

## PARALLEL ITERATIVE METHODS FOR SOLVING THE COMMON NULL POINT PROBLEM IN BANACH SPACES

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**ABSTRACT.** We consider the common null point problem in Banach spaces. Then, using the hybrid projection method and the  $\varepsilon$ -enlargement of maximal monotone operators, we prove two strong convergence theorems for finding a solution of this problem.

### 1. INTRODUCTION

Let  $H$  be a real Hilbert space, and let  $f : H \rightarrow (-\infty, \infty]$  be a proper, lower semicontinuous, and convex function. In order to find a minimum point of  $f$ , Martinet [11] proposed the iterative method as follows:  $x_1 \in H$  and

$$x_{n+1} = \arg \min_{y \in H} \left\{ f(y) + \frac{1}{2} \|y - x_n\|^2 \right\}$$

for all  $n \geq 1$ . He proved that the sequence  $\{x_n\}$  converges weakly to a minimum point of  $f$ . Note that, the above sequence  $\{x_n\}$  can be rewritten in the form

$$\partial f(x_{n+1}) + x_{n+1} \ni x_n \quad \forall n \geq 1.$$

We know that the subdifferential operator  $\partial f$  of  $f$  is a maximal monotone operator [14]. So, the problem of finding a null point of a maximal monotone operator plays an important role in optimization theory. One popular method of solving equation  $0 \in A(x)$  where  $A$  is a maximal monotone operator in Hilbert space  $H$ ,

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is the proximal point algorithm. The proximal point algorithm generates, for any starting point  $x_0 = x \in E$ , a sequence  $\{x_n\}$  by the rule

$$x_{n+1} = J_{r_n}^A(x_n), \quad \forall n \in \mathbb{N},$$

where  $\{r_n\}$  is a sequence of positive real numbers and  $J_{r_n}^A = (I + r_n A)^{-1}$  is the resolvent of  $A$ . Moreover, Rockafellar [15] has given a more practical method which is an inexact variant of the method

$$x_n + e_n \in x_{n+1} + r_n A x_{n+1}, \quad \forall n \in \mathbb{N}, \tag{1.1}$$

where  $\{e_n\}$  is regarded as an error sequence and  $\{r_n\}$  is a sequence of positive regularization parameters. Note that the algorithm (1.1) can be rewritten as

$$x_{n+1} = J_{r_n}^A(x_n + e_n) \quad \forall n \in \mathbb{N}.$$

This method is called inexact proximal point algorithm. It was shown in Rockafellar [15] that if  $\sum_{n=1}^{\infty} \|e_n\| < \infty$ , then  $x_n \rightharpoonup z \in H$  with  $0 \in Az$ .

There are many authors replaced the operator  $A$  in the equation (1.1) by the  $\varepsilon$ -enlargement  $A^\varepsilon$ , see, for instance, Burachick, Iusem, and Svaiter [3], Solodov and Svaitere [17], Moudafi and Elisabeth [13], and others. In [3], Burachick and others used the enlargement  $A^\varepsilon$  to devise an approximate generalized proximal point algorithm. The exact version of this algorithm can be stated as follows: Having  $x_n$ , the next element  $x_{n+1}$  is the solution of

$$0 \in r_n A(x) + \nabla f(x) - \nabla f(x_n), \tag{1.2}$$

where  $f$  is a suitable regularization function. Note that, if  $f(x) = \frac{1}{2} \|x\|^2$ , then the above algorithm becomes the classical proximal point algorithm. Approximate solutions of (1.2) are treated in [3] via  $A^\varepsilon$ . Specifically, an approximate solution of (1.2) can be regarded as an exact solution of

$$0 \in r_n A^{\varepsilon_n}(x) + \nabla f(x) - \nabla f(x_n),$$

for an appropriate value of  $\varepsilon_n$ . Note that, if  $f(x) = \frac{1}{2} \|x\|^2$ , then the above relation is equivalent to the problem of finding an element  $x_{n+1} \in H$  and  $v_{n+1} \in A^{\varepsilon_n}(x_{n+1})$  with  $\varepsilon_n \geq 0$  such that

$$0 = r_n v_{n+1} + (x_{n+1} - x_n). \tag{1.3}$$

They proved that if  $\sum_{n=1}^{\infty} \varepsilon_n < \infty$ , then the sequence  $\{x_n\}$  converges weakly to a null point of  $A$ .

The problem of finding a common null point of a finite family of maximal monotone operators in Banach or Hilbert spaces is the interesting topic of non-linear analysis. This problem has been investigated by many researchers, see, for instance, Sabach [16], Timnak, Naraghirad, and Hussain [19], Tuyen [20], Kim and Tuyen [10], and others.

Let  $E$  be a reflexive Banach space, and let  $A_i : E \rightarrow 2^{E^*}$ ,  $i = 1, 2, \dots, N$ , be  $N$  maximal monotone operators such that  $S = \bigcap_{i=1}^N A_i^{-1} 0 \neq \emptyset$ . Let  $g : E \rightarrow \mathbb{R}$  be a Legendre function that is bounded, uniformly Fréchet differentiable, and totally convex on bounded subsets of  $E$ . In 2011, Sabach [16] introduced two iterative

methods for finding an element  $x^* \in S$ . He proved the strong convergence of sequence  $\{x_n\}$  which is defined by

$$\begin{aligned} x_0 &\in E \text{ chosen arbitrarily,} \\ y_n &= \text{Res}_{\lambda_n^N A_N}^g \dots \text{Res}_{\lambda_n^1 A_1}^g (x_n + e_n), \\ C_n &= \{z \in E : D_g(z, y_n) \leq D_g(z, x_n + e_n)\}, \\ Q_n &= \{z \in E : \langle z - x_n, \nabla g(x_0) - \nabla g(x_n) \rangle \leq 0\}, \\ x_{n+1} &= \text{proj}_{C_n \cap Q_n}^g x_0, \quad n \geq 0, \end{aligned}$$

or

$$\begin{aligned} x_0 &\in E \text{ chosen arbitrarily,} \\ H_0 &= E, \\ y_n &= \text{Res}_{\lambda_n^N A_N}^g \dots \text{Res}_{\lambda_n^1 A_1}^g (x_n + e_n), \\ H_{n+1} &= \{z \in H_n : D_g(z, y_n) \leq D_g(z, x_n + e_n)\}, \\ x_{n+1} &= \text{proj}_{H_{n+1}}^g x_0, \quad n \geq 0, \end{aligned}$$

where, for each  $i = 1, 2, \dots, N$ ,  $\liminf_{n \rightarrow \infty} \lambda_n^i > 0$ , the sequence of errors  $\{e_n\}$  satisfies  $\liminf_{n \rightarrow \infty} e_n = 0$ , and  $\text{Res}_{\lambda_n^i A_i}^g = (\nabla g + \lambda_n^i A_i)^{-1} \nabla g$ .

