Abstract Functional Stochastic Evolution Equations Driven by Fractional Brownian Motion

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1. Introduction

The purpose of this paper is to study the global existence and convergence properties of mild solutions to a class of abstract functional stochastic evolution equations of the general form

\[ dx(t) = (Ax(t) + F(x)(t))\,dt + g(t)\,dB_H(t), \]

\[ 0 \leq t \leq T, \]

\[ x(0) = x_0, \]

in a real separable Hilbert space $U$. Here, $A : D(A) \subset U \rightarrow U$ is a linear (possibly unbounded) operator which generates a strongly continuous semigroup $\{S(t) : t \geq 0\}$ on $U$; $\mathcal{F} : C([0,T] ; L^2(\Omega;U)) \rightarrow L^2((0,T); L^2(\Omega;U))$ is a given mapping; $g : [0,T] \rightarrow (V;U)$ is a bounded, strongly measurable mapping (where $V$ is a real separable Hilbert space and $\mathcal{F}(V;U)$ denotes the space of Hilbert-Schmidt operators from $V$ into $U$ with norm $\|\cdot\|_{\mathcal{F}(V;U)}$ equipped with the strong topology); $\{B_H(t) : t \geq 0\}$ is a $U$-valued fBm with Hurst parameter $H \in (1/2,1)$; and $x_0 \in L^2(\Omega;U)$.

Stochastic partial functional differential equations naturally arise in the mathematical modeling of phenomena in the natural sciences (see [1–6]). It has been shown that some applications, such as communication networks and certain financial models, exhibit a self-similarity property in the sense that the processes $\{x(at) : 0 \leq t \leq T\}$ and $\{x^{H}(t) : 0 \leq t \leq T\}$ have the same law (see [4, 7]). Concrete data from a variety of applications have exhibited behavior that differs from standard Brownian motion ($H = 1/2$), and it seems that these differences enter in a nonnegligible way in the modeling of this phenomena. In fact, since $B_H(t)$ is not a semimartingale unless $H = 1/2$, the standard stochastic calculus involving the Itô integral cannot be used in the analysis of related stochastic evolution equations. There have been several papers devoted to the formulation of stochastic calculus for fBm [8–11] and differential/evolution equations driven by fBm [12–14] published in the past decade. We provide an outline of only the necessary concomitant technical details concerning the construction of the stochastic integral driven by an fBm and some of its properties in Section 2.

The present work may be regarded as a direct attempt to extend results developed in [1, 12, 15–18] to a broader class of functional stochastic equations. The equations considered in the aforementioned papers can be viewed as special cases of (1) by appropriately defining the functional $\mathcal{F}$, the correct space $U$, and the appropriate value of $H$. In particular, the existence and convergence results we present constitute...
generalizations of the theory governing standard models arising in the mathematical modeling of nonlinear diffusion processes \cite{1, 15, 18–22} and communication networks \cite{4}.

The outline of the paper is as follows. We collect some preliminary information about certain function spaces, linear semigroups, probability measures, the definition of fBm, and the stochastic integral driven by a fBm in Section 2. The main existence results in the Lipschitz and compactness cases are discussed in Section 3, while convergence results are developed in Section 4. An extension of an existence result of the case of second-order stochastic evolution equations is developed in Section 4. A discussion of three different stochastic partial differential equations in processes \cite{1, 15, 18–22} and communication networks \cite{4}.

Throughout this manuscript and write \([\Omega; U] : f \mapsto \mathbb{E} \|y\|^2_U < \infty\), where the expectation, \(E\), is defined by \(E(g) = \int_{\Omega} g(\omega) dP\). An important subspace is given by

\[
\mathcal{L}^2(\Omega; U) = \left\{ f \in \mathcal{L}^2(\Omega; U) : f \text{ is } (\mathcal{G}_0, \mathcal{B}(U))\text{-measurable} \right\},
\]

(2)

where \(\mathcal{G}_0 : 0 \leq t \leq T\) is the family of \(\sigma\)-algebras \(\mathcal{G}_0\), generated by \(\{\beta^H_j(s) : 0 \leq s \leq t\}\) and \(\mathcal{B}(U)\) is the Borel class on \(U\). The space of \(\mathcal{L}^2\)-continuous \(U\)-valued random variables \(y : [0, T] \to U\) such that

\[
\|y\|_C^2 \equiv \|y\|_C^2([0,T];\mathcal{L}^2(\Omega;U)) = \sup_{0 \leq t \leq T} E\|y(t)\|^2_U < \infty
\]

(3)

is denoted by \(C([0,T]; \mathcal{L}^2(\Omega;U))\).

The following alternative of the Leray-Schauder principle \cite{29} plays a role in Section 3.

**Theorem 1.** Let \(X\) be a Banach space, and let \(\Phi : X \to X\) be a completely continuous map. Then, either \(\Phi\) has a fixed point, or the set \(\xi(\Phi) = \{x \in X : \lambda x = \Phi x, \text{ for some } \lambda \geq 1\}\) is unbounded.

The probability measure \(\mathbb{P}\) induced by a \(U\)-valued random variable \(X : \Omega \to U\), denoted by \(\mathbb{P}_X\), is defined by \(\mathbb{P} \circ X^{-1} : \mathcal{B}(U) \to [0,1]\). A sequence \(\{\mathbb{P}_n\} \subset \mathcal{P}(U)\) is said to be weakly convergent to \(\mathbb{P}\) if \(\int_U f d\mathbb{P}_n \to \int_U f d\mathbb{P}\), for every bounded, continuous function \(f : U \to \mathbb{R}\); in such case, we write \(\mathbb{P}_n \rightharpoonup \mathbb{P}\). A family \(\{\mathbb{P}_n\}\) is tight if for each \(\varepsilon > 0\), there exists a compact set \(K_\varepsilon\) such that \(\mathbb{P}_n(K_\varepsilon) \geq 1 - \varepsilon\), for all \(n\). Kunita \cite{27} established the equivalence of tightness and relative compactness of a family of probability measures. Consequently, the Arzelà-Ascoli theorem can be used to establish tightness.

**Definition 2.** Let \(\mathbb{P} \in \mathcal{P}(U)\) and \(0 \leq t_1 < t_2 < \cdots < t_k \leq T\). Define \(\pi_{t_1, t_k} : C([0, T]; \mathcal{L}^2(\Omega; U)) \to U^k\) by \(\pi_{t_1, t_k}(X) = (X(t_1), \ldots, X(t_k))\). The probability measures induced by \(\pi_{t_1, t_k}\) are the finite dimensional joint distributions of \(\mathbb{P}\).

**Proposition 3.** If a sequence \(\{X_n : \Omega \to U\}\) of \(U\)-valued random variables converges weakly to a \(U\)-valued random variable \(X : \Omega \to U\) in the mean-square sense, then the sequence of finite dimensional joint distributions corresponding to \(\{\mathbb{P}_n\}\) converges weakly to the finite dimensional joint distribution of \(\mathbb{P}_X\).

The next theorem, in conjunction with Proposition 3, is the main tool used to prove one of the convergence results in this paper.

**Theorem 4.** Let \(\{\mathbb{P}_n\} \subset \mathcal{P}(U)\). If the sequence of finite dimensional joint distributions corresponding to \(\{\mathbb{P}_n\}\) converges weakly to the finite dimensional joint distribution of \(\mathbb{P}\) and \(\{\mathbb{P}_n\}\) is relatively compact, then \(\mathbb{P}_n \rightharpoonup \mathbb{P}\).

We next make precise the definition of a \(U\)-valued fBm and related stochastic integral used in this paper. The approach we use coincides with the one formulated and analyzed in \cite{12, 30}. Let \(\{\beta^H_j(t) : t \geq 0\}_{j=1}^\infty\) be a sequence of independent, one-dimensional fBms with Hurst parameter \(H \in (1/2, 1)\) such that, for all \(j = 1, 2, \ldots\),

(i) \(\beta^H_j(0) = 0\),

(ii) \(E[\beta^H_j(t) - \beta^H_j(s)]^2 = |t - s|^{2H} \nu_j\),

(iii) \(E[\beta^H_j'(1)]^2 = \nu_j > 0\),

(iv) \(\sum_{j=1}^\infty \nu_j < \infty\).

In such case, \(\sum_{j=1}^\infty E\|\beta^H_j(t)e_j\|^2_U = t^{2H} \sum_{j=1}^\infty \nu_j < \infty\), so that the following definition is meaningful.

**Definition 5.** For every \(t \geq 0\), \(\beta^H(t) = \sum_{j=1}^\infty \beta^H_j(t)e_j\) is a \(U\)-valued fBm, where the convergence is understood to be in the mean-square sense.

