

## 148. Korteweg-deVries Equation. IV

## Simplest Generalization

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1. Introduction. In the preceding note [1], [2] we have established the global existence theorem for the Cauchy problem for the *KdV* equation

$$(1) \quad \begin{cases} D_t u + u D u + D^3 u = 0 & (x, t) \in R^1 \times [0, \infty) \\ u(x, 0) = f(x) & x \in R^1 \end{cases} \quad \left( D_t = \frac{\partial}{\partial t}, D = \frac{\partial}{\partial x} \right).$$

Here we consider its simplest generalization

$$(2) \quad \begin{cases} D_t v + v^2 D v + D^3 v = 0 & (x, t) \in R^1 \times [0, \infty) \\ v(x, 0) = f(x) & x \in R^1. \end{cases}$$

These Cauchy problems are closely related to the study of anharmonic lattices [3]. Recently Miura [4] has discovered a remarkable nonlinear transformation

$$(3) \quad \sqrt{-6} D v + v^2 = u$$

which connects (1) and (2) in the following manner

$$(4) \quad D_t u + u D u + D^3 u = (2v + \sqrt{-6} D)(D_t v + v^2 D v + D^3 v).$$

For any smooth solution  $v \in \mathcal{E}_t^\infty(\mathcal{E}_{L^2}^\infty)$  of (2) we can associate uniquely the solution  $u \in \mathcal{E}_t^\infty(\mathcal{E}_{L^2}^\infty)$  of (1) through the transformation (3). But converse is not true. When we want to solve the equation (3) with respect to  $v$  for given  $u$  we have no uniqueness. First we show the example which violates the uniqueness of the solutions of the equation

(3). Let  $\varphi(x) \in \mathcal{E}_{L^2}^\infty$  be such that  $\varphi(x) > 0$  for  $\forall x \in R^1$ ,  $\varphi(x) = \frac{1}{|x|}$  for  $|x| > R$  for some  $R > 0$ . We define  $v, w, u$  as follows

$$v = \frac{1}{2}\varphi - \frac{\sqrt{-6}}{2} \frac{D\varphi}{\varphi}, \quad w = v - \varphi, \quad u = \sqrt{-6} D v + v^2.$$

Then  $v$  and  $w$  are distinct each other and satisfies the same equation (3). That is the violence of the uniqueness of the equation (3). Therefore the global existence theorem for the Cauchy problem (1) is insufficient for the global existence theorem for the Cauchy problem (2). We establish here the global existence theorem for the Cauchy problem (2) in a slightly general situation. Detailed proof will be published elsewhere.

## 2. Main theorem.

Consider the Cauchy problem for the generalized *KdV* equation.

$$(5) \quad \begin{cases} D_t v + v^2 Dv + D^3 v + a(x, t) Dv + b(x, t) v + g(x, t) = 0 \\ v(x, 0) = f(x) \end{cases} \quad \begin{matrix} (x, t) \in R^1 \times [0, \infty) \\ x \in R^1. \end{matrix}$$

Here we assume  $a(x, t), b(x, t) \in \mathcal{E}_t^\infty(\mathcal{B}^\infty)$

### Main theorem.

If

$$\begin{aligned} f(x) &\in \mathcal{E}_{L^2}^{3(k+1)+2} \\ g(x, t) &\in \mathcal{E}_t^{k+1}(\mathcal{E}_{L^2}^2) \cap [\mathcal{E}_t^k(\mathcal{E}_{L^2}^2) \cap \mathcal{E}_t^{k-1}(\mathcal{E}_{L^2}^5) \cap \dots \cap \mathcal{E}_t^0(\mathcal{E}_{L^2}^{3k+2})] \end{aligned}$$

then there exist uniquely the global solution

$$v(x, t) \in \mathcal{E}_t^k(\mathcal{E}_{L^2}^2) \cap \mathcal{E}_t^{k-1}(\mathcal{E}_{L^2}^5) \cap \dots \cap \mathcal{E}_t^0(\mathcal{E}_{L^2}^{3k+2})$$

of the Cauchy problem (5).

