

THE ANOSOV THEOREM FOR INFRA-NILMANIFOLDS WITH A 2-PERFECT HOLONOMY GROUP*

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Abstract. In this paper, we show that $N(f) = |L(f)|$ for any continuous selfmap $f : M \rightarrow M$ on an infra-nilmanifold M of which the holonomy group is 2-perfect (i.e. having no index two subgroup). Conversely, for any finite group F that is not 2-perfect, we show there exists at least one infra-nilmanifold M with holonomy group F and a continuous selfmap $f : M \rightarrow M$ such that $N(f) \neq |L(f)|$.

Key words. Nielsen number, Lefschetz number, infra-nilmanifold, holonomy group.

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1. Introduction. To a continuous selfmap $f : M \rightarrow M$ on a closed manifold M , two numbers are assigned that are of particular interest in fixed point theory: the Lefschetz number $L(f)$ and the Nielsen number $N(f)$. In [1], D. Anosov proves that $N(f) = |L(f)|$ when M is a nilmanifold. He also notes that there exists a continuous selfmap f on the Klein bottle such that $N(f) \neq |L(f)|$.

There are two ways to generalise the Anosov theorem. Firstly, one can search for classes of continuous selfmaps f for which the equation $N(f) = |L(f)|$ holds. In [7] for example, K. Dekimpe, B. De Rock and W. Malfait prove that for an expanding selfmap f on an infra-nilmanifold M , the equation $N(f) = |L(f)|$ holds if and only if M is orientable. Additionally, the class of nowhere expanding maps on infra-nilmanifolds is introduced and the Anosov theorem is generalised to this class of maps.

Another approach is to search for classes of manifolds M such that $N(f) = |L(f)|$ for every continuous selfmap $f : M \rightarrow M$. E. C. Keppelmann and C. K. McCord [11] for instance show that $N(f) = |L(f)|$ for all continuous selfmaps $f : M \rightarrow M$ on an exponential solvmanifold M .

For a continuous selfmap $f : M \rightarrow M$ on an arbitrary closed manifold M , the relation between $N(f)$ and $L(f)$ is hard to study because the Nielsen number cannot be easily calculated from its definition. In the case M is an infra-nilmanifold however, K. B. Lee provides a criterion ([13]) to decide whether $N(f) = |L(f)|$ for a given continuous selfmap $f : M \rightarrow M$. This criterion is a powerful tool in the generalisation of the Anosov theorem to certain classes of maps on infra-nilmanifolds or to certain classes of infra-nilmanifolds. For instance, it lies at the basis of the results in [7] and it is used in [8] to generalise the Anosov theorem to a well described class of infra-nilmanifolds with cyclic holonomy group.

When searching for classes of infra-nilmanifolds to which the Anosov theorem can be generalised, it is natural to use properties of the holonomy group or of the

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holonomy representation of an infra-nilmanifold M to prove that $N(f) = |L(f)|$ for every continuous selfmap $f : M \rightarrow M$. Indeed, the Anosov theorem is originally stated for nilmanifolds, and these are precisely the infra-nilmanifolds that have trivial holonomy group. In [7], the Anosov theorem is generalised to all infra-nilmanifolds with odd order holonomy group.

In this article, we generalise the Anosov theorem to all infra-nilmanifolds of which the holonomy group is 2-perfect (i.e. having no index two subgroup). Conversely, we show that for any finite group F that has an index two subgroup, there exists an infra-nilmanifold M with holonomy group F and a continuous selfmap $f : M \rightarrow M$ such that $N(f) \neq |L(f)|$.

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2. Preliminaries. In this section, we introduce the basic notions needed for the formulation of the results. For more information on the Lefschetz number and the Nielsen number, we refer to [4, 10, 12]. For more information on infra-nilmanifolds, we refer to [5].

2.1. Lefschetz number and Nielsen number. Let $f : M \rightarrow M$ be a continuous selfmap on a closed manifold M . The Lefschetz number $L(f)$ is defined by

$$L(f) = \sum_i (-1)^i \text{Trace}(f_* : H_i(M, \mathbb{Q}) \rightarrow H_i(M, \mathbb{Q})).$$

This number is of interest in fixed point theory since $L(f) \neq 0$ implies that f has a fixed point. Because the Lefschetz number is invariant under homotopy, $L(f) \neq 0$ implies that any map homotopic to f has a fixed point.

Nielsen's approach to estimate the number of fixed points of f is of a more geometric nature. We define an equivalence relation on the set $\text{Fix}(f)$ of fixed points of f : two fixed points $x, y \in \text{Fix}(f)$ are f -equivalent if and only if there exists a path w from x to y such that w and $f \circ w$ are homotopic relative to the end points. The equivalence classes obtained this way are called fixed point classes of f . To each fixed point class, we assign an integer index. When this index differs from zero, we call the fixed point class essential. The Nielsen number $N(f)$ is by definition the number of essential fixed point classes of f . The interest in the Nielsen number arises from the fact that $N(f)$ is a lower bound for the number of fixed points of f . Because the Nielsen number is invariant under homotopy, every map homotopic to f has at least $N(f)$ fixed points.

