCE OF WENTE'S $L^{\infty}$ ESTIMATE

 FOR THE NEUMANN PROBLEMNONEXISTENCE OF WENTE'S $L^{\infty}$ ESTIMATE FOR THE NEUMANN PROBLEM

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We provide a counterexample of Wente's inequality in the context of Neumann boundary conditions. We will also show that Wente's estimate fails for general boundary conditions of Robin type.

## 1. Introduction

Wente's $L^{\infty}$ estimate is a fundamental example of a "gain" of regularity due to the special structure of Jacobian determinants. It concerns the Dirichlet problem

$$
\left\{\begin{align*}
-\Delta u=f & \text { in } D,  \tag{1-1}\\
u=0 & \text { on } \partial D
\end{align*}\right.
$$

for the specific choice of $f=\operatorname{det}(\nabla V)$ with $V \in H^{1}\left(D, \mathbb{R}^{2}\right)$. Wente's theorem states:
Theorem 1.1. Let $\Omega \subset \mathbb{R}^{2}$ be the disc and $f \in \mathcal{H}^{1}(D)$. Then if $u$ is the unique solution in $W_{0}^{1,1}(\Omega, \mathbb{R})$ to (1-1), we have the estimate

$$
\|u\|_{L^{\infty}(D)}+\|\nabla u\|_{L^{2}(D)} \leq C\|\nabla V\|_{L^{2}(D)}^{2} .
$$

The proof can be found in the original article [Wente 1971]. Later on it was proved that Wente's inequality holds true under the slightly weaker assumption that $f \in \mathcal{H}^{1}(D)$, where $\mathcal{H}^{1}(D)$ is the local Hardy space; see [Semmes 1994, Definition 1.90]. Proofs can be found for instance in [Hélein 2002; Topping 1997]. This estimate found many applications; an incomplete list includes [Rivière 2008; Colding and Minicozzi 2008; Lamm and Lin 2013].

It is natural to ask whether a similar estimate holds true for the Neumann problem

$$
\begin{cases}-\Delta u=f & \text { in } D  \tag{1-2}\\ \frac{\partial u}{\partial v}=\frac{1}{2 \pi} \int_{D} f & \text { on } \partial D\end{cases}
$$

again for the specific choice of $f=\operatorname{det}(\nabla V)$ with $V \in H^{1}\left(D, \mathbb{R}^{2}\right)$.
The aim of this note is to show that Wente's $L^{\infty}$ estimate fails for the Neumann problem.

[^0]Theorem 1.2. There exists a sequence $V_{n}=\left(a_{n}, b_{n}\right) \in C^{\infty}\left(\bar{D}, \mathbb{R}^{2}\right),\left\|\nabla V_{n}\right\|_{L^{2,1}(D)} \leq C, \int \operatorname{det}\left(\nabla V_{n}\right)=0$ for all $n$ with the property that if $u_{n} \in W^{1,1}(D)$ are the solutions to (1-2) with $f_{n}=\operatorname{det}\left(\nabla V_{n}\right)$ one has

$$
\left\|u_{n}-f_{D} u_{n}\right\|_{L^{\infty}(D)},\left\|\nabla u_{n}\right\|_{L^{2}(D)} \rightarrow+\infty \quad \text { as } n \rightarrow \infty .
$$

Additionally we can extend the above example to more general boundary conditions. Namely we have the following:

Theorem 1.3. Let $E \subset \partial D$ be a nonempty union of open intervals, with $0<\mathcal{H}^{1}(E)<2 \pi$ and $\alpha, \beta, \gamma \in \mathbb{R}$ given, with $\alpha>0, \gamma \geq 0$. There exists a sequence $V_{n}=\left(a_{n}, b_{n}\right) \in C^{\infty}\left(\bar{D}, \mathbb{R}^{2}\right)$, with $\left\|\nabla V_{n}\right\|_{L^{2,1}(D)}<C$, with the property that if $u_{n} \in W^{1,1}(D)$ is the solution to

$$
\begin{cases}-\Delta u_{n}=\operatorname{det}\left(\nabla V_{n}\right) & \text { in } D,  \tag{1-3}\\ \alpha \frac{\partial u_{n}}{\partial v}+\beta \frac{\partial u_{n}}{\partial \tau}+\gamma u_{n}=0 & \text { on } E, \\ u=0 & \text { on } \partial D \backslash E,\end{cases}
$$

one has

$$
\left\|\nabla u_{n}\right\|_{L^{2}(D)} \rightarrow \infty \quad \text { as } n \rightarrow \infty
$$

The paper is organized as follows. In Section 3 we collect some known results and a priori estimates. In Section 4 we give the proof of Theorem 1.2 and in Section 5 its extension to mixed Robin boundary conditions.

While finishing this paper the author became aware that a similar example has been found independently by Francesca Da Lio and Francesco Palmurella [2017].

## 2. Some remarks on the conformal invariance of the problem

Let $m: U \rightarrow D$ be a smooth conformal map from a domain $U$ with Lipschitz continuous boundary to the disc (i.e., up to conjugation $m$ corresponds to holomorphic map on $U$ ). If $u$ is a solution of the Dirichlet problem (1-1) then $u \circ m$ is a solution of

$$
\begin{cases}-\Delta(u \circ m)=\left(\frac{1}{2}|\nabla m|^{2}\right) f \circ m & \text { in } U \\ u \circ m=0 & \text { on } \partial U\end{cases}
$$

In particular in the case $f=\operatorname{det}(\nabla V)$ we have $\left(\frac{1}{2}|\nabla m|^{2}\right) f \circ m=\operatorname{det}(\nabla(V \circ m))$. Additionally one notes that Wente's estimate in Theorem 1.1 is as well conformally invariant since for any function $w$ one has

$$
\|w \circ m\|_{L^{\infty}(U)}=\|w\|_{L^{\infty}(D)}, \quad\|\nabla(w \circ m)\|_{L^{2}(U)}=\|\nabla w\|_{L^{2}(D)}
$$

In the case of the Neumann problem one has to be a bit more careful. If $u$ is a solution to (1-2) then $u \circ m$ solves

$$
\begin{cases}-\Delta(u \circ m)=\left(\frac{1}{2}|\nabla m|^{2}\right) f \circ m & \text { in } U \\ \frac{\partial(u \circ m)}{\partial v}=\left(\frac{1}{2}|\nabla m|^{2}\right)^{1 / 2} \frac{1}{2 \pi} \int_{D} f & \text { on } \partial U\end{cases}
$$

Although we have

$$
\frac{1}{2 \pi} \int_{D} f=\frac{1}{2 \pi} \int_{U}\left(\frac{1}{2}|\nabla m|^{2}\right) f \circ m
$$

the problem is only conformally "invariant" if $\int_{D} f=0$ since $|\nabla m|=1$ on $\partial U$ implies that $m$ is a rigid motion. Furthermore one should note that even in the case $\int f=0$, in general one has

$$
f_{U} u \circ m \neq f_{D} u
$$

Nonetheless we can forget about the additional condition $\int_{D} \operatorname{det}\left(\nabla V_{n}\right)=0$ in the proofs of Theorems 1.2 and 1.3 by the following procedure. Consider a sequence $V_{n}$ as stated, but not necessarily satisfying $\alpha_{n}:=\int \operatorname{det}\left(\nabla V_{n}\right)=0$, that is compactly supported in some ball $B_{r_{0}}(p)$ for some $0<r_{0}<\frac{1}{4}$ and $p \in \partial D$. Let us fix two smooth functions $\hat{a}, \hat{b}$ supported in $B_{2 r_{0}}(p) \backslash B_{r_{0}}(p)$ satisfying

$$
\int_{D} d \hat{a} \wedge d \hat{b}=1
$$

For instance take $\hat{a}=\varphi_{1}(z)$ and $\hat{b}=\varphi_{2}(z) \theta$, where $\varphi_{i}$ are two bump functions such that $\operatorname{spt}\left(\varphi_{1}\right) \subset$ $\left\{\varphi_{2}=1\right\}$,

$$
\int_{D} d \hat{a} \wedge d \hat{b}=\int_{\partial D} \hat{a} \nabla_{\theta} \hat{b}=\int_{\partial D} \varphi_{1}=1
$$

