

## ORTHOGONAL SERIES METHODS FOR BOTH QUALITATIVE AND QUANTITATIVE DATA

BY PETER HALL

*Australian National University*

We introduce and describe orthogonal series methods for estimating the density of qualitative, quantitative or mixed data. The techniques are completely nonparametric in character, and so may be used in situations where parametric models are difficult to construct. Just this situation arises in the context of mixed—both qualitative and quantitative—data, where there are few parametric models.

**1. Introduction.** An advantage of orthogonal series methods of density estimation is that they are readily extended from the univariate case to multivariate distributions, provided the dimension is not too high. Our main aim in the present paper is to show that this advantage extends from the purely continuous case, where it is by now well known, to the case of *mixed* multivariate data, in which the components have both discrete and continuous distributions. We also demonstrate that orthogonal series methods may be used to smooth unbounded, discrete data. This requires us to construct a complete sequence of orthonormal functions on an ordered, countably infinite set, and is undertaken in Section 2. We handle the case of mixed data in Section 3.

Orthogonal series methods for the estimation of a continuous density were introduced by Whittle (1958), Čencov (1962), Schwartz (1967) and Kronmal and Tarter (1968). Ott and Kronmal (1976) suggested using Walsh series to estimate the density of a multivariate binary distribution. We tackle the problem differently from Ott and Kronmal, in that we consider general orthogonal sequences which are constructed by taking the product of sequences for univariate data. This yields the example of Walsh functions on a binary set as a special case. Our technique is completely nonparametric in character, and so may be used in circumstances where parametric models are difficult to construct. Just this situation arises in the context of mixed data.

**2. Unbounded, discrete data.** We shall assume that the range of the data is the set  $\{0, 1, 2, \dots\}$ , and base our orthogonal functions on the Poisson distribution. Expand the function  $G(x, t) = (1 + t)^x e^{-\lambda t}$  as a power series in  $t$ ,  $G(x, t) = \sum_{i=0}^{\infty} \psi_i(x) t^i / i!$ . The following properties of the polynomials  $\psi_i$  may be derived:

$$\psi_i(x) = \sum_{j=0}^i \binom{i}{j} (-\lambda)^{i-j} x(x-1) \cdots (x-j+1), \quad i \geq 0;$$

$\psi_{i+1}(x) = x\psi_i(x-1) - \lambda\psi_i(x)$ ,  $i \geq 0$  (this formula is easily used to generate the functions  $\psi_i$  numerically); and if the variable  $Z$  has the Poisson distribution with parameter  $\lambda$ ,  $E\{\psi_i(Z)\psi_j(Z)\} = \delta_{ij} i! \lambda^i$ , where  $\delta_{ij}$  is the Kronecker delta. Therefore if we define

$$\phi_i(x) = \psi_i(x) (i! \lambda^i)^{-1/2} \{\lambda^x e^{-\lambda} / \Gamma(x+1)\}^{1/2}, \quad i \geq 0 \quad \text{and} \quad x \geq 0,$$

then  $\sum_{i=0}^{\infty} \phi_i(n)\phi_j(n) = \delta_{ij}$ , so that the functions  $\phi_i$  are orthonormal. The functions  $\psi_i$  are the Charlier polynomials (see Abramowitz and Stegun, 1965, page 788), and the first six are listed in Table 1.

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TABLE 1  
*Polynomials orthogonal in Poisson ( $\lambda$ ) distribution*

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$\psi_0(x) = 1;$	$\psi_1(x) = x - \lambda;$	$\psi_2(x) = x^2 - (1 + 2\lambda)x + \lambda^2;$
$\psi_3(x) = x^3 - 3(1 + \lambda)x^2 + (2 + 3\lambda + 3\lambda^2)x - \lambda^3;$		
$\psi_4(x) = x^4 - 2(3 + 2\lambda)x^3 + (11 + 12\lambda + 6\lambda^2)x^2 - 2(3 + 4\lambda + 3\lambda^2 + 2\lambda^3)x + \lambda^4;$		
$\psi_5(x) = x^5 - 5(2 + \lambda)x^4 + 5(7 + 6\lambda + 2\lambda^2)x^3$		
$-5(10 + 11\lambda + 6\lambda^2 + 2\lambda^3)x^2 + (24 + 30\lambda + 20\lambda^2 + 10\lambda^3 + 5\lambda^4)x - \lambda^5.$		