We say that the Anosov theorem holds for a closed manifold M when $N(f) = |L(f)|$ for every continuous selfmap $f : M \rightarrow M$.

2.2. Infra-nilmanifolds. Let G be a connected, simply connected, nilpotent Lie group. We denote by $\text{Endo}(G)$ the semigroup of all endomorphisms of G . The semigroup $\text{Endo}(G)$ acts naturally on G and contains $\text{Aut}(G)$ as a subgroup. We use $\text{aff}(G)$ to denote the semigroup $G \rtimes \text{Endo}(G)$, which is $G \times \text{Endo}(G)$ as a set, with multiplication defined by $(d_1, D_1)(d_2, D_2) = (d_1 D_1(d_2), D_1 D_2)$. An element (d, D) of $\text{aff}(G)$ is called an affine endomorphism of G and it maps $g \in G$ to $dD(g)$. We can think of multiplication in $\text{aff}(G)$ as composition of maps. When D is an automorphism of G (that is: $D \in \text{Aut}(G)$), an affine endomorphism (d, D) is invertible as a selfmap on G and as an element of the semigroup $\text{aff}(G)$. We use $\text{Aff}(G)$ to denote the invertible affine endomorphisms of G , it equals $G \rtimes \text{Aut}(G)$ and is a subgroup of the semigroup $\text{aff}(G)$.

An almost-crystallographic group Γ (modelled on G) is a subgroup of $\text{Aff}(G)$ such that its subgroup of pure translations $N = \Gamma \cap G$ is a uniform lattice of G and N is of finite index in Γ . A torsion free almost-crystallographic group is an almost-Bieberbach group. We obtain an action of an almost-crystallographic group Γ on G by restricting the action of $\text{Aff}(G)$ on G to an action of Γ on G . Then the orbit space $\Gamma \backslash G$ is compact. In the case of an almost-Bieberbach group, the orbit space $\Gamma \backslash G$ is a closed (differentiable) manifold and its fundamental group $\pi_1(\Gamma \backslash G)$ is isomorphic to Γ ; in fact G is the universal covering space of $\Gamma \backslash G$ and the group of covering transformations is exactly Γ . A manifold $M = \Gamma \backslash G$, where Γ is an almost-Bieberbach group, is called an infra-nilmanifold (modelled on G). When $\Gamma \subset G$ is an almost-Bieberbach group, $\Gamma \backslash G$ is called a nilmanifold.

When $G = \mathbb{R}^n$, we refer to almost-crystallographic groups and almost-Bieberbach groups as crystallographic groups and Bieberbach groups respectively. When Γ is a Bieberbach group, the manifold $\Gamma \backslash \mathbb{R}^n$ is a closed flat manifold. All closed flat manifolds can be obtained in this way.

The holonomy group F of an almost-crystallographic group Γ can be defined as the finite group

$$F = \{x \in \text{Aut}(G) \mid \exists g \in G : (g, x) \in \Gamma\}.$$

By taking differentials, we obtain a morphism $\rho : F \rightarrow \text{Aut}(\mathfrak{g})$, where \mathfrak{g} is the Lie algebra associated to G . By fixing a basis for \mathfrak{g} , we obtain a faithful representation

$$\rho : F \rightarrow \text{GL}_n(\mathbb{R}),$$

that we call the holonomy representation of Γ . Because of the choice of a basis, this representation is determined up to similarity.

By the holonomy group and the holonomy representation of an infra-nilmanifold, we mean the holonomy group and the holonomy representation of the associated almost-Bieberbach group.

The holonomy representation holds a lot of information about the infra-nilmanifold in question. For instance, the holonomy representation of an infra-nilmanifold determines its orientability (see [3, p. 221] and [5, p. 135]):

PROPOSITION 2.1. *Let M be an infra-nilmanifold with holonomy group F and holonomy representation $\rho : F \rightarrow \text{GL}_n(\mathbb{R})$. Then M is orientable if and only if $\det(\rho(x)) = 1$ for every $x \in F$.*

2.3. Lefschetz number and Nielsen number of maps on infra-nilmanifolds. In this subsection, we present K. B. Lee's criterion to decide whether $N(f) = |L(f)|$ for a given continuous selfmap $f : M \rightarrow M$ on an infra-nilmanifold M . This criterion makes use of the notion of a homotopy lift.

DEFINITION 2.2. *Let M be an infra-nilmanifold modelled on a connected, simply connected, nilpotent Lie group G . Let $f : M \rightarrow M$ be a continuous selfmap. Let $h : G \rightarrow G$ be a continuous selfmap on the universal cover G of M . We say that h is a homotopy lift of f when h is a lift of a map homotopic to f .*

K. B. Lee proves the following theorem ([13, Corollary 1.2]):

THEOREM 2.3. *Every continuous selfmap on an infra-nilmanifold has a homotopy lift that is an affine endomorphism.*

REMARK 2.4. Let Γ be an almost-Bieberbach group modelled on a connected, simply connected, nilpotent Lie group G . Let $f : M \rightarrow M$ be a continuous selfmap on the corresponding infra-nilmanifold $M = \Gamma \backslash G$. Let $\delta \in \text{aff}(G)$ be a homotopy lift of f . Then $f : M \rightarrow M$ induces an endomorphism $f_\times : \Gamma \rightarrow \Gamma$ of the covering transformation group Γ , where we consider the universal cover of G over M . This morphism of groups $f_\times : \Gamma \rightarrow \Gamma$ is characterised by the equality $f_\times(\gamma)\delta = \delta\gamma$ for all $\gamma \in \Gamma$.

