

GLOBAL RESULTS IN CONTROL THEORY WITH APPLICATIONS TO UNIVALENT FUNCTIONS

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1. A problem in control theory. Many classical coefficient problems in the theory of univalent functions can be stated as the following control problem. Consider a first order differential system

$$dx/dt = f(x, u(t)),$$

where $x = (x_1, \dots, x_n)$, $u = (u_1, \dots, u_m)$ and $f(x, u) = (f_1(x, u), \dots, f_n(x, u))$ are real valued vectors. Assume that f is continuous on $R^n \times R^m$ and for fixed u , $f \in C^1(R^n)$. The values of $u(t)$ are in a compact domain $U \subset R^m$. Denote by \bar{F} the class of all piecewise continuous functions $u(t)$ for $t \geq 0$ with the values in U . Let $x(t)$ satisfy a fixed initial condition $x(0) = \xi$. Denote by $x(t, u)$ the solution of the system above for a given $u(t)$ in \bar{F} . Let $F(x) = F(x_1, \dots, x_n)$ belong to $C^1(R^n)$.

THEOREM 1. *Let $u^* = u^*(t)$ be a solution of the problem $\sup_{\bar{F}} F(x(T, u)) = F(x(T, u^*))$, for $T > 0$. Consider the system*

$$dx/dt = f(x, u^*(t)), \quad x(\tau) = \eta$$

for $0 \leq \tau \leq T$. Define a function F_τ by the equality $F_\tau(\eta) = F(x(T))$. Then $x(\tau, u^)$ solves the problem $\sup_{\bar{F}} F_\tau(x(\tau, u)) = F_\tau(x(\tau, u^*))$.*

The proof of the theorem follows by considering the functions $u(t)$ such that $u(t) = u^*(t)$ for $\tau < t \leq T$. In case where $f(x, u) = A(u)x$ and $F(x) = \lambda'_0 x$ Theorem 1 has a very simple form. Here $A(u) = (a_{ij}(u))_1^n$ and $a_{ij}(u) \in C(R^m)$. By A' and λ' we denote the corresponding transposed matrix and vector.

THEOREM 2. *Consider a control system $dx/dt = A(u(t))x$. Let $u^*(t)$ solve the linear problem*

$$\sup_{\bar{F}} \lambda'_0 x(T, u) = \lambda'_0 x(T, u^*).$$

Then $x(\tau, u^)$ solves the linear problem*

$$\sup_{\bar{F}} \lambda'(\tau)x(\tau, u) = \lambda'(\tau)x(\tau, u^*),$$

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$0 < \tau < T$, where $\lambda(t)$ is the solution of $d\lambda/dt = -A'(u^*)\lambda$, $\lambda(T) = \lambda_0$.

2. Univalent functions. Denote by S the set of all analytic univalent functions $f(z) = z + \sum_{k=2}^{\infty} a_k z^k$ in the unit disc D . Let f be a slit function, i.e. f maps D onto a slit domain. According to Loewner [1] f can be embedded in a semigroup of univalent functions $g(z, t) = e^t(z + \sum_{k=2}^{\infty} a_k(t)z^k)$ which satisfies the equation

$$\frac{\partial g}{\partial t} = z \frac{\partial g}{\partial z} \frac{1 + e^{i\varphi(t)}z}{1 - e^{i\varphi(t)}z}, \quad g(z, 0) = f(z).$$

Here $\varphi(t)$ is a real piecewise continuous function for $t \geq 0$. Denote by A_n the set of vectors $a^{(n)} = (a_1, \dots, a_n)$, ($a_1 = 1$) which are the first n coefficients of some f in S . Let $f(z, t) = e^{-t}g(z, t) = z + \sum_{k=2}^{\infty} a_k(t)z^k$. Then $a^{(n)}(t)$ satisfies the system

$$da^{(n)}(t)/dt = e^{i\varphi(t)G_n} A_n e^{-i\varphi(t)G_n} a^{(n)}(t), \quad a^{(n)}(0) = a^{(n)}.$$

Here $A_n = (a_{kj})_1^n$ and $G_n = (d_k \delta_{kj})_1^n$ are the matrices: $a_{kj} = 0$ for $j > k$, $a_{kk} = k - 1$, $a_{kj} = 2j$ for $j < k$, $d_k = k - 1$, $k, j = 1, \dots, n$. The following result is basic for applications of the method of control theory to coefficient problems for univalent functions.

THEOREM 3. *Let $\varphi(t)$ be a real measurable function for $t \geq 0$. Consider the system $da^{(n)}/dt = -e^{i\varphi(t)G_n} A_n e^{-i\varphi(t)G_n} a^{(n)}$ for $t \geq 0$.*

Then (i) A_n is invariant under the flow defined by the system above. That is, if $a^{(n)}(0) \in A_n$ then $a^{(n)}(t) \in A_n$ for any $t > 0$.