Let $\hat{u}$ be the smooth unique solution to (1-2) with $f_{D} \hat{u}=1, f=\operatorname{det}(\nabla \widehat{V})$ and $\widehat{V}=(\hat{a}, \hat{b})$. Since $\left|\alpha_{n}\right| \leq \frac{1}{2}\left\|\nabla V_{n}\right\|_{L^{2}(D)}^{2}$ and $\operatorname{spt}\left(V_{n}\right) \cap \operatorname{spt}(\widehat{V})=\varnothing$ for all $n$ we can pass to $\tilde{u}_{n}=u_{n}-\alpha_{n} \hat{u}$, which solves the Neumann problem (1-2) with right-hand side

$$
\operatorname{det}\left(\nabla V_{n}-\alpha \nabla \widehat{V}\right)=\operatorname{det}\left(\nabla V_{n}\right)-\alpha \operatorname{det}(\nabla \widehat{V})
$$

Since $\int_{D} \operatorname{det}\left(\nabla V_{n}-\alpha \nabla \widehat{V}\right)=0$ we have $\partial \tilde{u}_{n} / \partial v=0$ on $\partial D$. By the uniform boundedness of $\alpha_{n}$ we still have

$$
\left\|\tilde{u}_{n}-f_{D} \tilde{u}_{n}\right\|_{L^{\infty}(D)},\left\|\nabla \tilde{u}_{n}\right\|_{L^{2}(D)} \rightarrow+\infty \quad \text { as } n \rightarrow \infty
$$

and we obtain the full strength of the theorems.

## 3. Some known results

Classical solutions to (1-1) and (1-2) have to be understood in the distributional sense.
Definition 3.1. A function $u$ is called a solution of the Dirichlet problem if $u \in W_{0}^{1,1}(D, \mathbb{R})$ and

$$
\begin{equation*}
\int_{D} \nabla u \cdot \nabla \psi-f \psi=0 \quad \text { for all } \psi \in C_{0}^{1}(D) \tag{3-1}
\end{equation*}
$$

A function $u$ is called a solution of the Neumann problem if $u \in W^{1,1}(D, \mathbb{R})$ and

$$
\begin{equation*}
\frac{1}{2 \pi} \int_{D} f \int_{\partial D} \psi=\int_{D} \nabla u \cdot \nabla \psi-f \psi \quad \text { for } \psi \in C_{0}^{\infty}\left(\mathbb{R}^{2}\right) \text { for all } \psi \in C^{1}(\bar{D}) \tag{3-2}
\end{equation*}
$$

The Green's functions for both problems are explicit. For the Dirichlet problem it is

$$
\begin{equation*}
G_{D}(x, y)=\frac{1}{2 \pi} \ln (|x-y|)-\frac{1}{2 \pi} \ln \left(|y|\left|x-y^{*}\right|\right), \quad \text { with } y^{*}=\frac{y}{|y|^{2}} \tag{3-3}
\end{equation*}
$$

and for Neumann problem it is

$$
\begin{equation*}
G_{N}(x, y)=\frac{1}{2 \pi} \ln (|x-y|)+\frac{1}{2 \pi} \ln \left(|y|\left|x-y^{*}\right|\right)-\frac{1}{4}|x|^{2}-\frac{1}{4}|y|^{2} \tag{3-4}
\end{equation*}
$$

Using $G_{N}$ one has the representation formula

$$
u(y)-\int_{D} u=-\int_{\partial D} G_{N}(x, y) \frac{\partial u}{\partial v}+\int_{D} G(x, y) \Delta u \quad \text { for } u \in C^{2}(\bar{D})
$$

In terms of existence and uniqueness one has:
Lemma 3.2. For every $f \in L^{1}(D)$ there exists a solution $u_{D} / u_{N}$ to the Dirichlet/ Neumann problem in the sense of Definition 3.1. Furthermore the solutions belong to $W^{1, p}(D, \mathbb{R})$ for every $p<2$, are unique (up to constant in the Neumann problem) and satisfy the estimate

$$
\begin{equation*}
\|D u\|_{L^{p}(D)} \leq C_{p}\|f\|_{L^{1}(D)} \tag{3-5}
\end{equation*}
$$

Proof. There are several proofs in the literature treating the case of uniqueness and a priori estimates; see for instance [Littman et al. 1963; Ancona 2009, Appendix A]. In our case existence and the a priori estimate (3-5) can be obtained by using the Green's functions $G_{D}, G_{N}$. Uniqueness for the Dirichlet problem can be obtained by antisymmetric reflection: Let $u$ be a distributional solution of (3-1) with $f=0$. One checks that

$$
\hat{u}(x):= \begin{cases}u(x) & \text { for } x \in D \\ -u\left(x^{*}\right) & \text { for } x \notin D \text { with } x^{*}=x /|x|^{2}\end{cases}
$$

solves

$$
\int_{\mathbb{R}^{2}} \nabla \hat{u} \cdot \nabla \psi=\int_{D} \nabla u \cdot \nabla\left(\psi(x)-\psi\left(x^{*}\right)\right) \quad \text { for all } \psi \in C_{c}^{1}\left(\mathbb{R}^{2}\right) .
$$

But since $\psi(x)-\psi\left(x^{*}\right) \in C_{0}^{0,1}(D)$ we deduce that $\hat{u}$ is harmonic and therefore smooth in $\mathbb{R}^{2}$. Now the maximum principle applies since $u$ takes the boundary values in the strong sense.

Similarly we deduce the uniqueness in the Neumann problem using the symmetric reflection: Let $v$ be a distributional solution of (3-2) with $f=0$. As before one checks that

$$
\hat{v}(x):= \begin{cases}v(x) & \text { for } x \in D \\ v\left(x^{*}\right) & \text { for } x \notin D\end{cases}
$$

solves

$$
\int_{\mathbb{R}^{2}} \nabla \hat{v} \cdot \nabla \psi=\int_{D} \nabla v \cdot \nabla\left(\psi(x)+\psi\left(x^{*}\right)\right) \quad \text { for all } \psi \in C_{c}^{1}\left(\mathbb{R}^{2}\right)
$$

But since $\psi(x)+\psi\left(x^{*}\right) \in C^{0,1}(\bar{D})$ we deduce that $\hat{v}$ is harmonic and therefore smooth in $\mathbb{R}^{2}$. Now the maximum principle implies that $v=$ constant.