Now we have all ingredients necessary for the formulation of K. B. Lee’s criterion ([13, Theorem 2.2]).

THEOREM 2.5. *Let M be an infra-nilmanifold modelled on a connected, simply connected, nilpotent Lie group G and let $\rho : F \rightarrow \text{GL}_n(\mathbb{R})$ be the associated holonomy representation. Let $f : M \rightarrow M$ be a continuous selfmap on M and let $(d, D) \in \text{aff}(G)$ be a homotopy lift of f . Then $N(f) = |L(f)|$ if and only if $\det(\mathbb{1} - \rho(x_1)D_*) \det(\mathbb{1} - \rho(x_2)D_*) \geq 0$ for all $x_1, x_2 \in F$.*

3. The Anosov theorem for infra-nilmanifolds with a 2-perfect holonomy group. Our results rely on the following basic observation.

PROPOSITION 3.1. *Let M be an infra-nilmanifold modelled on a connected, simply connected, nilpotent Lie group G . Let $f : M \rightarrow M$ be a continuous selfmap. Let $(d, D) \in \text{aff}(G)$ be a homotopy lift of f . Let F be the holonomy group associated to M and $\rho : F \rightarrow \text{GL}_n(\mathbb{R})$ the holonomy representation. Then there exists a map $\phi : F \rightarrow F$ such that $\rho(\phi(x))D_* = D_*\rho(x)$ for all $x \in F$.*

Proof. Choose $x \in F$ arbitrarily. Choose $g \in G$ such that (g, x) belongs to the almost-Bieberbach group Γ associated to M . Let $f_\times : \Gamma \rightarrow \Gamma$ be the endomorphism of the covering transformation group Γ induced by f (where we consider the universal covering of G over M). Put $(g', x') = f_\times(g, x)$. By using Remark 2.4, one calculates that $(g'x'(d), x'D) = (dD(g), Dx)$, hence $x'D = Dx$. Thus for each $x \in F$, there exists $\phi(x) \in F$ such that $\phi(x)D = Dx$. By taking differentials, we finish the proof of the proposition. \square

In the previous proposition, if $D : G \rightarrow G$ is an automorphism of Lie groups, then $\phi : F \rightarrow F$ is necessarily an isomorphism of groups. The following example illustrates that in general however, we cannot assume that $\phi : F \rightarrow F$ is a morphism of groups.

EXAMPLE 3.2. Write $F = \mathbb{Z}_2 \oplus \mathbb{Z}_4$. We may identify \mathbb{Z}_2 with the matrix group generated by -1_2 and \mathbb{Z}_4 with the matrix group generated by

$$A = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}.$$

Using these identifications, we can define

$$\begin{aligned} \rho_1 : F &\rightarrow \text{GL}_2(\mathbb{R}) : (x, y) \mapsto x, \\ \rho_2 : F &\rightarrow \text{GL}_2(\mathbb{R}) : (x, y) \mapsto y \text{ and} \\ \rho_3 : F &\rightarrow \text{GL}_2(\mathbb{R}) : (x, y) \mapsto y^2. \end{aligned}$$

For $i = 1, \dots, 8$, let $e_i \in \mathbb{R}^8$ be the vector with 1 on the i -th place and zeroes elsewhere. Let Γ be the Bieberbach group generated by \mathbb{Z}^8 , (a_1, A_1) and (a_2, A_2) ,

where $a_1 = \frac{1}{2}e_1 + \frac{1}{2}e_2$, $a_2 = \frac{1}{4}e_2$ and where A_1 and A_2 are the block diagonal matrices defined by

$$A_1 = \text{diag}(\mathbb{1}_2, -\mathbb{1}_2, \mathbb{1}_2, \mathbb{1}_2), \quad A_2 = \text{diag}(\mathbb{1}_2, \mathbb{1}_2, A, A^2).$$

Put $\rho = 2\rho_{\text{triv}} \oplus \rho_1 \oplus \rho_2 \oplus \rho_3$, then ρ is the holonomy representation of Γ . Define D as the blockmatrix

$$D = \begin{pmatrix} B & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & \mathbb{1}_2 & 0 & 0 \end{pmatrix},$$

where 0 indicates the 2×2 matrix consisting of zeroes and where $B = \begin{pmatrix} 0 & 0 \\ 1/2 & 0 \end{pmatrix} \in \mathbb{R}^{2 \times 2}$. Then

$$\begin{aligned} (a_2, A_2) \circ D &= D \circ (a_1, A_1), & D &= D \circ (a_2, A_2), \\ (a_2, A_2)^2 \circ D &= D \circ (e_1, \mathbb{1}_8), & D &= D \circ (e_2, \mathbb{1}_8), \\ (e_7, \mathbb{1}_8) \circ D &= D \circ (e_3, \mathbb{1}_8), & (e_8, \mathbb{1}_8) \circ D &= D \circ (e_4, \mathbb{1}_8), \\ & D = D \circ (e_5, \mathbb{1}_8), & D &= D \circ (e_6, \mathbb{1}_8), \\ & D = D \circ (e_7, \mathbb{1}_8) \quad \text{and} & D &= D \circ (e_8, \mathbb{1}_8). \end{aligned}$$

