METRIC PROPERTIES OF A CLASS OF QUADRATIC DIFFERENTIAL FORMS

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Introduction. In the present paper a new invariant quadratic differential form Ω is geometrically defined for a general pair of surfaces S, S' whose corresponding points x, x' determine the metric normal to S at x. The ratio of the form Ω to the first fundamental form ds^2 of S, in which Ω and ds^2 are defined for a common arc element of S at x, is found to be independent of the direction of the element if and only if the surface S' is the locus of the center of mean curvature of S; the ratio thus determined is the Gaussian curvature K of S at x. We introduce at a point x of S the concept of conjugate elements of a given arc element of a conjugate net and prove that the form Ω for an arbitrary arc element is identical with the form Kds^2 for either conjugate element if and only if the surface S' is the plane net at infinity. The principal directions at x of the tensor whose components are the coefficients of the form Ω are the classical principal directions of S at x for an arbitrary choice of S'. Finally, we characterize the net of lines of mean-curvature of S and the mean-conjugate net of S as integral nets of equations of the form $\Omega = 0$, in which the forms Ω are defined with respect to certain geometrically determined transforms S' of S. The method of the present paper employs dual systems of linear homogeneous equations of the first order in compact forms which facilitate the use of a tensor notation with homogeneous cartesian point and plane coordinates.

1. The fundamental differential equations. The rectangular cartesian coordinates of a generic point x of an analytic surface S are defined by single-valued functions of two independent parameters u^1, u^2,

$$x^i = x^i(u^1, u^2), \qquad i = 0, 1, 2.$$

Let $g_{\alpha\beta}$ and $g^{\alpha\beta}$ denote the covariant and contravariant metric tensors of S, respectively, and let $d_{\alpha\beta}$ denote the second fundamental covariant tensor of S. It is known [1, p. 220][1] that the direction cosines z^i of the normal to S at x and the functions x^i are solutions of the differential equations

$$(1.1) \quad \frac{\partial^2 x}{\partial u^\beta \partial u^\alpha} = \left\{ \begin{matrix} \gamma \\ \alpha\beta \end{matrix} \right\} \frac{\partial x}{\partial u^\alpha} + d_{\alpha\beta}z, \quad \frac{\partial z}{\partial u^\alpha} = \left(\begin{matrix} \beta \\ 3\alpha \end{matrix} \right) \frac{\partial x}{\partial u^\beta}, \quad \alpha, \beta, \gamma = 1, 2,$$

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[1] Numbers in brackets refer to the bibliography at the end of the paper.

where the functions

$$\begin{Bmatrix} \gamma \\ \alpha\beta \end{Bmatrix}$$

are the Christoffel symbols of the second kind formed with respect to the first fundamental form of S and the functions

$$\begin{pmatrix} \beta \\ 3\alpha \end{pmatrix}$$

are components of the mixed tensor defined by

$$\begin{pmatrix} \beta \\ 3\alpha \end{pmatrix} = -d_{\alpha\gamma}g^{\gamma\beta}.$$

Homogeneous cartesian coordinates of a finite point of space may be obtained by adjoining to the three ordinary rectangular coordinates x^0, x^1, x^2 a fourth coordinate $x^3 = 1$. For a point at infinity the homogeneous cartesian coordinates are of the form x^0, x^1, x^2, 0. The point at infinity on the normal to S at x has homogeneous cartesian coordinates z^0, z^1, z^2, 0. As x moves over S this point at infinity describes the plane net S_z at infinity. We observe that the system (1.1) is satisfied by each pair of homogeneous coordinates x^i, z^i, $i = 0, 1, 2, 3$. *Thus the surface S and the corresponding plane net S_z at infinity generated by the infinite point on the normal to S at x are integral surfaces of the system* (1.1).

