

Dirichlet problem for elliptic equations of the second order in a singular domain of \mathbb{R}^2

by

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(Received February 6 1973)

1. Introduction.

In this paper we treat the regularity of solutions of the Dirichlet problem for elliptic equations of the second order in a domain with edges.

In the case where the boundary of a domain is smooth, we know well the regularity of solutions of the Dirichlet problem.

T. Carleman [1] had studied the boundary value problem of the Laplace equation for a domain with edges. M. Š. Birman and G. E. Skvortsov [2] dealt with a kind of regularity of solutions of the Dirichlet problem in the case where the boundary of a bounded domain in \mathbb{R}^2 consists of a finite number of three times continuously differentiable curves, which meet with the angles different from 0 or 2π .

V. A. Kondrat'ev [3] studied the general boundary value problem for a domain with conical or angular points in \mathbb{R}^n .

We shall extend the result of M. Š. Birman and G. E. Skvortsov. Let Ω be a bounded domain in \mathbb{R}^2 and let the boundary of Ω consist of a finite number of three times continuously differentiable curves, which may meet even with the angles 0 or 2π , but they have not contact of order ∞ .

Consider an elliptic differential operator of the second order:

$$(1.1) \quad Lu = - \sum_{i,j=1}^2 a_{ij}(x) \frac{\partial^2 u}{\partial x_i \partial x_j} + \sum_{i=1}^2 a_i(x) \frac{\partial u}{\partial x_i} + a(x)u$$

where the coefficients $a_{ij}(x)$ are real functions continuous on $\bar{\Omega}$ having the bounded first generalized derivatives, and $a_i(x)$ and $a(x)$ are real bounded measurable.

We set

$$D(L; \Omega) = \{u \in \mathcal{D}_{L^2}^1(\Omega); Lu \in L^2(\Omega)\}.$$
¹⁾

Then our main theorem is the following:

Theorem 1. *The co-dimension of $\mathcal{D}_{L^2}^1(\Omega) \cap \mathcal{E}_{L^2}^2(\Omega)$ in $D(L; \Omega)$ is equal to the number of the edges with the angles larger than π .*

In section 5 this theorem will be proved with help of the result of M. Š. Birman and G. E. Skvortsov and of the following theorem.

Theorem 2. *Suppose that*

$$\Omega = \{(x_1, x_2); 0 < x_1 < d, 0 < x_2 < x_1^\alpha\},$$

where $\alpha > 1$. Then the solution $u(x) \in \mathcal{D}_{L^2}^1(\Omega)$ of the equation $Lu = f$ belongs to $\mathcal{E}_{L^2}^2(\Omega)$, if $f \in L^2(\Omega)$.

We prove Theorem 2 in Section 2. In Sections 3 and 4, we prove the propositions which are needed in Section 2. Finally we prove Theorem 1 in Section 5.

2. Proof of Theorem 2.

In this section we prove Theorem 2 with help of three propositions below, which will be proved in Sections 3 and 4.

Proposition 1. *In the case where $L = -\Delta$, Theorem 2 is true, that is to say, for all $f(x) \in L^2(\Omega)$ the solution $u(x) \in \mathcal{D}_{L^2}^1(\Omega)$ of the equ-*

1) Throughout this paper, $\mathcal{E}_{L^2}^k(\Omega)$ denotes the Hilbert space of all functions $u(x) \in L^2(\Omega)$ whose derivatives (in the sense of distributions) up to order k belong to $L^2(\Omega)$, and $\mathcal{D}_{L^2}^k$ is the closure of $\mathcal{D}(\Omega)$ (in Schwartz' notation) in $\mathcal{E}_{L^2}^k(\Omega)$. For $u(x) \in \mathcal{E}_{L^2}^k(\Omega)$, we denote its norm by $\|u(x)\|_{k, L^2}$. Namely,

$$\|u(x)\|_{k, L^2}^2 = \sum_{|\nu| \leq k} \int_{\Omega} |D^\nu u(x)|^2 dx.$$

ation $\Delta u = f$ belongs to $\mathcal{E}_{L^2}^2(\Omega)$.

By definition, the set $C_0^k(\bar{\Omega})$ consists of all functions which are k -times continuously differentiable in $\bar{\Omega}$ and vanish at the boundary of Ω .

Proposition 2. $C_0^3(\bar{\Omega})$ is dense in $\mathcal{D}_{L^2}^1(\Omega) \cap \mathcal{E}_{L^2}^2(\Omega)$.

Proposition 3. Let L_1 and L_2 be two elliptic operators of the form (1.1). If the infimums of the coefficients $a(x)$ are sufficiently large, we have

$$(2.1) \quad |(L_1 u, L_2 u)| \geq c \|u\|_{2, L^2}^2 \quad \text{for } u \in C_0^3(\bar{\Omega}),$$

where c is a positive constant independent of $u(x)$.

From Proposition 2, the estimate (2.1) also holds for $u(x) \in \mathcal{D}_{L^2}^1(\Omega) \cap \mathcal{E}_{L^2}^2(\Omega)$.

