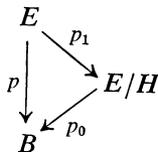


THE HOLONOMY GROUPS AND THE REFINEMENTS OF A PRINCIPAL STEENROD BUNDLE

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Let (ξ, H) be a structure consisting of a principal Steenrod bundles $\xi = (E, B, p, G; \mathcal{A})$ and a closed subgroup H of G . We shall assume that all elements are C^∞ differentiable.

It is well known [2, p. 57] that ξ and H define the commutative diagram



and the Steenrod bundles $\xi_0 = (E/H, B, p_0, G/H, G/N; \mathcal{A}_0)$, $\xi_1 = (E, E/H, p_1, H; \mathcal{A}_1)$. Here N is the largest invariant subgroup of G included in H , p_1 and p_0 are the canonical maps, and $\mathcal{A}_0, \mathcal{A}_1$ are trivialization atlases of ξ_0, ξ_1 respectively, canonically defined by \mathcal{A} , [4]. ξ_1 is a principal Steenrod bundle.

The structure $(\xi; \xi_0, \xi_1)$ will be called the refinement of ξ defined by H , and we shall utilize the following notation:

$\mathcal{A}^V, \mathcal{A}_1^V, \mathcal{A}_0^V$ are the vertical differential systems of ξ, ξ_1, ξ_0 respectively. Throughout this paper, differential system = distribution, [2, p. 10]. $\mathcal{A}_N^V (\subset \mathcal{A}_1^V)$ is the differential system of E defined by the orbits of N as a transformation group on E . $\mathfrak{g}, \mathfrak{g}_h, \mathfrak{g}_N$ are the Lie algebras of G, H, N respectively. $\gamma = \{\Gamma\}$, $\gamma_1 = \{\Gamma_1\}$ are the sets of connections of ξ, ξ_1 respectively. $\varphi_\Gamma^0(\alpha)$ is the restricted holonomy group of Γ with reference point α .

In this paper we shall establish some properties of holonomy groups of connections of γ and γ_1 . More precisely:

In γ the following equivalence relation is introduced ([4], [5]): Two connections $\Gamma, \Gamma' \in \gamma$ defined by the horizontal differential systems $\mathcal{A}_\Gamma^H, \mathcal{A}_{\Gamma'}^H$ are equivalent if $p_1'(\mathcal{A}_\Gamma^H) = p_1'(\mathcal{A}_{\Gamma'}^H)$. The equivalence class defined by $\Gamma \in \gamma$ has been denoted by Γ^* , [4, p. 381]. In the first section we shall make some remarks

on the relations which exist between the holonomy groups of two equivalent connections of ξ .

If Δ is a differential system of E satisfying the relations

$$(1) \quad \Delta \cap \Delta_1^V = 0, \quad \Delta \oplus \Delta_1^V = \Delta^V, \quad \forall a \in H \mid R'_a(\Delta) = \Delta,$$

then we can define a map $h_\Delta: \gamma \rightarrow \gamma_1$, ([4], [5]). In the second section we shall establish a relation between the holonomy groups of two connections of γ , which have the same image in h_Δ .

In the third section we shall make some observations on the relations which exist between the holonomy groups of connections $\Gamma \in \gamma$ and $h_\Delta(\Gamma) \in \gamma_1$, Δ being fixed.

1. The holonomy groups of connections belonging to the same class Γ^*

Let $\mathcal{FV}(E, \Delta_F^H), \mathcal{FV}(E, \Delta_N^V)$ be the vector bundles defined over E as the base space, by the differential systems Δ_F^H, Δ_N^V respectively. For the set Γ^* defined by Γ we have the theorem [5, Theorem 2]:

The set Γ^* is bijective with the set of homomorphism $\{T \mid T: \mathcal{FV}(E, \Delta_F^H) \rightarrow \mathcal{FV}(E, \Delta_N^V)\}$ satisfying the condition

$$(2) \quad \forall a \in H \mid R'_a \circ T = T \circ R'_a.$$

Here we shall prove two theorems concerning the holonomy groups of connections of Γ^* . To this purpose we shall first establish

