

On the principal symbols of K_C -invariant differential operators on Hermitian symmetric spaces

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Abstract. Let (G, K) be one of the following Hermitian symmetric pair: $(SU(p, q), S(U(p) \times U(q)))$, $(Sp(n, \mathbf{R}), U(n))$, or $(SO^*(2n), U(n))$. Let G_C and K_C be the complexifications of G and K , respectively, Q the maximal parabolic subgroup of G_C whose Levi part is K_C , and V the holomorphic tangent space at the origin of G/K . It is known that the ring of K_C -invariant differential operators on V has a generating system $\{\Gamma_k\}$ given in terms of determinant or Pfaffian that plays an essential role in the Capelli identities. Our main result is that determinant or Pfaffian of a deformation of the twisted moment map on the holomorphic cotangent bundle of G_C/Q provides a generating function for the principal symbols of Γ_k 's.

1. Introduction.

Let $V := \text{Alt}_n$ be the \mathbf{C} -vector space consisting of all alternating $n \times n$ complex matrices, and $\mathbf{C}[V]$ the \mathbf{C} -algebra consisting of all polynomial functions on V . Then the complex general linear group GL_n acts on V by

$$g.Z := gZ^t g \quad (g \in GL_n, Z \in V), \quad (1.1)$$

where ${}^t g$ denotes the transpose of g , and one can define a representation π of GL_n on $\mathbf{C}[V]$ by

$$\pi(g)f(Z) := f(g^{-1}.Z) \quad (g \in GL_n, f \in \mathbf{C}[V]). \quad (1.2)$$

For $Z = (z_{i,j})_{i,j=1,\dots,n} \in V$, with $z_{j,i} = -z_{i,j}$, let $M := (z_{i,j})_{i,j}$ and $D := (\partial_{i,j})_{i,j}$ be the alternating $n \times n$ matrices whose (i, j) -th entries are given by the multiplication operator $z_{i,j}$ and the derivation $\partial_{i,j} := \partial/\partial z_{i,j}$, respectively. Then the representation $d\pi$ of \mathfrak{gl}_n , the Lie algebra of GL_n , induced from π is given by

$$d\pi(E_{i,j}) = - \sum_{k=1}^n z_{k,j} \partial_{k,i} \quad (i, j = 1, 2, \dots, n) \quad (1.3)$$

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where $E_{i,j}$ denotes the matrix unit of size $n \times n$ which is a basis for \mathfrak{gl}_n .

Let us denote by $U(\mathfrak{gl}_n)$ and $U(\mathfrak{gl}_n)^{GL_n}$ the universal enveloping algebra of \mathfrak{gl}_n , and its subring consisting of GL_n -invariant elements, respectively. Also, let us denote by $\mathcal{P}\mathcal{D}(V)$ and $\mathcal{P}\mathcal{D}(V)^{GL_n}$ the ring of differential operators on V with polynomial coefficients, and its subring consisting of GL_n -invariant differential operators, respectively. Then the following fact is known:

THEOREM ([4]).

(1) *The ring homomorphism $U(\mathfrak{gl}_n)^{GL_n} \rightarrow \mathcal{P}\mathcal{D}(V)^{GL_n}$ induced canonically from $d\pi$ is surjective.*

(2) *For $k = 1, 2, \dots, \lfloor n/2 \rfloor^1$, let*

$$\Gamma_k := \sum_{I \subset [n], |I|=2k} \text{Pf}(z_I)\text{Pf}(\partial_I), \tag{1.4}$$

where the sum is taken over all subsets $I \subset [n] := \{1, 2, \dots, n\}$ such that its cardinality is $2k$, and z_I, ∂_I denote submatrices of M, D consisting of $z_{i,j}, \partial_{i,j}$ with $i, j \in I$.² Then $\{\Gamma_k\}_{k=1,2,\dots,\lfloor n/2 \rfloor}$ forms a generating system for $\mathcal{P}\mathcal{D}(V)^{GL_n}$.

In particular, for $k = 1, 2, \dots, \lfloor n/2 \rfloor$, there exist elements of $U(\mathfrak{gl}_n)^{GL_n}$, called *skew Capelli elements*, that correspond to Γ_k under the homomorphism. As the names show, they play an essential role in the skew Capelli identity.

Now, following [6], [8], let us consider a $2n \times 2n$ matrix Φ alternating along the anti-diagonal with entries in $\mathcal{P}\mathcal{D}(V)$:

$$\Phi := \left[\begin{array}{cccc|cccc} u & & & & z_{1,n} & \cdots & z_{1,2} & 0 \\ & u & & & \vdots & \ddots & 0 & -z_{1,2} \\ & & \ddots & & z_{n-1,n} & 0 & \ddots & \vdots \\ & & & u & 0 & -z_{n-1,n} & \cdots & -z_{1,n} \\ \hline \partial_{1,n} & \cdots & \partial_{n-1,n} & 0 & -u & & & \\ \vdots & \ddots & 0 & -\partial_{n-1,n} & & \ddots & & \\ \partial_{1,2} & 0 & \ddots & \vdots & & & -u & \\ 0 & -\partial_{1,2} & \cdots & -\partial_{1,n} & & & & -u \end{array} \right], \tag{1.5}$$

¹For $x \in \mathbf{R}$, $\lfloor x \rfloor$ stands for the greatest integer not exceeding x .

²For an alternating matrix A , $\text{Pf}(A)$ denotes the Pfaffian of A ; see [7], or (A.1) and (A.2) for its definition.

where u is a parameter that commutes with $x_{i,j}$ and $\partial_{i,j}$ for all i, j . Our original motivation of this work is to understand the skew Capelli elements more deeply, but let us focus on the corresponding *commutative* objects i.e. the principal symbols of Γ_k , which we denote by γ_k , before we enter the *noncommutative* world. So, it is immediate from the minor summation formula of Pfaffian (see [5], or (A.4) below) that the symbol $\sigma(\text{Pf}(\Phi))$ of $\text{Pf}(\Phi)$ provides a generating function for $\{\gamma_k\}$:

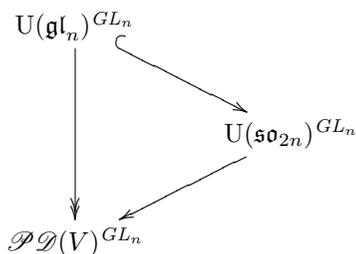
$$\sigma(\text{Pf}(\Phi)) = \sum_{k=0}^{\lfloor n/2 \rfloor} u^{n-2k} \gamma_k, \tag{1.6}$$

where we put $\gamma_0 = 1$ for convenience.

As for the noncommutative counterpart, we can show that $\text{Pf}(\Phi)$ can be expanded in the same way as (1.6), but with the coefficient u^{n-2k} of γ_k replaced by certain monic polynomial in u of degree $n - 2k$ which is essentially the Hermite polynomial (see [2]). Thus, if Φ came from $U(\mathfrak{gl}_n) \otimes \text{Mat}_n(\mathbf{C})$, it would follow immediately from the property of Pfaffian that all Γ_k belong to $U(\mathfrak{gl}_n)^{GL_n}$. However, it follows from (1.3) that there exist no elements of $U(\mathfrak{gl}_n)$ that correspond to the multiplication operators $z_{i,j}$, nor the derivations $\partial_{i,j}$.

What is the natural reason for considering the matrix Φ above (or, its commutative counterpart)?

We observe that the action (1.1) of GL_n on $V = \text{Alt}_n$ is the holomorphic part of the complexification of isotropy representation at the origin of Hermitian symmetric space $SO^*(2n)/U(n)$. So, we embed $U(\mathfrak{gl}_n)^{GL_n}$ into $U(\mathfrak{so}_{2n})^{GL_n}$ and seek for a generating function for $\{\gamma_k\}$ in the latter, in order to find an answer to the question raised above. Here \mathfrak{so}_{2n} denotes the complexification of the Lie algebra of $SO^*(2n)$.



The real linear Lie group $SO^*(2n)$ has irreducible unitary representations, called holomorphic discrete series representations. We construct one of them, say π_λ , via Borel-Weil theory, which we induce from a holomorphic character

$\lambda : Q \rightarrow \mathbf{C}^\times$ whose differential is given by a multiple of the half sum of the noncompact positive roots, where Q is the maximal parabolic subgroup of the complex special orthogonal group SO_{2n} whose Levi part is isomorphic to GL_n . Note that π_λ is represented on the Hilbert space consisting of square-integrable holomorphic functions defined on an open subset of V , and that the restriction of π_λ to K -finite part coincides with π given in (1.2) when λ is trivial.

Let $d\pi_\lambda$ be the differential representation induced from π_λ , which we extend to the representation of \mathfrak{so}_{2n} by linearity. Take a basis $\{X_i\}$ for \mathfrak{so}_{2n} , and its dual basis $\{X_i^\vee\}$, i.e. the basis for \mathfrak{so}_{2n} satisfying that

$$B(X_i, X_j^\vee) = \delta_{i,j},$$

where B is the nondegenerate bilinear form on \mathfrak{so}_{2n} given by $B(X, Y) := (1/2)\text{tr}(XY)$. For $X \in \mathfrak{so}_{2n}$ given, we denote by $\sigma_\lambda(X)$ the symbol of the differential operator $d\pi_\lambda(X)$ substituted $\xi_{i,j}$ for $\partial_{i,j}$. Now we define an element $\sigma_\lambda(\mathbf{X}) \in \mathbf{C}[z_{i,j}, \xi_{i,j}; 1 \leq i < j \leq n] \otimes \mathfrak{so}_{2n}$ by

$$\sigma_\lambda(\mathbf{X}) := \sum_i \sigma_\lambda(X_i^\vee) \otimes X_i.$$

Note that $\sigma_\lambda(\mathbf{X})$ is independent of the basis $\{X_i\}$ chosen and that it can be considered to be a variant of the twisted moment map on the holomorphic cotangent bundle $T^*(SO_{2n}/Q)$ (see [11]). Then we deform $\sigma_\lambda(\mathbf{X})$ by shifting the parameter of λ by γ_1 , and replace the shifted parameter with a newly introduced indeterminate, say τ ; we denote by $\tilde{\sigma}_\lambda(\mathbf{X})$ the deformed symbol with τ (see Section 3 for details).

One of our main results is that Pfaffian of $\tilde{\sigma}_\lambda(\mathbf{X})$ provides a generating function for $\{\gamma_k\}$ (Theorem 3.1 (3)). On the way of proof, we will find that there naturally appears a matrix which looks like Φ given in (1.5). Namely, if we regard $\tilde{\sigma}_\lambda(\mathbf{X})$ as the value at (x, ξ) of the map

$$T^*(SO_{2n}/Q) \rightarrow \mathbf{C}[\tau, z_{i,j}, \xi_{i,j}] \otimes \mathfrak{so}_{2n}, \quad (x, \xi) \mapsto \tilde{\sigma}_\lambda(\mathbf{X}),$$

and denote by u_x the element of U_Ω (see Section 2 for the notation) that translates the origin of SO_{2n}/Q to x , we see that $\text{Ad}(u_x^{-1})\tilde{\sigma}_\lambda(\mathbf{X})$ is of the form

$$\left[\begin{array}{cccc|cccc} \tau + \gamma_1 & & & & -\vartheta z_{1,n-1} & \cdots & -\vartheta z_{1,2} & 0 \\ & \tau + \gamma_1 & & & -\vartheta z_{2,n-1} & \cdots & 0 & \vartheta z_{1,2} \\ & & \ddots & & \vdots & \ddots & \vdots & \vdots \\ & & & \tau + \gamma_1 & 0 & \cdots & \vartheta z_{2,n-1} & \vartheta z_{1,n-1} \\ \hline -\xi_{1,n-1} & -\xi_{2,n-1} & \cdots & 0 & -\tau - \gamma_1 & & & \\ \vdots & \vdots & \ddots & \vdots & & \ddots & & \\ -\xi_{1,2} & 0 & \cdots & \xi_{2,n-1} & & & -\tau - \gamma_1 & \\ 0 & \xi_{1,2} & \cdots & \xi_{1,n-1} & & & & -\tau - \gamma_1 \end{array} \right],$$

where $(z_{i,j}; \xi_{i,j})$ are coordinates around $(x, \xi) \in T^*(SO_{2n}/Q)$, and we set $\vartheta := s - (\tau + \gamma_1)$ for brevity, with s the integral parameter of λ (Theorem 4.4).