Proof of Theorem 2. Set $L_1 = L + \lambda$ and $L_2 = -\Delta + \lambda$, where λ is a sufficiently large positive number. It is easily checked that

$$R(L_1) = \{L_1 u; u \in \mathcal{D}_{L^2}^1(\Omega) \cap \mathcal{E}_{L^2}^2(\Omega)\}$$

is a closed subspace of $L^2(\Omega)$ by setting $L_2 = L_1$ in Proposition 3. On the other hand, we see, from Proposition 1, that

$$(2.2) \quad R(L_2) = R(-\Delta + \lambda) = L^2(\Omega).$$

In order to show that $R(L_1) = L^2(\Omega)$, we have only to verify that $R(L_1)$ is dense in $L^2(\Omega)$. In fact, suppose that there exists a $g \in L^2(\Omega)$ such that $(g, L_1 u) = 0$ for all $u \in \mathcal{D}_{L^2}^1(\Omega) \cap \mathcal{E}_{L^2}^2(\Omega)$. Then there exists a solution $w(x) \in \mathcal{D}_{L^2}^1(\Omega) \cap \mathcal{E}_{L^2}^2(\Omega)$ of $L_2 w = g$ owing to (2.2) and $(L_2 w, L_1 w) = 0$. By virtue of Proposition 3, $w = 0$, therefore $g = 0$. Accordingly $R(L_1)$ is dense in $L^2(\Omega)$.

Now, let us take the solution in question $u \in \mathcal{D}_{L^2}^1(\Omega)$ of $Lu = f$. This equation can be rewritten as

$$L_1 u = Lu + \lambda u = f + \lambda u.$$

The right hand side $f + \lambda u \equiv h (\in L^2(\Omega))$ is the image of a $v \in \mathcal{D}_{L^2}^1(\Omega) \cap$

$\mathcal{E}_{L^2}^1(\Omega)$ by L_1 as is shown just above. Hence, we have two equations $L_1 u = h$ and $L_1 v = h$. By the uniqueness of the solution in $\mathcal{D}_{L^2}^1(\Omega)$, we have $u = v$, that is, u itself belongs to $\mathcal{E}_{L^2}^1(\Omega)$. Thus, our Theorem 2 is proved assuming Propositions 1, 2 and 3.

3. Proof of Propositions 1 and 2.

Remark at first that we may suppose that d is sufficiently small, because if necessary, we may take a C^∞ -function $\varphi(x)$ with a small compact support which is equal to 1 near the origin, and we may consider φu in place of u ;

$$L(\varphi u) = \varphi Lu + uL\varphi + \sum_{i,j=1}^2 a_{ij}(x) \left(\frac{\partial \varphi}{\partial x_i} \frac{\partial u}{\partial x_j} + \frac{\partial \varphi}{\partial x_j} \frac{\partial u}{\partial x_i} \right) - a(x)\varphi u \in L^2(\Omega)$$

We begin with the change of variable $(x_1, x_2) \rightarrow (\xi, \eta)$

$$(3.1) \quad \begin{cases} \xi = (\beta - 1)x_1^{-\frac{1}{\beta-1}} \\ \eta = x_1^{-\frac{\beta}{\beta-1}} \cdot x_2 \end{cases} \quad \text{or} \quad \begin{cases} x_1 = (\beta - 1)^{\beta-1} \cdot \xi^{1-\beta} \\ x_2 = (\beta - 1)^\beta \xi^{-\beta} \cdot \eta, \end{cases}$$

where $1/\alpha + 1/\beta = 1$. Then the domain Ω is mapped homeomorphically onto the domain:

$$\tilde{\Omega} = \{(\xi, \eta) \in \mathbb{R}^2; \xi > A, 0 < \eta < 1\}$$

where $A = (\beta - 1)d^{-\frac{1}{\beta-1}}$. We obtain the following rules of calculus:

$$(3.2) \quad \left\{ \begin{array}{l} \frac{\partial u}{\partial x_1} = -(\beta - 1)^{-\beta} \xi^\beta \frac{\partial u}{\partial \xi} - \beta(\beta - 1)^{-\beta} \xi^{\beta-1} \eta \frac{\partial u}{\partial \eta} \\ \frac{\partial u}{\partial x_2} = (\beta - 1)^{-\beta} \xi^\beta \frac{\partial u}{\partial \eta} \\ \frac{\partial^2 u}{\partial x_1^2} = (\beta - 1)^{-2\beta} \xi^{2\beta} \frac{\partial^2 u}{\partial \xi^2} + 2\beta(\beta - 1)^{-2\beta} \xi^{2\beta-1} \eta \frac{\partial^2 u}{\partial \xi \partial \eta} \\ \qquad \qquad \qquad + \beta^2(\beta - 1)^{-2\beta} \xi^{2\beta-2} \eta^2 \frac{\partial^2 u}{\partial \eta^2} \end{array} \right.$$

$$\begin{aligned}
& + \beta(\beta-1)^{-2\beta}\xi^{2\beta-1} \frac{\partial u}{\partial \xi} + (2\beta^2 - \beta)(\beta-1)^{-2\beta}\xi^{2\beta-2}\eta \frac{\partial u}{\partial \eta} \\
\frac{\partial^2 u}{\partial x_1 \partial x_2} & = -(\beta-1)^{-2\beta}\xi^{2\beta} \frac{\partial^2 u}{\partial \xi \partial \eta} - \beta(\beta-1)^{-2\beta}\xi^{2\beta-1}\eta \frac{\partial^2 u}{\partial \eta^2} \\
& \qquad \qquad \qquad - \beta(\beta-1)^{-2\beta}\xi^{2\beta-1} \frac{\partial u}{\partial \eta} \\
\frac{\partial^2 u}{\partial x_2^2} & = (\beta-1)^{-2\beta}\xi^{2\beta} \frac{\partial^2 u}{\partial \eta^2}
\end{aligned}$$

$$(3.3) \quad \frac{\partial(x_1, x_2)}{\partial(\xi, \eta)} = -(\beta-1)^{2\beta}\xi^{-2\beta}.$$

