

Persistently Expansive Geodesic Flows

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Abstract. We prove that C^1 -persistently expansive geodesic flows of compact, boundaryless Riemannian manifolds have the property that the closure of the set of closed orbits is a hyperbolic set. In the case of compact surfaces we deduce that the geodesic flow is C^1 -persistently expansive if and only if it is an Anosov flow.

Introduction

In this paper we present some results concerning geodesic flows possessing certain topological properties which persist under small perturbations. Recall that if (M, g) is a complete Riemannian manifold and T_1M is its unit tangent bundle, the geodesic flow $\varphi_t: T_1M \rightarrow T_1M$ is defined as follows: given a point $(p, v) \in T_1M$, $\varphi_t(p, v) = (\gamma(t), \gamma'(t))$, where $\gamma(t)$ is the unit geodesic of M such that $\gamma(0) = p$ and $\gamma'(0) = v$. Let us denote as $\kappa^k(M)$ the set of geodesic flows of Riemannian metrics of M endowed with the C^k topology. Given any one parameter family of homeomorphisms $\psi_t: N \rightarrow N$ acting on a metric space N , we say that it is *expansive* if there is an $\varepsilon > 0$ such that every $p \in N$ satisfies the following property: if $q \in N$ and there exists a continuous surjection $f_q: \mathbb{R} \rightarrow \mathbb{R}$ with $d(\psi_t(p), \psi_{f_q(t)}(q)) \leq \varepsilon$ for every $t \in \mathbb{R}$, then there exists $t_0 \in \mathbb{R}$ depending on ε, p, q , with $t_0 \rightarrow 0$ if $d(p, q) \rightarrow 0$ such that $q = \psi_{t_0}(p)$. When $t \in \mathbb{Z}$ for every t we just take $f_q(t) = t$ and $t_0 = 0$.

The persistence of expansivity is closely related with hyperbolicity and stability of dynamical systems. Let $E^k(M)$ be the subset of $\kappa^k(M)$ of expansive geodesic flows. An Anosov geodesic flow of a compact manifold M is expansive, and since it is C^1 -structurally stable [1] it belongs to $\text{int}(E^1(M))$ – the interior of $E^1(M)$ in $\kappa^1(M)$. Axiom A systems are expansive near the closure of the set of periodic orbits, and since they are Ω -stable [10, 12] this property persists under C^1 perturbations. On the other hand, Mañé [6] proves that the interior of the set of expansive diffeomorphisms in $\text{Diff}^1(M)$ (i.e. the set of C^∞ diffeomorphisms of M endowed with the C^1 topology) coincides with the

set of Quasi-Anosov ones. (A diffeomorphism $f: M \rightarrow M$ is called Quasi-Anosov if for every $p \in M$ and $V \in T_p M$ we have that $\|Df^n(V)\| \rightarrow \infty$ when either $n \rightarrow +\infty$ or $n \rightarrow -\infty$.) Mañé shows in particular that such diffeomorphisms are Axiom A systems. We obtain in this work analogous results for persistently expansive geodesic flows. If ψ_t is a flow acting on a Riemannian manifold N we say that an invariant set $X \subseteq N$ is *hyperbolic* if there exist constants $C > 0$, $0 < \lambda < 1$, and a splitting $E_p^s \oplus E_p^u \oplus E_p = T_p N$ for every $p \in X$ such that

- i) E_p^s, E_p^u are invariant by $d\psi_t$ and E_p is the direction of the flow at p . (If p is a singularity take $E_p = 0$.)
- ii) $\|d\psi_t|_{E_p^s}\| \leq C\lambda^t \forall t \geq 0$,
 $\|d\psi_t|_{E_p^u}\| \leq C\lambda^{-t} \forall t \leq 0$.

When $X = N$ the flow is called an *Anosov* flow. Denote as $A(M)$ the set of Anosov geodesic flows of the manifold M .

Theorem A. *Let M be a compact manifold of dimension two. Then $\text{int}(E^1(M)) = A(M)$.*

This theorem will follow from the fact that periodic orbits of expansive geodesic flows of surfaces are dense (see Sect. 3) together with the following result:

Theorem B. *Let (M, g) be a compact Riemannian manifold of dimension n . If the geodesic flow φ_t belongs to $\text{int}(E^1)$ the set $\overline{P(\varphi)}$ – the closure of the set $P(\varphi)$ of periodic orbits of φ_t – is a hyperbolic set.*

The method used to prove Theorem B combines some classical results concerning symplectic dynamics – the so-called Birkhoff-Lewis fixed point theorem – with the general theory of persistent invariant bundles. Indeed, we deduce that if $\varphi_t \in E^1(M)$ then the closed orbits are C^1 -persistently hyperbolic, and from [6] this implies that there exists an extended, continuous invariant bundle defined in $\overline{P(\varphi)}$ – which coincides with the hyperbolic splitting along each periodic orbit-satisfying what is called the *domination condition* (see [6] and also Sect. 2). It is important to remark that the absence of a closing lemma for geodesic flows determines essential differences between the arguments used here and those of [6] for diffeomorphisms. Roughly speaking, Pugh's closing lemma [9] says that for every diffeomorphism $f: M \rightarrow M$ defined on a compact manifold M we can approximate "almost" periodic parts of orbits of f by periodic orbits of C^1 perturbations of f .

On the other hand, we shall show that the splitting mentioned above satisfies an algebraic property associated to the symplectic structure of the geodesic flow: it comes to be a Lagrangian splitting. Invariant splittings of Anosov geodesic flows are easily seen to be Lagrangian, while the reciprocal statement is not necessarily true. What we prove is that a continuous, Lagrangian, invariant splitting defined on a compact invariant set for the geodesic flow is hyperbolic if and only if it satisfies the domination condition.