Using Sobolev's lemma we obtain

### Corollary 1.

If

$$\begin{aligned} f(x) &\in \mathcal{E}_{L^2}^{3(k+2)+2} \\ g(x, t) &\in \mathcal{E}_t^{k+2}(\mathcal{E}_{L^2}^2) \cap [\mathcal{E}_t^{k+1}(\mathcal{E}_{L^2}^2) \cap \mathcal{E}_t^k(\mathcal{E}_{L^2}^5) \cap \dots \cap \mathcal{E}_t^0(\mathcal{E}_{L^2}^{3(k+1)+2})] \end{aligned}$$

then for any  $i, j$  such that  $i+j \leq k$

$$D_t^i D^{3j} v(x, t) \in \mathcal{B}^0(R^1 \times [0, T]) \quad \text{for } \forall T > 0.$$

**Remark.** In Corollary 1 if we take  $k=1$  we obtain the global existence theorem of the classical solution.

### Corollary 2.

If

$$f(x) \in \mathcal{E}_{L^2}^\infty, \quad g(x, t) \in \mathcal{E}_t^\infty(\mathcal{E}_{L^2}^\infty)$$

then

$$v(x, t) \in \mathcal{E}_t^\infty(\mathcal{E}_{L^2}^\infty)$$

especially

$$v(x, t) \in \mathcal{B}^\infty(R^1 \times [0, T]) \quad \text{for } \forall T > 0.$$

**Remark.** These results are also true when the functional space  $\mathcal{E}_{L^2}^k$  are replaced by the functional space  $\mathcal{P}_l^k$  for any  $l > 0$ . In this case we must assume that  $a(x, t)$  and  $b(x, t)$  have period  $l$  in  $x$ . Here  $\mathcal{P}_l^k$  represents the functional space which consists of all the functions having the period  $l$  and belonging to the functional space  $\mathcal{E}_{L^2, \text{loc}}^k(R^1)$ .

**3. Proof of the main theorem.** To prove the main theorem we need global a priori estimate and local existence theorem. To obtain a priori estimate of the solutions of the Cauchy problem (5) we use the infinite sequence of polynomial conserved densities (definition will be found in [1] or [5]) of the generalized *KdV* equation (2) which is obtained from that of the *KdV* equation (1) replacing  $u$  by the left hand member of the equation (3). We can assert the existence of infinite sequence of polynomial conserved densities of the generalized

KdV equation in the following canonical form.

**Theorem 1.** *The generalized KdV equation (2) has the polynomial conserved densities of the form*

$$\begin{aligned}
 S_0(v) &= v^2 \\
 S_1(v) &= (Dv)^2 - \frac{1}{6} v^4 \\
 S_2(v) &= (D^2v)^2 - \frac{5}{3} v^2(Dv)^2 - \frac{1}{\sqrt{-6}} v^4 Dv + \frac{1}{18} v^6 \\
 S_k(v) &= (D^k v)^2 + P_k(v, Dv)(D^{k-1}v)^2 + Q_k(v, \dots, D^{k-2}v)D^{k-1}v \\
 &\quad + R_k(v, \dots, D^{k-2}v) \quad k=3, 4, \dots
 \end{aligned}$$

Here  $P_k, Q_k$  and  $R_k$  are polynomials.

Integrating these conserved densities on the whole  $x$ -axis we get step by step following infinite sequence of a priori estimate of the solutions of the Cauchy problem (5).

**Theorem 2.** *The solutions of the Cauchy problem (5) satisfy following infinite sequence of a priori estimate*

$$\begin{aligned}
 \|D^k v\| &\leq V_k(t, |a|_t, \dots, |D^k a|_t, |b|_t, \dots, |D^k b|_t, \\
 \|f\|, \dots, \|D^k f\|, \|g\|_t, \dots, \|D^k g\|_t) \quad k=0, 1, 2, \dots
 \end{aligned}$$

Here  $V_k$  are positive valued smooth monotone increasing function in each arguments.  $V_0$  contains  $|Da|_t$  exceptionally.

$$\begin{aligned}
 |a|_t &= \sup_{0 \leq s \leq t} |a(s)|, \quad |a| = |a|_{\mathcal{B}^0}, \\
 \|g\|_t &= \sup_{0 \leq s \leq t} \|g(s)\|, \quad \|g\| = \|g\|_{L^2}
 \end{aligned}$$

The local existence theorem is obtained by the method of successive approximation

$$\begin{aligned}
 (6) \quad v_0(x, t) &= f(x) \quad (x, t) \in R^1 \times [0, \infty) \\
 (7) \quad \begin{cases} D_t v_n + v_{n-1}^2 Dv_n + D^3 v_n + a(x, t) Dv_n + b(x, t) v_n + g(x, t) = 0 \\ v_n(x, 0) = f(x) \end{cases} \quad \begin{matrix} (x, t) \in R^1 \times [0, \infty) \\ x \in R^1 \end{matrix}
 \end{aligned}$$

By induction in  $n$  and  $k$  we obtain the uniform (with respect to  $n$ ) energy estimate for the sequence of approximate solutions  $v_n$ .

