

## 20. Strong Continuity of the Solution to the Ljapunov Equation $XL - BX = C$ Relative to an Elliptic Operator $L$

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**§ 1. Introduction.** An operator equation, the so called Ljapunov equation, often appears in stabilization studies of linear parabolic systems. The equation is written as  $XL - BX = C$ , where the operators  $L$ ,  $B$ , and  $C$  are given linear operators acting in separable Hilbert spaces, and are derived from a specific boundary feedback control system [6, 7, 8]. A general stabilization scheme for an unstable parabolic equation has been established in [6]. The parabolic equation containing  $L$  as a coefficient operator is often affected by small perturbations which may be sometimes interpreted as errors in mathematical formulation of a physical system. In such a case, does the feedback scheme still work for stabilization of the perturbed equation? A study of continuity of a solution  $X$  relative to  $L$  is fundamental to answer the question. It is the purpose of the paper to examine the continuity of  $X$ . We will see in § 2 below an affirmative result on this problem.

Let us specify the operators  $L$ ,  $B$ , and  $C$ .  $\mathcal{L}$  will denote a strongly elliptic differential operator of order 2 in a connected bounded domain  $\Omega$  of  $\mathbb{R}^m$  with a finite number of smooth boundaries  $\Gamma$  of  $(m-1)$ -dimension;

$$\mathcal{L}u = - \sum_{i,j=1}^m \frac{\partial}{\partial x_i} \left( a_{ij}(x) \frac{\partial u}{\partial x_j} \right) + \sum_{i=1}^m b_i(x) \frac{\partial u}{\partial x_i} + c(x)u,$$

where  $a_{ij}(x) = a_{ji}(x)$ ,  $1 \leq i, j \leq m$ , and for some positive  $\delta$

$$\sum_{i,j=1}^m a_{ij}(x) \xi_i \xi_j \geq \delta |\xi|^2, \quad \xi = (\xi_1, \dots, \xi_m), \quad x \in \Omega.$$

Associated with  $\mathcal{L}$  is a generalized Neumann boundary operator  $\tau$ ;

$$\tau u = \frac{\partial u}{\partial \nu} + \sigma(\xi)u,$$

where  $\partial/\partial \nu = \sum_{i,j=1}^m a_{ij}(\xi) \nu_i(\xi) \partial/\partial x_j$ , and  $(\nu_1(\xi), \dots, \nu_m(\xi))$  indicates the outward normal at  $\xi \in \Gamma$ . Then,  $L$  is defined in  $L^2(\Omega)$  by

$$Lu = \mathcal{L}u, \quad u \in \mathcal{D}(L) = \{u \in H^2(\Omega); \tau u = 0 \text{ on } \Gamma\}.$$

All norms hereafter will be either  $L^2(\Omega)$ - or  $\mathcal{L}(L^2(\Omega))$ -norm unless otherwise indicated. As is well known [2], the spectrum  $\sigma(L)$  lies in the interior of a parabola  $\{\lambda = \sigma + i\tau; \sigma = a\tau^2 - b, \tau \in \mathbb{R}^1\}$ ,  $a > 0$ . Second, the general structure of the operator  $B$  is specified in the following lemma:

**Lemma 1.1** [6]. *Let  $A$  be a positive-definite self-adjoint operator in a separable Hilbert space  $H_0$  with a compact resolvent. Let  $\{\mu_i^2, \zeta_{ij}; i \geq 1, 1 \leq j \leq n_i (< \infty)\}$  denote the eigenpairs of  $A$  ( $\mu_i^2$  are labelled according to increasing order, and  $\zeta_{ij}$  normalized). Define  $H$  and  $B$  as*

$$H = \mathcal{D}(A^{1/2}) \times H_0,$$

and

$$B = \begin{bmatrix} 0 & -1 \\ A & 2aA^{1/2} \end{bmatrix}, \quad \mathcal{D}(B) = \mathcal{D}(A) \times \mathcal{D}(A^{1/2}), \quad a \in (0, 1)$$

respectively. Furthermore, set

$$\eta_{ij}^\pm = \frac{1}{\sqrt{2} \mu_i} \begin{bmatrix} \zeta_{ij} \\ -\mu_i \omega^\pm \zeta_{ij} \end{bmatrix}, \quad i \geq 1, 1 \leq j \leq n_i, \quad \omega^\pm = a \pm \sqrt{1 - a^2} i.$$