In 2017, Timnak and others [19] proposed a new Halpern-type iterative scheme for finding an element  $x^* \in S$ . They proved strong convergence of the sequence  $\{x_n\}$  which is defined by

$$\begin{aligned} u &\in E, \quad x_1 \in E \text{ chose arbitrarily,} \\ y_n &= \nabla g^* [\beta_n \nabla g(x_n) + (1 - \beta_n) \nabla g(\text{Res}_{r_N A_N}^g \dots \text{Res}_{r_1 A_1}^g (x_n))], \\ x_{n+1} &= \nabla g^* [\alpha_n \nabla g(u) + (1 - \alpha_n) \nabla g(y_n)], \quad n \geq 1, \end{aligned}$$

where  $r_i > 0$ , for each  $i = 1, 2, \dots, N$ , and  $\{\alpha_n\}$  and  $\{\beta_n\}$  are two sequences in  $[0, 1]$  satisfying the following conditions:

- i)  $\lim_{n \rightarrow \infty} \alpha_n = 0$ ;
- ii)  $\sum_{n=1}^{\infty} \alpha_n = \infty$ ;
- iii)  $0 < \liminf_{n \rightarrow \infty} \beta_n \leq \limsup_{n \rightarrow \infty} \beta_n < 1$ .

In 2016, Ibaraki [7] studied the shrinking projection method [18] with error for finding a null point of a monotone operator in a Banach space. Let  $A : E \rightarrow 2^{E^*}$  be a monotone operator such that  $A^{-1}0 \neq \emptyset$  and  $D(A) \subset C \subset J_E^{-1}R(J_E + r_n A)$ , where  $C$  is a nonempty, closed, and convex subset of  $E$ , and  $\{r_n\}$  is a sequence of positive real numbers. He considered the sequence  $\{x_n\}$  generated by  $x_1 = u \in C$ ,  $C_1 = C$ , and

$$\begin{aligned} y_n &= J_{r_n}(x_n), \\ C_{n+1} &= \{z \in C : \langle y_n - z, J_E(x_n) - J_E(y_n) \rangle \geq 0\} \cap C_n, \\ x_{n+1} &\in \{z \in C : \|u - z\|^2 \leq d(u, C_{n+1})^2 + \delta_{n+1}\} \cap C_{n+1}, \end{aligned}$$

where  $\{\delta_n\}$  is a sequence of non-negative numbers and  $d(u, C_{n+1})$  is the distance from  $u$  to  $C_{n+1}$ . He proved that if  $\limsup_{n \rightarrow \infty} \delta_n = 0$ , then  $\{x_n\}$  converges strongly to  $P_{A^{-1}0}u$  as  $n \rightarrow \infty$ . The result of Ibaraki is the extension the results of Ibaraki and Kimura [6] and Kimura [9].

Thus, there are some open questions which are posed as follows:

- 1) Can we extend the above iterative method for finding an element  $x^* \in S = \bigcap_{i=1}^N A_i^{-1}0 \neq \emptyset$ , where  $A_i, i = 1, 2, \dots, N$ , are maximal monotone operators on the Banach spaces  $E$ ?
- 2) Can we replace the equation  $y_n = J_{r_n}(x_n)$  by the following inclusion equation

$$r_n A^{\varepsilon_n}(y_n) + J_E(y_n) \ni J_E(x_n),$$

where  $A^{\varepsilon_n}$  is the  $\varepsilon_n$ -enlargement of  $A$  with  $\varepsilon_n \geq 0$ ?

In this paper, by using the tools of  $\varepsilon$ -enlargement of maximal monotone operators and the shrinking projection method, we introduce two strong convergence theorems to answer two above open questions. This results are the extension of Ibaraki's result [7]. Moreover, we also give an application of the main results for solving the problem of finding a common minimum point of convex functions.

## 2. PRELIMINARIES

Let  $E$  be a real Banach space with norm  $\|\cdot\|$ , and let  $E^*$  be its dual. The value of  $f \in E^*$  at  $x \in E$  will be denoted by  $\langle x, f \rangle$ . When  $\{x_n\}$  is a sequence in  $E$ , then  $x_n \rightarrow x$  (resp.  $x_n \rightharpoonup x, x_n \overset{*}{\rightharpoonup} x$ ) will denote strong (resp. weak, weak\*) convergence of the sequence  $\{x_n\}$  to  $x$ . Let  $J_E$  denote the normalized duality mapping from  $E$  into  $2^{E^*}$  given by

$$J_E x = \{f \in E^* : \langle x, f \rangle = \|x\|^2 = \|f\|^2\} \quad \forall x \in E.$$

We always use  $S_E$  to denote the unit sphere  $S_E = \{x \in E : \|x\| = 1\}$ . A Banach space  $E$  is said to be strictly convex if  $x, y \in S_E$  with  $x \neq y$  and, for all  $t \in (0, 1)$ ,

$$\|(1-t)x + ty\| < 1.$$

A Banach space  $E$  is said to be uniformly convex if for any  $\varepsilon \in (0, 2]$  and the inequalities  $\|x\| \leq 1, \|y\| \leq 1, \|x - y\| \geq \varepsilon$ , there exists a  $\delta = \delta(\varepsilon) > 0$  such that

$$\frac{\|x + y\|}{2} \leq 1 - \delta.$$

A Banach space  $E$  is said to be smooth provided the limit

$$\lim_{t \rightarrow 0} \frac{\|x + ty\| - \|x\|}{t}$$

exists for each  $x$  and  $y$  in  $S_E$ . In this case, the norm of  $E$  is said to be Gâteaux differentiable. It is said to be uniformly Gâteaux differentiable if for each  $y \in S_E$ , this limit attained uniformly for  $x \in S_E$ .

Let  $E$  be a reflexive Banach space; we know that  $E$  is uniformly convex if and only if  $E^*$  is uniformly smooth.

We have following properties of the normalized duality mapping  $J_E$ :

- (i)  $E$  is reflexive if and only if  $J_E$  is surjective;
- (ii) If  $E^*$  is strictly convex, then  $J_E$  is single-valued;
- (iii) If  $E$  is a smooth, strictly convex and reflexive Banach space, then  $J_E$  is single-valued bijection;

- (iv) If  $E^*$  is uniformly convex, then  $J_E$  is uniformly continuous on each bounded set of  $E$ .

