33. On the Injective Radius of Noncompact Riemannian Manifolds

By Masao MAEDA

Department of Mathematics, Tokyo Institute of Technology

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In this note all Riemannian manifolds which we deal are connected and complete. Let M be a Riemannian manifold and $p \in M$. C(p)(respectively Q(p)) denotes the cut locus (respectively the first conjugate locus) of p in M. For $p, q \in M, d(p, q)$ denotes the metric distance between p and q. As is well known, the function $i: M \to R \cup \{\infty\}$ defined by $i(p) := \min_{q \in C(p)} d(p, q)$ is continuous and i(p) is called the injective radius of \exp_p where $\exp_p: T_p(M) \to M$ is the exponential mapping. If M is compact, then under some conditions, several estimations of the injective radius are obtained, see [3]. Recently in [4], Toponogov asserted that if M is a noncompact Riemannian manifold and for all tangent two plane σ its sectional curvature K_{σ} satisfy the inequality $0 < K_{\sigma} \leq \lambda$ then for all $p \in M$

(1)
$$i(p) \ge \frac{\pi}{\sqrt{\lambda}}$$

Furthermore he asserted that if M is noncompact and $0 \leq K_{\sigma} \leq \lambda$ for all σ , then there exists a positive L such that for all $p \in M$

$$(2) i(p) \ge L.$$

In this note, we give an another proof of estimation (1) by the result of Cheeger and Gromoll [2] and we show that this method remains valid for some two dimensional noncompact Riemannian manifolds.

Every geodesic is always parametrized with respect to arclength. A geodesic $c: [0, \infty) \rightarrow M$ is called a ray, if any segment of c is minimal. A subset A of M is called totally convex, if for any $p, q \in A$, any geodesic segment joining p and q is contained in A. Let A be a non-empty closed totally convex subset of M. Then A is an imbedded topological submanifold of M with totally geodesic interior and possibly non-smooth boundary ∂A , which might be empty, see [2]. Let M be a noncompact manifold of nonnegative sectional curvature. Then the following facts were also proved in [2]. Let C be a closed totally convex subset of M. If $\partial C \neq \emptyset$, we set

$$C^{a} := \{ p \in C : d(p, \partial C) \ge a \}$$
$$C^{\max} := \bigcap_{C^{a} \neq a} C^{a}.$$

Then for any $a \ge 0$, C^a is totally convex and dim $C^{\max} < \dim C$. For any

No. 2]

 $p \in M$, there exists a family of compact totally convex sets $C_t, t \ge 0$ such that

1) $t_2 \ge t_1$ implies $C_{t_2} \supset C_{t_1}$ and

$$_{1} = \{q \in C_{t_{2}} \colon d(q, \partial C_{t_{2}}) \geq t_{2} - t_{1}\}$$

in particular, $\partial C_{t_1} = \{q \in C_{t_2} : d(q, \partial C_{t_2}) = t_2 - t_1\},$

- 2) $\bigcup_{t\geq 0} C_t = M$,
- 3) $p \in C_0$ and if $\partial C_0 \neq \emptyset$, then $p \in \partial C_0$.

We set $C(0) := C_0$ and if $\partial C(0) \neq \emptyset$, we set $C(1) := C(0)^{\max}$. Inductively we set $C(i+1) := C(i)^{\max}$, if $\partial C(i) \neq \emptyset$. Then there exists integer $k \ge 0$ such that $\partial C(k) = \emptyset$. C(k) will be called a soul of M and denoted by S. If M is homeomorphic to *n*-dimensional Euclidean space E^n , then any soul of M is one point set, see [2].

Theorem 1. Let M be a noncompact n-dimensional Riemannian manifold.

1) if $0 < K_{\sigma} \leq \lambda$ for all tangent plane σ , then

$$i(p) \ge \frac{\pi}{\sqrt{\lambda}}$$
 for all $p \in M$,

2) if M is homeomorphic to E^2 and $0 \leq K \leq \lambda$ where K is the Gaussian curvature of M, then $i(p) \geq \pi/\sqrt{\lambda}$ for all $p \in M$.

Remark. If *M* is noncompact and $0 < K_o$, then following [2], *M* is diffeomorphic to E^n . So 2) can be considered as a generalization of 1) for the case n=2. We do not know whether 2) is true for all $n \ge 2$.