Lemma 1. *Suppose that $\xi = (E, B, p, F, G; \mathcal{A})$ is a Steenrod bundle, and Δ is a differential system of E satisfying the following three conditions*

- 1) $\Delta \cap \Delta^V = 0$, 2) $\Delta \oplus \Delta^V = T(E)$,
- 3) *for every curve of B there is a horizontal lift with respect to p (horizontal = tangent to Δ), uniquely determined by an initial point (we shall say that the differential system Δ has the unique path lifting property with respect to p).*

Then Δ is involutive if and only if the horizontal lift with respect to p of an arbitrary closed zero homotopic curve of B is a closed curve of E .

Proof. Let Δ be an involutive differential system. Then for every point $x \in B$, there is an open neighborhood $U_x \subset B$ such that the intersection of the integral manifold of Δ , defined by an arbitrary point $\alpha \in p^{-1}(x)$, with $p^{-1}(U_x)$ be a differentiable manifold, diffeomorphic to U_x by p .

Let $x = x(t)$ be an arbitrary curve of B , closed in x_0 and zero homotopic. By applying the factorization lemma to $x = x(t)$ ([3, p. 47] or ([2, p. 284]) we see that every utilized lasso is contained in an above specified neighborhood U_x . The horizontal lifts of these lassos with respect to p and with a fixed point $\alpha_0 \in p^{-1}(x_0)$ as initial point, are also lassos. The product of these lassos is a closed curve, the horizontal lift of $x = x(t)$ with respect to p .

Conversely, we shall prove that if the horizontal lift with respect to p of an arbitrary closed zero homotopic curve of B is a closed curve in E , then Δ is an involutive differential system. Consider the vector fields $\partial/\partial x^i$, $i = 1, \dots, n$, locally defined on B , and denote by Z_i , $i = 1, \dots, n$, the horizontal lifts of these fields with respect to p . The vector fields Z_i , $i = 1, \dots, n$, define a local base for Δ . Under our hypothesis we shall establish that $[Z_i, Z_j] = 0$. In order to prove this, consider the vector fields $\partial/\partial x^i$, $\partial/\partial x^j$, $-\partial/\partial x^i$, $-\partial/\partial x^j$ of B and their integral curves c_1, c_2, c_3, c_4 . Using the geometrical interpretation of $[\partial/\partial x^i, \partial/\partial x^j]$, [1, p. 28], we see that the equality $[\partial/\partial x^i, \partial/\partial x^j] = 0$ implies that the curve defined by c_1, c_2, c_3, c_4 is closed and also zero homotopic. The horizontal lifts of c_1, c_2, c_3, c_4 with respect to p are denoted $\bar{c}_1, \bar{c}_2, \bar{c}_3, \bar{c}_4$, and these curves are tangent to $Z_i, Z_j, -Z_i, -Z_j$. The hypothesis of the lemma implies that the curve defined by these four curves $\bar{c}_1, \bar{c}_2, \bar{c}_3, \bar{c}_4$ are closed and hence $[Z_i, Z_j] = 0$.

Theorem 1. *Let $(\xi; \xi_0, \xi_1)$ be the refinement of ξ defined by H , and let Γ be a connection of ξ defined by the horizontal differential system Δ_r^H . If $\Delta_r = p_1'(\Delta_r^H)$, then Δ_r is a differential system of E/H and has the unique path lifting property with respect to p_0 . Δ_r is involutive if and only if $\forall \alpha \in E | \varphi_r^0(\alpha) \subset H$.*

Proof. The relation $p = p_0 \circ p_1$ implies that Δ_r is a differential system of E/H .