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Let  $p$  be a density on  $\{0, 1, 2, \dots\}$ . The generalized Fourier series for  $p$  is  $p(x) = \sum_{r=0}^{\infty} c_r \phi_r(x)$ , where  $c_r = \sum_{x=0}^{\infty} p(x) \phi_r(x)$ , and an unbiased estimator of  $c_r$  based on the random sample  $X_1, \dots, X_n$ , is given by  $\hat{c}_r = n^{-1} \sum_{j=1}^n \phi_r(X_j)$ . A “smoothed” estimator of  $p$  can be constructed by weighting the estimated Fourier coefficients:  $\hat{p}(x) = \sum_{r=0}^{\infty} w_r \hat{c}_r \phi_r(x)$  for weights  $w_r$ . The problem of selecting the weights is examined in a very general context in the next section.

The parameter  $\lambda$  plays a similar role to the kernel type in classical nonparametric density estimation. Note that  $\lambda$  is not a smoothing parameter, and that changing the value of  $\lambda$  has very little effect on the results. For example,  $\sum_{r=0}^{\infty} \text{var}\{\phi_r(X_1)\}$  does not depend on  $\lambda$ .

**3. General orthogonal series estimators.** We shall show how to construct orthogonal series estimators of mixed multivariate densities, based on univariate components. The univariate, continuous case is well known; see Kronmal and Tarter (1968). We have just examined the case of a univariate density on an unbounded discrete set. If the set is univariate and bounded, the orthogonal functions may be taken proportional to *orthogonal contrasts*. For example, vectors  $(\phi_i(0), \dots, \phi_i(4))$  defining functions orthogonal on  $(0, 1, \dots, 4)$ , may be taken equal to  $5^{-1/2}(1, 1, 1, 1, 1)$ ,  $2^{-1}(1, 1, 0, -1, -1)$ ,  $2^{-1}(1, -1, 0, 1, -1)$ ,  $2^{-1}(1, -1, 0, -1, 1)$  and  $(20)^{-1/2}(1, 1, -4, 1, 1)$ .

More generally, suppose data take values on the  $d$ -variate sample space  $S = S_1 \times \dots \times S_d$ . If  $\{\phi_i^{(j)}, i \geq 0\}$  is an orthonormal basis for the space of functions on  $S_j$ , and if we define

$$\phi_r(x) = \prod_{j=1}^d \phi_{r_j}^{(j)}(x_j) \text{ for each } x = (x_j) \in S \text{ and vector } r = (r_j),$$

then  $\{\phi_r\}$  is an orthonormal basis for the space of functions on  $S$ . It is a little cumbersome to write down the orthogonality relations in complete generality. For example, if  $S = \{0, 1, \dots, m\} \times \{0, 1, 2, \dots\} \times (a, b)$ , the relations take the form

$$\sum_{x_1=0}^m \sum_{x_2=0}^{\infty} \int_a^b dx_3 \phi_r(x_1, x_2, x_3) \phi_s(x_1, x_2, x_3) = \delta_{rs}.$$

Let us agree to write this as

$$(3.1) \quad \int_S \phi_r(x) \phi_s(x) dx = \delta_{rs}.$$

A density  $p$  on  $S$  admits the expansion  $p(x) = \sum_r c_r \phi_r(x)$ , where in the notation suggested by (3.1),  $c_r = \int \phi_r(x) p(x) dx$ . A “smoothed” orthogonal series estimator of  $p$  based on a random sample  $X_1, \dots, X_n$ , is given by  $\hat{p}(x) = \sum_r w_r \hat{c}_r \phi_r(x)$ , where  $\hat{c}_r = n^{-1} \sum_{j=1}^n \phi_r(X_j)$  and the  $w_r$  are weights. Generalized weighted mean “integrated” square error (MISE), with integration in the sense of (3.1), may be defined by

$$(3.2) \quad \int E \{\hat{p}(x) - p(x)\}^2 dx = n^{-1} \sum_r w_r^2 \text{var}\{\phi_r(X_1)\} + \sum_r (w_r - 1)^2 c_r^2.$$

For most choices of orthonormal sequences, the function  $\phi_0$  will be a constant, and then the condition  $\sum_x \hat{p}(x) = 1$  may be imposed by simply insisting that  $w_0 = 1$ .