It has been shown in \cite{12, 30} that the covariance operator of \(\{\beta^H_j(t) : t \geq 0\}\) is a positive nuclear operator \(Q\) such that

\[
\text{tr}Q(t, s) = \frac{1}{2} \sum_{j=1}^\infty \nu_j \left[ t^{2H} + s^{2H} - |t - s|^{2H} \right].
\]

(4)

Next, we outline the discussion leading to the definition of the stochastic integral associated with \(\beta^H(t) : t \geq 0\)
for bounded, strongly measurable functions \( g : [0, T] \rightarrow \mathcal{V}(V; U) \). To begin, assume that such a function \( g \) is simple, meaning that there exists \( \{g_i : i = 1, \ldots, n \} \subseteq \mathcal{V}(V; U) \) such that
\[
g(t) = g_i, \quad \forall t_{i-1} \leq t < t_i,
\]
where \( 0 = t_0 < t_1 < \cdots < t_{n-1} < t_n = T \) and \( \max_{1 \leq i \leq n} \|g_i\|_{\mathcal{V}(V; U)} = K \).

**Definition 6.** The \( U \)-valued stochastic integral \( \int_0^T g(t) d\beta^H(t) \) is defined by
\[
\int_0^T g(t) d\beta^H(t) = \sum_{j=1}^\infty \left( \int_0^T g(t) d\beta_j^H(t) \right) e_j,
\]
where \( \{e_j : j \in \mathbb{N} \} \) is a sequence of simple functions converging uniformly on \( [0, T] \) to \( g \). This integral is well defined if \( \sum_{j=1}^\infty \|g_j\|_{\mathcal{V}(V; U)} < \infty \). To begin, assume that such a function \( g \) is simple, meaning that there exists \( \{g_i : i = 1, \ldots, n \} \subseteq \mathcal{V}(V; U) \) such that
\[
g(t) = g_i, \quad \forall t_{i-1} \leq t < t_i,
\]
where \( 0 = t_0 < t_1 < \cdots < t_{n-1} < t_n = T \) and \( \max_{1 \leq i \leq n} \|g_i\|_{\mathcal{V}(V; U)} = K \).

**Definition 7.** A stochastic process \( x \in C([0, T]; \mathcal{V}(\Omega; U)) \) is a mild solution of (1) if
\[
x(t) = S(t) x_0 + \int_0^t S(t-s) \mathcal{F}(x)(s) ds + \int_0^t S(t-s) g(s) d\beta^H(s),
\]
\( \forall 0 \leq t \leq T \), a.s. \([P]\).

For our first result, we impose the following conditions on (1):

(H1) \( A : D(A) \subset U \rightarrow U \) is the infinitesimal generator of a strongly continuous semigroup \( \{S(t) : t \geq 0 \} \) on \( U \) such that \( \|S(t)\|_{\mathcal{L}(U; U)} \leq M \exp(\alpha t) \), for all \( 0 \leq t \leq T \), for some \( M \geq 1 \) and \( \alpha > 0 \);

(H2) \( \mathcal{F} : C([0, T]; \mathcal{V}(\Omega; U)) \rightarrow \mathcal{L}^2([0, T]; \mathcal{V}(\Omega; U)) \) is such that there exists a positive constant \( M_{\mathcal{F}} \) for which
\[
\|\mathcal{F}(x) - \mathcal{F}(y)\|_{\mathcal{L}^2} \leq M_{\mathcal{F}} \|x - y\|_C,
\]
for all \( x, y \in C([0, T]; \mathcal{V}(\Omega; U)) \);

(H3) \( g : [0, T] \rightarrow \mathcal{V}(V; U) \) is a bounded, strongly measurable mapping;

(H4) \( \{\beta^H(t) : t \geq 0 \} \) is a \( U \)-valued fBm;

(H5) \( x_0 \in \mathcal{L}^2(\Omega; U) \).

(Henceforth, we write \( M_S = \max_{0 \leq t \leq T} \|S(t)\|_{\mathcal{B}(U; U)} \), which can be shown to be finite by using (H1) and the Uniform Boundedness Principle.)

The following technical properties involving the stochastic integral \( \int_0^T S(t-s) g(s) d\beta^H(s) \), under assumptions (H1), (H3), and (H4), are used in the proofs of the main results in this paper.

**Lemma 8.** Assume (H1), (H3), and (H4). Then, for all \( 0 \leq t \leq T \),

(i) \( E\|\int_0^t S(t-s) g(s) d\beta^H(s)\|_U^2 \leq C_t \sum_{j=1}^\infty v_j \),

(ii) \( \lim_{h \rightarrow 0} E\|\int_0^{t+h} [S(t+h-s) - S(t-s)] g(s) d\beta^H(s)\|_U^2 = 0 \).

Here, \( C_t \) is a positive constant depending on \( t \), \( \{S(t) : 0 \leq t \leq T \} \), and \( \{v_j : j \in \mathbb{N} \} \) is defined as in the discussion leading to Definition 5.

**Proof.** Property (i) can be established as in Lemma 6 in [12]. To verify property (ii), let \( 0 \leq t \leq T \) and observe that
\[
E\|\int_0^t S(t+h-s) - S(t-s)\ g(s) d\beta^H(s)\|_U^2
= E\sum_{j=1}^\infty \int_0^t S(t+h-s) - S(t-s)\ g(s) e_j d\beta_j^H(s)\|_U^2
\leq 2E\sum_{j=1}^\infty \int_0^t S(t+h-s) - S(t-s)\ g(s) e_j d\beta_j^H(s)\|_U^2
+ 2E\sum_{j=m+1}^\infty \int_0^t S(t+h-s) - S(t-s)\ g(s) e_j d\beta_j^H(s)\|_U^2.
\]

The strong continuity of \( S(\cdot) \), together with (H3), guarantees that the first term on the right side of (10) goes to zero as \( h \rightarrow 0 \). To argue the second term goes to zero, we first assume that \( g \) is a simple function as defined in (5). Arguing as in [12] yields the estimate
\[
E\|\int_0^t S(t+h-s) - S(t-s)\ g(s) e_j d\beta_j^H(s)\|_U^2 \leq C_t t^{2h} v_j,
\]
(11)
where $C_j$ is defined as in part (i) of this lemma. Using (11) in the second term on the right side of (10) yields
\[
E \sum_{j=m+1}^{\infty} \int_0^t \left[ S(t + h - s) - S(t - s) \right] g(s) e_j d\beta^H_j(s) \right]^2 U_i \leq \sum_{j=m+1}^{\infty} C_j t^{2h} \nu_j. \tag{12}
\]
The convergence of $\sum_{j=1}^\infty \nu_j$ ensures that the right side of (12) goes to zero as $m \to \infty$. As such, property (ii) holds for a simple function $g$. It is not difficult to extend the argument to general bounded, strongly measurable functions $g$. This completes the proof. \qed

Consider the solution map $\Phi : C([0, T]; \mathcal{L}^2(\Omega; U)) \to C([0, T]; \mathcal{L}^2(\Omega; U))$ defined by
\[
\Phi(x)(t) = S(t)x_0 + \int_0^t S(t-s) \mathcal{F}(x)(s) ds + \int_0^t S(t-s) g(s) d\beta^H(s), \quad 0 \leq t \leq T. \tag{13}
\]
The first integral on the right side of (13) is taken in the Bochner sense, while the second is defined in Section 2. The operator $\Phi$ satisfies the following properties.

**Lemma 9.** Assume that (H1)--(H5) hold. Then, $\Phi$ is a well-defined, continuous map.

**Proof.** Using the discussion in Section 2 and the properties of $x$, one can see that for any $x \in C([0, T]; \mathcal{L}^2(\Omega; U))$, $\Phi(x)(t)$ is a well-defined stochastic process, for each $0 \leq t \leq T$. In order to verify the continuity of $\Phi$ on $[0, T]$, let $z \in C([0, T]; \mathcal{L}^2(\Omega; U))$ and consider $0 \leq t^* \leq T$ and $|h|$ sufficiently small. Observe that
\[
E \| \Phi(z)(t^* + h) - \Phi(z)(t^*) \|^2_U \leq 3 \left[ E \| S(t^* + h - s) - S(t^* - s) \|_U \right]^2 \\
+ E \left[ \int_0^{t^*} S(t^* + h - s) \mathcal{F}(z)(s) ds \right]^2 \\
+ E \left[ \int_0^{t^*} S(t^* - s) \mathcal{F}(z)(s) ds \right]^2 \\
+ E \left[ \int_0^{t^*} S(t^* + h - s) g(s) d\beta^H(s) \right]^2 \\
+ E \left[ \int_0^{t^*} S(t^* - s) g(s) d\beta^H(s) \right]^2 \\
= 3 \sum_{i=1}^3 \| I_i(t^* + h) - I_i(t^*) \|. \tag{14}
\]
The semigroup property enables us to write
\[
\| I_1(t^* + h) - I_1(t^*) \| = E \| (S(t^* + h) - S(t^*)) x_0 \|_U^2 \\
= E \| (S(h) - 1) S(t^*) x_0 \|_U^2. \tag{15}
\]
So, the strong continuity of $S(\cdot)$ implies that the right side of (15) goes to 0 as $|h| \to 0$. Next, using the Hölder inequality with (H2) yields
\[
E \int_0^{t^*} \left[ S(t^* + h - s) \mathcal{F}(z)(s) ds \right]^2_U \\
\leq 2M_2^2 M_2 h^2 \left[ 1 + \|z\|_U^2 + \|\mathcal{F}(0)\|_U^2 \right] \\
\]
which clearly goes to 0 as $|h| \to 0$. Also, the strong continuity of $S(\cdot)$ with (H2) enables us to conclude, with the help of the dominated convergence theorem, that
\[
E \int_0^{t^*} \left[ S(t^* + h - s) - S(t^* - s) \right] \mathcal{F}(z)(s) ds \right]^2_U \to 0 \tag{17}
\]
as $|h| \to 0$. Consequently, since $\| I_2(t^* + h) - I_2(t^*) \|$ is dominated by the expressions in (16) and (17), both of which go to 0 as $|h| \to 0$, it follows that $\| I_2(t^* + h) - I_2(t^*) \| \to 0$ as $|h| \to 0$.