Let $x = x(t)$ be an arbitrary curve of B , and α_1^0 a point in E/H so that $p_0(\alpha_1^0) = x(0)$. If $\alpha^0 \in E$ and $p_1(\alpha^0) = \alpha_1^0$, then there is a unique horizontal lift $\alpha = \alpha(t)$ of $x = x(t)$ with respect to p (horizontal = tangent to Δ_r^H), so that $\alpha(0) = \alpha^0$. The curve $p_1(\alpha(t)) = \alpha_1(t)$ is a horizontal lift of $x = x(t)$ with respect to p_0 , and $\alpha_1(0) = \alpha_1^0$ (horizontal = tangent to Δ_r). If $\beta_1 = \beta_1(t)$ is another horizontal lift of $x = x(t)$ with respect to p_0 so that $\beta_1(0) = \alpha_1^0$, then $\alpha_1(t) = \beta_1(t)$. Indeed, let Δ be a differential system of E satisfying conditions (1). Then Δ and Δ_r^H determine a horizontal differential system of a connection Γ_1 in ξ_1 . If $\beta_1 = \beta_1(t)$ is a horizontal lift of $x = x(t)$ with respect to p_0 (horizontal = tangent to Δ_r), then the horizontal lift of $\beta_1 = \beta_1(t)$ with respect to p_1 (horizontal = tangent to horizontal differential system of Γ_1) is a curve $\beta = \beta(t)$, $\beta(0) = \alpha^0$. This implies that $\beta = \beta(t)$ is a horizontal lift of $x = x(t)$ with respect to p (horizontal = tangent to Δ_r^H). But from the unicity of the horizontal lift follow $\beta(t) = \alpha(t)$ and $p_1(\alpha(t)) = p_1(\beta(t))$ and hence $\alpha_1(t) = \beta_1(t)$. Thus we have established that Δ_r has the unique path lifting property.

Let $x = x(t)$ be a closed zero homotopic curve of B . Denote by $\alpha = \alpha(t)$ the horizontal lift of $x = x(t)$ with respect to p (horizontal = tangent to Δ_r^H) so that $\alpha(0) = \alpha^0$, and by $\alpha_1 = \alpha_1(t)$ the horizontal lift $x = x(t)$ with respect to p_0 (horizontal = tangent to Δ_r) so that $\alpha_1(0) = p_1(\alpha^0) = \alpha_1^0$. From Lemma 1, Δ_r is involutive if and only if $\alpha_1(1) = \alpha_1^0$. This condition is equivalent to the condition $\alpha(1) \in p_1^{-1}(\alpha_1^0)$. Since $\alpha(1) = \alpha^0 \cdot a$, a being an element of $\varphi_r^0(\alpha^0)$, the last condition is equivalent to the condition $\forall \alpha^0 \in E | \varphi_r^0(\alpha^0) \subset H$.

Remark 1. The relation $\forall \alpha \in E | \varphi_r^0(\alpha) \subset H$ is equivalent to the relation $\forall \alpha \in E | \varphi_r^0(\alpha) \subset N$. For the former statement to be true it is sufficient that

at least one point $\alpha \in E$ should exist such that $\varphi_R^0(\alpha) \subset N$. It means that the last statement of Theorem 1 may be substituted by the following one :

The differential system Δ_R of E/H is involutive if and only if there is at least one point $\alpha \in E$ such that $\varphi_R^0(\alpha) \subset N$.