Let us define points x_0, x_1, x_2, x_3 by the relations

$$(1.2) \qquad x = x_0, \qquad \frac{\partial x_0}{\partial u^\alpha} = x_\alpha, \quad \alpha = 1, 2, \qquad z = x_3.$$

These relations enable us to put the system (1.1) in the form of the following system of linear homogeneous differential equations of the first order,

$$(1.3) \qquad \frac{\partial x_i}{\partial u^\alpha} - \begin{pmatrix} h \\ i\alpha \end{pmatrix} x_h = 0, \qquad i, h = 0, 1, 2, 3; \alpha = 1, 2,$$

where

$$\begin{pmatrix} h \\ 0\alpha \end{pmatrix} = \delta_\alpha^h, \quad \begin{pmatrix} 0 \\ i\alpha \end{pmatrix} = 0, \quad \begin{pmatrix} 3 \\ 3\alpha \end{pmatrix} = 0;$$

$$\begin{pmatrix} \gamma \\ \alpha\beta \end{pmatrix} = \begin{Bmatrix} \gamma \\ \alpha\beta \end{Bmatrix}, \quad \begin{pmatrix} 3 \\ \alpha\beta \end{pmatrix} = d_{\alpha\beta}, \quad \begin{pmatrix} \beta \\ 3\alpha \end{pmatrix} = -d_{\alpha\gamma}g^{\gamma\beta}, \qquad \alpha, \beta, \gamma = 1, 2.$$

Let $|x|$ denote the determinant whose elements are the functions $x_i^{(p)}$ and let ξ_i^r denote the normalized cofactor of x_j^i in $|x|$, defined by the relations

$$(1.4) \qquad\qquad \xi_i^r x_h^i = \delta_h^r, \qquad\qquad h, r = 0, 1, 2, 3,$$

in which the right members are the Kronecker deltas. The functions ξ_i^r, $i = 0, 1, 2, 3$, form a set of homogeneous cartesian plane coordinates of the plane determined by the three points x_h, $h \neq r$. Differentiating (1.4) with respect to u^α and making use of (1.3), we obtain

$$(1.5) \qquad\qquad x_h^i \frac{\partial \xi_i^r}{\partial u^\alpha} + \binom{r}{h\alpha} |x| = 0.$$

On forming the inner product of the left member of this equation with ξ_k^h and dividing by $|x|$, we find that the plane coordinates ξ_k^r are solutions of the system of equations

$$(1.6) \qquad\qquad \frac{\partial \xi^r}{\partial u^\alpha} + \xi^h \binom{r}{h\alpha} = 0, \qquad\qquad \alpha = 1, 2.$$

A relation of the form

$$(1.7) \qquad\qquad x' = z + kx,$$

where k is an arbitrary function of u^1, u^2, defines the general coordinates of a point x' which is collinear with x and z and generates a surface S' as u^1, u^2 vary. For the sake of convenience we denote the points x, x_1, x_2, x' by y_0, y_1, y_2, y_3, respectively, so that the fundamental differential equations (1.3) may be written in the form

$$(1.8) \qquad \frac{\partial y_i}{\partial u^\alpha} - \binom{h}{i\alpha}' y_h = 0; \qquad i, h = 0, 1, 2, 3; \alpha = 1, 2,$$

in which

$$\binom{h}{0\alpha}' = \delta_\alpha^h, \quad \binom{0}{\alpha\beta}' = -k\binom{3}{\alpha\beta}, \quad \binom{\gamma}{\alpha\beta}' = \left\{\begin{matrix}\gamma\\\alpha\beta\end{matrix}\right\}, \quad \binom{0}{3\alpha}' = \frac{\partial k}{\partial u^\alpha},$$

$$\binom{\alpha}{3\alpha}' = k + \binom{\alpha}{3\alpha}, \quad \binom{3}{\alpha\beta}' = \binom{3}{\alpha\beta}, \quad \binom{3}{3\alpha}' = 0, \quad \alpha, \beta, \gamma = 1, 2;$$

$$\binom{\beta}{3\alpha}' = \binom{\beta}{3\alpha}, \qquad\qquad \alpha, \beta = 1, 2, \alpha \neq \beta.$$

Let $|y|$ denote the determinant whose elements are the functions y_i^p, i, $p = 0, 1, 2, 3$, and let η_i^i denote the normalized cofactor of y_j^i

in $|y|$. The functions η_i^r, $i=0, 1, 2, 3$, are homogeneous plane coordinates of the plane determined by the three points y_h, $h \neq r$. The differential equations satisfied by the functions η_i^r are easily found to be

$$(1.9) \qquad \frac{\partial \eta^r}{\partial u} + \eta^h \begin{pmatrix} r \\ h\alpha \end{pmatrix}' = 0.$$

2. **The invariant quadratic differential form.** Let x', X' denote the points of S' whose curvilinear coordinates are u^1, u^2 and u^1+du^1, u^2+du^2, respectively, and let π, p denote the corresponding tangent planes of S. Let l denote the line joining the points x' and X' and let y and Y denote the intersections of l with the planes π and p, respectively. We prove the following theorem.