(ii) Let $\alpha^{(n)} \in A_n$ and consider the set of all possible paths $a^{(n)}(t)$ starting from the point $\alpha^{(n)}$ for all choices of φ . Then this set is dense in A_n .

Let $a_*^{(n)} = (a_1^*, \dots, a_n^*)$ be a boundary point of A_n . According to [2], the corresponding function $f^*(z) = z + \sum_{k=2}^{\infty} a_k^* z^k$ is a slit function. So $f^*(z)$ generates the corresponding $\varphi^*(t)$ which appears in the Loewner equation. Using Theorems 2 and 3, we obtain

THEOREM 4. *Let $a_*^{(n)}$ solve the problem*

$$\max_{A_n} \operatorname{Re} \left\{ \sum_{k=1}^n \lambda_k^0 a_k^* \right\} = \operatorname{Re} \left\{ \sum_{k=1}^n \lambda_k^0 a_k^* \right\}$$

subject to m constraints $a_k = a_k^$, $k = 1, \dots, m$, ($m \leq n - 1$). Let $a^{(n)}(t)$ be generated by the Loewner equation*

$$da^{(n)}/dt = e^{i\varphi^*(t)G_n} A_n e^{-i\varphi^*(t)G_n} a^{(n)}, \quad a^{(n)}(0) = a_*^{(n)}.$$

Define $\lambda^{(n)}(t)$ to be

$$d\lambda^{(n)}/dt = -e^{-i\varphi^*(t)G_n} A_n' e^{i\varphi^*(t)G_n} \lambda^{(n)}, \quad \lambda^{(n)}(0) = \lambda_0^{(n)}.$$

Then $a^{(n)}(t)$ solves the problem

$$\max_{A_n} \operatorname{Re} \left\{ \sum_{k=1}^n \lambda_k(t) a_k \right\} = \operatorname{Re} \left\{ \sum_{k=1}^n \lambda_k(t) a_k(t) \right\}$$

$$a_k = a_k(t), \quad k = 1, \dots, m, \text{ for } t > 0.$$

In particular we obtain that if $a_*^{(n)}$ is a supporting point of A_n , so is $a^{(n)}(t)$ for $t > 0$ [2, 10.3]. Let $\xi^k = (0, \dots, 0, 1, \xi_{k+2}^k, \dots, \xi_n^k)$ and $\eta^k = (\eta_1^k, \dots, \eta_k^k, 1, 0, \dots, 0)$, $k = 0, \dots, n - 1$, where

$$\xi_r^k = (-1)^k \binom{r+k}{r-k-1}, \eta_r^k = (-1)^{r-1} \frac{r}{k+1} \binom{2k+2}{k-r+1}.$$

THEOREM 5. Assume that the Koebe function $K(z) = z/(1-z)^2$ solves a linear problem

$$\max_{A_n} \operatorname{Re} \{ \lambda^{(n)'} a^{(n)} \} = \operatorname{Re} \{ \lambda^{(n)'} e^{(n)} \}$$

where $e^{(n)} = (1, 2, \dots, n)$.

Then the Koebe function also satisfies $\max_{A_n} \operatorname{Re} \{ \lambda^{(n)}(x)' a^{(n)} \} = \operatorname{Re} \{ \lambda^{(n)}(x)' e^{(n)} \}$, for $0 < x < 1$, where $\lambda^{(n)}(x) = \sum_{r=0}^{n-1} x^r (\lambda^{(n)'} \xi^r) \eta^r$. In particular, if $\operatorname{Re} \{ a_n \} \leq n$, then

$$\begin{aligned} & \operatorname{Re} \left\{ \sum_{r=0}^{n-1} (-1)^r x^r \binom{n+r}{n-r-1} [(\eta^r)' a^{(n)}] \right\} \\ & \leq \operatorname{Re} \left\{ \sum_{r=0}^{n-1} (-1)^r x^r \binom{n+r}{n-r-1} [(\eta^r)' e^{(n)}] \right\}, \quad \text{for } 0 < x < 1. \end{aligned}$$

Thus, from $\operatorname{Re} \{ a_4 \} \leq 4$ we obtain the inequality

$$\begin{aligned} & \operatorname{Re} \{ x^2 a_4 + 6x(1-x)a_3 + 2(7x^2 - 12x + 5)a_2 \} \\ & \leq 14x^2 - 30x + 20 \end{aligned}$$

for $0 < x < 1$. The full details and the proofs will appear elsewhere.

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