All the setup so far also applies to the other two classical irreducible Hermitian symmetric pairs of noncompact type $(SU(p, q), S(U(p) \times U(q)))$ and $(Sp(n, \mathbf{R}), U(n))$. Let (G, K) be one of the two. Then the differential operators Γ_k given above have analogous objects, i.e. $K_{\mathcal{C}}$ -invariant differential operators acting on the space of polynomial functions on V , the holomorphic tangent space at the origin of G/K , which generate $\mathcal{P}\mathcal{D}(V)^{K_{\mathcal{C}}}$ and play an essential role in the corresponding Capelli identity, where $K_{\mathcal{C}}$ denotes a complexification of K (cf. [4]). In these cases, they are given in terms of (minor-)determinants defined analogously to M and D above (see (3.1) for details). If we define $\tilde{\sigma}_{\lambda}(\mathbf{X})$ in the same fashion as in the case of \mathfrak{so}_{2n} , we can show that the determinant of $\tilde{\sigma}_{\lambda}(\mathbf{X})$ provides a generating function for their principal symbols (Theorem 3.1 (1) and (2)).

The contents of this paper are as follows: In Section 2, we give explicit realizations of $G = SU(p, q), Sp(n, \mathbf{R})$ and $SO^*(2n)$, and their complexification $G_{\mathcal{C}}$. Then we make a brief review of construction of the holomorphic discrete series representations π_{λ} via Borel-Weil theory, which we induce from a character λ of a maximal parabolic subgroup of $G_{\mathcal{C}}$ whose Levi part is $K_{\mathcal{C}}$. In Section 3, we recall the definition of the $K_{\mathcal{C}}$ -invariant differential operators $\{\Gamma_k\}$ for each G , and introduce our main objects $\sigma_{\lambda}(\mathbf{X})$ and $\tilde{\sigma}_{\lambda}(\mathbf{X})$. Then we state our main result that the determinant or Pfaffian of $\tilde{\sigma}_{\lambda}(\mathbf{X})$ provides a generating function for the principal symbols of $\{\Gamma_k\}$ (Theorem 3.1). The proof is done case-by-case in Section 4 according as $G = SO^*(2n), Sp(n, \mathbf{R})$, or $SU(p, q)$ ($p \geq q$), which is based on explicit forms of the differential operators $d\pi_{\lambda}(X_i)$, with $\{X_i\}$ a basis for $\mathfrak{g} := \text{Lie}(G) \otimes_{\mathbf{R}} \mathbf{C}$. In Section 5, we show that $\sigma_{\lambda}(\mathbf{X})$ can be considered to be a variant of the twisted moment map. In the appendix, we recall the definition of Pfaffian, and collect a couple of minor summation formulae of Pfaffian and determinant without proof, which we make use of in proving the main results.

2. Holomorphic discrete series.

In what follows, let G denote one of $SU(p, q)$ ($p \geq q$), $Sp(n, \mathbf{R})$, or $SO^*(2n)$, which we realize as follows:

$$\begin{aligned} SU(p, q) &= \{g \in SL_{p+q}(\mathbf{C}); {}^t\bar{g}I_{p,q}g = I_{p,q}\}, \\ Sp(n, \mathbf{R}) &= \{g \in SU(n, n); {}^t gJ_{n,n}g = J_{n,n}\}, \\ SO^*(2n) &= \{g \in SU(n, n); {}^t gJ_{2n}g = J_{2n}\}. \end{aligned} \tag{2.1}$$

Here, for positive integers $p, q, n = 1, 2, \dots$, the matrices $I_{p,q}$, J_n , and $J_{n,n}$ are given by

$$I_{p,q} = \begin{bmatrix} 1_p & \\ & -1_q \end{bmatrix}, \quad J_n = \begin{bmatrix} & & & 1 \\ & & \cdot & \\ & & & \\ 1 & & & \end{bmatrix}, \quad J_{n,n} = \begin{bmatrix} & J_n \\ -J_n & \end{bmatrix}.$$

Let K be a maximal compact subgroup of G given by $K := \{ \begin{bmatrix} a & 0 \\ 0 & d \end{bmatrix} \in G \}$, where, for an element $\begin{bmatrix} a & 0 \\ 0 & d \end{bmatrix}$ in K , the submatrices a and d are of size $p \times p$ and $q \times q$, respectively, when $G = SU(p, q)$, or, both of size $n \times n$ when $G = SO^*(2n)$ and $Sp(n, \mathbf{R})$. Let $G_{\mathbf{C}}$ and $K_{\mathbf{C}}$ be the complexifications of G and K , respectively, and Q the maximal parabolic subgroup of $G_{\mathbf{C}}$ given by $Q := \{ \begin{bmatrix} a & 0 \\ c & d \end{bmatrix} \in G_{\mathbf{C}} \}$ so that its Levi part is $K_{\mathbf{C}}$. Define a holomorphic character $\lambda : Q \rightarrow \mathbf{C}^\times$ by

$$\lambda \left(\begin{bmatrix} a & 0 \\ c & d \end{bmatrix} \right) = (\det d)^{-s} \tag{2.2}$$

for $s \in \mathbf{Z}$. Denote by \mathbf{C}_λ the one-dimensional Q -module defined by $p.v = \lambda(p)v$ ($p \in Q, v \in \mathbf{C}$), and by L_λ the pull-back of the holomorphic line bundle $G_{\mathbf{C}} \times_Q \mathbf{C}_\lambda$ by the embedding $G/K = GQ/Q \hookrightarrow G_{\mathbf{C}}/Q$.

The space $\Gamma(L_\lambda)$ of all holomorphic sections for L_λ are identified with the space of all holomorphic functions f on the open subset $GQ \subset G_{\mathbf{C}}$ that satisfy

$$f(xp) = \lambda(p)^{-1}f(x) \quad (x \in GQ, p \in Q). \tag{2.3}$$

Define $\Gamma_{L^2}(L_\lambda)$ to be the subspace of $\Gamma(L_\lambda)$ consisting of square integrable holomorphic sections with respect to Haar measure on G :

$$\Gamma_{L^2}(L_\lambda) := \left\{ f \in \Gamma(L_\lambda); \int_G |f(g)|^2 dg < \infty \right\}, \tag{2.4}$$

and let G act on $\Gamma_{L^2}(L_\lambda)$ by

$$(T_\lambda(g)f)(x) := f(g^{-1}x) \quad (g \in G, x \in GQ).$$

Then $(T_\lambda, \Gamma_{L^2}(L_\lambda))$ is an irreducible unitary representation of G if it is not zero, called a *holomorphic discrete series*. One must impose some condition on s in order to require that $\Gamma_{L^2}(L_\lambda)$ be nonzero, which we do not consider here since we will be concerned with the representations of Lie algebras in this paper (see e.g. [9] for the condition).

Now, according as $G = SU(p, q)$ ($p \geq q$), $Sp(n, \mathbf{R})$, or $SO^*(2n)$, let us realize the bounded symmetric domain Ω as follows:

$$\begin{aligned} \text{if } G = SU(p, q), \quad \Omega &:= \{z \in \text{Mat}_{p,q}(\mathbf{C}); 1_q - {}^t\bar{z}z > 0\}; \\ \text{if } G = Sp(n, \mathbf{R}), \quad \Omega &:= \{z \in \text{Mat}_n(\mathbf{C}); 1_n - {}^t\bar{z}z > 0, J_n {}^t z J_n = z\}; \\ \text{if } G = SO^*(2n), \quad \Omega &:= \{z \in \text{Mat}_n(\mathbf{C}); 1_n - {}^t\bar{z}z > 0, J_n {}^t z J_n = -z\}, \end{aligned}$$

and let G act on Ω by linear fractional transformation:

$$g.z = (az + b)(cz + d)^{-1} \quad \left(g = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \in G, z \in \Omega \right). \tag{2.5}$$

Then Ω is isomorphic to G/K in each case. If we denote by $\mathcal{O}(\Omega)$ the space of all holomorphic functions on Ω , we define a map

$$\Phi : \Gamma(L_\lambda) \rightarrow \mathcal{O}(\Omega), \quad f \mapsto F$$

by

$$F(z) = f\left(\begin{bmatrix} 1 & z \\ 0 & 1 \end{bmatrix}\right).$$

Then Φ is a bijection. Let $\mathcal{H}_\lambda := \Phi(\Gamma_{L^2}(L_\lambda))$, and define an action π_λ of G on \mathcal{H}_λ so that the diagram (2.6) commutes for all $g \in G$:

$$\begin{array}{ccc} \Gamma_{L^2}(L_\lambda) & \xrightarrow{\Phi} & \mathcal{H}_\lambda \\ T_\lambda(g) \downarrow & & \downarrow \pi_\lambda(g) \\ \Gamma_{L^2}(L_\lambda) & \xrightarrow{\Phi} & \mathcal{H}_\lambda. \end{array} \tag{2.6}$$

Explicitly, it is given by

$$(\pi_\lambda(g)F)(z) = \det(cz + d)^s F((az + b)(cz + d)^{-1}) \tag{2.7}$$

for $g \in G$ and $F \in \mathcal{H}_\lambda$, where $g^{-1} = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$.

Let us introduce a few more notations. Let $\mathfrak{g} := \text{Lie}(G) \otimes_{\mathbf{R}} \mathbf{C}$, $\mathfrak{q} := \text{Lie}(Q)$, $\bar{\mathfrak{u}}$ the nilradical of \mathfrak{q} , and \mathfrak{u} its opposite. Then we have $\mathfrak{g} = \mathfrak{u} \oplus \mathfrak{q}$ and $\mathfrak{q} = \mathfrak{k} \oplus \bar{\mathfrak{u}}$, where $\mathfrak{k} := \text{Lie}(K) \otimes_{\mathbf{R}} \mathbf{C}$. We denote by \mathfrak{t} the Cartan subalgebra of \mathfrak{g} that consists of diagonal matrices in \mathfrak{g} . Let $d\pi_\lambda$ be the differential representation of $\text{Lie}(G)$ induced from π_λ , which we extend to the representation of the complex Lie algebra \mathfrak{g} by linearity. Furthermore, identifying Ω with an open subset of \mathfrak{u} by $z \leftrightarrow \begin{bmatrix} 0 & z \\ 0 & 0 \end{bmatrix}$, let U_Ω be the image of $\Omega \subset \mathfrak{u}$ by the exponential map. Note that if $t \in \mathbf{R}$ is sufficiently small, then $\exp tX$ acts on Ω for any $X \in \mathfrak{g}$ by (2.5), hence on \mathcal{H}_λ by (2.7). Thus its differential at $t = 0$ coincides with $d\pi_\lambda$.

