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Let $u$ be a mapping from a bounded domain $S \subset \mathbb{R}^{4}$ into a compact Riemannian manifold $N$. Its intrinsic biharmonic energy $E_{2}(u)$ is given by the squared $L^{2}$-norm of the intrinsic Hessian of $u$. We consider weakly converging sequences of critical points of $E_{2}$. Our main result is that the energy dissipation along such a sequence is fully due to energy concentration on a finite set and that the dissipated energy equals a sum over the energies of finitely many entire critical points of $E_{2}$.

## 1. Introduction and main result

Let $S \subset \mathbb{R}^{4}$ be a bounded Lipschitz domain and let $N$ be a compact Riemannian manifold without boundary. For convenience we assume that $N$ is embedded in $\mathbb{R}^{n}$ for some $n \geq 2$. We denote the second fundamental form of this embedding by $A$ and we denote the Riemannian curvature tensor of $N$ by $R$. For $u \in C^{\infty}(S, N)$ define the pull-back vector bundle $u^{-1} T N$ in the usual way and denote the norm on it and on related bundles by $|\cdot|$. Together with the Levi-Cività connection on the tangent bundle $T N$, the mapping $u$ induces a covariant derivative $\nabla^{u}$ on $u^{-1} T N$. We extend this covariant derivative to tensor fields in the usual way. Denote by $\pi_{N}$ the nearest point projection from a neighborhood of $N$ onto $N$ and set $P_{u}(x)=D \pi_{N}(u(x))$. Then $P_{u}(x)$ is the orthogonal projection from $\mathbb{R}^{4}$ onto the tangent space $T_{u(x)} N$ to $N$ at $u(x)$. Let $X \in L^{2}\left(S, \mathbb{R}^{n}\right)$ be a section of $u^{-1} T N$. Following [Moser 2008] we define

$$
\nabla^{u} X=\left(P_{u} \partial_{\alpha} X\right) \otimes d x^{\alpha}
$$

Denote the derivative of $u$ by $D u=\left(\partial_{\alpha} u\right) \otimes d x^{\alpha}$. The intrinsic Hessian $\nabla^{u} D u$ is a section of $(T S)^{*} \otimes$ $(T S)^{*} \otimes u^{-1} T N$. By a standard fact about $D \pi_{N}$, it is given by

$$
\begin{aligned}
\nabla^{u} D u & =\left(P_{u} \partial_{\alpha} \partial_{\beta} u\right) \otimes d x^{\alpha} \otimes d x^{\beta} \\
& =\left(\partial_{\alpha} \partial_{\beta} u+A(u)\left(\partial_{\alpha} u, \partial_{\beta} u\right)\right) \otimes d x^{\alpha} \otimes d x^{\beta}
\end{aligned}
$$

We define the Sobolev spaces

$$
W^{k, p}(S, N)=\left\{u \in W^{k, p}\left(S, \mathbb{R}^{n}\right): u(x) \in N \text { for almost all } x \in S\right\}
$$

[^0]and we introduce the energy functional $E_{2}: W^{2,2}(S, N) \rightarrow \mathbb{R}_{+}$given by
$$
E_{2}(u)=\frac{1}{4} \int_{S}\left|\nabla^{u} D u\right|^{2}
$$

Critical points of $E_{2}$ are called intrinsically biharmonic mappings. There are also other kinds of second order functionals whose critical points are called "biharmonic" mappings. The functional $E_{2}$ is defined intrinsically, that is, it does not depend on the embedding of $N$ into $\mathbb{R}^{n}$. Another intrinsically defined second order functional that is naturally associated with $u$ is $F_{2}(u)=\frac{1}{4} \int_{S}|\tau(u)|^{2}$, where $\tau(u):=$ trace $\nabla^{u} D u$ denotes the tension field of $u$. Critical points of $F_{2}$ are usually called intrinsically biharmonic mappings. Another functional that can be associated with $u$ is the energy $\tilde{E}_{2}(u)=\frac{1}{4} \int_{S}\left|D^{2} u\right|^{2}$. Its critical points are usually called extrinsically biharmonic mappings. The functional $\tilde{E}_{2}$ enjoys better analytical properties than $E_{2}$ and $F_{2}$, but it has the drawback of depending on the particular embedding of $N$ into $\mathbb{R}^{n}$.

Biharmonic mappings, being the next higher order equivalent of harmonic mappings, have attracted a lot of attention in the differential geometry literature; see [Montaldo and Oniciuc 2006] for an overview. Analytic aspects of the problem are less well understood, and on questions other than regularity (see [Chang et al. 1999; Wang 2004b; Wang 2004a; Wang 2004c; Lamm and Rivière 2008; Struwe 2008]) not much work has been done. This is the case in particular for intrinsic biharmonic mappings, because the problem is difficult due to a lack of coercivity of the corresponding functions in the Sobolev spaces traditionally used. Thus despite the fact that the intrinsic case is geometrically more interesting, the problem has not widely been studied from the analysis point of view.

Recent progress has been made, however, based on the observation that the lack of coercivity can be removed for one type of intrinsic biharmonic mappings (the type studied in the present paper), provided that one works in a geometrically motivated variant of Sobolev spaces [Moser 2008; Scheven 2009]. This approach permits methods analogous to what has been used for harmonic mappings. But since we have a fourth order equation for biharmonic mappings (in contrast to second order for harmonic mappings), and since we have to work in different spaces, such an approach still requires additional ideas and arguments. In this paper, we develop the theory a step further.

The existence of minimizers of $E_{2}$ under given boundary conditions on the mapping itself and on its first derivatives was established in [Moser 2008] using the direct method of the calculus of variations. For simplicity, from now on we will omit the adverb "intrinsically":

In the present paper, a mapping $u \in W^{2,2}(S, N)$ will be called biharmonic if it is critical for $E_{2}$ under outer variations, that is,

$$
\left.\frac{d}{d t}\right|_{t=0} E_{2}\left(\pi_{N}(u+t \phi)\right)=0 \quad \text { for all } \phi \in C_{0}^{\infty}\left(S, \mathbb{R}^{n}\right)
$$

see [Scheven 2009; Moser 2008]. In [Scheven 2009] it is shown that a mapping $u \in W^{2,2}(S, N)$ is biharmonic precisely if it satisfies

$$
\begin{equation*}
\int_{S} \nabla_{\alpha} \partial_{\beta} u \cdot\left(\nabla_{\alpha} \nabla_{\beta} \phi+R(u)\left(\phi, \partial_{\alpha} u\right) \partial_{\beta} u\right)=0 \tag{1}
\end{equation*}
$$

for every section $\phi \in W_{0}^{2,2}\left(S, \mathbb{R}^{n}\right) \cap L^{\infty}\left(S, \mathbb{R}^{n}\right)$ of $u^{-1} T N$.

We will study sequences of biharmonic mappings $\left(u_{k}\right) \subset W^{2,2}(S, N)$ with uniformly bounded energy, that is, $\lim \sup _{k \rightarrow \infty} E_{2}\left(u_{k}\right)<\infty$. Since our results are analogous to known facts about harmonic mappings, we describe the situation encountered in that context: Let $\Omega \subset \mathbb{R}^{2}$ be a bounded Lipschitz domain in $\mathbb{R}^{2}$. A mapping $u \in W^{1,2}(\Omega, N)$ is said to be (weakly) harmonic if it is a critical point for the Dirichlet energy

$$
E_{1}(u)=\frac{1}{2} \int_{\Omega}|D u|^{2}
$$

A given sequence $\left(u_{k}\right) \subset W^{1,2}(\Omega, N)$ of harmonic mappings with uniformly bounded Dirichlet energy has a subsequence that converges weakly in $W^{1,2}$ to some mapping $u \in W^{1,2}(\Omega, N)$. This convergence in general fails to be strong, that is, in general $\liminf _{k \rightarrow \infty} E_{1}\left(u_{k}\right)>E_{1}(u)$. The only reason for this loss is that the energy can concentrate on a lower dimensional subset $\Sigma_{0} \subset \Omega$. In particular, $u_{k} \rightarrow u$ in $C_{\text {loc }}^{1}\left(\Omega \backslash \Sigma_{0}, \mathbb{R}^{n}\right)$. By the results in [Hélein 1991; Hélein 1990], the mappings $u_{k}$ and $u$ are smooth. In addition, the set $\Sigma_{0}$ is finite. Moreover, for each point $x \in \Sigma_{0}$ there exist $M_{x} \in \mathbb{N}$ and entire harmonic mappings $v_{1}^{x}, \ldots, v_{M_{x}}^{x} \in C^{\infty}\left(\mathbb{R}^{2}, N\right)$ such that, after passing to a subsequence,

$$
\lim _{k \rightarrow \infty} \int_{\Omega}\left|D u_{k}\right|^{2} \geq \int_{\Omega}|D u|^{2}+\sum_{x \in \Sigma_{0}} \sum_{j=1}^{M_{x}} \int_{\mathbb{R}^{2}}\left|v_{j}^{x}\right|^{2}
$$

Later the converse inequality was shown to hold as well [Jost 1991; Parker 1996; Ding and Tian 1995]. Our main result is the analogue of these facts for critical points of the functional $E_{2}$. It is summarized in the following theorem:

Theorem 1.1. Let $S \subset \mathbb{R}^{4}$ be a bounded Lipschitz domain and let $N$ be a smooth compact manifold without boundary embedded in $\mathbb{R}^{n}$. Let $\left(u_{k}\right) \subset W^{2,2}(S, N)$ be a sequence of biharmonic mappings and assume that

$$
\begin{equation*}
\limsup _{k \rightarrow \infty} \int_{S}\left|\nabla^{u_{k}} D u_{k}\right|^{2}+\left|D u_{k}\right|^{4}<\infty \tag{2}
\end{equation*}
$$

Then $u_{k} \in C^{\infty}(S, N)$ and we may pass to a subsequence in $k$ (again called $\left(u_{k}\right)$ ) and find a biharmonic map $u \in C^{\infty}(S, N)$ and a finite set $\Sigma_{0} \subset S$ such that
(i) $u_{k} \rightharpoonup u$ weakly in $\left(W^{2,2} \cap W^{1,4}\right)\left(S, \mathbb{R}^{n}\right)$,
(ii) $u_{k} \rightarrow u$ in $C_{\mathrm{loc}}^{2}\left(S \backslash \Sigma_{0}, \mathbb{R}^{n}\right)$.