Hence $D : \mathbb{R}^8 \rightarrow \mathbb{R}^8$ induces a continuous selfmap $f : \Gamma \backslash \mathbb{R}^8 \rightarrow \Gamma \backslash \mathbb{R}^8$.

Suppose for a contradiction that there exists a morphism of groups $\phi : F \rightarrow F$ such that

$$\rho(\phi(x, y))D = D\rho(x, y) \quad \text{for all } (x, y) \in F.$$

Write $\phi(-\mathbb{1}_2, \mathbb{1}_2) = (x, y)$, then $\rho(x, y)D = D\rho(-\mathbb{1}_2, \mathbb{1}_2)$ implies that

$$\begin{pmatrix} \mathbb{1}_2 & 0 & 0 & 0 \\ 0 & x & 0 & 0 \\ 0 & 0 & y & 0 \\ 0 & 0 & 0 & y^2 \end{pmatrix} \begin{pmatrix} B & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & \mathbb{1}_2 & 0 & 0 \end{pmatrix} = \begin{pmatrix} B & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & \mathbb{1}_2 & 0 & 0 \end{pmatrix} \begin{pmatrix} \mathbb{1}_2 & 0 & 0 & 0 \\ 0 & -\mathbb{1}_2 & 0 & 0 \\ 0 & 0 & \mathbb{1}_2 & 0 \\ 0 & 0 & 0 & \mathbb{1}_2 \end{pmatrix},$$

such that

$$\begin{pmatrix} B & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & y^2 & 0 & 0 \end{pmatrix} = \begin{pmatrix} B & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & -\mathbb{1}_2 & 0 & 0 \end{pmatrix},$$

such that $y^2 = -\mathbb{1}_2$. Hence

$$\begin{aligned} (\mathbb{1}_2, \mathbb{1}_2) &= \phi(\mathbb{1}_2, \mathbb{1}_2) = \phi((-\mathbb{1}_2, \mathbb{1}_2)(-\mathbb{1}_2, \mathbb{1}_2)) \\ &= \phi(-\mathbb{1}_2, \mathbb{1}_2)\phi(-\mathbb{1}_2, \mathbb{1}_2) = (x, y)(x, y) = (\mathbb{1}_2, y^2) = (\mathbb{1}_2, -\mathbb{1}_2), \end{aligned}$$

a contradiction.

The observation in Proposition 3.1 is used in [7] for the proof of various theorems. One of these theorems is [7, Theorem 4.2], which can be stated as follows:

THEOREM 3.3. *Let $f : M \rightarrow M$ be an expanding selfmap on an infra-nilmanifold M . Then $N(f) = |L(f)|$ if and only if M is orientable.*

By using Proposition 3.1 and K. B. Lee’s criterion, this Theorem 3.3 is a direct consequence of the following theorem:

THEOREM 3.4. *Let $\rho : F \rightarrow \text{GL}_n(\mathbb{R})$ be a representation of a finite group F . Let $\phi : F \rightarrow F$ be any map. Let $D \in \mathbb{R}^{n \times n}$ be a matrix and suppose that $\rho(\phi(x))D = D\rho(x)$ for all $x \in F$. Suppose that $|\lambda| > 1$ for all eigenvalues λ of D . Then $\det(\mathbb{1} - \rho(x_1)D) \det(\mathbb{1} - \rho(x_2)D) \geq 0$ for all $x_1, x_2 \in F$ if and only if $\det(\rho(x)) = 1$ for all $x \in F$.*

In fact, this theorem is proved in the proof of Theorem 3.3 in [7].

Likewise, the proof of [7, Theorem 4.6] on nowhere-expanding maps largely consists of a proof of the following theorem:

THEOREM 3.5. *Let $\rho : F \rightarrow \text{GL}_n(\mathbb{R})$ be a representation of a finite group F . Let $\phi : F \rightarrow F$ be any map. Let $D \in \mathbb{R}^{n \times n}$ be a matrix and suppose that $\rho(\phi(x))D = D\rho(x)$ for all $x \in F$. Suppose that $|\lambda| \leq 1$ for all eigenvalues λ of D . Then $\det(\mathbb{1} - \rho(x_1)D) \det(\mathbb{1} - \rho(x_2)D) \geq 0$ for all $x_1, x_2 \in F$.*

In this article, we use a similar approach. We use Proposition 3.1 and K. B. Lee’s criterion (Theorem 2.5) to deduce a generalisation of the Anosov theorem from the lemma below. In this lemma we are talking about a subrepresentation $\hat{\rho}$ of a representation ρ . By this we mean, as usual, that there exists a subvector space $W \cong \mathbb{R}^k$ of \mathbb{R}^n , such that W is invariant under the action of ρ and the restriction of ρ to W is equivalent to $\hat{\rho}$. In fact, in this case there exists a second subrepresentation ρ' of ρ such that ρ is equivalent to $\hat{\rho} \oplus \rho'$.