Proof. For the present we may assume that M is diffeomorphic to E^n and have the sectional curvature $0 \leq K_{\sigma} \leq \lambda$. We assume that there exist a point $q_0 \in M$ such that $i(q_0) < \pi/\sqrt{\lambda}$. As is mentioned above, for $q_0 \in M$, there exists a family of compact totally convex sets $\{C_t\}_{t\geq 0}$ such that $q_0 \in C_0$. Let $S = \{s\}$ be a soul of M obtained from $\{C_t\}_{t\geq 0}$. C_0 is compact, so there exists a point $q_1 \in C_0$ such that

$$i(q_1) = \min \{i(q) : q \in C_0\}.$$

Then $i(q_1) \leq i(q_0) < \pi/\sqrt{\lambda}$. By the assumption, sectional curvature satisfies $0 \leq K_o \leq \lambda$. So by the Theorem of Morse-Schoenberg and Lemma 2 in [3; p. 226] there exists a geodesic loop $\gamma_1: [0, 2i(q_1)] \rightarrow M$ such that $\gamma_1(0) = \gamma_1(2i(q_1)) = q_1$. Since C_0 is totally convex we have $\gamma_1([0, 2i(q_1)]) \subset C_0$. We show γ_1 is a closed geodesic. For, if $\dot{\gamma}_1(0) \neq \dot{\gamma}_1$ $(2i(q_1))$, then by Lemma 2 [3; p. 226], $i(\gamma_1(i(q_1))) < i(q_1)$. This contradicts the choice of q_1 . Thus $\gamma_1: [0, 2i(q_1)] \rightarrow M$ extends the closed geodesic $\gamma_1: (-\infty, \infty) \rightarrow M$ having the period $2i(q_1)$. We take t > 0. Then by [2], the function $\psi: (-\infty, \infty) \rightarrow R$ defined by

$$\psi(s) := d(\gamma_1(s), \partial C_t)$$

is concave. So $\psi(s) \equiv l > 0$ for all $s \in (-\infty, \infty)$, because ψ is bounded. Let $c: [0, l] \to M$ be a minimal geodesic from $\gamma_1(0)$ to ∂C_t , and X be the parallel field along c such that $X(0) = \dot{\gamma}_1(0)$. Then by the Comparison Theorem of Berger, it follows that there exists $\delta > 0$, such that for $0 \leq s < \delta$, the curve $c_s(u) := \exp_{c(u)} sX(u)$ has length $\leq l$ with equality holding for some s' > 0 if and only if $V: [0, l] \times [0, s'] \rightarrow M$ defines a flat totally geodesic rectangle where $V(u, s) := c_s(u)$. For each s, the length of the curve c_s is not longer than l. So $c_s(l) \subset C_t$ for all $s, 0 \leq s < \delta$. On the other hand, by means of a property of convex sets, $c_s(l) \notin int C_t$. This shows $c_s(l) \in \partial C_t$ and hence length of the curve c_s is equal to l. That is, for all $s, 0 < s < \delta$, $V([0, 1] \times [0, s])$ is a flat totally geodesic submanifold of M. Now, we assume that M is noncompact and $0 < K_{\sigma} \leq \lambda$, then M is diffeomorphic to E^n . Then above fact proves 1). We show 2) by contradiction. Let $s \in M$ be a soul of M, then $i(s) \ge \pi/\sqrt{\lambda}$. If $i(s) < \pi/\sqrt{\lambda}$, then by the argument in 1), there exists a geodesic loop $\gamma: [0, 2i(s)] \rightarrow M$ such that $\gamma(0) = \gamma(2i(s)) = s$. Since $\{s\}$ is totally convex, $\gamma([0, 2i(s)]) \subset \{s\}$. This is a contradiction. We assume that there exists a point $q_0 \in M$ such that $i(q_0) < \pi/\sqrt{\lambda}$. Let $\{C_t\}_{t \ge 0}$ be a family of totally convex set such that $q_0 \in C_0$. We set $A := \{q \in C_0 : i(q) = \min_{r \in C_0} \{i(r)\}\}$. Since A is compact, there exists a points $q_1 \in A$ such that $d(q_1, \partial C_0)$ $=\max \{d(q, \partial C_0): q \in A\}.$ We set $t_1:=d(q_1, \partial C_0).$ Then $i(q_1) \leq i(q_0) <$ $\pi/\sqrt{\lambda}$. So there exists a closed geodesic $\gamma_1: (-\infty, \infty) \rightarrow M$ such that $\gamma_1(0) = \gamma_1(2i(q_1)) = q_1$. Since *M* is homeomorphic to E^2 , ∂C_0 is homeomorphic to a circle. Hence, by the argument in 1) $\gamma_1((-\infty,\infty)) = \partial C_0^{t_1}$ where $C_0^{t_1} := \{q \in C_0 : d(q, \partial C_0) \ge t_1\}$. Let s_0 be the soul of M obtained from C_0 . Then as is mentioned above, $i(s_0) \ge \pi/\sqrt{\lambda}$. From this fact and by the choice of q_1 , we can find a point $q'_2 \in \operatorname{int} C_0^{t_1}$ such that $\pi/\sqrt{\lambda}$ $>i(q_2)>i(q_1)$. We set $t_2:=d(q_2,\partial C_0^{t_1})$. Let $q_2\in C_0^{t_1+t_2}$ be a point such that $i(q_2) = \min \{i(q); q \in C_0^{t_1+t_2}\}$. Clearly $\pi/\sqrt{\lambda} > i(q'_2) \ge i(q_2) > i(q_1)$. Then as in 1), there exists a closed geodesic $\gamma_2: (-\infty, \infty) \rightarrow M$ such that $\gamma_2(0) = \gamma_2(2i(q_2)) = q_2$. By the same reason for $\gamma_1, \gamma_2((-\infty, \infty)) = \partial C_0^{t_1+t_2}$. Hence, by the Theorem of Gauss-Bonnet, we get