We know that, if  $E$  is a smooth, strictly convex, and reflexive Banach space and  $C$  is a nonempty, closed, and convex subset of  $E$ , then, for each  $x \in E$ , there exists unique  $z \in C$  such that

$$\|x - z\| = \inf_{y \in C} \|x - y\|.$$

The mapping  $P_C : E \rightarrow C$  defines by  $P_C x = z$  is called metric projection from  $E$  on to  $C$ , and we denote by  $d(x, C) = \|x - z\|$ .

Let  $E$  be a smooth Banach space. Define a function  $\phi : E \times E \rightarrow \mathbb{R}$  by

$$\phi(x, y) = \|x\|^2 - 2\langle x, J_E y \rangle + \|y\|^2$$

for all  $x, y \in E$ . From the definition of  $\phi$ , it is easy to see that the function  $\phi$  has the following properties:

- (i)  $(\|x\| - \|y\|)^2 \leq \phi(x, y) \leq (\|x\| + \|y\|)^2$  for all  $x, y \in E$ ;
- (ii)  $\phi(x, y) = \phi(x, z) + \phi(z, y) + 2\langle x - z, J_E z - J_E y \rangle$  for all  $x, y, z \in E$ ;
- (iii) If  $E$  is strictly convex, then  $\phi(x, y) = 0$  if and only if  $x = y$ .

Let  $A : E \rightarrow 2^{E^*}$  be an operator. The effective domain of  $A$  is denoted by  $D(A)$ ; that is,  $D(A) = \{x \in E : Ax \neq \emptyset\}$ . Recall that  $A$  is called monotone operator if  $\langle x - y, u - v \rangle \geq 0$  for all  $x, y \in D(A)$  and for all  $u \in Ax$  and  $v \in A(y)$ . A monotone operator  $A$  on  $E$  is called maximal monotone if its graph is not properly contained in the graph of any other monotone operator on  $E$ . We know that if  $A$  is maximal monotone operator on  $E$  and  $E$  is a uniformly convex and smooth Banach space, then  $R(J_E + rA) = E^*$ , for all  $r > 0$ , where  $R(J_E + rA)$  is the range of  $J_E + rA$  [2]; if additionally  $E$  is strictly convex then, for each  $x \in E$  and  $r > 0$ , there exists unique  $x_r \in E$  such that

$$J_E x \in J_E x_r + rA x_r.$$

Hence, in this case we can define a mapping  $J_r : E \rightarrow E$  by  $J_r x = x_r$ , and  $J_r$  is called the generalized resolvent of  $A$ .

The set of null point of  $A$  is defined by  $A^{-1}0 = \{z \in E : 0 \in Az\}$ , and we know that  $A^{-1}0$  is a closed and convex subset of  $E$ .

Let  $A : E \rightarrow 2^{E^*}$  be a maximal monotone operator. In [4], for each  $\varepsilon \geq 0$ , Burachik and Svaiter defined  $A^\varepsilon(x)$ , an  $\varepsilon$ -enlargement of  $A$ , as follows:

$$A^\varepsilon x = \{u \in E^* : \langle y - x, v - u \rangle \geq -\varepsilon, \forall y \in E, v \in Ay\}.$$

It is easy to see that  $A^0 x = Ax$ , and if  $0 \leq \varepsilon_1 \leq \varepsilon_2$ , then  $A^{\varepsilon_1} x \subseteq A^{\varepsilon_2} x$  for any  $x \in E$ . The using of element in  $A^\varepsilon$  instead of  $A$  allows an extra degree freedom which is very useful in various applications.

Let  $\{C_n\}$  be the sequence of closed, convex, and nonempty subsets of a reflexive Banach space  $E$ . We define the subsets s-Li $_n C_n$  and w-Ls $_n C_n$  of  $E$  as follows:  $x \in$  s-Li $_n C_n$  if and only if there exists  $\{x_n\} \subset E$  converges strongly to  $x$  and that  $x_n \in C_n$  for all  $n \geq 1$ ;  $x \in$  w-Ls $_n C_n$  if and only if there exists a subsequence  $\{C_{n_k}\}$  of  $\{C_n\}$  and the sequence  $\{y_k\} \subset E$  such that  $y_k \rightarrow x$  and  $y_k \in C_{n_k}$  for all  $k \geq 1$ . If s-Li $_n C_n =$  w-Ls $_n C_n = \Omega_0$ , then  $\Omega_0$  is called the limits of  $\{C_n\}$  in the sense of Mosco [12], and it is denoted by  $\Omega_0 = \text{M-lim}_{n \rightarrow \infty} C_n$ .

The following lemmas will be needed in what follows for the proof of main theorems.

**Lemma 2.1.** [21] *Let  $E$  be a Banach space,  $r \in (0, \infty)$ , and  $B_r = \{x \in E : \|x\| \leq r\}$ . If  $E$  is uniformly convex, then there exists a continuous, strictly increasing, and convex function  $g : [0, 2r] \rightarrow [0, \infty)$  with  $g(0) = 0$  such that*

$$\|\alpha x + (1 - \alpha)y\|^2 \leq \alpha\|x\|^2 + (1 - \alpha)\|y\|^2 - \alpha(1 - \alpha)g(\|x - y\|)$$

for all  $x, y \in B_r$  and  $\alpha \in [0, 1]$ .

**Lemma 2.2.** [8] *Let  $E$  be a uniformly convex and smooth Banach space, and let  $\{y_n\}$  and  $\{z_n\}$  be two sequences of  $E$ . If  $\phi(y_n, z_n) \rightarrow 0$  and either  $\{y_n\}$  or  $\{z_n\}$  is bounded, then  $y_n - z_n \rightarrow 0$ .*

**Lemma 2.3.** [5] *Let  $E$  be a smooth, reflexive, and strictly convex Banach space having the Kadec–Klee property. Let  $\{C_n\}$  be a sequence of nonempty, closed, and convex subsets of  $E$ . If  $C_0 = M - \lim_{n \rightarrow \infty} C_n$  exists and is nonempty, then  $\{P_{C_n}x\}$  converges strongly to  $P_{C_0}x$  for each  $x \in C$ .*

**Lemma 2.4.** [4] *The graph of  $A^\varepsilon : \mathbb{R}_+ \times E \rightarrow 2^{E^*}$  is demiclosed; that is, the conditions below hold:*