It remains to show that $\| I_3(t^* + h) - I_3(t^*) \| \to 0$ as $|h| \to 0$. Observe that
\[
\| I_3(t^* + h) - I_3(t^*) \| \\
= E \int_0^{t^*} \left[ S(t^* + h - s) g(s) d\beta^H(s) \right]^2_U \\
- \int_0^{t^*} S(t^* - s) g(s) d\beta^H(s) \right|^2_U \\
= E \int_0^{t^*} S(t^* + h - s) g(s) d\beta^H(s) \right|^2_U \\
+ \int_0^{t^*} S(t^* - s) g(s) d\beta^H(s) \right|^2_U \\
\leq 2E \sum_{j=1}^{\infty} \left[ \int_0^{t^*} S(t^* + h - s) g(s) e_j d\beta^H_j(s) \right]^2_U \\
+ 2E \sum_{j=1}^{\infty} \left[ \int_0^{t^*} S(t^* + h - s) g(s) e_j d\beta^H_j(s) \right]^2_U \\
\]
and that
\[
E \int_0^{t^*} \left[ S(t^* + h - s) g(s) e_j d\beta^H_j(s) \right]^2_U \\
= E \sum_{j=1}^{\infty} \left[ \int_0^{h} S(u) g(t^* + h - u) e_j d\beta^H_j(t^* + h - u) \right]^2_U. \tag{18}
\]
Using the property \(E(\beta^H(s) - \beta^H(t))^2 = |t-s|^{2H}y_j\) with \(s = t^* + h\) and \(t = t^*\) enables us to conclude that the right side of (19) goes to 0 as \(|h| \to 0\). The second term on the right side of (18) goes to 0 as \(|h| \to 0\) by Lemma 8(ii). Thus, \(\|I_s(t^* + h) - I_s(t^*)\| \to 0\) as \(|h| \to 0\) when \(s\) is a simple function. Since the set of all such simple functions is dense in \(Ω\), a standard density argument can be used to extend this conclusion to a general bounded, measurable function \(g\). This establishes the continuity of \(Φ\).

Finally, we assert that \(Φ(0, T]; C(Ω; U)) \subset C([0, T]; L^2(Ω; U))\). Successive applications of Hölder’s inequality yields

\[
\left[ E\int_0^T S(t - s) \mathcal{F}(z)(s) ds \right]^2 \leq T^{1/2} M_s \left[ \int_0^T \|\mathcal{F}(z)(s)\|_{L^2(Ω; U)}^2 ds \right]^{1/2}
\]

Subsequently, an application of (H2), together with Minkowski’s inequality, enables us to continue the string of inequalities in (20) to conclude that

\[
\left[ E\int_0^T S(t - s) \mathcal{F}(z)(s) ds \right]^2 \leq T^{1/2} M_s \left[ M_{\mathcal{F}} \|z\|_C + \|Φ(0)\|_{L^2} \right].
\]

Taking the supremum over \([0, T]\) in (21) then implies that

\[
\left[ \int_0^T S(t - s) \mathcal{F}(z)(s) ds \right] \subset C([0, T]; L^2(Ω; U)),\ 
\] for any \(z \in C([0, T]; L^2(Ω; U))\). The other estimates can be established as above, and when used in conjunction with Lemma 8, one can readily verify that \(\sup_{t \in [0, T]} \|Φ(z)(t)\|_{L^2(U)} < \infty\) for any \(z \in C([0, T]; U)\). Thus, we conclude that \(Φ\) is well defined, and the proof of Lemma 9 is complete.

Our first existence result is as follows.

**Theorem 10.** Assume that (H1)–(H5) hold. Then, (1) has a unique mild solution on \([0, T]\).

**Proof.** We know that \(Φ\) is well defined and continuous from Lemma 9. Let \(δ = 1/(M_s^2 M_{\mathcal{F}}^2 + 1)\). We prove that \(Φ\) has a unique fixed point in \(C([0, δ]; L^2(Ω; U))\). To this end, let \(x, y \in C([0, δ]; L^2(Ω; U))\). Observe that (13) implies that

\[
(Φx)(t) - (Φy)(t) = \int_0^t S(t - s) \left[ \mathcal{F}(x)(s) - \mathcal{F}(y)(s) \right] ds.
\]

Squaring both sides and taking the expectation in (22) yields, with the help of Young’s inequality,

\[
E\|Φx(t) - (Φy)(t)\|_{L^2(U)}^2 
\leq E\left[ \int_0^t S(t - s) \left[ \mathcal{F}(x)(s) - \mathcal{F}(y)(s) \right] ds \right]^2
\]

Taking the supremum over \([0, δ]\) in (23) and applying reasoning similar to that which led to (16) yield

\[
\|Φx - Φy\|_{C([0, δ]; L^2(Ω; U))} 
\leq \int_0^T S(t - s) \left[ \mathcal{F}(x)(s) - \mathcal{F}(y)(s) \right] ds \leq M_{S,M_{\mathcal{F}}} \delta^{1/2} x - y \in C([0, δ]; L^2(Ω; U))
\]

where the last inequality in (24) follows from the choice of \(δ\). Hence, \(Φ\) is a strict contraction on \([0, δ]\) and so has a unique fixed point which coincides with a mild solution of (1) on \([0, δ]\). Performing this same argument on \([δ, \sqrt{δ}]\), \([\sqrt{δ}, \sqrt[5]{δ}]\), and so on enables us to construct in finitely many steps a unique piecewise-defined function in \(C([0, T]; L^2(Ω; U))\) which is a unique mild solution of (1) on the original interval \([0, T]\). This completes the proof.

Next, we consider the following initial-value problem:

\[
dx(t) = \left( A x(t) + \int_0^T B(t, s) f_1(s, x(s)) ds + f_2(t, x(t)) \right) dt
\]

\[
x(0) = x_0,
\]

where \(\{B(t, s) : 0 ≤ s ≤ t ≤ T\} ∈ \mathcal{B}(U)\) and \(f_i : [0, T] × U \to U \ (i = 1, 2)\) satisfy the following conditions:

(H6) \(\{B(t, s) : U \to U \ | \ 0 ≤ t ≤ s ≤ T\}\) is a collection of bounded linear operators for which there exists a positive constant \(M_B\) such that

\[
\|B(t, s)\|_{\mathcal{B}(U; U)} ≤ M_B, \quad \forall 0 ≤ t ≤ s ≤ T.
\]

(H7) \(f_i : [0, T] × U \to U \ (i = 1, 2)\) is such that there exists a positive constant \(M_{f_i}\) for which

\[
\|f_i(t, x) - f_i(t, y)\|_U ≤ M_{f_i} \|x - y\|_U.
\]

**Corollary 11.** If (H1), (H4), (H5), (H6a), and (H6) hold, then (22) has a unique mild solution on \([0, T]\).

**Proof.** Define \(\mathcal{F} : C([0, T]; L^2(Ω; U)) \to L^2((0, T); L^2(Ω; U))\) by

\[
\mathcal{F}(x)(t) = \int_0^T B(t, s) f_1(s, x(s)) ds + f_2(t, x(t)),
\]

for \(0 ≤ t ≤ T\).
Standard computations involving properties of expectation and Hölder’s inequality imply, with the help of (H6) and (H7), that, for all \( x, y \in C([0,T]; L^2(\Omega; U)) \),

\[
\| F(x) - F(y) \|_{L^2_x}^2 \\
\leq 2 \int_0^T \left[ TM^2 h \int_0^s E \| f_1(s, x(s)) - f_1(s, y(s)) \|_{L^2}^2 ds + E \| f_2(s, x(s)) - f_2(s, y(s)) \|_{L^2}^2 ds \right] ds
\]

\[
\leq 2T \left[ TM^2 M^2 f_1 + M^2 f_2 \right] \| x - y \|_C.
\]

(29)

Thus, if we let \( M_F = 2T [TM^2 M^2 f_1 + M^2 f_2] \) in (H2), we can conclude from Theorem 10 that (25) has a unique mild solution on \([0,T]\). \( \square \)

We now develop existence results for (1) in which the Lipschitz condition on \( F \) is replaced by the combination of continuity and a sublinear growth condition. This is done at the expense of a compactness restriction on the semigroup. Precisely, we use the following assumptions:

(H8) A generates a compact \( C_0 \)-semigroup \( S(t) : t \geq 0 \) on \( U \);

(H9) \( F : C([0,T]; L^2(\Omega; U)) \rightarrow L^2((0,T); L^2(\Omega; U)) \) is a continuous map such that there exists positive constants \( c_1 \) and \( c_2 \) such that

\[
\| F(x) \|_{L^2_x} \leq c_1 \| x \|_C + c_2,
\]

for all \( x \in C([0,T]; L^2(\Omega; U)) \).