Moreover, for each $x \in \Sigma_{0}$ there exist $M_{x} \in \mathbb{N}$ and biharmonic mappings $v_{1}^{x}, \ldots, v_{M_{x}}^{x} \in C^{\infty}\left(\mathbb{R}^{4}, N\right)$ such that

$$
\begin{align*}
\lim _{k \rightarrow \infty} \int_{S}\left|\nabla^{u_{k}} D u_{k}\right|^{2} & =\int_{S}\left|\nabla^{u} D u\right|^{2}+\sum_{x \in \Sigma_{0}} \sum_{j=1}^{M_{x}} \int_{\mathbb{R}^{4}}\left|\nabla^{v_{j}^{x}} D v_{j}^{x}\right|^{2} \\
\lim _{k \rightarrow \infty} \int_{S}\left|D u_{k}\right|^{4} & =\int_{S}|D u|^{4}+\sum_{x \in \Sigma_{0}} \sum_{j=1}^{M_{x}} \int_{\mathbb{R}^{4}}\left|D v_{j}^{x}\right|^{4} \tag{3}
\end{align*}
$$

Remarks. (i) By [Moser 2008, Theorem 2.1] the hypothesis (2) is equivalent to the seemingly weaker hypothesis $\lim \sup _{k \rightarrow \infty} \int_{S}\left|\nabla^{u_{k}} D u_{k}\right|^{2}+\left|D u_{k}\right|^{2}<\infty$ and also to the seemingly stronger hypothesis

$$
\limsup _{k \rightarrow \infty}\left\|u_{k}\right\|_{W^{2,2}(S, N)}<\infty
$$

(ii) Moser [2008] showed that every biharmonic mapping $v \in W^{2,2}(S, N)$ in fact satisfies $v \in C^{\infty}(S, N)$.
(iii) To obtain smoothness of the limiting mapping $u$ as well, one needs a removability result for isolated singularities of biharmonic mappings. This is derived in Lemma 2.3 below. Another auxiliary result is the existence of a uniform lower bound on the energy of entire nonconstant biharmonic mappings, given in Lemma 2.6 below. Analogues of these facts are well known for harmonic mappings and also for critical points of other higher order functionals; see for example [Wang 2004b].
(iv) The main contribution of Theorem 1.1 are the energy identities of (3). To obtain an equality (and not just a lower bound for the left hand sides), one has to show that no energy concentrates in a "neck" region around a concentration point $x \in \Sigma_{0}$. This is proven in Section 3 below. Similar results are known in the context of harmonic mappings; see for example [Jost 1991; Parker 1996; Ding and Tian 1995; Lin and Rivière 2002]. They are also known for other kinds of biharmonic mappings, but only if the target manifold is a round sphere, since then the Euler-Lagrange equations enjoy a special structure [Wang 2004b]. Under the general hypotheses of Theorem 1.1 no such structure seems available, so a different approach is needed.

Notation. By $e_{1}, \ldots, e_{4}$ we denote the standard basis of $\mathbb{R}^{4}$. We also set $e_{r}(x)=x /|x|$ for all $x \in \mathbb{R}^{4}$. By $B_{r}(x)$ we denote the open ball in $\mathbb{R}^{4}$ with center $x$ and radius $r$. We set $B_{r}=B_{r}(0)$. If $A$ and $B$ are tensors of the same type, then $A \cdot B$ denotes their scalar product. We will often write $\nabla D u$ instead of $\nabla^{u} D u$, and we identify $\mathbb{R}^{k}$ with its dual $\left(\mathbb{R}^{k}\right)^{*}$, writing, for example, $e_{\alpha}$ instead of $d x^{\alpha}$.

## 2. Proof of Theorem 1.1

We define the energy densities

$$
e_{1}(u)=|D u|^{4} \quad \text { and } \quad e_{2}(u)=|\nabla D u|^{2} .
$$

(These should not be confused with the unit vectors in $\mathbb{R}^{4}$.) We also set $e(u)=e_{1}(u)+e_{2}(u)$. For $U \subset S$ we define $\mathscr{E}_{i}(u ; U)=\int_{U} e_{i}(u)$, where $i=1,2$, and we define $\mathscr{E}(u ; U)=\mathscr{E}_{1}(u ; U)+\mathscr{E}_{2}(u ; U)$.

Theorem 1.1 is a consequence of the following two propositions.
Proposition 2.1. There exists an $\varepsilon_{1}>0$ such that the following holds: Let $\left(u_{k}\right) \subset W^{2,2}(S, N)$ be a sequence of biharmonic mappings (so $u_{k} \in C^{\infty}(S, N)$ ) and assume that $u \in W^{2,2}(S, N)$ is such that

$$
\begin{equation*}
u_{k} \rightharpoonup u \quad \text { weakly in }\left(W^{2,2} \cap W^{1,4}\right)\left(S, \mathbb{R}^{n}\right) \tag{4}
\end{equation*}
$$

Define

$$
\Sigma_{0}=\left\{x \in S: \liminf _{k \rightarrow \infty} \mathscr{E}\left(u_{k} ; B_{r}(x)\right) \geq \varepsilon_{1} / 2 \text { for all } r>0\right\}
$$

Then $u \in C^{\infty}(S, N)$ is biharmonic and $u_{k} \rightarrow u$ in $C_{\text {loc }}^{2}\left(S \backslash \Sigma_{0}, N\right)$. Moreover, there exist functions $\theta_{1}$, $\theta_{2}: \Sigma_{0} \rightarrow(0, \infty)$ such that $\theta_{1}(x) \geq \varepsilon_{1}$ for all $x \in \Sigma_{0}$ and

$$
\begin{equation*}
\mathscr{L}^{4}\left\lfloore _ { i } ( u _ { k } ) \stackrel { * } { \rightharpoonup } \mathscr { L } ^ { 4 } \left\lfloor e_{i}(u)+\sum_{x \in \Sigma_{0}} \theta_{i}(x) \delta_{\{x\}} \quad \text { for } i=1,2\right.\right. \tag{5}
\end{equation*}
$$

weakly-* in the dual space of $C_{0}^{0}(S)$.
Remarks. (i) By Remark (i) following Theorem 1.1, the hypothesis (2) implies (4) for a subsequence.
(ii) The measures $\sum_{x \in \Sigma_{0}} \theta_{i}(x) \delta_{\{x\}}$ are called defect measures. Their common support $\Sigma_{0}$ is empty if and only if the convergence (4) is strong. In that case the last sum in (5) is defined to be zero.

Proposition 2.2. Let $u_{k}, u, \Sigma_{0}$ and $\theta_{i}$ be as in Proposition 2.1. Then, for each $x \in \Sigma_{0}$, there exists $M_{x} \in \mathbb{N}$ and biharmonic mappings $v_{1}^{x}, \ldots, v_{M_{x}}^{x} \in C^{\infty}\left(\mathbb{R}^{4}, N\right)$ such that $\theta_{i}(x)=\sum_{j=1}^{M_{x}} \mathscr{E}_{i}\left(v_{j}^{x} ; \mathbb{R}^{4}\right)$. In particular,

$$
\lim _{k \rightarrow \infty} \mathscr{E}_{i}\left(u_{k} ; S\right)=\mathscr{E}_{i}(u ; S)+\sum_{x \in \Sigma_{0}} \sum_{j=1}^{M_{x}} \mathscr{E}_{i}\left(v_{j}^{x} ; \mathbb{R}^{4}\right) \quad \text { for } i=1,2
$$

For the proof of Proposition 2.1 we need three auxiliary results. The following lemma is a simple consequence of [Moser 2008, Theorem 2.1]:
Lemma 2.1. There exists a universal constant $C$ such that the following holds: Let $r>0$, let $u \in$ $W^{2,2}\left(B_{r}, N\right)$ and let $X \in L^{2}\left(B_{r}, \mathbb{R}^{n}\right)$ be a section of $u^{-1} T N$. If $\nabla^{u} X \in L^{2}\left(B_{r}\right)$ then $X \in L^{4}\left(B_{r}\right)$, and

$$
\|X\|_{L^{4}\left(B_{r}\right)} \leq C\left(\left\|\nabla^{u} X\right\|_{L^{2}\left(B_{r}\right)}+r^{-1}\|X\|_{L^{2}\left(B_{r}\right)}\right)
$$

For $u \in C^{k}$ we introduce the notation $[u]_{C^{k}}(x)=\sum_{j=1}^{k}\left|D^{j} u(x)\right|^{1 / j}$. An obvious consequence of [Scheven 2009, Lemma 5.3] is the following:
Lemma 2.2. There exists $\varepsilon_{1}>0$ such that, for all $r>0$ and for all biharmonic $u \in C^{\infty}\left(B_{r}, N\right)$ satisfying

$$
\int_{B_{r}}|D u|^{4} \leq \varepsilon_{1} \quad \text { we have } \quad \sup _{x \in B_{r / 2}}|x|[u]_{C^{3}}(x) \leq 1
$$

The following lemma shows that isolated singularities of biharmonic mappings are removable.
Lemma 2.3. Let $\Sigma \subset S$ be finite and let $u \in W^{2,2}(S, N)$ be biharmonic on $S \backslash \Sigma$. Then $u$ is biharmonic on $S$. In particular, $u \in C^{\infty}(S, N)$.

Proof. This proof closely follows that of [Jost 2005, Lemma 8.5.3]. We assume without loss of generality that $S=B_{1}$ and that $\Sigma=\{0\}$. Then (1) is equivalent to

$$
\begin{equation*}
\int_{B_{1}} \nabla_{\alpha} \partial_{\beta} u \cdot \nabla_{\alpha} \nabla_{\beta} \phi=\int_{B_{1}} f\left(u, D u \otimes D u \otimes D^{2} u\right) \cdot \phi \tag{6}
\end{equation*}
$$

for some $\mathbb{R}^{n}$-valued mapping $f$ that is smooth in the first argument and linear in the second argument. Since $u$ is biharmonic on $B_{1} \backslash\{0\}$, Equation (6) is satisfied for all $\phi \in\left(L^{\infty} \cap W_{0}^{2,2}\right)\left(B_{1} \backslash\{0\}, \mathbb{R}^{n}\right)$ that are sections of $u^{-1} T N$. From the properties of $f$ we deduce that

$$
\begin{equation*}
\left|f\left(u, D u \otimes D u \otimes D^{2} u\right)\right| \leq C\left(\left|D^{2} u\right|^{2}+|D u|^{4}\right) \tag{7}
\end{equation*}
$$

Hence $f\left(u, D u \otimes D u \otimes D^{2} u\right) \in L^{1}\left(B_{1}, \mathbb{R}^{n}\right)$. For small $R \in(0,1)$ we set

$$
\tau_{R}(t)= \begin{cases}0 & \text { for } t \in\left[0, R^{2}\right] \\ 1-\log (t / R) /|\log R| & \text { for } t \in\left[R^{2}, R\right] \\ 1 & \text { for } t \in[R, 1)\end{cases}
$$

One readily checks that

$$
\begin{equation*}
\lim _{R \rightarrow 0} \int_{B_{1}}\left|D^{2} \tau_{R}(|x|)\right|^{2}+\left|D \tau_{R}(|x|)\right|^{4} d x=0 \tag{8}
\end{equation*}
$$

Now let $\phi \in\left(L^{\infty} \cap W^{2,2}\right)\left(B, \mathbb{R}^{n}\right)$ be a section of $u^{-1} T N$. Then, for all $R \in(0,1)$,

$$
\phi_{R}(x)=\tau(|x|) \phi(x)
$$

is still a section of $u^{-1} T N$, and $\phi_{R} \in\left(L^{\infty} \cap W_{0}^{2,2}\right)\left(B_{1} \backslash\{0\}, \mathbb{R}^{n}\right)$. Hence it is an admissible test function for (6). Using (7) and (8) it is easy to check that (6) holds for all $\phi$ as above, that is, $u$ is biharmonic. Since $u \in W^{2,2}(S, N)$, Remark (ii) to Theorem 1.1 implies that $u \in C^{\infty}(S, N)$.
Proof of Proposition 2.1. Clearly (4) implies $\lim \sup _{k \rightarrow \infty} \mathscr{E}\left(u_{k} ; S\right)<\infty$. Hence $\Sigma_{0}$ is finite whatever the choice of $\varepsilon_{1}$. We choose $\varepsilon_{1}$ as in the statement of Lemma 2.2. Then the Arzèla-Ascoli theorem implies that $u_{k} \rightarrow u$ in $C_{\text {loc }}^{2}\left(S \backslash \Sigma_{0}, N\right)$. Hence $u$ is biharmonic on $S \backslash \Sigma_{0}$. Lemma 2.3 therefore implies that $u \in C^{\infty}(S, N)$ and that $u$ is biharmonic on $S$.