## 4. Proof of Theorem 1.2

In the following we will always identify $\mathbb{R}^{2}$ with the complex plane $\mathbb{C}$, i.e., $i=e_{2}$.
Proof of Theorem 1.2. The main step of the proof consists in the following claim: For every $r_{0}>0$ there exists a sequence $\left(a_{n}, b_{n}\right) \in C^{\infty}\left(\bar{D}, \mathbb{R}^{2}\right)$ with the properties that

$$
\begin{gather*}
\operatorname{spt}\left(a_{n}\right) \cup \operatorname{spt}\left(b_{n}\right) \subset B_{r_{0}}\left(-e_{2}\right),  \tag{4-1a}\\
a_{n}, b_{n} \rightharpoonup 0 \quad \text { in } H^{1}(D),  \tag{4-1b}\\
\left\|a_{n}\right\|_{L^{\infty}(D)}+\left\|\nabla a_{n}\right\|_{L^{2,1}(D)}, \quad\left\|b_{n}\right\|_{L^{\infty}(D)}+\left\|\nabla b_{n}\right\|_{L^{2,1}(D)} \leq C,  \tag{4-1c}\\
\left\|d a_{n} \wedge d b_{n}\right\|_{H^{-1}(D)} \rightarrow \infty \quad \text { as } n \rightarrow \infty . \tag{4-2}
\end{gather*}
$$

Given such a sequence we can conclude the theorem. Let $u_{n}$ be the unique solution to the Dirichlet problem (1-1) with right-hand side $f_{n}=d a_{n} \wedge d b_{n}$ and $h_{n}$ be the unique harmonic function satisfying

$$
\frac{\partial h_{n}}{\partial v}=\frac{\partial u_{n}}{\partial v}-\frac{1}{2 \pi} \int_{\partial D} \frac{\partial u_{n}}{\partial v} \quad \text { on } \partial D .
$$

Such a harmonic function exists since

$$
\int_{\partial D}\left(\frac{\partial u_{n}}{\partial v}-\frac{1}{2 \pi} \int_{\partial D} \frac{\partial u_{n}}{\partial v}\right)=0 .
$$

It is straightforward to check that

$$
v_{n}:=u_{n}-h_{n}
$$

is the unique solution to the Neumann problem (1-2). Observe that $v_{n}$ is a Cauchy sequence in $W^{1, p}(D)$ for all $p<2$ converging to $v \in W^{1, p}(D)$, the unique solution of (1-2) with $f=d a \wedge d b$. By Wente's theorem we have

$$
\left\|\nabla v_{n}\right\|_{L^{2}(D)} \geq\left\|\nabla h_{n}\right\|_{L^{2}(D)}-\left\|\nabla u_{n}\right\|_{L^{2}(D)} \geq\left\|\nabla h_{n}\right\|_{L^{2}(D)}-C\left\|\nabla a_{n}\right\|_{L^{2}(D)}\left\|\nabla b_{n}\right\|_{L^{2}(D)}
$$

The theorem follows by showing that

$$
\begin{equation*}
\left\|\nabla h_{n}\right\|_{L^{2}(D)} \rightarrow \infty . \tag{4-3}
\end{equation*}
$$

To do so we will use the Dirichlet-to-Neumann map in the following formulation: Let

$$
\begin{aligned}
X_{0} & :=\left\{h \in H^{1}(D): \Delta h=0 \text { in } D \text { and } f_{D} h=0\right\}, \\
Y_{0} & :=\left\{u \in H^{1}(D): f_{D} u=0\right\} .
\end{aligned}
$$

Endowed with the $L^{2}$ inner product $\langle u, v\rangle=\int_{D} \nabla u \cdot \nabla v$, we obtain Hilbert spaces satisfying $X_{0} \subset Y_{0}$. If we set $Z_{0}^{*}:=\left\{l \in Y_{0}^{*}: l(\psi)=0\right.$ for all $\left.\psi \in H_{0}^{1}(D) \cap Y_{0}\right\}$ then classical results concerning Dirichlet-to-Neumann operators imply that the operator

$$
A: X_{0} \rightarrow Z_{0}^{*}, \quad \text { with } A h:=\frac{\partial h}{\partial v}
$$

is continuous and onto; i.e., it has a continuous inverse $A^{-1}$.

Next we identify

$$
\frac{\partial u_{n}}{\partial v}-\frac{1}{2 \pi} \int_{\partial D} \frac{\partial u_{n}}{\partial v}
$$

with a linear functional $l_{n} \in Y_{0}^{*}$; i.e.,

$$
l_{n}(\psi):=\int_{\partial D}\left(\frac{\partial u_{n}}{\partial v}-\frac{1}{2 \pi} \int_{\partial D} \frac{\partial u_{n}}{\partial v}\right) \psi
$$

We will show that they are elements of $Z_{0}^{*}$ with the property that $\left\|l_{n}\right\|_{H^{-1}(D)} \rightarrow+\infty$. The normal derivative of a solution $u \in W^{1,1}(D)$ to the Dirichlet problem (1-1), with $f \in L^{1}(D)$, is given in the sense of distributions by

$$
\begin{equation*}
\int_{\partial D} \frac{\partial u}{\partial v} \psi:=\int_{D} \nabla u \cdot \nabla \psi-f \psi \quad \text { for } \psi \in C^{1}(\bar{D}) \tag{4-4}
\end{equation*}
$$

The distribution is supported on $\partial D$ since given $\psi_{1}, \psi_{2} \in C^{\infty}(\bar{D})$ with $\psi_{1}=\psi_{2}$ on $\partial D$ we have $\varphi=\psi_{1}-\psi_{2} \in C_{0}^{1}(\bar{D})$ with $\varphi=0$ on $\partial D$ and so by (3-1) we have

$$
\int_{\partial D} \frac{\partial u}{\partial v} \varphi=\int_{D} \nabla u \cdot \nabla \varphi-f \varphi=0 .
$$

By density of $C_{c}^{\infty}(D)$ in $H_{0}^{1}(D)$ we conclude $l_{n}(\psi)=0$ for all $\psi \in H_{0}^{1}(D)$. Furthermore it is straightforward to check that $l_{n}$ vanishes on the constant functions and hence $l_{n}$ is a well-defined element of $Y_{0}^{*}$, since $l_{n}(\psi)=l_{n}(\psi-f \psi)$. Thus we conclude that $l_{n} \in Z_{0}^{*}$ for all $n$. The first part of (4-4) and the second part in the definition of $l_{n}$ are uniformly bounded by Wente's theorem (Theorem 1.1) because

$$
\begin{gathered}
\int_{D} \nabla u_{n} \cdot \nabla \psi \leq\left\|\nabla u_{n}\right\|_{L^{2}(D)}\|\nabla \psi\|_{L^{2}(D)} \\
\left|\frac{1}{2 \pi} \int_{\partial D} \frac{\partial u_{n}}{\partial v}\right|=\left|\frac{1}{2 \pi} \int_{D} f_{n}\right| \leq \frac{1}{2 \pi}\left\|\nabla a_{n}\right\|_{L^{2}(D)}\left\|\nabla b_{n}\right\|_{L^{2}(D)}
\end{gathered}
$$

Hence $\left\|l_{n}\right\|_{H^{-1}(D)} \rightarrow \infty$ by (4-2). Since $h_{n}=A^{-1}\left(l_{n}\right)$ and $A^{-1}$ is continuous, we conclude (4-3).
It remains to construct the sequence $\left(a_{n}, b_{n}\right)$ with the properties (4-1)-(4-2). Performing a translation we can consider the translated disc $D^{\prime}:=D+i$; i.e., $D^{\prime} \subset H:=\mathbb{C} \cap\{y \geq 0\}=\left\{r e^{i \theta}: 0<\theta<\pi\right\}$. Furthermore one readily checks that if $\mathfrak{R}(h)$ and $\Im(h)$ are the real and imaginary parts of a holomorphic function $h$ then we have pointwise

$$
\begin{equation*}
d \mathfrak{R}(h) \wedge d \Im(h)=\left|h^{\prime}(z)\right|^{2} d x \wedge d y \quad \text { and } \quad|d \Re(h)|^{2}=|d \Im(h)|^{2}=\left|h^{\prime}(z)\right|^{2} \tag{4-5}
\end{equation*}
$$

We will construct our contradicting sequence $\left(a_{n}, b_{n}\right)$ as the real and imaginary parts of a sequence of holomorphic functions $h_{n}$ on $H$ multiplied by a truncation function $\varphi$.

