

THE TOPOLOGY OF COMPLETE ONE-ENDED MINIMAL SURFACES AND HEEGAARD SURFACES IN \mathbf{R}^3

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In this note we announce two fundamental theorems on the topological uniqueness of certain surfaces in \mathbf{R}^3 . The first of these theorems, which will depend on the second theorem, shows that a properly embedded minimal surface in \mathbf{R}^3 with one end is unknotted. More precisely,

Theorem 1.1. *Two properly embedded one-ended minimal surfaces in \mathbf{R}^3 of the same genus are ambiently isotopic¹.*

Theorem 1.1 was conjectured by Frohman [4] who proved it in the case that the surfaces are triply periodic. A result of Callahan, Hoffman, and Meeks (Corollary 2 in [1]) states that a doubly periodic minimal surface has one end and infinite genus, when it is not a plane. Their result and Theorem 1.1 have the following corollary.

Corollary 1.1. *Any two properly embedded nonplanar minimal surfaces in \mathbf{R}^3 that are invariant under at least two linearly independent translations are ambiently isotopic.*

Essential in understanding the uniqueness theorems described here is the concept of a Heegaard surface in a noncompact three-manifold, which generalizes the usual notion of a Heegaard surface M in a closed three-manifold N^3 . Recall that a compact embedded surface M is called a *Heegaard surface* if it separates N^3 into two genus- g handlebodies where g is the genus of M .

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¹Two surfaces in \mathbf{R}^3 are ambiently isotopic if and only if there exists a one-parameter family of diffeomorphisms of \mathbf{R}^3 taking one surface to the other.

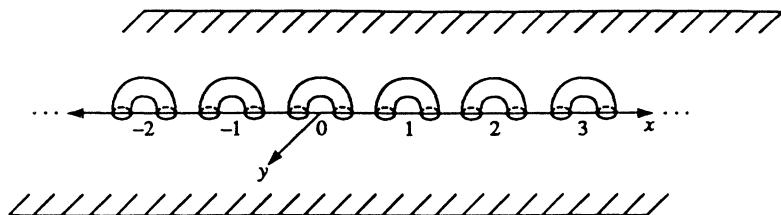


FIGURE 1

Noncompact three-manifolds such as \mathbf{R}^3 fail to have compact Heegaard surfaces. However, there is a natural notion of Heegaard surface for these manifolds where the surface is allowed to be noncompact. We say that a properly embedded surface M is a *Heegaard surface* in \mathbf{R}^3 if the closures of each of the two components of $\mathbf{R}^3 - M$ are handlebodies².

We show that these handlebodies are each diffeomorphic to the three-manifold constructed as follows. Attach g trivial one-handles to the closed lower half-space H in \mathbf{R}^3 where g is the genus of M , possibly infinite. When $g = \infty$, this attaching of handles on H can be performed on neighborhoods of the integer points on the x -axis contained in ∂H to obtain a one-periodic Heegaard surface in \mathbf{R}^3 (see Figure 1). Note that this implies that a Heegaard surface in \mathbf{R}^3 has *one* end.

Our second main theorem is

Theorem 1.2. *Heegaard surfaces of the same genus in \mathbf{R}^3 are ambiently isotopic. Equivalently, given two diffeomorphic Heegaard surfaces in \mathbf{R}^3 , there exists a diffeomorphism of \mathbf{R}^3 that takes one surface to the other surface.*

Before discussing their proofs we wish to put Theorems 1.1 and 1.2 in historical perspective. First Waldhausen [14] proved the topological uniqueness of Heegaard surfaces in the unit three-sphere $S^3 \subset \mathbf{R}^4$. Later Lawson [9], using an argument of Frankel [2], proved that two closed minimal surfaces of genus g in S^3 are Heegaard surfaces and hence isotopic by Waldhausen's theorem. Meeks [10] also proved some related topological uniqueness theorems for compact minimal surfaces with boundary in \mathbf{R}^3 . More recently, Meeks and Yau [12] proved a topological uniqueness re-

²A three-manifold with boundary is a *handlebody* if it is homeomorphic to a closed regular neighborhood of a properly embedded one-dimensional *CW*-complex in \mathbf{R}^3 .

sult for properly embedded minimal surfaces that is closely related to Theorem 1.1. Their main theorem states that two proper diffeomorphic minimal surfaces in \mathbf{R}^3 of finite topology are ambiently isotopic.