Then

- (i)  $\sigma(B) = \{\mu_i \omega^\pm; i \geq 1\}$ ,  $0 < \mu_1 < \mu_2 < \dots \rightarrow \infty$ ;
- (ii)  $B\eta_{ij}^\pm = \mu_i \omega^\pm \eta_{ij}^\pm$ ,  $i \geq 1, 1 \leq j \leq n_i$ ; and
- (iii) the set  $\{\eta_{ij}^\pm; i \geq 1, 1 \leq j \leq n_i\}$  forms a normalized Riesz basis for  $H$ .

**Remark.** Define a real Hilbert space  $\hat{H}$  by

$$\hat{H} = \left\{ h \in H; h = \sum_{i=1}^{\infty} \sum_{j=1}^{n_i} (h_{ij} \eta_{ij}^+ + \overline{h_{ij}} \eta_{ij}^-), \sum_{i,j} |h_{ij}|^2 < \infty \right\}.$$

Then, it is easy to see that  $B$  maps  $\mathcal{D}(B) \cap \hat{H}$  onto  $\hat{H}$ .

Let  $c$  be a positive constant, and set  $L_c = L + c$  so that  $\sigma(L_c)$  is entirely contained in the right half-plane. Choose real-valued  $w_k \in L^2(\Gamma)$ , and  $\xi_k \in \hat{H}$ ,  $1 \leq k \leq N$ ,  $N$  being some integer. Then, the operator  $C$  is defined as

$$Cu = - \sum_{k=1}^N \langle L_c^{\alpha/2} u, w_k \rangle_r \xi_k, \quad \alpha = \frac{1}{2} + 2\epsilon, \quad 0 < \epsilon < \frac{1}{4},$$

where  $\langle \cdot, \cdot \rangle_r$  indicates the inner product in  $L^2(\Gamma)$ . Physically,  $w_k$ 's are interpreted as weighting functions for observations located on  $\Gamma$ , and  $\xi_k$ 's as actuators of a so called compensator [6, 7, 8] in a feedback control system. The number  $N$  plays an important role in stabilization studies. Let  $\xi_k$  be expressed by  $\sum_{i,j} (\xi_{ij}^k \eta_{ij}^+ + \overline{\xi_{ij}^k} \eta_{ij}^-)$ . Finally, we assume that

$$\sigma(L) \cap \sigma(B) = \emptyset.$$

Under this assumption, we have

**Theorem 1.2** [6]. *The Ljapunov equation  $XL - BX = C$  on  $\mathcal{D}(L)$  has a unique solution  $X \in \mathcal{L}(L^2(\Omega); H) \cap \mathcal{L}(L_R^2(\Omega); \hat{H})^*$ . The solution  $X$  is expressed by*

$$(1) \quad Xu = \sum_{i,j} \sum_{k=1}^N f_k(\mu_i \omega^+; u) \xi_{ij}^k \eta_{ij}^+ + \sum_{i,j} \sum_{k=1}^N f_k(\mu_i \omega^-; u) \overline{\xi_{ij}^k} \eta_{ij}^-, \\ f_k(\lambda; u) = \langle L_c^{\alpha/2} (\lambda - L)^{-1} u, w_k \rangle_r, \quad 1 \leq k \leq N.$$

When  $\mathcal{L}$  and  $\tau$  are perturbed, the resultant operators will be written as

$$\tilde{\mathcal{L}}u = - \sum_{i,j=1}^m \frac{\partial}{\partial x_i} \left( \tilde{a}_{ij}(x) \frac{\partial u}{\partial x_j} \right) + \sum_{i=1}^m \tilde{b}_i(x) \frac{\partial u}{\partial x_i} + \tilde{c}(x)u,$$

and

$$\tilde{\tau}u = \frac{\partial u}{\partial \bar{y}} + \tilde{\sigma}(\xi)u = \sum_{i,j=1}^m \tilde{a}_{ij}(\xi) \nu_i(\xi) \frac{\partial u}{\partial x_j} + \tilde{\sigma}(\xi)u$$

respectively. Then,  $\tilde{L}$  is defined by

$$\tilde{L}u = \tilde{\mathcal{L}}u, \quad u \in \mathcal{D}(\tilde{L}) = \{u \in H^2(\Omega); \tilde{\tau}u = 0 \text{ on } \Gamma\}.$$