Hence, the relation between the Laplacians corresponding to two systems of variables can be expressed as

$$\begin{aligned}
(3.4) \quad \Delta_{x_1, x_2} & = (\beta-1)^{-2\beta}\xi^{2\beta} \left\{ \Delta_{\xi, \eta} + 2\beta\xi^{-1}\eta \frac{\partial^2}{\partial \xi \partial \eta} + \beta^2\xi^{-2}\eta^2 \frac{\partial^2}{\partial \eta^2} \right. \\
& \qquad \qquad \qquad \left. + \beta\xi^{-1} \frac{\partial}{\partial \xi} + (2\beta^2 - \beta)\xi^{-2}\eta \frac{\partial}{\partial \eta} \right\}.
\end{aligned}$$

The formulae (3.2) and (3.3) lead us to the following:

- Lemma 1.** 1) $u(x_1, x_2) \in L_x^2$, if and only if $\xi^{-\beta}u(\xi, \eta) \in L_{\xi, \eta}^2$;
2) $u(x_1, x_2) \in \mathcal{O}_{L_x^2}^1$, if and only if $\xi^{-\beta}u(\xi, \eta)$, $\frac{\partial u}{\partial \xi}$ and $\frac{\partial u}{\partial \eta} \in L_{\xi, \eta}^2$;
3) $u(x_1, x_2) \in \mathcal{O}_{L_x^2}^2$, if $\xi^{-\beta}u$, $\xi^{\beta-1} \frac{\partial u}{\partial \xi}$, $\xi^{\beta-1} \frac{\partial u}{\partial \eta}$, $\xi^\beta \frac{\partial^2 u}{\partial \xi^2}$, $\xi^\beta \frac{\partial^2 u}{\partial \xi \partial \eta}$ and $\xi^\beta \frac{\partial^2 u}{\partial \eta^2} \in L_{\xi, \eta}^2$;

where L_x^2 and $L_{\xi, \eta}^2$ are understood as L^2 -spaces with respect to the usual Lebesgue measures $dx_1 dx_2$ and $d\xi d\eta$ respectively.

We introduce some functional spaces, at first define

$$\mathcal{O}_{\xi, \eta}^k = \{u(\xi, \eta); \xi^\beta D_{\xi, \eta}^k u(\xi, \eta) \in L_{\xi, \eta}^2 \text{ for } |v| \leq k\}$$

with the norms

$$\|u(\xi, \eta)\|_{\mathcal{E}_{\xi, \eta}^k}^2 = \sum_{|\mu| \leq k} \|\xi^\beta D_{\xi, \eta}^\mu u(\xi, \eta)\|_{L_{\xi, \eta}^2}^2.$$

Because $\{\sqrt{2} \sin n\pi\eta\}_{n=1}^\infty$ is a complete orthonormal system in $L_\eta^2(0, 1)$, we can develop every function $u(\xi, \eta) \in \mathcal{E}_{\xi, \eta}^0$ in a Fourier series with respect to η ;

$$(3.5) \quad u(\xi, \eta) = \sum_{n=1}^\infty u_n(\xi) \sin n\pi\eta,$$

with coefficients $u_n(\xi)$ such that $\xi^\beta u_n(\xi) \in L_\xi^2(A, \infty)$.

We denote by $\mathcal{D}_{\xi, \eta}$ the set of all functions $u(\xi, \eta)$ in $\mathcal{E}_{\xi, \eta}^2$ which satisfy the following two conditions

$$(3.6) \quad u(A, \eta) = 0$$

and

$$(3.7) \quad \sum_{n=1}^\infty \{n^4 \|\xi^\beta u_n\|_{L_\xi^2}^2 + n^2 \|\xi^\beta \frac{\partial u_n}{\partial \xi}\|_{L_\xi^2}^2 + \|\xi^\beta \frac{\partial^2 u_n}{\partial \xi^2}\|_{L_\xi^2}^2\} < \infty.$$

The norm of u in $\mathcal{D}_{\xi, \eta}$ is defined as the square root of the left hand side of (3.7). Then, for every function belonging to $\mathcal{D}_{\xi, \eta}$, the norms in $\mathcal{E}_{\xi, \eta}^2$ and in $\mathcal{D}_{\xi, \eta}$ are equivalent. The condition (3.7) implies a boundary condition at $\eta=0$ and $\eta=1$ to each element of $\mathcal{D}_{\xi, \eta}$.

It is easy to see that $A_{\xi, \eta}$ is a bounded linear operator from $\mathcal{D}_{\xi, \eta}$ to $\mathcal{E}_{\xi, \eta}^0$. Our first step is to construct an operator $G: \mathcal{E}_{\xi, \eta}^0 \rightarrow \mathcal{D}_{\xi, \eta}$ which is the inverse of $A_{\xi, \eta}$.

For $g(\xi, \eta) \in \mathcal{E}_{\xi, \eta}^0$, we develop $g(\xi, \eta)$ in a Fourier series with respect to η ;

$$(3.8) \quad g(\xi, \eta) = \sum_{n=1}^\infty g_n(\xi) \sin n\pi\eta.$$

We define $u_n(\xi)$ by

$$(3.9) \quad u_n(\xi) = \int_A^\infty \frac{1}{2n\pi} \{-e^{-n\pi|\xi-s|} + e^{n\pi(2A-\xi-s)}\} g_n(s) ds$$

In fact $u_n(\xi)$ is the solution of the ordinary differential equation:

$$(3.10) \quad \frac{d^2 u_n(\xi)}{d\xi^2} = (n\pi)^2 u_n + g_n$$

with the boundary conditions $u_n(A)=0$ and $u_n(\infty)=0$. Set

$$(3.11) \quad Gg(\xi, \eta) = \sum_{n=1}^{\infty} u_n(\xi) \sin n\pi\eta.$$

This is the operator which we have looked for. We are going to check up (3.6), (3.7) for $u=Gg$ and $\Delta_{\xi,\eta}Gg=g$ on $\mathcal{E}_{\xi,\eta}^0$. Assuming the condition (3.7) for $u=Gg$, the condition (3.6) and the equality $\Delta_{\xi,\eta}Gg=g$ are easily verified from (3.9) and (3.10). We now show (3.7).