Theorem 2. *Let $(\xi; \xi_0, \xi_1)$ be a refinement, and Γ^* a class of connections of ξ . If $\Gamma, \Gamma' \in \Gamma^*$, and $\varphi_R^0(\alpha^0), \varphi_{R'}^0(\alpha^0)$ are the restricted holonomy groups of Γ, Γ' respectively with reference point α^0 , then*

$$(3) \quad \varphi_R^0(\alpha^0) \cdot N = \varphi_{R'}^0(\alpha^0) \cdot N .$$

Proof. We shall establish the inclusion $\varphi_{R'}^0(\alpha^0) \subset \varphi_R^0(\alpha^0) \cdot N$. If $a' \in \varphi_{R'}^0(\alpha^0)$, then there is a zero homotopic curve $x = x(t) \subset B$, such that its horizontal lift with respect to p (horizontal = tangent to $\Delta_{R'}^H$) determined by $\alpha^0 \in E$ be a curve $\alpha = \alpha(t)$ such that $\alpha(0) = \alpha^0, \alpha(1) = \alpha^0 \cdot a'$. In the same way the horizontal lift of $x = x(t)$ with respect to p (horizontal = tangent to Δ_R^H) determined by $\alpha^0 \in E$ is a curve $\alpha = \alpha(t)$ such that $\alpha(0) = \alpha^0, \alpha(1) = \alpha^0 \cdot a, a \in \varphi_R^0(\alpha^0)$. But observing that $\Gamma, \Gamma' \in \Gamma^*$ we obtain $p_1(\alpha(t)) = p_1(\alpha'(t))$; the horizontal lift of $x = x(t)$ with respect to p_0 , horizontal meaning that this lift is tangent to $\Delta_R = p_1'(\Delta_R^H) = p_1'(\Delta_{R'}^H)$, is uniquely determined by $p_1(\alpha^0)$. This implies that for every $0 \leq t \leq 1$ we have $\alpha'(t) = \alpha(t) \cdot b(t)$, where $b(t) \in H$. This relation is satisfied for all the points $\alpha^0 \in p^{-1}(x(0))$. It follows that we have $a' = a \cdot b(1)$ and $\forall c \in G \mid \alpha'(t) \cdot c = \alpha(t) \cdot b(t) \cdot c$ so that $c^{-1} \cdot b(1) \cdot c \in H$. But this means that $b(1) \in N$ and that $\varphi_{R'}^0(\alpha^0) \subset \varphi_R^0(\alpha^0) \cdot N$.

The inclusion established implies also that $\varphi_{R'}^0(\alpha^0) \cdot N \subset \varphi_R^0(\alpha^0) \cdot N$. In the same way we can prove the inclusion $\varphi_R^0(\alpha^0) \cdot N \subset \varphi_{R'}^0(\alpha^0) \cdot N$ and hence $\varphi_R^0(\alpha^0) \cdot N = \varphi_{R'}^0(\alpha^0) \cdot N$.

Corollaries .1. *If among the connections of Γ^* there is one whose restricted holonomy group with reference point a fixed point in E is included in N , then the restricted holonomy groups of all connections of Γ^* , with arbitrary reference points, are included in N (in this case the differential system $\Delta_R = p_1'(\Delta_R^H)$ is involutive).*

2. *If the restricted holonomy groups of two connections of Γ^* with the same reference point in E contain the group N , then these two groups coincide.*

2. The holonomy groups of connections of a class $h_d^{-1}(\Gamma_1)$

Let Δ be a differential system of E , which satisfies conditions (1). By means of Δ we can define a map $h_d: \gamma \rightarrow \gamma_1$ [4, p. 380] as follows: If $\Gamma \in \gamma$, and the horizontal differential system of Γ is Δ_Γ^H , then $h_d(\Gamma)$ is the element of γ_1 , whose horizontal differential system is $\Delta \oplus \Delta_\Gamma^H$.

Denote by $\bar{\Delta}$ the differential system of E which is maximal among all the differential systems of E satisfying the conditions

$$(4) \quad \bar{\Delta} \subset \Delta, \quad \forall a \in G \mid R'_a(\bar{\Delta}) = \bar{\Delta},$$

and recall the following theorem [5, Theorem 7].