LEMMA 3.6. *Let $\rho : F \rightarrow \text{GL}_n(\mathbb{R})$ be a representation of a finite group F . Then the following statements are equivalent:*

- (A) $\det(\hat{\rho}(x)) = 1$ for all $x \in F$ and for every subrepresentation $\hat{\rho}$ of ρ over \mathbb{R} .
- (B) For any map $\phi : F \rightarrow F$ and any matrix $D \in \mathbb{R}^{n \times n}$ satisfying

$$\rho(\phi(x))D = D\rho(x) \quad \text{for all } x \in F,$$

we have that

$$\det(\mathbb{1} - \rho(x_1)D) \det(\mathbb{1} - \rho(x_2)D) \geq 0 \quad \text{for all } x_1, x_2 \in F.$$

Proof. Let us first prove the implication (B) \implies (A). Suppose for a contradiction that statement (B) holds, but that $\det(\hat{\rho}(y)) = -1$ for a subrepresentation $\hat{\rho} : F \rightarrow \text{GL}_{\hat{n}}(\mathbb{R})$ of ρ over \mathbb{R} and for some $y \in F$. Choose $P \in \text{GL}_n(\mathbb{R})$ such that $P\rho(x)P^{-1} = (\hat{\rho} \oplus \rho')(x)$ for all $x \in F$ for a representation $\rho' : F \rightarrow \text{GL}_{n-\hat{n}}(\mathbb{R})$. By applying Theorem 3.4 with $D = 2\mathbb{1}_{\hat{n}}$, we see that there exist $x_1, x_2 \in F$ such that

$$\det(\mathbb{1}_{\hat{n}} - \hat{\rho}(x_1)(2\mathbb{1}_{\hat{n}})) \det(\mathbb{1}_{\hat{n}} - \hat{\rho}(x_2)(2\mathbb{1}_{\hat{n}})) < 0.$$

Now put

$$D = P^{-1} \begin{pmatrix} 2\mathbb{1}_{\hat{n}} & 0_{\hat{n} \times (n-\hat{n})} \\ 0_{(n-\hat{n}) \times \hat{n}} & 0_{(n-\hat{n}) \times (n-\hat{n})} \end{pmatrix} P,$$

and let $\phi : F \rightarrow F : x \mapsto x$ be the identity map, then $\rho(\phi(x))D = D\rho(x)$ for all $x \in F$. Additionally, $\det(\mathbb{1} - \rho(x_1)D) \det(\mathbb{1} - \rho(x_2)D) < 0$, a contradiction with (B).

Let us now prove the implication **(A)** \implies **(B)**. Suppose statement **(A)** holds. Let $\phi : F \rightarrow F$ be any map and let $D \in \mathbb{R}^{n \times n}$ be a matrix such that $\rho(\phi(x))D = D\rho(x)$ for all $x \in F$. Because $\text{Ker}(D)$ is invariant under ρ , without loss of generality, by conjugation, we may assume that $\rho = \rho_0 \oplus \rho_1$ for some representations $\rho_0 : F \rightarrow \text{GL}_{n_0}(\mathbb{R})$ and $\rho_1 : F \rightarrow \text{GL}_{n_1}(\mathbb{R})$, where n_0 is the dimension of $\text{Ker}(D)$ and we may assume that D has the form of a blockmatrix

$$D = \begin{pmatrix} 0 & * \\ 0 & D_1 \end{pmatrix},$$

where $D_1 \in \mathbb{R}^{n_1 \times n_1}$. Remark that for any $x \in F$,

$$\det(\mathbf{1} - \rho(x)D) = \det(\mathbf{1} - \rho_1(x)D_1) \quad \text{and} \quad \rho_1(\phi(x))D_1 = D_1\rho_1(x).$$

Hence we may replace ρ by ρ_1 and D by D_1 . By applying this procedure repeatedly, we may assume that $\text{Ker}(D) = \{0\}$. In this case, D belongs to the normaliser $N_{\text{GL}_n(\mathbb{R})}(\rho(F))$ of $\rho(F)$ in $\text{GL}_n(\mathbb{R})$. The centraliser $C_{\text{GL}_n(\mathbb{R})}(\rho(F))$ of $\rho(F)$ in $\text{GL}_n(\mathbb{R})$ is a normal subgroup of $N_{\text{GL}_n(\mathbb{R})}(\rho(F))$ and the quotient is isomorphic to a subgroup of $\text{Aut}(\rho(F))$. Since $\text{Aut}(\rho(F))$ is finite, $C_{\text{GL}_n(\mathbb{R})}(\rho(F))$ is a finite index normal subgroup of $N_{\text{GL}_n(\mathbb{R})}(\rho(F))$ and there exists $k \in \mathbb{N} \setminus \{0\}$ such that $D^k \in C_{\text{GL}_n(\mathbb{R})}(\rho(F))$.