1. Generic Properties of Poincaré Maps of Closed Orbits

Let (M, g) be a complete Riemannian manifold, and let T_1M be unit tangent bundle. The metric g induces a Riemannian structure on T_1M given by the metric \hat{g} , which we define as follows: Let $\pi: TM \rightarrow M$ be the projection $\pi(p, v) = p$, where (p, v) is a point of TM in local coordinates $U \times \mathbb{R}^n$, U an open subset of M . Let

$$K: T(TM) \rightarrow TM$$

$$K: Y_{(q,v)} \mapsto \overline{V_{\frac{d\pi(Y)}{q}} d\pi(Y)_q},$$

where $\bar{V}: TM \times TM \rightarrow TM$ is the Levi-Civita connection of (M, g) , and $\overline{d\pi(Y)_q}$ is any differentiable vector field defined in an open neighborhood of p such that $\overline{d\pi(Y)_p} = d\pi(Y)_p$. Then, if $V, W \in T_\xi(TM)$, define

$$\hat{g}(V, W) = g(d\pi(V), d\pi(W)) + g(K(V), K(W)).$$

It is easy to see that $\text{Ker}(K_\xi) \oplus \text{Ker}(d\pi_\xi) = T_\xi(TM)$, where the sum is orthogonal with respect to \hat{g} , and $\dim[\text{Ker}(K_\xi)] = \dim[\text{Ker}(d\pi_\xi)] = n$. Now, let us consider the restriction of this metric to T_1M , which we still denote as \hat{g} .

Let $\varphi_t: T_1M \rightarrow T_1M$ be the geodesic flow of (M, g) . Consider $N_\xi = \{v \in T_\xi(T_1M) \setminus \hat{g}(v, E_\xi) = 0\}$, where E_ξ is the direction tangent to the flow at $\xi \in T_1M$, and let $H_\xi \subset N_\xi$, $V_\xi \subset N_\xi$ be the horizontal and the vertical subspaces respectively, where

$$H_\xi = \text{Ker}(K_\xi) \cap N_\xi,$$

$$V_\xi = \text{Ker}(d\pi_\xi) \cap N_\xi.$$

Note that $\dim(H_\xi) = \dim(V_\xi) = n - 1$ and $N_\xi = H_\xi \oplus V_\xi$. Define

$$\mathfrak{J}: T(T_1M) \rightarrow T(T_1M),$$

$$\mathfrak{J}(X, Y) = (-Y, X).$$

Observe that $\mathfrak{J}^2 = -I$, and that there exists a canonical symplectic structure on N_ξ induced by J . Recall that a *symplectic form* ω on \mathbb{R}^{2m} is an alternate, non-degenerate two-form on \mathbb{R}^{2m} . We call the pair $(\mathbb{R}^{2m}, \omega)$ a *symplectic structure*. Now, for each $\xi \in T_1M$ consider the following form:

$$\Omega_\xi(V, W) = \hat{g}(V, \mathfrak{J}(W)) \quad \forall V, W \in N_\xi.$$

It is clear that Ω_ξ depends differentiably on ξ , and since \mathfrak{J} is both an isomorphism and an involution we get that Ω_ξ is in fact a symplectic form $\forall \xi$. We shall denote as Ω the two-form in $\Lambda^2(T_1M)$, the space of two-forms of T_1M , defined by $\Omega(\xi) = \Omega_\xi$.

A simple, but important remark is that the geodesic flow of (M, g) preserves both N_ξ and Ω , i.e., $d\varphi_t(N_\xi) = N_{\varphi_t(\xi)} \quad \forall \xi \in T_1M$ and

$$\varphi_t^*(\Omega_{\varphi_t(\xi)}) = \Omega_\xi \quad \forall t \in \mathbb{R},$$

where the map $F^*: \Lambda^2(T_{F(p)}X) \rightarrow \Lambda^2(T_pX)$ is defined as

$$F^* \omega_{F(p)}(V, W) = \omega_p(dF^{-1}(V), dF^{-1}(W))$$

for every diffeomorphism $F: X \rightarrow X$ on a manifold X , with $\Lambda^k(T_p X)$ being the space of k forms on $T_p X$. This implies in particular that $\hat{g}(d\varphi_t(V), \text{ and } \mathfrak{J}(d\varphi_t(W))) = \hat{g}(\mathfrak{J}(V), W)$, so

$$(d\varphi_t)^* \circ \mathfrak{J} \circ (d\varphi_t) = \mathfrak{J},$$

where $(d\varphi_t)^*$ is the adjoint operator of $d\varphi_t$. A diffeomorphism $F: \mathbb{R}^{2n} \rightarrow \mathbb{R}^{2n}$, $F(0) = 0$ which preserves a symplectic form is called a *symplectic diffeomorphism*.

Now, let $\varphi_t(\eta)$ be a periodic orbit, and let $S_\eta \subset T_1 M$ be a local transversal section containing η . Recall that the *Poincaré map* $\mathfrak{P}_\eta: S_\eta \rightarrow S_\eta$ of the orbit associated to S_η assigns to each point $q \in S_\eta$ the point $\mathfrak{P}_\eta(q) = \varphi_{t_0}(q)$, where $t_0 = \inf_{t > 0} \{\varphi_t(q) \cap S_\eta \neq \emptyset\}$. By the above comments, if S_η is normal to the direction of the flow at η , the linear part of the Poincaré map is a symplectic isomorphism. Poincaré maps corresponding to different sections containing η are conjugate, so we can suppose that there is a unique Poincaré map when talking about properties which are invariant under conjugation. Also, up to a change of coordinates we can suppose that Ω is the canonical form $\omega = \sum_{i=1}^m dx_i \wedge dy_i$. So let $J_s^k(2m)$ be the set of k -jets of symplectic automorphisms of $(\omega, \mathbb{R}^{2m})$ which fix $0 \in \mathbb{R}^{2m}$. Let Q be any subset of $J_s^k(2m)$ which is invariant under conjugacies by every $\sigma \in J_s^k(2m)$. Then Takens and Klingenberg in [4] show the following theorem:

Theorem 1.1. *Let $Q \subset J_s^k(2m)$ as above be generic. Then the following property P_Q is C^k -generic in $\kappa^k(M)$: the geodesic flow of g has the property P_Q if the Poincaré map of every closed orbit belongs to Q .*

In other words, generic properties of symplectic automorphisms of \mathbb{R}^{2n} are generic for Poincaré maps of closed orbits of geodesic flows. We now show that:

Proposition 1.1. *Let $g \in \text{int}(E^1(M))$. Then every periodic orbit is hyperbolic.*

For the proof we recall a classical result describing local invariant submanifolds of symplectic diffeomorphisms near periodic points [3]:

Lemma 1.1. *Let $U \subseteq \mathbb{R}^{2m}$ be an open neighborhood of $0 \in \mathbb{R}^{2m}$, and let $P: U \rightarrow U$ be a symplectic diffeomorphism with $P(0) = 0$. Let $\bar{P} = dP(0)$ and let*

$$V^s \oplus V^u \oplus V^{ce}$$

be the direct splitting of \mathbb{R}^{2m} into the stable, unstable and central subspaces with respect to \bar{P} . Then there exist local imbeddings $W^s, W^u: \mathbb{R}^p \rightarrow \mathbb{R}^{2m}$ and $W^{ce}: \mathbb{R}^{2q} \rightarrow \mathbb{R}^{2m}$ such that $T_0 W^s = V^s$, $T_0 W^u = V^u$ and $T_0 W^{ce} = V^{ce}$. They are called stable, unstable and central manifolds respectively. If P is of class C^k , these manifolds are of class C^k and while W^s and W^u are unique, W^{ce} is not unique in general.

So for the Poincaré map of a closed orbit there exists a central manifold (which could be a point) of the same differentiable class as the map. Let us call $P_{ce} = P|_{W^{ce}}$, the restriction of P to W^{ce} .

Definition. $P: \mathbb{R}^{2m} \rightarrow \mathbb{R}^{2m}$, $P(0) = 0$ is of *twist type* if

- (a) The corresponding linear map \bar{P} is not hyperbolic.
- (b) \bar{P} is *elementary* (i.e., all the eigenvalues are different).
- (c) \bar{P} is 4-elementary (i.e., if $\varrho_1, \varrho_2, \dots, \varrho_k$ is the set of eigenvalues of P with modulus less than 1 and $\lambda_{k+1}, \dots, \lambda_m$ is any subset of eigenvalues of modulus 1 then for every m -tuple (a_1, a_2, \dots, a_m) of integers we have

$$(\varrho_1)^{a_1} \cdot \dots \cdot (\varrho_k)^{a_k} \cdot (\lambda_{k+1})^{a_{k+1}} \cdot \dots \cdot (\lambda_m)^{a_m} \neq 1.$$

- (d) If

$$(z^*)^k = z^k \exp 2\pi i (a^k - \sum_i b_i^k z^i z^{-i}) + w^k(z, \bar{z})$$

is the *Birkhoff normal form* of P_{ce} , then $\det(b_i^k) \neq 0$.

Remark that properties (a), (b), (c) are C^1 generic, and property (d) is C^3 generic (see for example [3, 8]). As a consequence of Theorem 1.1 we have the following result:

Lemma 1.2. *Let $\varphi_t(\xi)$ be a periodic orbit of $\varphi_t: T_1M \rightarrow T_1M$ the geodesic flow of (M, g) and let $\gamma(t) = \pi \circ \varphi_t(\xi)$ be the underlying geodesic. Let \mathfrak{P} be the Poincaré map. Assume that the linear part P has $2q$ eigenvalues on the unit circle. Then, in an arbitrarily small tubular neighborhood of $\gamma(t) \subset M$ there exist arbitrarily small perturbations of g supported on these neighborhoods such that, for the perturbed metrics $\gamma(t)$ is still a geodesic, the associated Poincaré map is C^3 -close to \mathfrak{P} and its restriction to $W^{ce}(\xi)$ is of twist type.*

On the other hand, we have the following generalized version of the so-called *Birkhoff-Lewis fixed point theorem*, which is due to Moser [8]:

Theorem 1.2. *Let $P: \mathbb{R}^{2n} \rightarrow \mathbb{R}^{2n}$, $P(0) = 0$ be a locally symplectic diffeomorphism of twist type with no hyperbolic part (i.e., $V^s = V^u = 0$, where V^s and V^u are given in Lemma 1.1). Then in every neighborhood of 0 there exist infinitely many closed orbits. The number of closed orbits of period $\leq k$ is finite for every $k \in \mathbb{N}$.*

The proof of Proposition 1.1 is as follows: let $g \in \text{int } E^k(M)$ and let $\varphi_t(\xi)$ be a closed orbit of the geodesic flow. If the Poincaré map is not hyperbolic, its linear part has some eigenvalues in the unit sphere. Thus, we can apply Lemma 1.2 to the restriction of the Poincaré map to the central manifold P_{ce} and deduce that there exist arbitrarily small perturbations g_n of the metric and sequences $\{\varphi_t(\xi_n)\}$ of closed orbits of ${}^n\varphi_t: (T_1M, g_n) \rightarrow (T_1M, g_n)$ – the geodesic flows of g_n – such that $\varphi_t(\xi)$ is a closed orbit of ${}^n\varphi_t$ for every $n \in \mathbb{N}$ and:

$$\lim_{m \rightarrow +\infty} \sup_{s \in \mathbb{R}} d_{g_n}({}^n\varphi_s(\xi_m), {}^n\varphi_s(\xi)) = 0 \quad \forall n \in \mathbb{N}.$$

This means that the metrics $g_n \notin E^1(M)$ which clearly contradicts the fact that $g \in \text{int } E^1(M)$. \square

Following [7] let $\mathcal{F}^k(M) \subset \kappa^k(M)$ be the set of geodesic flows of Riemannian metrics of M satisfying the following property: for every $\varphi \in \mathcal{F}^k(M)$ there exists a neighborhood $V(\varphi) \subset \kappa^k(M)$ of φ such that if $\psi \in V(\varphi)$ then every closed orbit of ψ is hyperbolic. Then:

Corollary 1.1. $\text{int } E^1(M) \subset \mathcal{F}^1(M)$.