- (i) *If  $\{x_n\} \subset E$  converges strongly to  $x_0$ ,  $\{u_n \in A^{\varepsilon_n}x_n\}$  converges weakly\* to  $u_0$  in  $E^*$ , and  $\{\varepsilon_n\} \subset \mathbb{R}_+$  converges to  $\varepsilon$ , then  $u_0 \in A^\varepsilon x_0$ ;*
- (ii) *If  $\{x_n\} \subset E$  converges weak to  $x_0$ ,  $\{u_n \in A^{\varepsilon_n}x_n\}$  converges strongly to  $u_0$  in  $E^*$ , and  $\{\varepsilon_n\} \subset \mathbb{R}_+$  converges to  $\varepsilon$ , then  $u_0 \in A^\varepsilon x_0$ .*

### 3. MAIN RESULTS

Let  $E$  be a uniformly convex and smooth Banach space, and let  $A_i : E \rightarrow 2^{E^*}$ ,  $i = 1, 2, \dots, N$ , be maximal monotone operators of  $E$  into  $2^{E^*}$  such that  $S = \bigcap_{i=1}^N A_i^{-1}0 \neq \emptyset$ . Consider the following problem.

$$\text{Find an element } x^* \in S. \tag{3.1}$$

In order to solve the Problem (3.1), we propose two algorithms as follows: Let  $\{\varepsilon_n\}$  and  $\{\delta_n\}$  be non-negative real sequences, and let  $\{r_{i,n}\}$ ,  $i = 1, 2, \dots, N$ , be positive real sequences such that  $\min_i \{\inf_n \{r_{i,n}\}\} \geq r > 0$ .

**Algorithm 3.1.** *For a given point  $u \in E$ , we define the sequence  $\{x_n\}$  by  $x_1 = x \in E$ ,  $C_1 = E$ , and*

$$\begin{aligned} &\text{Find } y_{i,n} \in E \text{ such that } J_E(y_{i,n}) - J_E(x_n) + r_{i,n}A_i^{\varepsilon_n}y_{i,n} \ni 0, \quad i = 1, \dots, N \\ &\text{Choose } i_n \text{ such that } \|y_{i_n,n} - x_n\| = \max_{i=1, \dots, N} \{\|y_{i,n} - x_n\|\}, \text{ let } y_n = y_{i_n,n}, \end{aligned} \tag{3.2}$$

$$C_{n+1} = \{z \in C_n : \langle y_n - z, J_E(x_n) - J_E(y_n) \rangle \geq -\varepsilon_n r_{i_n,n}\},$$

$$\text{Find } x_{n+1} \in \{z \in C_{n+1} : \|u - z\|^2 \leq d^2(u, C_{n+1}) + \delta_{n+1}\}, \quad n \geq 1.$$

**Algorithm 3.2.** For a given point  $u \in E$ , we define the sequence  $\{x_n\}$  by  $x_1 = x \in E$ ,  $C_1 = E$ , and

$$\begin{aligned} & \text{Find } y_{i,n} \in E \text{ such that } J_E(y_{i,n}) - J_E(x_n) + r_{i,n}A_i^{\varepsilon_n}y_{i,n} \ni 0, \quad i = 1, \dots, N; \\ & C_{n+1}^i = \{z \in C_n : \langle y_{i,n} - z, J_E(x_n) - J_E(y_{i,n}) \rangle \geq -\varepsilon_n r_{i,n}\}, \quad i = 1, 2, \dots, N \\ & C_{n+1} = \bigcap_{i=1}^N C_{n+1}^i; \\ & \text{Find } x_{n+1} \in \{z \in C_{n+1} : \|u - z\|^2 \leq d^2(u, C_{n+1}) + \delta_{n+1}\}, \quad n \geq 1. \end{aligned} \tag{3.3}$$

We will prove the strong convergence of Algorithms 3.1 and 3.2 under the following conditions:

- C1)  $\lim_{n \rightarrow \infty} \varepsilon_n r_{i,n} = 0$  for all  $i = 1, 2, \dots, N$ ;  
 C2)  $\lim_{n \rightarrow \infty} \delta_n = 0$ .

*Remark 3.3.*

- i) In Algorithm 3.2, in order to define the element  $x_{n+1}$ , we have to find the projection of  $u$  onto the intersection of  $n \times N$  half-spaces. But in Algorithm 3.1, we only find the projection of  $u$  onto the intersection of  $n$  half-spaces. So, the algorithm to define  $x_{n+1}$  in Algorithm 3.1 is simpler than the algorithm in Algorithm 3.2. However, in the both cases, we can find the element  $x_{n+1}$  by the approximation solution of the following minimization problem: Find a minimum point of the convex function  $f(x) = \frac{1}{2}\|x - u\|^2$  over the intersection of a finite family of half-spaces  $C_i$ . In particular, if  $E = \mathbb{R}^m$ , then we can find  $x_{n+1}$  easily by using the ‘‘Quadratic Programming Algorithms’’ package in MATLAB software.
- ii) In Algorithms 3.1 and 3.2, if  $N = 1$  and  $\varepsilon_n = 0$ , for all  $n \geq 1$ , then we obtain the Ibaraki’s result [7, Theorem 4.2].

First, we need the following lemma.

**Lemma 3.4.** If  $\{C_n\}$  is a decreasing sequence of closed and convex subsets of a reflexive Banach space  $E$  and  $\Omega_0 = \bigcap_{n=1}^{\infty} C_n \neq \emptyset$ , then  $\Omega_0 = M\text{-}\lim_{n \rightarrow \infty} C_n$ .

*Proof.* Indeed, it is clear that if  $x \in \Omega_0$ , then  $x \in \text{s-Li}_n C_n$  and  $x \in \text{w-Ls}_n C_n$ , because the sequence  $\{x_n\}$  with  $x_n = x$ , for all  $n \geq 1$ , converges strongly to  $x$ . Thus, we have  $\Omega_0 \subset \text{s-Li}_n C_n$  and  $\Omega_0 \subset \text{w-Ls}_n C_n$ .

