

95. Calculus in Ranked Vector Spaces. V

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(2.1.8) **Proposition.** *If E_2 is a separated ranked vector space, then the only remainder $r \in R(E_1; E_2)$ which is linear is the zero map.*

Proof. Let x be an arbitrary point of E_1 and consider a sequence $\{x_n\}$ such that $x_n = x$ for $n = 0, 1, 2, \dots$. Then by (1.7.3) $\{x_n\}$ is a quasi-bounded sequence. Let $\{\lambda_n\}$ be a sequence in \mathfrak{R} with $\lambda_n \rightarrow 0$, then it follows from $r \in R(E_1; E_2)$ that

$$\left\{ \lim \frac{r(\lambda_n x_n)}{\lambda_n} \right\} \ni 0.$$

The linearity of r implies

$$\begin{aligned} \frac{r(\lambda_n x_n)}{\lambda_n} &= \frac{\lambda_n r(x_n)}{\lambda_n} = r(x_n) \\ \therefore \left\{ \lim r(x_n) \right\} &\ni 0. \end{aligned}$$

On the other hand, using $r(x_n) = r(x)$ for $n = 0, 1, 2, \dots$ and (1.2.4), we have

$$\left\{ \lim r(x_n) \right\} \ni r(x).$$

Since E_2 is a separated ranked vector space, by (1.4.3)

$$r(x) = 0.$$

Hence $r: E_1 \rightarrow E_2$ is the zero map.

2.2. Differentiability at a point. In order to make use of (2.1.8) we assume henceforth that all spaces E_1, E_2, \dots are separated.

(2.2.1) **Proposition.** *Let $f: E_1 \rightarrow E_2$ be a map between ranked vector spaces E_1, E_2 . If there exists a map $l \in L(E_1; E_2)$ such that the map $r: E_1 \rightarrow E_2$ defined by*

$$f(a+h) = f(a) + l(h) + r(h)$$

is a remainder, then l is uniquely determined.

Proof. Suppose that there exist two maps $l_1, l_2 \in L(E_1; E_2)$ such that the maps r_1, r_2 defined by

$$f(a+h) = f(a) + l_1(h) + r_1(h),$$

$$f(a+h) = f(a) + l_2(h) + r_2(h)$$

are remainders. Then we have

$$l_1(h) - l_2(h) = r_2(h) - r_1(h).$$

Since by (2.1.4) $R(E_1; E_2)$ is a vector space and by (2.1.5) $L(E_1; E_2)$ is also a vector space,

$$r_2 - r_1 \in R(E_1; E_2) \quad \text{and} \quad r_2 - r_1 \in L(E_1; E_2).$$

Hence it follows, using (2.1.8), that

$$r_2 - r_1 = 0 \quad \therefore \quad l_1 = l_2$$

which completes the proof.

(2.2.2) **Definition.** If there exists a map $l \in L(E_1; E_2)$ such that the map $r: E_1 \rightarrow E_2$ defined by

$$f(a+h) = f(a) + l(h) + r(h)$$

is a remainder, then the map $f: E_1 \rightarrow E_2$ is said to be *differentiable at the point a* and the map $l \in L(E_1; E_2)$ which by (2.2.1) is uniquely determined, is then called the *derivative of f at the point a* . It will be denoted as follows:

$$l = Df(a) \quad \text{or} \quad l = f'(a).$$

(2.2.3) **Example.** A constant map $K: E_1 \rightarrow E_2$ is differentiable at each point $a \in E_1$, and $DK(a) = 0$.

(2.2.4) **Proposition.** If $f: E_1 \rightarrow E_2$ is differentiable at a point a , then it is continuous at the point a in the sense of L -convergence.

Proof. Let $\{\text{Lim } x_n\} \ni a$, i.e.,

$$x_n - a = \lambda_n x'_n, \quad \text{for } n = 0, 1, 2, \dots$$

where $\lambda_n \rightarrow 0$ in \mathfrak{R} and $\{x'_n\}$ is a quasi-bounded sequence in E_1 .

By assumption we have

$$f(a+h) = f(a) + l(h) + r(h)$$

where $l \in L(E_1; E_2)$ and $r \in R(E_1; E_2)$. Hence

$$\begin{aligned} f(x_n) &= f(a + x_n - a) \\ &= f(a) + l(x_n - a) + r(x_n - a) \\ &= f(a) + l(\lambda_n x'_n) + r(\lambda_n x'_n) \end{aligned}$$

$$\therefore f(x_n) - f(a) = l(\lambda_n x'_n) + r(\lambda_n x'_n).$$

Since $l \in L(E_1; E_2)$,

$$= \lambda_n l(x'_n) + r(\lambda_n x'_n)$$

$$\therefore f(x_n) - f(a) = \lambda_n \left(l(x'_n) + \frac{r(\lambda_n x'_n)}{\lambda_n} \right).$$

By $r \in R(E_1; E_2)$

$$\left\{ \lim \frac{r(\lambda_n x'_n)}{\lambda_n} \right\} \ni 0$$

and therefore $\left\{ \frac{r(\lambda_n x'_n)}{\lambda_n} \right\}$ is a quasi-bounded sequence.