Define two operators;

$$(3.12) \quad \begin{cases} K_{1,n}g(\xi) = \int_A^{\infty} e^{-n\pi|\xi-s|}g(s)ds \\ K_{2,n}g(\xi) = \int_A^{\infty} e^{n\pi(2A-\xi-s)}g(s)ds, \end{cases}$$

and the space;

$$\mathcal{E}_{\xi}^0 = \{u(\xi); \xi^{\beta}u(\xi) \in L^2(A, \infty)\}$$

with the norm:

$$\|u(\xi)\|_{\mathcal{E}_{\xi}^0} = \|\xi^{\beta}u(\xi)\|_{L_{\xi}^2}.$$

Then the following lemma holds.

Lemma 2. $K_{1,n}$ and $K_{2,n}$ are bounded operators on \mathcal{E}_{ξ}^0 , moreover

$$(3.13) \quad \|K_{i,n}\|_{\mathcal{E}_{\xi}^0 \rightarrow \mathcal{E}_{\xi}^0} \leq \frac{c}{n} \quad (i=1, 2)$$

where c is independent of A for sufficiently large A .

Proof We are going to show the inequalities:

$$(3.14) \quad \int_A^{\infty} e^{-n\pi|\xi-s|} ds \leq \frac{c}{n}$$

$$(3.15) \quad \int_A^\infty e^{-n\pi|\xi-s|} \left(\frac{\xi}{s}\right)^{2\beta} d\xi \leq \frac{c}{n},$$

$$(3.16) \quad \int_A^\infty e^{n\pi(2A-\xi-s)} ds \leq \frac{c}{n},$$

$$(3.17) \quad \int_A^\infty e^{n\pi(2A-\xi-s)} \left(\frac{\xi}{s}\right)^{2\beta} d\xi \leq \frac{c}{n},$$

where c is independent of $n \geq 1$ and $s, \xi \geq A$.

(3.14) and (3.16) are trivial. For (3.15), we can write

$$\int_A^\infty e^{-n\pi|\xi-s|} \left(\frac{\xi}{s}\right)^{2\beta} d\xi = \int_A^s e^{n\pi(\xi-s)} \left(\frac{\xi}{s}\right)^{2\beta} d\xi + \int_s^\infty e^{-n\pi(\xi-s)} \left(\frac{\xi}{s}\right)^{2\beta} d\xi,$$

the first term of the right hand side $\leq \int_A^s e^{n\pi(\xi-s)} d\xi < \frac{1}{n\pi}$. In order to estimate the last term, we set $\xi = st$ and integrate by parts,

$$\begin{aligned} \text{the last term} &= s \int_1^\infty e^{-n\pi s(t-1)} t^{2\beta} dt \\ &= \frac{1}{n\pi} + \frac{2\beta}{n\pi} \int_1^\infty e^{-n\pi s(t-1)} t^{2\beta-1} dt \\ &< \frac{c}{n}, \text{ because } s \geq A. \end{aligned}$$

We have then proved (3.15). (3.17) is simpler than (3.15). From (3.14) and Schwarz' inequality,

$$\begin{aligned} |K_{1,n}g(\xi)|^2 &\leq \int_A^\infty e^{-n\pi|\xi-s|} ds \cdot \int_A^\infty e^{-n\pi|\xi-s|} \cdot |g(s)|^2 ds \\ &\leq \frac{c}{n} \int_A^\infty e^{-n\pi|\xi-s|} \cdot |g(s)|^2 ds. \end{aligned}$$

Moreover from (3.15) and Fubini's theorem, we have

$$\begin{aligned} \int_A^\infty \xi^{2\beta} \cdot |K_{1,n}g(\xi)|^2 d\xi &\leq \frac{c}{n} \int_A^\infty \xi^{2\beta} d\xi \cdot \int_A^\infty e^{-n\pi|\xi-s|} \cdot |g(s)|^2 ds \\ &\leq \frac{c}{n} \int_A^\infty s^{2\beta} |g(s)|^2 ds \int_A^\infty e^{-n\pi|\xi-s|} \left(\frac{\xi}{s}\right)^{2\beta} d\xi \end{aligned}$$

$$\leq \left(\frac{c}{n}\right)^2 \|g(\xi)\|_{\mathcal{E}_\xi^0}^2,$$

which is precisely the estimate (3.13) for $i=1$. Similarly, we can treat the case of $K_{2,n}$. (Q.E.D.)