Let $\Gamma \in \gamma$ be a connection, and $\Gamma_1 = h_d(\Gamma) \in \gamma_1$ its image in h_d . Then there is a bijection between the set $h_d^{-1}(\Gamma_1)$ and the set of homomorphisms $\{T|T: \mathcal{FV}(E, \Delta_\Gamma^H) \rightarrow \mathcal{FV}(E, \bar{\Delta})\}$ satisfying the conditions

$$(5) \quad \forall a \in G | R'_a \circ T = T \circ R'_a .$$

($\mathcal{FV}(E, \bar{\Delta})$ is the vector bundle defined over E , as the base space, by the differential system $\bar{\Delta}$.)

In what follows we shall utilize an invariant subgroup $N^d \subset G$, defined by Δ in the following way :

Let M^d be the set of elements of Lie algebra g defined by the relation

$$(6) \quad M^d = \bigcup_{\alpha \in E} (d\sigma_\alpha^{-1}(\bar{\Delta}(\alpha))) ,$$

where σ_α is the map $\sigma_\alpha: b \in G \rightarrow \alpha \cdot b \in p^{-1}(p(\alpha))$, and $\bar{\Delta}$ is the differential system of E defined by (4). Utilizing the relation

$$(7) \quad \forall \alpha \in E , \quad a \in G | R_{\alpha^{-1}} \circ \sigma_{\alpha a} = \sigma_\alpha \circ \text{adj } a ,$$

we can prove that

$$(8) \quad M^d \cap g_H = 0 , \quad \forall a \in G | \text{adj } a \cdot (M^d) = M^d .$$

Denote by g^d the smallest linear space of g , which includes the set M^d . From (8) follows $\forall a \in G | \text{adj } a \cdot (g^d) = g^d$. Utilizing the relation $[X, Y] = \lim_{t \rightarrow 0} t^{-1}(\text{adj } a_t^{-1} \cdot X - X)$, [2, p. 41], where $X \in g^d$ and $Y \in g$, we obtain that g^d is an ideal of g . Denote by N^d the invariant subgroup of G , which is connected and defined by g^d .

By means of N^d we shall have

Theorem 3. *Let Δ be a differential system of E satisfying conditions (1), and $h_d: \gamma \rightarrow \gamma_1$ the map defined by Δ . For the restricted holonomy groups of two connections $\Gamma, \Gamma' \in h_d^{-1}(\Gamma_1)$ with reference to the same point in E , we have the next relation*

$$(9) \quad \forall \alpha^0 \in E | \varphi_\Gamma^0(\alpha^0) \cdot N^d = \varphi_{\Gamma'}^0(\alpha^0) \cdot N^d .$$

Proof. In order to establish relation (9) it is sufficient to prove that $\varphi_\Gamma^0(\alpha^0) \subset \varphi_{\Gamma'}^0(\alpha^0) \cdot N^d$ and that $\varphi_{\Gamma'}^0(\alpha^0) \subset \varphi_\Gamma^0(\alpha^0) \cdot N^d$. If these two conditions are satisfied, then $\varphi_\Gamma^0(\alpha^0) \cdot N^d \subset \varphi_{\Gamma'}^0(\alpha^0) \cdot N^d$ and $\varphi_{\Gamma'}^0(\alpha^0) \cdot N^d \subset \varphi_\Gamma^0(\alpha^0) \cdot N^d$, and hence $\varphi_\Gamma^0(\alpha^0) \cdot N^d = \varphi_{\Gamma'}^0(\alpha^0) \cdot N^d$.

We shall prove that $\varphi_\Gamma^0(\alpha^0) \subset \varphi_{\Gamma'}^0(\alpha^0) \cdot N^d$. Let a be an arbitrary element of $\varphi_\Gamma^0(\alpha^0)$. Then there is a curve $x = x(t)$ of B , which is closed in $p(\alpha^0)$ and zero homotopic, the horizontal lift $\alpha = \alpha(t)$ of which with respect to p (horizontal = tangent to Δ_Γ^H) satisfies the conditions $\alpha(0) = \alpha^0$, $\alpha(1) = \alpha^0 \cdot a$. Let us also

consider the horizontal lift $\alpha' = \alpha'(t)$ of $x = x(t)$ with respect to p (horizontal = tangent to Δ_R^H). Evidently we have $\alpha(t) \cdot a(t) = \alpha'(t)$ where $a(t) \in G$. By means of Leibnitz formula we obtain

$$(10) \quad \frac{d\alpha'}{dt} = \frac{d\alpha}{dt} \cdot a(t) + d\sigma_{\alpha(t) \cdot a(t)} \circ L'_{(a(t))^{-1}} \frac{da}{dt}.$$