Since we realize the real linear Lie groups G as in (2.1), the corresponding complex Lie algebras \mathfrak{g} are given by

$$\begin{aligned} \mathfrak{sl}_{p+q} &= \{X \in \text{Mat}_{p+q}(\mathbf{C}); \text{tr}(X) = 0\}, \\ \mathfrak{sp}_n &= \{X \in \text{Mat}_{2n}(\mathbf{C}); {}^tXJ_{n,n} + XJ_{n,n} = O\}, \\ \mathfrak{so}_{2n} &= \{X \in \text{Mat}_{2n}(\mathbf{C}); {}^tXJ_{2n} + XJ_{2n} = O\}, \end{aligned} \tag{2.8}$$

respectively.

REMARK 2.1. If we denote the character of \mathfrak{q} induced from $\lambda : Q \rightarrow \mathbf{C}^\times$ by the same letter λ , then it is proportional to ρ_n , the half sum of the noncompact positive roots; more precisely,

$$\lambda = \frac{2s}{\ell + \varepsilon} \rho_n,$$

where ℓ is the rank of \mathfrak{g} , and $\varepsilon = +1$ if $\mathfrak{g} = \mathfrak{sl}_{p+q}$ or \mathfrak{sp}_n , and $\varepsilon = -1$ if $\mathfrak{g} = \mathfrak{so}_{2n}$.

3. Principal symbols of $K_{\mathbf{C}}$ -invariant differential operators.

Let V denote the holomorphic tangent space at the origin of G/K . Then one can identify V with \mathfrak{u} and construct a representation of $K_{\mathbf{C}}$ on the \mathbf{C} -algebra $\mathbf{C}[V]$ of all polynomial function on V through the action of $K_{\mathbf{C}}$ on $V = \mathfrak{u}$. Let $\mathcal{P}\mathcal{D}(V)^{K_{\mathbf{C}}}$ be the ring of $K_{\mathbf{C}}$ -invariant differential operators with polynomial coefficient and $r := \mathbf{R}\text{-rank } G$, the real rank of G . Then it is known that there exists a generating system $\{\Gamma_k\}_{k=1,2,\dots,r}$ for $\mathcal{P}\mathcal{D}(V)^{K_{\mathbf{C}}}$ which is given in terms of

determinant or Pfaffian as follows ([4]):

3.1. The case $G = SU(p, q)$ ($p \geq q$).

In this case, $V = \mathfrak{u}$ is isomorphic to $\text{Mat}_{p,q}(\mathbf{C})$. Let M and D be $p \times q$ matrices whose (i, j) -th entries are given by the multiplication operators $z_{i,j}$ and the differential operators $\partial_{i,j} := \partial/\partial z_{i,j}$ for $i = 1, 2, \dots, p$ and $j = 1, 2, \dots, q$, and z_J^I and ∂_J^I submatrices of M and D consisting of $z_{i,j}$ and $\partial_{i,j}$, respectively, with $i \in I \subset [p]$ and $j \in J \subset [q]$. Then we define

$$\Gamma_k = \sum_{\substack{I \subset [p], J \subset [q] \\ |I|=|J|=k}} \det(z_J^I) \det(\partial_J^I) \quad (k = 1, 2, \dots, q), \quad (3.1a)$$

which indeed form a generating system for $\mathcal{PD}(V)^{\tilde{K}_C}$ with $\tilde{K}_C = GL_p \times GL_q \supset K_C$.

3.2. The case $G = Sp(n, \mathbf{R})$.

In this case, $V = \mathfrak{u}$ is isomorphic to the vector space of all symmetric $n \times n$ complex matrices $z = (z_{i,j})$, $z_{j,i} = z_{i,j}$. Let

$$\tilde{\partial}_{i,j} = \begin{cases} 2\partial_{i,j} & (i = j), \\ \partial_{i,j} & (i \neq j), \end{cases}$$

and let M and D be symmetric $n \times n$ matrices whose (i, j) -th entries are given by the multiplication operators $z_{i,j}$ and the differential operators $\tilde{\partial}_{i,j}$ for $i, j = 1, 2, \dots, n$. Then we define

$$\Gamma_k = \sum_{\substack{I, J \subset [n] \\ |I|=|J|=k}} \det(z_J^I) \det(\tilde{\partial}_J^I) \quad (k = 1, 2, \dots, n), \quad (3.1b)$$

where $z_J^I, \tilde{\partial}_J^I$ are as above, with $I, J \subset [n]$.

3.3. The case $G = SO^*(2n)$.

In this case, $V = \mathfrak{u}$ is isomorphic to the vector space of all alternating $n \times n$ complex matrices $z = (z_{j,i})$, $z_{j,i} = -z_{i,j}$. Let M and D be alternating $n \times n$ matrices whose (i, j) -th entries are given by the multiplication operators $z_{i,j}$ and the differential operators $\partial_{i,j}$ for $i, j = 1, 2, \dots, n$. Then we define

$$\Gamma_k = \sum_{I \subset [n], |I|=2k} \text{Pf}(z_I) \text{Pf}(\partial_I), \quad (k = 1, 2, \dots, \lfloor n/2 \rfloor) \quad (3.1c)$$

where z_I, ∂_I are as in the Introduction, with $I \subset [n]$.

Let \mathfrak{g} denote one of $\mathfrak{sl}_{p+q}, \mathfrak{sp}_n$, or \mathfrak{so}_{2n} again. Define a nondegenerate G_C -invariant bilinear form B on \mathfrak{g} by

$$B(X, Y) = \begin{cases} \text{tr}(XY) & \text{if } \mathfrak{g} = \mathfrak{sl}_{p+q}, \\ \frac{1}{2}\text{tr}(XY) & \text{if } \mathfrak{g} = \mathfrak{so}_{2n}, \text{ or } \mathfrak{sp}_n. \end{cases} \tag{3.2}$$

Given a basis $\{X_i\}_{i=1, \dots, \dim \mathfrak{g}}$ for \mathfrak{g} , let us denote by $\{X_i^\vee\}$ the dual basis with respect to B i.e. the basis for \mathfrak{g} satisfying

$$B(X_i, X_j^\vee) = \delta_{i,j}$$

for $i, j = 1, \dots, \dim \mathfrak{g}$. Then we define an element \mathbf{X} of $U(\mathfrak{g}) \otimes \text{Mat}_N(\mathbf{C})$ by

$$\mathbf{X} := \sum_{i=1}^{\dim \mathfrak{g}} X_i^\vee \otimes X_i, \tag{3.3}$$

where $U(\mathfrak{g})$ denotes the universal enveloping algebra of \mathfrak{g} , and N the size of matrices when \mathfrak{g} is realized as in (2.8). We regard the former and the latter factors in (3.3) as elements of $U(\mathfrak{g})$ and $\text{Mat}_N(\mathbf{C})$ respectively.

Denoting by $\sigma_\lambda(X)$ the symbol of the differential operator $d\pi_\lambda(X)$ for $X \in \mathfrak{g}$, let us define a \mathfrak{g} -valued polynomial function on the holomorphic cotangent bundle $T^*(G_C/Q)$ by

$$\sigma_\lambda(\mathbf{X}) := \sum_{i=1}^{\dim \mathfrak{g}} \sigma_\lambda(X_i^\vee) \otimes X_i. \tag{3.4}$$

By definition, \mathbf{X} and $\sigma_\lambda(\mathbf{X})$ are independent of the basis $\{X_i\}$ chosen.

Note that $\sigma_\lambda(X_i^\vee)$ involves the parameter s if and only if X_i^\vee is in \mathfrak{t} , or in \mathfrak{u}^- . We will see that $\sigma_\lambda(X_i^\vee)$ takes the following form:

$$\sigma_\lambda(X_i^\vee) = \begin{cases} \kappa_i s + (\text{linear terms in } \xi_\alpha \text{'s}) & \text{if } X_i^\vee \in \mathfrak{t}, \\ \kappa_i s z_i + (\text{linear terms in } \xi_\alpha \text{'s}) & \text{if } X_i^\vee \in \mathfrak{u}^-, \end{cases} \tag{3.5}$$

for some $\kappa_i \neq 0 \in \mathbf{Q}$, where $(z_\alpha; \xi_\alpha)$ are coordinates around $(z, \xi) \in T^*(G_C/Q)$ (see Propositions 4.1, 4.5 and 4.8 below). Now, we shift the parameter s by γ_1 and replace $s - \gamma_1$ by a new parameter, say τ , as follows:

- If the symbol $\sigma_\lambda(X_i^\vee)$ involves s , we rewrite $\kappa_i s$ in (3.5) as

$$\kappa_i s = \frac{\kappa_i}{|\kappa_i|} (s - (1 - |\kappa_i|)s),$$

and substitute $\tau + \gamma_1$ into the former s :

$$\frac{\kappa_i}{|\kappa_i|} (\tau + \gamma_1 - (1 - |\kappa_i|)s).$$

Let us denote by $\tilde{\sigma}_\lambda(X_i^\vee)$ the deformed symbol with τ obtained in this way.

- If the symbol $\sigma_\lambda(X_i^\vee)$ does not involve s , we let $\tilde{\sigma}_\lambda(X_i^\vee) := \sigma_\lambda(X_i^\vee)$.

Finally, we define

$$\tilde{\sigma}_\lambda(\mathbf{X}) := \sum_{i=1}^{\dim \mathfrak{g}} \tilde{\sigma}_\lambda(X_i^\vee) \otimes X_i \in \mathbf{C}[\tau, z_\alpha, \xi_\alpha] \otimes \mathfrak{g}. \tag{3.6}$$

Denoting the principal symbol of Γ_k by γ_k for each $k = 1, 2, \dots, r$, our main result is the following.

THEOREM 3.1. *The determinant or Pfaffian of $\tilde{\sigma}_\lambda(\mathbf{X})$ provides a generating function for $\{\gamma_k\}_{k=1,2,\dots,r}$. More precisely, we have the following identities:*

1. For $G = SU(p, q)$ with $p \geq q$,

$$\begin{aligned} \det(\tilde{\sigma}_\lambda(\mathbf{X})) &= (-1)^q \sum_{k=0}^q \left(\tau + \gamma_1 - \frac{p}{p+q} s \right)^{p-k} \\ &\quad \cdot \left(\tau + \gamma_1 - \frac{q}{p+q} s \right)^{q-k} (s - (\tau + \gamma_1))^k \gamma_k; \end{aligned} \tag{3.7a}$$

2. For $G = Sp(n, \mathbf{R})$,

$$\det(\tilde{\sigma}_\lambda(\mathbf{X})) = (-1)^n \sum_{k=0}^n (\tau + \gamma_1)^{2n-2k} (s - (\tau + \gamma_1))^k \gamma_k; \tag{3.7b}$$

3. For $G = SO^*(2n)$,

$$\text{Pf}(\tilde{\sigma}_\lambda(\mathbf{X})) = \sum_{k=0}^{\lfloor n/2 \rfloor} (\tau + \gamma_1)^{n-2k} (s - (\tau + \gamma_1))^k \gamma_k; \tag{3.7c}$$

where we set $\gamma_0 = 1$.

We will give the proof of these identities in the next section case-by-case.