By definition of $K_{1,n}$ and $K_{2,n}$, we can write

$$(3.18) \quad u_n(\xi) = -\frac{1}{2n\pi} \{K_{1,n}g_n(\xi) - K_{2,n}g_n(\xi)\}.$$

From Lemma 2,

$$(3.19) \quad \sum_{n=1}^{\infty} n^4 \|\xi^\beta u_n(\xi)\|_{L_\xi^2}^2 \leq \sum_{n=1}^{\infty} c \|\xi^\beta g_n(\xi)\|_{L_\xi^2}^2 \leq c' \|g(\xi, \eta)\|_{\mathcal{E}_\xi^0}^2,$$

Differentiate the both sides of (3.9), then

$$(3.20) \quad \frac{du_n}{d\xi} = \frac{1}{2} \int_A^\infty s g_n(\xi - s) e^{-n\pi|\xi-s|} g_n(s) ds - \frac{1}{2} \int_A^\infty e^{n\pi(2A-\xi-s)} g_n(s) ds.$$

Therefore

$$(3.21) \quad \sum_{n=1}^{\infty} n^2 \left\| \xi^\beta \frac{du_n}{d\xi} \right\|_{L_\xi^2}^2 \leq \sum_{n=1}^{\infty} n^2 \{ \|\xi^\beta K_{1,n}(|g_n|)\|_{L_\xi^2}^2 + \|\xi^\beta K_{2,n}g_n\|_{L_\xi^2}^2 \} \\ \leq c \|g(\xi, \eta)\|_{\mathcal{E}_\xi^0}^2,$$

And from (3.10) and (3.19),

$$(3.22) \quad \sum_{n=1}^{\infty} \left\| \xi^\beta \frac{d^2 u_n}{d\xi^2} \right\|_{L_\xi^2}^2 \leq c \|g(\xi, \eta)\|_{\mathcal{E}_\xi^0}^2,$$

By (3.19), (3.21) and (3.22), which together mean (3.7), we find that G is a bounded operator from $\mathcal{E}_{\xi, \eta}^0$ to $\mathcal{D}_{\xi, \eta}$.

Proof of Proposition 1. By (3.4), the equation $\Delta_{x_1, x_2} u = f$ turns out to be

$$(3.23) \quad \Delta_{\xi, \eta} u + 2\beta\xi^{-1}\eta \frac{\partial^2 u}{\partial\xi\partial\eta} + \beta^2\xi^{-2}\eta^2 \frac{\partial^2 u}{\partial\eta^2} + \beta\xi^{-1} \frac{\partial u}{\partial\xi} + (2\beta^2 - \beta)\xi^{-2}\eta \frac{\partial u}{\partial\eta} \\ = (\beta - 1)^2 \beta \xi^{-2} \eta f.$$

Denote the right hand side of (3.23) by $h(\xi, \eta)$, then $h(\xi, \eta)$ belongs to $\mathcal{E}_{\xi, \eta}^0$. Look for the solution u of the form $u = Gg$ with some $g \in \mathcal{E}_{\xi, \eta}^0$, then, g must satisfy

$$(3.24) \quad g + Tg = h,$$

where

$$(3.25) \quad Tg = 2\beta\xi^{-1}\eta\frac{\partial^2 Gg}{\partial\xi\partial\eta} + \beta^2\xi^{-2}\eta^2\frac{\partial^2 Gg}{\partial\eta^2} + \beta\xi^{-1}\frac{\partial Gg}{\partial\xi} \\ + (2\beta^2 - \beta)\xi^{-2}\eta\frac{\partial Gg}{\partial\eta}.$$

Since G is a bounded linear operator from $\mathcal{E}_{\xi, \eta}^0$ to $\mathcal{D}_{\xi, \eta}$, T is a bounded linear operator on $\mathcal{E}_{\xi, \eta}^0$, and if we take sufficiently large A , the operator norm of T may be smaller than 1. Therefore $I + T$ has the inverse $(I + T)^{-1}$. Since the equation $\Delta_{x_1, x_2}u = f$ has a unique solution in $\mathcal{D}_{L_x^2}^1(\Omega)$, if we know that $\mathcal{D}_{\xi, \eta}$ is included in $\mathcal{D}_{L_x^2}^1(\Omega)$, $u = G(I + T)^{-1}h$ is the unique solution of the equation $\Delta_{x_1, x_2}u = f$ and belongs to $\mathcal{D}_{\xi, \eta}$, a fortiori to $\mathcal{E}_{L_x^2}^2(\Omega)$.

Let us show the inclusion $\mathcal{D}_{\xi, \eta} \subset \mathcal{D}_{L_x^2}^1(\Omega)$. Take an infinitely differentiable function $\zeta(\xi)$ such that $\zeta(\xi) \equiv 1$ on $\xi < 2A$ and $\zeta(\xi) \equiv 0$ on $\xi > 3A$, and define

$$\zeta_M(\xi) = \zeta\left(\frac{\xi}{M}\right).$$

For every $u(\xi, \eta) = \sum_{n=1}^{\infty} u_n(\xi) \sin n\pi\eta$ in $\mathcal{D}_{\xi, \eta}$, we set

$$(3.26) \quad u_{N, M}(\xi, \eta) = \sum_{n=1}^N \zeta_M(\xi) u_n(\xi) \sin n\pi\eta.$$

As $M \rightarrow \infty$, $u_{N, M}(\xi, \eta)$ tends to $u_N(\xi, \eta) \equiv \sum_{n=1}^N u_n(\xi) \sin n\pi\eta$ in $\mathcal{D}_{\xi, \eta}$, and as $N \rightarrow \infty$, $u_N(\xi, \eta)$ tends to $u(\xi, \eta)$ in $\mathcal{D}_{\xi, \eta}$. Because the topology of $\mathcal{D}_{\xi, \eta}$ is stronger than that of $\mathcal{E}_{L_x^2}^1(\Omega)$ and because the left hand side of (3.26) belongs to $\mathcal{D}_{L_x^2}^1(\Omega)$, $u(\xi, \eta)$ belongs to $\mathcal{D}_{L_x^2}^1(\Omega)$. Thus we see that $\mathcal{D}_{\xi, \eta} \subset \mathcal{D}_{L_x^2}^1(\Omega)$. Proposition 1 is proved.