We begin by establishing certain compactness properties of the mapping \( \Phi : C([0,T]; L^2(\Omega; U)) \rightarrow C([0,T]; L^2(\Omega; U)) \) defined by

\[
\Phi(\mu)(t) = \int_0^t S(t-s) \mu(s) ds, \quad 0 \leq t \leq T.
\]

(31)

The well definedness of this mapping is essentially a stochastic analog of Lemma 3.1 in [31] (where \( S(t) \) plays the role of the resolvent operator) and its proof follows similarly by making the natural modifications.

Lemma 12. Assume that \( \{S(t) : 0 \leq t \leq T\} \) is a compact semigroup on \( U \). Then, \( \Phi \) is a compact map from \( L^2((0,T); L^2(\Omega; U)) \) into \( C([0,T]; L^2(\Omega; U)) \).

Theorem 13. Assume that (H3), (H4), (H5), (H8), and (H9) hold. Then, (1) has at least one mild solution on \([0,T]\).

Proof. We use Schaefer’s theorem to prove that \( \Phi \) (as defined in (13)) has a fixed point. The well definedness of \( \Phi \) under (H3), (H4), (H5), (H8), and (H9) can be established using reasoning similar to that employed in the proof of Theorem 10. To verify the continuity of \( \Phi \), let \( \{\mu_n\}_{n=1}^{\infty} \) be a sequence in \( C([0,T]; L^2(\Omega; U)) \) such that \( \mu_n \rightarrow \mu \) as \( n \rightarrow \infty \). Standard computations yield

\[
\| \Phi(\mu_n) - \Phi(\mu) \|_C
\]

\[
\leq M_S \left( E \left( \int_0^T \| F(\mu_n)(s) - F(\mu)(s) \|_{L^2} ds \right)^2 \right)^{1/2}
\]

\[
\leq M_S T^{1/2} \| F(\mu_n) - F(\mu) \|_{L^2_x}.
\]

(32)

The continuity of \( F \) ensures that the right side of (32) goes to 0 as \( n \rightarrow \infty \), thereby verifying the continuity of \( \Phi \).

Next, let \( \delta = 1/(3M_S^2c_1^2+1) \). We will show that the set \( \xi(\Phi) \), as defined in Theorem 1 with \( C([0,\delta]; L^2(\Omega; U)) \) in place of \( X \), is bounded. Let \( v \in \xi(\Phi) \) and observe that, arguing as in (20), applications of the Hölder and Young inequalities (with (H8)) yield

\[
\delta^{1/2} \left( E \int_0^\delta \| F(\mu)(s) \|_{L^2} ds \right)^{1/2} \leq \delta^{1/2} \left( c_1 \| \mu \|_C + c_2 \right).
\]

(33)

Also, from Lemma 8 we can infer that

\[
E \left( \int_0^T S(t-s) g(s) ds \beta^H(s) \right)^2 \leq C_T \sum_{j=1}^{\infty} v_j.
\]

(34)

Thus, we conclude that, for all \( \mu \in \xi(\Phi) \) and \( 0 \leq t \leq \delta \),

\[
\lambda \| \mu \|_C \leq \sqrt{3} \left[ M_S \| x_0 \|_{L^2(\Omega; U)} + M_S \delta^{1/2} \left( c_1 \| \mu \|_C + c_2 \right) + C_T \sum_{j=1}^{\infty} v_j \right].
\]

(35)

Taking into account that \( \lambda \geq 1 \) and the choice of \( \delta \), we conclude from (33) that \( \| \mu \|_C \leq \eta \), where \( \eta \) is a constant independent of \( \mu \) and \( \lambda \). So, \( \xi(\Phi) \) is bounded.

In order to apply Schaefer’s theorem, it remains to show that \( \Phi \) is compact. To this end, let \( r > 0 \) and define \( K_r = \{ \mu \in C([0,\delta]; L^2(\Omega; U)) : \| \mu \|_C \leq r \} \). Using the notation of (13) and (31), we have

\[
\Phi(\mu) = S(\cdot)x_0 + \Phi_1(\mu)(\cdot) + \int_0^\delta S(\cdot-s) g(s) d\beta^H(s), \quad \mu \in C([0,\delta]; L^2(\Omega; U)).
\]

(36)

We assert that \( \Phi(K_r) \) is precompact in \( C([0,\delta]; L^2(\Omega; U)) \). Indeed, the fact that \( \{\Phi(\mu) : \mu \in K_r\} \) is a bounded subset of \( L^2((0,\delta); L^2(\Omega; U)) \) (cf. (H9)), it follows from Lemma 12 that the set \( \{\Phi(\mu) : \mu \in K_r\} \) is precompact in \( C([0,\delta]; L^2(\Omega; U)) \). Since the set

\[
\left\{ S(\cdot)x_0 + \int_0^\delta S(\cdot-s) g(s) d\beta^H(s) : \mu \in K_r \right\}
\]

(37)
is trivially precompact, we conclude that \( \Phi(K_r) \) is precompact in \( C([0, \delta]; \mathcal{L}^2(\Omega; U)) \). So, Schaefer’s theorem implies that \( \Phi \) has a fixed point \( x \in C([0, \delta]; \mathcal{L}^2(\Omega; U)) \) which is a mild solution to (1) on \([0, \delta]\). Performing this same argument on \([\delta, 2\delta]\), \([2\delta, 3\delta]\), and so on enables us to construct in finitely many steps a piecewise-defined function in \( C([0, T]; \mathcal{L}^2(\Omega; U)) \), that is, a mild solution of (1) on the original interval \([0, T]\). This completes the proof. \( \square \)

Next, we state a corollary regarding (25) under the following assumptions on \( f_i \):

\[(H_{10}) \quad f_i : [0, T] \times U \to U \quad (i = 1, 2) \]

is well defined and continuous. Routine calculations is trivially precompact, we conclude that \( \Phi \) has a fixed point \( x \in C([0, \delta]; \mathcal{L}^2(\Omega; U)) \) which is a mild solution to (1) on \([0, \delta]\). Performing this same argument on \([\delta, 2\delta]\), \([2\delta, 3\delta]\), and so on enables us to construct in finitely many steps a piecewise-defined function in \( C([0, T]; \mathcal{L}^2(\Omega; U)) \), that is, a mild solution of (1) on the original interval \([0, T]\). This completes the proof. \( \square \)

**Corollary 14.** If \((H_3), (H_4), (H_5), (H_8), \) and \((H_{10}) \) hold, then (25) has at least one mild solution on \([0, T]\).

**Proof.** An argument similar to the one used in [32, Chapter 26, pg. 561] shows that \((H_{10}) \) guarantees the mapping \( \Phi : C([0, T]; \mathcal{L}^2(\Omega; U)) \to \mathcal{L}^2([0, T]; \mathcal{L}^2(\Omega; U)) \) defined in (28) is well defined and continuous. Routine calculations show that \( \Phi \) satisfies (H9) with \( c_1 = 2T(a_{1,1}M_3T^{3/2} + a_{2,1}) \) and \( c_2 = 2T(a_{1,2}M_3T^{3/2} + a_{2,2}) \). Consequently, (25) has at least one mild solution by Theorem 13. \( \square \)

We can formulate a stronger version of Corollary 14 by replacing assumption \((H_{10})\) by the following:

\[(H_{11}) \quad f_i : [0, T] \times U \to U \quad (i = 1, 2) \]

(i) for each \( k \in \mathbb{N} \), there exists \( g_{i,k} \in \mathcal{L}^1(\Omega, \mathcal{F}) \) such that for almost all \( t \in (0, T) \),

\[ \sup_{1 \leq i \leq k} E \| f_i(t, x) \|_U^2 \leq g_{i,k}(t) \];

(ii) \( \lim_{k \to \infty} k^{-2} \int_0^T g_{i,k}(s) ds = a_i < \infty \).

