BROWNIAN MOTION, GEOMETRY, AND GENERALIZATIONS OF PICARD'S LITTLE THEOREM

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ABSTRACT. Brownian motion is introduced as a tool in Riemannian geometry, and it is shown to be useful in the function theory of manifolds, as well as in the study of maps between manifolds. As applications, a generalization of Picard's little theorem, and a version of it for Riemann surfaces of large genus are given.

1. Picard's theorem for nonhyperbolic manifolds. Let M and N be complete Riemannian manifolds with metrics Mg , Ng , resp. Assume $F: M \longrightarrow N$ is a C^2 map. F is said to be harmonic [2] if its second fundamental form has trace 0. Define the tensor

$$\xi^{\alpha\beta}(x) = {}^{M}g_{ij} \left[\frac{\partial F^{\alpha}}{\partial x^{i}} \frac{\partial F^{\beta}}{\partial x^{j}} \right](x), x \in M.$$

Since $(\xi^{\alpha\beta}(x))$ is a symmetric matrix, its eigenvalues are nonnegative, and we may order them as follows: $\lambda_1(x) \ge \lambda_2(x) \ge \cdots \ge \lambda_n(x) \ge 0$. F is said to be K-quasiconformal [5] if $\lambda_1(x) \le K^2 \lambda_n(x)$ for all $x \in M$.

We define polar coordinates (r, θ) on N via the exponential map. There will be two restrictions on the curvature of N:

- (i) The sectional curvatures of N are bounded below by $-L^2 < 0$.
- (ii) Each of the sectional curvatures at $(r, \theta) \in N$ determined by dr and some other tangent vector, is bounded above by K(r), where K(r) satisfies (a) for some $\epsilon > 0$, $-K(r) \sim r^{2\epsilon-2}$; (b) there exists a C^{∞} solution u(r) of the equation

$$u''(r) = K(r)u(r), \quad u(0) = 0, \quad u'(0) = 1,$$

and u'(r) is always positive.

(Note that such a solution can always be found if K(r) is negative.)

THEOREM 1. Suppose M and N are as above with the curvature of N satisfying (i) and (ii). Then, if Brownian motion on M has trivial tail σ -field, every K-quasiconformal harmonic map $F: M \longrightarrow N$ is constant.

Received by the editors January 26, 1982 and, in revised form, March 23, 1982.

¹⁹⁸⁰ Mathematics Subject Classification. Primary 32H25, 53C21, 60J65.

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2. Proof of Theorem 1. The following lemmas are essential.

LEMMA 2. Let X_t be Brownian motion on M, with X_0 chosen so that $F(X_0) = x_N \in N \setminus \{x_0\}$. Then, there is a random time change $\sigma(t) (= \int_0^t ds/\lambda_1(x_s))$ and a constant C > 0, such that if $\rho_t = r \circ F(X_{\sigma(t)}), d\rho_t = a(X_{\sigma(t)})dB_t + b(X_{\sigma(t)})dt$, when $F(X_t) \neq x_0$, where B_t is some Brownian motion, $1/K \leq |a(X_{\sigma(t)})| \leq 1$ and $b(X_{\sigma(t)}) \geq C\rho_t^{\epsilon/2-1}$ if ρ_t is larger than some constant R.

The statement uses the stochastic calculus discussed in [8].

Let τ be a stopping time for $X_{\sigma(t)}$.

LEMMA 3. If $\rho_t^{(\tau)}$ is the distance of $F(X_{\sigma(t)})$ from $F(X_{\sigma(\tau)})$, then for $t > \tau$ and $\rho_t^{(\tau)} \neq 0$, $d\rho_t^{(\tau)} = a^{(\tau)}(X_{\sigma(t)})dB_t^{(\tau)} + b^{(\tau)}(X_{\sigma(t)})dt$, where $1/K \leq |a^{(\tau)}(X_{\sigma(t)})| \leq 1$ and $|b^{(\tau)}(X_{\sigma(t)})| \leq (n/2)L$ coth $L\rho_t^{(\tau)}$.