Weak lower semicontinuity of the $L^{2}$-norm and (4) imply the existence of (positive) Radon measures $\mu_{1}$ and $\mu_{2}$ on $S$ such that

$$
\begin{equation*}
\mathscr{L}^{4}\left\lfloore _ { i } ( u _ { k } ) \stackrel { * } { \rightharpoonup } \mathscr { L } ^ { 4 } \left\lfloor e_{i}(u)+\mu_{i} \quad \text { for } i=1,2 .\right.\right. \tag{9}
\end{equation*}
$$

We claim that

$$
\begin{equation*}
\mu_{1}(\{x\}) \geq \varepsilon_{1} \quad \text { for all } x \in \operatorname{spt} \mu_{1} . \tag{10}
\end{equation*}
$$

In fact, let $x \in S$ be such that $\mu_{1}(\{x\})<\varepsilon_{1}$. Then by (9) there exists $r>0$ such that

$$
\limsup _{k \rightarrow \infty} \int_{B_{r}(x)} e_{1}\left(u_{k}\right) \leq \int_{B_{r}(x)} e_{1}(u)+\mu_{1}\left(\bar{B}_{r}(x)\right)<\varepsilon_{1} .
$$

Thus $u_{k} \rightarrow u$ in $C^{2}\left(B_{r / 2}(x)\right)$ by Lemma 2.2 and the Arzèla-Ascoli theorem. (First only for a subsequence, but all subsequences must converge to the same limit $u$ because $u_{k} \rightharpoonup u$ in $W^{2,2}\left(S, \mathbb{R}^{n}\right)$.) Thus $\mu_{1}\left(B_{r} / 2(x)\right)=0$, so $x \notin \operatorname{spt} \mu_{1}$. This proves (10), which in turn implies that spt $\mu_{1}$ is finite and that $\mu_{1}=\sum_{x \in \operatorname{spt} \mu_{1}} \theta_{1}(x) \delta_{\{x\}}$ for a function $\theta_{1}:$ spt $\mu_{1} \rightarrow\left[\varepsilon_{1}, \infty\right)$.

If $x \notin \operatorname{spt} \mu_{1}$, then (9) implies that

$$
\begin{equation*}
\inf _{r>0} \lim _{k \rightarrow \infty} \int_{B_{r}(x)} e_{1}\left(u_{k}\right)=\inf _{r>0} \int_{B_{r}(x)} e_{1}(u)=0 \tag{11}
\end{equation*}
$$

On the other hand, if $x \in \operatorname{spt} \mu_{1}$ then there exists $r>0$ such that $B_{2 r}(x) \cap \operatorname{spt} \mu_{1}=\{x\}$ because spt $\mu_{1}$ is finite. Thus $\mu\left(\partial B_{r}(x)\right)=0$, and so (9) implies

$$
\lim _{k \rightarrow \infty} \int_{B_{r}(x)} e_{1}\left(u_{k}\right)=\int_{B_{r}(x)} e_{1}(u)+\mu_{1}(\{x\})
$$

We conclude that

$$
\begin{equation*}
\inf _{r>0} \lim _{k \rightarrow \infty} \int_{B_{r}(x)} e_{1}\left(u_{k}\right)=\mu_{1}(\{x\}) \quad \text { for all } x \in S \tag{12}
\end{equation*}
$$

Now (12) together with (10) imply that spt $\mu_{1} \subset \Sigma_{0}$. On the other hand, if $x \notin \operatorname{spt} \mu_{1}$ then (11) and Lemma 2.2 imply that there is $r>0$ such that $u_{k} \rightarrow u$ on $C^{2}\left(B_{r}(x), N\right)$; hence $x \notin \operatorname{spt} \mu_{2}$ and $x \notin \Sigma_{0}$. Thus spt $\mu_{2} \subset \operatorname{spt} \mu_{1}=\Sigma_{0}$. It remains to check that spt $\mu_{1} \subset \operatorname{spt} \mu_{2}$. But (9) implies that, for $r \in\left(0, \operatorname{dist}_{\partial S}(x)\right)$,

$$
\begin{equation*}
\limsup _{k \rightarrow \infty} \int_{B_{r}(x)}\left(\frac{\left|D u_{k}\right|^{2}}{r^{2}}+e_{2}\left(u_{k}\right)\right) \leq \int_{B_{r}(x)}\left(\frac{|D u|^{2}}{r^{2}}+e_{2}(u)\right)+\mu_{2}\left(\bar{B}_{r}(x)\right), \tag{13}
\end{equation*}
$$

because by Sobolev embedding we have $D u_{k} \rightarrow D u$ strongly in $L^{2}$. If $x \notin \operatorname{spt} \mu_{2}$, then the infimum over $r>0$ of the right side of (13) is zero, since $D u \in L^{4}$. Hence Lemma 2.1 implies that $x \notin \Sigma_{0}$.

For the proof of Proposition 2.2 we will need the following three lemmas:
Lemma 2.4. There exists a modulus of continuity $\omega$ (that is, $\omega \in C^{0}([0, \infty)$ ) is nondecreasing and $\omega(0)=0)$ such that, whenever $r>0$ and $u \in W^{2,2}\left(B_{r}, N\right)$ is biharmonic, then

$$
\operatorname{dist}_{\partial B_{r}}(x)[u]_{C^{3}}(x) \leq \omega\left(\int_{B_{r}}|D u|^{4}\right) \quad \text { for all } x \in B_{r} .
$$

Proof. Notice that $u \in C^{\infty}\left(B_{r}, N\right)$ by Remark (ii) to Theorem 1.1. The claim follows from a scaled version of [Scheven 2009, Lemma 5.3] and from the fact that, by Jensen's inequality,

$$
\left(\rho^{-2} \int_{B_{\rho}(a)}|D u|^{2}\right)^{2} \leq \int_{B_{\rho}(a)}|D u|^{4}
$$

We will also need the following crucial estimate.
Lemma 2.5. There exists a constant $C_{3}$ such that the following holds: For all $R \in(0,3 / 8)$ and for all biharmonic $u \in C^{\infty}\left(B_{1}, N\right)$ satisfying

$$
\varepsilon:=\sup _{\rho \in(R, 1 / 2)} \mathscr{E}\left(u ; B_{2 \rho} \backslash B_{\rho}\right) \leq C_{3}^{-1}
$$

we have

$$
\begin{equation*}
\mathscr{E}\left(u ; B_{1} \backslash B_{R}\right) \leq C_{3} \omega(\varepsilon)+2 \varepsilon \tag{14}
\end{equation*}
$$

Here, $\omega$ is as in the conclusion of Lemma 2.4.
The proof of Lemma 2.5 will be given in Section 3.
Finally, we will need the existence of a uniform lower bound on the energy of nonconstant entire biharmonic mappings. An analogous fact is well known for harmonic mappings and also for other kinds of biharmonic mappings; see for example [Wang 2004b].

Lemma 2.6. There exists a constant $\alpha>0$ such that $\mathscr{E}\left(u ; \mathbb{R}^{4}\right) \geq \alpha$ for every nonconstant biharmonic mapping $u \in C^{\infty}\left(\mathbb{R}^{4}, N\right)$.

Proof. If the claim were false then there would exist nonconstant biharmonic $u_{m} \in C^{\infty}\left(\mathbb{R}^{4}, N\right)$ such that $\lim _{m \rightarrow \infty} \mathscr{E}\left(u_{m} ; \mathbb{R}^{4}\right)=0$. After passing to a subsequence we have $D u_{m} \rightarrow 0$ pointwise almost everywhere. Therefore, since $u_{m}$ is nonconstant and since $D u_{m}$ is continuous, there exist $x_{m} \in \mathbb{R}^{4}$ such that $r_{m}:=\left|D u_{m}\left(x_{m}\right)\right|$ are nonzero but $\lim _{m \rightarrow \infty} r_{m}=0$. Define $\tilde{u}_{m}(x)=u_{m}\left(x_{m}+x / r_{m}\right)$. Then $\mathscr{E}\left(\tilde{u}_{m} ; \mathbb{R}^{4}\right)=\mathscr{E}\left(u_{m} ; \mathbb{R}^{4}\right)$ converges to zero as $m \rightarrow \infty$. By Lemma 2.2 this implies the existence of a constant mapping $u$ such that $\tilde{u}_{m} \rightarrow u$ in $C_{\text {loc }}^{2}\left(\mathbb{R}^{4}, N\right)$. But on the other hand, $\left|D \tilde{u}_{m}(0)\right|=1$ for all $m$, so $|D u(0)|=1$. This contradiction finishes the proof.

Proof of Proposition 2.2. By Proposition 2.1 we have $u_{k}, u \in C^{\infty}(S, N)$. Since the case $\Sigma_{0}=\varnothing$ is trivial, we assume that $\Sigma_{0}$ is nonempty. After translating, rescaling (the energy $\mathscr{E}$ is scaling invariant) and restricting, we may assume that $\Sigma_{0}=\{0\}$ and that $S=B_{1}$. By Proposition 2.1 we have $u_{k} \rightharpoonup u$ weakly in $\left(W^{2,2} \cap W^{1,4}\right)\left(B_{1}, \mathbb{R}^{n}\right)$ and $u_{k} \rightarrow u$ in $C_{\text {loc }}^{2}\left(B_{1} \backslash\{0\}, N\right)$. Moreover, there is some

$$
\begin{equation*}
\theta \geq \varepsilon_{1} \tag{15}
\end{equation*}
$$

such that

$$
\begin{equation*}
\mathscr{L}^{4}\left\lfloore ( u _ { k } ) \stackrel { * } { \rightharpoonup } \mathscr { L } ^ { 4 } \left\lfloor e(u)+\theta \delta_{\{0\}} .\right.\right. \tag{16}
\end{equation*}
$$

Let $\varepsilon \in(0,1)$ be such that $C_{3} \omega(\varepsilon)+3 \varepsilon \leq \min \left\{\alpha / 4, \varepsilon_{1} / 4\right\}$, where $\omega$ is as in Lemma 2.4, $C_{3}$ is as in Lemma 2.5 and $\varepsilon_{1}$ is as in Lemma 2.2. Since $u \in W^{2,2}\left(B_{1}, \mathbb{R}^{n}\right)$, there exists $Q \in(0,1)$ such that

$$
\begin{equation*}
\int_{B_{Q}} e(u) \leq \varepsilon / 2 \tag{17}
\end{equation*}
$$

We claim that there exists a sequence $R_{k} \rightarrow 0$ such that, for all $k$ large enough,

$$
\begin{align*}
\mathscr{E}\left(u_{k} ; B_{2 \rho} \backslash B_{\rho}\right) & \leq \varepsilon \quad \text { for all } \rho \in\left[R_{k}, Q / 2\right]  \tag{18}\\
\mathscr{E}\left(u_{k} ; B_{2 R_{k}} \backslash B_{R_{k}}\right) & =\varepsilon \tag{19}
\end{align*}
$$

In fact, set

$$
\mathscr{R}_{k}=\left\{r \in(0, Q / 2): \mathscr{E}\left(u_{k} ; B_{2 r} \backslash B_{r}\right)>\varepsilon\right\}
$$

If infinitely many of the $\mathscr{R}_{k}$ were empty, Lemma 2.5 would imply that there exists $k_{i} \rightarrow \infty$ such that $\mathscr{E}\left(u_{k_{i}} ; B_{Q} \backslash B_{r_{i}}\right) \leq C_{3} \omega(\varepsilon)+2 \varepsilon$ for any sequence $r_{i} \rightarrow 0$. Choosing this sequence in such a way that $\mathscr{E}\left(u_{k_{i}} ; B_{r_{i}}\right) \leq \varepsilon$ for all $i$, we would conclude that $\mathscr{E}\left(u_{k_{i}} ; B_{Q}\right) \leq C_{3} \omega(\varepsilon)+3 \varepsilon \leq \varepsilon_{1} / 4$, contradicting (15).