Thus it follows from (1.7.7), (1.7.5) that

$$\left\{ l(x'_n) + \frac{r(\lambda_n x'_n)}{\lambda_n} \right\}$$

is also a quasi-bounded sequence.

$$\therefore \{\text{Lim } f(x_n)\} \ni f(a)$$

which completes the proof.

2.3. The chain rule. (2.3.1) Theorem. Let E_1, E_2, E_3 be ranked vector spaces, and suppose that there are two maps given:

$$f: E_1 \rightarrow E_2, \quad g: E_2 \rightarrow E_3.$$

If $f: E_1 \rightarrow E_2$ is differentiable at a point $a \in E_1$ and $g: E_2 \rightarrow E_3$ is differentiable at the point $b = f(a) \in E_2$, then $g \cdot f$ is differentiable at the point $a \in E_1$ and

$$D(g \cdot f) = Dg(b) \cdot Df(a).$$

Proof. By assumption we have

$$f(a+h) = f(a) + l_1(h) + r_1(h),$$

$$g(b+k) = g(b) + l_2(k) + r_2(k)$$

where $l_1 = Df(a) \in L(E_1; E_2)$, $l_2 = Dg(b) \in L(E_2; E_3)$, $r_1 \in R(E_1; E_2)$, and $r_2 \in R(E_2; E_3)$.

$$g(f(a+h)) = g(b+k)$$

where $k = l_1(h) + r_1(h)$

$$= g(b) + l_2(k) + r_2(k)$$

$$= g(f(a)) + l_2(l_1(h) + r_1(h)) + r_2(l_1(h) + r_1(h))$$

$$= (g \cdot f)(a) + (l_2 \cdot l_1)(h) + (l_2 \cdot r_1)(h) + (r_2 \cdot (l_1 + r_1))(h)$$

since $l_1 \in L(E_1; E_2)$ and $l_2 \in L(E_2; E_3)$,

$$l_2 \cdot l_1 \in L(E_1; E_3).$$

By (2.1.4), (2.1.6), (2.1.7)

$$l_2 \cdot r_1 + r_2 \cdot (l_1 + r_1) \in R(E_1; E_3).$$

Therefore $g \cdot f$ is differentiable at the point $a \in E_1$ and

$$D(g \cdot f) = l_2 \cdot l_1 = Dg(b) \cdot Df(a).$$

§ 3. Examples and special cases. 3.1. The classical case.

(3.1.1) **Proposition.** If E_1, E_2 are normed vector spaces, on which we consider the ranked topology, as in (1.6.6), determined by the norm, then the notions of differentiability at a point $a \in E_1$ and derivative of a map $f: E_1 \rightarrow E_2$ coincide with the classical notions in the sense of Fréchet.

Proof. (a) Suppose that a map $f: E_1 \rightarrow E_2$ is differentiable at a point $a \in E_1$ in the sense of Fréchet, i.e., there exists a map $l \in L(E_1; E_2)$ such that the map r defined by $f(a+h) = f(a) + l(h) + r(h)$ has the following property:

$$(3.1.2) \quad \lim_{h \rightarrow 0} \frac{\|r(h)\|}{\|h\|} = 0,$$

where $f'(a) = l$.

Let $\{x_n\}$ be any quasi-bounded sequence in E_1 , and $\{\lambda_n\}$ a sequence in \mathfrak{R} with $\lambda_n \rightarrow 0$, then by (1.9.1)

$$\|\lambda_n x_n\| \rightarrow 0, \quad \text{for } n \rightarrow \infty.$$

Consider

$$\left\| \frac{r(\lambda_n x_n)}{\lambda_n} \right\| = \|x_n\| \frac{\|r(\lambda_n x_n)\|}{\|\lambda_n x_n\|}$$

then it follows, using (3.1.2) and the fact that by (1.9.2) $\{\|x_n\|\}$ is bounded, that

$$\left\| \frac{r(\lambda_n x_n)}{\lambda_n} \right\| \rightarrow 0, \quad \text{for } n \rightarrow \infty$$

$$\therefore \left\{ \lim \frac{r(\lambda_n x_n)}{\lambda_n} \right\} \ni 0.$$

That is, $r: E_1 \rightarrow E_2$ is a remainder, and therefore $f: E_1 \rightarrow E_2$ is differentiable at a point $a \in E_1$ in the sense of ranked vector space.