If each subspace  $S_j$  is discrete, then the estimator defined by taking  $w_r = 1$  for each  $r$  is well defined, and equals the cell proportion estimator  $\hat{p}_0(x)$ . However, if one or more of the subspaces is continuous, and each  $w_r = 1$ , then the variance component of MISE diverges. Even in the purely discrete case, we could choose the weights so as to minimise MISE. The solution to this problem is given by

$$w_r = c_r^2 / [c_r^2 + n^{-1} \text{var}\{\phi_r(X_1)\}],$$

for each  $r$ . (Compare Watson and Leadbetter, 1963.) Unbiased estimators of the numerator and denominator are given by  $(n\hat{c}_r^2 - \hat{b}_r^2)/(n - 1)$  and  $\hat{c}_r^2$ , respectively, where  $\hat{b}_r^2 = n^{-1} \sum_{i=1}^n \phi_r^2(X_i)$ . Therefore we might consider the estimator

$$(3.3) \quad \hat{p}_1(x) = \sum_{r \in Q_1} (n\hat{c}_r^2 - \hat{b}_r^2) \{(n - 1)\hat{c}_r\}^{-1} \phi_r(x),$$

where  $Q_1$  denotes the set of indices  $r$  with  $n\hat{c}_r^2 \geq \hat{b}_r^2$ . We shall prove in Appendix I that if each  $S_j$  is bounded and discrete, and each  $c_r$  is nonzero, then  $n^{1/2}\{\hat{p}_1(x) - \hat{p}_0(x)\} \rightarrow 0$  in probability as  $n \rightarrow \infty$ . Therefore  $\hat{p}_1$  satisfies the same central limit theorem as  $\hat{p}_0$ . This result is an analogue of part (b) of the Theorem of Wang and van Ryzin (1981). The case where  $c_r = 0$  for some  $r$  is discussed in Appendix I.

An alternative way of selecting the weights is to take each  $w_r$  equal to 0 or 1. Arguing as in Section 4.1 of Ott and Kronmal (1976), we are led to the estimator  $\hat{p}_2(x) = \sum_{r \in Q_2} \hat{c}_r \phi_r(x)$ , where  $Q_2$  equals the set of indices  $r$  with  $(n + 1)\hat{c}_r^2 \geq 2\hat{b}_r^2$ . Again, if each  $S_j$  is bounded and discrete, and each  $c_r$  is nonzero,  $n^{1/2}\{\hat{p}_2(x) - \hat{p}_0(x)\} \rightarrow 0$  in probability. Interestingly, this estimator is almost identical to that constructed by least-squares cross-validation, which is defined by  $\hat{p}_3(x) = \sum_{r \in Q_3} \hat{c}_r \phi_r(x)$ , where  $Q_3$  equals the set of indices  $r$  with  $n\hat{c}_r^2 \geq 2(1 - 1/2n)\hat{b}_r^2$ . See Appendix II.

Suppose the sample space can be written as  $S = S^{(1)} \times S^{(2)}$ , where  $S^{(1)}$  is purely continuous and  $S^{(2)}$  purely discrete. Let  $r = (r^{(1)}, r^{(2)})$  denote the analogous decomposition of  $r$ . An estimator of the marginal density on  $S^{(1)}$  would usually be constructed using weights  $u_{r^{(1)}}$  which equal 1 if  $r^{(1)} \leq m$  (for some vector  $m$ ), 0 otherwise. The marginal density on  $S^{(2)}$  can be constructed separately with a very different weighting scheme  $v_{r^{(2)}}$  such as that given in (3.3), and the two combined into a product series estimator,

$$\hat{p}_4(x) = \sum_{r=(r^{(1)}, r^{(2)})} u_{r^{(1)}} v_{r^{(2)}} \hat{c}_r \phi_r(x).$$