Remark *The three transformations in the diagram*

$$\mathcal{D}_{L_x^2}^1(\Omega) \cap \mathcal{E}_{L_x^2}^2(\Omega) \xrightarrow{Ax_1, x_2} L_x^2(\Omega) \xrightarrow{(\beta-1)^{2\beta} \xi^{-2\beta} x} \mathcal{E}_{\xi, \eta}^0 \xrightarrow{G(1+T)^{-1}} \mathcal{D}_{\xi, \eta}$$

are continuous and the composition of them is identity mapping on $\mathcal{D}_{L_x^2}^1(\Omega) \cap \mathcal{E}_{L_x^2}^2(\Omega)$, therefore the norm in $\mathcal{E}_{L_x^2}^2(\Omega)$ and the norm in $\mathcal{D}_{\xi, \eta}$ are equivalent on $\mathcal{D}_{L_x^2}^1(\Omega) \cap \mathcal{E}_{L_x^2}^2(\Omega)$.

Proof of Proposition 2. By the above Remark, we have only to show that $C_0^3(\bar{\mathcal{D}})$ is dense in $\mathcal{D}_{\xi, \eta}$. For every $u(\xi, \eta) = \sum_{n=1}^{\infty} u_n(\xi) \sin n\pi\eta$ in $\mathcal{D}_{\xi, \eta}$, we extend $u_n(\xi)$ to $\xi < A$ in such a way that

$$(3.27) \quad u_n(\xi) = \begin{cases} u_n(\xi) & \text{if } \xi \geq A \\ -u_n(2A - \xi) & \text{if } \xi < A. \end{cases}$$

$$(3.28) \quad u_{N, M, \varepsilon}(\xi, \eta) = \sum_{n=1}^N \{ \rho_\varepsilon(\xi) * (\zeta_M(\xi) u_n(\xi)) \} \sin n\pi\eta,$$

where $\rho_\varepsilon(\xi) *$ is Friedrichs' mollifier and $\rho_\varepsilon(\xi)$ is an even function of ξ , then $u_{N, M, \varepsilon}(\xi, \eta)$ belongs to $C_0^\infty(\bar{\mathcal{D}})$.²⁾ As $\varepsilon \rightarrow +0$, $u_{N, M, \varepsilon}(\xi, \eta)$ tends to $u_{N, M}(\xi, \eta)$ in $\mathcal{D}_{\xi, \eta}$, and as $M \rightarrow \infty$, $u_{N, M}(\xi, \eta)$ tends to $u_N(\xi, \eta)$. Finally $u_N(\xi, \eta)$ tends to $u(\xi, \eta)$ in $\mathcal{D}_{\xi, \eta}$ as $N \rightarrow \infty$. Thus $C_0^\infty(\bar{\mathcal{D}})$ is dense in $\mathcal{D}_{\xi, \eta}$. (Q.E.D.)

4. Proof of Proposition 3.

In the case where the boundary of a domain is of class C^3 , Proposition 3 has already been proved by Ladyzhenskaya [4]. If the boundary is piece-wise smooth and has no edge with the angle 0, Proposition 3 also holds.

In this section, for convenience, L_1 and L_2 are written as L and M , respectively, and (x_1, x_2) as (x, y) . Denote several positive constants by c_i .

Now we divide L and M as

$$L = L_0 + L' + \lambda,$$

$$M = M_0 + M' + \lambda,$$

2) $C_0^\infty(\bar{\mathcal{D}})$ denotes $\bigcap_{k=0}^{\infty} C_0^k(\bar{\mathcal{D}})$.

where L_0 and M_0 are homogeneous parts of the second order of L and M , L' and M' are lower order parts, and λ is the positive number which will be determined later.

Lemma 3. *If $d > 0$ is sufficiently small, we have*

$$(4.1) \quad \operatorname{Re}(L_0 u, M_0 u) \geq c_1 \|u\|_{2, L^2}^2 - c_2 \|u\|_{1, L^2}^2 \quad \text{for } u \in C_0^3(\bar{\Omega})$$

Proof Denote

$$L_0 u = a u_{xx} + 2b u_{xy} + c u_{yy}$$

(4.2)

$$M_0 u = a' u_{xx} + 2b' u_{xy} + c' u_{yy}$$

and

$$(4.3) \quad v = u_x, \quad w = u_y,$$

then we can write

$$L_0 u = a v_x + b w_x + b v_y + c w_y,$$

$$M_0 u = a' v_x + b' w_x + b' v_y + c' w_y.$$

Now set

$$L_0 u \cdot \overline{M_0 u} = J_0 + J_1,$$

where

$$(4.4) \quad J_0 = (a v_x + b w_x)(a' \bar{v}_x + b' \bar{w}_x) + (b v_y + c w_y)(b' \bar{v}_y + c' \bar{w}_y) \\ + (a v_y + b w_y)(b' \bar{v}_x + c' \bar{w}_x) + (b v_x + c w_x)(a' \bar{v}_y + b' \bar{w}_y)$$

and

$$(4.5) \quad J_1 = (a v_x + b w_x)(b' \bar{v}_y + c' \bar{w}_y) - (a v_y + b w_y)(b' \bar{v}_x + c' \bar{w}_x) \\ + (b v_y + c w_y)(a' \bar{v}_x + b' \bar{w}_x) - (b v_x + c w_x)(a' \bar{v}_y + b' \bar{w}_y).$$