We now give a brief outline of the proofs of Theorems 1.1 and 1.2. The main step in the proof of Theorem 1.2 is to show that for every compact subdomain Δ of a Heegaard surface $M \subset \mathbf{R}^3$, there exists a compact ball $B \subset \mathbf{R}^3$ with $\Delta \subset \text{Int}(B)$ and ∂B intersects M transversely in a single simple closed curve. The proof of this step is nontrivial and is proved in part by generalizing a technique due to Haken in his study of Heegaard splittings of reducible three-manifolds [7]. The existence of B , together with Waldhausen's [14] uniqueness of Heegaard splittings of a ball with one boundary curve, implies there exists an exhaustion by balls $B_1 \subset B_2 \subset \dots$ of \mathbf{R}^3 such that $\partial B_i \cap M$ is a simple closed curve, $B_1 \cap M$ is a standard genus-one splitting of B_1 , and $\overline{B_{i+1}} - \overline{B_i} \cap M$ is a standard genus-one splitting of $\overline{B_{i+1}} - \overline{B_i}$. This result implies M is unique up to ambient isotopy.

Theorem 1.1 follows from Theorem 1.2 by proving that a properly embedded minimal surface $M \subset \mathbf{R}^3$ with one end is a Heegaard surface. Suppose M is not a Heegaard surface. Then the closure N of one of the complements of M is not a handlebody. In this case we prove that there must exist a simple closed curve $\gamma \subset M$ that separates $M = \partial N$ and such that γ is the boundary of a properly embedded noncompact stable minimal surface $\Sigma \subset N$ of finite total curvature and Σ is *incompressible* in N . The proof of the existence of Σ is delicate. It relies heavily on the curvature estimates of Schoen [13], the ability to minimize the area of a compact incompressible surface in its isotopy or homotopy class to acquire an embedded least-area surface [3, 11], and the half-space theorem [8] that states that a properly immersed minimal surface contained in a half-space must be a plane. However, using the asymptotic behavior of a finite total curvature surface in N , it is easily shown that no such surface Σ can be incompressible when $M = \partial N$ has one end. This contradiction completes the proof that N must be a handlebody and therefore M is a Heegaard surface. These results appear in [6].

We have also developed some theoretical results to deal with the topology and asymptotic behavior of properly embedded minimal surfaces in \mathbf{R}^3 with more than one end [5]. This work is based

on an ordering theorem for the ends of such a surface. Loosely speaking our main theorem states that, after a rotation of \mathbf{R}^3 , the ends of the surface can be ordered by their heights over the (x_1, x_2) -plane. In order to make precise the statement of the theorem, one needs the concept of a limit tangent plane for a properly embedded minimal surface. This definition, as well as the proof of existence and uniqueness of *the* limit tangent plane when the minimal surface has more than one end, is given in [1].

Theorem 1.3 (Ordering Theorem). *Suppose M is a properly embedded minimal surface in \mathbf{R}^3 with more than one end and whose limit tangent plane is the (x_1, x_2) -plane. Then the ends of M are naturally ordered by their “height” over the (x_1, x_2) -plane.*

We then go on to prove that the above ordering is a topological one:

Theorem 1.4. *Suppose M_1 and M_2 satisfy the hypotheses of M in Theorem 1.3 and $F: \mathbf{R}^3 \rightarrow \mathbf{R}^3$ is a diffeomorphism such that $F(M_1) = M_2$. Then F preserves or reverses the natural ordering of the ends of M_1 and M_2 . In particular, if M satisfies the hypotheses of Theorem 1.3 and $F: \mathbf{R}^3 \rightarrow \mathbf{R}^3$ is a diffeomorphism such that $F(M) = M$, then F preserves or reverses the ordering of the ends of M .*

Conjecture 1.1. The ordering of ends of M given in Theorem 1.3 is almost a well-ordering in the sense that it is equivalent to the ordering on a closed subset \mathcal{S} of the interval $[0, 1]$ with $\mathcal{S} \cap (0, 1)$ discrete. In particular, M can only have a countable number of ends.

The ordering theorem is proved by first showing that the ends of the surface M can be separated by a collection, possibly infinite, of pairwise disjoint stable minimal surfaces Σ_i , each of which is asymptotic to an end of a plane or catenoid. Since the Σ_i are disjoint and asymptotic to planes and ends of catenoids, eventually they are “parallel.” We use this to define an ordering of the ends of M . The construction of the surfaces Σ_i is based on earlier work in [1, 12].

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