**Proposition 1.** *For any non negative integer  $k$ , if we take*

$$t_k = \min \left\{ 1, \frac{\log M}{C_k} \right\} \quad (M > 1 \text{ fixed})$$

then we have

$$\sup_{0 \leq t \leq t_k} \|D_t^k v_n\| \leq c_k, \quad \sup_{0 \leq t \leq t_k} \|D_t^i D^{3j} v_n\| \leq C_k \quad (i + j \leq k).$$

Here we use the following notations

$$\begin{aligned}
 v(0) &= f(x) \\
 v^{(1)}(0) &= -[f^2(x) Df(x) + D^3 f(x) + a(x, 0) Df(x) \\
 &\quad + b(x, 0) f(x) + g(x, 0)]
 \end{aligned}$$

$$\begin{aligned}
 v^{(k)}(0) = & - \left[ \sum_{\alpha_1 + \alpha_2 + \alpha_3 = k-1} \frac{(k-1)!}{\alpha_1! \alpha_2! \alpha_3!} v^{(\alpha_1)}(0) v^{(\alpha_2)}(0) Dv^{(\alpha_3)}(0) \right. \\
 & + D^3 v^{(k-1)}(0) + \sum_{\beta=0}^{k-1} \binom{k-1}{\beta} D_t^{k-1-\beta} a(x, 0) Dv^{(\beta)}(0) \\
 & \left. + \sum_{\beta=0}^{k-1} \binom{k-1}{\beta} D_t^{k-1-\beta} b(x, 0) v^{(\beta)}(0) + D_t^{k-1} g(x, 0) \right] \\
 c_k^2 = & M \left[ \|v^{(k)}(0)\|_{\mathcal{E}_{L^2}^2}^2 + 2 \sum_{l=0}^{k-1} c_l^2 + \sup_{0 \leq t \leq 1} \|D_t^k g\|_{\mathcal{E}_{L^2}^2}^2 \right]
 \end{aligned}$$

$C_k$  is a polynomial in  $c_0, \dots, c_k, \sup_{0 \leq t \leq 1} |D_t^i D^{3j} a|_{\mathcal{B}^2}, \sup_{0 \leq t \leq 1} |D_t^i D^{3j} b|_{\mathcal{B}^2} (i + j \leq k)$ , and  $\sup_{0 \leq t \leq 1} \|D_t^i D^{3j} g\|_{\mathcal{E}_{L^2}^2} (i + j \leq k-1)$  with positive coefficients.

From (7) we derive the following equation for the differences  $v_{n+1} - v_n = \varphi_n$

$$\begin{cases}
 D_t \varphi_n + v_n^2 D \varphi_n + D^3 \varphi_n + a(x, t) D \varphi_n + b(x, t) \varphi_n \\
 + \varphi_{n-1} (v_n + v_{n-1}) D v_n = 0 \\
 \varphi_n(x, 0) = 0
 \end{cases}$$

Using uniform estimate for  $v_n$  in Proposition 1 we obtain the following estimate for  $\varphi_n$ .

**Proposition 2.** *For any non negative integer  $k$ , if take*

$$T_k = \frac{\rho}{C_{k+1}} \quad (0 < \rho < 1 \text{ fixed})$$

then we have

$$\sup_{0 \leq t \leq T_k} \sum_{i=0}^k \|D_t^i \varphi_n\|_{\mathcal{E}_{L^2}^2}^2 \leq \rho \sup_{0 \leq t \leq T_k} \sum_{i=0}^k \|D_t^i \varphi_{n-1}\|_{\mathcal{E}_{L^2}^2}^2.$$

From this estimate it follows easily that

$$D_t^i v_n \rightarrow D_t^i v \text{ in } \mathcal{E}_t^0(\mathcal{E}_{L^2}^2) \text{ as } n \rightarrow \infty \text{ for } 0 \leq i \leq k$$

Observing equation (7) we can easily conclude that

$$D_t^i D^{3j} v_n \rightarrow D_t^i D^{3j} v \text{ in } \mathcal{E}_t^0(\mathcal{E}_{L^2}^2) \text{ as } n \rightarrow \infty \text{ for } i + j \leq k.$$

Therefore we obtain the following local existence theorem

**Theorem 3.** *If  $f(x)$  and  $g(x, t)$  have the same regularity assumptions as that of the main theorem then the Cauchy problem (5) has unique solution  $v(x, t)$  in  $0 \leq t \leq T_k$  which has the same regularity as that of the main theorem.*

Combine this local existence theorem with the global a priori estimate (Theorem 2) we can easily conclude the global existence theorem (Main theorem). This completes the proof of the main theorem.

**Remark.** Uniqueness of the solutions is easily obtained by the usual method of  $L^2$ -energy estimate.

### References

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