

#### 44. Mountain Pass Theorems for Non-differentiable Functions and Applications

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**Abstract:** We present some versions of the Mountain Pass Theorem of Ambrosetti and Rabinowitz for locally Lipschitz functionals. A multivalued elliptic problem is solved as an application of these results.

**Key words:** Clarke subdifferential; critical point theory; multivalued elliptic problem.

**1. Introduction.** The Mountain Pass Theorem of Ambrosetti and Rabinowitz [1] is a very useful tool for finding critical points of  $C^1$ -functionals. We shall give some variants of this celebrated theorem for locally Lipschitz mappings.

Throughout,  $X$  will be a real Banach space. As usual,  $X^*$  denotes the dual of  $X$  and  $\langle \cdot, \cdot \rangle$  is the duality pairing between  $X^*$  and  $X$ . We say that a function  $f : X \rightarrow \mathbf{R}$  is locally Lipschitz ( $f \in Lip_{loc}(X, \mathbf{R})$ ) if, for each  $x \in X$ , there is a neighbourhood  $V$  of  $x$  and a constant  $k = k(V)$  depending on  $V$  such that  $|f(y) - f(z)| \leq k \|y - z\|$  for each  $y, z \in V$ .

We recall in what follows the definition of the Clarke subdifferential and some of its most important properties (see, for details, [6]).

For each  $x, v \in X$ , we define the generalized directional derivative at  $x$  in the direction  $v$  of a given  $f \in Lip_{loc}(X, \mathbf{R})$  as

$$f^0(x, v) = \limsup_{y \rightarrow x, \lambda \searrow 0} (f(y + \lambda v) - f(y)) / \lambda.$$

It is known that, if  $f \in Lip_{loc}(X, \mathbf{R})$ , then  $f^0(x, v)$  is a finite number and  $|f^0(x, v)| \leq k \|v\|$ . The mapping  $v \mapsto f^0(x, v)$  is positively homogeneous and subadditive, and then, it is convex continuous. The generalized gradient (the Clarke subdifferential) of  $f$  at  $x$  is the subset  $\partial f(x)$  of  $X^*$  defined by  $\partial f(x) = \{x^* \in X^*; f^0(x, v) \geq \langle x^*, v \rangle, \forall v \in X\}$ .

The fundamental properties of the Clarke subdifferential are: a) For each  $x \in X$ ,  $\partial f(x)$  is a nonempty convex  $\star$ -compact subset of  $X^*$ .

b) For each  $x, v \in X$ , we have  $f^0(x, v) = \max \{\langle x^*, v \rangle; x^* \in \partial f(x)\}$ ,

c) The set-valued mapping  $x \rightarrow \partial f(x)$  is upper semi-continuous in the sense that for each  $x_0 \in X$ ,  $\varepsilon > 0$ ,  $v \in X$ , there is  $\delta > 0$  such that for each  $x^* \in \partial f(x)$  with  $\|x - x_0\| < \delta$ , there exists  $x_0^* \in \partial f(x_0)$  such that  $|\langle x^* - x_0^*, v \rangle| < \varepsilon$ .

d) The function  $f^0(\cdot, \cdot)$  is upper semi-continuous.

e) If  $f$  attains a local minimum or maximum at  $x$ , then  $0 \in \partial f(x)$ .

f) The function  $\lambda(x) = \min \{\|x^*\|; x^* \in \partial f(x)\}$  exists and is lower

semi-continuous.

**Definition 1.** A point  $u \in X$  is said to be a critical point of  $f \in Lip_{loc}(X, \mathbf{R})$  if  $0 \in \partial f(u)$ , namely  $f^0(x, v) \geq 0$  for every  $v \in X$ . A real number  $c$  is called a critical value of  $f$  if there is a critical point  $u \in X$  such that  $\partial f(u) = c$ .

**Definition 2.** If  $f \in Lip_{loc}(X, \mathbf{R})$  and  $c$  is a real number, we say that  $f$  satisfies the Palais-Smale condition at the level  $c$  (in short  $(PS)_c$ ) if any sequence  $(x_n)$  in  $X$  with the properties  $\lim_{n \rightarrow \infty} f(x_n) = c$  and  $\lim_{n \rightarrow \infty} \lambda(x_n) = 0$  has a convergent subsequence.

**2. Main results.** In what follows,  $f$  will be a locally Lipschitz function on the real Banach space  $X$ . Let  $K$  be a compact metric space and let  $K^*$  be a nonempty closed subset of  $K$ . If  $p^*$  is a fixed continuous map defined on  $K$ , let  $\mathcal{P} = \{p \in C(K, X) ; p = p^* \text{ on } K^*\}$ . Define

$$(1) \quad c = \inf_{p \in \mathcal{P}} \max_{t \in K} f(p(t)).$$

Clearly,  $c \geq \max_{t \in K^*} f(p^*(t))$ .