4. Proof of main result.

Let us denote the $m \times n$ matrix whose (i, j) -th entry is 1 and all others are 0 by $E_{i,j}^{(m,n)}$, which, if $m = n$, we abbreviate to $E_{i,j}^{(n)}$; moreover, if the size of $E_{i,j}^{(n)}$ is equal to the size of the linear Lie algebra under consideration, we suppress the superscript.

4.1. The case $G = SO^*(2n)$.

First let us prove the case where $G = SO^*(2n)$, or $\mathfrak{g} = \mathfrak{so}_{2n}$, since this is our starting point of this project. Take a basis $\{X_{i,j}^\epsilon\}_{\epsilon=0,\pm; i,j \in [n]}$ for \mathfrak{so}_{2n} as follows:

$$\begin{aligned} X_{i,j}^0 &:= E_{i,j} - E_{-j,-i} \quad (1 \leq i, j \leq n), \\ X_{i,j}^+ &:= E_{i,-j} - E_{j,-i} \quad (1 \leq i < j \leq n), \\ X_{i,j}^- &:= E_{-j,i} - E_{-i,j} \quad (1 \leq i < j \leq n), \end{aligned} \tag{4.1}$$

where we agree that $-i$ stands for $2n + 1 - i$ in what follows.

PROPOSITION 4.1. *The differential operators $d\pi_\lambda(X_{i,j}^\epsilon)$ ($\epsilon = 0, \pm; i, j \in [n]$) are given by*

$$d\pi_\lambda(X_{i,j}^0) = s\delta_{i,j} - \sum_{k \in [n]} z_{k,j} \partial_{k,i}, \tag{4.2}$$

$$d\pi_\lambda(X_{i,j}^+) = -\partial_{i,j}, \tag{4.3}$$

$$d\pi_\lambda(X_{i,j}^-) = -2sz_{i,j} - \sum_{1 \leq k < l \leq n} (z_{k,i}z_{j,l} - z_{k,j}z_{i,l}) \partial_{k,l}. \tag{4.4}$$

PROOF. Let $\tilde{z} = \sum_{k,l \in [n]} z_{k,l} E_{k,l}^{(n)}$ with $z_{l,k} = -z_{k,l}$. Then $z := \tilde{z}J_n$ belongs to Ω if it is positive definite.

(I) First we calculate $d\pi_\lambda(X_{i,j}^0)$. Writing $\begin{bmatrix} a & 0 \\ 0 & d \end{bmatrix} := \exp(-tX_{i,j}^0)$, we see that

$$\begin{aligned} &\exp(-tX_{i,j}^0).z \\ &= azd^{-1} \\ &= \left(1_n - tE_{i,j}^{(n)} + O(t^2)\right)z \left(1_n + tE_{n+1-j, n+1-i}^{(n)} + O(t^2)\right)^{-1} \end{aligned}$$

$$\begin{aligned}
&= \left(\tilde{z} - t \left(E_{i,j}^{(n)} \tilde{z} + \tilde{z} E_{j,i}^{(n)} \right) \right) J_n + O(t^2) \\
&= \left(\sum_{k,l \in [n]} z_{k,l} E_{k,l}^{(n)} - t \sum_{k,l \in [n]} z_{k,l} \left(E_{i,j}^{(n)} E_{k,l}^{(n)} + E_{k,l}^{(n)} E_{j,i}^{(n)} \right) \right) J_n + O(t^2) \\
&= \sum_{k,l \in [n]} \left(z_{k,l} - t(\delta_{i,k} z_{j,l} + \delta_{i,l} z_{k,j}) \right) E_{k,l}^{(n)} J_n + O(t^2)
\end{aligned}$$

and that

$$(\det d)^s = \left(\det \left(1_n + t E_{n+1-j, n+1-i}^{(n)} + O(t^2) \right) \right)^s = e^{s \operatorname{str} \left(E_{n+1-j, n+1-i}^{(n)} \right) + O(t^2)}.$$

Therefore, for $F \in \mathcal{H}_\lambda$, we obtain that

$$\begin{aligned}
&(\mathrm{d}\pi_\lambda(X_{i,j}^0)F)(z) \\
&= \frac{d}{dt} \Big|_{t=0} \left(\pi_\lambda(\exp(tX_{i,j}^0))F \right)(z) \\
&= \frac{d}{dt} \Big|_{t=0} e^{s \operatorname{str} \left(E_{n+1-j, n+1-i}^{(n)} \right)} F \left(\sum_{k,l \in [n]} \left(z_{k,l} - t(\delta_{i,k} z_{j,l} + \delta_{i,l} z_{k,j}) \right) E_{k,l}^{(n)} J_n \right) \\
&= \left(s\delta_{i,j} - \sum_{k < l} (\delta_{i,k} z_{j,l} + \delta_{i,l} z_{k,j}) \partial_{k,l} \right) F(z) \\
&= \left(s\delta_{i,j} - \sum_{i < l} z_{j,l} \partial_{i,l} - \sum_{k < i} z_{k,j} \partial_{k,i} \right) F(z) \\
&= \left(s\delta_{i,j} - \sum_{k \in [n]} z_{j,k} \partial_{i,k} \right) F(z).
\end{aligned}$$

(II) Next we calculate $\mathrm{d}\pi_\lambda(X_{i,j}^+)$. Writing $\begin{bmatrix} 1 & b \\ 0 & 1 \end{bmatrix} := \exp(-tX_{i,j}^+)$, we see that

$$\begin{aligned}
\exp(-tX_{i,j}^+).z &= z + b \\
&= \left(\tilde{z} - t \left(E_{i,j}^{(n)} - E_{j,i}^{(n)} \right) \right) J_n \\
&= \sum_{k,l \in [n]} (z_{k,l} - t\delta_{i,k}\delta_{j,l} + t\delta_{j,k}\delta_{i,l}) E_{k,l}^{(n)} J_n,
\end{aligned}$$

hence we obtain

$$\begin{aligned} d\pi_\lambda(X_{i,j}^+) &= -\sum_{k<l}(\delta_{i,k}\delta_{j,l} - \delta_{i,l}\delta_{j,k})\partial_{k,l} \\ &= -\partial_{i,j}. \end{aligned}$$

(III) Finally, let us calculate $d\pi_\lambda(X_{i,j}^-)$. Writing $\begin{bmatrix} 1 & 0 \\ c & 1 \end{bmatrix} := \exp(-tX_{i,j}^-)$, we see that

$$\begin{aligned} &\exp(-tX_{i,j}^-).z \\ &= z(1_n + cz)^{-1} \\ &= z\left(1_n + tJ_n\left(E_{i,j}^{(n)} - E_{j,i}^{(n)}\right)z\right)^{-1} \\ &= \left(\tilde{z} - t\tilde{z}\left(E_{i,j}^{(n)} - E_{j,i}^{(n)}\right)\tilde{z}\right)J_n + O(t^2) \\ &= \left(\sum_{k,l} z_{k,l}E_{k,l}^{(n)} - t\sum_{a,b,c,d} z_{a,b}z_{c,d}E_{a,b}^{(n)}\left(E_{i,j}^{(n)} - E_{j,i}^{(n)}\right)E_{c,d}^{(n)}\right)J_n + O(t^2) \\ &= \sum_{k,l} \left(z_{k,l} - t(z_{k,i}z_{j,l} - z_{k,j}z_{i,l})\right)E_{k,l}^{(n)}J_n + O(t^2), \end{aligned}$$

and that

$$\begin{aligned} \det(1_n + cz)^s &= \left(\det\left(1_n + tJ_n\left(E_{i,j}^{(n)} - E_{j,i}^{(n)}\right)\tilde{z}J_n\right)\right)^s \\ &= e^{st\text{tr}\left(\left(E_{i,j}^{(n)} - E_{j,i}^{(n)}\right)\tilde{z}\right) + O(t^2)} \\ &= e^{st(z_{j,i} - z_{i,j}) + O(t^2)} = e^{-2stz_{i,j} + O(t^2)}, \end{aligned}$$

from which we obtain

$$d\pi_\lambda(X_{i,j}^-) = -2sz_{i,j} - \sum_{k<l}(z_{k,i}z_{j,l} - z_{k,j}z_{i,l})\partial_{k,l}.$$

This completes the proof. □

Noting that the dual basis of (4.1) is given by

$$(X_{i,j}^0)^\vee = X_{j,i}^0, \quad (X_{i,j}^\pm)^\vee = X_{i,j}^\mp,$$

let us define the element \mathbf{X} of $U(\mathfrak{g}) \otimes \text{Mat}_{2n}(\mathbb{C})$ by (3.3); it looks like

$$\mathbf{X} = \left[\begin{array}{cccc|cccc} X_{1,1}^0 & X_{2,1}^0 & \cdots & X_{n,1}^0 & X_{1,n}^- & \cdots & X_{1,2}^- & 0 \\ X_{1,2}^0 & X_{2,2}^0 & \cdots & X_{n,2}^0 & \vdots & \ddots & 0 & -X_{1,2}^- \\ \vdots & \vdots & & \vdots & X_{n-1,n}^- & 0 & \ddots & \vdots \\ X_{1,n}^0 & X_{2,n}^0 & \cdots & X_{n,n}^0 & 0 & -X_{n-1,n}^- & \cdots & -X_{1,n}^- \\ \hline X_{1,n}^+ & \cdots & X_{n-1,n}^+ & 0 & -X_{n,n}^0 & \cdots & -X_{n,2}^0 & -X_{n,1}^0 \\ \vdots & \ddots & 0 & -X_{n-1,n}^+ & \vdots & & \vdots & \vdots \\ X_{1,2}^+ & 0 & \ddots & \vdots & -X_{2,n}^0 & \cdots & -X_{2,2}^0 & -X_{2,1}^0 \\ 0 & -X_{1,2}^+ & \cdots & -X_{1,n}^+ & -X_{1,n}^0 & \cdots & -X_{1,2}^0 & -X_{1,1}^0 \end{array} \right].$$

REMARK 4.2. It is well known that Pfaffian $\text{Pf}(\mathbf{X})$ of the matrix \mathbf{X} given above³ is a central element of the universal enveloping algebra $U(\mathfrak{so}_{2n})$ (see [7] for the definition and the properties of Pfaffian with noncommutative entries).

Following the prescription (3.4), let us define $\sigma_\lambda(\mathbf{X})$ by substituting $\xi_{i,j}$ into $\partial_{i,j}$:

$$\sigma_\lambda(\mathbf{X}) := \sum_{\epsilon; i,j} \sigma_\lambda((X_{i,j}^\epsilon)^\vee) \otimes X_{i,j}^\epsilon. \tag{4.5}$$

THEOREM 4.3. Let $u(z) := \exp \sum_{i < j} z_{i,j} (X_{i,j}^-)^\vee \in U_\Omega$. Then we have

$$\text{Ad}(u(z)^{-1})\sigma_\lambda(\mathbf{X}) = s \sum_i X_{i,i}^0 - \sum_{i < j} \xi_{i,j} X_{i,j}^- \tag{4.6}$$

$$= \left[\begin{array}{cccc|cccc} s & & & & & & & \\ & s & & & & & & \\ & & \ddots & & & & & \\ & & & s & & & & \\ \hline -\xi_{1,n-1} & -\xi_{2,n-1} & \cdots & 0 & -s & & & \\ \vdots & \vdots & \ddots & \vdots & & \ddots & & \\ -\xi_{1,2} & 0 & \cdots & \xi_{2,n-1} & & & -s & \\ 0 & \xi_{1,2} & \cdots & \xi_{1,n-1} & & & & -s \end{array} \right]. \tag{4.7}$$

³Throughout the paper, for a $2n \times 2n$ matrix A alternating along the antidiagonal, we denote $\text{Pf}(AJ_{2n})$ by $\text{Pf}(A)$ for brevity.