The proofs of Lemmas 2 and 3 require Ito's lemma, the K-quasiconformal condition, and the Hessian comparison theorem of Greene and Wu [3]. Lemma 2 is used to determine the speed with which ρ_t goes to ∞ .

LEMMA 4.
$$\liminf_{t\to\infty} \rho_t/t^{2/4-\epsilon} > c > 0$$
.

Lemma 4 will be required in the proof of

Lemma 5. Let τ_Q be the first time that $\rho_t \ge Q$. Then, for h sufficiently large, there is a $q \in (0, 1)$ and a constant C_1 such that

$$P\{\rho_{t+\tau_{O}} > C_{1}(t+h)^{2/4-\epsilon} \text{ for } t > 0 \mid X_{\sigma(\tau_{O})}\} > q$$

uniformly in $X_{\sigma(\tau_O)}$.

LEMMA 6. Let $r = \inf(r(x), r(y))$ for $x, y \in N$. If $|\Theta(x, y)|$ denotes the angular distance between $\theta(x)$ and $\theta(y)$, then for some constants C and R, r > R,

$$|\Theta(x, y)| \le C \frac{N_d(x, y)}{\exp(r^{\epsilon})}$$
,

where ^Nd denotes the distance in the manifold N.

PROOF. We use the Rauch comparison theorem for the same comparison manifold P as is used in the proof of Lemma 2.

LEMMA 7. There exists a random time T such that for all m > T,

$$\sup_{\sigma(m) \leq t \leq \sigma(m+1)} {}^N d(F(X_t), F(X_{\sigma(m)})) \leq m.$$

PROOF. Using Lemma 3, we must show, for m > T, that $\sup_{m \le t \le m+1} \rho_t^{(m)} \le m$. The argument is similar to an idea of Prat [11], and is also used by Kendall [7] and Pinsky [10].

LEMMA 8. Fix $\delta > 0$. If τ is a stopping time, we may choose an integer J so large that

$$P\{\sup_{\tau \leq t-m \leq \tau+1} \rho_t^{(\tau+m)} \leq m+J, \text{ for all } m \geq 1\} \geq 1-\delta.$$

Lemmas 4–8, and a result of Stroock and Varadhan [12, Theorem 3.1] show that the tail σ -field $\lim_{t\to\infty} \theta(F(X_t))$ of X_t exists and is nontrivial. This is a contradiction, so F must be constant.

3. Picard's theorem for Riemann surfaces of large genus. In the sequel, let M and N be compact Riemann surfaces with a finite number of points deleted. Any such surface N is homeomorphic to a sphere with t(N) tori attached and p(N) points deleted. Let n(N) = 2t(N) + p(N).

THEOREM 2. Let $F: M \to N$ be a holomorphic map. If t(M) > 0, p(M) > 0, p(N) > 1, and p(N) - p(M) > 0, then F is constant.

PROOF OF THEOREM 2. The proof uses Brownian motion on Riemann surfaces, which can be defined as follows. Let $\{m_i\}$ be coordinate patches on M, and for each i, let $c_i : m_i \to C$, where C is the complex plane, be a holomorphic map. For $p \in M$, choose a patch $m_{i(1)}$ containing p. Let W(t) be Brownian motion in C, and let σ_1 be the first time that p + W(t) hits the boundary of $c_{i(1)}(m_{i(1)})$. For $0 \le t \le \sigma_1$, let $B(t) = c_{i(1)}^{-1}(p + W(t))$. Next, let $m_{i(2)}$ be a patch containing $B(\sigma_1)$, and let σ_2 be the first time that $c_{i(2)}(B(\sigma_1)) + W(t) - W(\sigma_1)$ hits the boundary of $m_{i(2)}$. For $\sigma_1 \le t \le \sigma_2$, let

$$B(t) = c_{i(2)}^{-1}(c_{i(2)}(B(\sigma_1)) + W(t) - W(\sigma_1)),$$

and note that we have defined B(t) to be continuous at σ_1 . For k > 2, define σ_k and B(t), $\sigma_k \le t \le \sigma_{k+1}$, analogously.