Let $V_{\leq 1}^{\mathbb{C}}$ be the complex vector space spanned by

$$\{z \in \mathbb{C}^n \mid z \text{ is a generalised eigenvector of } D \text{ with eigenvalue } \lambda, \text{ where } |\lambda| \leq 1\}.$$

Remark that the dimension of $V_{\leq 1}^{\mathbb{C}}$ equals the number of entries of modulus ≤ 1 on the diagonal of the Jordan normal form of D . Since the generalised eigenspace of D corresponding to an eigenvalue $\mu \in \mathbb{C}$ of D is a subspace of the generalised eigenspace of D^k corresponding to the eigenvalue μ^k of D^k , the vector space $V_{\leq 1}^{\mathbb{C}}$ is a subspace of the vector space spanned by

$$\{z \in \mathbb{C}^n \mid z \text{ is a generalised eigenvector of } D^k \text{ with eigenvalue } \lambda, \text{ where } |\lambda| \leq 1\}.$$

Because these vector spaces have the same dimension, they are equal.

Let $z \in \mathbb{C}^n$ be in the generalised eigenspace of D^k corresponding to an eigenvalue $\lambda \in \mathbb{C}$ of D^k : there exists $m \in \mathbb{N} \setminus \{0\}$ such that $(D^k - \lambda\mathbf{1})^m z = 0$. Then for any $x \in F$,

$$(D^k - \lambda\mathbf{1})^m \rho(x)z = \rho(x)(D^k - \lambda\mathbf{1})^m z = 0,$$

hence also $\rho(x)z$ belongs to the generalised eigenspace of D^k that corresponds to the eigenvalue λ . Additionally,

$$(D^k - \lambda\mathbf{1})^m Dz = D(D^k - \lambda\mathbf{1})^m z = 0,$$

so also Dz is in the generalised eigenspace of D^k that corresponds to the eigenvalue λ . We see that $V_{\leq 1}^{\mathbb{C}}$ is invariant under ρ and that $D(V_{\leq 1}^{\mathbb{C}}) \subset V_{\leq 1}^{\mathbb{C}}$.

Similarly, one shows that the vector space $V_{> 1}^{\mathbb{C}}$ spanned by

$$\{z \in \mathbb{C}^n \mid z \text{ is a generalised eigenvector of } D \text{ with eigenvalue } \lambda, \text{ where } |\lambda| > 1\}$$

is invariant under ρ and that $D(V_{> 1}^{\mathbb{C}}) \subset V_{> 1}^{\mathbb{C}}$. Remark that \mathbb{C}^n is the internal direct sum of $V_{\leq 1}^{\mathbb{C}}$ and $V_{> 1}^{\mathbb{C}}$. Define $V_{\leq 1} = V_{\leq 1}^{\mathbb{C}} \cap \mathbb{R}^n$ and $V_{> 1} = V_{> 1}^{\mathbb{C}} \cap \mathbb{R}^n$. Remark that

because D is a real matrix, if $v \in V_{\leq 1}^{\mathbb{C}}$, then also the complex conjugate \bar{v} belongs to $V_{\leq 1}^{\mathbb{C}}$. Hence the dimension of the real vector space $V_{\leq 1}$ equals the dimension of the complex vector space $V_{\leq 1}^{\mathbb{C}}$. Similarly, the dimension of the real vector space $V_{> 1}$ equals the dimension of the complex vector space $V_{> 1}^{\mathbb{C}}$. Hence \mathbb{R}^n is the internal direct sum of $V_{\leq 1}$ and $V_{> 1}$. Additionally, both $V_{\leq 1}$ and $V_{> 1}$ are invariant under ρ and $D(V_{\leq 1}) \subset V_{\leq 1}$ and $D(V_{> 1}) \subset V_{> 1}$. Hence, by conjugation, we may assume that $\rho = \rho_{\leq 1} \oplus \rho_{> 1}$ for some representations $\rho_{\leq 1} : F \rightarrow \text{GL}_{n_{\leq 1}}(\mathbb{R})$ and $\rho_{> 1} : F \rightarrow \text{GL}_{n_{> 1}}(\mathbb{R})$ and that D has the form of a blockmatrix

$$D = \begin{pmatrix} D_{\leq 1} & 0 \\ 0 & D_{> 1} \end{pmatrix},$$

where $D_{\leq 1} \in \mathbb{R}^{n_{\leq 1} \times n_{\leq 1}}$ has only eigenvalues of modulus ≤ 1 and $D_{> 1} \in \mathbb{R}^{n_{> 1} \times n_{> 1}}$ has only eigenvalues of modulus > 1 . For any $x \in F$,

$$\det(\mathbb{1} - \rho(x)D) = \det(\mathbb{1} - \rho_{\leq 1}(x)D_{\leq 1}) \det(\mathbb{1} - \rho_{> 1}(x)D_{> 1}).$$

By Theorem 3.5,

$$\det(\mathbb{1} - \rho_{\leq 1}(x_1)D_{\leq 1}) \det(\mathbb{1} - \rho_{\leq 1}(x_2)D_{\leq 1}) \geq 0 \quad \text{for all } x_1, x_2 \in F.$$