**Proposition 15.** Assume that \((H_3), (H_4), (H_5), \) (H8), and \((H_{11}) \) hold. Then, (25) has at least one mild solution on \([0, T]\).

**Proof.** We use Schauder’s fixed-point theorem to argue that \( \Phi \) (as defined in (13) with \( \mathcal{F} \) given by (28)) has a fixed point. The continuity and compactness follow by making slight changes to the proof of Theorem 13. Choose \( \delta \) such that

\[ 4M_S \left( \delta^{1/2} a_2^{1/2} + M_B \delta a_1^{1/2} \right) < 1. \]
and subsequently,

\[
\lim_{k \to \infty} k^{-1} \| \Phi(u_k) \|_C \\
\leq 2M_{S} \lim_{k \to \infty} \left[ k^{-1} \| x_0 \|_{\mathcal{L}^{2}(\Omega; U)} + \delta^{1/2} \left( k^{-2} \int_{0}^{\delta} g_{2,k}(s) ds \right)^{1/2} + M_{\delta} \delta^{1/2} \left( k^{-2} \int_{0}^{\delta} g_{1,k}(s) ds \right)^{1/2} + 2k^{-1} E \int_{0}^{\delta} S(t - s) g(s) d\beta^{H}(s) \right] \\
\leq 2M_{S} \delta^{1/2} (\alpha_{2}^{1/2} + M_{\delta} \delta^{1/2}) < 1,
\]

contradicting (41). Consequently, there is an \( n_{0} \in \mathbb{N} \) such that \( \Phi(B_{n_{0}}) \subset B_{n_{0}} \). Thus, Schauder’s fixed point theorem guarantees the existence of \( x \in B_{n_{0}} \) such that \( \Phi(x) = x \), which is a mild solution of (25) on \([0, \delta)\). Performing this same argument on \([\delta, 2\delta)\), \([2\delta, 3\delta)\), and so on enables us to construct in finitely many steps a piecewise-defined function in \( C([0, T]; \mathcal{L}^{2}(\Omega; U)) \), that is, a mild solution of (1) on the original interval \([0, T]\). This completes the proof.

\[\boxdot\]

4. Convergence and Approximation Results

Throughout this section we assume that \( A, \mathcal{F}, \) and \( g \) satisfy (H1)--(H5).

For each \( n \in \mathbb{N} \), consider a linear operator \( A_{n} : D(A_{n}) = D(A) \to U \) and mappings \( \mathcal{F}_{n} : C([0, T]; \mathcal{L}^{2}(\Omega; U)) \to \mathcal{L}^{2}(\Omega; U) \), and \( g_{n} : [0, T] \to \mathcal{S}(V; U) \) satisfying the following conditions:

(H12) \( A_{n} \) generates a \( C_{0} \)-semigroup \( \{ S_{n}(t) : t \geq 0 \} \) such that \( \| S_{n}(t) \|_{\mathcal{S}(U)} \leq M_{S} e^{\alpha t} \), for some \( \alpha > 0 \) (independent of \( n \)), for each \( n \in \mathbb{N} \), and \( \| A_{n} x - Ax \|_{U} \to 0 \) as \( n \to \infty \), for each \( x \in D(A) \);

(H13) (i) \( \| \mathcal{F}_{n}(x) - \mathcal{F}_{n}(y) \|_{\mathcal{L}^{2}} \leq M_{F} \| x - y \|_{C} \), for all \( x, y \in C([0, T]; \mathcal{L}^{2}(\Omega; U)) \);

(ii) \( \| \mathcal{F}_{n}(x) - \mathcal{F}(x) \|_{\mathcal{L}^{2}} \to 0 \) as \( n \to \infty \), for all \( x \in C([0, T]; \mathcal{L}^{2}(\Omega; U)) \);

(H14) \( g_{n} : [0, T] \to \mathcal{S}(V; U) \) is a bounded, strongly measurable mapping and \( \| g_{n}(t) - g(t) \|_{\mathcal{S}(U)} \to 0 \) as \( n \to \infty \), for all \( 0 \leq t \leq T \).

(Here, the constant \( M_{F} \) is the same one appearing in (H2) and so is independent of \( n \).)

Assume that (H1)--(H5) hold. Then, by Theorem 10, (1) has a unique mild solution \( x \in C([0, T]; \mathcal{L}^{2}(\Omega; U)) \). By virtue of (H4), (H12)--(H14), Theorem 10 implies that, for each \( n \in \mathbb{N} \), the initial-value problem

\[dx_{n}(t) = (A_{n} x_{n}(t) + \mathcal{F}_{n}(x_{n}(t)))(t) dt + g_{n}(t) d\beta^{H}(t), \]

\[0 \leq t \leq T,
\]

has a unique mild solution \( x_{n} \in C([0, T]; \mathcal{L}^{2}(\Omega; U)) \).

Consider the following initial-value problem:

\[dy_{n}(t) = (A_{n} y_{n}(t) + \mathcal{F}_{n}(x(t)))(t) dt + g_{n}(t) d\beta^{H}(t), \]

\[0 \leq t \leq T,
\]

\[y_{n}(0) = x_{0}\]

Since \( x_{0} \) is a fixed element of \( \mathcal{L}^{2}(\Omega; U) \), a standard argument guarantees the existence of a unique mild solution \( y_{n} \) of (47).

We need the following lemma.

\[\textbf{Lemma 16}. \text{If (H12)--(H14) hold, then } \| y_{n} - x \|_{C} \to 0 \text{ as } n \to \infty.
\]

\[\text{Proof}. \text{Using (H12) in conjunction with Theorem 4.1 in [24, pg. 46], we infer that } S_{n}(t) z \to S(t)z \text{ as } n \to \infty, \text{ for all } z \in U, \text{ uniformly in } t \in [0, T]. \text{ Observe that}
\]

\[E \| y_{n}(t) - x(t) \|_{U}^{2} \leq 4E \| S_{n}(t) - S(t) \|_{U}^{2}
\]

\[+ 4E \int_{0}^{t} \| S_{n}(t - s) (\mathcal{F}_{n}(x(s)) - \mathcal{F}(x(s))) \|_{U}^{2} ds
\]

\[+ 4E \int_{0}^{t} \| (S_{n}(t - s) - S(t-s)) \mathcal{F}(x(s)) \|_{U}^{2} ds
\]

\[+ 4E \int_{0}^{t} \| (S_{n}(t-s) - S(t-s)) (g_{n}(s) - g(s)) + (S_{n}(t-s) - S(t-s)) g(s) d\beta^{H}(s) \|_{U}^{2}.
\]

A standard argument invoking (H12) and (H13), involving the Trotter-Kato Theorem [28], can be used to conclude that each of the first three terms on the right side of (48) goes to 0 as \( n \to \infty \). As for the fourth term, observe that

\[E \left( \int_{0}^{t} [S_{n}(t - s) (g_{n}(s) - g(s)) + (S_{n}(t-s) - S(t-s)) g(s) d\beta^{H}(s) \right)_{U}^{2}
\]

\[\leq E \int_{0}^{t} \| S_{n}(t-s) (g_{n}(s) - g(s)) d\beta^{H}(s) \|_{U}^{2}
\]

\[+ E \int_{0}^{t} \| (S_{n}(t-s) - S(t-s)) g(s) d\beta^{H}(s) \|_{U}^{2}.
\]
The uniform boundedness of \( \{S_n(t) : 0 \leq t \leq T, n \in \mathbb{N}\} \) (cf. (H12)) with (H14) guarantees that the supremum (over \([0, T]\)) of the first term on the right side of (49) goes to 0 as \( n \to \infty \). An argument in the spirit of the one used to verify Lemma 8 (ii) can be used to show the supremum (over \([0, T]\)) of the second term in (49) and also goes to 0 as \( n \to \infty \), as needed. This completes the proof. \(\square\)

The following is the first of our two main convergence results.

**Theorem 17.** If (H1)–(H5) and (H12)–(H14) hold and
\[4M_\delta T \mu_\varepsilon < 1,\]
where \( M_\delta = M_\delta e^{2r T} \), then \( \|x_n - x\|_C \to 0 \) as \( n \to \infty \).