PROOF. This is just a simple matrix calculation, but we give a rather detailed one, which we will need in proving the theorem stated below. In what follows, for a matrix A given, let us denote its (i, j) -th entry by A_{ij} .

Writing $\begin{bmatrix} 1 & z \\ 0 & 1 \end{bmatrix} := u(z)$ and $\begin{bmatrix} A & B \\ C & D \end{bmatrix} := \sigma_\lambda(\mathbf{X})$, we have

$$\text{Ad}(u(z)^{-1})\sigma_\lambda(\mathbf{X}) = \begin{bmatrix} A - zC & Az - zCz + B - zD \\ C & Cz + D \end{bmatrix}. \tag{4.8}$$

(I) First, we calculate the $(1, 1)$ and $(2, 2)$ -blocks. Let $\tilde{C} := J_n C$. Note that, by definition, A_{ij} is $\sigma_\lambda(X_{j,i}^0)$. Since $(zC)_{ij} = (\tilde{z}\tilde{C})_{ij}$ equals $\sum_{k=1}^n z_{i,k}\xi_{k,j} - \sum_{k=1}^n z_{i,k}\xi_{j,k}$, it follows from (4.2) that

$$A = s1_n + zC. \tag{4.9}$$

Then the fact that (4.8) is an element of \mathfrak{so}_{2n} implies that

$$Cz + D = -J_n{}^t(A - zC)J_n = -s1_n. \tag{4.10}$$

(II) Next we show that the $(1, 2)$ -block equals 0. Let $\tilde{B} := BJ_n$. Since $(\tilde{z}\tilde{C}\tilde{z})_{ij}$ equals

$$\sum_{k,l \in [n]} z_{i,k}\xi_{k,l}z_{l,j} = \left(\sum_{k < l} + \sum_{k > l} \right) z_{i,k}z_{l,j}\xi_{k,l} = \sum_{1 \leq k < l \leq n} (z_{k,i}z_{j,l} - z_{k,j}z_{i,l})\xi_{k,l},$$

it follows from (4.4) that $\tilde{B} = -2s\tilde{z} - \tilde{z}\tilde{C}\tilde{z}$ and

$$B = -2sz - zCz. \tag{4.11}$$

Therefore we obtain that

$$\begin{aligned} Az - zCz + B - zD &= (s1_n + zC)z - zCz - 2sz - zCz - z(-s1_n - Cz) \\ &= 0. \end{aligned}$$

This completes the proof. □

Now, using the principal symbol $\gamma_1 = \sum_{k < l} z_{k,l}\xi_{k,l}$ of the Euler operator Γ_1 on V and a new parameter τ , we deform the symbols $\sigma_\lambda(X_{i,i}^0)$ and $\sigma_\lambda(X_{i,j}^-)$, following the prescription given in Section 3 (see the paragraph just before Theorem 3.1). Note that they can be written as

$$\sigma_\lambda(X_{i,i}^0) = s - \gamma_1 + \sum_{\substack{k < l \\ k, l \neq i}} z_{k,l} \xi_{k,l},$$

$$\sigma_\lambda(X_{i,j}^-) = -(s - \gamma_1 + s)z_{i,j} + \gamma_1 z_{i,j} - \sum_{k < l} (z_{k,i} z_{j,l} - z_{k,j} z_{i,l}) \xi_{k,l}.$$

We replace $s - \gamma_1$ by τ in the above formulae, and denote the deformed symbols with τ by $\tilde{\sigma}_\lambda(X_{i,i}^0)$ and $\tilde{\sigma}_\lambda(X_{i,j}^-)$, respectively:

$$\tilde{\sigma}_\lambda(X_{i,i}^0) := \tau + \sum_{\substack{k < l \\ k, l \neq i}} z_{k,l} \xi_{k,l}, \tag{4.12}$$

$$\tilde{\sigma}_\lambda(X_{i,j}^-) := -(\tau + s + \gamma_1)z_{i,j} - \sum_{k < l} (z_{k,i} z_{j,l} - z_{k,j} z_{i,l}) \xi_{k,l}; \tag{4.13}$$

as for the other symbols, we set $\tilde{\sigma}_\lambda(X_{i,j}^\epsilon) := \sigma_\lambda(X_{i,j}^\epsilon)$. Then we define $\tilde{\sigma}_\lambda(\mathbf{X})$ by

$$\tilde{\sigma}_\lambda(\mathbf{X}) := \sum_{\epsilon; i, j} \tilde{\sigma}_\lambda((X_{i,j}^\epsilon)^\vee) \otimes X_{i,j}^\epsilon.$$

THEOREM 4.4. *Let $u(z) \in U_\Omega$ be as in Theorem 4.3. Then we have*

$$\begin{aligned} & \text{Ad}(u(z)^{-1})\tilde{\sigma}_\lambda(\mathbf{X}) \\ &= (\tau + \gamma_1) \sum_i X_{i,i}^0 - \sum_{i < j} \xi_{i,j} X_{i,j}^- - (s - (\tau + \gamma_1)) \sum_{i < j} z_{i,j} X_{i,j}^+ \end{aligned} \tag{4.14}$$

$$= \left[\begin{array}{cccc|cccc} \tau + \gamma_1 & & & & -\vartheta z_{1,n-1} & \cdots & -\vartheta z_{1,2} & 0 \\ & \tau + \gamma_1 & & & -\vartheta z_{2,n-1} & \cdots & 0 & \vartheta z_{1,2} \\ & & \ddots & & \vdots & \ddots & \vdots & \vdots \\ & & & \tau + \gamma_1 & 0 & \cdots & \vartheta z_{2,n-1} & \vartheta z_{1,n-1} \\ \hline -\xi_{1,n-1} & -\xi_{2,n-1} & \cdots & 0 & -\tau - \gamma_1 & & & \\ \vdots & \vdots & \ddots & \vdots & & \ddots & & \\ -\xi_{1,2} & 0 & \cdots & \xi_{2,n-1} & & & -\tau - \gamma_1 & \\ 0 & \xi_{1,2} & \cdots & \xi_{1,n-1} & & & & -\tau - \gamma_1 \end{array} \right]. \tag{4.15}$$

Here, we set $\vartheta := s - (\tau + \gamma_1)$ in (4.15) for brevity.

PROOF. Let $\begin{bmatrix} A(\tau) & B(\tau) \\ C & D(\tau) \end{bmatrix} := \tilde{\sigma}_\lambda(\mathbf{X})$. (Note that the submatrix C is the same

as in the proof of Theorem 4.3). Then it suffices to show that

$$A(\tau) - zC = (\tau + \gamma_1)1_n, \tag{4.16}$$

$$A(\tau)z - zCz + B(\tau) - zD(\tau) = (\tau + \gamma_1 - s)z, \tag{4.17}$$

$$Cz + D(\tau) = -(\tau + \gamma_1)1_n \tag{4.18}$$

(see (4.8)).

(I) First we show (4.16) and (4.18). But the latter follows from the former, as in the proof of Theorem 4.3. Note that $A(\tau)_{ij} = \tilde{\sigma}_\lambda(X_{j,i})$ can be written as

$$A(\tau)_{ij} = \left(\tau + \sum_{k<l} z_{k,l} \xi_{k,l} \right) \delta_{i,j} - \sum_{k=1}^n z_{k,i} \xi_{k,j}. \tag{4.19}$$

Since the second summation in (4.19) is equal to $-(\tilde{z}\tilde{C})_{ij} = -(zC)_{ij}$ as shown in (I) of the proof of Theorem 4.3, we obtain that

$$A(\tau) = (\tau + \gamma_1)1_n + zC.$$

(II) Next we show (4.17). Let $\tilde{B}(\tau) := B(\tau)J_n$. Since the summation part of $\tilde{\sigma}_\lambda(X_{i,j}^-) = \tilde{B}(\tau)_{ij}$ equals $(\tilde{z}\tilde{C}\tilde{z})_{ij}$ as in (II) of the proof of Theorem 4.3, we obtain that

$$B(\tau) = -(\tau + s + \gamma_1)z - zCz. \tag{4.20}$$

Now, combining (4.20) with (4.16) and (4.18), we obtain that

$$A(\tau)z - zCz + B(\tau) - zD(\tau) = (\tau + \gamma_1 - s)z.$$

This completes the proof. □

Note the similarity between the matrix Φ given in (1.5) and $\tilde{\sigma}_\lambda(\mathbf{X})$ conjugated by $u(z)^{-1} \in U_\Omega$ given in (4.15).

It follows immediately from Theorem 4.4 and the minor summation formula of Pfaffian (Theorem A.1) that $\text{Pf}(\tilde{\sigma}_\lambda(\mathbf{X}))$ yields a generating function for $\{\gamma_k\}$.

4.2. The case $G = Sp(n, \mathbf{R})$.

Next we prove the case where $G = Sp(n, \mathbf{R})$, or $\mathfrak{g} = \mathfrak{sp}_n$. Take a basis $\{X_{i,j}^\epsilon\}_{\epsilon=0,\pm; i,j \in [n]}$ for \mathfrak{sp}_n as follows:

$$\begin{aligned}
 X_{i,j}^0 &:= E_{i,j} - E_{-j,-i} \quad (1 \leq i, j \leq n), \\
 X_{i,j}^+ &:= E_{i,-j} + E_{j,-i} \quad (1 \leq i \leq j \leq n), \\
 X_{i,j}^- &:= E_{-j,i} + E_{-i,j} \quad (1 \leq i \leq j \leq n),
 \end{aligned}
 \tag{4.21}$$

where $-i$ stands for $2n + 1 - i$ as in Section 4.1.

PROPOSITION 4.5. *The differential operators $d\pi_\lambda(X_{i,j}^\epsilon)$ ($\epsilon = 0, \pm; i, j \in [n]$) are given by*

$$d\pi_\lambda(X_{i,j}^0) = s\delta_{i,j} - \sum_{k=1}^n z_{j,k} \tilde{\partial}_{i,k}, \tag{4.22}$$

$$d\pi_\lambda(X_{i,j}^+) = -\tilde{\partial}_{i,j}, \tag{4.23}$$

$$d\pi_\lambda(X_{i,j}^-) = -2sz_{i,j} + \sum_{1 \leq k,l \leq n} z_{k,i} z_{j,l} \tilde{\partial}_{k,l}. \tag{4.24}$$

PROOF. Let $E_{i,j}^{(n)}$ be as in the proof of Proposition 4.1, and let $\tilde{z} := \sum_{k,l} z_{k,l} E_{k,l}^{(n)}$ with $z_{l,k} = z_{k,l}$. Then $z := \tilde{z} J_n$ belongs to Ω if it is positive definite. Then, we can calculate the differential operators $d\pi_\lambda(X_{i,j}^\epsilon)$ as in the case of \mathfrak{so}_{2n} .