**Theorem 1.** Assume that

$$(2) \quad c > \max_{t \in K^*} f(p^*(t))$$

Then there exists a sequence  $(x_n)$  in  $X$  such that

$$i) \lim_{n \rightarrow \infty} f(x_n) = c, \quad ii) \lim_{n \rightarrow \infty} \lambda(x_n) = 0.$$

**Corollary 1.** If  $f$  has  $(PS)_c$  and satisfies the same assumptions as in Theorem 1, then  $c$  is a critical value of  $f$ , corresponding to a critical point which is not in  $p^*(K^*)$ .

The proof follows from Theorem 1 and the lower-semicontinuity of the function  $\lambda$ .

**Corollary 2.** Suppose  $f(0) = 0$  and there exists  $v \in X \setminus \{0\}$  such that  $f(v) \leq 0$ . If  $c > 0$  and  $f$  satisfies  $(PS)_c$ , then  $c$  is a critical value of  $f$ .

For the proof, it suffices to apply Corollary 1 for  $K = [0, 1]$ ,  $K^* = \{0, 1\}$ ,  $p^*(0) = 0$  and  $p^*(1) = v$ .

If (2) fails, a sufficient condition which ensures the validity of Theorem 1 is given by the following result, which is a variant of Theorem 1 in [9].

**Theorem 2.** Assume that for every  $p \in \mathcal{P}$  there is some point  $t \in K \setminus K^*$  such that  $f(p(t)) \geq c$ . Then there exists a sequence  $(x_n)$  in  $X$  such that

$$i) \lim_{n \rightarrow \infty} f(x_n) = c, \quad ii) \lim_{n \rightarrow \infty} \lambda(x_n) = 0.$$

Assume, in addition, that  $f$  satisfies  $(PS)_c$ . Then  $c$  is a critical value of  $f$ . Furthermore, if  $(p_n)$  is any sequence in  $\mathcal{P}$  such that  $\lim_{n \rightarrow \infty} \max f(p_n(t)) = c$ , then there exists a sequence  $(t_n)$  in  $K$  such that  $\lim_{n \rightarrow \infty} f(p_n(t_n)) = c$  and  $\lim_{n \rightarrow \infty} \lambda(p_n(t_n)) = 0$ .

*Proof of Theorem 1.* We apply Ekeland's variational principle to the functional  $\phi(p) = \max \{f(p(t)) ; t \in K\}$  defined on the complete metric space  $\mathcal{P}$ , endowed with the usual metric. The function  $\phi$  is continuous on  $\mathcal{P}$  and bounded below, because  $\phi(p) \geq \max_{t \in K^*} f(p^*(t))$ . Since  $c = \inf_{p \in \mathcal{P}} \phi(p)$ , it follows that, for every  $\varepsilon > 0$ , there exists  $p \in \mathcal{P}$  such that

$$(3) \quad \phi(q) - \phi(p) + \varepsilon d(p, q) \geq 0, \text{ for each } q \in \mathcal{P}$$

$$(4) \quad c \leq \phi(p) \leq c + \varepsilon.$$

Setting

$$B(p) = \{t \in K ; f(p(t)) = \phi(p)\}$$

it suffices to prove that there exists  $t' \in B(p)$  such that

$$(5) \quad \lambda(p(t')) \leq 2\varepsilon.$$

Then the conclusion of the theorem follows easily by choosing  $\varepsilon = \frac{1}{n}$  and  $x_n = p(t')$ .

We need now the following result :

**Lemma 1.** *Let  $M$  be a compact metric space and let  $\varphi : M \rightarrow 2^{X^*}$  be a set-valued mapping which is upper semi-continuous (in the sense of property c) and with  $\star$ -compact convex values. For  $t \in M$  denote  $\gamma(t) = \inf \{\|x^*\| ; x^* \in \varphi(t)\}$  and  $\gamma = \inf \{\gamma(t) ; t \in M\}$ .*

*Then, given  $\varepsilon > 0$ , there exists a continuous function  $v : M \rightarrow X$  such that for all  $t \in M$  and  $x^* \in \varphi(t)$ ,  $\|v(t)\| \leq 1$  and  $\langle x^*, v(t) \rangle \geq \gamma - \varepsilon$ .*

For the proof of this lemma, see [5]. Applying Lemma 1 for  $M = B(p)$  and  $\varphi(t) = \partial f(p(t))$  we obtain a continuous function  $v : B(p) \rightarrow X$  such that for all  $t \in B(p)$  and  $x^* \in \partial f(p(t))$ ,

$$(6) \quad \|v(t)\| \leq 1 \text{ and } \langle x^*, v(t) \rangle \geq \gamma - \varepsilon.$$

where  $\gamma = \inf_{t \in B(p)} \lambda(p(t))$ .