We also need

LEMMA 9. Let p(N) > 0. Then the fundamental group of N is the free group with n(N) - 1 generators. The generators may be taken to be the cycles around single points (except one) and the canonical generators of the tori.

Suppose F is not constant. Let G(M) be the fundamental group of M with base point p, and let G(N) be the fundamental group of N with base point F(p). Let $\{\alpha_i^M\}$, $\{\alpha_i^N\}$ be the generators of G(M), G(N), resp., as described in Lemma 9. Choose 2 generators α_1^M , α_2^M of G(M) which are generators of a torus, and let α_3^M , ..., $\alpha_{n(M)-1}^M$ be the remaining generators. Let H(M) be the smallest normal subgroup of G(M) containing α_3^M , ..., $\alpha_{n(M)-1}^M$ and the commutator [G(M), G(M)]. Let $\hat{G}(M) = G(M)/H(M)$, and note that $\hat{G}(M)$ is isomorphic to $\mathbb{Z} \times \mathbb{Z}$.

Let 0, 0_2 , 0_3 be neighborhoods of p, contained in $m_{i(1)}$, whose images under $c_{i(1)}$ are discs of radii ϵ , 2ϵ , 3ϵ , respectively. Let $B^Q(t)$ be the Brownian motion on M whose initial distribution B(0) is the measure Q, concentrated on the boundary of 0. Let $\tau_0 = 0$; given τ_i , let τ_{i+1} be the first time after τ_i for which $B(\tau_{i+1}) \in \partial 0$, and $\{B(t): \tau_i \leq t \leq \tau_{i+1}\}$ corresponds to a nontrivial element of $\hat{G}(M)$. Note that since M is compact except for deleted points, all τ_i are finite.

Next, let $x_n = B^Q(\tau_n)$, and note that x_n is a Markov process with respect to the fields $\sigma\{B(t): t \leq \tau_n\}$. Let m be the measure on $\partial \mathcal{O}$ induced by Lebesgue measure on the circle $c_{i(1)}(\partial \mathcal{O})$. By a theorem of Harris [6], it can be shown that x_n has an invariant measure. We set Q equal to this measure.

Let \hat{X}_i be the element of $\hat{G}(M)$ corresponding to $\{B^Q(t): 0 \le t \le \tau_i\}$. Since $\hat{G}(M) \cong \mathbb{Z} \times \mathbb{Z}$, we may regard \hat{X}_i as a random walk on \mathbb{R}^2 . Let $\Delta_i = \hat{X}_i - \hat{X}_{i-1}$. Then, $\{\Delta_i\}$ is a stationary process with $E|\Delta_i|^4 < \infty$. Moreover the process is symmetric, so Δ_i and $-\Delta_i$ have the same distribution. Using the central limit theorem (see Theorem 9 of Phillip [9]), it is shown that \hat{X}_i is recurrent. By Lemma 3.1 of [1], it follows that X_i is recurrent.

Now, F induces a map F_H from H/[H, H] to G(N)/[G(N), G(N)]. Since these are commutative groups with difference in dimension at least 3, it follows that there must be at least 3 generators α_1^N , α_2^N , α_3^N of G(N) which generate a subgroup of G(N)/[G(N), G(N)] modulo $F_H(H/[H, H])$ isomorphic to $\mathbf{Z} \times \mathbf{Z} \times \mathbf{Z}$. Let H(N) be the smallest normal subgroup of G(N) containing α_4^N , ..., $\alpha_{n(N)-1}^N$ and G(N), G(N), and let G(N) = G(N)/H(N). Then, F induces a map F from G(M) to G(N).

Using Brownian motion on N, we construct as before an invariant measure Q on $F(\mathcal{O})$ and a random walk \hat{Y}_i from F(B(t)). By a theorem of Lévy [1], F(B(t)) is Brownian motion on N with a new time scale. By the Borel-Cantelli lemma, \hat{Y}_i is transient. Davis's argument [1] then shows that the random walk Y_i induced by F(B(t)) with B(0) = p is also transient. But then $\hat{F}(X_i) = Y_i$, and X_i is recurrent. This contradiction shows that F must be constant.

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