Thus, for $k$ large, $\mathscr{R}_{k} \neq \varnothing$ and we can define $R_{k}=\sup \mathscr{R}_{k}$. Clearly $R_{k}>0$ because $\int_{B_{2 r} \backslash B_{r}} e\left(u_{k}\right) \leq$ $\int_{B_{2 r}} e\left(u_{k}\right) \rightarrow 0$ as $r \rightarrow 0$. On the other hand, $R_{k} \rightarrow 0$, since otherwise $\rho=\frac{1}{2} \liminf _{k \rightarrow \infty} R_{k}$ is positive, so

$$
\limsup _{k \rightarrow 0} \int_{B_{2 R_{k}} \backslash B_{R_{k}}} e\left(u_{k}\right) \leq \lim _{k \rightarrow 0} \int_{B_{Q} \backslash B_{\rho}} e\left(u_{k}\right)=\int_{B_{Q} \backslash B_{\rho}} e(u) \leq \varepsilon / 2
$$

by (17). This contradicts the fact that $R_{k}$ is contained in the closure of $\mathscr{R}_{k}$, which by continuity of $r \mapsto \int_{B_{2 r} \backslash B_{r}} e\left(u_{k}\right)$ implies that $\int_{B_{2 R_{k}} \backslash B_{R_{k}}} e\left(u_{k}\right) \geq \varepsilon$. This also proves (19). Then (18) follows from the definition of $R_{k}$.

Combining (18) with (a scaled version of) Lemma 2.5 , we conclude that

$$
\begin{equation*}
\mathscr{E}\left(u_{k} ; B_{Q} \backslash B_{R_{k}}\right) \leq C_{3} \omega(\varepsilon)+2 \varepsilon \leq \alpha / 4 \tag{20}
\end{equation*}
$$

Set $v_{k}(x)=u_{k}\left(R_{k} x\right)$. Then by (16)

$$
\begin{equation*}
\limsup _{k \rightarrow \infty} \mathscr{E}\left(v_{k} ; B_{R}\right)=\limsup _{k \rightarrow \infty} \mathscr{E}\left(u_{k} ; B_{R R_{k}}\right) \leq \inf _{\rho>0} \limsup _{k \rightarrow \infty} \mathscr{E}\left(u_{k} ; B_{\rho}\right)=\theta \tag{21}
\end{equation*}
$$

for all $R>0$. Set

$$
\Sigma^{(1)}=\left\{x \in \mathbb{R}^{4}: \liminf _{k \rightarrow \infty} \mathscr{E}\left(v_{k} ; B_{r}(x)\right) \geq \varepsilon_{1} / 2 \text { for all } r>0\right\} .
$$

By (21) we can apply Proposition 2.1 to each $B_{R}$. We conclude that $\Sigma^{(1)}$ is locally finite and that there exists a biharmonic mapping $v \in C^{\infty}\left(\mathbb{R}^{4}, N\right)$ such that, after passing to a subsequence, $v_{k} \rightharpoonup v$ weakly in $\left(W_{\text {loc }}^{1,4} \cap W_{\text {loc }}^{2,2}\right)\left(\mathbb{R}^{4}, \mathbb{R}^{n}\right)$ and

$$
\begin{equation*}
v_{k} \rightarrow v \quad \text { in } C_{\mathrm{loc}}^{2}\left(\mathbb{R}^{4} \backslash \Sigma^{(1)}, \mathbb{R}^{n}\right), \tag{22}
\end{equation*}
$$

and we find that there are a functions $\theta_{1}^{(1)}, \theta_{2}^{(1)}: \Sigma^{(1)} \rightarrow(0, \infty)$ such that

$$
\begin{equation*}
\mathscr{L}^{4}\left\lfloor e_{i}\left(v_{k}\right) \stackrel{*}{\stackrel{ }{L} \mathscr{L}^{4}\left\lfloor e_{i}(v)+\sum_{x \in \Sigma^{(1)}} \theta_{i}^{(1)}(x) \delta_{\{x\}} \quad \text { for } i=1,2 . . ~ . ~\right.}\right. \tag{23}
\end{equation*}
$$

On the other hand, the bound (20) implies that

$$
\underset{k \rightarrow \infty}{\limsup } \mathscr{E}\left(v_{k} ; B_{R} \backslash \bar{B}_{1}\right) \leq C_{3} \omega(\varepsilon)+2 \varepsilon \text { for all } R>1 .
$$

Thus $\Sigma^{(1)} \subset \bar{B}_{1}$ (so $\Sigma^{(1)}$ is finite) and therefore

$$
v_{k} \rightarrow v \text { in } C_{\text {loc }}^{2}\left(\mathbb{R}^{4} \backslash \bar{B}_{1}, \mathbb{R}^{n}\right)
$$

by (22). From this and since $\mathscr{E}\left(v_{k} ; B_{2} \backslash \bar{B}_{1}\right)=\mathscr{E}\left(u_{k} ; B_{2 R_{k}} \backslash \bar{B}_{R_{k}}\right)=\varepsilon$ for all $k$ by (19), we conclude that $\mathscr{E}\left(v ; \mathbb{R}^{4}\right) \geq \varepsilon$. Hence Lemma 2.6 implies that $\mathscr{E}\left(v ; \mathbb{R}^{4}\right) \geq \alpha$.

Claim \#1. For all $\eta>0$, there exist $R>1$ and $\rho \in(0,1)$ such that

$$
\liminf _{k \rightarrow \infty} \mathscr{E}\left(u_{k} ; B_{\rho} \backslash B_{R R_{k}}\right) \leq \eta .
$$

To prove this claim, let us first show that for all $\delta>0$ there exist $R$ and $\rho$ and a sequence $k_{i} \rightarrow \infty$ such that

$$
\begin{equation*}
\mathscr{E}\left(u_{k_{i}} ; B_{2 r} \backslash B_{r}\right) \leq \delta \quad \text { for all } i \in \mathbb{N} \text { and all } r \in\left[R R_{k_{i}}, \rho / 2\right] \tag{24}
\end{equation*}
$$

In fact, assume that this were not the case. Then there would exist $\delta \in(0, \varepsilon)$ such that for all $R$ and $\rho$, the set

$$
\hat{\mathscr{R}}_{k}=\left\{r \in\left[R R_{k}, \rho / 2\right]: \mathscr{E}\left(u_{k} ; B_{2 r} \backslash B_{r}\right)>\delta\right\}
$$

is nonempty for all $k$ large enough. We choose $R>2$ so large and $\rho \in(0, Q)$ so small that

$$
\begin{gather*}
\mathscr{E}\left(v ; B_{4 \hat{R}} \backslash B_{\hat{R} / 2}\right) \leq \delta / 4 \quad \text { for all } \hat{R} \geq R, \text { and }  \tag{25}\\
\mathscr{E}\left(u ; B_{\rho}\right) \leq \delta / 4 \tag{26}
\end{gather*}
$$

This is clearly possible because $e(v) \in L^{1}\left(\mathbb{R}^{4}\right)$. Let $\hat{R}_{k}=\sup \hat{\mathscr{R}}_{k}$, hence $\hat{R}_{k} \in\left[R R_{k}, \rho / 2\right]$. Arguing as above for $R_{k}$, using (26) one readily checks that $\hat{R}_{k} \rightarrow 0$. We claim that

$$
\begin{equation*}
\hat{R}_{k} / R_{k} \rightarrow \infty \tag{27}
\end{equation*}
$$

Indeed, if this were not the case then (after passing to a subsequence) there would exist $\hat{R} \in[R, \infty)$ such that $\hat{R}_{k} / R_{k} \in[\hat{R} / 2,2 \hat{R}]$ for $k$ large enough. Thus by the definition of $\hat{R}_{k}$ and since $\hat{R} \geq R>2$ and $\Sigma^{(1)} \subset \bar{B}_{1}$,

$$
\delta \leq \limsup _{k \rightarrow \infty} \mathscr{E}\left(u_{k} ; B_{2 \hat{R}_{k}} \backslash B_{\hat{R}_{k}}\right) \leq \limsup _{k \rightarrow \infty} \mathscr{E}\left(v_{k} ; B_{4 \hat{R}} \backslash B_{\hat{R} / 2}\right)
$$

This contradiction to (25) shows that (27) must be true.
Now define $\hat{v}_{k}(x)=u_{k}\left(\hat{R}_{k} x\right)$. As done above for $R_{k}$ and $v_{k}$, using the fact that $\delta \leq \varepsilon$, one shows that there exists a nontrivial biharmonic mapping $\hat{v} \in C^{\infty}\left(\mathbb{R}^{4}, N\right)$ such that, after passing to a subsequence, $\hat{v}_{k} \rightharpoonup v$ in $\left(W_{\text {loc }}^{2,2} \cap W_{\text {loc }}^{1,4}\right)\left(\mathbb{R}^{4}, \mathbb{R}^{n}\right)$. Since $\hat{v}$ is nontrivial, Lemma 2.6 implies that $\mathscr{E}\left(\hat{v} ; \mathbb{R}^{4}\right) \geq \alpha$. Hence by (27) and since $\hat{R}_{k} \rightarrow 0$, for all $\hat{R}>1$ we have

$$
\begin{aligned}
\liminf _{k \rightarrow \infty} \mathscr{E}\left(u_{k} ; B_{\rho} \backslash B_{R R_{k}}\right) & \geq \liminf _{k \rightarrow \infty} \mathscr{E}\left(u_{k} ; B_{\hat{R} \hat{R}_{k}} \backslash B_{R R_{k}}\right) \\
& =\liminf _{k \rightarrow \infty} \mathscr{E}\left(\hat{v}_{k} ; B_{\hat{R}} \backslash B_{R\left(R_{k} / \hat{R}_{k}\right)}\right) \\
& \geq \sup _{r>0} \liminf _{k \rightarrow \infty} \mathscr{E}\left(\hat{v}_{k} ; B_{\hat{R}} \backslash B_{r}\right) \geq \mathscr{E}\left(\hat{v} ; B_{\hat{R}}\right)
\end{aligned}
$$

because $\hat{v}_{k} \rightharpoonup \hat{v}$ on $B_{\hat{R}}$. Taking the supremum over all $\hat{R}>1$ and recalling that $\mathscr{E}\left(\hat{v} ; \mathbb{R}^{4}\right) \geq \alpha$, we conclude that $\liminf _{k \rightarrow \infty} \mathscr{E}\left(u_{k} ; B_{\rho} \backslash B_{R R_{k}}\right) \geq \alpha$. This contradiction to (20) concludes the proof of (24).

