ON THE CYCLIC CONNECTIVITY THEOREM*

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1. Introduction. We shall call the following theorem the cyclic connectivity theorem.

Every two points of a locally connected continuum having no cut point lie together on a simple closed curve in that continuum.

The demonstration for this theorem originally given by the present author† for the case of plane continua and in particular the demonstration given later by Ayres‡ for the theorem in general space are undeniably quite complicated. Indeed, the complexity of the proof of this theorem constituted a strong incentive to the author to seek and find a new treatment of the cyclic element theory which not only avoids using this theorem as principal point of departure as does the original one but also has validity in all connected, locally connected, metric, and separable spaces, and thus in spaces in which the proposition in question obviously does not hold. The same complexity was the prevailing influence motivating a development by Kuratowski and the author of most of the cyclic element theory for compact locally connected continua in a simple and direct way independent of the cyclic connectivity theorem, based on a definition of cyclic element suggested by R. L. Moore.**

Thus it is seen that although this proposition has been almost successfully avoided in so far as the cyclic element theory is

^{*} Presented to the Society, February 28, 1931.

[†] See Proceedings of the National Academy of Sciences, vol. 13 (1927), pp. 31-38.

[‡] W. L. Ayres, American Journal of Mathematics, vol. 51 (1929), pp. 577-594.

[§] See Transactions of this Society, vol. 32 (1930), pp. 926–943.

See American Journal of Mathematics, vol. 50 (1928), pp. 167–194.

[¶] C. Kuratowski et G. T. Whyburn, Sur les éléments cycliques et leurs applications, Fundamenta Mathematicae, vol. 16 (1930), pp. 305-331. The authors of this article describe the proof of the cyclic connectivity theorem as being "fort compliquée."

^{**} R. L. Moore, Monatshefte für Mathematik und Physik, vol. 36 (1929), pp. 81–88.

concerned, it has not been proved in the direct and simple manner which is characteristic of demonstrations for the majority of theorems concerning cyclic elements. The present paper offers as its principal contribution just such a demonstration for this theorem, based on a small amount of the cyclic element theory which, for the sake of completeness, is appended at the end of the paper, together with a few fundamental and long established properties of locally connected continua. The cyclic connectivity theorem thus finds its proper place in the subject as an important *consequence* of the cyclic-element decomposition of locally connected continua and an important complement to the cyclic element theory.

2. The Proof. Let M designate any locally connected, locally compact, separable and metric continuum, which we shall consider as a space, and let C designate any such space which has no cut point.

LEMMA 1. If A and B are non-degenerate,* closed and mutually exclusive subsets of C, there exist two mutually exclusive arcs in C joining A and B.

There exists an arc ab in C where $ab \cdot A = a$, $ab \cdot B = b$; and if p is a point of A - a, clearly there exist points x which can be joined in C to p by an arc px containing no point of ab. Thus there exist points x such that mutually exclusive arcs ab and px exist in C so that

(1)
$$ab \cdot A \supset a$$
, $ab \cdot B \supset b$, and $px \cdot A \supset p$.

Let S denote the set of all such points x. I shall show that S = C. Suppose this is not so. Then since C is connected and clearly S is open in C, it follows that at least one point y of C - S is a limit point of S. There exists an arc a'b' in C - y such that $a'b' \cdot A = a'$ and $a'b' \cdot B = b'$. Let R be a region (= connected open subset of C) containing y but having no point or boundary point in a'b' + A. Then R contains a point x of S, and there exist arcs ab and px satisfying (1). Since y does not belong to S, it follows at once that $ab \cdot R \neq 0$. The arcs ab and px contain arcs aw and px respectively such that $aw \cdot \overline{R} = w$ and $px \cdot \overline{R} = r$. Let H = A + aw + px.

^{*} A point set is degenerate or non-degenerate according as it does or does not reduce to a single point. This terminology is due to R. L. Moore.

Then a'b' contains an arc uv such that $uv \cdot H = u$ and $uv \cdot B = v$. Let T denote one of the sets aw and pr which does not contain u and let Z denote the other one of these sets. Let Q be a region containing the point $T \cdot \overline{R}$ and containing no point of Z + uv. Then Z + uv contains an arc mn and T + Q + R contains an arc qy such that $mn \cdot A \supset m$, mn, $B \supset m$, $qy \cdot A \supset q$, and $mn \cdot qy = 0$. But this is impossible since y does not belong to S. Therefore S = C. Accordingly S contains a point x of B, and thus there exist two mutually exclusive arcs ab and px joining A and B.

LEMMA 2. Every point x of C is an interior point of some arc axb in C.

This is obvious if x is a cut point of some region R in C; for then it is only necessary to take a and b in different components of R-x and any arc ab in R will contain x. Thus we may suppose that x is a cut point of no region in C. Now let a and b be any two distinct points of C-x. Let R_1 be a region containing x of diameter < 1 so that $\overline{R}_1 \cdot (a+b) = 0$. There exists a locally connected subcontinuum E_1 of C of diameter <1 which contains \overline{R}_1 but does not contain either a or b. Since x is not a cut point of R_1 , it cannot be a cut point of E_1 ; and since it is not an end point of E_1 it therefore (see appendix below) lies in some non-degenerate cyclic element C_1 of E_1 . By Lemma 1 there exist in C two mutually exclusive arcs aa_1 and bb_1 where $aa_1 \cdot C_1 = a_1$ and $bb_1 \cdot C_1 = b_1$. Obviously, we may suppose $a_1 \neq x \neq b_1$. Let R_2 be a region in C_1 containing x of diameter less than 1/2, such that $\overline{R}_2 \cdot (a_1 + b_1) = 0$. There exists a locally connected subcontinuum E_2 of C_1 of diameter less than 1/2 which contains \overline{R}_2 but does not contain either a_1 or b_1 . Again we may suppose that x cuts no region in C_1 ; and it follows just as in the case of E_1 that x lies in some non-degenerate cyclic element C_2 of E_2 . By Lemma 1 there exist in C_1 two mutually exclusive arcs a_1a_2 and b_1b_2 such that $a_1a_2 \cdot C_2 = a_2$ and $b_1b_2 \cdot C_2 = b_2$. Let R_3 be a region in C_2 of diameter less than 1/3, and so on. If we continue this process indefinitely, it is clear that the point set