**Proof.** Let \( y_n \) be the mild solution of (47). Observe that
\[
\begin{align*}
\|x_n(t) - x(t)\|_{L^2(\Omega; U)}^2 &\leq 2 \left[ \|x_n(t) - y_n(t)\|_U^2 + \|y_n(t) - x(t)\|_U^2 \right] \\
&\leq 2 \left\{ \left[ \int_0^t \|S_n(t-s) (\mathcal{F}_n(x_n)(s) - \mathcal{F}_n(x)(s))\|_U^2 \, ds \right]^{1/2} \\
&\quad + \|y_n(t) - x(t)\|_U^2 \right\}.
\end{align*}
\]
Taking the expectation, followed by taking square roots in (50), yields the following estimate after some computation
\[
\begin{align*}
\|x_n(t) - x(t)\|_{L^2(\Omega; U)} &\leq 2 \left[ \int_0^T \mathbb{E} \left| \mathcal{F}_n (x_n)(s) - \mathcal{F}_n(x)(s) \right|_U^2 \, ds \right]^{1/2} \\
&\quad + \|y_n(t) - x(t)\|_{L^2(\Omega; U)} \right\}.
\end{align*}
\]
Observe that (H12) yields, with the help of Hölder’s inequality,
\[
\begin{align*}
\left( \int_0^T \mathbb{E} \|S_n(t-s) (\mathcal{F}_n(x_n)(s) - \mathcal{F}_n(x)(s))\|_U^2 \, ds \right)^{1/2} &\leq T^{1/2} M_\delta \|\mathcal{F}_n (x_n) - \mathcal{F}_n(x)\|_{L^2} \\
&\leq T^{1/2} M_\delta M_\mu \|x_n - x\|_C.
\end{align*}
\]
Using (51) and (52) in (50) yields, after taking supremum over \([0, T]\),
\[
\begin{align*}
\frac{1}{2} \left( 1 - 4M_\delta TM_\mu \right) \|x_n - x\|_C \leq \|y_n - x\|_C.
\end{align*}
\]
In view of (H12)–(H14) and the fact that \( 1 - 4M_\delta TM_\mu > 0 \), we can apply Lemma 16 to conclude from (53) that \( \|x_n - x\|_C \to 0 \) as \( n \to \infty \). This completes the proof. \(\square\)

Now, let \( P_x \) and \( P_{x_n} \) denote the probability measures on \( C([0, T]; \mathcal{L}^2(\Omega; U)) \) induced by the mild solutions \( x \) and \( x_n \) of (1) and (46), respectively. Using Theorem 17, we will prove that \( P_{x_n} \to P_x \) as \( n \to \infty \), for a special subclass of initial-value problems. Precisely, we have the following.

**Theorem 18.** Assume that (H1), (H3), (H4), and (H5) hold, in addition to the following:

(H16) \( \mathcal{F} : C([0, T]; \mathcal{L}^2(\Omega; U)) \to \mathcal{L}^p((0, T); \mathcal{L}^2(\Omega; U)) \)

where \( p \geq 4 \) is such that there exists a positive constant \( M_\varepsilon \) for which
\[
\|\mathcal{F}(x) - \mathcal{F}(y)\|_{\mathcal{L}^p} \leq M_\varepsilon \|x - y\|_C,
\]
\( \forall x, y \in C([0, T]; \mathcal{L}^2(\Omega; U)) \);

(H17) \( \mathcal{F}_n : C([0, T]; \mathcal{L}^2(\Omega; U)) \to \mathcal{L}^p((0, T); \mathcal{L}^2(\Omega; U)) \)

where \( p \geq 4 \) is such that
(i) \( \|\mathcal{F}_n(x) - \mathcal{F}_n(y)\|_{\mathcal{L}^p} \leq M_\varepsilon \|x - y\|_C \), for all \( x, y \) \in \( C([0, T]; \mathcal{L}^2(\Omega; U)) \),
(iii) \( \|\mathcal{F}_n(x) - \mathcal{F}(x)\|_{\mathcal{L}^p} \to 0 \) as \( n \to \infty \), for all \( x \) \in \( C([0, T]; \mathcal{L}^2(\Omega; U)) \), where \( M_\varepsilon \) is the constant defined in (H15);

(H18) The operators \( A_n : D(A) \subset U \to U \) are bounded and linear.

If \( 1 - M_\delta T^{2/q} \to 0 \) (where \( 1/p + 1/q = 1 \)), then \( P_{x_n} \to P_x \) as \( n \to \infty \).

**Proof.** We begin by showing that \( \{P_{x_n}\}_{n=1}^{\infty} \) is relatively compact in \( C([0, T]; \mathcal{L}^2(\Omega; U)) \) by appealing to the Arzelá-Ascoli theorem. To this end, we will first show that there exists \( \eta > 0 \) such that
\[
\sup_{n \in \mathbb{N}} \sup_{0 \leq t \leq T} \|x_n(t)\|_{\mathcal{L}^2(\Omega; U)} = \eta < \infty.
\]
Note that \( x_n \) is given by
\[
\begin{align*}
x_n(t) &= S_n(t)x_0 + \int_0^t S_n(t-s) \mathcal{F}_n(x_n)(s) \, ds \\
&\quad + \int_0^t S_n(t-s) g_n(s) \, d\beta^I(s), \quad 0 \leq t \leq T.
\end{align*}
\]
Observe that
\[
\|S_n(t)x_0\|_{\mathcal{L}^2(\Omega; U)}^2 \leq M_\delta^2 \|x_0\|^2_{\mathcal{L}^2(\Omega; U)}.
\]
Likewise, (H16) guarantees the existence of a positive constant \( M_\varepsilon \) such that \( \|\mathcal{F}_n(0)\|_{\mathcal{L}^p} \leq M_\varepsilon \), for all \( n \), so that a standard argument now yields
\[
\begin{align*}
E \int_0^t \|S_n(t-s) \mathcal{F}_n(x_n)(s) ds\|_U^2 &\leq T^{2/2} M_\delta^2 \left[ M_\varepsilon \|x_n\|_{\mathcal{L}^2(\Omega; U)} + M_\varepsilon^2 \right].
\end{align*}
\]
Also, \(|E[\int_0^t S_n(t-s)g_n(s)dB^H(s)]^2 : n \in \mathbb{N}\)| is uniformly bounded because of (H12) and (H14) and the uniform boundedness of \([g_n : n \in \mathbb{N}]\) in \(\mathcal{Q}(V;U)\). Combining the estimates (57) and (58) and rearranging terms enable us to conclude from (56) that (55) holds because 1 – \(MS^2T^{2/q}M_{c}^{-2} > 0\) and all constants in (56)–(58) are independent of \(n\).

Next, we establish the equicontinuity by showing \(E[\|x_n(t) - x_n(s)\|_{L^4}^4] \rightarrow 0\) as \((t-s) \rightarrow 0\), for all \(0 \leq s \leq t \leq T\), uniformly for all \(n \in \mathbb{N}\). We estimate each term of the expression for \(x_n(t) - x_n(s)\) separately. The boundedness of \([\|A_n\|_{\mathcal{B}(U)} : n \in \mathbb{N}]\) (as guaranteed by (H18)) ensures that

\[ M_{SA} = \sup_{n \in \mathbb{N}} \|A_n\|_{\mathcal{B}(U)} < \infty. \]  

Employing Theorem 2.4(d) in [28] and taking into account (H12), (H14), and (59), we conclude that

\[ E[\|S_n(t) - S_n(s)\|_{L^4}^4] \leq T^{4/3} \int_s^t E[\|S_n(\tau) A_n x_0\|_{L^4}^4]d\tau \leq T^{4/3} M_{SA}^4 \|x_0\|_{X^1_{\alpha}(\Omega;U)}^4 (t-s)^2. \]  

Next, observe that

\[
\begin{align*}
\int_0^t S_n(t-\tau) \mathcal{F}_n(x_n)(\tau) d\tau = & \int_0^t S_n(s-\tau) \mathcal{F}_n(x_n)(\tau) d\tau \\
= & \int_0^t [S_n(t-\tau) - S_n(s-\tau)] \mathcal{F}_n(x_n)(\tau) d\tau \\
& + \int_0^t S_n(t-\tau) \mathcal{F}_n(x_n)(\tau) d\tau.
\end{align*}
\]

Using (59), (H12), and (H13) when estimating each of the two integrals on the right side of (61) separately yields

\[
\begin{align*}
E \left[ \int_0^t [S_n(t-\tau) - S_n(s-\tau)] \mathcal{F}_n(x_n)(\tau) d\tau \right]^4 
& \leq T^{4/3} \int_0^t \int_0^{t-\tau} E[\|S_n(w) A_n \mathcal{F}_n(x_n)(w)\|_{L^4}^4]dw d\tau \\
& \leq M_{SA}^4 T^{11/3} \left[ M_{\mathcal{F}}^4 \|x_0\|_{L^4}^4 + M_{c}^{-4} \right] (t-s)^{(p-4)/p}.
\end{align*}
\]