Indeed consider the family of Möbius transformations of the complex plane $\mathbb{C}$

$$
m_{\epsilon}(z):=\frac{z-i \epsilon}{z+i \epsilon}
$$

We observe that $m_{\epsilon}$ maps the upper half-space $H$ onto the disc $D$ for every $\epsilon>0$. Furthermore one readily calculates

$$
\begin{equation*}
m_{\epsilon}^{\prime}(z)=\frac{2 i \epsilon}{(z+i \epsilon)^{2}}, \quad m_{\epsilon}^{-1}(z)=i \epsilon \frac{z+1}{1-z} \tag{4-6}
\end{equation*}
$$

We note that for every $\delta>0$ one has $m_{\epsilon}^{\prime}(z) \rightarrow 0$ and $m_{\epsilon}(z) \rightarrow 1$ uniformly on $\mathbb{C} \backslash D_{\delta}$ for $\epsilon \rightarrow 0$. Furthermore $m_{\epsilon}^{-1}(z) \rightarrow 0$ uniformly on $\mathbb{C} \backslash D_{\delta}(1)$. Thus we can conclude that $l_{\epsilon}:=\left|m_{\epsilon}^{\prime}(z)\right|^{2} d x \wedge d y \rightarrow \pi \delta_{0}$ in the sense of distributions; i.e., given $\psi \in C_{c}^{0}(\mathbb{C})$ arbitrary one has

$$
\int_{H} \psi(z)\left|m_{\epsilon}^{\prime}(z)\right|^{2} d x \wedge d y=\int_{D} \psi \circ m_{\epsilon}^{-1}(z) d x \wedge d y \rightarrow \psi(0) \pi
$$

Furthermore we conclude that if $\varphi$ is any cutoff function with $\varphi=1$ in a neighborhood of 0 we still have $l_{\epsilon}\left\lfloor\varphi \rightarrow \pi \delta_{0}\right.$. Since $\pi \delta_{0} \notin H^{-1}(H)$ we conclude that $\| l_{\epsilon}\left\lfloor\varphi \|_{H^{-1}(D)} \rightarrow \infty\right.$ as $\epsilon \rightarrow 0$. Fixing a sequence $\epsilon_{n} \rightarrow 0$, we have

$$
a_{n}:=\varphi \Re\left(m_{\epsilon_{n}}-1\right) \quad \text { and } \quad b_{n}:=\varphi \Im\left(m_{\epsilon_{n}}-1\right)
$$

satisfy $a_{n}, b_{n} \in C^{\infty}(H)$ and $a_{n}, b_{n} \rightarrow 0$ uniformly in $C^{1}$ on $\bar{H} \backslash D_{\delta}$ for any $\delta>0$. Hence for an appropriate choice of $\varphi$ the first two parts of (4-1) follow.

We calculate

$$
d a_{n} \wedge d b_{n}=l_{\epsilon}\left\lfloor\varphi^{2}+\varphi d \varphi \wedge\left(\Re\left(m_{\epsilon_{n}}\right) d \Im\left(m_{\epsilon_{n}}\right)-\Im\left(m_{\epsilon_{n}}\right) d \Re\left(m_{\epsilon_{n}}\right)\right)=l_{\epsilon}\left\lfloor\varphi^{2}+\varphi d \varphi \wedge w_{\epsilon}\right.\right.
$$

Since we have $\operatorname{spt}(d \varphi) \subset \mathbb{C} \backslash D_{\delta}$ for some $\delta>0$ and $\left|w_{\epsilon}\right| \rightarrow 0$ uniformly on $\mathbb{C} \backslash D_{\delta}$ we conclude that $\left\|\varphi d \varphi \wedge w_{\epsilon}\right\|_{H^{-1}} \rightarrow 0$ as $n \rightarrow \infty$. Hence $d a_{n} \wedge d b_{n} \rightarrow \pi \delta_{0}$ in the sense of distributions and therefore $\left\|d a_{n} \wedge d b_{n}\right\|_{H^{-1}(H)} \rightarrow \infty$ as $n \rightarrow \infty$; i.e., (4-2) holds.

It remains to show that $\left|d a_{n}\right|,\left|d b_{n}\right|$ are uniformly bounded in $L^{2,1}$. By (4-6) we have

$$
\left\{z \in H:\left|m_{\epsilon}^{\prime}(z)\right| \geq t\right\}=B_{r(t)}(-i \epsilon) \cap H, \quad \text { with } \frac{2 \epsilon}{r(t)^{2}}=t
$$

and $\left|m_{\epsilon}^{\prime}\right|(z) \leq 2 / \epsilon$ for all $z \in H$. Hence we may estimate

$$
\mu(t):=\left|\left\{z \in H:\left|m_{\epsilon}^{\prime}(z)\right| \geq t\right\}\right| \leq \pi r(t)^{2}=\frac{2 \epsilon}{t} \pi
$$

Recall that the $L^{2,1}$ norm can be written as

$$
\|f\|_{L^{2,1}(H)}=2 \int_{0}^{\infty} \mu_{f}(t)^{1 / 2} d t
$$

Here $\mu_{f}(t)=|\{z \in H:|f(z)|>t\}|$ is the distribution function; see [Grafakos 2014, Proposition 1.4.9]. Using the estimates above we obtain

$$
\left\|\left|m_{\epsilon}^{\prime}\right|\right\|_{L^{2,1}(H)} \leq 2 \sqrt{2 \pi \epsilon} \int_{0}^{2 / \epsilon} \frac{1}{\sqrt{t}} d t \leq 8 \sqrt{\pi}
$$

which is uniformly bounded in $\epsilon$, proving the last part of (4-1).

Remark 4.1. Observe that if the solution to the Neumann problem is not in $H^{1}(D)$ then it can neither be in $L^{\infty}$ nor in $W^{2,1}(D)$. Indeed $u \in W^{2,1}(D)$ would imply $u \in L^{\infty}$ since $W^{2,1}(D)$ embeds in $L^{\infty}$ in two dimensions; see for instance Theorem 3.3.10 combined with Theorem 3.3.4 in [Hélein 2002]. If $u$ were in $L^{\infty}(D)$ then we could take $u_{\epsilon} \in C^{\infty}(\bar{D})$ with $u_{\epsilon} \rightarrow u$ in $W^{1,1}(D)$ and uniformly bounded in $L^{\infty}(D)$. Testing (3-2) with $u_{\epsilon}$ would give

$$
\int_{D} \nabla u \cdot \nabla u_{\epsilon}=\int_{D} f u_{\epsilon}+\frac{1}{2 \pi} \int_{D} f \int_{\partial D} u_{\epsilon} \leq 2\|f\|_{L^{1}}\left\|u_{\epsilon}\right\|_{L^{\infty}}
$$

The right-hand side is bounded independent of $\epsilon$ so we conclude that $u \in H^{1}(D)$, a contradiction.
By using more or less an abstract functional analytic argument we are able to obtain the following corollary. Its proof is presented in the Appendix.
Corollary 4.2. There exists $a, b \in H^{1}(D)$ with the additional properties $a, b \in L^{\infty}(D)$ and da, $d b \in$ $L^{2,1}(D)$ such that if $u \in W^{1,1}(D)$ denotes the solution to the Neumann problem (1-2) with $f=d a \wedge d b$ then $u \notin H^{1}(D)$.