Now we will show that  $\Omega_0 \supseteq \text{s-Li}_n C_n$  and  $\Omega_0 \supseteq \text{w-Ls}_n C_n$ . Let  $x \in \text{s-Li}_n C_n$ , from the definition of  $\text{s-Li}_n C_n$ , there exists a sequence  $\{x_n\} \subset E$  with  $x_n \in C_n$ , for all  $n \geq 1$ , such that  $x_n \rightarrow x$ , as  $n \rightarrow \infty$ . Since  $\{C_n\}$  is a decreasing sequence,  $x_{n+k} \in C_n$  for all  $n \geq 1$  and  $k \geq 0$ . So, letting  $k \rightarrow \infty$  and by the closedness of  $C_n$ , we get that  $x \in C_n$  for all  $n \geq 1$ . Thus,  $x \in \Omega_0$ , and hence  $\Omega_0 \supseteq \text{s-Li}_n C_n$ . Next, let  $y \in \text{w-Ls}_n C_n$ , from the definition of  $\text{w-Ls}_n C_n$ , there exists a subsequence  $\{C_{n_k}\}$  of  $\{C_n\}$  and the sequence  $\{y_k\} \subset E$  such that  $y_k \rightharpoonup x$  and  $y_k \in C_{n_k}$  for all  $k \geq 1$ . From  $\{C_n\}$  is a decreasing sequence, we have

$$y_{k+p} \in C_{n_k} \tag{3.4}$$

for all  $k \geq 1$  and  $p \geq 0$ . Since  $C_{n_k}$  is closed and convex,  $C_{n_k}$  is weakly closed in  $E$  for all  $k \geq 1$ . So, in (3.4) letting  $p \rightarrow \infty$ , we get that  $y \in C_{n_k}$  for all  $k \geq 1$ . Since  $C_k \supseteq C_{n_k}$ ,  $y \in C_k$  for all  $k \geq 1$ . So,  $y \in \Omega_0$ , and hence  $\Omega_0 \supseteq \text{w-LS}_n C_n$ .

Consequently, we obtain that  $\text{s-Li}_n C_n = \text{w-LS}_n C_n = \Omega_0$ . Thus,  $\Omega_0 = \text{M-lim}_{n \rightarrow \infty} C_n$ . □

The strong convergence of Algorithm 3.1 is given by the following theorem.

**Theorem 3.5.** *If the conditions C1) and C2) are satisfied, then the sequence  $\{x_n\}$  generated by Algorithm 3.1 converges strongly to  $P_S u$ , as  $n \rightarrow \infty$ .*

*Proof.* First, we show that  $S \subset C_n$ , for all  $n \geq 1$ , by mathematical induction. Indeed, it is clear that  $S \subset C_1 = E$ . Suppose that  $S \subset C_n$  for some  $n \geq 1$ . Take  $v \in S$ , we have

$$J_E(y_{i_n,n}) - J_E(x_n) + r_{i_n,n} A_{i_n}^{\varepsilon_n} y_{i_n,n} \ni 0, \quad A_{i_n} v \ni 0.$$

From the definition of  $A_{i_n}^{\varepsilon_n}$ , we get

$$\langle y_n - v, J_E(x_n) - J_E(y_n) \rangle \geq -\varepsilon_n r_{i_n,n}.$$

Thus,  $u \in C_{n+1}$ . Since  $v$  is arbitrary in  $S$ ,  $S \subset C_{n+1}$ . So, by induction we obtain that  $S \subset C_n$  for all  $n \geq 1$ .

Moreover,  $C_n$  is a closed and convex subset of  $E$  for all  $n$ . Hence, the sequence  $\{x_n\}$  is well defined.

Now, for each  $n$ , denote by  $p_n = P_{C_n} u$ . Since,  $\{C_n\}$  is the sequence of decreasing subsets of  $E$  which contains  $S$ , and from Lemma 3.4, there exists the limit  $\Omega_0 = \text{M-lim}_{n \rightarrow \infty} C_n$ . By Lemma 2.3, we have  $p_n \rightarrow p_0 = P_{\Omega_0} u$ , as  $n \rightarrow \infty$ .

Since  $p_n = P_{C_n} u$ ,  $d(u, C_n) = \|u - p_n\|$ . From  $x_n \in C_n$  and the definition of  $C_n$ , we have

$$\|u - x_n\|^2 \leq \|u - p_n\|^2 + \delta_n \quad \forall n \geq 2. \tag{3.5}$$

From the convexity of  $C_n$ , we have  $\alpha p_n + (1 - \alpha)x_n \in C_n$  for all  $\alpha \in (0, 1)$ . Thus, from the definition of  $p_n = P_{C_n} u$  and Lemma 2.1, we get

$$\begin{aligned} \|p_n - u\|^2 &\leq \|\alpha p_n + (1 - \alpha)x_n - u\|^2 \\ &\leq \alpha \|p_n - u\|^2 + (1 - \alpha) \|x_n - u\|^2 - \alpha(1 - \alpha)g(\|x_n - p_n\|), \end{aligned}$$

which implies that

$$\|p_n - u\|^2 \leq \|x_n - u\|^2 - \alpha g(\|x_n - p_n\|).$$

Thus, it follows from (3.5) that

$$\alpha g(\|x_n - p_n\|) \leq \delta_n \quad \forall \alpha \in (0, 1). \tag{3.6}$$

In (3.6), letting  $\alpha \rightarrow 1^-$ , we get

$$g(\|x_n - p_n\|) \leq \delta_n.$$

By the property of  $g$  and  $\delta_n \rightarrow 0$ , we have

$$\|x_n - p_n\| \rightarrow 0.$$

From  $p_{n+1} \in C_{n+1}$  and the definition of  $C_{n+1}$ , we have

$$\langle y_n - p_{n+1}, J_E(x_n) - J_E(y_n) \rangle \geq -\varepsilon_n r_{i_n,n}.$$

Thus, from the property of  $\phi$ , we obtain

$$\begin{aligned} -2\varepsilon_n r_{i,n} &\leq 2\langle p_{n+1} - y_n, J_E(y_n) - J_E(x_n) \rangle \\ &= \phi(p_{n+1}, x_n) - \phi(p_{n+1}, y_n) - \phi(y_n, x_n) \\ &\leq \phi(p_{n+1}, x_n) - \phi(y_n, x_n). \end{aligned}$$

Hence,

$$\phi(y_n, x_n) \leq \phi(p_{n+1}, x_n) + 2\varepsilon_n r_{i,n}.$$

From Lemma 2.2 and  $p_n \rightarrow p_0$ ,  $x_n \rightarrow p_0$ , letting  $n \rightarrow \infty$  we get that

$$\|x_n - y_n\| \rightarrow 0.$$

By the definition of  $y_n$ , we have

$$\|x_n - y_{i,n}\| \rightarrow 0 \quad \forall i = 1, 2, \dots, N.$$

This implies that  $y_{i,n} \rightarrow p_0$  for all  $i = 1, 2, \dots, N$ , as  $n \rightarrow \infty$ . Since  $E$  is uniformly smooth, the duality mapping  $J_E$  is uniformly norm-to-norm continuous on each bounded subset on  $E$ . Therefore, we obtain

$$\|J_E(x_n) - J_E(y_{i,n})\| \rightarrow 0, \quad \forall i = 1, 2, \dots, N. \quad (3.7)$$

Furthermore, from  $\min_i \{\inf_n \{r_{i,n}\}\} \geq r > 0$  and (3.7), we have

$$0 \leftarrow \frac{J_E(x_n) - J_E(y_{i,n})}{r_{i,n}} \in A_i^{\varepsilon_n} y_{i,n}$$

for all  $i = 1, 2, \dots, N$ , as  $n \rightarrow \infty$ . So, by Lemma 2.4, we obtain  $p_0 \in A_i^{-1}0$  for all  $i = 1, 2, \dots, N$ ; that is,  $p_0 \in S$ .