It follows that for each  $t \in B(p)$ ,

$$f^0(p(t), -v(t)) = \max\{\langle x^*, -v(t) \rangle ; x^* \in \partial f(p(t))\} = -\min\{\langle x^*, v(t) \rangle ; x^* \in \partial f(p(t))\} \leq -\gamma + \varepsilon.$$

By assumption (2),  $B(p) \cap K^* = \emptyset$ . Thus there is a continuous function  $w : K \rightarrow X$  which extends  $v$  such that  $w|_{K^*} = 0$  and  $\|w(t)\| \leq 1$  for each  $t \in K$ . We take for  $q$ , in (3), small variations of the path  $p$ :  $q_h(t) = p(t) - hw(t)$  where  $h > 0$  is small enough.

It follows from (3) that for every  $h > 0$

$$(7) \quad -\varepsilon \leq -\varepsilon \|w\|_\infty \leq \frac{\phi(q_h) - \phi(p)}{h}.$$

In what follows,  $\varepsilon > 0$  is fixed while we let  $h \rightarrow 0$ . Let  $t_h \in K$  be such that  $f(q_h(t_h)) = \max_{t \in K} f(q_h(t))$ . For a suitable sequence  $h_n \rightarrow 0$ ,  $t_{h_n}$  converges to some  $t_0$  which belongs to  $B(p)$ . Therefore,

$$\frac{\phi(q_h) - \phi(p)}{h} = \frac{\phi(p - hw) - \phi(p)}{h} \leq \frac{f(p(t_h) - hw(t_h)) - f(p(t_h))}{h}.$$

It follows from (7) that

$$\begin{aligned} \varepsilon &\leq \frac{f(p(t_h) - hw(t_h)) - f(p(t_h))}{h} \leq \\ &\leq \frac{f(p(t_h) - hw(t_0)) - f(p(t_h))}{h} + \frac{f(p(t_h) - hw(t_h)) - f(p(t_h) - hw(t_0))}{h}. \end{aligned}$$

Using the fact that  $f$  is locally Lipschitz and that the sequence  $(t_{h_n})$  converges to  $t_0$ , we get

$$\lim_{n \rightarrow \infty} \frac{f(p(t_{h_n}) - h_n w(t_{h_n})) - f(p(t_{h_n}) - h_n w(t_0))}{h_n} = 0.$$

Therefore,

$$-\varepsilon \leq \limsup_{n \rightarrow \infty} \frac{f(p(t_0) + z_n - h_n w(t_0)) - f(p(t_0) + z_n)}{h_n}$$

where  $z_n = p(t_{h_n}) - p(t_0)$ . Consequently,

$$-\varepsilon \leq f^0(p(t_0), -w(t_0)) = f^0(p(t_0), -v(t_0)) \leq -\gamma + \varepsilon$$

which implies  $\gamma = \inf \{\|x^*\|; x^* \in \partial f(p(t)), t \in B(p)\} \leq 2\varepsilon$ .

It follows from the lower semi-continuity of  $\lambda$  that there is some  $t' \in B(p)$  such that  $\lambda(p(t')) = \inf \{\|x^*\|; x^* \in \partial f(p(t))\} \leq 2\varepsilon$ .

*Proof of Theorem 2.* We shall apply Ekeland's variational principle to the functional  $\phi_\varepsilon(p) = \max \{f(p(t)) + \varepsilon d(t); t \in K\}$

for each  $\varepsilon > 0$  and  $p \in \mathcal{P}$ , where  $d(t) = \min \{\text{dist}(t, K^*), 1\}$ .

If  $c_\varepsilon = \inf_{p \in \mathcal{P}} \phi_\varepsilon(p)$ , then  $c \leq c_\varepsilon \leq c + \varepsilon$ .

Applying Ekeland's variational principle, we get a path  $p \in \mathcal{P}$  such that for each  $q \in \mathcal{P}$ ,

$$(8) \quad \phi_\varepsilon(q) - \phi_\varepsilon(p) + \varepsilon d(p, q) \geq 0$$

$$(9) \quad c \leq c_\varepsilon \leq \phi_\varepsilon(p) \leq c_\varepsilon + \varepsilon \leq c + 2\varepsilon.$$

Setting  $B_\varepsilon(p) = \{t \in K; f(p(t)) + \varepsilon d(t) = \phi_\varepsilon(p)\}$ ,

it remains to prove that we can find some  $t' \in B_\varepsilon(p)$  such that  $\lambda(p(t')) \leq 2\varepsilon$ . We obtain thereafter the conclusion of the first part of the theorem by choosing  $\varepsilon = \frac{1}{n}$  and  $x_n = p(t')$ .