## 5. More general boundary conditions

Our construction of the counterexample relies mainly on the continuity of the Dirichlet-to-Neumann map $D_{0}$. The extension to more general boundary conditions of Robin type follows by finding a replacement of the Dirichlet-to-Neumann map. The replacement is constructed as follows:

$$
\begin{aligned}
X & :=\left\{h \in H^{1}(D): \Delta h=0 \text { in } D \text { and } h=0 \text { on } \partial D \backslash E\right\}, \\
Y & :=\left\{u \in H^{1}(D): u=0 \text { on } \partial D \backslash E\right\} .
\end{aligned}
$$

Since by assumption $\mathcal{H}^{1}(\partial D \backslash E)>0$ we can endow $X, Y$ with the norm $\|u\|=\|\nabla u\|_{L^{2}(D)}$. Finally we define the closed subset $Z^{*} \subset Y^{*}$ by

$$
Z^{*}:=\left\{l \in Y^{*}: l(u)=0 \text { for all } u \in H_{0}^{1}(D)\right\}
$$

Obviously one has the inclusion $X \subset Y$ and $Z^{*} \subset Y^{*}$.
Lemma 5.1. The operator $B: X \rightarrow Z^{*}$ defined by

$$
\langle B h, \psi\rangle=\int_{\partial D}\left(\alpha \frac{\partial h}{\partial v}+\beta \frac{\partial h}{\partial \tau}+\gamma h\right) \psi:=\alpha \int_{D} \nabla h \cdot \nabla \psi+\beta \int_{\partial D} \frac{\partial h}{\partial \tau} \psi+\gamma \int_{\partial D} h \psi
$$

is continuous and onto, with continuous inverse $B^{-1}: Z^{*} \rightarrow X$.
Proof. Instead of $B$ itself we consider the family of operators $B_{s}: X \rightarrow Z^{*}$ for $s \in[0,1] . B_{s}$ is defined as $B$ with $s \beta, s \gamma$ replacing $\beta, \gamma$. Since $h$ is harmonic in $D$ we have $\left\langle B_{s} h, \psi\right\rangle=0$ for all $\psi \in H_{0}^{1}(D)$ by density of $C_{c}^{\infty}(D)$ in $H_{0}^{1}(D)$. Furthermore we have the estimate

$$
\begin{aligned}
\left\langle B_{s} h, \psi\right\rangle & \leq \alpha\|\nabla h\|_{L^{2}(D)}+|s \beta|\left\|\frac{\partial h}{\partial \tau}\right\|_{H^{-1 / 2} \partial D}\|\psi\|_{H^{1 / 2} \partial D}+s \gamma\|h\|_{L^{2}(\partial D)}\|\psi\|_{L^{2}(\partial D)} \\
& \leq(\alpha+C|\beta|+C \gamma)\|\nabla h\|_{L^{2}(D)}\|\nabla \psi\|_{L^{2}(D)} .
\end{aligned}
$$

In the last line we used that for harmonic functions we have

$$
\left\|\frac{\partial h}{\partial \tau}\right\|_{H^{-1 / 2}(\partial D)}=\left\|\frac{\partial h}{\partial v}\right\|_{H^{-1 / 2}(\partial D)}=\|\nabla h\|_{L^{2}(D)}
$$

and the trace theorem for Sobolev functions.
This shows that $B_{s}$ is a family of uniformly bounded operators taking values in $Z^{*}$. Since $X \subset Y$ we have the lower bound

$$
\begin{aligned}
\left\langle B_{s} h, h\right\rangle & =\alpha \int_{D} \nabla h \cdot \nabla h+s \beta \frac{1}{2} \int_{\partial D} \frac{\partial h^{2}}{\partial \tau}+s \gamma \int_{\partial D} h^{2} \\
& =\alpha \int_{D} \nabla h \cdot \nabla h+s \gamma \int_{\partial D} h^{2} \geq \alpha\|\nabla h\|_{L^{2}(D)}^{2}
\end{aligned}
$$

Finally since $B_{s}=(1-s) B_{0}+s B$, the method of continuity, see, e.g., [Gilbarg and Trudinger 1998, Theorem 5.2], applies and $B=B_{1}$ is onto if and only if $B_{0}$ is onto. By construction we have $B_{0} h=\alpha(\partial h / \partial \nu)$, the classical normal derivative on $E$, which is known to be onto by the Dirichlet-to-Neumann map.

Now we are able to complete the proof of the theorem.
Proof of Theorem 1.3. The construction is now essentially the same as in the proof of Theorem 1.2. After a rotation we may assume that $-i=-e_{2} \in E$. Fix $r_{0}>0$ such that $\partial D \cap B_{r_{0}}(-i) \subset E$. Let $a_{n}, b_{n}, u_{n} \in C^{\infty}(\bar{D})$ be the sequences constructed in the proof of Theorem 1.2. By the choice of $r_{0}>0$ we have ensured that

$$
\operatorname{spt}\left(a_{n}\right) \cup \operatorname{spt}\left(b_{n}\right) \subset B_{r_{0}}(-i)
$$

Observe that

$$
l_{n}:=\alpha \frac{\partial u_{n}}{\partial v}+\beta \frac{\partial u_{n}}{\partial \tau}+\gamma u_{n} \in Z^{*}
$$

because

$$
\left\langle B u_{n}, \psi\right\rangle=\alpha \int_{\partial D} \frac{\partial u_{n}}{\partial v} \psi=\alpha \int_{D} \nabla u_{n} \cdot \nabla \psi-\alpha \int_{D} d a_{n} \wedge d b_{n} \psi
$$

and the discussion below (4-4) applies. Furthermore we have

$$
\left\|l_{n}\right\|_{Z^{*}} \geq \alpha\left\|d a_{n} \wedge d b_{n}\right\|_{H^{-1}(D)}-\alpha\left\|\nabla u_{n}\right\|_{L^{2}(D)}
$$

By Wente's theorem (Theorem 1.1), $\left\|\nabla u_{n}\right\|_{L^{2}(D)}$ is uniformly bounded and so the application of Lemma 5.1 gives for $h_{n}:=B^{-1}\left(l_{n}\right)$ that

$$
\left\|\nabla h_{n}\right\|_{L^{2}(D)} \rightarrow \infty \quad \text { as } n \rightarrow \infty
$$

We conclude by observing that $v_{n}:=u_{n}-h_{n}$ satisfies the boundary value problem (1-3) because $u_{n}=h_{n}=0$ on $\partial D \backslash E$ and

$$
\begin{cases}-\Delta v_{n}=-\Delta u_{n}=d a_{n} \wedge d b_{n} & \text { in } D \\ \alpha \frac{\partial v_{n}}{\partial v}+\beta \frac{\partial v_{n}}{\partial \tau}+\gamma v_{n}=l_{n}-B\left(h_{n}\right)=0 & \text { on } E\end{cases}
$$

The blow-up of the $H^{1}$ norm now follows since

$$
\left\|\nabla v_{n}\right\|_{L^{2}(D)} \geq\left\|\nabla h_{n}\right\|_{L^{2}(D)}-\left\|\nabla u_{n}\right\|_{L^{2}(D)} \rightarrow \infty
$$

As before we obtain as a consequence of Theorem 1.3 the following:
Corollary 5.2. There exists $a, b \in H^{1}(D)$ with the additional properties $a, b \in L^{\infty}(D)$ and $d a, d b \in$ $L^{2,1}(D)$ such that if $u \in W^{1,1}(D)$ denotes the solution to the problem (1-3) with $f=d a \wedge d b$ then $u \notin H^{1}(D)$.