Finally, we show that  $p_0 = P_S u$ . Indeed, let  $x^* = P_S u$ . Since  $S \subset C_n$ ,  $x^* \in C_n$ . Thus, from  $p_n = P_{C_n} u$ , we have

$$\|p_n - u\| \leq \|u - x^*\| \quad \forall n \geq 1.$$

Letting  $n \rightarrow \infty$ , we get that  $\|u - p_0\| \leq \|u - x^*\|$ . By the uniqueness of  $x^*$ , we obtain that  $p_0 = x^* = P_S u$ .

This completes the proof.  $\square$

Now, we will prove the strong convergence of Algorithm 3.2.

**Theorem 3.6.** *If the conditions C1) and C2) are satisfied, then the sequence  $\{x_n\}$  generated by Algorithm 3.2 converges strongly to  $P_S u$ , as  $n \rightarrow \infty$ .*

*Proof.* First, we show that  $S \subset C_n$ , for all  $n \geq 1$ , by mathematical induction. Indeed, it is clear that  $S \subset C_1 = E$ . Suppose that  $S \subset C_n$  for some  $n \geq 1$ . Take  $v \in S$ , we have

$$J_E(y_{i,n}) - J_E(x_n) + r_{i,n} A_i^{\varepsilon_n} y_{i,n} \ni 0 \quad A_i v \ni 0.$$

From the definition of  $A_i^{\varepsilon_n}$ , we get

$$\langle y_{i,n} - v, J_E(x_n) - J(y_{i,n}) \rangle \geq -\varepsilon_n r_{i,n}.$$

Thus,  $v \in C_{n+1}^i$  for all  $i = 1, 2, \dots, N$ . So,  $v \in C_{n+1} = \bigcap_{i=1}^N C_{n+1}^i$ . By induction we obtain that  $S \subset C_n$  for all  $n \geq 1$ .

Now, for each  $n$ , putting  $p_n = P_{C_n} u$ . It is similar to the proof of Theorem 3.5, we obtain the following statements:

- a)  $p_n \rightarrow p_0 = P_{\Omega_0}u$  with  $\Omega_0 = \bigcap_{n=1}^{\infty} C_n$ ;
- b)  $\|x_n - p_n\| \rightarrow 0$ .

We have  $p_{n+1} \in C_{n+1} = \bigcap_{i=1}^N C_{n+1}^i$ . Hence,  $p_{n+1} \in C_{n+1}^i$  for all  $i = 1, 2, \dots, N$ . Thus, from the definition of  $C_{n+1}^i$ , we have

$$\langle y_{i,n} - p_{n+1}, J_E(x_n) - J_E(y_{i,n}) \rangle \geq -\varepsilon_n r_{i,n}.$$

Thus, from the property of  $\phi$ , we obtain

$$\begin{aligned} -2\varepsilon_n r_{i,n} &\leq 2\langle p_{n+1} - y_{i,n}, J_E(y_{i,n}) - J_E(x_n) \rangle \\ &= \phi(p_{n+1}, x_n) - \phi(p_{n+1}, y_{i,n}) - \phi(y_{i,n}, x_n) \\ &\leq \phi(p_{n+1}, x_n) - \phi(y_{i,n}, x_n). \end{aligned}$$

Hence,

$$\phi(y_{i,n}, x_n) \leq \phi(p_{n+1}, x_n) + 2\varepsilon_n r_{i,n}$$

for all  $i = 1, 2, \dots, N$ . From a), b), and Lemma 2.2, we obtain that

$$\|x_n - y_{i,n}\| \rightarrow 0$$

for all  $i = 1, 2, \dots, N$ .

The rest of the proof follows the pattern of Theorem 3.5.

This completes the proof. □

Next, we have the following corollaries.

**Corollary 3.7.** *Let  $E$  be a uniformly convex and smooth Banach space, and let  $A_i : E \rightarrow 2^{E^*}$ ,  $i = 1, 2, \dots, N$ , be maximal monotone operators of  $E$  into  $2^{E^*}$  such that  $S = \bigcap_{i=1}^N A_i^{-1}0 \neq \emptyset$ . Let  $J_r^i$  be the generalized resolvent of  $A_i$  for  $r > 0$  with  $i = 1, 2, \dots, N$ . Let  $\{\delta_n\}$  be non-negative real sequence, and let  $\{r_{i,n}\}$ ,  $i = 1, 2, \dots, N$ , be positive real sequences such that  $\min_i \{\inf_n \{r_{i,n}\}\} \geq r > 0$ . For a given point  $u \in E$ , we define the sequence  $\{x_n\}$  by  $x_1 = x \in E$ ,  $C_1 = E$ , and*

- i)  $y_{i,n} = J_{r_{i,n}}^i x_n$ ,  $i = 1, 2, \dots, N$
- ii) Choose  $i_n$  such that  $\|y_{i_n,n} - x_n\| = \max_{i=1,\dots,N} \{\|y_{i,n} - x_n\|\}$ , let  $y_n = y_{i_n,n}$ ,  
 $C_{n+1} = \{z \in C_n : \langle y_n - z, J_E(x_n) - J_E(y_n) \rangle \geq 0\}$ , or  
 ii\*)  $C_{n+1}^i = \{z \in C_n : \langle y_{i,n} - z, J_E(x_n) - J_E(y_{i,n}) \rangle \geq 0\}$ ,  $i = 1, 2, \dots, N$   
 $C_{n+1} = \bigcap_{i=1}^N C_{n+1}^i$ ,
- iii) Find  $x_{n+1} \in \{z \in C_{n+1} : \|u - z\|^2 \leq d^2(u, C_{n+1}) + \delta_{n+1}\}$ ,  $n = 1, 2, \dots$ .

If  $\lim_{n \rightarrow \infty} \delta_n = 0$ , then the sequence  $\{x_n\}$  converges strongly to  $P_{S^u}$ , as  $n \rightarrow \infty$ .