Here, the symmetry of  $\tilde{a}_{ij}$  is not generally assumed, i.e.,  $\tilde{a}_{ij} \neq \tilde{a}_{ji}$ . The

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\*)  $L_R^2(\Omega)$  indicates a subspace of  $L^2(\Omega)$  consisting of real-valued functions.

strong ellipticity of  $\tilde{L}$  is ensured when  $\tilde{a}_{ij} - a_{ij}$  are small enough.  $\tilde{X}$  will denote the solution to the Ljapunov equation with  $L$  replaced by  $\tilde{L}$ , i.e.,  $\tilde{X}\tilde{L} - B\tilde{X} = \tilde{C} = -\sum_{k=1}^N \langle \tilde{L}_c^{\alpha/2}, w_k \rangle \xi_k$ . Our goal is to show strong continuity of  $\tilde{X}$  relative to  $\tilde{a}_{ij}$ ,  $\tilde{b}_i$ ,  $\tilde{c}$ , and  $\tilde{\sigma}$ . For a control theoretic and geometric property of  $X$ , we refer the reader to [6, 7, 8].

**§ 2. Main result.** In order to ensure strong continuity of  $\tilde{X}$ , we assume throughout the section that  $\tilde{a}_{ij}(x)$  and  $\tilde{b}_i(x)$ ,  $1 \leq i, j \leq m$ , are uniformly bounded in  $C^2(\bar{\Omega})$  and so is  $\tilde{\sigma}(\xi)$  in  $C^2(\Gamma)$ . We further assume that  $\xi_k$  satisfy

$$\sum_{i,j} \mu_i^{2\alpha} |\xi_{ij}^k|^2 < \infty, \quad 1 \leq k \leq N.$$

Then, our main result is stated as follows :

**Theorem 2.1.** *The operator  $\tilde{X}$  strongly converges to  $X$  uniformly in every bounded set of  $L^2(\Omega)$  if  $\delta = \sum_{i,j=1}^m \|\tilde{a}_{ij} - a_{ij}\|_{C^1(\bar{\Omega})} + \sum_{i=1}^m \|\tilde{b}_i - b_i\|_{C^0(\bar{\Omega})} + \|\tilde{c} - c\|_{C^0(\bar{\Omega})} + \|\tilde{\sigma} - \sigma\|_{C^1(\Gamma)}$  tends to 0.*

*Outline of the proof.* The operator  $\tilde{X}$  is written by (1) with  $f_k(\lambda; u)$  replaced by  $\tilde{f}_k(\lambda; u) = \langle \tilde{L}_c^{\alpha/2}(\lambda - \tilde{L})^{-1}u, w_k \rangle_{\Gamma}$ . We have to estimate the  $L^2(\Gamma)$ -norm of

$$h(\lambda) = \tilde{L}_c^{\alpha/2}(\lambda - \tilde{L})^{-1}u - L_c^{\alpha/2}(\lambda - L)^{-1}u, \quad \lambda = \mu_i \omega^{\pm}.$$