(I) Writing $\begin{bmatrix} a & 0 \\ 0 & d \end{bmatrix} := \exp(-tX_{i,j}^0)$, we see that

$$\begin{aligned}
 \exp(-tX_{i,j}^0).z &= azd^{-1} \\
 &= \sum_{k,l \in [n]} (z_{k,l} - t(\delta_{i,k} z_{j,l} + \delta_{i,l} z_{k,j})) E_{k,l}^{(n)} J_n + O(t^2)
 \end{aligned}$$

and

$$(\det d)^s = e^{s \operatorname{tr}(E_{n+1-j, n+1-i}^{(n)}) + O(t^2)}.$$

Hence

$$\begin{aligned}
 d\pi_\lambda(X_{i,j}^0) &= s\delta_{i,j} - \sum_{i \leq l} z_{j,l} \partial_{i,l} - \sum_{k \leq i} z_{k,j} \partial_{k,i} \\
 &= s\delta_{i,j} - \sum_{k \in [n]} z_{j,k} \tilde{\partial}_{i,k}.
 \end{aligned}$$

(II) Writing $\begin{bmatrix} 1 & b \\ 0 & 1 \end{bmatrix} := \exp(-tX_{i,j}^+)$, we see that

$$\begin{aligned} \exp(-tX_{i,j}^+).z &= z + b \\ &= \left(\tilde{z} - t(E_{i,j}^{(n)} + E_{j,i}^{(n)})\right)J_n \\ &= \sum_{k,l \in [n]} (z_{k,l} - t\delta_{i,k}\delta_{j,l} - t\delta_{j,k}\delta_{i,l})E_{k,l}^{(n)}J_n. \end{aligned}$$

Hence

$$\begin{aligned} d\pi_\lambda(X_{i,j}^+) &= -\sum_{k \leq l} (\delta_{i,k}\delta_{j,l} + \delta_{i,l}\delta_{j,k})\partial_{k,l} \\ &= -\tilde{\partial}_{i,j}. \end{aligned}$$

(III) Writing $\begin{bmatrix} 1 & 0 \\ c & 1 \end{bmatrix} := \exp(-tX_{i,j}^-)$, we see that

$$\begin{aligned} \exp(-tX_{i,j}^-).z &= z(1_n + cz)^{-1} \\ &= z\left(1_n - tJ_n(E_{i,j}^{(n)} + E_{j,i}^{(n)})z\right)^{-1} \\ &= \left(\tilde{z} + t\tilde{z}(E_{i,j}^{(n)} + E_{j,i}^{(n)})\tilde{z}\right)J_n + O(t^2) \\ &= \sum_{k,l} (z_{k,l} + t(z_{k,i}z_{j,l} + z_{k,j}z_{i,l}))E_{k,l}^{(n)}J_n + O(t^2), \end{aligned}$$

and

$$\begin{aligned} \det(1_n + cz)^s &= \left(\det\left(1_n - tJ_n(E_{i,j}^{(n)} + E_{j,i}^{(n)})\tilde{z}J_n\right)\right)^s \\ &= e^{-st\text{tr}((E_{i,j}^{(n)} + E_{j,i}^{(n)})\tilde{z}) + O(t^2)} \\ &= e^{-st(z_{j,i} + z_{i,j}) + O(t^2)} = e^{-2stz_{i,j} + O(t^2)}. \end{aligned}$$

Hence

$$\begin{aligned} d\pi_\lambda(X_{i,j}^-) &= -2sz_{i,j} + \sum_{k \leq l} (z_{k,i}z_{j,l} + z_{k,j}z_{i,l})\partial_{k,l} \\ &= -2sz_{i,j} + \sum_{k,l \in [n]} z_{k,i}z_{j,l}\tilde{\partial}_{k,l}. \end{aligned}$$

This completes the proof. □

Noting that the dual basis of (4.21) is given by

$$(X_{i,j}^0)^\vee = X_{j,i}^0, \quad (X_{i,j}^\pm)^\vee = \begin{cases} X_{i,j}^\mp & (i \neq j), \\ \frac{1}{2}X_{i,j}^\mp & (i = j), \end{cases}$$

let us define $\sigma_\lambda(\mathbf{X})$ by substituting $\tilde{\xi}_{i,j}$ into $\tilde{\partial}_{i,j}$ following the prescription (3.4) as above.

THEOREM 4.6. *Let $u(z) := \exp \sum_{i \leq j} z_{i,j}(X_{i,j}^-)^\vee \in U_\Omega$. Then we have*

$$\text{Ad}(u(z)^{-1})\sigma_\lambda(\mathbf{X}) = s \sum_i X_{i,i}^0 - \sum_{i \leq j} \tilde{\xi}_{i,j} X_{i,j}^- \tag{4.25}$$

$$= \left[\begin{array}{cccc|cccc} s & & & & & & & \\ & s & & & & & & \\ & & \ddots & & & & & \\ & & & s & & & & \\ \hline -\xi_{1,n-1} & -\xi_{2,n-1} & \cdots & -2\xi_{n,n} & -s & & & \\ \vdots & \vdots & \ddots & \vdots & & \ddots & & \\ -\xi_{1,2} & -2\xi_{2,2} & \cdots & -\xi_{2,n-1} & & & -s & \\ -2\xi_{1,1} & -\xi_{1,2} & \cdots & -\xi_{1,n-1} & & & & -s \end{array} \right]. \tag{4.26}$$

PROOF. Again, this is just a simple matrix calculation, and can be shown in the same way as in the case of \mathfrak{so}_{2n} . In fact, if we write $\begin{bmatrix} A & B \\ C & D \end{bmatrix} := \sigma_\lambda(\mathbf{X})$, then the summation $\sum_k z_{i,k} \tilde{\xi}_{j,k}$ in $\sigma_\lambda(X_{j,i}^0) = A_{ij}$ equals $-(zC)_{ij}$, from which it follows that

$$A = s1_n + zC.$$

Similarly, the summation $\sum_{k,l} z_{i,k} z_{l,j} \tilde{\xi}_{k,l}$ in $\sigma_\lambda(X_{i,j}^-) = (BJ_n)_{ij}$ equals $(zCzJ_n)_{ij}$, from which it follows that

$$B = -2sz - zCz.$$

Now exactly the same calculation as in the proof of Theorem 4.3 yields the identity to be shown. □

Now as above, following the prescription given in Section 3, we deform the symbols $\sigma_\lambda(X_{i,i}^0)$ and $\sigma_\lambda(X_{i,j}^-)$ using $\gamma_1 = \sum_{k,l \in [n]} z_{k,l} \tilde{\xi}_{k,l}$ and a new parameter τ . The results, which we denote by $\tilde{\sigma}_\lambda(X_{i,i}^0)$ and $\tilde{\sigma}_\lambda(X_{i,j}^-)$, are given by

$$\tilde{\sigma}_\lambda(X_{i,i}^0) := \tau + \sum_{\substack{k,l \in [n] \\ l \neq i}} z_{k,l} \tilde{\xi}_{k,l}, \tag{4.27}$$

$$\tilde{\sigma}_\lambda(X_{i,j}^-) := -(\tau + s + \gamma_1)z_{i,j} + \sum_{k,l \in [n]} z_{k,i}z_{j,l} \tilde{\xi}_{k,l}, \tag{4.28}$$

respectively; as for the others, we set $\tilde{\sigma}_\lambda(X_{i,j}^\epsilon) := \sigma_\lambda(X_{i,j}^\epsilon)$. Then we define $\tilde{\sigma}_\lambda(\mathbf{X})$ by

$$\tilde{\sigma}_\lambda(\mathbf{X}) := \sum_{\epsilon; i,j} \tilde{\sigma}_\lambda((X_{i,j}^\epsilon)^\vee) \otimes X_{i,j}^\epsilon.$$

THEOREM 4.7. *Let $u(z) \in U_\Omega$ be as in Theorem 4.6. Then we have*

$$\begin{aligned} & \text{Ad}(u(z)^{-1})\tilde{\sigma}_\lambda(\mathbf{X}) \\ &= (\tau + \gamma_1) \sum_i X_{i,i}^0 - \sum_{i \leq j} \tilde{\xi}_{i,j} X_{i,j}^- - (s - (\tau + \gamma_1)) \sum_{i \leq j} z_{i,j} X_{i,j}^+ \end{aligned} \tag{4.29}$$

$$= \left[\begin{array}{cccc|cccc} \tau + \gamma_1 & & & & -\vartheta z_{1,n} & \cdots & -\vartheta z_{1,2} & -\vartheta z_{1,1} \\ & \tau + \gamma_1 & & & -\vartheta z_{2,n} & \cdots & -\vartheta z_{2,2} & -\vartheta z_{1,2} \\ & & \ddots & & \vdots & \ddots & \vdots & \vdots \\ & & & \tau + \gamma_1 & -\vartheta z_{1,n} & \cdots & -\vartheta z_{2,n} & -\vartheta z_{1,n} \\ \hline -\xi_{1,n} & -\xi_{2,n} & \cdots & -2\xi_{n,n} & -\tau - \gamma_1 & & & \\ \vdots & \vdots & \ddots & \vdots & & \ddots & & \\ -\xi_{1,2} & -2\xi_{2,2} & \cdots & -\xi_{2,n} & & & -\tau - \gamma_1 & \\ -2\xi_{1,1} & -\xi_{1,2} & \cdots & -\xi_{1,n} & & & & -\tau - \gamma_1 \end{array} \right]. \tag{4.30}$$

Here, we set $\vartheta := s - (\tau + \gamma_1)$ in (4.30) for brevity.

PROOF. The theorem follows from matrix calculation parallel to that in the proof of Theorem 4.4.

In fact, if we write $\begin{bmatrix} A(\tau) & B(\tau) \\ C & D(\tau) \end{bmatrix} := \tilde{\sigma}_\lambda(\mathbf{X})$, then we see that

$$A(\tau)_{ij} = \left(\tau + \sum_{k,l} z_{k,l} \tilde{\xi}_{k,l} \right) \delta_{i,j} - \sum_{k=1}^n z_{k,i} \tilde{\xi}_{k,j} \tag{4.31}$$

and the second summation in (4.31) equals $-(\tilde{z}\tilde{C})_{ij} = -(zC)_{ij}$, hence we obtain that

$$A(\tau) = (\tau + \gamma_1)1_n + zC.$$

Similarly, we see that the summation in $\tilde{\sigma}_\lambda(X_{i,j}^-) = \tilde{B}(\tau)_{ij}$ equals $(\tilde{z}\tilde{C}\tilde{z})_{ij}$ as shown in the proof of Theorem 4.6. Thus we obtain that

$$B(\tau) = -(\tau + s + \gamma_1)z - zCz. \tag{4.32}$$

Again, exactly the same matrix calculation as in the proof of Theorem 4.4 yields the identity to be shown. □

It follows immediately from Theorem 4.7 and Proposition A.2 that determinant of $\tilde{\sigma}_\lambda(\mathbf{X})$ yields a generating function for $\{\gamma_k\}$.