2. Invariant Splittings on Persistently Hyperbolic Sets of Periodic Orbits

Let $\varphi \in \mathcal{F}^1(M)$, let $\xi \in T_1M$ be a closed orbit. From the last section there exist a stable subspace $E_\xi^s \subset T_\xi T_1M$ and an unstable subspace $E_\xi^u \subset T_\xi T_1M$, the former being contracted by $d\varphi_t$, $t \geq 0$, and the later being contracted by $d\varphi_t$, $t \leq 0$. Mañé proves in [7] that the bundles $\xi \mapsto E_\xi^s$ and $\xi \mapsto E_\xi^u$ defined on $\overline{P(\varphi_t)}$ admit continuous, φ_t -invariant extensions to bundles on the whole $\overline{P(\varphi_t)}$ with special properties, which are very close to hyperbolicity. For instance, these properties imply the hyperbolicity of the extended bundles [7] in the case of structurally stable diffeomorphisms. This is one of the more difficult, elaborated steps toward the proof of the C^1 -stability conjecture for diffeomorphisms.

Definition. Given a symplectic form β in \mathbb{R}^{2n} a *Lagrangian subspace* C of \mathbb{R}^{2n} is defined as:

- (a) $\forall V \in X, \beta(V, W) = 0 \leftrightarrow W \in X$.
- (b) $\dim(X) = n$.

Definition. Let φ_t be the geodesic flow of (M, g) and let Ω_ξ be the associated symplectic form of N_ξ for every $\xi \in T_1M$. If $A \subseteq T_1M$ a *Lagrangian bundle* over A , $\xi \rightarrow L_\xi$, is a map which assigns to each $\xi \in A$ a Lagrangian subspace L_ξ of N_ξ . A splitting $S_\xi \oplus U_\xi = N_\xi$ over A is said to be *Lagrangian* if both $\xi \rightarrow S_\xi$ and $\xi \rightarrow U_\xi$ are Lagrangian bundles over A .

Let us make precise the extension theorem [7]:

Theorem 2.1. *If $\varphi_t \in \text{int}(E^1(M))$ there exist a neighborhood U of φ_t in $\text{int}(E^1(M))$ and constants $K > 0, D > 0, 0 < \lambda < 1$ such that:*

- (a) *If $\varphi'_t: (T_1M, g') \rightarrow (T_1M, g')$ belongs to U and $\varphi'_t(\zeta) \in P(\varphi'_t)$ has minimum period $w \geq D$, then*

$$\prod_{i=0}^{k-1} \|d\varphi'_D|_{E'^s_{\varphi'_t(\zeta)}}\|_{g'} \leq K\lambda^k$$

and

$$\prod_{i=0}^{k-1} \|d\varphi'_{-D}|_{E'^u_{\varphi'_t(\zeta)}}\|_{g'} \leq K\lambda^k,$$

where $E'^s \oplus E'^u \oplus E'_\xi = T'_\xi(T_1M)$ is the hyperbolic splitting for ξ in the orbit $\varphi'_t(\zeta)$, and $k = \left\lceil \frac{w}{D} \right\rceil$.

- (b) *There exists a continuous splitting for $T_\xi(T_1M) = G_\xi^s \oplus G_\xi^u \oplus E_\xi$, $\xi \in \overline{P(\varphi_t)}$ with*

$$\|(d_\xi \varphi_D)|_{G_\xi^s}\| \circ \|(d_{\varphi_D(\xi)} \varphi_{-D})|_{G_\xi^u}\| \leq \lambda$$

and $G_\xi^s = E_\xi^s, G_\xi^u = E_\xi^u$ if $\xi \in P(\varphi_t)$.

If $\psi_t: \Sigma \rightarrow \Sigma$ is a differentiable flow acting on a manifold Σ , and X is an invariant subset of Σ in which the flow has no singularities, an invariant splitting $S_\xi \oplus U_\xi \oplus E_\xi = T_\xi \Sigma$ defined on every $\xi \in X$ is said to be *dominated* if there exist constants $0 < \delta < 1, m > 0$ such that $\|d\psi_m|_{S_\xi}\| \cdot \|d\psi_{-m}|_{U_{\psi_m(\xi)}}\| \leq \delta$. The space E_ξ is as before the direction of the flow in ξ . Statement (b) in the last

theorem says that $G_\xi^s \oplus G_\xi^u \oplus E_\xi = T_\xi T_1 M$, $\xi \in \overline{P(\varphi)}$ is dominated. Hyperbolic splittings are clearly dominated. The converse of this assertion is not true in general. However, we shall prove that in the case of Lagrangian splittings the domination condition is equivalent to hyperbolicity.

Lemma 2.1. $\xi \mapsto G_\xi^s$ is Lagrangian for $\xi \in \overline{P(\varphi)}$.