Combining Lemma 2.5 with (24) and choosing $\delta$ small enough shows that Claim \#1 is true.
The results obtained so far apply to any $\theta>0$. Now we argue by induction: Assume that $m \in \mathbb{N}$ is such that $\theta \in((m-1) \alpha, m \alpha]$. If $m \geq 2$ then assume, in addition, that Proposition 2.2 is true for all $\theta \in(0,(m-1) \alpha]$. On one hand, for $i=1,2$, for all $R \in(1, \infty)$ and for all $\rho \in(0,1)$ we have

$$
\begin{aligned}
\theta_{i}+\mathscr{E}_{i}\left(u ; B_{\rho}\right)=\lim _{k \rightarrow \infty}\left(\mathscr{E}_{i}\left(u_{k} ; B_{\rho} \backslash B_{R R_{k}}\right)+\mathscr{E}_{i}\left(u_{k} ; B_{R R_{k}}\right)\right) & \geq \lim _{k \rightarrow \infty} \mathscr{E}_{i}\left(v_{k} ; B_{R}\right) \\
& =\mathscr{E}_{i}\left(v ; B_{R}\right)+\sum_{x \in \Sigma^{(1)}} \theta_{i}^{(1)}(x) .
\end{aligned}
$$

(First we used (5) and that $\mu_{i}\left(\partial B_{\rho}\right)=0$ for all $\rho \in(0,1)$, and then we used (23) together with the fact that $\Sigma^{(1)} \subset \bar{B}_{1}$.) Taking $\rho \rightarrow 0$ and $R \rightarrow \infty$ we conclude

$$
\begin{equation*}
\theta_{i} \geq \mathscr{E}_{i}\left(v ; \mathbb{R}^{4}\right)+\sum_{x \in \Sigma^{(1)}} \theta_{i}^{(1)}(x) \quad \text { for both } i=1,2 \tag{28}
\end{equation*}
$$

Hence

$$
\begin{equation*}
\theta \geq \mathscr{E}\left(v ; \mathbb{R}^{4}\right)+\sum_{x \in \Sigma^{(1)}} \theta^{(1)}(x) \tag{29}
\end{equation*}
$$

Since $\mathscr{E}\left(v ; \mathbb{R}^{4}\right) \geq \alpha$ this implies that $\theta^{(1)}(x) \leq \theta-\alpha$ for all $x \in \Sigma^{(1)}$. If $m \geq 2$ we can thus apply the induction hypothesis to conclude that

$$
\begin{equation*}
\theta_{i}^{(1)}(x)=\sum_{j=1}^{M_{x}} \mathscr{E}_{i}\left(v_{x}^{j} ; \mathbb{R}^{4}\right) \quad \text { for both } i=1,2 \tag{30}
\end{equation*}
$$

Here $v_{x}^{1}, \ldots, v_{x}^{M_{x}} \in C^{\infty}\left(\mathbb{R}^{4}, N\right)$ are biharmonic and $M_{x} \in(0, m-1]$ is a natural number. (If $m=1$, then (29) implies that $\Sigma^{(1)}=\varnothing$ and that $\theta=\alpha=\mathscr{E}\left(v ; \mathbb{R}^{4}\right)$. This concludes the proof of the case $m=1$.)

On the other hand, for all $\rho \in(0,1)$ and all $R>1$,

$$
\begin{align*}
\theta & \leq \lim _{k \rightarrow \infty}\left(\mathscr{E}\left(u_{k} ; B_{\rho} \backslash B_{R R_{k}}\right)+\mathscr{E}\left(u_{k} ; B_{R R_{k}}\right)\right) \\
& \leq \liminf _{k \rightarrow \infty} \mathscr{E}\left(u_{k} ; B_{\rho} \backslash B_{R R_{k}}\right)+\lim _{k \rightarrow \infty} \mathscr{E}\left(v_{k} ; B_{R}\right) \\
& =\liminf _{k \rightarrow \infty} \mathscr{E}\left(u_{k} ; B_{\rho} \backslash B_{R R_{k}}\right)+\mathscr{E}\left(v ; B_{R}\right)+\sum_{x \in \Sigma^{(1)}} \theta^{(1)}(x) \delta_{\{x\}} . \tag{31}
\end{align*}
$$

We used that $\Sigma^{(1)} \subset \bar{B}_{1}$, so $\lim _{k \rightarrow \infty} \mathscr{E}\left(v_{k} ; B_{R}\right)=\mathscr{E}\left(v ; B_{R}\right)+\sum_{x \in \Sigma^{(1)}} \theta^{(1)}(x) \delta_{\{x\}}$. Now let $\rho \rightarrow 0$ and $R \rightarrow \infty$ in (31) using Claim \#1. We conclude that $\theta \leq \mathscr{E}\left(v ; \mathbb{R}^{4}\right)+\sum_{x \in \Sigma^{(1)}} \theta^{(1)}(x)$. Thus by (29) and (30),

$$
\theta=\mathscr{E}\left(v ; \mathbb{R}^{4}\right)+\sum_{x \in \Sigma^{(1)}} \sum_{j=1}^{M_{x}} \mathscr{E}\left(v_{x}^{j} ; \mathbb{R}^{4}\right)
$$

Combining this with the inequalities (28) immediately implies that

$$
\theta_{i}=\mathscr{E}\left(v ; \mathbb{R}^{4}\right)+\sum_{x \in \Sigma^{(1)}} \sum_{j=1}^{M_{x}} \mathscr{E}_{i}\left(v_{x}^{j} ; \mathbb{R}^{4}\right) \quad \text { for both } i=1,2 .
$$

## 3. Energy estimates on the "neck" region

The purpose of this section is to prove the following proposition.
Proposition 3.1. There exists a constant $C_{1}$ such that the following holds: For all $R \in(0,1 / 2)$ and for all biharmonic $u \in C^{\infty}\left(B_{1}, N\right)$ satisfying

$$
\begin{equation*}
\varepsilon:=\sup _{x \in B_{1} \backslash \bar{B}_{R}}|x|[u]_{C^{3}}(x)<1 \tag{32}
\end{equation*}
$$

we have

$$
\begin{equation*}
\int_{B_{1} \backslash B_{R}}\left|\nabla^{u} D u\right|^{2} \leq C_{1}\left(\varepsilon+\mathscr{E}\left(u ; B_{1} \backslash B_{R}\right)\right) \varepsilon \tag{33}
\end{equation*}
$$

Corollary 3.1. There exists a constant $C_{2}$ such that the following holds: For all $R \in(0,1 / 2)$ and for all biharmonic $u \in C^{\infty}\left(B_{1}, N\right)$ satisfying (32), we have

$$
\begin{equation*}
\int_{B_{1} \backslash B_{R}} \frac{|D u|^{2}}{|x|^{2}} \leq C_{2}\left(\varepsilon+\mathscr{E}\left(u ; B_{1} \backslash B_{R}\right)\right) \varepsilon . \tag{34}
\end{equation*}
$$

If, in addition, $\varepsilon \leq 1 /\left(2\left(C_{1}+C_{2}\right)\right)$, then

$$
\begin{equation*}
\mathscr{E}\left(u ; B_{1} \backslash B_{R}\right) \leq 2\left(C_{1}+C_{2}\right) \varepsilon^{2} \tag{35}
\end{equation*}
$$

Proof. Set $\varepsilon=\sup _{x \in B_{1} \backslash \bar{B}_{R}}|x|[u]_{C^{3}}(x)$. By (33) and by (63) from Lemma 5.2, we have

$$
\int_{B_{1} \backslash \bar{B}_{R}} \frac{|D u|^{2}}{|x|^{2}} \leq C_{1}\left(\varepsilon+\mathscr{E}\left(u ; B_{1} \backslash \bar{B}_{R}\right)\right) \varepsilon+2 \mathscr{H}^{3}\left(\partial B_{1}\right) \varepsilon^{2}
$$

This implies (34) because $\varepsilon<1$. We clearly have

$$
\int_{B_{1} \backslash \bar{B}_{R}}|D u|^{4} \leq \varepsilon^{2} \int_{B_{1} \backslash \bar{B}_{R}} \frac{|D u|^{2}}{|x|^{2}} .
$$

Thus (34) implies that

$$
\int_{B_{1} \backslash \bar{B}_{R}}|D u|^{4} \leq C_{2}\left(\varepsilon+\mathscr{E}\left(u ; B_{1} \backslash \bar{B}_{R}\right)\right) \varepsilon^{3}
$$

Adding this to (33) yields

$$
\mathscr{E}\left(u ; B_{1} \backslash \bar{B}_{R}\right) \leq\left(C_{1}+C_{2}\right) \varepsilon^{2}+\left(C_{1}+C_{2}\right) \mathscr{E}\left(u ; B_{1} \backslash \bar{B}_{R}\right) \varepsilon,
$$

because $\varepsilon<1$. Since $\varepsilon \leq 1 /\left(2\left(C_{1}+C_{2}\right)\right)$, we can absorb the second term into the left hand side. This yields (35).

As a consequence of Corollary 3.1 we obtain Lemma 2.5:
Proof of Lemma 2.5. Set $\varepsilon=\sup _{\rho \in(R, 1 / 2)} \mathscr{E}\left(u ; B_{2 \rho} \backslash B_{\rho}\right)$. We claim that

$$
\begin{equation*}
|x|[u]_{C^{3}}(x) \leq 4 \omega(\varepsilon) \quad \text { for all } x \in B_{1 / 2} \backslash \bar{B}_{4 R / 3} \tag{36}
\end{equation*}
$$

In fact, let $x \in B_{1 / 2} \backslash \bar{B}_{4 R / 3}$ and apply Lemma 2.4 to the ball $B_{|x| / 4}(x)$. This yields

$$
\operatorname{dist}_{\partial B_{|x| / 4}(x)}(x)[u]_{C^{3}}(x) \leq \omega\left(\int_{B_{|x| / 4}(x)}|D u|^{4}\right)
$$

Since $B_{|x| / 4}(x) \subset B_{3|x| / 2} \backslash \bar{B}_{3|x| / 4}$, this implies (36).
Applying (35) (with $B_{1 / 2}$ instead of $B_{1}$ and $B_{4 R / 3}$ instead of $B_{R}$ ) to (36) implies

$$
\begin{equation*}
\mathscr{E}\left(u ; B_{1 / 2} \backslash B_{4 R / 3}\right) \leq C \omega^{2}(\varepsilon) \tag{37}
\end{equation*}
$$

for some constant $C$, provided that $\varepsilon$ is small enough (since then $\omega(\varepsilon)$ is small, and so $|x|[u]_{C^{3}}(x)$ is small by (36)). Finally, note that by definition of $\varepsilon$ we have $\mathscr{E}\left(u ; B_{1} \backslash B_{1 / 2}\right)+\mathscr{E}\left(u ; B_{2 R} \backslash B_{R}\right) \leq 2 \varepsilon$. Together with (37) and smallness of $\omega(\varepsilon)$ this implies (14).