4.3. The case $G = SU(p, q)$ ($p \geq q$).

Finally, we prove the case where $G = SU(p, q)$, or $\mathfrak{g} = \mathfrak{sl}_{p+q}$, with $p \geq q$. Take a basis $\{H_i, E_{i,j}^\pm, X_{i,j}^\pm\}$ for \mathfrak{sl}_{p+q} as follows:

$$\begin{aligned} H_i &:= E_{i,i} - E_{p+q,p+q} && (1 \leq i \leq p+q-1), \\ E_{i,j}^+ &:= E_{i,j} && (1 \leq i \neq j \leq p), \\ E_{i,j}^- &:= E_{p+i,p+j} && (1 \leq i \neq j \leq q), \\ X_{i,j}^+ &:= E_{i,p+j} && (1 \leq i \leq p, 1 \leq j \leq q), \\ X_{i,j}^- &:= E_{p+j,i} && (1 \leq i \leq p, 1 \leq j \leq q). \end{aligned} \tag{4.33}$$

PROPOSITION 4.8. *The differential operators $d\pi_\lambda(H_i)$, $d\pi_\lambda(E_{i,j}^\pm)$, $d\pi_\lambda(X_{i,j}^\pm)$ are given by*

$$d\pi_\lambda(H_i) = s - \sum_{l=1}^q z_{i,l} \partial_{i,l} - \sum_{k=1}^p z_{k,q} \partial_{k,q} \quad (1 \leq i \leq p), \tag{4.34}$$

$$d\pi_\lambda(H_{p+j}) = \sum_{k=1}^p (z_{k,j} \partial_{k,j} - z_{k,q} \partial_{k,q}) \quad (1 \leq j \leq q-1), \tag{4.35}$$

$$d\pi_\lambda(E_{i,j}^+) = -\sum_{l=1}^q z_{j,l} \partial_{i,l} \quad (1 \leq i \neq j \leq p), \tag{4.36}$$

$$d\pi_\lambda(E_{i,j}^-) = \sum_{k=1}^p z_{k,i} \partial_{k,j} \quad (1 \leq i \neq j \leq q), \tag{4.37}$$

$$d\pi_\lambda(X_{i,j}^+) = -\partial_{i,j} \quad (1 \leq i \leq p, 1 \leq j \leq q), \tag{4.38}$$

$$d\pi_\lambda(X_{i,j}^-) = -sz_{i,j} + \sum_{\substack{1 \leq k \leq p, \\ 1 \leq l \leq q}} z_{k,j} z_{i,l} \partial_{k,l} \quad (1 \leq i \leq p, 1 \leq j \leq q). \tag{4.39}$$

PROOF. Let $z := \sum_{i \in [p], j \in [q]} z_{i,j} E_{i,j}^{(p,q)}$. Then z belongs to Ω if it is positive definite.

(I) Write $\begin{bmatrix} a & 0 \\ 0 & d \end{bmatrix} := \exp(-tH_i)$. For $i = 1, \dots, p$, we see that

$$\begin{aligned} \exp(-tH_i).z &= azd^{-1} \\ &= \left(1_p - tE_{i,i}^{(p)} + O(t^2)\right) z \left(1_q + tE_{q,q}^{(q)} + O(t^2)\right)^{-1} \\ &= \sum_{k \in [p], l \in [q]} (z_{k,l} - t(\delta_{i,k} z_{i,l} + \delta_{l,q} z_{k,q})) E_{k,l}^{(p,q)} + O(t^2) \end{aligned}$$

and

$$(\det d)^s = e^{s \operatorname{tr}(E_{p+q,p+q}^{(q)} + O(t^2))}.$$

Hence

$$d\pi_\lambda(H_i) = s - \sum_{l \in [q]} z_{i,l} \partial_{i,l} - \sum_{k \in [p]} z_{k,q} \partial_{k,q} \quad (i = 1, \dots, p).$$

For $j = 1, \dots, q - 1$, we see that

$$\begin{aligned} \exp(-tH_{p+j}).z &= azd^{-1} \\ &= z \left(1_q - t \left(E_{j,j}^{(q)} - E_{q,q}^{(q)}\right) + O(t^2)\right)^{-1} \\ &= \sum_{k \in [p], l \in [q]} (z_{k,l} + t(\delta_{l,j} z_{k,j} - \delta_{l,q} z_{k,q})) E_{k,l}^{(p,q)} + O(t^2) \end{aligned}$$

and $(\det d)^s = 1$. Hence

$$d\pi_\lambda(H_{p+j}) = \sum_{k \in [p]} (z_{k,j} \partial_{k,j} - z_{k,q} \partial_{k,q}) \quad (j = 1, \dots, q-1).$$

(II) Writing $\begin{bmatrix} a & 0 \\ 0 & 1 \end{bmatrix} := \exp(-tE_{i,j}^+)$, we see that

$$\begin{aligned} \exp(-tE_{i,j}^+).z &= az \\ &= \left(1_p - tE_{i,j}^{(p)}\right)z \\ &= \sum_{k \in [p], l \in [q]} (z_{k,l} - t\delta_{i,k}z_{j,l})E_{k,l}^{(p,q)} + O(t^2). \end{aligned}$$

Hence

$$d\pi_\lambda(E_{i,j}^+) = - \sum_{l \in [q]} z_{j,l} \partial_{i,l}.$$

(III) Writing $\begin{bmatrix} 1 & 0 \\ 0 & d \end{bmatrix} := \exp(-tE_{i,j}^-)$, we see that

$$\begin{aligned} \exp(-tE_{i,j}^-).z &= zd^{-1} \\ &= z \left(1_q - tE_{i,j}^{(q)}\right)^{-1} \\ &= \sum_{k \in [p], l \in [q]} (z_{k,l} + t\delta_{j,l}z_{k,i})E_{k,l}^{(p,q)} + O(t^2) \end{aligned}$$

and $\det d = 1$. Hence

$$d\pi_\lambda(E_{i,j}^-) = \sum_{k \in [p]} z_{k,i} \partial_{k,j}.$$

(IV) Writing $\begin{bmatrix} 1 & b \\ 0 & 1 \end{bmatrix} := \exp(-tX_{i,j}^+)$, we see that

$$\begin{aligned} \exp(-tX_{i,j}^+).z &= z + b \\ &= z - tE_{i,j}^{(p,q)}. \end{aligned}$$

Hence

$$d\pi_\lambda(X_{i,j}^+) = -\partial_{i,j}.$$

(V) Writing $\begin{bmatrix} 1 & 0 \\ c & 1 \end{bmatrix} := \exp(-tX_{i,j}^-)$, we see that

$$\begin{aligned} \exp(-tX_{i,j}^-).z &= z(1_q + cz)^{-1} \\ &= z\left(1_q - tE_{j,i}^{(q,p)}z\right)^{-1} \\ &= z + tzE_{j,i}^{(q,p)}z + O(t^2) \\ &= \sum_{k \in [p], l \in [q]} (z_{k,l} + tz_{k,j}z_{i,l})E_{k,l}^{(p,q)} + O(t^2), \end{aligned}$$

and

$$\begin{aligned} \det(1_q + cz)^s &= \left(\det\left(1_q - tE_{j,i}^{(q,p)}z\right)\right)^s = e^{-st\text{tr}(E_{j,i}^{(q,p)}z) + O(t^2)} \\ &= e^{-stz_{i,j} + O(t^2)}. \end{aligned}$$

Hence

$$d\pi_\lambda(X_{i,j}^-) = -sz_{i,j} + \sum_{k \in [p], l \in [q]} z_{k,j}z_{i,l}\partial_{k,l}.$$

This completes the proof. □

Noting that the dual basis of (4.33) is given by

$$H_i^\vee = H_i - \frac{1}{p+q} \sum_{k=1}^{p+q-1} H_k, \quad (E_{i,j}^\pm)^\vee = E_{j,i}^\pm, \quad (X_{i,j}^\pm)^\vee = X_{i,j}^\mp,$$

let us define $\sigma_\lambda(\mathbf{X})$ following the prescription (3.4) as above.

THEOREM 4.9. *Let $u(z) := \exp \sum_{i \in [p], j \in [q]} z_{i,j}(X_{i,j}^-)^\vee \in U_\Omega$. Then we have*

$$\begin{aligned} &\text{Ad}(u(z)^{-1})\sigma_\lambda(\mathbf{X}) \\ &= \frac{q}{p+q}s \sum_{i=1}^p H_i - \frac{p}{p+q}s \sum_{j=1}^{q-1} H_{p+j} - \sum_{i \in [p], j \in [q]} \xi_{i,j} X_{i,j}^- \end{aligned} \tag{4.40}$$

$$= \left[\begin{array}{ccc|ccc} \frac{q}{p+q}s & & & & & \\ & \frac{q}{p+q}s & & & & \\ & & \ddots & & & \\ & & & \frac{q}{p+q}s & & \\ \hline -\xi_{1,1} & -\xi_{2,1} & \cdots & -\xi_{p,1} & -\frac{p}{p+q}s & \\ -\xi_{1,2} & -\xi_{2,2} & \cdots & -\xi_{p,2} & & -\frac{p}{p+q}s \\ \vdots & \vdots & & \vdots & & \ddots \\ -\xi_{1,q} & -\xi_{2,q} & \cdots & -\xi_{p,q} & & -\frac{p}{p+q}s \end{array} \right]. \tag{4.41}$$

PROOF. It follows from (4.34) and (4.35) that

$$\frac{1}{p+q} \sum_{k=1}^{p+q-1} \sigma_\lambda(H_k) = \frac{p}{p+q}s - \sum_{k \in [p]} z_{k,q} \xi_{k,q}.$$

Thus we obtain that

$$\begin{aligned} \sigma_\lambda(H_i^\vee) &= \frac{q}{p+q}s - \sum_{l \in [q]} z_{i,l} \xi_{i,l} & (i = 1, \dots, p), \\ \sigma_\lambda(H_{p+j}^\vee) &= -\frac{p}{p+q}s + \sum_{k \in [p]} z_{k,j} \xi_{k,j} & (j = 1, \dots, q-1). \end{aligned} \tag{4.42}$$

Now, if we write $\begin{bmatrix} A & B \\ C & D \end{bmatrix} := \sigma_\lambda(\mathbf{X})$, then

$$A_{ij} = \frac{q}{p+q}s \delta_{i,j} - \sum_{l \in [q]} z_{i,l} \xi_{j,l} \tag{4.43a}$$

$$B_{ij} = -sz_{i,j} + \sum_{k \in [p], j \in [q]} z_{k,j} z_{i,l} \xi_{k,l} \tag{4.43b}$$

$$C_{ij} = -\xi_{j,i} \tag{4.43c}$$

$$D_{ij} = -\frac{p}{p+q}s \delta_{i,j} + \sum_{k \in [p]} z_{k,j} \xi_{k,i} \tag{4.43d}$$

by (4.36), (4.37), (4.38), (4.39) and (4.42). Now exactly the same matrix calculation as in the proof of Theorem 4.6 yields the formula to be shown. \square

As above, following the prescription given in Section 3, we deform the symbols

$\sigma_\lambda(H_i^\vee)$ and $\sigma_\lambda(X_{i,j}^-)$ using $\gamma_1 = \sum_{k,l \in [n]} z_{k,l} \tilde{\xi}_{k,l}$ and a new parameter τ . The results, which we denote by $\tilde{\sigma}_\lambda(H_i^\vee)$ and $\tilde{\sigma}_\lambda(X_{i,j}^-)$, are given by

$$\tilde{\sigma}_\lambda(H_i^\vee) := \left(\tau - \frac{p}{p+q}s \right) + \sum_{\substack{k \in [p], l \in [q] \\ k \neq i}} z_{k,l} \xi_{k,l} \quad (i = 1, \dots, p), \tag{4.44}$$

$$\tilde{\sigma}_\lambda(H_{p+j}^\vee) := \left(-\tau + \frac{q}{p+q}s \right) - \sum_{\substack{k \in [p], l \in [q] \\ l \neq j}} z_{k,l} \xi_{k,l} \quad (j = 1, \dots, q-1), \tag{4.45}$$

$$\tilde{\sigma}_\lambda(X_{i,j}^-) := -(\tau + \gamma_1)z_{i,j} + \sum_{k \in [p], l \in [q]} z_{k,j} z_{i,l} \xi_{k,l} \quad (i = 1, \dots, p; j = 1, \dots, q) \tag{4.46}$$

respectively; as for the others, we set $\tilde{\sigma}_\lambda(\cdot) := \sigma_\lambda(\cdot)$. Then we define $\tilde{\sigma}_\lambda(\mathbf{X})$ by

$$\tilde{\sigma}_\lambda(\mathbf{X}) = \sum_i \tilde{\sigma}_\lambda(H_i^\vee) \otimes H_i + \sum_{\epsilon; i,j} (\tilde{\sigma}_\lambda((E_{i,j}^\epsilon)^\vee) \otimes E_{i,j}^\epsilon + \tilde{\sigma}_\lambda((X_{i,j}^\epsilon)^\vee) \otimes X_{i,j}^\epsilon).$$