Applying Lemma 1 for  $M = B_\varepsilon(p)$  and  $\varphi(t) = \partial f(p(t))$ , we get a continuous map  $v : B_\varepsilon(p) \rightarrow X$  such that for all  $t \in B_\varepsilon(p)$  and  $x^* \in \partial f(p(t))$ ,

$$\|v(t)\| \leq 1 \text{ and } \langle x^*, v(t) \rangle \geq \gamma - \varepsilon$$

where  $\gamma = \inf \{\lambda(p(t)); t \in B_\varepsilon(p)\}$ .

But our hypothesis implies

$$(10) \quad \phi_\varepsilon(p) > \max \{f(p(t)); t \in K^*\}.$$

Hence,  $B_\varepsilon(p) \cap K^* = \emptyset$ . Thus, there exists a continuous function  $w$  defined on  $K$  which extends  $v$  such that  $w|_{B_\varepsilon(p)} = 0$  and  $\|w(t)\| \leq 1$  for all  $t \in K^*$ . We take for  $q$ , in (8), small variations of the path  $p$ :

$q_h(t) = p(t) - hw(t)$  for  $h > 0$  small enough.

In what follows,  $\varepsilon > 0$  will be fixed while we let  $h \rightarrow 0$ . There exists  $t_h \in B_\varepsilon(p)$  such that  $f(q_h(t_h)) + \varepsilon d(t_h) = \phi_\varepsilon(q_h)$ . For a suitable sequence  $h_n \rightarrow 0$ ,  $t_{h_n}$  converges to some  $t_0 \in B_\varepsilon(p)$ . It follows that

$$\begin{aligned} -\varepsilon &\leq -\varepsilon \|w\|_\infty \leq \frac{\phi_\varepsilon(q_h) - \phi_\varepsilon(p)}{h} = \frac{f(q_h(t_h)) + \varepsilon d(t_h) - \phi_\varepsilon(p)}{h} \leq \\ &\leq \frac{f(q_h(t_h)) - f(p(t_h))}{h} = \frac{f(p(t_h) - hw(t_h)) - f(p(t_h))}{h}. \end{aligned}$$

With the same reasoning as in the proof of Theorem 1 we get that there is some  $t' \in B_\varepsilon(p)$  such that  $\lambda(p(t')) \leq 2\varepsilon$ .

If  $f$  has  $(PS)_c$ , then  $c$  is a critical value because of the lower semi-continuity of  $\lambda$ .

For the second part of the proof, there exists, by Ekeland's variational principle, a sequence of paths  $(q_n)$  in  $\mathcal{P}$  such that for each  $q \in \mathcal{P}$ ,

$\phi_{\varepsilon_n^2}(q) - \phi_{\varepsilon_n^2}(q_n) + \varepsilon_n d(q, q_n) \geq 0$  and  $\phi_{\varepsilon_n^2}(q_n) \leq \phi_{\varepsilon_n^2}(p_n) - \varepsilon_n d(p_n, q_n)$ , where  $(\varepsilon_n)$  is a sequence of positive numbers which tends to 0 and  $(p_n)$  are

paths in  $\mathcal{P}$  such that  $\psi_{\varepsilon_n^2}(p_n) \leq c + 2\varepsilon_n^2$ . It follows that  $d(p_n, q_n) \leq 2\varepsilon_n$ . Applying the preceding argument to  $(q_n)$ , instead of  $p$ , we find some elements  $t_n \in K$  such that  $c - \varepsilon_n^2 \leq f(q_n(t_n)) \leq c + 2\varepsilon_n^2$  and  $\lambda(q_n(t_n)) \leq 2\varepsilon_n$ .

This is the desired sequence  $(t_n)$ . Indeed, by  $(PS)_c$ , a subsequence of  $q_n(t_n)$  converges to a critical point and then the corresponding subsequence of  $p_n(t_n)$  converges to the same limit. A standard argument, using the continuity of  $f$  and the lower semi-continuity of  $\lambda$ , shows that for the full sequence,  $\lim_{n \rightarrow \infty} f(p_n(t_n)) = c$  and  $\lim_{n \rightarrow \infty} \lambda(p_n(t_n)) = 0$ .