Denote $d\alpha'/dt - (d\alpha/dt) \cdot a(t) = X_{\alpha(t)a(t)}$. Obviously, $X_{\alpha(t)a(t)} \in \bar{\Delta}(\alpha(t)a(t))$. If we denote $X_{\alpha(t)} = R'_{a^{-1}(t)}(X_{\alpha(t)a(t)})$, then we have $X_{\alpha(t)} \in \bar{\Delta}(\alpha(t))$. Relation (10) is equivalent to

$$(11) \quad d\sigma_{\alpha^{-1}}(X_{\alpha(t)}) = R'_{(a(t))^{-1}} da/dt.$$

By the lemma [2, p. 69] and $d\sigma_{\alpha(t)}^{-1}(X_{\alpha(t)}) \in M^d$, $\forall t \in [0, 1]$, we obtain a unique curve $a(t) \in N^d$ such that $a(0) = e$, satisfying (11), differentiable of at least order 1. For this curve relation (10) is satisfied and hence $\alpha'(t) = \alpha(t) \cdot a(t)$. It follows that $\alpha(1) \cdot a(1) = \alpha'(1)$ and consequently $a \cdot a(1) = a'$ where a' is the element of $\varphi_R^0(\alpha^0)$ defined by the horizontal lift of $x = x(t)$ with respect to p (horizontal = tangent to Δ_R^H). In conclusion we have proved that to each element $a \in \varphi_R^0(\alpha^0)$ we can associate an element $a_1 \in N^d$ such that $aa_1 \in \varphi_R^0(\alpha^0)$. Then $a = (aa_1) \cdot a_1^{-1} \in \varphi_R^0(\alpha^0) \cdot N^d$ and hence $\varphi_R^0(\alpha^0) \subset \varphi_R^0(\alpha^0) \cdot N^d$. In the same way we can prove the inclusion $\varphi_R^0(\alpha^0) \subset \varphi_R^0(\alpha^0) \cdot N^d$. According to the first part of this proof, we obtain relation (9).

Remark 2. Let M be the union of sets M^d for all Δ satisfying conditions (1). If g_0 is the smallest linear space of g which contains M , then g_0 is an ideal of g , which defines an invariant subgroup N_0 of g . Evidently for every Δ we have $N^d \subset N_0$, and if $\Gamma' \in h_{\Delta}^{-1}(h_{\Delta}(\Gamma))$ then

$$(12) \quad \forall \alpha \in E \mid \varphi_R^0(\alpha^0) \cdot N_0 = \varphi_R^0(\alpha^0) \cdot N_0.$$

If N_1 is an invariant subgroup of G such that $N_1 \cap H = \{e\}$, then $g_{N_1} \subset M$ and $N_1 \subset N_0$, where g_{N_1} is the Lie algebra of N_1 .

Remark 3. Relation (6) shows that the subgroup N^d is defined by the differential system $\bar{\Delta}$ satisfying conditions (4). Accordingly we can obtain the following result: Let $\Gamma, \Gamma' \in \gamma$ be a pair of connections. If we consider the homomorphism $T: \mathcal{F}\mathcal{V}(E, \Delta_R^H) \rightarrow \mathcal{F}\mathcal{V}(E, \Delta^V)$ defined by the couple Γ, Γ' [5, Theorem 1] and if $\text{Im } T \cap \Delta_1^V = 0$, then between the restricted holonomy groups of Γ, Γ' we have relation (9) where N^d is substituted by the invariant subgroup $N^{d_{m^T}}$ of G .