Next,

\[
\begin{align*}
E \left[ \int_0^t S_n(t-\tau) g_n(\tau) d\beta^H(\tau) \right]^4 
& \leq E \left[ \sum_{j=1}^\infty \left[ \int_0^t S_n(t-\tau) g_n(\tau) e_j d\beta^H_j(\tau) \right]^4 \\
& \leq E \left[ \sum_{j=1}^\infty \left[ \int_0^t S_n(t-\tau) g_n(\tau) d\beta^H_j(\tau) \right]^4 \\
& \leq E \left[ \sum_{j=1}^\infty \int_0^t [S_n(t-\tau) - S_n(s-\tau)] g_n(\tau) e_j d\beta^H_j(\tau) \right]^4 \\
& \leq \sum_{j=1}^\infty \int_0^t [S_n(t-\tau) - S_n(s-\tau)] g_n(\tau) e_j d\beta^H_j(\tau) \right]^4 \\
& \leq E \left[ \sum_{j=1}^\infty \int_0^t S_n(t-\tau) g_n(\tau) e_j d\beta^H_j(\tau) \right]^4 \right] \right|^4 \\
& \leq E \left[ \sum_{j=1}^\infty \int_0^t S_n(t-\tau) g_n(\tau) e_j d\beta^H_j(\tau) \right]^4 \right] \right|^4.
\end{align*}
\]

Using the uniform boundedness of \([g_n : n \in \mathbb{N}]\) in \(\mathcal{Q}(V;U)\), one can argue as in Lemma 8 to show that the right side of (63) goes to 0 as \((t-s) \rightarrow 0\). We conclude from the above estimates that \(E[\|x_n(t) - x_n(s)\|_{L^4}^4] \rightarrow 0\) as \((t-s) \rightarrow 0\), uniformly for \(0 \leq s \leq t \leq T\) and \(n \in \mathbb{N}\), as desired. Thus, the family \([P_{x_n}]_{n=1}^\infty\) is relatively compact in \(\mathcal{C}([0,T]; \mathcal{L}^4(\Omega;U))\) and hence tight (by Prokhorov’s theorem [9]).

To finish the proof, we remark that Theorem 17 implies that the finite-dimensional joint distributions of \(P_{x_n}\) converge weakly to those of \(P\) (cf. Proposition 3). Hence, Theorem 4 ensures that \(P_{x_n} \Rightarrow P\) as \(n \rightarrow \infty\). This completes the proof.

\[ \square \]

5. Extension to the Second-Order Case

Consider the abstract second-order stochastic Cauchy problem

\[
dx'(t) = \left( \mathcal{B}x'(t) + \mathcal{C}x(t) + F(x)(t) \right)dt + G(t) d\beta^H(t),
\]

\[0 \leq t \leq T,
\]

\[x(0) = x_0, \quad x'(0) = x_1
\]

(64)

in a real separable Hilbert space \(\tilde{U}\). Here, \(\mathcal{B} : \tilde{U} \rightarrow \tilde{U}\) is a bounded linear operator; \(\mathcal{C} : D(\mathcal{C}) \subset \tilde{U} \rightarrow \tilde{U}\) is a linear (possibly unbounded) operator for which \((-\mathcal{C})^{1/2}\) exists; \(F\) and \(G\) are mappings that satisfy (H2) and (H3), respectively; \(\{\beta^H(t) : t \geq 0\}\) is a \(\tilde{U}\)-valued fBm with Hurst parameter \(H \in (1/2, 1)\); and \(x_0, x_1 \in \mathcal{D}_{\alpha}(\Omega; \tilde{U})\).

We will convert (64) to a first-order system that, in turn, can be represented abstractly in the form (1). To this end, let

\[
z_1(t) = x(t), \quad z_1(0) = x_0,
\]

\[
z_2(t) = x'(t), \quad z_2(0) = x_1.
\]

(65)
Then,
\[ \begin{align*}
\dot{z}_1 (t) &= z_2 (t) dt, \\
\dot{z}_2 (t) &= (\mathcal{B}z_2 (t) + \mathcal{C}z_1 (t) + F (z_1) (t)) dt + G (t) d\beta^H (t).
\end{align*} \tag{66} \]

As such,
\[ \begin{align*}
\frac{d}{dt} \begin{bmatrix} z_1 (t) \\
 z_2 (t) \end{bmatrix} &= \begin{bmatrix} 0 & I \\
 \mathcal{C} & 0 \end{bmatrix} \begin{bmatrix} z_1 (t) \\
 z_2 (t) \end{bmatrix} + \begin{bmatrix} 0 \\
 0 \end{bmatrix} \begin{bmatrix} z_1 (t) \end{bmatrix} + \begin{bmatrix} 0 \\
 F (z_1) (t) \end{bmatrix} dt \\
+ \begin{bmatrix} 0 \\
 G (t) \end{bmatrix} d\beta^H (t), \quad 0 \leq t \leq T,
\end{align*} \]
\[ \begin{bmatrix} z_1 (0) \\
 z_2 (0) \end{bmatrix} = \begin{bmatrix} x_0 \\
 x_1 \end{bmatrix}. \tag{67} \]

The space \( U = D(\mathcal{C}^{1/2}) \times \overline{U} \) is a Banach space when equipped with the usual graph norm. Define \( X : [0, T] \to U, A : D(A) \subset U \to U, B : D(B) \subset U \to U, g : [0, T] \to \mathcal{L}(V; U), \) and \( F : C ([0, T]; \mathcal{L}^2(\Omega; U)) \to \mathcal{L}^2((0, T); \mathcal{L}^2(\Omega; U)) \) by
\[ X(t) = \begin{bmatrix} z_1 (t) \\
 z_2 (t) \end{bmatrix}, \]
\[ A = \begin{bmatrix} 0 & I \\
 \mathcal{C} & 0 \end{bmatrix}, \quad D(A) = D(\mathcal{C}) \times D(\mathcal{C}^{1/2}) \subset U, \]
\[ B = \begin{bmatrix} 0 \\
 0 \end{bmatrix}, \quad D(B) = D(\mathcal{C}^{1/2}) \times \overline{U} \subset U, \]
\[ g(t) = \begin{bmatrix} 0 \\
 G(t) \end{bmatrix}, \quad F(X)(t) = \begin{bmatrix} 0 \\
 F(z_1) \end{bmatrix}(t). \]

Since
\[ X(0) = \begin{bmatrix} z_1 (0) \\
 z_2 (0) \end{bmatrix} = \begin{bmatrix} x_0 \\
 x_1 \end{bmatrix}, \tag{69} \]
we can use these identifications to rewrite (64) abstractly in the form
\[ dX(t) = ((A + B)X(t) + F(X)(t)) dt + g(t) d\beta^H (t), \quad 0 \leq t \leq T, \]
\[ X(0) = X_0. \tag{70} \]

We assume that the following conditions are satisfied.

(H19) \( \mathcal{B} : D(\mathcal{B}) \subset \overline{U} \to \overline{U} \) is a bounded linear operator.

(H20) \( \mathcal{C} : D(\mathcal{C}) \subset \overline{U} \to \overline{U} \) generates a strongly continuous cosine family on \( \overline{U} \) and \( (\mathcal{C})^{1/2} \) exists.

Since \( \mathcal{B} \in \mathcal{B}(U) \), it follows that \( A + B \) generates a strongly continuous semigroup on \( U \). As such, we can view (70) (and so, (64)) as a special case of (1). Theorem 10 can be applied directly to (70) under the same hypotheses to conclude that (64) has a unique mild solution \( X \in C ([0, T]; \mathcal{L}^2(\Omega; U)) \).

6. Applications

Let \( \mathcal{D} \) be a bounded domain in \( \mathbb{R}^N \) with smooth boundary \( \partial \mathcal{D} \) and consider the initial-boundary value problem
\[ x_i (t, z) = \Delta z_i (t, z) + \int_0^t a(t, s) f_1 (s, x_i (s, z), \int_0^s k(s, \tau, x_i (\tau, z)) d\tau) ds \\
+ f_2 (t, z) d\beta^H (t), \quad \text{a.e. on } (0, T) \times \mathcal{D}, \]
\[ x_i (0, z) = x_i_0 (z), \quad \text{a.e. on } \mathcal{D}, \]
\[ x_i (t, 0) = 0, \quad \text{a.e. on } (0, T) \times \partial \mathcal{D}. \tag{71} \]

We consider (71) under the following conditions on the data:
(H22) \( f_1 : [0, T] \times \mathbb{R} \to \mathbb{R} \) satisfies the Carathéodory conditions (i.e., measurable in \((t, x)\) and continuous in the third variable), and
(i) \( f_1 (\cdot, 0, 0) \in L^2 (0, T); \)
(ii) there exists a positive constant \( M_{f_1} \) such that
\[ |f_1 (t, x_1, y_1) - f_1 (t, x_2, y_2)| \leq M_{f_1} |x_1 - x_2| + |y_1 - y_2|, \]
for all \( x_1, x_2, y_1, y_2 \in \mathbb{R} \) and almost all \( t \in (0, T) \);
(H23) \( f_2 : [0, T] \times \mathcal{D} \to \mathcal{L}(\mathcal{L}^2 (\mathcal{D}); \mathcal{L}^2 (\mathcal{D})) \) is a bounded, strongly measurable mapping;
(H24) \( a \in L^2 ((0, T)^3) \);
(H25) \( k : Z \times \mathbb{R} \to \mathbb{R} \), where \( Z = \{(t, s) : 0 \leq t \leq s \leq T\} \), satisfies the Carathéodory conditions and there exists a positive constant \( M_k \) such that
\[ |k(t, s, x_1) - k(t, s, x_2)| \leq M_k |x_1 - x_2|, \]
for all \( x_1, x_2 \in \mathbb{R} \) and almost all \((t, s) \in Z\).