Define an auxiliary operator  $\hat{L}$  by

$$\hat{L}u = \tilde{L}u, \quad u \in \mathcal{D}(\hat{L}) = \mathcal{D}(L).$$

Note that  $\hat{L}_c = \hat{L} + c$  is not necessarily an accretive operator. There is a sector  $\bar{\Sigma} = \{\lambda = \mu - d; \theta \leq |\arg \mu| \leq \pi\}$ ,  $d > 0$ ,  $0 < \theta < \pi/2$ , such that the resolvents  $(\lambda - L)^{-1}$ ,  $(\lambda - \tilde{L})^{-1}$ , and  $(\lambda - \hat{L})^{-1}$  exist in  $\bar{\Sigma}$  and satisfy

$$\|(\lambda - L)^{-1}\|, \quad \|(\lambda - \tilde{L})^{-1}\|, \quad \|(\lambda - \hat{L})^{-1}\| \leq \frac{\text{const}}{1 + |\lambda|}, \quad \lambda \in \bar{\Sigma},$$

and that  $\mu_i \omega^{\pm} \in \bar{\Sigma}$ ,  $i \geq 1$ . Here, the above constant is independent of  $\delta$ , and so will be constants appearing below. As is well known [1],  $\mathcal{D}(L_c) = \mathcal{D}(\tilde{L}_c) = H^{2\gamma}(\Omega)$  if  $0 \leq \gamma < 3/4$  (constants for the equivalence relations depend on  $\delta$ ).

A further analysis via  $\hat{L}$  shows

**Lemma 2.2.** *If  $0 \leq \gamma < 3/4$ ,  $\|\tilde{L}_c L_c^{-\gamma}\|$  is uniformly bounded, and  $\tilde{L}_c L_c^{-\gamma}$  strongly converges to 1 as  $\delta \rightarrow 0$ .*

According to  $m$ -accretiveness of  $\tilde{L}_c^{1/2}$  and  $L_c^{1/2}$ , we can show

**Lemma 2.3.** *If  $0 \leq \gamma \leq 1/2$ ,  $\|L_c \tilde{L}_c^{-\gamma}\|$  is uniformly bounded. As a consequence of Lemma 2.2,  $L_c \tilde{L}_c^{-\gamma}$  strongly converges to 1 as  $\delta \rightarrow 0$ .*

Given a  $g \in H^{1/2}(\Gamma)$ , let us consider the boundary value problem

$$(2) \quad (\lambda - \tilde{L})u = 0, \quad \tilde{\tau}u = g.$$

**Lemma 2.4.** *There exists a unique solution  $u \in H^2(\Omega)$  to eqn. (2) for  $\lambda \in \bar{\Sigma}$ . The solution  $u$  is denoted by  $\tilde{N}(\lambda)g$ . Then,  $\tilde{N}(\lambda)$  belongs to  $\mathcal{L}(H^{1/2}(\Gamma); H^2(\Omega))$ , and satisfies an estimate*

$$\|\tilde{L}_c \tilde{N}(\lambda)g\| \leq \text{const} |\lambda|^\gamma \|g\|_{H^{1/2}(\Gamma)}, \quad \lambda \in \bar{\Sigma}, \quad 0 \leq \gamma < \frac{3}{4}.$$

Before estimating  $h(\lambda)$ , let us note a relation

$$h(\lambda) = -\tilde{L}_c^{\alpha/2} \tilde{N}(\lambda)(\tilde{\tau} - \tau)(\lambda - \hat{L})^{-1}u + \tilde{L}_c^{\alpha/2}(\lambda - L)^{-1}(\hat{L} - L)(\lambda - \hat{L})^{-1}u + (\tilde{L}_c^{\alpha/2} - L_c^{\alpha/2})(\lambda - L)^{-1}u.$$

Based on the preceding lemmas and the trace theorem [2, 5], we estimate  $h(\lambda)$  as

$$\|h(\mu_i \omega^\pm)\|_{L^2(\Gamma)} \leq \text{const } \mu_i^\alpha \delta \|u\| + \text{const } \|(\tilde{L}_c^\alpha L_c^{-\alpha} - \tilde{L}_c^{\alpha/2} L_c^{-\alpha/2}) L_c^\alpha (\mu_i \omega^\pm - L)^{-1} u\|.$$

By recalling that each  $L_c^\alpha (\mu_i \omega^\pm - L)^{-1}$  is a compact operator, the second term of the above right-hand side converges to 0 uniformly in  $i \geq 1$  and in  $u$  (in a bounded set of  $L^2(\Omega)$ ). Thus, the assertion of Theorem 2.1 immediately follows. Details of the proof will appear elsewhere.

### References

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