THEOREM 1. *The principal part of the cross ratio (x', y, X', Y) is the quadratic differential invariant*

$$\Omega = a_{\alpha\beta}du^\alpha du^\beta,$$

where $a_{\alpha\beta}$ is the tensor defined by

$$a_{\alpha\beta} = kd_{\alpha\beta} - h_{\alpha\beta},$$

in which $d_{\alpha\beta}$ is the second fundamental tensor of S and $h_{\alpha\beta}$ is the first fundamental tensor of the spherical representation of S.

Except for terms of order at least two, the point coordinates of X' and the plane coordinates of π and p are given by

$$X' = y_3 + \begin{pmatrix} h \\ 3\alpha \end{pmatrix}' y_h du^\alpha, \qquad \begin{pmatrix} 3 \\ 3\alpha \end{pmatrix}' = 0,$$

and

$$\pi = \eta^3, \qquad p = \eta^3 - \eta^h \begin{pmatrix} 3 \\ h\alpha \end{pmatrix}' du^\alpha,$$

respectively. The homogeneous cartesian coordinates of y, except for terms of order at least two, are obviously given by the form

$$y = \begin{pmatrix} h \\ 3\alpha \end{pmatrix}' y_h du^\alpha.$$

The coordinates of Y are defined by a relation of the form

$$Y = y + \Omega y_3$$

such that the condition $Y^i p_i = 0$ is fulfilled. The function Ω is, therefore, the root of the equation

$$\left(\Omega y_3^i + \binom{h}{3\beta}' y_h^i du^\beta\right)\left(\eta_i^3 - \eta_i^h\binom{3}{h\alpha}' du^\alpha\right) = 0.$$

Since $y_j^i \eta_i^p = \delta_j^p$, multiplication of the factors of the left member yields

$$(2.1) \qquad\qquad \Omega = \binom{h}{3\beta}'\binom{3}{h\alpha}' du^\beta du^\alpha.$$

On making use of the relations between corresponding coefficients of (1.7) and (1.3) we obtain the form

$$(2.2) \qquad\qquad \Omega = a_{\alpha\beta} du^\alpha du^\beta,$$

where $a_{\alpha\beta} = kd_{\alpha\beta} - g^{\delta\gamma} d_{\delta\beta} d_{\gamma\alpha}$. It is known [1, p. 253] that the first fundamental tensor of Gauss's spherical representation of S is defined by

$$(2.3) \qquad\qquad h_{\alpha\beta} = g^{\delta\gamma} d_{\delta\beta} d_{\gamma\alpha}.$$

The proof of the theorem is, therefore, complete.

3. New geometric characterizations of the form Kds^2. The plane at infinity is the surface S' for which $k = 0$. The associated tensor $a_{\alpha\beta}$ is, therefore, defined by

$$(3.1) \qquad\qquad a_{\alpha\beta} = -h_{\alpha\beta},$$

and *the invariant* $-\Omega$ *is identical with the first fundamental form of the spherical representation of* S.

It is known that for a unique conjugate parametric net, namely, the mean-conjugate net, the first fundamental form of the spherical representation is expressible in the form

$$d\bar{s}^2 = \sigma^2(g_{11}(du^1)^2 - 2g_{12} du^1 du^2 + g_{22}(du^2)^2).$$

Let us determine all of the parametric nets on an unspecialized surface S for which Ω is expressible in the form

$$(3.2) \qquad \Omega = \phi(g_{11}(du^1)^2 - 2g_{12} du^1 du^2 + g_{22}(du^2)^2).$$

The conditions to be fulfilled are represented by the relations

$$(3.3) \qquad\qquad h_{11}/g_{11} = -h_{12}/g_{12} = h_{22}/g_{22}.$$

It is known [1, p. 253] that the tensor $h_{\alpha\beta}$ may be expressed in terms of the first and second fundamental tensors by means of the relation

$$(3.4) \qquad\qquad h_{\alpha\beta} = d_{\alpha\beta} K_m - g_{\alpha\beta} K$$

in which K and K_m are the Gaussian curvature and mean curvature of

S defined by

(3.5)
$$K = (d_{11}d_{22} - d_{12}^2)/g,$$
$$K_m = 2(g_{11}d_{22} - g_{12}d_{12})/g.$$