The rest of this section will be devoted to the proof of Proposition 3.1. We will use the notation

$$
\partial_{r} u=e_{r}^{\alpha} \partial_{\alpha} u, \quad D_{r} u=\partial_{r} u \otimes e_{r}, \quad D_{S^{3}} u=D u-D_{r} u, \quad D^{2} u=\left(\partial_{\alpha} \partial_{\beta} u\right) \otimes e_{\alpha} \otimes e_{\beta}
$$

Above and in what follows we tacitly sum over repeated indices. A short calculation shows that

$$
\begin{equation*}
D_{S^{3}} u=\left(|x| \partial_{\partial_{\alpha} e_{r}} u\right) \otimes e_{\alpha} \tag{38}
\end{equation*}
$$

Proof of Proposition 3.1. Since $u \in C^{\infty}\left(B_{1}, N\right)$, [Scheven 2009, Lemma 4.2] implies that (1) is equivalent to

$$
\begin{equation*}
\Delta^{2} u=-\partial_{\alpha} E_{\alpha}[u]+G[u], \tag{39}
\end{equation*}
$$

where $E_{\alpha}[u]=-\partial_{\beta}\left(A(u)\left(\partial_{\alpha} u, \partial_{\beta} u\right)\right)+F_{\alpha}[u]$, and $F_{\alpha}[u]: S \rightarrow\left(\mathbb{R}^{4}\right)^{*} \otimes \mathbb{R}^{n}$ and $G[u]: S \rightarrow \mathbb{R}^{n}$ are as in [Scheven 2009, Lemma 4.2], that is, $F_{\alpha}[u]=f_{\alpha}(u, \nabla D u \otimes D u)$ for functions $f_{\alpha}$ that are smooth in the first and linear in the second argument, and $G[u]=g_{1}(u, \nabla D u \otimes \nabla D u)+g_{2}(u, \nabla D u \otimes D u \otimes D u)$ for functions $g_{1}$ and $g_{2}$ that again are smooth in the first and linear in the second argument. Therefore,

$$
\begin{align*}
|G[u]| & \leq C\left(\left|D^{2} u\right|^{2}+|D u|^{4}\right),  \tag{40}\\
\left|E_{\alpha}[u]\right| & \leq C\left(\left|D^{2} u\right||D u|+|D u|^{3}\right) . \tag{41}
\end{align*}
$$

For $r_{1}<r_{2}$ define the open annulus $A\left(r_{1}, r_{2}\right)=B_{r_{2}} \backslash \bar{B}_{r_{1}}$ and set $A=A(R, 1)$. (This should not be confused with the second fundamental form of $N$.) As we will show at the end of this proof, we may assume without loss of generality that $R=2^{-L}$ for some integer $L>1$.

Define $R_{k}=2^{k} R$ and set $A_{k}=A\left(R_{k}, R_{k+1}\right)$. Set

$$
\begin{equation*}
\varepsilon=\sup _{x \in B_{1} \backslash \bar{B}_{R}}|x|[u]_{C^{3}}(x) . \tag{42}
\end{equation*}
$$

Following an idea used in [Sacks and Uhlenbeck 1981] and [Ding and Tian 1995] in the context of harmonic mappings, we introduce the unique radial mapping $q: A \rightarrow \mathbb{R}^{n}$ solving the following boundary value problem for all $k=0, \ldots, L$ :

$$
\begin{align*}
\Delta^{2} q & =0 \quad \text { on } A_{k}  \tag{43}\\
q\left(R_{k}\right) & =\frac{1}{\mathscr{H}^{3}\left(\partial B_{R_{k}}\right)} \int_{\partial B_{R_{k}}} u \quad \text { and } \quad q^{\prime}\left(R_{k}\right)=\frac{1}{\mathscr{H}^{3}\left(\partial B_{R_{k}}\right)} \int_{\partial B_{R_{k}}} \partial_{r} u . \tag{44}
\end{align*}
$$

(For a radial function of the form $q(x)=\tilde{q}(|x|)$, we often write $q$ instead of $\tilde{q}$.) Notice that $q$ is indeed well and uniquely defined on each $A_{k}$ by (43) and (44) because (43) is simply a fourth order ordinary differential equation on ( $R_{k}, R_{k+1}$ ), since $q$ is radial. (See Lemma 5.1 below for details.) The rest of this proof is divided into Lemma 3.1 and Lemma 3.2 below. Combining their conclusions one obtains that of Proposition 3.1.

Let us finally check that the case of arbitrary $R \in(0,1)$ follows from the case when $R=2^{-L}$. In fact, for general $R$ let $L$ be such that $2^{L} R \in\left[\frac{1}{2}, 1\right)$. The definition of $\varepsilon$ implies that

$$
\int_{A\left(2^{L} R, 1\right)}|\nabla D u|^{2} \leq \varepsilon^{2} \int_{A\left(2^{L} R, 1\right)}|x|^{-4} \leq \varepsilon^{2} \mathscr{H}^{3}\left(\partial B_{1}\right) \log 2 .
$$

Applying Proposition 3.1 with $B_{2^{L} R}$ instead of $B_{1}$, the estimate (33) follows.
Lemma 3.1. For $u, q$ and $R$ as in the proof of Proposition 3.1 we have

$$
\begin{align*}
& \int_{A}\left|D^{2}(u-q)\right|^{2} \leq C\left(\varepsilon+\int_{A}\left|\nabla^{u} D u\right|^{2}+|D u|^{4}\right) \varepsilon  \tag{45}\\
& \int_{A} \frac{|D(u-q)|^{2}}{|x|^{2}} \leq C\left(\varepsilon+\int_{A}\left|\nabla^{u} D u\right|^{2}+|D u|^{4}\right) \varepsilon \tag{46}
\end{align*}
$$

Proof. Since $\left.q\right|_{A_{k}}$ is a solution of a linear ordinary differential equation with smooth coefficients, it is $C^{\infty}$ up to the boundary of $A_{k}$. Moreover, for $r \in\left(R_{k}, R_{k+1}\right)$, by Lemma 5.1 there exists a universal constant $C$ such that

$$
\begin{equation*}
\left|q^{\prime}(r)\right| \leq C\left(\left|q^{\prime}\left(R_{k}\right)\right|+\left|q^{\prime}\left(R_{k+1}\right)\right|+R_{k}^{-1}\left|q\left(R_{k+1}\right)-q\left(R_{k}\right)\right|\right) \tag{47}
\end{equation*}
$$

By (44) and by (42) this implies that $\left|u(x)-q\left(R_{k}\right)\right| \leq\|D u\|_{L^{\infty}\left(\partial B_{R_{k}}\right)} \cdot \operatorname{diam}\left(\partial B_{R_{k}}\right)$ for all $x \in \partial B_{R_{k}}$ and all $k$. Therefore,

$$
\begin{equation*}
\left|q\left(R_{k+1}\right)-q\left(R_{k}\right)\right| \leq\|D u\|_{L^{\infty}\left(A_{k}\right)} \operatorname{diam} A_{k} \leq C \varepsilon \tag{48}
\end{equation*}
$$

by (42) and because diam $A_{k} \leq C R_{k}$. Since $|x|$ is comparable to $R_{k}$ on $A_{k}$ and since $k$ was arbitrary, we conclude from (47) and (48) and from (44) and (42) that $|x||D q(x)| \leq C \varepsilon$ for all $x \in A$. By (44) and by (42) this implies that $|u-q| \leq C \varepsilon$. Summarizing, we have shown that

$$
\begin{equation*}
|(u-q)(x)|+|x||D(u-q)(x)| \leq C \varepsilon \quad \text { for all } x \in A . \tag{49}
\end{equation*}
$$

Notice that while (44) implies that $q \in C^{1}\left(A, \mathbb{R}^{n}\right)$ and that $\left.q\right|_{A_{k}} \in C^{\infty}\left(\bar{A}_{k}, \mathbb{R}^{n}\right)$ for all $k$, in general $q \notin C^{2}\left(A ; \mathbb{R}^{n}\right)$.

By partial integration one obtains, for arbitrary $v \in C^{2}\left(\bar{A}_{k}, \mathbb{R}^{n}\right)$,

$$
\int_{A_{k}}\left|D^{2} v\right|^{2}=\int_{A_{k}}\left(\partial_{\alpha} \partial_{\beta} v\right) \cdot\left(\partial_{\alpha} \partial_{\beta} v\right)=\int_{A_{k}}\left(\Delta^{2} v\right) \cdot v+\left[\int_{\partial A_{k}}\left(\partial_{r} \partial_{\beta} v\right) \cdot \partial_{\beta} v-\left(\partial_{r} \Delta v\right) \cdot v\right]_{r=R_{k}}^{R_{k+1}}
$$

Here and below we use the notation

$$
[f(r)]_{r=t_{1}}^{t_{2}}:=f\left(t_{2}\right)-f\left(t_{1}\right)
$$

for functions $f \in C^{0}\left(\left[t_{1}, t_{2}\right]\right)$. Inserting $v=u-q$ and summing over $k=0, \ldots, L$ yields

$$
\begin{align*}
& \int_{A}\left|D^{2}(u-q)\right|^{2}=\int_{A}\left(\Delta^{2} u\right) \cdot(u-q) \\
& \quad+\sum_{k=0}^{L}\left[\int_{\partial B_{\rho}}\left(\partial_{r} \partial_{\beta}(u-q)\right) \cdot \partial_{\beta}(u-q)-\left(\partial_{r} \Delta(u-q)\right) \cdot(u-q)\right]_{\rho=R_{k}}^{R_{k+1}} \\
& =\int_{A}\left(\Delta^{2} u\right) \cdot(u-q)+\left[\int_{\partial B_{\rho}} \partial_{r} \partial_{\beta} u \cdot \partial_{\beta}(u-q)-\partial_{r} \Delta u \cdot(u-q)\right]_{\rho=R}^{1} \\
& \quad-\sum_{k=0}^{L}\left[\int_{\partial B_{\rho}}\left(\partial_{r} \partial_{r} q\right)(\rho) \cdot \partial_{r}(u-q)(x)-\left(\partial_{r} \Delta q\right)(\rho) \cdot(u-q)(x) d \mathscr{H}^{3}(x)\right]_{\rho=R_{k}}^{R_{k+1}} . \tag{50}
\end{align*}
$$

In the first step we used that $\Delta^{2} q=0$ on $A_{k}$. In the last step we used that the boundary integrals with continuous integrands cancel successively, and we used that $q$ is radial. Since $q$ is radial, the same is true for $\partial_{r} \partial_{r} q$ and $\partial_{r} \Delta q$; see (60). The choice of boundary conditions (44) implies that

$$
\left(\partial_{r} \partial_{r} q\right)(\rho) \cdot \int_{\partial B_{\rho}} \partial_{r}(u-q)(x) d \mathscr{H}^{3}(x)=0 \quad \text { and } \quad\left(\partial_{r} \Delta q\right)(\rho) \cdot \int_{\partial B_{\rho}}(u-q)(x) d \mathscr{H}^{3}(x)=0
$$

for all $\rho \in\left\{R_{0}, R_{1}, \ldots, R_{L}\right\}$. So the sum in the last term in (50) is zero. (The discontinuous expressions $q^{\prime \prime}=\partial_{r} \partial_{r} q$ and $q^{\prime \prime \prime}$ occurring in $\partial_{r} \Delta q$ must be understood in the trace sense: If $\partial B_{R_{k}}$ belongs to $\partial A_{k}$ then $q^{\prime \prime}\left(R_{k}\right)=\lim _{r \uparrow R_{k}} q^{\prime \prime}(r)$ and if $\partial B_{R_{k}}$ belongs to $\partial A_{k+1}$ then $q^{\prime \prime}\left(R_{k}\right)=\lim _{r \downarrow R_{k}} q^{\prime \prime}(r)$. These limits exists because, as noted above, $\left.q\right|_{A_{k}}$ is smooth up to the boundary of $A_{k}$.)