Since $v_y = w_x = u_{xy}$, we have $J_0 \geq c_3(|u_{xx}|^2 + 2|u_{xy}|^2 + |u_{yy}|^2)$ with c_3 independent of u and of (x, y) , because of the ellipticity of L and M .³⁾ Accordingly

$$(4.6) \quad \iint_{\Omega} J_0 dx dy \geq c_3(\|u\|_{2, L^2}^2 - \|u\|_{1, L^2}^2).$$

Next, we look at J_1 . Because $\operatorname{Re}(v_x \bar{v}_y - v_y \bar{v}_x) = \operatorname{Re}(w_x \bar{w}_y - w_y \bar{w}_x) = 0$, we have

$$\operatorname{Re} J_1 = F(v_x \bar{w}_y - v_y \bar{w}_x - w_x \bar{v}_y + w_y \bar{v}_x)$$

where $F = \frac{1}{2}(ac' + ca' - 2bb')$. Furthermore,

$$\begin{aligned} \operatorname{Re} J_1 dx dy &= F(dv \wedge d\bar{w} - dw \wedge d\bar{v}) \\ &= d\{F(vd\bar{w} - wd\bar{v})\} + (vd\bar{w} - wd\bar{v}) \wedge dF \\ &= d\omega + J_2 dx dy \end{aligned}$$

where $\omega = F(vd\bar{w} - wd\bar{v})$, and J_2 is a sum of products of the first derivatives of F , the first derivatives of u and the second derivatives of u . Therefore for an arbitrary small positive number ε ,

3) Using the equality $v_y = w_x$, we obtain

$$\begin{aligned} J_0 &= (av_x + bv_y)(a'\bar{v}_x + b'\bar{w}_x) + (bw_x + cw_y)(b'\bar{v}_y + c'\bar{w}_y) + \\ &\quad + (aw_x + bw_y)(b'\bar{v}_x + c'\bar{w}_x) + (bv_x + cv_y)(a'\bar{v}_y + b'\bar{w}_y) \\ &= a'\{\bar{v}_x(av_x + bv_y) + \bar{v}_y(bv_x + cv_y)\} \\ &\quad + b'\{\bar{w}_x(av_x + bv_y) + \bar{w}_y(bv_x + cv_y)\} \\ &\quad + b'\{\bar{v}_x(aw_x + bw_y) + \bar{v}_y(bw_x + cw_y)\} \\ &\quad + c'\{\bar{w}_x(aw_x + bw_y) + \bar{w}_y(bw_x + cw_y)\}. \end{aligned}$$

Set $A = \begin{bmatrix} a & b \\ b & c \end{bmatrix}$, then there exists a real orthogonal $(2, 2)$ -matrix T such that ${}^t T A T = \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix}$ ($\lambda_1, \lambda_2 > 0$). Setting $\begin{bmatrix} V_1 \\ V_2 \end{bmatrix} = {}^t T \begin{bmatrix} v_x \\ v_y \end{bmatrix}$ and $\begin{bmatrix} W_1 \\ W_2 \end{bmatrix} = {}^t T \begin{bmatrix} w_x \\ w_y \end{bmatrix}$, we obtain

$$\begin{aligned} J_0 &= a'(\lambda_1 |V_1|^2 + \lambda_2 |V_2|^2) + b'(\lambda_1 V_1 \bar{W}_1 + \lambda_2 V_2 \bar{W}_2) + \\ &\quad + b'(\lambda_1 \bar{V}_1 W_1 + \lambda_2 \bar{V}_2 W_2) + c'(\lambda_1 |W_1|^2 + \lambda_2 |W_2|^2) \\ &\geq c_8(|V_1|^2 + |V_2|^2 + |W_1|^2 + |W_2|^2) \\ &= c_8(|u_{xx}|^2 + 2|u_{xy}|^2 + |u_{yy}|^2), \end{aligned}$$

where we used the positivity of the matrix $A' = \begin{bmatrix} a' & b' \\ b' & c' \end{bmatrix}$.

$$(4.7) \quad \left| \iint_{\Omega} J_2 dx dy \right| \leq c_4 (\varepsilon \|u\|_{2, L^2}^2 + \varepsilon^{-1} \|u\|_{1, L^2}^2).$$

We will estimate

$$\iint_{\Omega} d\omega = \int_{\substack{y=0 \\ 0 \leq x \leq d}} \omega + \int_{\substack{x=d \\ 0 \leq y \leq d^\alpha}} \omega - \int_{\substack{y=x^\alpha \\ 0 \leq x \leq d}} \omega \equiv I_1 + I_2 + I_3$$

Because $u=v=dv=0$ on $y=0$, $I_1=0$. Similarly $I_2=0$. As $v=-\alpha x^{\alpha-1}w$ on $y=x^\alpha$, so

$$I_3 = - \int_0^d F \cdot \alpha(\alpha-1)x^{\alpha-2} \cdot |w|^2 dx$$

We pass to the coordinate system (ξ, η) defined by (3.1), then

$$dx = -(\beta-1)^\beta \xi^{-\beta} d\xi, \quad x^{\alpha-2} = (\beta-1)^{-(\beta-2)} \xi^{\beta-2},$$

and

$$w = (\beta-1)^{-\beta} \xi^\beta \times \frac{\partial u}{\partial \eta}(\xi, 1)$$

Therefore

$$(4.8) \quad |I_3| \leq c_5 \int_A^\infty \xi^{2\beta-2} \left| \frac{\partial u}{\partial \eta} \right|^2 d\xi \leq c_5 A^{-2} \int_A^\infty \xi^\beta \left| \frac{\partial u}{\partial \eta} \right|^2 d\xi.$$