*Proof.* In (3.2) and (3.3) if  $\varepsilon_n = 0$ , for all  $n \geq 1$ , then the elements  $y_{i,n}$ ,  $i = 1, 2, \dots, N$ , can be rewritten in the form

$$J_E(y_{i,n}) - J_E(x_n) + r_{i,n} A_i y_{i,n} \ni 0;$$

this is equivalent to

$$y_{i,n} = J_{r_{i,n}}^i x_n$$

for all  $i = 1, 2, \dots, N$ .

So, apply Theorems 3.5 and 3.6 with  $\varepsilon_n = 0$  for all  $n \geq 1$ , we obtain the proof of this corollary.  $\square$

**Corollary 3.8.** *Let  $E$  be a uniformly convex and smooth Banach space, and let  $A_i : E \rightarrow 2^{E^*}$ ,  $i = 1, 2, \dots, N$ , be maximal monotone operators of  $E$  into  $2^{E^*}$  such that  $S = \bigcap_{i=1}^N A_i^{-1}0 \neq \emptyset$ . Let  $\{\varepsilon_n\}$  be non-negative real sequence, and let  $\{r_{i,n}\}$ ,  $i = 1, 2, \dots, N$ , be positive real sequences such that  $\min_i \{\inf_n \{r_{i,n}\}\} \geq r > 0$ . For a given point  $u \in E$ , we define the sequence  $\{x_n\}$  by  $x_1 = x \in E$ ,  $C_1 = E$ , and*

i) Find  $y_{i,n} \in E$  such that  $J_E(y_{i,n}) - J_E(x_n) + r_{i,n}A_i^{\varepsilon_n}y_{i,n} \ni 0$ ,  $i = 1, 2, \dots, N$

ii) Choose  $i_n$  such that  $\|y_{i_n,n} - x_n\| = \max_{i=1,\dots,N} \{\|y_{i,n} - x_n\|\}$ , let  $y_n = y_{i_n,n}$ ,

$C_{n+1} = \{z \in C_n : \langle y_n - z, J_E(x_n - y_n) \rangle \geq -\varepsilon_n r_{i_n,n}\}$ , or

ii\*)  $C_{n+1}^i = \{z \in C_n : \langle y_{i,n} - z, J_E(x_n) - J_E(y_{i,n}) \rangle \geq -\varepsilon_n r_{i,n}\}$ ,  $i = 1, 2, \dots, N$

$C_{n+1} = \bigcap_{i=1}^N C_{n+1}^i$ ,

iii)  $x_{n+1} = P_{C_{n+1}}u$ ,  $n = 1, 2, \dots$

If  $\lim_{n \rightarrow \infty} \varepsilon_n r_{i,n} = 0$  for all  $i = 1, 2, \dots, N$ , then the sequence  $\{x_n\}$  converges strongly to  $P_S u$ , as  $n \rightarrow \infty$ .

*Proof.* In (3.2) and (3.3), if  $\delta_n = 0$ , for all  $n \geq 1$ , then we have the element  $x_{n+1}$  is defined by

$$x_{n+1} \in \{z \in C_{n+1} : \|u - z\| \leq d(u, C_{n+1})\};$$

that is,  $x_{n+1} = P_{C_{n+1}}u$ .

So, apply Theorem 3.5 with  $\delta_n = 0$  for all  $n \geq 1$ , we obtain the proof of this corollary.  $\square$

*Remark 3.9.* If  $\varepsilon = \delta_n = 0$ , for all  $n \geq 1$ , then in Corollaries 3.7 and 3.8 the sequence  $\{x_n\}$  will be defined by  $x_1 = x \in E$ ,  $C_1 = E$ , and

i)  $y_{i,n} = J_{r_{i,n}}^i x_n$ ,  $i = 1, 2, \dots, N$

ii) Choose  $i_n$  such that  $\|y_{i_n,n} - x_n\| = \max_{i=1,\dots,N} \{\|y_{i,n} - x_n\|\}$ , let  $y_n = y_{i_n,n}$ ,

$C_{n+1} = \{z \in C_n : \langle y_n - z, J_E(x_n) - J_E(y_n) \rangle \geq 0\}$ , or

ii\*)  $C_{n+1}^i = \{z \in C_n : \langle y_{i,n} - z, J_E(x_n) - J_E(y_{i,n}) \rangle \geq 0\}$ ,  $i = 1, 2, \dots, N$

$C_{n+1} = \bigcap_{i=1}^N C_{n+1}^i$ ,

iii)  $x_{n+1} = P_{C_{n+1}}u$ ,  $n = 1, 2, \dots$

*Remark 3.10.* In Remark 3.9, if  $E$  is a real Hilbert space and  $N = 1$ , then we obtain the result of Takahashi, Takeuchi, and Kubota (see, [18, Theorem 4.5]). But, in this case we do not use the condition  $r_n \rightarrow \infty$ . So, the Corollaries 3.7 and 3.8 are more general than the result of Takahashi and others.

#### 4. AN APPLICATION

Let  $E$  be a Banach space, and let  $f : E \rightarrow (-\infty, \infty]$  be a proper, lower semicontinuous, and convex function. The subdifferential of  $f$  is multi-valued

mapping  $\partial f : E \rightarrow 2^{E^*}$  which is defined by

$$\partial f(x) = \{g \in E^* : f(y) - f(x) \geq \langle y - x, g \rangle, \forall y \in E\}$$

for all  $x \in E$ . We know that  $\partial f$  is maximal monotone operator (see [14]) and  $x_0 \in \arg \min_E f(x)$  if and only if  $\partial f(x_0) \ni 0$ .

The  $\varepsilon$ -subdifferential enlargement of  $\partial f$ , is given by

$$\partial_\varepsilon f(x) = \{u \in E^* : f(y) - f(x) \geq \langle y - x, u \rangle - \varepsilon, \forall y \in E\}$$

for each  $\varepsilon \geq 0$ . We know that  $\partial_\varepsilon f(x) \subset (\partial f)^\varepsilon(x)$  for any  $x \in E$ . Moreover, in the some particular cases, we have that  $\partial_\varepsilon f(x) \subsetneq (\partial f)^\varepsilon(x)$  (see, [3, Example 2 and Example 3]).

In [1] when  $E$  is a real Hilbert space, Alvarez proposed the following approximate inertial proximal algorithm:

$$c_n \partial_{\varepsilon_n} f(x_{n+1}) + x_{n+1} - x_n - \alpha_n(x_n - x_{n-1}) \ni 0.$$

In [13], Moudafi and Elisabeth extended the above iterative method in the form

$$c_n(\partial f)^{\varepsilon_n}(x_{n+1}) + x_{n+1} - x_n - \alpha_n(x_n - x_{n-1}) \ni 0. \tag{4.1}$$

They proved that if there exists  $c > 0$  such that  $c_n \geq c$  for all  $n \geq 1$ , and there is  $\alpha \in [0, 1)$  such that  $\{\alpha_n\} \subset [0, \alpha]$ ,  $\sum_{n=1}^\infty c_k \varepsilon_k < \infty$ , and

$$\sum_{n=1}^\infty \alpha_n \|x_n - x_{n-1}\|^2 < \infty,$$

then the sequence  $\{x_n\}$  converges weakly to a minimum point of  $f$ .