Because $\det(\rho_{> 1}(x)) = 1$ for all $x \in F$, by Theorem 3.4,

$$\det(\mathbb{1} - \rho_{> 1}(x_1)D_{> 1}) \det(\mathbb{1} - \rho_{> 1}(x_2)D_{> 1}) \geq 0 \quad \text{for all } x_1, x_2 \in F.$$

Hence for any $x_1, x_2 \in F$,

$$\begin{aligned} & \det(\mathbb{1} - \rho(x_1)D) \det(\mathbb{1} - \rho(x_2)D) \\ &= \det(\mathbb{1} - \rho_{\leq 1}(x_1)D_{\leq 1}) \det(\mathbb{1} - \rho_{\leq 1}(x_2)D_{\leq 1}) \det(\mathbb{1} - \rho_{> 1}(x_1)D_{> 1}) \det(\mathbb{1} - \rho_{> 1}(x_2)D_{> 1}) \\ &\geq 0. \end{aligned}$$

□

Using Proposition 3.1 and K. B. Lee’s criterion (Theorem 2.5), we ‘translate’ this lemma into a generalisation of the Anosov theorem:

THEOREM 3.7. *Let M be an infra-nilmanifold with holonomy group F and holonomy representation $\rho : F \rightarrow \text{GL}_n(\mathbb{R})$. Suppose that $\det(\hat{\rho}(x)) = 1$ for all $x \in F$ and for every subrepresentation $\hat{\rho}$ of ρ over \mathbb{R} . Then the Anosov theorem holds for M .*

Proof. Let G be the connected, simply connected, nilpotent Lie group on which M is modelled. Let $f : M \rightarrow M$ be a continuous selfmap and let $(d, D) \in \text{aff}(G)$ be a homotopy lift of f . By Proposition 3.1, there exists a map $\phi : F \rightarrow F$ such that $\rho(\phi(x))D_* = D_*\rho(x)$ for all $x \in F$. By Lemma 3.6,

$$\det(\mathbb{1} - \rho(x_1)D_*) \det(\mathbb{1} - \rho(x_2)D_*) \geq 0 \quad \text{for all } x_1, x_2 \in F.$$

By Theorem 2.5, $N(f) = |L(f)|$. □

Remark that for a representation $\rho : F \rightarrow \text{GL}_n(\mathbb{R})$ of a finite cyclic group F , statement **(A)** in Lemma 3.6 is equivalent to the condition that -1 is no eigenvalue of $\rho(x_0)$, where x_0 is a generator of F . This is precisely the condition on the holonomy representation of an infra-nilmanifold M with cyclic holonomy group under which the

main result of [8] states that the Anosov theorem holds for M . Hence Theorem 3.7 generalises the main result of [8].

Let us now state and prove the main theorem of this section:

THEOREM 3.8. *Let F be a finite group. Then the Anosov theorem holds for every infra-nilmanifold with holonomy group F if and only if F is 2-perfect.*

Proof. Suppose F has no index two subgroup. Let M be an infra-nilmanifold with holonomy group F and holonomy representation $\rho : F \rightarrow \text{GL}_n(\mathbb{R})$. We want to show that the Anosov theorem holds for M . By Theorem 3.7, it suffices to show that $\det(\hat{\rho}(x)) = 1$ for all $x \in F$ and for every subrepresentation $\hat{\rho}$ of ρ over \mathbb{R} . Suppose for a contradiction that there exists a subrepresentation $\hat{\rho}$ of ρ over \mathbb{R} and an element y of F such that $\det(\hat{\rho}(y)) = -1$. Define

$$\psi : F \rightarrow \{-1, 1\} : x \mapsto \det(\hat{\rho}(x)),$$

then $\psi^{-1}(\{1\})$ is an index two subgroup of F , a contradiction. Hence $\det(\hat{\rho}(x)) = 1$ for all $x \in F$ and for every subrepresentation $\hat{\rho}$ of ρ over \mathbb{R} . By Theorem 3.7, the Anosov theorem holds for M .

Conversely suppose that F has an index two subgroup H . We want to show there exists an infra-nilmanifold M with holonomy group F and a continuous selfmap $f : M \rightarrow M$ such that $N(f) \neq |L(f)|$. By [2, Theorem 3], there exists a closed flat manifold M with holonomy group F . We consider two cases.

Suppose M is not orientable. By [9], there exists an expanding map $f : M \rightarrow M$. By Theorem 3.4, $N(f) \neq |L(f)|$.