$$x + aa_1 + a_1a_2 + a_2a_3 + \cdots + bb_1 + b_1b_2 + \cdots$$

so obtained is an arc axb in C.

THEOREM. C is cyclicly connected.

Let a and b be any two points of C. Now every point x of C

lies on some simple closed curve in C; for by Lemma 2 there exists an arc pxq in C and there exists an arc pyq in C-x, and clearly pxq + pyq contains a simple closed curve containing x. Thus there exist simple closed curves C_a and C_b in C containing a and b, respectively. Now if $C_a \cdot C_b = 0$, then by Lemma 1 there exist mutually exclusive arcs mn and uv in C where $mn \cdot C_a = m$, $mn \cdot C_b = n$, $uv \cdot C_a = u$, and $uv \cdot C_b = v$; and in this case clearly the set mn+arc nbv of $C_b+uv+arc uam$ of C_a is a simple closed curve in C containing a+b. If $C_a \cdot C_b = p$, a single point, then C-p contains an arc uv so that $uv \cdot C_a = u$ and $uv \cdot C_b = v$; and in this case uv + arc vbp of $C_b + arc pau$ of C_a is a simple closed curve in C containing a+b. Finally, if $C_a \cdot C_b$ contains more than one point, then C_b contains an arc pbq, where $pbq \cdot C_a = p + q$; and in this case pbq + arc paq of C_a is a simple closed curve in Ccontaining a+b. Thus the cyclic connectivity theorem is established.

3. Appendix. For the sake of completeness, proofs will now be given for that part of the cyclic element theory which has been used in the above demonstration of the cyclic connectivity theorem.

DEFINITION. A cyclic element of our space M is either a cut point of the space or a set M_p , where p is a non-cut point and M_p is the set of all points which are not separated from p by any single point. (See references in §1.)

(1) $M_p = p$ only when p is an end point.

For suppose $M_p = p$, and let ϵ be any positive number. Since p is not a cut point of M, there exists a δ , $0 < \delta < \epsilon$, such that $M - V_{\epsilon}(p)$ is a subset of some single component N of $M - V_{\delta}(p)$, where $V_{\epsilon}(p)$ denotes the set of all points whose distance from p is $< \epsilon$, and similarly for δ . Let pq be an arc such that $pq \cdot N = q$. There exists a point x which separates p and p, because p and p. Clearly p connected, p separates p and p. Hence p and therefore p is an end point.

(2) Every M_p has the property that each component N of $M-M_p$ has just one limit point in M_p .

For if M_p contains two limit points of N, then since clearly M_p is closed, it follows that there exists an arc ab such that $ab \cdot M_p = a + b$. Hence if q is a point of ab - (a+b), some point x separates p and q. But then x necessarily separates q and the set $M_p - x$, which is impossible since we have the subarcs qa and qb of ab joining q and the set M_p .

(3) If the set Z is connected, so also is $Z \cdot M_p$ (when non-vacuous).

If, on the contrary, $Z \cdot M_p = H_1 + H_2$, where H_1 and H_2 are mutually separated, then let Z be divided into two sets Z_1 and Z_2 in such a way that these sets contain H_1 and H_2 , respectively, and any other point x of Z belongs to Z_1 or to Z_2 according as the boundary point of the component of $M - M_p$ containing x belongs to H_1 or to H_2 . Obviously $H_2 \cdot Z_2 = 0$. And if a point $H_2 \cdot Z_2 = 0$ or these sets, say of $H_2 \cdot Z_2 = 0$ is a limit point of the other, $H_2 \cdot Z_2 = 0$.

the local connectivity of M, any component of $M-M_p$ containing points of Z_2 is a neighborhood of any one of its points and contains no point of Z_1 , it follows that x belongs to H_2 . But then if V is a region containing x but containing no point of H_1 , V contains a point y of $Z_1 \cdot (M-M_p)$, and clearly this is impossible because the boundary point of the component of $M-M_p$ containing y belongs to H_1 and hence not to V.

(4) Every M_p is closed, connected, and locally connected and has no cut point. Taking Z = M, we have $Z \cdot M_p = M_p$; and thus by (3) it follows that M_p is connected. Similarly, since each pair of sufficiently near points of M_p lie together in a connected subset of M of arbitrarily small diameter and the product of this connected set by M_p is connected, it follows that M_p is locally connected. Obviously M_p is closed. Finally, if some point x cuts M_p , let a and b be points lying in different components of $M_p - x$. Now a and b must lie together in some component N of M - x, for otherwise x would separate either a or b from p in M. But by (3), $N \cdot M_p$ is connected, which is absurd, because N does not contain x. Therefore M_p has no cut point.

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