Its combined proof with Corollary 4.2 can be found in the Appendix.

## Appendix: Abstract functional analytic argument

Now we want to present the abstract functional analytic argument that leads to Corollaries 4.2 and 5.2. We will first proof an "easier" version where every embedding of the involved spaces is linear. Thereafter we show how the same idea translates to our setting.

Lemma A.1. Consider Banach spaces $E_{1} \subset E_{2}$ and $F_{1} \subset F_{2}$ such that the inclusion $\subset$ corresponds to a continuous embedding. Let $A: E_{2} \rightarrow F_{2}$ be a continuous linear operator. Suppose that $F_{1}$ is a Hilbert space and there is a sequence $\left\{x_{n}\right\}_{n \in \mathbb{N}}$ with the properties that
(a) $A x_{n} \in F_{1}$ and $\left\|x_{n}\right\|_{E_{1}} \leq 1$ for all $n \in \mathbb{N}$;
(b) $\lim \sup _{n \rightarrow \infty}\left\|A x_{n}\right\|_{F_{1}}=\infty$;
(c) $f \in F_{1} \mapsto\left\langle A x_{n}, f\right\rangle$ extends to a linear functional $l_{n}$ on $F_{2}$ for each $n$.

Then there exists $x \in E_{1}$ such that $A x \in F_{2} \backslash F_{1}$ in the sense that there is a sequence $l_{n} \in F_{2}^{*}$ with $\left\|l_{n}\right\|_{F_{1}^{*}} \leq 1$ but

$$
l_{n}(A x) \rightarrow \infty
$$

Proof. Passing to a subsequence we may assume that the lim sup in (b) is actually a limit.
In a first step we show by induction that there exists $\left\{y_{1}, \ldots, y_{n}\right\} \in E_{1}$ with the properties
(i) $\left\|y_{i}\right\|_{E_{1}} \leq 1$ for all $i$;
(ii) $\left\langle A y_{i}, A y_{j}\right\rangle=0$ if $i \neq j$;
(iii) $\left\|A y_{i}\right\|_{F_{1}} \geq 2^{2 i}$ for all $i$.

By (b) there exists $m_{1} \in \mathbb{N}$ such that $\left\|A x_{m_{1}}\right\| \geq 4$. Hence we may set $y_{1}:=x_{m_{1}}$.
Now suppose $\left\{y_{1}, \ldots, y_{n}\right\}$ have been chosen. We define the linear continuous operator $P_{n}: F_{1} \rightarrow F_{1}$ by

$$
P_{n}:=\sum_{i=1}^{n} \frac{A y_{i} \otimes A y_{i}}{\left\|A y_{i}\right\|^{2}}
$$

It is obvious that $P_{n}=P_{n}^{t}$ and (ii) implies that $P_{n}^{2}=P_{n}$; i.e., $P_{n}$ is the orthogonal projection onto the finite-dimensional space $V_{n}:=\operatorname{span}\left\{A y_{1}, \ldots, A y_{n}\right\}$. Hence $\left(P_{n} A\right): E_{1} \rightarrow V_{n}$ is a continuous linear operator onto a finite-dimensional vector space. Let $\left(P_{n} A\right)^{-1}: V_{n} \rightarrow \operatorname{span}\left\{y_{1}, \ldots, y_{n}\right\}$ denote the inverse of the operator $\left(P_{n} A\right)$ restricted to the finite-dimensional space $\operatorname{span}\left\{y_{1}, \ldots, y_{n}\right\}$. We may define now the operator

$$
Q_{n}: E_{1} \rightarrow E_{1}, \quad Q_{n}:=\left(P_{n} A\right)^{-1} \circ\left(P_{n} A\right)
$$

We note that $Q_{n}$ is continuous and $Q_{n}^{2}=Q_{n}$; hence $Q_{n}$ is a projection operator. As a direct consequence we have as well that $\left(I-Q_{n}\right)$ is a continuous projection operator; here $I$ denotes the identity map on $E_{2}$.

By construction we have

$$
\begin{equation*}
P_{n} A\left(I-Q_{n}\right)=0 \tag{A-1}
\end{equation*}
$$

The range of $Q_{n}$ is finite and $\left(A Q_{n}\right)$ is a continuous operator and therefore

$$
\limsup _{m \rightarrow \infty}\left\|\left(A Q_{n}\right) x_{m}\right\|_{F_{1}}<\infty
$$

Hence we have

$$
\lim _{m \rightarrow \infty}\left\|A\left(I-Q_{n}\right) x_{m}\right\|_{F_{1}} \geq \lim _{m \rightarrow \infty}\left\|A x_{m}\right\|_{F_{1}}-\limsup _{m \rightarrow \infty}\left\|\left(A Q_{n}\right) x_{m}\right\|_{F_{1}}=\infty
$$

Thus there exists $m_{n+1} \in \mathbb{N}$ such that

$$
\left\|A\left(I-Q_{n}\right) x_{m_{n+1}}\right\|_{F_{1}}>2^{2(n+1)}\left\|I-Q_{n}\right\|
$$

We define $y_{n+1}=\left(I-Q_{n}\right) x_{m_{n+1}} /\left\|I-Q_{n}\right\|$. Clearly we have $\left\|y_{n+1}\right\|_{E_{1}} \leq 1$ and (iii) holds by the choice of $m_{n+1}$. Finally (ii) follows using that $P_{n}$ is a orthogonal projection, that $Q_{n}$ is a projection and (A-1):

$$
\left\langle A y_{i}, A y_{n+1}\right\rangle=\left\langle P_{n} A y_{i}, A\left(I-Q_{n}\right) y_{n+1}\right\rangle=\left\langle P_{n} A y_{i},\left(P_{n} A\left(I-Q_{n}\right)\right) y_{n+1}\right\rangle=0
$$

Having the sequence $\left\{y_{i}\right\}_{i \in \mathbb{N}}$ at our disposal we obtain $x$ as follows: For each $n$ we define the elements $z_{n} \in E_{1}$ and $f_{n} \in F_{1}$ by

$$
z_{n}:=\sum_{i=1}^{n} 2^{-i} y_{i} \quad \text { and } \quad f_{n}:=\sum_{i=1}^{n} 2^{-i} \frac{A y_{i}}{\left\|A y_{i}\right\|_{F_{1}}}
$$

Since $E_{1}, F_{1}$ are Banach spaces we have that their limits exist: $z=\lim _{n \rightarrow \infty} z_{n}=\sum_{i=1}^{\infty} 2^{-i} y_{i} \in E_{1}$ and

$$
f=\lim _{n \rightarrow \infty} f_{n}=\sum_{i=1}^{\infty} 2^{-i} \frac{A y_{i}}{\left\|A y_{i}\right\|_{F_{1}}}
$$