To estimate the second term in (50) we use (49) and (42). This gives

$$
\int_{\partial B_{r}}\left|\partial_{r} \partial_{\beta} u \| \partial_{\beta}(u-q)\right| \leq C \mathscr{H}^{3}\left(\partial B_{r}\right) \frac{\varepsilon}{r^{2}} \frac{\varepsilon}{r} \leq C \varepsilon^{2}
$$

Similarly, $\int_{\partial B_{r}}\left|\partial_{r} \Delta u \| u-q\right| \leq C \varepsilon^{2}$. Thus (50) implies

$$
\begin{equation*}
\int_{A}\left|D^{2}(u-q)\right|^{2} \leq\left|\int_{A}\left(\Delta^{2} u\right) \cdot(u-q)\right|+C \varepsilon^{2} \tag{51}
\end{equation*}
$$

To estimate the term $\left|\int_{A}\left(\Delta^{2} u\right) \cdot(u-q)\right|$ in (51), we use (39) to replace $\Delta^{2} u$. We obtain

$$
\begin{align*}
\int_{A}\left(\Delta^{2} u\right) \cdot(u-q) & =\int_{A}\left(-\partial_{\alpha} E_{\alpha}[u]\right) \cdot(u-q)+G[u] \cdot(u-q) \\
& =\int_{A} E_{\alpha}[u] \cdot \partial_{\alpha}(u-q)+\int_{A} G[u] \cdot(u-q)-\left[\int_{\partial B_{r}} \frac{x_{\alpha}}{|x|} E_{\alpha}[u] \cdot(u-q)\right]_{r=R}^{1} \tag{52}
\end{align*}
$$

To estimate the last term in (52) we simply use that $\left|E_{\alpha}[u]\right| \leq\left|D^{2} u\right||D u|+|D u|^{3} \leq C \varepsilon^{2} /|x|^{3}$ pointwise by (41). Thus

$$
\int_{\partial B_{r}}\left|E_{\alpha}[u]\right||u-q| \leq C \varepsilon^{3} \mathscr{H}^{3}\left(\partial B_{r}\right) r^{-3} \leq C \varepsilon^{3}
$$

for both $r=1$ and $r=R$.
To estimate the second term in (52), we use (40) and (49) to find

$$
\int_{A}|G[u]||u-q| \leq C \varepsilon \int_{A}\left(\left|D^{2} u\right|^{2}+|D u|^{4}\right) .
$$

To estimate the first term in (52) notice that by (41) and by (49) we have

$$
\begin{equation*}
\int_{A}\left|E_{\alpha}[u]\right||D(u-q)| \leq C \varepsilon \int_{A}\left|D^{2} u\right| \frac{|D u|}{|x|}+\frac{|D u|^{3}}{|x|} \leq C \varepsilon \int_{A}\left(\left|D^{2} u\right|^{2}+|D u|^{4}+\frac{|D u|^{2}}{|x|^{2}}\right) \tag{53}
\end{equation*}
$$

Applying Lemma 5.2 to $v=u$ with $r_{1}=R$ and $r_{2}=1$, we have

$$
\int_{A} \frac{|D u|^{2}}{|x|^{2}} \leq \int_{A}\left|D^{2} u\right|^{2}+\left[\frac{1}{r} \int_{\partial B_{r}}|D u|^{2}\right]_{r=R}^{1}
$$

The boundary terms can be estimated as above using the definition of $\varepsilon$, Thus

$$
\int_{A} \frac{|D u|^{2}}{|x|^{2}} \leq \int_{A}\left|D^{2} u\right|^{2}+C \varepsilon^{2}
$$

So (53) implies

$$
\int_{A}\left|E_{\alpha}[u]\right||D(u-q)| \leq C \varepsilon\left(\varepsilon^{2}+\int_{A}\left|D^{2} u\right|^{2}+|D u|^{4}\right)
$$

Since $\left|D^{2} u\right|^{2} \leq C(N)\left(|\nabla D u|^{2}+|D u|^{4}\right)$ for some constant $C(N)$ depending only on the immersion $N \hookrightarrow \mathbb{R}^{n}$, this concludes the proof of (45).

To prove (46) we apply Lemma 5.2 to each restriction $\left.(u-q)\right|_{A_{k}}$. This yields

$$
\int_{A_{k}} \frac{|D(u-q)|^{2}}{|x|^{2}} \leq \int_{A_{k}}\left|D^{2}(u-q)\right|^{2}+\left[\frac{1}{r} \int_{\partial B_{r}}|D(u-q)|^{2}\right]_{r=R_{k}}^{R_{k+1}}
$$

When we sum over $k=0, \ldots, L$, the terms in square brackets cancel successively because $D(u-q)$ is continuous. After estimating the boundary terms on $\partial B_{1}$ and on $\partial B_{R}$ using (42), this yields (46).

Lemma 3.2. For $u, q$ and $R$ as in the proof of Proposition 3.1 we have

$$
\int_{A(R, 1)}\left|D^{2}(u-q)\right|^{2} \geq\left(\frac{1}{2}-\frac{\sqrt{2}}{3}\right) \int_{A(R, 1)}\left|\nabla^{u} D u\right|^{2}-C\left(\varepsilon+\int_{A}\left|\nabla^{u} D u\right|^{2}+|D u|^{4}\right) \varepsilon .
$$

Proof. For $v \in C^{\infty}\left(S, \mathbb{R}^{n}\right)$ we have

$$
D^{2} v=D D_{S^{3}} v+D D_{r} v
$$

where $D_{S^{3}} v=D v-D_{r} v$. Thus

$$
\begin{equation*}
\left|D^{2} v\right|^{2} \geq\left|D D_{S^{3}} v\right|^{2}+2 D\left(D v-D_{r} v\right) \cdot D D_{r} v \tag{54}
\end{equation*}
$$

Now $D\left(D v-D_{r} v\right) \cdot D D_{r} v$ equals

$$
\begin{aligned}
& \partial_{\alpha}\left(\left(\partial_{\beta} v\right) \otimes\right.\left.\left(e_{\beta}-e_{r}^{\beta} e_{r}\right)\right) \cdot \partial_{\alpha}\left(\partial_{\gamma} v \otimes e_{r}^{\gamma} e_{r}\right) \\
&=\left(\left(\partial_{\alpha} \partial_{\beta} v\right) \otimes\left(e_{\beta}-e_{r}^{\beta} e_{r}\right)-\left(\partial_{\beta} v\right) \otimes \partial_{\alpha}\left(e_{r}^{\beta} e_{r}\right)\right) \cdot\left(\left(\partial_{\alpha} \partial_{\gamma} v\right) \otimes e_{r}^{\gamma} e_{r}+\left(\partial_{\gamma} v\right) \otimes \partial_{\alpha}\left(e_{r}^{\gamma} e_{r}\right)\right) \\
&=\left(\left(\partial_{\alpha} \partial_{\beta} v\right) \otimes\left(e_{\beta}-e_{r}^{\beta} e_{r}\right)\right) \cdot \\
& \quad\left(\left(\partial_{\gamma} v\right) \otimes \partial_{\alpha}\left(e_{r}^{\gamma} e_{r}\right)\right) \\
& \quad-\left|\left(\partial_{\beta} v\right) \otimes \partial_{\alpha}\left(e_{r}^{\beta} e_{r}\right)\right|^{2}-\left(\partial_{\beta} v\right) \otimes \partial_{\alpha}\left(e_{r}^{\beta} e_{r}\right) \cdot\left(\partial_{\alpha} \partial_{\gamma} v\right) \otimes e_{r}^{\gamma} e_{r} \\
&=\left(\left(\partial_{\alpha} \partial_{\beta} v\right) \otimes\left(e_{\beta}-e_{r}^{\beta} e_{r}\right)\right) \cdot \\
&\left(\left(\partial_{r} v\right) \otimes\left(\partial_{\alpha} e_{r}\right)\right) \\
& \quad-\left|\left(\partial_{\beta} v\right) \otimes \partial_{\alpha}\left(e_{r}^{\beta} e_{r}\right)\right|^{2}-\left(\partial_{\beta} v\right) \otimes\left(\partial_{\alpha} e_{r}^{\beta}\right) e_{r} \cdot\left(\partial_{\alpha} \partial_{\gamma} v\right) \otimes e_{r}^{\gamma} e_{r} \\
&=\left(\partial_{\partial_{\alpha} e_{r}} \partial_{\alpha} v\right) \cdot\left(\partial_{r} v\right)-\left|\partial_{\beta} v\right|^{2}\left|\partial_{\alpha}\left(e_{r}^{\beta} e_{r}\right)\right|^{2}-\partial_{\partial_{\alpha} e_{r}} v \cdot\left(\partial_{r} \partial_{\alpha} v\right) .
\end{aligned}
$$

This shows that

$$
\begin{align*}
D\left(D v-D_{r} v\right) \cdot D D_{r} v & \geq-2\left|D e_{r}\right|\left|D^{2} v\right||D v|-2|D v|^{2}\left|D e_{r}\right|^{2} \\
& \geq-\left(\left|D^{2} v\right|^{2}+C\left|D e_{r}\right|^{2}|D v|^{2}\right) \tag{55}
\end{align*}
$$

for some universal constant $C>0$. Since $\left|D e_{r}(x)\right|^{2}=3 /|x|^{2}$, inserting (55) into the estimate (54) yields

$$
3\left|D^{2} v\right|^{2} \geq\left|D D_{S^{3}} v\right|^{2}-C|D v|^{2} /|x|^{2}
$$

Inserting $v=u-q$, integrating and using that $D_{S^{3}} q=0$ gives

$$
\begin{aligned}
3 \int\left|D^{2}(u-q)\right|^{2} & \geq \int\left|D D_{S^{3}} u\right|^{2}-C \int \frac{|D(u-q)|^{2}}{|x|^{2}} \\
& \geq \int\left|\nabla D u-\nabla D_{r} u\right|^{2}-C \int \frac{|D(u-q)|^{2}}{|x|^{2}} \\
& \geq\left(1-\frac{1}{\sqrt{2}}\right) \int|\nabla D u|^{2}+(1-\sqrt{2}) \int\left|\nabla D_{r} u\right|^{2}-C \int \frac{|D(u-q)|^{2}}{|x|^{2}} .
\end{aligned}
$$

In the second step we used that

$$
D u=D_{S^{3}} u+D_{r} u
$$

and the trivial estimate $|D f| \geq\left|\nabla^{u} f\right|$. By (58) the last line equals

$$
\begin{aligned}
&\left(\frac{3}{2}-\sqrt{2}\right) \int|\nabla D u|^{2}+(\sqrt{2}-1) \int \frac{\left|\nabla^{u}\left(|x| \partial_{r} u\right)\right|^{2}}{|x|^{2}}-C \int \frac{|D(u-q)|^{2}}{|x|^{2}} \\
& \quad+\frac{1-\sqrt{2}}{2}\left[\int_{\partial B_{r}}\left(\frac{3}{r}|D u|^{2}+2\left(\nabla_{r}^{u} \partial_{r} u\right) \cdot \partial_{r} u-\frac{2}{r}\left|\partial_{r} u\right|^{2}\right) d \mathscr{H}^{3}\right]_{r=R}^{1}
\end{aligned}
$$

The claim follows by dropping the second term, which is nonnegative, and noticing that the fourth term is dominated by $\varepsilon^{2}$ by (42) while, by (46), the third term is dominated by

$$
\varepsilon\left(\varepsilon+\int_{A}|\nabla D u|^{2}+|D u|^{4}\right)
$$

## 4. An equality for stationary biharmonic mappings

The following lemma is true for mappings that are stationary with respect to the energy $E_{2}$ in the sense of [Moser 2008]. We do not need the precise definition here. We only remark that every smooth biharmonic mapping is also stationary. Therefore by Remark (ii) to Theorem 1.1 , every $u \in W^{2,2}(S, N)$ that is biharmonic is also stationary. To recall the monotonicity formula from [Moser 2008], for $u \in W^{2,2}\left(B_{1}, N\right)$ we define

$$
\mathscr{F}(r)=\frac{1}{4} \int_{B_{r}}|\nabla D u|^{2}+\frac{1}{4} \int_{\partial B_{r}}\left(\frac{3}{r}|D u|^{2}+2\left(D_{r} \partial_{r} u \cdot \partial_{r} u\right)\right) d \mathscr{H}^{3} .
$$