If we take an infinitely differentiable function $\gamma(\eta)$ such that

$$\gamma(\eta) = \begin{cases} 0 & \text{if } \eta \leq \frac{1}{3} \\ 1 & \text{if } \eta \geq \frac{1}{2} \end{cases}$$

then

$$(4.9) \quad \int_A^\infty \xi^\beta \left| \frac{\partial u}{\partial \eta} \right|^2 d\xi = \int_A^\infty \int_0^1 \frac{\partial}{\partial \eta} \left\{ \gamma(\eta) \xi^{2\beta} \left| \frac{\partial u}{\partial \eta} \right|^2 \right\} d\eta d\xi \\ \leq \int_A^\infty \int_0^1 |\gamma'(\eta)| \cdot \xi^\beta \left| \frac{\partial u}{\partial \eta} \right|^2 d\eta d\xi +$$

$$\begin{aligned}
& + 2 \int_A \int_0^1 |\gamma(\eta)| \cdot \left| \xi^\beta \frac{\partial u}{\partial \eta} \right| \cdot \left| \xi^\beta \frac{\partial^2 u}{\partial \eta^2} \right| d\eta d\xi \\
& \leq c_6 \|u\|_{\mathcal{L}_{\xi, \eta}^2}^2 \leq c_7 \|u\|_{\mathbb{L}_{\xi, \eta}^2}^2
\end{aligned}$$

Thus

$$(4.10) \quad \left| \int_{\partial\Omega} \omega \right| \leq c_8 A^{-2} \|u\|_{\mathbb{L}_{\xi, \eta}^2}^2$$

Taking sufficiently large A , we obtain (4.1) from (4.6), (4.7) and (4.10.)
(Q. E. D.)

Let us finish the proof of Proposition 3. Writing

$$\begin{aligned}
(Lu, Mu) &= (L_0u, M_0u) + \{(L'u, M_0u) + (L_0u, M'u)\} + \lambda\{(L_0u, u) \\
& \quad + (u, M_0u)\} + \lambda\{(L'u, u) + (u, M'u)\} + \lambda^2 \|u\|_{L^2}^2 + (L'u, M'u),
\end{aligned}$$

we estimate each term,

$$\begin{aligned}
\operatorname{Re} (L_0u, M_0u) &\geq c_1 \|u\|_{\mathbb{L}_{\xi, \eta}^2}^2 - c_2 \|u\|_{L^2}^2 \\
|(L'u, M_0u) + (L_0u, M'u)| &\leq c_9 (\varepsilon \|u\|_{\mathbb{L}_{\xi, \eta}^2}^2 + \varepsilon^{-1} \|u\|_{L^2}^2) \\
\lambda \operatorname{Re} \{(L_0u, u) + (u, M_0u)\} &\geq \lambda c_{10} (\|u\|_{L^2}^2 - \|u\|_{\mathbb{L}_{\xi, \eta}^2}^2) \\
\lambda |(L'u, u) + (u, M'u)| &\leq \lambda c_{11} (\varepsilon \|u\|_{\mathbb{L}_{\xi, \eta}^2}^2 + \varepsilon^{-1} \|u\|_{L^2}^2). \\
|(L'u, M'u)| &\leq c_{12} \|u\|_{L^2}^2
\end{aligned}$$

Summing them up, we have

$$\begin{aligned}
\operatorname{Re} (Lu, Mu) &\geq (c_1 - \varepsilon c_9) \|u\|_{\mathbb{L}_{\xi, \eta}^2}^2 + (\lambda c_{10} - \lambda \varepsilon c_{11} - \varepsilon^{-1} c_9 - c_2 - c_{12}) \|u\|_{L^2}^2 \\
& \quad + (\lambda^2 - \varepsilon^{-1} \lambda c_{11} - \lambda c_{10}) \|u\|_{L^2}^2.
\end{aligned}$$

There exist a large λ and a small ε such that

$$\begin{aligned}
c_1 - \varepsilon c_9 &> 0 \\
\lambda c_{10} - \lambda \varepsilon c_{11} - \varepsilon^{-1} c_9 - c_2 - c_{12} &\geq 0
\end{aligned}$$

and

$$\lambda^2 - \varepsilon^{-1} \lambda c_{11} - \lambda c_{10} \geq 0.$$

Proposition 3 is hence established.

5. Outline of the proof of Theorem 1.

Using a partition of unity in the same way as in [2], we have only to examine the case where the boundary has only one edge. And we have only to examine the case where the angle is equal to 0 and the case where the angle is equal to 2π , for in other cases this question is solved in [2].

In case of the angle 2π , we can apply the method of M. Š. Birman and G. E. Skvortsov after mapping a neighborhood of the edge onto a rectangle with a slit OE (fig. 1). But the two sides of OE must be distinguished.

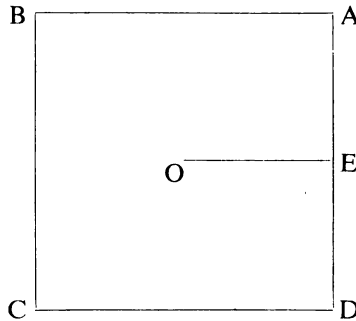


fig. 1

In turn, in case of the angle 0, this question is reduced to Theorem 2 after mapping a neighborhood of the edge onto the domain defined in Theorem 2.

The author would like to thank Professor S. Mizohata and Professor N. Shimakura for their many helpful and constructive suggestions.

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