Proof. Since the bundle is continuous on $\overline{P(\varphi)}$ it suffices to show that $\xi \mapsto G_\xi^s$ is Lagrangian for $\xi \in P(\varphi)$. So let $\varphi_t(\xi)$ be a periodic orbit and $T_{\varphi_t(\xi)}(T_1 M) = G_{\varphi_t(\xi)}^s \oplus G_{\varphi_t(\xi)}^u \oplus E_{\varphi_t(\xi)}$ be the corresponding splitting. Let $T > 0$ be the minimum period of ξ . Recall that there exist $K(\xi) > 0$, $0 < \lambda(\xi) < 1$ such that if $V \in G_\xi^s = E_\xi^s$ then

$$\|d\varphi_t(V)\| \leq K(\xi) \lambda(\xi)^t \|V\| \quad \forall t \geq 0.$$

First of all, E_ξ^s and E_ξ^u are perpendicular to $E_\xi \forall \xi \in \overline{P(\varphi)}$: indeed, let us suppose that $V \in E_\xi^s$ is written as $V = \alpha + \beta$, where $\alpha \in N_\xi$, $\beta \in E_\xi$. Since $d\varphi_t$ preserves N_ξ and E_ξ , and $\|d\varphi_t(W)\| = \|W\|$ for every $W \in E_\xi$ we have

$$\begin{aligned} \|d\varphi_t(V)\|^2 &= \|d\varphi_t(\alpha)\|^2 + \|d\varphi_t(\beta)\|^2 \\ &\geq \|d\varphi_t(\beta)\|^2 \\ &= \|\beta\|^2, \end{aligned}$$

$$\rightarrow \|\beta\| \leq \lim_{t \rightarrow +\infty} \|d\varphi_t(V)\| = 0.$$

So $E_\xi^s \subset N_\xi$. Similarly, $E_\xi^u \subset N_\xi$.

Since \mathfrak{J} is an isometry we have

$$\|d\varphi_t(V)\| = \|\mathfrak{J} \circ d\varphi_t(V)\|.$$

Hence if $V, W \in E_\xi^s$ we have

$$\begin{aligned} |\Omega(V, W)| &= |\Omega(d\varphi_t(V), d\varphi_t(W))| = |\hat{g}(d\varphi_t(V), \mathfrak{J} \circ d\varphi_t(W))| \\ &\leq K(\xi)^2 \lambda(\xi)^{-2t} \|V\| \circ \|W\| \quad \forall t \geq 0 \end{aligned}$$

$$\rightarrow |\Omega(V, W)| = \lim_{t \rightarrow +\infty} K(\xi)^2 \lambda(\xi)^{-2t} \|V\| \circ \|W\| = 0.$$

Similarly, $\Omega(V, W) = 0 \forall V, W \in E_\xi^u$. Now, recall the following property of Lagrangian subspaces:

Sublemma. A subspace X of $(\mathbb{R}^{2n}, \omega)$ is Lagrangian if and only if

- i) $\omega(Z, V) = 0 \forall Z, V \in X$.
- ii) there exists a subspace Y of \mathbb{R}^{2n} such that $X \oplus Y = \mathbb{R}^{2n}$ and $\omega(V, W) = 0 \forall V, W \in Y$.

Therefore, Lemma 2.1 holds from the sublemma applied to $X = E_\xi^s$, $Y = E_\xi^u$ and (N_ξ, Ω_ξ) . \square

Proposition 2.1. Let $S_\xi \oplus U_\xi = N_\xi$ be a continuous, invariant Lagrangian splitting defined on a compact, invariant set $X \subseteq T_1 M$. The splitting is dominated if and only if it is hyperbolic, where S_ξ is forward-contracted by φ_t and U_ξ is backward-contracted by φ_t .

We prove first two lemmas.

Lemma 2.2. *Let $S_\xi \oplus U_\xi = N_\xi$ be a continuous Lagrangian splitting defined on a compact invariant set $X \subseteq T_1M$. Then $\lim_{k \rightarrow +\infty} \|(d_\xi \varphi_m)^k(\beta)\| = +\infty \forall \beta \in U_\xi$, $\forall \xi \in X$ if and only if $\lim_{k \rightarrow +\infty} \|(d_\xi \varphi_m)^k|_{S_\xi}\| = 0$. Similarly, S_ξ is backward-expanded by φ_m if and only if U_ξ is backward-contracted.*

Proof. (\Rightarrow) Consider the family of linear operators

$$\{T_v: U_\xi \rightarrow \mathbb{R}, v \in S_\xi, \|v\| = 1, \xi \in X\}$$

defined by $T_v(w) = \Omega(v, w)$. Since the splitting $S_\xi \oplus U_\xi = N_\xi$ is both continuous and Lagrangian and X is a compact set this is a compact family of linear, non-trivial operators. So for every $\xi \in X$ and $v \in S_\xi$ the kernel $K(v)$ of T_v is a codimension 1 subspace of U_ξ and there exists $w = w(v) \in U_\xi$ such that

$$T_v(w) = 1$$

and

$$g(K(v), w) = 0.$$

This dual vector $w = w(v)$ depends continuously on $\xi \in X$ and $v \in S_\xi$ and there exist constants $0 < C_1 \leq C_2$ such that

$$C_1 \leq \|w(v)\| \leq C_2$$

for every pair $(\xi, v) \in S_0 = \{(\xi, v), \xi \in X, v \in S_\xi, \|v\| = 1\}$. Remark also that $d\varphi_t(K(v)) = K(d\varphi_t(v)) = K\left(\frac{d\varphi_t(v)}{\|d\varphi_t(v)\|}\right)$ because Ω is invariant by the flow φ_t .