(b) Suppose conversely that $f: E_1 \rightarrow E_2$ is differentiable at a point $a \in E_1$ in the sense of ranked vector space, i.e., it can be written in the following way:

$$f(a+h) = f(a) + l(h) + r(h)$$

where $l \in L(E_1; E_2)$ and $r \in R(E_1; E_2)$.

Let $\{x_n\}$ be any sequence in E_1 such that

$$\left\{ \lim_n x_n \right\} \ni 0, \quad \text{i.e., } \lim_{n \rightarrow \infty} \|x_n\| = 0,$$

and put

$$y_n = \frac{x_n}{\|x_n\|}, \quad n=0, 1, 2, \dots,$$

then by (1.9.2) $\{y_n\}$ is a quasi-bounded sequence.

$$\frac{\|r(x_n)\|}{\|x_n\|} = \frac{\|r(\|x_n\| y_n)\|}{\|x_n\|}.$$

Since $r \in R(E_1; E_2)$,

$$\frac{\|r(\|x_n\| y_n)\|}{\|x_n\|} \rightarrow 0, \quad \text{for } n \rightarrow \infty$$

$$\therefore \lim \frac{\|r(x_n)\|}{\|x_n\|} = 0$$

$$\therefore \lim_{h \rightarrow 0} \frac{\|r(h)\|}{\|h\|} = 0.$$

Therefore $f: E_1 \rightarrow E_2$ is differentiable at a point $a \in E_1$ in the sense of Fréchet.

It is obvious that the derivative of a map $f: E_1 \rightarrow E_2$ coincides with the classical one in the sense of Fréchet.

3.2. Linear and bilinear maps. (3.2.1) Proposition. *Let $f: E_1 \rightarrow E_2$ be a linear and continuous map between separated ranked vector spaces E_1 and E_2 , then it is differentiable at each point $a \in E_1$ and $f'(a) = f$.*

Proof. By assumption we have

$$f(a+h) = f(a) + f(h) + 0$$

where $f \in L(E_1; E_2)$ and $0 \in R(E_1; E_2)$. Hence $f: E_1 \rightarrow E_2$ is differentiable at each point $a \in E$ and $f'(a) = f$.

(3.2.2) Proposition. *Let $b: E_1 \times E_2 \rightarrow E_3$ be a bilinear and continuous map between separated ranked vector spaces $E_1 \times E_2, E_3$. Then*

$$b \in R(E_1 \times E_2; E_3).$$

Proof. (1) It is obvious that one has $b(0)=0$.

(2) Let $\{z_n\}=\{(x_{n1}, x_{n2})\}$ be a quasi-bounded sequence in $E_1 \times E_2$ and $\{\lambda_n\}$ a sequence in \mathfrak{R} such that $\lambda_n \rightarrow 0$.

$$\begin{aligned}\theta_b(\lambda_n, z_n) &= \frac{b(\lambda_n z_n)}{\lambda_n} = \frac{b(\lambda_n x_{n1}, \lambda_n x_{n2})}{\lambda_n} \\ &= \lambda_n b(x_{n1}, x_{n2}) \\ &= \pm b(\sqrt{|\lambda_n|} x_{n1}, \sqrt{|\lambda_n|} x_{n2})\end{aligned}$$

since by (1.7.8) $\{x_{n1}\}, \{x_{n2}\}$ are quasi-bounded sequences and $\sqrt{|\lambda_n|} \rightarrow 0$ in \mathfrak{R} ,

$$\{\lim \sqrt{|\lambda_n|} x_{n1}\} \ni 0 \quad \text{and} \quad \{\lim \sqrt{|\lambda_n|} x_{n2}\} \ni 0.$$

It follows, using that $b: E_1 \times E_2 \rightarrow E_3$ is continuous, that

$$\begin{aligned}\{\lim \theta_b(\lambda_n, z_n)\} &\ni 0 \\ \therefore b &\in R(E_1 \times E_2; E_3).\end{aligned}$$

(3.2.3) **Proposition.** *Let $b: E_1 \times E_2 \rightarrow E_3$ be bilinear and continuous. Then b is differentiable at each point $a=(a_1, a_2) \in E_1 \times E_2$ and*

$$b'(a_1, a_2)(h_1, h_2) = b(h_1, a_2) + b(a_1, h_2).$$

Proof. Let $a=(a_1, a_2)$ and $h=(h_1, h_2)$, then

$$\begin{aligned}b(a+h) &= b(a_1+h_1, a_2+h_2) \\ &= b(a_1, a_2) + b(h_1, a_2) + b(a_1, h_2) + b(h_1, h_2).\end{aligned}$$