Note that, if  $\alpha_n = 0$  for all  $n \geq 1$ , then (4.1) becomes

$$c_n(\partial f)^{\varepsilon_n}(x_{n+1}) + x_{n+1} - x_n \ni 0.$$

From Theorems 3.5 and 3.6, we have the following theorem.

**Theorem 4.1.** *Let  $E$  be a uniformly convex and smooth Banach space, and let  $f_i$ ,  $i = 1, 2, \dots, N$ , be proper, lower semicontinuous, and convex functions of  $E$  into  $(-\infty, \infty]$  such that  $S = \bigcap_{i=1}^N \arg \min_{x \in E} f_i(x) \neq \emptyset$ . Let  $\{\varepsilon_n\}$  and  $\{\delta_n\}$  be non-negative real sequences, and let  $\{r_{i,n}\}$ ,  $i = 1, 2, \dots, N$ , be positive real sequences such that  $\min_i \{\inf_n \{r_{i,n}\}\} \geq r > 0$ . For a given point  $u \in E$ , we define the sequence  $\{x_n\}$  by  $x_1 = x \in E$ ,  $C_1 = E$ , and*

i) Find  $y_{i,n} \in E$  such that  $J_E(y_{i,n}) - J_E(x_n) + r_{i,n}(\partial f_i)^{\varepsilon_n}(y_{i,n}) \ni 0$ ,  $i = 1, 2, \dots, N$

ii) Choose  $i_n$  such that  $\|y_{i_n,n} - x_n\| = \max_{i=1, \dots, N} \{\|y_{i,n} - x_n\|\}$ , let  $y_n = y_{i_n,n}$ ,

$$C_{n+1} = \{z \in C_n : \langle y_n - z, J_E(x_n) - J_E(y_n) \rangle \geq -\varepsilon_n r_{i_n,n}\}, \text{ or}$$

$$\text{ii*) } C_{n+1}^i = \{z \in C_n : \langle y_{i,n} - z, J_E(x_n) - J_E(y_{i,n}) \rangle \geq -\varepsilon_n r_{i,n}\}, \quad i = 1, 2, \dots, N$$

$$C_{n+1} = \bigcap_{i=1}^N C_{n+1}^i,$$

iii) Find  $x_{n+1} \in \{z \in C_{n+1} : \|u - z\|^2 \leq d^2(u, C_{n+1}) + \delta_{n+1}\}$ ,  $n = 1, 2, \dots$

If  $\lim_{n \rightarrow \infty} \varepsilon_n r_{i,n} = \lim_{n \rightarrow \infty} \delta_n = 0$ , for all  $i = 1, 2, \dots, N$ , then the sequence  $\{x_n\}$  converges strongly to  $P_S u$ , as  $n \rightarrow \infty$ .

*Remark 4.2.* Since  $\partial_\varepsilon f(x) \subset (\partial f)^\varepsilon(x)$ , in Theorem 4.1, we can replace  $(\partial f_i)^{\varepsilon_n}$  by  $(\partial f_i)_{\varepsilon_n}$  for all  $i = 1, 2, \dots, N$ .

In Theorem 4.1, if  $\varepsilon_n = 0$  for all  $n \geq 1$ , then we have the following corollary.

**Corollary 4.3.** *Let  $E$  be a uniformly convex and smooth Banach space, and let  $f_i$ ,  $i = 1, 2, \dots, N$ , be proper, lower semi-continuous, and convex functions of  $E$  into  $(-\infty, \infty]$  such that  $S = \bigcap_{i=1}^N \arg \min_E f_i(x) \neq \emptyset$ . Let  $\{\delta_n\}$  be non-negative real sequence, and let  $\{r_{i,n}\}$ ,  $i = 1, 2, \dots, N$ , be positive real sequences such that  $\min_i \{\inf_n \{r_{i,n}\}\} \geq r > 0$ . For a given point  $u \in E$ , we define the sequence  $\{x_n\}$  by  $x_1 = x \in E$ ,  $C_1 = E$ , and*

i)  $y_{i,n} = \arg \min_{y \in E} \left\{ f_i(y) + \frac{1}{2r_{i,n}} \|y\|^2 - \frac{1}{r_{i,n}} \langle y, J_E(x_n) \rangle \right\}$ ,  $i = 1, 2, \dots, N$

ii) Choose  $i_n$  such that  $\|y_{i_n,n} - x_n\| = \max_{i=1,\dots,N} \{\|y_{i,n} - x_n\|\}$ , let  $y_n = y_{i_n,n}$ ,

$C_{n+1} = \{z \in C_n : \langle y_n - z, J_E(x_n) - J_E(y_n) \rangle \geq 0\}$ , or

ii\*)  $C_{n+1}^i = \{z \in C_n : \langle y_{i,n} - z, J_E(x_n) - J_E(y_{i,n}) \rangle \geq 0\}$ ,  $i = 1, 2, \dots, N$

$C_{n+1} = \bigcap_{i=1}^N C_{n+1}^i$ ,

iii) Find  $x_{n+1} \in \{z \in C_{n+1} : \|u - z\|^2 \leq d^2(u, C_{n+1}) + \delta_{n+1}\}$ ,  $n = 1, 2, \dots$ .

If  $\lim_{n \rightarrow \infty} \delta_n = 0$ , then the sequence  $\{x_n\}$  converges strongly to  $P_S u$ , as  $n \rightarrow \infty$ .

*Proof.* We have

$$y_{i,n} = \arg \min_{y \in E} \left\{ f_i(y) + \frac{1}{2r_{i,n}} \|y\|^2 - \frac{1}{r_{i,n}} \langle y, J_E(x_n) \rangle \right\}$$

if and only if

$$\partial f_i(y_{i,n}) + \frac{1}{r_{i,n}} (J_E(y_{i,n}) - J_E(x_n)) \ni 0,$$

which implies that

$$y_{i,n} = J_{r_{i,n}}^i(x_n),$$

where  $J_{r_{i,n}}^i = (J_E + r_{i,n} \partial f_i)^{-1}$ .

So, by using Theorems 3.5 and 3.6 we get the proof of this corollary. □

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