Equations (3.3), if $h_{\alpha\beta}$ is replaced by the right members of (3.4), assume the forms

(3.6)
$$K_m(g_{22}d_{11} - g_{11}d_{22}) = 0,$$
$$K_m(d_{11}g_{12} + g_{11}d_{12}) = 2Kg_{11}g_{12},$$
$$K_m(d_{22}g_{12} + g_{22}d_{12}) = 2Kg_{12}g_{22}.$$

On substituting the right members of (3.5) in equations (3.6) and simplifying, we obtain the relations

(3.7)
$$g_{22}d_{11} - g_{11}d_{22} = 0,$$
$$d_{11}d_{12} = d_{12}d_{22} = 0.$$

These relations are satisfied if $d_{11} = d_{22} = 0$, $d_{12} \neq 0$, that is, if the asymptotic curves of S are parametric. If, however, the asymptotic curves of S are not the parametric curves of S, the first of equations (3.7) is the condition that the parametric net be a duametric net [2, p. 308]; the second and third conditions insure that the parametric net be a conjugate net. Hence, in this case, the parametric net is the unique conjugate duametric net of S, that is, *the mean-conjugate net of S*. We have, therefore, that Ω *assumes the form* (3.2) *when S' is the plane net at infinity if, and only if, the parametric net of S is either the asymptotic net or the mean conjugate net.* For the case of the asymptotic parametric net $\phi = K$ and for the mean conjugate parametric net $\phi = -K$.

The result described above in terms of the asymptotic parametric net leads to the following geometric determination of the invariant Kds^2. Let C_λ, $C_{-\lambda}$ denote the curves which pass through x of the conjugate net defined by

(3.8) $$(du^2)^2 - \lambda^2(du^1)^2 = 0$$

whose directions at x are λ, $-\lambda$, respectively. Let x and P denote the points of S whose curvilinear coordinates are u^1, u^2 and $u^1 + du^1$, $u^2 + du^2$, respectively. The u^1 and u^2 asymptotic curves which pass through P intersect the curve $C_{-\lambda}$ in the points Q, Q' whose curvilinear coordinates are $u^1 - du^1$, $u^2 + du^2$, and $u^1 + du^1$, $u^2 - du^2$, respectively. We shall call the elements xQ and xQ' the conjugate elements of xP. We are able now to describe our characterization of Kds^2 by means of the following theorem.

THEOREM 2. *The form Ω for an arbitrary arc element xP of a conjugate net is identical with the form Kds^2 for either conjugate element xQ or xQ' if and only if the surface S' is the plane net at infinity.*

An analogous characterization of $-Kds^2$ can obviously be formulated with reference to the mean-conjugate parametric net of S, but we shall not describe this result here.

Another geometric characterization of Kds^2 arises from the determination of the surface S' such that the invariant Ω of S, S' is expressible in the form

$$(3.9) \qquad\qquad \Omega = \sigma ds^2.$$

Just one such surface S' exists since the equations

$$(3.10) \qquad\qquad kd_{\alpha\beta} - h_{\alpha\beta} = \sigma g_{\alpha\beta}$$

possess a unique solution (k, σ). For, on substituting the right member of (3.4) for $h_{\alpha\beta}$ in (3.10) we find the equations

$$(3.11) \qquad\qquad (k - K_m)d_{\alpha\beta} = (\sigma - K)g_{\alpha\beta},$$

which hold for an unspecialized surface S if, and only if,

$$k = K_m, \qquad \sigma = K.$$

Hence, we have the following theorem.

THEOREM 3. *The differential form Ω of S, S' and the first fundamental form of S, defined with respect to a common direction, are related by the equation*

$$\Omega = \sigma ds^2$$

if and only if S' is the locus of the center of mean curvature of S. The associated function σ is the Gaussian curvature of S at x.

4. The principal directions, the lines of mean curvature, and the mean conjugate net of S. Since we have

$$a_{\alpha\beta} = kd_{\alpha\beta} - h_{\alpha\beta}, \qquad h_{\alpha\beta} = d_{\alpha\beta}K_m - g_{\alpha\beta}K,$$

we may write

$$(4.1) \qquad\qquad a_{\alpha\beta} = (k - K_m)d_{\alpha\beta} + Kg_{\alpha\beta}.$$

It is obvious, in view of the form of (4.1), that if $k \neq K_m$, the principal directions for the tensor $a_{\alpha\beta}$ are identical with the classical principal directions of S.