Assumption (c) implies that for each $i \in \mathbb{N}$ the map

$$
f \in F_{1} \mapsto\left\langle\frac{A y_{i}}{\left\|A y_{i}\right\|_{F_{1}}}, f\right\rangle
$$

extends to a continuous linear functional $l_{i} \in F_{1}^{*}$. Therefore the continuous linear functional $L_{n}:=$ $\sum_{i=1}^{n} 2^{-i} l_{i}$ has the desired properties using (i)-(iii) since

$$
\begin{aligned}
L_{n}(A z) & =\lim _{m \rightarrow \infty} L_{n}\left(A z_{m}\right)=\lim _{m \rightarrow \infty}\left\langle f_{n}, A z_{m}\right\rangle \\
& =\lim _{m \rightarrow \infty} \sum_{i=1}^{n} \sum_{j=1}^{m} 2^{-i-j}\left\langle\frac{A y_{i}}{\left\|A y_{i}\right\|_{F_{1}}}, A y_{j}\right\rangle=\sum_{i=1}^{n} 2^{-2 i}\left\|A y_{i}\right\|_{F_{1}} \geq n
\end{aligned}
$$

Observe that we could directly apply the above result with the following choice of spaces: let $E_{1}=$ $\mathcal{H}_{\mathrm{loc}}^{1}(D)$ be the local Hardy space of the disk, $E_{2}=L^{1}(D), F_{1}=\left\{f \in H^{1}(D): f_{D} f=0\right\}$ and $F_{2}=$ $W^{1,1}(D)$. But this would not give single elements $a, b \in H^{1}(D)$ as stated in the Corollaries 4.2 and 5.2.

Proof of Corollaries 4.2 and 5.2. We introduce the space

$$
X:=\left\{h \in H^{1}(D): f_{D} h=0 \text { and } d h \in L^{2,1}(D)\right\} .
$$

It becomes a complete Banach space with respect to the norm $\|h\|_{X}:=\|d h\|_{L^{2,1}}$. Furthermore as suggested before we set $E_{2}:=L^{1}(D), F_{1}:=H^{1}(D), F_{2}=W^{1,1}(D)$. Observe that we have a "bilinear" linear embedding of $X \times X \hookrightarrow E_{2}$ by $(h, k) \mapsto d h \wedge d k$ with $\|d h \wedge d k\|_{L^{1}} \leq\|d h\|_{L^{2,1}}\|d k\|_{L^{2,1}}$.

The construction of $(a, b)$ out of the contradicting sequence is the same in the case of a Neumann or Robin-type boundary condition. Hence we will give a simultaneous proof for both. We denote by $A: L^{1}(D) \rightarrow W^{1,1}(D)$ the solution operator to problem (1-2) or problem (1-3). Recall that by classical elliptic theory there is a constant $C_{A}>0$ such that $\|A x\|_{H^{1}} \leq C_{A}\|x\|_{L^{2}}$.

Let $\left(a_{n}, b_{n}\right) \in C^{\infty}\left(\bar{D}, \mathbb{R}^{2}\right)$ be the corresponding contradicting sequence of Theorem 1.2 or Theorem 1.3. Without loss of generality we may assume that $f a_{n}=0=f b_{n}$ for all $n$; hence $a_{n}, b_{n} \in X$. From now on we do not have to distinguish the cases anymore.

We will now proceed approximately as in Lemma A.1. By induction we show the existence of a sequence $\left\{y_{1}, y_{2}, \ldots, y_{n}\right\} \in L^{1}(D) \cap C^{\infty}(\bar{D})$ with the properties
(i) $\left\|y_{i}\right\|_{L^{1}} \leq 1$ for all $i$;
(ii) $\left\langle A y_{i}, A y_{j}\right\rangle=0$ if $i \neq j$;
(iii) $\left\|A y_{i}\right\|_{F_{1}} \geq 2^{3 i}$ for all $i$.

Simultaneously we will construct a sequence of tuples $\left(h_{i}, k_{i}\right) \in X \cap C^{\infty}(\bar{D}) \times X \cap C^{\infty}(\bar{D}), i=1, \ldots, n$, such that
(1) $\left\|h_{i}\right\|_{L^{\infty}}+\left\|d h_{i}\right\|_{L^{2,1}}+\left\|k_{i}\right\|_{L^{\infty}}+\left\|d k_{i}\right\|_{L^{2,1}} \leq 1$;
(2) $d h_{i} \wedge d k_{i}=y_{i}+R_{i}$ with $\left\|R_{i}\right\|_{L^{2}} \leq 1$;
(3) $\left\|d h_{i}\right\|_{L^{2}}+\left\|d k_{i}\right\|_{L^{2}} \leq\left(1+\sum_{j<i}\left\|d h_{j}\right\|_{L^{\infty}}+\left\|d k_{j}\right\|_{L^{\infty}}\right)^{-1}$.

We start the induction by choosing $\left(a_{1}, b_{1}\right)$ in the contradicting sequence such that $\left\|A\left(d a_{1} \wedge d b_{1}\right)\right\|>2^{2}$. We set $y_{1}=d a_{1} \wedge d b_{1}$ and $\left(h_{1}, k_{1}\right)=\left(a_{1}, b_{1}\right)$. All properties are clearly satisfied $\left(R_{1}=0\right)$.

Now suppose that we have chosen $y_{i},\left(h_{i}, k_{i}\right)$ for $i=1, \ldots, n$. We want to construct $y_{n+1}$ and the tuple $\left(h_{n+1}, k_{n+1}\right)$. As in the previous lemma we define the projection operators

$$
P_{n}:=\sum_{i=1}^{n} \frac{A y_{i} \otimes A y_{i}}{\left\|A y_{i}\right\|^{2}}, \quad Q_{n}:=\left(P_{n} A\right)^{-1}\left(P_{n} A\right)
$$

Here $\left(P_{n} A\right)^{-1}$ denotes as before the inverse of $\left(P_{n} A\right)$ if restricted to the space $\operatorname{span}\left\{y_{1}, \ldots, y_{n}\right\}$. Hence for all $x \in L^{1}(D)$ we have $Q_{n} x=\sum_{i=1}^{n} \alpha_{i} y_{i}$ and the existence of a constant $C_{n}>0$ such that $\sum_{i=1}^{n}\left|\alpha_{i}\right| \leq C_{n}$ for all $x \in L^{1}(D)$ with $\|x\|_{L^{1}} \leq 1$. Furthermore due to the properties of the contradicting sequence, there exists $m \in \mathbb{N}$ such that

$$
\left\|A\left(I-Q_{n}\right) d a_{m} \wedge d b_{m}\right\|_{H^{1}} \geq 2^{3(n+1)} C_{n}^{2}\left(n+3+\sum_{j \leq n}\left\|d h_{j}\right\|_{L^{\infty}}+\left\|d k_{j}\right\|_{L^{\infty}}\right)^{2}
$$

Let $Q_{n} d a_{m} \wedge d b_{m}=\sum_{i=1}^{n} \alpha_{i} y_{i}$, and define the elements

$$
\tilde{y}_{n+1}:=\left(I-Q_{n}\right) d a_{m} \wedge d b_{m}, \quad \tilde{h}_{n+1}:=a_{m}-\sum_{i=1}^{n} \alpha_{i} h_{i}, \quad \tilde{k}_{n+1}:=b_{m}+\sum_{i=1}^{n} k_{i}
$$

We calculate

$$
\begin{aligned}
& d \tilde{h}_{n+1} \wedge d \tilde{k}_{n+1}= d a_{m} \wedge d b_{m}- \\
& \sum_{i=1}^{n}\left(\alpha_{i} d h_{i} \wedge d k_{i}\right) \\
&+\underbrace{d\left(-\sum_{i=1}^{n} \alpha_{i} h_{i}\right) \wedge d b_{m}}_{(I)}+\underbrace{d a_{m} \wedge d\left(\sum_{i=1}^{n} k_{i}\right)}_{(I I)}-\underbrace{\sum_{i<j}\left(\alpha_{i} d h_{i} \wedge d k_{j}+\alpha_{j} d h_{j} \wedge d k_{i}\right)}_{(I I I)} \\
& \stackrel{(2)}{=} d a_{m} \wedge d b_{m}-\sum_{i=1}^{n} \alpha_{i} y_{i}-\sum_{i=1}^{n} \alpha_{i} R_{i}+(I)+(I I)+(I I I) .
\end{aligned}
$$