So take a vector $(\xi, v) \in S_0$ and consider $w = w(v) \in U_\xi$. From the hypotheses we get that

$$\lim_{n \rightarrow +\infty} \|d\varphi_m^n(w)\| = +\infty,$$

and from the compactness of S_0 the vectors $w(v)$ are uniformly expanded by the positive iterates of φ_m . Then we have

$$\begin{aligned} 1 &= \Omega(v, w) = T_v(w) \\ &= \Omega(d\varphi_m^n(v), d\varphi_m^n(w)) \\ &= \Omega\left(\frac{d\varphi_m^n(v)}{\|d\varphi_m^n(v)\|}, \|d\varphi_m^n(v)\| \cdot d\varphi_m^n(w)\right) \\ &= T_{v_n}(\|d\varphi_m^n(v)\| \cdot d\varphi_m^n(w)), \end{aligned}$$

where $v_n = \frac{d\varphi_m^n(v)}{\|d\varphi_m^n(v)\|}$. Obviously $(\varphi_m^n(\xi), v_n) \in S_0 \forall n$, and from the last equality we deduce that there exists a vector $z_n \in K(v_n)$ such that

$$\|d\varphi_m^n(v)\| \cdot d\varphi_m^n(w) = w(v_n) + z_n.$$

Since $K(\alpha)$ is φ_t -invariant $\forall t$ there exists $k_n \in K(v)$ such that $d\varphi_m^n(k_n) = z_n$. This implies that

$$\begin{aligned} w(v_n) &= \|d\varphi_m^{k(n)}(v)\| \cdot d\varphi_m^{k(n)}(w) - d\varphi_m^{k(n)}(k_n) \\ &= d\varphi_m^{k(n)}(\|d\varphi_m^{k(n)}(v)\| \cdot w - k_n). \end{aligned}$$

The vectors $\|d\varphi_m^{k(n)}(v)\| \cdot w - k_n$ belong to U_ξ , so by the hypotheses they must be expanded by the positive iterates of φ_m . But since $C_1 \leq \|w(v_n)\| \leq C_2$, this means that

$$\| \|d\varphi_m^{k(n)}(v)\| \cdot w - k_n \| \rightarrow 0$$

if n goes to $+\infty$. Since $w = w(v)$ and $K(v)$ are perpendicular this implies that

$$\lim_{n \rightarrow +\infty} \|d\varphi_m^{k(n)}(v)\| \cdot w = 0,$$

and therefore $\lim_{n \rightarrow +\infty} \|d\varphi_m^{k(n)}(v)\| = 0$ which proves the assertion.

(\Leftarrow) If there exist $w \in U_\xi$, a sequence $k(n) \rightarrow +\infty$ and $D > 0$ such that $\|d\varphi_m^{k(n)}(w)\| \leq D$ for every $k \geq 0$, then for every $v \in S_\xi$ we have

$$\begin{aligned} |\Omega(v, w)| &= |\Omega(d\varphi_m^{k(n)}(v), d\varphi_m^{k(n)}(w))| \\ &\leq \|d\varphi_m^{k(n)}(v)\| \cdot \|d\varphi_m^{k(n)}(w)\| \\ &\leq D \cdot \|d\varphi_m^{k(n)}(v)\| \rightarrow 0 \end{aligned}$$

by hypotheses. This implies that $\Omega(v, w) = 0 \forall v \in S_\xi$. But since S_ξ is Lagrangian this means that $w \in S_\xi \cap U_\xi = \{0\}$. The proof of the second statement of Lemma 2.2 is completely analogous. \square

Lemma 2.3. *Let $S_\xi \oplus U_\xi = N_\xi$ be a continuous, dominated Lagrangian splitting defined on a compact, invariant set $X \subseteq T_1M$. Then $\lim_{k \rightarrow +\infty} \|d\varphi_m^k(w)\| = +\infty \forall w \in U_\xi, \forall \xi \in X$. In a similar way, $\lim_{k \rightarrow +\infty} \|d\varphi_m^k(v)\| = +\infty \forall v \in S_\xi, \forall \xi \in X$. Here, $m > 0$ is the constant appearing in the domination condition.*

Proof. If $\lim_{k \rightarrow +\infty} \|d\varphi_m^k(v)\| = 0 \forall v \in S_\xi$ the statement is a consequence of Lemma 2.2. So let us suppose that there exist $\xi \in X, v \in S_\xi, \delta > 0$ and a sequence $k(n) \rightarrow +\infty$ such that $\|d\varphi_m^{k(n)}(v)\| \geq \delta$. Without loss of generality we can take $\delta = 1$. From the domination condition we get

$$\|d\varphi_m^{k(n)}|_{S_\xi}\| \cdot \|d\varphi_m^{-k(n)}|_{U_\xi}\| \leq \prod_{i=1}^{k(n)-1} \|d\varphi_m|_{S_{\phi_m^i(\xi)}}\| \cdot \|d\varphi_m^{-1}|_{U_{\phi_m^{i+1}(\xi)}}\| \leq \lambda^{k(n)-1},$$

where $\lambda \in (0, 1)$ gives the domination in the splitting. On the other hand, if $A: \mathbb{R}^n \rightarrow \mathbb{R}^n$ is an invertible linear map, we have that $\|v\| = \|A^{-1} \circ A(v)\| \leq \|A^{-1}\| \cdot \|A(v)\|$, which implies that $\frac{\|v\|}{\|A(v)\|} \leq \|A^{-1}\| \forall v \in \mathbb{R}^n$, and in particular

$$\frac{1}{\inf_{\|v\|=1} \|A(v)\|} \leq \|A^{-1}\|.$$

The contradiction assumption and the last two inequalities imply

$$\begin{aligned} \frac{1}{\inf_{\|v\|=1} \|d\varphi_{m k(n)}|_{U_\xi}\|} &\leq \|d\varphi_m^{k(n)}|_{S_\xi}\| \cdot \|d\varphi_m^{-k(n)}|_{U_\xi}\| \leq \lambda^{k(n)-1} \\ \Rightarrow \inf_{\|v\|=1} \|d\varphi_m^{k(n)}|_{U_\xi}\| &\geq (1/\lambda)^{-(k(n)-1)} \rightarrow +\infty. \end{aligned}$$

Now, from the compactness of X and the continuity of the bundle $\xi \rightarrow U_\xi$ it is easy to check that

$$\lim_{k \rightarrow +\infty} \|d\varphi_m^k(w)\| = +\infty$$

for every $w \in U_\xi$, and every $\xi \in X$. Analogously we can prove that $\lim_{k \rightarrow +\infty} \|d\varphi_m^k(v)\| = +\infty \forall v \in S_\xi, \forall \xi \in X$. \square