Put

$$l(h) = b(h_1, a_2) + b(a_1, h_2), \quad r(h) = b(h),$$

then it is obvious that one has

$$l \in L(E_1 \times E_2; E_3),$$

and by (3.2.2)

$$r \in R(E_1 \times E_2; E_3).$$

Hence $b: E_1 \times E_2 \rightarrow E_3$ is differentiable at the point $a=(a_1, a_2)$ and

$$b'(a_1, a_2)(h_1, h_2) = b(h_1, a_2) + b(a_1, h_2).$$

3.3. The special case $f: \mathfrak{R} \rightarrow E$. (3.3.1) **Proposition.** *If $f: \mathfrak{R} \rightarrow E$ is differentiable at a point $\alpha \in \mathfrak{R}$, then for any sequence $\{x_n\}$ in \mathfrak{R} such that $x_n \rightarrow 0$,*

$$(3.3.2) \quad \left\{ \lim \frac{f(\alpha + x_n) - f(\alpha)}{x_n} \right\} \ni f'(\alpha),$$

where $f'(\alpha) = f'(\alpha)(1)$.

Proof. By assumption we have

$$f(\alpha + h) = f(\alpha) + l(h) + r(h)$$

where $l \in L(\mathfrak{R}; E)$ and $r \in R(\mathfrak{R}; E)$. Thus

$$f(\alpha + x_n) = f(\alpha) + l(x_n) + r(x_n),$$

since $l \in L(\mathfrak{R}; E)$ implies $l(x_n) = l(x_n \cdot 1) = x_n l(1)$,

$$f(\alpha + x_n) - f(\alpha) = x_n l(1) + r(x_n)$$

$$\frac{f(\alpha + x_n) - f(\alpha)}{x_n} - l(1) = \frac{r(x_n)}{x_n}.$$

It follows from $r \in R(\mathfrak{R}; E)$ that

$$\left\{ \lim \frac{r(x_n \cdot 1)}{x_n} \right\} \ni 0$$

$$\therefore \left\{ \lim \frac{f(\alpha + x_n) - f(\alpha)}{x_n} \right\} \ni l(1).$$

Since we assume that E is a separated ranked vector space, we may write in the following way:

$$\lim_n \frac{f(\alpha + x_n) - f(\alpha)}{x_n} = f'(\alpha)$$

instead of (3.3.2).

(3.3.3) Proposition. *Suppose that for any sequence $\{x_n\}$ in \mathfrak{R} with $x_n \rightarrow 0$ the following holds at a point $\alpha \in \mathfrak{R}$:*

$$\left\{ \lim \frac{f(\alpha + x_n) - f(\alpha)}{x_n} \right\} \ni a$$

where a is an element of a separated ranked vector space E . Then $f: \mathfrak{R} \rightarrow E$ is differentiable at the point $\alpha \in R$ and $f'(\alpha)(x) = xa$.

Proof. Let us define a map $r: \mathfrak{R} \rightarrow E$ by

$$f(\alpha + x) = f(\alpha) + xa + r(x)$$

then it only remains to prove that $r \in R(\mathfrak{R}; E)$.

Let $\{x_n\}$ be any quasi-bounded sequence in \mathfrak{R} and $\{\lambda_n\}$ a sequence in \mathfrak{R} such that $\lambda_n \rightarrow 0$.

$$\begin{aligned} \frac{r(\lambda_n x_n)}{\lambda_n} &= \frac{1}{\lambda_n} \{f(\alpha + \lambda_n x_n) - f(\alpha) - \lambda_n x_n a\} \\ &= x_n \left\{ \frac{f(\alpha + \lambda_n x_n) - f(\alpha)}{\lambda_n x_n} - a \right\}. \end{aligned}$$

Put

$$y_n = \frac{f(\alpha + \lambda_n x_n) - f(\alpha)}{\lambda_n x_n} - a$$

for $n=0, 1, 2, \dots$. By assumption we have

$$\left\{ \lim y_n \right\} \ni 0.$$

Since $\{x_n\}$ is a quasi-bounded sequence in \mathfrak{R} , by (1.9.2) it is bounded, i.e., there exists a number M such that

$$|x_n| < M, \quad n=0, 1, 2, \dots$$

$$\therefore \left\{ \lim \frac{x_n}{M} y_n \right\} \ni 0,$$

$$\therefore \left\{ \lim M \frac{x_n}{M} y_n \right\} \ni 0,$$

$$\therefore \left\{ \lim x_n y_n \right\} \ni 0.$$

Therefore

$$\left\{ \lim \frac{r(\lambda_n x_n)}{\lambda_n} \right\} \ni 0, \quad \therefore r \in R(\mathfrak{R}; E).$$

Thus $f: \mathfrak{R} \rightarrow E$ is differentiable at the point $\alpha \in \mathfrak{R}$, and $f'(\alpha)(x) = xa$.