Theorem 3.1 in [Moser 2008] (see also [Hornung and Moser 2012]) then states that, if $u \in W^{2,2}(S, N)$ is stationary, then

$$
\begin{equation*}
\mathscr{F}\left(r_{2}\right)-\mathscr{F}\left(r_{1}\right)=\int_{B_{r_{2}} \backslash B_{r_{1}}}\left(\frac{\left|\nabla^{u}\right| x\left|\partial_{r} u(x)\right|^{2}}{|x|^{2}}+2 \frac{\left|\partial_{r} u(x)\right|^{2}}{|x|^{2}} d x\right) \tag{56}
\end{equation*}
$$

for almost all $r_{1}, r_{2}$ with $0<r_{1} \leq r_{2} \leq 1$. As a corollary to this fact we obtain the following lemma:

Lemma 4.1. Let $u \in W^{2,2}\left(B_{1}, N\right)$ be stationary and let $R \in(0,1)$. Then

$$
\begin{align*}
& \int_{B_{1} \backslash B_{R}}\left|\nabla^{u} D_{r} u\right|^{2}=\int_{B_{1} \backslash B_{R}}\left(\frac{1}{4}\left|\nabla^{u} D u\right|^{2}+2 \frac{\left|\partial_{r} u\right|^{2}}{|x|^{2}}\right) \\
&+\frac{1}{4}\left[\int_{\partial B_{r}}\left(\frac{3}{r}|D u|^{2}-\frac{4}{r}\left|\partial_{r} u\right|^{2}+2\left(\nabla_{r}^{u} \partial_{r} u\right) \cdot \partial_{r} u\right) d \mathscr{H}^{3}\right]_{r=R}^{1}  \tag{57}\\
&=\int_{B_{1} \backslash B_{R}}\left(\frac{1}{2}\left|\nabla^{u} D u\right|^{2}-\frac{\left|\nabla^{u}\left(|x| \partial_{r} u\right)\right|^{2}}{|x|^{2}}\right) \\
&+\frac{1}{2}\left[\int_{\partial B_{r}}\left(\frac{3}{r}|D u|^{2}+2\left(\nabla_{r}^{u} \partial_{r} u\right) \cdot \partial_{r} u-\frac{2}{r}\left|\partial_{r} u\right|^{2}\right) d \mathscr{H}^{3}\right]_{r=R}^{1} \tag{58}
\end{align*}
$$

We remark that Lemma 4.1 can be regarded as a biharmonic counterpart of [Sacks and Uhlenbeck 1981, Lemma 3.5].

Proof. First notice that $\left|\nabla D_{r} u\right|^{2}=\left|\nabla \partial_{r} u\right|^{2}+\left|D e_{r}\right|^{2}\left|\partial_{r} u\right|^{2}$ and that $\left|D e_{r}\right|^{2}=3 /|x|^{2}$. Moreover, a short calculation using (38) shows that $|x| \nabla \partial_{r} u=\nabla\left(|x| \partial_{r} u\right)-D_{r} u$. Using these facts we calculate

$$
\begin{align*}
\left|\nabla D_{r} u\right|^{2} & =\left|\frac{\nabla\left(|x| \partial_{r} u\right)}{|x|}-\frac{D_{r} u}{|x|}\right|^{2}+\left|D e_{r}\right|^{2}\left|\partial_{r} u\right|^{2} \\
& =\frac{\left|\nabla\left(|x| \partial_{r} u\right)\right|^{2}}{|x|^{2}}+4 \frac{\left|\partial_{r} u\right|^{2}}{|x|^{2}}-\frac{2}{|x|^{2}} D\left(|x| \partial_{r} u\right) \cdot D_{r} u \\
& =\frac{\left|\nabla\left(|x| \partial_{r} u\right)\right|^{2}}{|x|^{2}}+4 \frac{\left|\partial_{r} u\right|^{2}}{|x|^{2}}-\operatorname{div}\left(\frac{\left|\partial_{r} u\right|^{2}}{|x|^{2}} x\right) . \tag{59}
\end{align*}
$$

Integrating over $B_{1} \backslash B_{R}$ and using (56) we obtain (57). On the other hand, (59) clearly equals

$$
2\left(\frac{\left|\nabla\left(|x| \partial_{r} u\right)\right|^{2}}{|x|^{2}}+2 \frac{\left|\partial_{r} u\right|^{2}}{|x|^{2}}\right)-\frac{\left|\nabla\left(|x| \partial_{r} u\right)\right|^{2}}{|x|^{2}}-\operatorname{div}\left(\frac{\left|\partial_{r} u\right|^{2}}{|x|^{2}} x\right)
$$

Integrating this over $B_{1} \backslash B_{R}$ and using (56) we obtain (58).

## 5. Appendix

Lemma 5.1. There exists a universal constant $C_{4}$ such that for all $R>0$ and for all radial solutions $q \in C^{\infty}\left(B_{2 R} \backslash \bar{B}_{R}, \mathbb{R}^{n}\right)$ of the equation $\Delta^{2} q=0$ on $B_{2 R} \backslash \bar{B}_{R}$, the following estimate holds:

$$
\left\|q^{\prime}\right\|_{C^{0}\left(B_{2 R} \backslash \bar{B}_{R}, \mathbb{R}^{n}\right)} \leq C_{4}\left(\left|q^{\prime}(R)\right|+\left|q^{\prime}(2 R)\right|+R^{-1}|q(2 R)-q(R)|\right)
$$

Proof. After rescaling we may assume without loss of generality that $R=1$. Since

$$
\begin{equation*}
\Delta q(x)=3 \frac{q^{\prime}(|x|)}{|x|}+q^{\prime \prime}(|x|) \tag{60}
\end{equation*}
$$

we see that $\Delta^{2} q=0$ is equivalent to $q^{\prime}$ being a solution of the third order system

$$
\begin{equation*}
\frac{3}{t}\left(\frac{3 f(t)}{t}+f^{\prime}(t)\right)^{\prime}+\left(\frac{3 f(t)}{t}+f^{\prime}(t)\right)^{\prime \prime}=0 \tag{61}
\end{equation*}
$$

Denote by $X \subset C^{\infty}\left(B_{2} \backslash B_{1}, \mathbb{R}^{n}\right)$ the (at most three dimensional) subspace of solutions to (61). Denote by $L: X \rightarrow \mathbb{R}^{3}$ the functional given by $L f=\left(f(1), f(2), \int_{1}^{2} f\right)$. We claim that $L$ is surjective.

In fact, let $a \in \mathbb{R}^{3}$. By the direct method it is easy to see that the functional $v \mapsto \int_{B_{2} \backslash B_{1}}\left|\nabla^{2} v\right|^{2}$ has a minimizer in the class of all radial $v \in W^{2,2}$ satisfying $v^{\prime}(1)=a_{1}$ and $v^{\prime}(2)=a_{2}$ and $v(2)-v(1)=a_{3}$. This minimizer $q$ satisfies the Euler-Lagrange equation $\Delta^{2} q=0$, so its radial derivative $q^{\prime}$ solves the ODE (61). Thus $q^{\prime} \in X$ and $L q^{\prime}=a$. This proves surjectivity of $L$.

Hence $X$ is three dimensional and $L$ is in fact bijective. Since all norms on $X$ are equivalent and since the inverse of $L$ is of course bounded, we conclude that $\|f\|_{C^{0}\left((1,2), \mathbb{R}^{n}\right)} \leq C|L f|$ for all $f \in X$. This implies the claim.

Lemma 5.2. Let $0<r_{1}<r_{2} \leq 1$ and assume that $v \in W^{2,2}\left(B_{r_{2}} \backslash \bar{B}_{r_{1}}, \mathbb{R}^{n}\right)$. Then

$$
\begin{equation*}
\int_{B_{r_{2}} \backslash B_{r_{1}}} \frac{|D v|^{2}}{|x|^{2}} \leq \int_{B_{r_{2}} \backslash B_{r_{1}}}\left|D^{2} v\right|^{2}+\left[\frac{1}{r} \int_{\partial B_{r}}|D v|^{2}\right]_{r=r_{1}}^{r_{2}} \tag{62}
\end{equation*}
$$

If $v \in W^{2,2}\left(B_{r_{2}} \backslash \bar{B}_{r_{1}}, N\right)$ then

$$
\begin{equation*}
\int_{B_{r_{2}} \backslash B_{r_{1}}} \frac{|D v|^{2}}{|x|^{2}} \leq \int_{B_{r_{2}} \backslash B_{r_{1}}}\left|\nabla^{v} D v\right|^{2}+\left[\frac{1}{r} \int_{\partial B_{r}}|D v|^{2}\right]_{r=r_{1}}^{r_{2}} \tag{63}
\end{equation*}
$$

Proof. For $v \in C^{2}\left(A\left(r_{1}, r_{2}\right), \mathbb{R}^{n}\right)$ we have

$$
2 \frac{|D v|^{2}}{|x|^{2}}=\operatorname{div}\left(\frac{|D v|^{2}}{|x|^{2}} x\right)-\frac{\partial_{r}|D v|^{2}}{|x|}
$$

Hence if $D v$ is continuous up to the boundary of $A\left(r_{1}, r_{2}\right)$ then

$$
\begin{align*}
2 \int_{A\left(r_{1}, r_{2}\right)} \frac{|D v|^{2}}{|x|^{2}} & =-\int_{A\left(r_{1}, r_{2}\right)} \frac{\partial_{r}|D v|^{2}}{|x|}+\left[\int_{\partial B_{r}} \frac{|D v|^{2}}{|x|^{2}} x \cdot \frac{x}{|x|}\right]_{r=r_{1}}^{r_{2}} \\
& =-2 \int_{A\left(r_{1}, r_{2}\right)}\left(\partial_{r} \partial_{\alpha} v\right) \cdot \frac{\partial_{\alpha} v}{|x|}+\left[\frac{1}{r} \int_{\partial B_{r}}|D v|^{2}\right]_{r=r_{1}}^{r_{2}} . \tag{64}
\end{align*}
$$

By density and by continuity of the trace operator, this equality remains true for $v \in W^{2,2}\left(A\left(r_{1}, r_{2}\right), \mathbb{R}^{n}\right)$. We conclude that

$$
2 \int_{A\left(r_{1}, r_{2}\right)} \frac{|D v|^{2}}{|x|^{2}} \leq \int_{A\left(r_{1}, r_{2}\right)}\left|D^{2} v\right|^{2}+\int_{A\left(r_{1}, r_{2}\right)} \frac{|D v|^{2}}{|x|^{2}}+\left[\frac{1}{r} \int_{\partial B_{r}}|D v|^{2}\right]_{r=r_{1}}^{r_{2}}
$$

Absorbing the second term on the right into the left hand side yields (62).
If $v$ takes values in $N$ then the first term on the right hand side of (64) equals

$$
-2 \int_{A\left(r_{1}, r_{2}\right)}\left(\nabla_{r}^{v} \partial_{\alpha} v\right) \cdot \frac{\partial_{\alpha} v}{|x|}
$$

because $\partial_{\alpha} v(x) \in T_{v(x)} N$ for all $x$. Estimating as above yields (63).

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## ANALYSIS \& PDE

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