Proof of Proposition 2.1. From Lemmas 2.2 and 2.3 we have that

$$\begin{aligned} \lim_{k \rightarrow +\infty} \|d\varphi_m^k(v)\| &= 0 \quad \forall v \in S_\xi, \quad \forall \xi \in X, \\ \lim_{k \rightarrow -\infty} \|d\varphi_m^k(w)\| &= 0 \quad \forall w \in U_\xi, \quad \forall \xi \in X. \end{aligned}$$

Now, recall the following lemma due to Eberlein [2]:

Lemma. *Let $f: \mathbb{R}^+ \rightarrow \mathbb{R}^+$ be a continuous function satisfying*

- i) $\lim_{t \rightarrow +\infty} f(t) = 0$.
- ii) $f(t + s) \leq f(t) \cdot f(s)$.

Then there exist $L > 0, 0 < a < 1$ such that $f(t) \leq La^t$.

We can apply this lemma to the function $f_\xi(t) = \|d\varphi_t|_{S_\xi}\|$ for each $\xi \in X$ and deduce that there are constants $L(\xi) > 0, 0 < a(\xi) < 1$ such that $\|d\varphi_t|_{S_\xi}\| \leq L(\xi) a(\xi)^t \forall t \geq 0$. From the compactness of X and the continuity of the bundle S_ξ it is straightforward to deduce that there exist $E > 0$ and $0 < \alpha < 1$ such that

$$\|d\varphi_t|_{S_\xi}\| \leq E\alpha^t \quad \forall t \geq 0, \quad \forall \xi \in X.$$

By the same reasoning we get constants $D > 0, 0 < v < 1$ such that

$$\|d\varphi_{-t}|_{U_\xi}\| \leq Dv^t \quad \forall t \geq 0, \quad \forall \xi \in X.$$

Taking $C = \sup(E, D)$ and $\lambda = \sup(\alpha, v)$ we have that the set X is a hyperbolic set for φ_t with splitting $S_\xi \oplus U_\xi = T_\xi M$ and constants C and λ . This concludes the proof of the proposition.

3. Density of Periodic Orbits of Expansive Geodesic Flows

We shall expose first some canonical facts of the theory of expansive systems. Our main references are [4, 10]. Throughout this section N will be a compact manifold.

Definition. Let $\psi_t: N \rightarrow N$ be a continuous flow acting on N . For a given $\varepsilon > 0$, let $\tilde{C}_\varepsilon^s(p)$ be the set of points q of N with the following property: There exists a continuous, surjective map $\alpha: \mathbb{R}^+ \rightarrow \mathbb{R}^+$ with $\alpha(0) = 0$ such that

$$d(\psi_t(p), \psi_{\alpha(t)}(q)) \leq \varepsilon$$

for every $t \geq 0$. Analogously, let $\tilde{C}_\varepsilon^u(p)$ be the set of points q in N such that there exists a continuous, surjective function $\beta: \mathbb{R}^- \rightarrow \mathbb{R}^-$ with $\beta(0) = 0$

such that

$$d(\psi_t(p), \psi_{\beta(t)}(q)) \leq \varepsilon$$

for every $t \in \mathbb{R}^-$.

Notice that $\tilde{C}_\varepsilon^s(p)$ is forward invariant by ψ_t in the following sense: for every $t \geq 0$ and $q \in \tilde{C}_\varepsilon^s(p)$ there exists $t_0 \geq 0$ such that $\psi_{t_0}(q) \in \tilde{C}_\varepsilon^s(\psi_t(p))$. If the flow ψ_t were an Anosov flow the set $\tilde{C}_\varepsilon^s(p)$ would be the result of intersecting the weak stable submanifold of p (i.e. the saturated stable submanifold of p) with some neighborhood of p and then taking the connected component of this set containing p . Similarly, for every $t \leq 0$ and $q \in \tilde{C}_\varepsilon^u(p)$ there exists $t_1 \leq 0$ such that $\psi_{t_1}(q) \in \tilde{C}_\varepsilon^u(\psi_t(p))$.

Theorem 3.1. *Let $\dim N = 3$ and let $\psi_t: N \rightarrow N$ be an expansive flow without singularities with expansivity constant $\varepsilon > 0$. Then the following assertions are true:*

a) *There exists $\delta > 0$ such that $\tilde{C}_\delta^s(\xi), \tilde{C}_\delta^u(\xi)$ are connected, non-trivial sets $\forall \xi \in N$ (i.e., they do contain points which are not in the orbit of ξ).*

b) *Let $\Sigma_\varepsilon = \exp_\varepsilon \{w \in T_\xi N \setminus \{0\} \mid \|w\| < \varepsilon, \langle w, X(\xi) \rangle = 0\}$, where $\langle \cdot, \cdot \rangle$ is the metric of N . Then there exist periodic points $\eta_i, i = 1, 2, \dots, n$ such that for every point $\xi \in G = N - \bigcup_{i, t \in \mathbb{R}} \{\psi_t(\eta_i)\}$ there exists an open neighborhood V of ξ with diameter less than $\frac{\varepsilon}{2}$ such that the sets*

$$\begin{aligned} C_\delta^s(\xi) &= \Sigma \cap V \cap \tilde{C}_\delta^s(\xi), \\ C_\delta^u(\xi) &= \Sigma \cap V \cap \tilde{C}_\delta^u(\xi) \end{aligned}$$

are connected curves satisfying a local product structure: There exists a homeomorphism

$$F: (0, 1)^2 \rightarrow V \cap \Sigma$$

such that

- (i) $F(0, 0) = \xi$,
- (ii) $F_x(z) = C_\delta^s(F(x, z))$,
- (iii) $F^z(x) = C_\delta^u(F(x, z))$,

for every x, z in $(0, 1)$, where $F_x: (0, 1) \rightarrow \Sigma, F^z: (0, 1) \rightarrow \Sigma$ are the maps $F_x(z) = F(x, z), F^z(x) = F(x, z)$.