Let us assume, for the sake of convenience, that the lines of curvature are the parametric curves of S. The results which we present are,

however, independent of the choice of the parametric net. The author
[2, p. 309] has called a curve a line of mean curvature of S if at each
of its points the normal curvature $1/\rho$ of S in the direction of the
curve is equal to the arithmetic mean of the principal normal curva-
tures of S at the point, that is, if

$$\frac{1}{\rho} = \frac{1}{2}\left(\frac{1}{\rho_1} + \frac{1}{\rho_2}\right).$$

From equations (6.5) and (6.6) of [2, p. 310] we find that if $g_{12} = d_{12}$
$= 0$, the lines of mean curvature of S are the integral curves of

(4.2) $\Delta(g_{11}(du^1)^2 - g_{22}(du^2)^2) = 0$

in which $\Delta = g_{11}d_{22} - g_{22}d_{11}$. The significance of the presence of Δ in
equation (4.2) is that the lines of mean curvature form a determinate
net, except when $\Delta = g_{12} = d_{12} = 0$; in this exceptional case S is a sphere.

We inquire if there exists a surface S' for which Ω is expressible in
the form

(4.3) $\Omega = \sigma\Delta(g_{11}(du^1)^2 - g_{22}(du^2)^2).$

The affirmative answer is readily reached, for we find that the equa-
tions

$$kd_{11} - h_{11} = \sigma\Delta g_{11},$$

(4.4) $$kd_{12} - h_{12} = 0,$$

$$kd_{22} - h_{22} = -\sigma\Delta g_{22}$$

can be satisfied simultaneously. The second equation of (4.4) is satis-
fied identically in k, σ since $g_{12} = d_{12} = h_{12} = 0$. The other two equations
may be written in the forms

$$kd_{11} - g_{22}d_{11}^2/g = \sigma\Delta g_{11},$$

(4.5)

$$kd_{22} - g_{11}d_{22}^2/g = -\sigma\Delta g_{22}.$$

Solving, we find

(4.6) $$k = (d_{11}^2 g_{22}^2 + g_{11}^2 d_{22}^2)/g(g_{22}d_{11} + g_{11}d_{22}),$$

$$\sigma = d_{11}d_{22}/g(g_{22}d_{11} + g_{11}d_{22}).$$

Making use of the expressions

$$K = d_{11}d_{22}/g,$$

$$K_m = (g_{11}d_{22} + g_{22}d_{11})/g$$

for the Gaussian and mean curvatures of S, we express k, σ in terms of K and K_m as follows:

$$(4.7) \qquad k = K_m - 2K/K_m, \qquad \sigma = K/gK_m.$$

Hence we have the following theorem.

THEOREM 4. *If and only if S' is characterized in relation to S by (1.7) with k expressed in terms of the Gaussian and mean curvatures of S by the relation*

$$k = K_m - 2K/K_m,$$

the lines of mean curvature of S are the integral curves of the associated differential equation $\Omega = 0$.

Let us recall that a curve of the mean conjugate net is characterized by the property that at each of its points the radius of normal curvature of S in the direction of the curve is the arithmetic mean of the principal radii of normal curvature of S at the point, that is,

$$\rho = (\rho_1 + \rho_2)/2.$$

Retaining the lines of curvature as parametric curves, the mean conjugate net is the integral net of the equation

$$(4.8) \qquad \Delta(d_{11}(du^1)^2 - d_{22}(du^2)^2) = 0.$$

It is not difficult to prove, by the method we have employed above, that a surface S' exists such that the associated form Ω is expressible by the relation

$$(4.9) \qquad \Omega = \sigma\Delta(d_{11}(du^1)^2 - d_{22}(du^2)^2).$$

In fact, we find that

$$(4.10) \qquad k = K_m/2, \qquad \sigma = 1/2g.$$

We are now in a position to state our concluding result.

THEOREM 5. *If and only if k is the arithmetic mean of the principal normal curvatures of S at x, the integral net of the associated differential equation $\Omega = 0$ is the mean conjugate net of S.*

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