**3. An application.** Let  $\Omega$  be a smooth bounded domain in  $\mathbf{R}^N (N \geq 3)$  and  $g$  be a measurable function defined on  $\Omega \times \mathbf{R}$  satisfying, for all  $(x, t) \in \Omega \times \mathbf{R}$

$$(11) \quad |g(x, t)| \leq C_0(1 + |t|^p)$$

where  $C_0$  is a positive constant and  $1 \leq p < \frac{N+2}{N-2}$ .

Define the functional  $\phi$  in  $L^{p+1}(\Omega)$  by

$$\phi(u) = \int_{\Omega} \int_0^{u(x)} g(x, t) dt dx.$$

The fact that  $\phi$  is a locally Lipschitz function in  $L^{p+1}(\Omega)$  follows from the growth condition (11) and the Hölder inequality.

Setting  $G(x, t) = \int_0^t g(x, s) ds$ , then, by Theorem 2.1. in [Ch], the Clarke subdifferential  $\partial_t G(x, t)$  of the mapping  $t \mapsto G(x, t)$  is given by  $\partial_t G(x, t) = [\underline{g}(x, t), \bar{g}(x, t)]$ , where

$$\begin{aligned} \underline{g}(x, t) &= \lim_{\varepsilon \searrow 0} \text{ess inf} [g(x, s) ; |t - s| < \varepsilon] \\ \bar{g}(x, t) &= \lim_{\varepsilon \searrow 0} \text{ess sup} [g(x, s) ; |t - s| < \varepsilon]. \end{aligned}$$

Assuming that

$$(12) \quad \underline{g} \text{ and } \bar{g} \text{ are measurable on } \Omega \times \mathbf{R},$$

by Theorems 2.1. and 2.2. in [Ch] it follows that

$$(13) \quad \partial_{\phi|_{H_0^1(\Omega)}}(u) \subset \partial\phi(u) \subset \partial_t G(x, t) \quad a.e. x \in \Omega.$$

We suppose, in addition, that

$$(14) \quad g(x, 0) = 0 \text{ and } \limsup_{t \rightarrow 0} \left| \frac{g(x, t)}{t} \right| < \lambda_1 \text{ uniformly in } x \in \Omega$$

and

$$(15) \quad \mu G(x, t) \leq \begin{cases} t \underline{g}(x, t), & a.e. x \in \Omega, t \geq r \\ t \bar{g}(x, t), & a.e. x \in \Omega, t \leq -r \end{cases}$$

for some  $\mu > 2$  and  $r \geq 0$ .

**Proposition 1.** *Let  $a \in L^\infty(\Omega)$  be a non-negative function and suppose that conditions (11), (12), (13), (14) and (15) hold. Then the multivalued non-linear elliptic problem*

$$(16) \quad -\Delta u(x) + a(x)u(x) \in [g(x, u(x)), \bar{g}(x, u(x))] \quad a.e. x \in \Omega$$

has a solution in  $H_0^1(\Omega) \cap W^{2,p'}(\Omega)$ , where  $p'$  is the conjugated exponent of  $p$ .

*Sketch of the proof.* We consider in  $H_0^1(\Omega)$  the locally Lipschitz function

$$\varphi(u) = \frac{1}{2} \|\nabla u\|_{L^2(\Omega)}^2 + \frac{1}{2} \int_{\Omega} a(x)u^2(x) dx - \phi(u).$$

To prove our statement it suffices to show that  $\varphi$  has a critical point

$u_0 \in H_0^1(\Omega)$  corresponding to a positive critical value. Indeed, it is obvious that  $\partial\varphi(u) = -\Delta u + a(x)u - \partial\psi|_{H_0^1(\Omega)}(u)$  in  $H^{-1}(\Omega)$ .

If  $u_0$  would be a critical point of  $\varphi$  it follows that there would exist  $w \in \partial\varphi|_{H_0^1(\Omega)}(u_0)$  such that  $-\Delta u_0 + a(x)u_0 = w$  in  $H^{-1}(\Omega)$ .

But  $w \in L^{p'}(\Omega)$ . Then by a standard regularity theorem for elliptic equations we obtain that  $u_0 \in W^{2,p}(\Omega)$  and  $u_0$  is a solution of the problem (16).

To prove that  $\varphi$  has a critical point we apply Corollary 2, by showing that  $\varphi$  satisfies the Palais-Smale condition and the following geometrical assumptions:

$\varphi(0) = 0$  and there exists  $v \in H_0^1(\Omega)$  such that  $\varphi(v) \leq 0$ .

There exist  $c > 0$  and  $0 < R < \|v\|$  such that  $\varphi|_{\partial B(0,R)} \geq c$ .

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