(c) $\tilde{C}_\delta^s(\xi)$ *contracts uniformly as t goes to $+\infty$ (respectively $\tilde{C}_\delta^u(\xi)$ contracts with $t \rightarrow -\infty$). In other words, for every $t > 0, \nu > 0$ there exist $T > 0$ such that*

$$\psi_t(\tilde{C}_\delta^s(\xi)) \subset \bigcup_{s \leq t} \tilde{C}_\nu^s(\psi_s(\xi))$$

for every $t \geq T$ and every $\xi \in G$.

In particular, $C_\delta^s(\xi), C_\delta^u(\xi)$ are connected curves with intersect only at ξ , and they depend continuously on $\xi \in G$.

Recall that a point p is *non-wandering* for a flow $\psi_t: N \rightarrow N$ if for every open neighborhood V of p there exists a sequence $\{t_n\}$ of real numbers with $|t_n| \rightarrow +\infty$ and $\psi_{t_n}(V) \cap V \neq \emptyset$.

Proposition 3.1. *Let $\psi_t: N \rightarrow N$ be expansive in N , where $\dim N = 3$. If the set of non-wandering points of ψ_t is dense in N then the set of periodic orbits of ψ_t is also dense.*

Proof. Let $\xi \in G$, $V(\xi)$ and Σ as in Theorem 3.1. From Theorem 3.1(b) there exist projections

$$\begin{aligned} \Pi_s: \Sigma \cap V &\rightarrow C_\delta^s(\xi), \\ \Pi_u: \Sigma \cap V &\rightarrow C_\delta^u(\xi), \end{aligned}$$

defined by $\Pi_s(\zeta) = C_\delta^s(\xi) \cap C_\delta^u(\zeta)$, $\Pi_u(\zeta) = C_\delta^u(\xi) \cap C_\delta^s(\zeta)$ for every $\zeta \in \Sigma \cap V$. Remark that by Theorem 3.1(b), $F[(0,1)^2] = V \cap \Sigma$ is homeomorphic to $C_\delta^s(\xi) \times C_\delta^u(\xi)$: for every $\zeta \in V \cap \Sigma$ there are well-defined coordinates

$$\zeta \rightarrow (\Pi_s(\zeta), \Pi_u(\zeta)).$$

Suppose that ξ is a non-wandering point. Let $P: \Sigma \cap V \rightarrow \Sigma \cap V$ be the Poincaré map of the flow ψ_t . There are sequences $\{\xi_n\}$ of points in Σ such that $\xi_n \rightarrow \xi$, and $\{k_n\}$ of integers with $|k_n| \rightarrow +\infty$ such that $P^{k_n}(\xi_n) \rightarrow \xi$. We can suppose that $k_n \geq 0 \forall n$ without loss of generality. They correspond to sequences $\xi_n \rightarrow \xi$ of points and $t_n \rightarrow +\infty$ such that $\psi_{t_n}(\xi_n) = P^{k_n}(\xi_n)$. Consider an open neighborhood V_α of radius α of ξ with $\bar{V}_\alpha \subset V$. From Theorem 3.1(c) we can deduce that there exist $Q > 0$ such that

- (i) $d(P^{k_n}(\xi_n), \xi) < \frac{\alpha}{4} \forall n \geq Q$,
- (ii) $d(P^{k_n}(C_\delta^s(\xi_n)), P^{k_n}(\xi_n)) < \frac{\alpha}{4} \forall n \geq Q$,
- (iii) $C_\delta^u(\xi) \subset P^{k_n}(C_\delta^u(\xi)) \forall n \geq Q$, $\forall \zeta$ not belonging to the orbit of any η_i (Theorem 3.1(a)). From (i) and (ii) we get that

$$\begin{aligned} &d(P^{k_n}(C_\delta^s(\xi_n)), \xi) < \frac{\alpha}{2}, \\ \rightarrow &P^{k_n}(C_\delta^s(\xi_n)) \subset V_\alpha \end{aligned}$$

for every $n \geq Q$. Let us consider the restriction $\hat{\Pi}_s$ of Π_s to $C_\delta^s(\xi_n)$. From this last statement and (iii) the map Π_s is well defined in the set $P^{k_n}(C_\delta^s(\xi_n)) = P^{k_n}(\hat{\Pi}_s^{-1}(C_\delta^s(\xi)))$ and

$$\Pi_s(P^{k_n}(C_\delta^s(\xi_n))) \subset C_\delta^s(\xi).$$

This implies that the map $\Pi_s \circ P^{k_n} \circ \hat{\Pi}_s^{-1}: C_\delta^s(\xi) \rightarrow C_\delta^s(\xi)$ has a fixed point ξ_0 that, according to the construction, satisfies

$$\begin{aligned} &\xi_0 \subset C_\delta^u(P^{k_n}(\xi_0)) \cap V_\alpha \\ \rightarrow &C_\delta^u(\xi_0) = C_\delta^u(P^{k_n}(\xi_0)) \subset P^{k_n}(C_\delta^u(\xi_0)) \end{aligned}$$

by (iii). But this means that the map

$$P^{-k_n}: C_\delta^u(\xi_0) \rightarrow C_\delta^u(\xi_0)$$

has a fixed point ξ_1 . Since α is arbitrary, and non-wandering points are dense, the periodic orbits are dense as well \square

Corollary 3.1. *If the geodesic flow of a compact surface is expansive, then the closed orbits are dense.*

This is due to the fact that every point of T_1M is non-wandering, so Proposition 3.1 applies with $N = T_1M$ and $\psi_t = \varphi_t$.

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