Suppose M is orientable. Let $\Gamma \subset \text{Aff}(\mathbb{R}^n)$ be the Bieberbach group associated to M and $\rho : F \rightarrow \text{GL}_n(\mathbb{R})$ the holonomy representation. Define the representation

$$\hat{\rho} : F \rightarrow \text{GL}_1(\mathbb{R}) : x \mapsto \begin{cases} 1 & \text{if } x \text{ belongs to the index two subgroup } H \text{ of } F \\ -1 & \text{else.} \end{cases}$$

Now Γ acts on \mathbb{Z} by

$$(a, A) \cdot z = \hat{\rho}(A)(z) \quad \text{for every } (a, A) \in \Gamma \text{ and every } z \in \mathbb{Z}.$$

Define Γ' as the semi-direct product $\Gamma' = \mathbb{Z} \rtimes \Gamma$. Because Γ is torsion free, also $\Gamma' = \mathbb{Z} \rtimes \Gamma$ is torsion free. We can embed Γ' in $\text{Aff}(\mathbb{R}^{n+1})$ by identifying $(z, (a, A)) \in \Gamma'$ with $(t, (\hat{\rho} \oplus \rho)(A)) \in \text{Aff}(\mathbb{R}^{n+1})$, where $t = (z, a_1, \dots, a_n)$ if $a = (a_1, \dots, a_n) \in \mathbb{R}^n$. Because $\Gamma \cap \mathbb{R}^n$ is a uniform lattice in \mathbb{R}^n , also $\Gamma' \cap \mathbb{R}^{n+1}$ is a uniform lattice in \mathbb{R}^{n+1} . Let $\{\alpha_1, \dots, \alpha_m\}$ be a finite set of representatives of the right cosets of $\Gamma \cap \mathbb{R}^n$ in Γ . Because every $(z, (a, A)) \in \Gamma'$ can be written as $(z, (0, \mathbf{1}))(0, (a, A)) = (z, (0, \mathbf{1}))(0, (t, \mathbf{1}))(0, \alpha_i)$ for some $t \in \Gamma \cap \mathbb{R}^n$ and some α_i and because $(z, (0, \mathbf{1}))(0, (t, \mathbf{1})) \in \Gamma' \cap \mathbb{R}^{n+1}$, we see that $\Gamma' \cap \mathbb{R}^{n+1}$ has only finitely many right cosets. Hence $\Gamma' \cap \mathbb{R}^{n+1}$ is of finite index in Γ' and hence Γ' is a Bieberbach group. Let M' be the associated closed flat manifold. It is clear that F is the holonomy group of M' and that $\hat{\rho} \oplus \rho$ is the holonomy representation. Again, we can find an expanding map $f' : M' \rightarrow M'$ and because M' is not orientable by Proposition 2.1, we have that $N(f') \neq |L(f')|$ by Theorem 3.4. \square

COROLLARY 3.9. *As a special case of Theorem 3.8, the Anosov theorem holds for any infra-nilmanifold of which the holonomy group is a simple group, different*

from \mathbb{Z}_2 (the group with two elements). This is a new result and does not follow from earlier publications.

REMARK 3.10. When the holonomy group F of an infra-nilmanifold M has an index two subgroup, this does not a priori imply there exists a continuous selfmap $f : M \rightarrow M$ for which $N(f) \neq |L(f)|$. A generalised Hantzsche-Wendt manifold is by definition an n -dimensional closed flat manifold with holonomy group isomorphic to \mathbb{Z}_2^{n-1} . The groups \mathbb{Z}_2^{n-1} clearly have an index two subgroup (at least when $n > 1$). Nevertheless, the Anosov theorem holds for all orientable generalised Hantzsche-Wendt manifolds ([6]).

REMARK 3.11. Whether the Anosov theorem holds for an infra-nilmanifold M does not depend solely on the holonomy representation of M . For instance, let Γ be the Bieberbach group generated by $(e_1, \mathbb{1}_4), (e_2, \mathbb{1}_4), (e_3, \mathbb{1}_4), (e_4, \mathbb{1}_4), (a_1, A_1)$ and (a_2, A_2) , where $e_i \in \mathbb{R}^4$ has 1 on the i -th place and 0 elsewhere, $a_1 = (0, \frac{1}{2}, \frac{1}{2}, 0)$, $a_2 = (0, 0, 0, \frac{1}{2})$, $A_1 = \text{diag}(1, 1, -1, -1)$ and $A_2 = \text{diag}(1, -1, -1, 1)$. Let M be the closed flat manifold associated to Γ . One can verify by using Theorem 2.5 that $N(f) = |L(f)|$ for every continuous selfmap $f : M \rightarrow M$. Let Γ' be the Bieberbach group generated by $(e_1, \mathbb{1}_4), (e_2, \mathbb{1}_4), (e_3, \mathbb{1}_4), (e_4, \mathbb{1}_4), (a'_1, A_1)$ and (a_2, A_2) , where $a'_1 = (\frac{1}{2}, 0, 0, 0)$. Let M' be the closed flat manifold associated to Γ' . Put $d = (0, 0, 0, 0)$ and let D be the matrix $D = \text{diag}(3, 0, 3, 3)$, then $\det(\mathbb{1}_4 - D) \det(\mathbb{1}_4 - A_1 D) < 0$. One can verify that $(d, D) \in \text{aff}(\mathbb{R}^4)$ induces a continuous selfmap $f' : M' \rightarrow M'$ and by Theorem 2.5, $N(f') \neq |L(f')|$. Remark that M and M' have the same holonomy group \mathbb{Z}_2^2 and the same holonomy representation.

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