Let \( U = V = \mathcal{L}^2 (\mathcal{D}) \) and set
\[ A = \Delta z, \quad D(A) = H^2 (\mathcal{D}) \cap H^1_0 (\mathcal{D}). \tag{74} \]

It is well known that \( A \) generates a \( C_0 \)-semigroup on \( D(A) \) (see [28], Chapter 7).

Next, define
\[ \mathcal{F} : \mathcal{C} ([0, T]; \mathcal{L}^2 (\Omega; U)) \to \mathcal{L}^2 ((0, T); \mathcal{L}^2 (\Omega; U)), \]
\[ f_2 : [0, T] \times \mathcal{D} \to \mathcal{L} (\mathcal{L}^2 (\mathcal{D}); \mathcal{L}^2 (\mathcal{D})), \tag{75} \]
respectively, by
\[ F(x)(t, \cdot) = \int_0^t a(t, s) f_1 (s, x(s, \cdot), \int_0^s k(s, \tau, x(\tau, \cdot)) d\tau) ds, \]
\[ g(t)(\cdot) = f_2 (t, \cdot). \tag{76} \]
One can use (H22)–(H25) to verify that $F$ satisfies (H2) with

$$M_x = 2M_{f1}T[a|_{L^2((0,T)}|^2(1 + M_{f1}T^3)\right)^{1/2}$$

(77)

and that $g$ is strongly measurable. Thus, (71) can be rewritten in the form (1) in $U$, with $A, \mathcal{F}$, and $g$ defined above so that an application of Theorem 10 immediately yields the following result.

**Theorem 19.** If (H22)–(H25) hold (with $M_x$ given by (77)), then (71) has a unique mild solution $x \in C([0,T]; L^2(\Omega; L^2(\mathcal{O})))$.

**Example 20.** We now consider a modified version of (71) which constitutes a model related to the one in [12]. Precisely, let $\mathcal{O} = \mathbb{R}$ and consider the initial-boundary value problem given by

$$\partial_t x(t, z) = - (I - \Delta)\alpha/2 (\Delta - \Delta)^{\alpha/2} x(t, z) + \int_0^t a(s, x(s, z)) \int_0^s k(s, \tau, x(\tau, z)) d\tau) d\tau + f_2(t, z) d\beta^H(t), \quad a.e. \text{on} \quad (0, T) \times \mathcal{O},
$$

$$x(t, z) = 0, \quad a.e. \text{on} \quad (0, T) \times \partial\mathcal{O},
$$

$$x(0, z) = x_0(z), \quad a.e. \text{on} \quad \mathcal{O}. \tag{78}$$

The operator $(\Delta - \Delta)^{\alpha/2}$ is defined by

$$D((\Delta - \Delta)^{\alpha/2}) = \left\{ h \in L^2_w(\mathbb{R}) : h, |y|^{\alpha} \hat{h}(y) \in L^1(\mathbb{R}) \cap L^2(\mathbb{R}) \right\},
$$

$$\frac{1}{\sqrt{2\pi}} \int_{\mathbb{R}} e^{izy} |y|^{\alpha} \hat{h}(y) dy \in L^2_w(\mathbb{R}) \right\}, \tag{79}$$

where $\hat{h}$ denotes the Fourier transform of $h$, and the space $L^2_w(\mathbb{R})$ is given by

$$L^2_w(\mathbb{R}) = \left\{ h : h \text{ is measurable}, \frac{1}{\sqrt{2\pi}} \int_{\mathbb{R}} e^{izy} |y|^{\alpha} \hat{h}(y) dy \right\}, \tag{80}$$

where $w(z) = (1 + z^2)^{-\xi/2}$, for $\xi > 1$. Also, the operator $(I - \Delta)^{\alpha/2}$ is defined by

$$(I - \Delta)^{\alpha/2} h(z) = \frac{1}{\sqrt{2\pi}} \int_{\mathbb{R}} e^{izy} (1 + y^2)^{\alpha/2} \hat{h}(y) dy,
$$

$$D((I - \Delta)^{\alpha/2}) = \left\{ h \in L^2_w(\mathbb{R}) : h, (1 + y^2)^{\alpha/2} \hat{h}(y) \in L^1(\mathbb{R}) \cap L^2(\mathbb{R}) \right\},
$$

$$\frac{1}{\sqrt{2\pi}} \int_{\mathbb{R}} e^{izy} (1 + y^2)^{\alpha/2} \hat{h}(y) dy \in L^2_w(\mathbb{R}) \right\}. \tag{81}$$

As shown in Proposition 1 of [12], the operator $-(I - \Delta)^{\alpha/2} (\Delta - \Delta)^{\alpha/2}$ generates a strongly continuous semigroup on $L^2_w(\mathbb{R})$, assuming that $\alpha + \gamma > (\lambda - 1)/2$ and $\lambda < 1$. As such, by taking $U = L^2_w(\mathbb{R})$ and $V = \mathbb{R}$ and defining the operator $A = -(I - \Delta)^{\alpha/2} (\Delta - \Delta)^{\alpha/2}$, we can argue as in (71) to show that (78) has a unique mild solution $x \in C([0,T]; L^2(\Omega; L^2(\mathcal{O})))$.

**Example 21.** Let $\mathcal{O}$ be a bounded domain in $\mathbb{R}^n$ with smooth boundary $\partial\mathcal{O}$. Consider the following initial-boundary value problem:

$$\partial \left( \frac{\partial x(t, \bar{z})}{\partial t} \right) = \left( B \left( \frac{\partial x(t, \bar{z})}{\partial t} \right) \sum_{j=1}^{n} \frac{\partial}{\partial z_j} \left( a_{jk}(\bar{z}) \frac{\partial x(t, \bar{z})}{\partial z_j} \right) \right) \partial t + c(\bar{z}) x(t, \bar{z}) \partial t + \left( f_1(t, x(t, \bar{z})) + \int_0^t b(t-s) f_2(s, x(s, \bar{z})) ds \right) \partial t + f_3(t, \bar{z}) d\beta^H(t), \quad 0 < t < T, \quad \bar{z} \in \mathcal{O},
$$

$$x(0, \bar{z}) = x_0(\bar{z}), \quad \frac{\partial x(0, \bar{z})}{\partial t} = x_1(\bar{z}), \quad a.e. \text{on} \quad \mathcal{O},
$$

$$x(t, \bar{z}) = 0, \quad a.e. \text{on} \quad (0, T) \times \partial\mathcal{O}, \tag{82}$$

where $\bar{z} = (z_1, \ldots, z_n) \in \mathcal{O}, x_0(\cdot) \in D(A) \cap L^2(\Omega; L^2(\mathcal{O})), \quad (83)$

and $x_1(\cdot) \in E \cap L^2(\Omega; L^2(\mathcal{O})).$ Here, $a_{jk} : \mathcal{O} \to \mathbb{R}$ and $c : \mathcal{O} \to \mathbb{R}$ are bounded, strongly measurable mappings; and $f_i (i = 1, 2, 3)$, $B$, and $b$ satisfy the following assumptions:

(H26) $f_i : [0, T] \times \mathbb{R} \to \mathbb{R}$ $(i = 1, 2)$ satisfies the Carathéodory conditions, and

(i) $(f_i(0, 0) \in L^2(0, T));
(ii) there exists a positive constant $M_{f_i}$ such that
$$|f_i(t, x) - f_i(t, y)| \leq M_{f_i} |x - y|,$$

for all $x, y \in \mathbb{R}$, and almost all $t \in (0, T);$
If (H26)–(H29) are satisfied, then Theorem 22 yields the following result.

**Theorem 22.** If (H26)–(H29) are satisfied, then (82) has a unique mild solution \( x \in C([0, T]; \mathcal{L}^2(\Omega; \mathcal{L}^2(\mathcal{D}))) \).

**Conflict of Interests**

The authors declare that there is no conflict of interests regarding the publication of this paper.

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**References**