3. The holonomy groups of connections $\Gamma \in \gamma$ and $h_{\Delta}(\Gamma) \in \gamma_1$

Let Δ be a differential system of E satisfying conditions (1). If $\Gamma \in \gamma$ and

$\Gamma_1 = h_\Delta(\Gamma)$, then for the holonomy groups of the two connections we have [4, p. 380]

$$(13) \quad \forall \alpha \in E \mid \varphi_\Gamma(\alpha) \cap H \subset \varphi_{\Gamma_1}(\alpha) \subset H .$$

Lemma 2. *Let $(\xi; \xi_0, \xi_1)$ be the refinement of ξ defined by H . For an arbitrary point $x \in B$, the restriction of ξ_1 to $p_0^{-1}(x)$ is a principal differentiable bundle $\xi_x = (p^{-1}(x), p_0^{-1}(x), p_1/p^{-1}(x), H; \mathcal{A}_x)$ isomorphic to $(G, G/H)$, [6, p. 39].*

Proof. ξ_x is a principal differentiable bundle with $p^{-1}(x)$ as the total space, $p_0^{-1}(x)$ as the base space, $p_1/p^{-1}(x)$ as the projection, H as the type fiber and structural group. The trivialization atlas \mathcal{A}_x is defined by means of the trivialization atlases of ξ and $(G, G/H)$ in the following way: If (U, φ_U) is a trivialization map of ξ so that $x \in U$, and if (u, f) is a trivialization map of $(G, G/H)$, then define a map $(V, \psi) \in \mathcal{A}_x$ by the relations: $V = U_1 \cap p_0^{-1}(x)$ where $U_1 = \varphi_{U,1}(U \times u)$ and $\psi = \varphi_{u,12}(V \times H)$ (see [4, Relation (19), p. 372]).

We can observe that for an arbitrary $a \in H$ the right translation of ξ_x coincides with the right translation of ξ_1 ,

Let α be a fixed element of $p^{-1}(x)$. Define an isomorphism $(i_\alpha, i'_\alpha) : \xi_x \rightarrow (G, G/H)$ by the relations

$$i_\alpha : \beta = \alpha \cdot a \rightarrow a \in G ; \quad i'_\alpha = 1_H .$$

Then we have $\forall b \in G \mid i_\alpha(\beta \cdot b) = i_\alpha(\beta) \cdot i'_\alpha(b)$.

Remark 4. The differential system Δ of E satisfying conditions (1) defines a connection Γ_Δ^x in every ξ_x . The holonomy group of Γ_Δ^x with reference point $\alpha \in p^{-1}(x)$ is denoted by $\varphi_{(x,\Delta)}(\alpha)$.

Remark 5. If the differential system Δ of E satisfying conditions (1) is fixed and if Γ_1 is a connection at ξ_1 such that $\Delta_{\Gamma_1}^H \supset \Delta$, then

$$(14) \quad \forall \alpha \in E \mid \varphi_{(x,\Delta)}(\alpha) \subset \varphi_{\Gamma_1}(\alpha) \subset H , \quad p(\alpha) = x .$$

Remark 6. 1. Relation (13) shows that if for a point $\alpha \in E$ the holonomy group $\varphi_\Gamma(\alpha)$ of a connection $\Gamma \in \gamma$ satisfies the conditions $\varphi_\Gamma(\alpha) \supset H$, then $h_\Delta(\Gamma)$ for all Δ has H as a holonomy group.

2. Relation (14) shows that if Δ is a differential system of E satisfying conditions (1) such that the connection defined by Δ in ξ_x (x arbitrary in B) has H as holonomy groups, then all connections Γ_1 satisfying the condition $\Delta \subset \Delta_{\Gamma_1}^H$ have H as holonomy group.

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