THEOREM 4.10. *Let $u(z) \in U_\Omega$ be as in Theorem 4.9. Then we have*

$$\begin{aligned} & \text{Ad}(u(z)^{-1})\tilde{\sigma}_\lambda(\mathbf{X}) \\ &= \left(\tau + \gamma_1 - \frac{p}{p+q}s \right) \sum_{i=1}^p H_i + \left(-\tau - \gamma_1 + \frac{q}{p+q}s \right) \sum_{j=1}^{q-1} H_{p+j} \\ & \quad - \sum_{i \in [p], j \in [q]} \xi_{i,j} X_{i,j}^- - (s - (\tau + \gamma_1)) \sum_{i \in [p], j \in [q]} z_{i,j} X_{i,j}^+ \end{aligned} \tag{4.47}$$

$$= \frac{\begin{bmatrix} \tau_+ & & & & -\vartheta z_{1,1} & -\vartheta z_{1,2} & \cdots & -\vartheta z_{1,q} \\ & \tau_+ & & & -\vartheta z_{2,1} & -\vartheta z_{2,2} & \cdots & -\vartheta z_{2,q} \\ & & \ddots & & \vdots & \vdots & & \vdots \\ & & & \tau_+ & -\vartheta z_{p,1} & -\vartheta z_{p,2} & \cdots & -\vartheta z_{p,q} \end{bmatrix}}{\begin{bmatrix} -\xi_{1,1} & -\xi_{2,1} & \cdots & -\xi_{p,1} & \tau_- & & & \\ -\xi_{1,2} & -\xi_{2,2} & \cdots & -\xi_{p,2} & & \tau_- & & \\ \vdots & \vdots & & \vdots & & & \ddots & \\ -\xi_{1,q} & -\xi_{2,q} & \cdots & -\xi_{p,q} & & & & \tau_- \end{bmatrix}}. \tag{4.48}$$

Here, we set $\tau_+ := \tau + \gamma_1 - (p/(p+q))s$, $\tau_- := -\tau - \gamma_1 + (q/(p+q))s$ and

$\vartheta := s - (\tau + \gamma_1)$ in (4.48) for brevity.

PROOF. If we write $\begin{bmatrix} A(\tau) & B(\tau) \\ C & D(\tau) \end{bmatrix} := \tilde{\sigma}_\lambda(\mathbf{X})$, then we can show that

$$A(\tau) = \left(\tau + \gamma_1 - \frac{p}{p+q}s \right) 1_p + zC, \quad (4.49)$$

$$B(\tau) = -(\tau + \gamma_1)z - zCz, \quad (4.50)$$

$$D(\tau) = \left(-\tau - \gamma_1 + \frac{q}{p+q}s \right) 1_q - Cz \quad (4.51)$$

exactly in the same way as in the proofs of Theorems 4.4 and 4.7. Thus we obtain the theorem. \square

It follows immediately from Theorem 4.10 and Proposition A.2 that determinant of $\tilde{\sigma}_\lambda(\mathbf{X})$ yields a generating function for $\{\gamma_k\}$.

REMARK 4.11. There is one more classical irreducible Hermitian symmetric pair of noncompact type, namely, $(SO_0(p, 2), SO(p) \times SO(2))$. Let us denote by \mathfrak{q} the maximal parabolic subalgebra of \mathfrak{so}_{p+2} whose Levi part is $\mathfrak{k} \simeq \mathfrak{so}_p \oplus \mathbf{C}$. If we define the character $\lambda : \mathfrak{q} \rightarrow \mathbf{C}$ by

$$\lambda = \frac{2s}{p} \rho_n,$$

with $s \in \mathbf{Z}$ and ρ_n the half sum of the noncompact positive roots as above, then all formulae corresponding to those stated in the theorems in Section 4 also hold true.

5. Twisted moment map.

In general, let G be a Lie group, \mathfrak{g} its Lie algebra, and \mathfrak{g}^* the dual of \mathfrak{g} . If M is a G -manifold, then the cotangent bundle T^*M is a symplectic G -manifold, and the moment map $\mu : T^*M \rightarrow \mathfrak{g}^*$ is given by

$$\langle \mu(x, \xi), X \rangle = \xi(X_M(x)) \quad (x \in M, \xi \in T_x^*M) \quad (5.1)$$

for $X \in \mathfrak{g}$, where $\langle \cdot, \cdot \rangle$ denotes the canonical pairing between \mathfrak{g}^* and \mathfrak{g} , and $X_M(x) \in T_x M$ the tangent vector at $x \in M$ given by

$$X_M(x)f = \left. \frac{d}{dt} \right|_{t=0} f(\exp(-tX).x) \tag{5.2}$$

for functions f defined around $x \in M$ (see e.g. [10]).

Returning to our case, it follows from (5.1) and (5.2) that the principal part of $\sigma_\lambda(\mathbf{X})$ (i.e., the linear part in ξ 's) is identical to the moment map $\mu : T^*(G_C/Q)|_{G/K} \rightarrow \mathfrak{g}^*$ composed by the isomorphism $\mathfrak{g}^* \simeq \mathfrak{g}$ via the bilinear form B given in (3.2), which we also denote by μ . Furthermore, the total symbol $\sigma_\lambda(\mathbf{X})$ can be regarded as a *variant* of the twisted moment map $\mu_\lambda : T^*(G_C/Q)|_{G/K} \rightarrow \mathfrak{g}^* \simeq \mathfrak{g}$ due to Rossmann, though we follow the notation by Schmid and Vilonen (see Section 7 of [11]). In fact, the difference $\mu_\lambda - \mu$, which they denote by λ_x with $x \in G_C/Q$, can be expressed as $\mu_\lambda - \mu = \text{Ad}(g)\lambda^\vee$, or

$$\mu_\lambda(x, \xi) = \text{Ad}(g)\lambda^\vee + \mu(x, \xi), \tag{5.3}$$

where $\lambda^\vee \in \mathfrak{g}$ corresponds to $\lambda \in \mathfrak{g}^*$ under the isomorphism $\mathfrak{g}^* \simeq \mathfrak{g}$ via the bilinear form B , and g is an element of a compact real form U_R of G_C such that $x = g\dot{e}$ with \dot{e} the origin of G_C/Q . Note that if x is in the open subset $G/K = GQ/Q = U_\Omega Q/Q \subset G_C/Q$, one can choose a unique u_x from U_Ω (which we denoted by $u(z)$ in Section 4) so that $x = u_x\dot{e}$ instead of g from U_R . Then, writing $\mu'_\lambda(x, \xi) := \sigma_\lambda(\mathbf{X})$ to make its dependence on x and ξ transparent, one can immediately verify that

$$\mu'_\lambda(x, \xi) = \text{Ad}(u_x)\lambda^\vee + \mu(x, \xi). \tag{5.4}$$

Theorems 4.3, 4.6, and 4.9 state that an analogue of U_R -equivariance of the twisted moment map holds:

$$\text{Ad}(u_x^{-1})\mu'_\lambda(x, \xi) = \mu'_\lambda(u_x^{-1}.(x, \xi)), \tag{5.5}$$

though U_Ω is not a subgroup. Since $u_x^{-1}.(x, \xi) = (\dot{e}, (u_x)^*\xi)$ and $(u_x)^*\xi \in T_{\dot{e}}^*(G_C/Q)$, the relation (5.5) says that all the symbols of the representation operators $d\pi_\lambda(X)$, with $X \in \mathfrak{g}$, are determined by those at the origin.

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A. Minor summation formulae.

In this appendix, we collect a couple of formulae concerning Pfaffian and determinant needed to show the identities in (3.7).

Recall from [7] that for an alternating $2n \times 2n$ matrix $A = (a_{i,j})$, $a_{j,i} = -a_{i,j}$, with entries in an associative algebra \mathcal{A} , the Pfaffian $\text{Pf}(A)$ is defined by

$$\text{Pf}(A) = \frac{1}{2^n n!} \sum_{\sigma \in \mathfrak{S}_{2n}} \text{sgn}(\sigma) a_{\sigma(1),\sigma(2)} a_{\sigma(3),\sigma(4)} \cdots a_{\sigma(2n-1),\sigma(2n)}. \tag{A.1}$$

If \mathcal{A} happens to be commutative, it reduces to

$$\text{Pf}(A) = \sum_{\sigma} \text{sgn}(\sigma) a_{\sigma(1),\sigma(2)} a_{\sigma(3),\sigma(4)} \cdots a_{\sigma(2n-1),\sigma(2n)}, \tag{A.2}$$

where the sum is taken over those σ satisfying

$$\sigma(2i - 1) < \sigma(2i) \text{ for } i = 1, 2, \dots, n \text{ and } \sigma(1) < \sigma(3) < \cdots < \sigma(2n - 1).$$

Let X be a $2n \times 2n$ complex matrix alternating along the anti-diagonal. Since XJ_{2n} is an alternating matrix, one can define Pfaffian of XJ_{2n} , which we denote by $\text{Pf}(X)$ as mentioned above. If we write X as $X = \begin{bmatrix} a & -J_n^t b J_n \\ c & -J_n^t a J_n \end{bmatrix}$ with submatrices a, b, c all being of size $n \times n$, then b and c are also alternating along the anti-diagonal. Thus we parametrize the submatrices a, b, c as follows:

$$a = \begin{bmatrix} a_{1,1} & \cdots & a_{1,n} \\ \vdots & & \vdots \\ a_{n,1} & \cdots & a_{n,n} \end{bmatrix}, \quad b = \begin{bmatrix} b_{1,n} & \cdots & b_{1,2} & 0 \\ \vdots & \ddots & 0 & -b_{1,2} \\ b_{n-1,n} & 0 & \ddots & \vdots \\ 0 & -b_{n-1,n} & \cdots & -b_{1,n} \end{bmatrix}, \tag{A.3}$$

$$c = \begin{bmatrix} c_{1,n} & \cdots & c_{n-1,n} & 0 \\ \vdots & \ddots & 0 & -c_{n-1,n} \\ c_{1,2} & 0 & \ddots & \vdots \\ 0 & -c_{1,2} & \cdots & -c_{1,n} \end{bmatrix}.$$

THEOREM A.1 ([5]). *Let $X = \begin{bmatrix} a & -J_n^t b J_n \\ c & -J_n^t a J_n \end{bmatrix}$ be a $2n \times 2n$ complex matrix alternating along the anti-diagonal with submatrices a, b, c parametrized as in (A.3). Then we can expand Pfaffian $\text{Pf}(X)$ in the following way.*

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