Alternatively, for  $x = (x^{(1)}, x^{(2)}) \in S^{(1)} \times S^{(2)}$  we could define

$$\hat{p}_5(x) = \sum_{z \in S^{(2)}} \hat{w}(x^{(2)}, z) \hat{p}_0(x^{(1)}, z),$$

where  $\hat{p}_0$  is an unsmoothed estimator and  $\hat{w}(\cdot, \cdot)$  is a system of weights designed for smoothing the cell proportion estimator on  $S^{(2)}$ . There are many possible choices for  $\hat{w}$ . For example, if  $S^{(2)} = \{0, 1\}^k$ , one could use weights associated with a kernel estimator, as in Aitchison and Aitken (1976). An alternative would be to construct the weights for a near neighbour estimator of order  $\ell$  for any  $\ell$  in the range  $0 \leq \ell \leq k$ , using methods of Hills (1967) or Hall (1981). In this regard, Dr. H. J. Trampisch has kindly pointed out that the equations for  $w_{00}$  and  $\hat{w}_{00}$  at the top of page 574 of Hall (1981), which represent an alternative method of computing the vector  $w_{00}$  at the foot of page 573, hold only in the case  $\ell = k$ , since that condition is required for  $h = P1_{r+1}$ . In the case  $\ell < k$ ,  $w_{00}$  can be estimated using the maximum likelihood estimate of  $P$ .

#### APPENDICES

(I) *Limiting distributions of  $\hat{p}_1, \hat{p}_2$ .* If  $c_r \neq 0$  then  $(n\hat{c}_r^2 - \hat{b}_r^2)\{(n - 1)\hat{c}_r\}^{-1} = \hat{c}_r + O_p(n^{-1})$  and  $P(r \in Q_1) \rightarrow 1$ , while if  $c_r = 0$ ,  $n^{1/2}(n\hat{c}_r^2 - \hat{b}_r^2)\{(n - 1)\hat{c}_r\}^{-1} I(r \in Q_1) \rightarrow b_r(Z - Z^{-1})I(|Z| > 1)$  in distribution, where  $Z$  is  $N(0, 1)$  and  $b_r^2 = E\hat{b}_r^2$ . This results in a normal  $N\{0, p(r) - p^2(r)\}$  limit for  $n^{1/2}\{\hat{p}_1(r) - p(r)\}$  if each  $c_r$  is nonzero, and a nonnormal limit if some  $c_r$  vanishes and the corresponding  $b_r$  is nonzero. In the same way,  $\hat{p}_2$  can have a nonnormal limit if some  $c_r$  vanishes, and similar results may be proved for Ott and

Kronmal's estimators. However, these results are of a pathological nature, since insisting that  $c_r = 0$  for some  $r$  places a linear constraint on the class of probability densities, and so is unlikely from a Bayesian viewpoint.

(II) *Cross-validation.* Let  $\hat{p}(x) = \sum_r w_r \hat{c}_r \phi_r(x)$  be an estimator in which each  $w_r = 0$  or 1, let  $\hat{p}_{ni}$  denote the version of  $\hat{p}$  calculated for the  $(n - 1)$ -sample with  $X_i$  deleted, and let  $\delta_i$  be the density concentrated at  $X_i$ . Following Bowman (1982) we choose the weights to minimise  $n^{-1} \sum_i \int \{\hat{p}_{ni}(x) - \delta_i(x)\}^2 dx$ , which results in the rule: set  $w_r = 1$  iff  $n^2 \hat{c}_r^2 \geq (2n - 1) \hat{\delta}_r^2$ .

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DEPARTMENT OF STATISTICS  
THE FACULTIES  
THE AUSTRALIAN NATIONAL UNIVERSITY  
P.O. BOX 4  
CANBERRA ACT 2600  
AUSTRALIA