We estimate the size of the remainder terms in $L^{2}(D)$ : Due to (2), we have $\left\|\sum_{i=1}^{n} \alpha_{i} R_{i}\right\|_{L^{2}} \leq C_{n}$. The terms (I), (II) are similarly estimated by

$$
\begin{aligned}
\left\|d\left(-\sum_{i=1}^{n} \alpha_{i} h_{i}\right) \wedge d b_{m}\right\|_{L^{2}} & \leq\left(\sum_{i=1}^{n}\left|\alpha_{i}\right|\left\|d h_{i}\right\|_{L^{\infty}}\right)\left\|d b_{m}\right\|_{L^{2}} \\
\left\|d a_{m} \wedge d\left(\sum_{i=1}^{n} k_{i}\right)\right\|_{L^{2}} & \leq\left(\sum_{i=1}^{n}\left\|d k_{i}\right\|_{L^{\infty}}\right)\left\|d a_{m}\right\|_{L^{2}}
\end{aligned}
$$

Adding both we obtain $\|(I)\|_{L^{2}}+\|(I I)\|_{L^{2}} \leq C_{n}\left(1+\sum_{j \leq n}\left\|d h_{j}\right\|_{L^{\infty}}+\left\|d k_{j}\right\|_{L^{\infty}}\right)$. The last term can be estimated using only property (3) by

$$
\begin{aligned}
\|(I I I)\|_{L^{2}} & \leq \sum_{i=1}^{n}\left|\alpha_{i}\right|\left\|d h_{i}\right\|_{L^{2}}\left(\sum_{j<i}\left\|d k_{j}\right\|_{L^{\infty}}\right)+\left\|d k_{i}\right\|_{L^{2}}\left(\sum_{j<i}\left|\alpha_{j}\right|\left\|d h_{j}\right\|_{L^{\infty}}\right) \\
& \leq\left(\sum_{i=1}^{n}\left|\alpha_{i}\right|\right)+\sup _{j \leq n}\left|\alpha_{j}\right| n \leq(n+1) C_{n} .
\end{aligned}
$$

Hence we found that $\left\|\widetilde{R}_{n+1}\right\|_{L^{2}} \leq C_{n}\left(n+3+\sum_{j \leq n}\left\|d h_{j}\right\|_{L^{\infty}}+\left\|d k_{j}\right\|_{L^{\infty}}\right)$, where $\widetilde{R}_{n+1}=-\sum_{i=1}^{n} \alpha_{i} R_{i}+$ $(I)+(I I)+(I I I)$ and

$$
d \tilde{h}_{n+1} \wedge d \tilde{k}_{n+1}=\left(I-Q_{n}\right) d a_{m} \wedge d b_{m}+\widetilde{R}_{n+1}=\tilde{y}_{n+1}+\widetilde{R}_{n+1}
$$

The desired functions are now simply

$$
y_{n+1}=\frac{\tilde{y}_{n+1}}{\lambda_{n}}, \quad h_{n+1}=\frac{\tilde{h}_{n+1}}{\lambda_{n}}, \quad k_{n+1}=\frac{\tilde{k}_{n+1}}{\lambda_{n}}, \quad \text { with } \lambda_{n}=C_{n}\left(n+3+\sum_{j \leq n}\left\|d h_{j}\right\|_{L^{\infty}}+\left\|d k_{j}\right\|_{L^{\infty}}\right)
$$

Having established the existence of the sequences $y_{i}, h_{i}, k_{i}$ with the claimed properties we construct $a, b \in X$ and a sequence $f_{n} \in H^{1}(D)=F_{1}$ very much as in the proof of Lemma A.1: Due to (1) and the
fact that $X$ is a complete Banach space we can define elements

$$
a:=\sum_{i=1}^{\infty} 2^{-i} h_{i}, \quad b:=\sum_{i=1}^{\infty} 2^{-i} k_{i}
$$

Furthermore for each $n \in \mathbb{N}$ let

$$
f_{n}:=\sum_{i=1}^{n} 2^{-i} \frac{A y_{i}}{\left\|A y_{i}\right\|_{H^{1}}}
$$

Observe that $f_{n}$ is a finite sum of $C^{1}$-functions; hence it is $C^{1}$ and can therefore be considered as an element of $\left(L^{1}\right)^{*}=L^{\infty}$. It remains to check that $\lim _{n \rightarrow \infty} \int_{D} f_{n} A(d a \wedge d b)=+\infty$. We have

$$
A(d a \wedge d b)=\lim _{m \rightarrow \infty} \sum_{i=1}^{m} 2^{-2 i} A\left(d h_{i} \wedge d k_{i}\right)+\sum_{i<j}^{m} 2^{-i-j} A\left(d h_{i} \wedge d k_{j}+d h_{j} \wedge d k_{i}\right)
$$

Using (2) we estimate

$$
\left\langle\frac{A y_{k}}{\left\|A y_{k}\right\|_{H^{1}}}, A\left(d h_{i} \wedge d k_{i}\right)\right\rangle=\left\langle\frac{A y_{k}}{\left\|A y_{k}\right\|_{H^{1}}}, A y_{i}+A R_{i}\right\rangle \geq \delta_{k i}\left\|A y_{i}\right\|_{H^{1}}-C_{A}\left\|R_{i}\right\|_{L^{2}} \geq \delta_{k i}\left\|A y_{i}\right\|_{H^{1}}-C_{A}
$$

Hence

$$
\sum_{i=1}^{m} 2^{-2 i}\left\langle\frac{A y_{k}}{\left\|A y_{k}\right\|_{H^{1}}}, A\left(d h_{i} \wedge d k_{i}\right)\right\rangle \geq 2^{-2 k}\left\|A y_{k}\right\|_{H^{1}}-\lim _{m \rightarrow \infty} \sum_{i=1}^{m} 2^{-2 i} C_{A} \geq 2^{k}-C_{A}
$$

Using (3) we get

$$
\begin{aligned}
\sum_{i<j}^{m} 2^{-i-j}\left\|A\left(d h_{i} \wedge d k_{j}+d h_{j} \wedge d k_{i}\right)\right\|_{H^{1}} & \leq C_{A} \sum_{i<j}^{m} 2^{-i-j}\left(\left\|d h_{i}\right\|_{L^{2}}\left\|d k_{j}\right\|_{L^{\infty}}+\left\|d h_{j}\right\|_{L^{\infty}}\left\|d k_{i}\right\|_{L^{2}}\right) \\
& \leq C_{A} \sum_{i=1}^{m} 2^{-i} 2 \leq 2 C_{A}
\end{aligned}
$$

Finally combining both we obtain

$$
\left\langle\frac{A y_{k}}{\left\|A y_{k}\right\|_{H^{1}}}, A(d a \wedge d b)\right\rangle \geq 2^{k}-3 C_{A} .
$$

This completes the estimate since

$$
\int_{D} f_{n} A(d a \wedge d b)=\sum_{k=1}^{n} 2^{-k}\left\langle\frac{A y_{k}}{\left\|A y_{k}\right\|_{H^{1}}}, A(d a \wedge d b)\right\rangle \geq n-3 C_{A}
$$

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