$$\iint_{C_0^{t_1}} K dv = \iint_{C_0^{t_1+t_2}} K dv = 2\pi,$$

where K is the Gaussian curvature of M and dv is the area element of M. This equation means $K \equiv 0$ on $C_0^{t_1} - C_0^{t_1+t_2}$. So, $L(\gamma_1) = L(\gamma_2)$. This contradicts the fact that $L(\gamma_1) < L(\gamma_2)$. Q.E.D.

W. Klingenberg showed the following theorem, see [3; p. 227].

Theorem (W. Klingenberg). Let M be a compact simply connected even dimensional Riemannian manifold and $0 < K_{\sigma} \leq \lambda$ for all σ . Then for all $p \in M$,

$$i(p) \geq \frac{\pi}{\sqrt{\lambda}}.$$

Let *M* be a 2-dimensional compact simply connected Riemannian manifold having the Gaussian curvature $0 \le K \le \lambda$. Then *M* is homeomorphic to sphere S^2 . By the Comparison Theorem of Berger, just as the

proof of the Theorem of Klingenberg, we can easily see $i(p) \ge \pi/\sqrt{\lambda}$ for all $p \in M$. Summarizing above we get

Corollary. Let M be a simply connected 2-dimensional Riemannian manifold and its Gaussian curvature satisfies $0 \leq K \leq \lambda$. Then $i(p) \geq \pi/\sqrt{\lambda}$ for all $p \in M$.

We give an application of Theorem 1. Let M be a compact manifold. Then its volume (we denote by Vol (M)) is finite. Conversely if M have finite volume, then is M compact? This is not true in general.

Theorem 2. Let M be an n-dimensional Riemannian manifold and whose sectional curvature satisfies $0 < K_{\sigma} \leq \lambda$ for all σ or M be a 2-dimensional Riemannian manifold whose Gaussian curvature satisfies $0 \leq K \leq \lambda$. Then M is compact if and only if Vol (M) is finite.

Proof. It sufficies to show that if M is noncompact and $0 < K \leq \lambda$ (or M is a 2-dimensional noncompact Riemannian manifold and $0 \leq K \leq \lambda$) then Vol (M) is infinite. Let $p \in M$. Then, since M is noncompact, there exist a ray $c: [0, \infty) \to M$ such that c(0) = p. Let M be an n-dimensional Riemannian manifold with $0 < K_{\sigma} \leq \lambda$, then $i(p) \geq \pi/\sqrt{\lambda}$ for all $p \in M$. Let $B_r(p)$ denotes the closed metric ball in M around p with radius r. $S^n(1/\sqrt{\lambda})$ denotes the n-dimensional sphere in E^{n+1} of constant sectional curvature λ . Then by [1], Vol $(B_{\pi/\sqrt{\lambda}}(c)(2j + 1)\pi/\sqrt{\lambda}))$) $\geq Vol (S^n(1/\sqrt{\lambda}))$. We consider a family of closed balls $\{B_{\pi/\sqrt{\lambda}}(c((2j + 1)\pi/\sqrt{\lambda})) \cap B_{\pi/\sqrt{\lambda}}(c((2k+1)\pi/\sqrt{\lambda})) = \emptyset$, because c is a ray. Hence Vol $(M) \geq \sum_{j=0}^{\infty} Vol (B_{\pi/\sqrt{\lambda}}(c(2j+1)\pi/\sqrt{\lambda})) \geq \lim_{j\to\infty} j \cdot Vol (S^n(1/\sqrt{\lambda})) = \infty$.

If M is 2-dimensional and $0 \le K \le \lambda$, then by Classification Theorem in [1], M is isometric to a cylinder or a flat open möbius band or P^2 which is homeomorphic to E^2 . If M is homeomorphic to E^2 , then by Theorem 1, $i(p) \ge \pi/\sqrt{\lambda}$ for all $p \in M$. And just as in above we see Vol $(M) = \infty$. Q.E.D.

Remark. If Toponogov's result in [4] is true, then Theorem 2 is true for all manifolds satisfying $0 \leq K_{\sigma} \leq \lambda$.

References

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