

**OSCILLATION CRITERIA FOR
 SYSTEMS OF PARABOLIC EQUATIONS
 WITH FUNCTIONAL ARGUMENTS**

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ABSTRACT. Sufficient conditions are established for the oscillations of systems of parabolic equations with functional arguments of the form

$$\begin{aligned} \frac{\partial}{\partial t} u_i(x, t) &= a_i(t) \Delta u_i(x, t) + \sum_{k=1}^m \sum_{j=1}^s a_{ikj}(t) \Delta u_k(x, \rho_j(t)) \\ &\quad - \sum_{k=1}^m \sum_{h=1}^l q_{ikh}(x, t) u_k(x, \sigma_h(t)), \\ (x, t) &\in \Omega \times [0, \infty) \equiv G, \quad i = 1, 2, \dots, m, \end{aligned}$$

under boundary conditions of Dirichlet and Neumann type, where Ω is a bounded domain in R^n with a piecewise smooth boundary $\partial\Omega$, and Δ is the Laplacian in Euclidean n -space R^n . These results are illustrated by some examples.

1. Introduction. Recently, the oscillation theory for systems of partial functional differential equations has been studied extensively [3–7]. In this paper, we study the oscillation of systems of parabolic differential equations with functional arguments of the form

$$\begin{aligned} \frac{\partial}{\partial t} u_i(x, t) &= a_i(t) \Delta u_i(x, t) + \sum_{k=1}^m \sum_{j=1}^s a_{ikj}(t) \Delta u_k(x, \rho_j(t)) \\ (1) \quad &\quad - \sum_{k=1}^m \sum_{h=1}^l q_{ikh}(x, t) u_k(x, \sigma_h(t)), \\ &\quad (x, t) \in \Omega \times [0, \infty) \equiv G, \quad i = 1, 2, \dots, m, \end{aligned}$$

This work is supported by the Natural Science Foundation of Shandong Province, China.

1991 AMS *Mathematics Subject Classification.* 35B05, 35R10.

Key words and phrases. Oscillation, system, parabolic equation, functional argument.

Received by the editors on July 21, 2000.

where Ω is a bounded domain in R^n with a piecewise smooth boundary $\partial\Omega$, and $\Delta u_i(x, t) = \sum_{r=1}^n (\partial^2 u_i(x, t) / \partial x_r^2)$, $i = 1, 2, \dots, m$.

Suppose that the following conditions hold:

(C1) $a_i \in C([0, \infty); [0, \infty))$, $a_{ikj} \in C([0, \infty); R)$, $a_{iij}(t) > 0$ and

$$A_j(t) = \min_{1 \leq i \leq m} \left\{ a_{iij}(t) - \sum_{k=1, k \neq i}^m |a_{kij}(t)| \right\} \geq 0,$$

$$i, k \in I_m = \{1, 2, \dots, m\}, \quad j \in I_s = \{1, 2, \dots, s\};$$

(C2) $q_{ikh} \in C(\bar{G}; R)$, and $q_{iij}(x, t) > 0$; $q_{iij}(t) = \min_{x \in \bar{\Omega}} q_{iij}(x, t)$,

$$\bar{q}_{ikh}(t) = \max_{x \in \bar{\Omega}} |q_{ikh}(x, t)|, \quad \text{and}$$

$$Q_h(t) = \min_{1 \leq i \leq m} \left\{ q_{iij}(t) - \sum_{k=1, k \neq i}^m \bar{q}_{kih}(t) \right\} \geq 0,$$

$$i, k \in I_m, \quad h \in I_l = \{1, 2, \dots, l\};$$

(C3) $\rho_j, \sigma_h \in C([0, \infty); [0, \infty))$, $\lim_{t \rightarrow \infty} \rho_j(t) = \lim_{t \rightarrow \infty} \sigma_h(t) = \infty$, $j \in I_s$, $h \in I_l$.

Consider the following boundary conditions:

$$(2) \quad \frac{\partial u_i(x, t)}{\partial N} + g_i(x, t)u_i(x, t) = 0, \quad (x, t) \in \partial\Omega \times [0, \infty), \quad i \in I_m,$$

where N is the unit exterior normal vector to $\partial\Omega$ and $g_i(x, t)$ is a nonnegative continuous function on $\partial\Omega \times [0, \infty)$, $i \in I_m$, and

$$(3) \quad u_i(x, t) = 0, \quad (x, t) \in \partial\Omega \times [0, \infty), \quad i \in I_m.$$

Definition 1.1. The vector function $u(x, t) = \{u_1(x, t), u_2(x, t), \dots, u_m(x, t)\}^T$ is said to be a solution of the problem (1), (2) (or (1), (3)) if it satisfies (1) in $G = \Omega \times [0, \infty)$ and boundary condition (2) (or (3)).

Definition 1.2. The vector solution $u(x, t) = \{u_1(x, t), u_2(x, t), \dots, u_m(x, t)\}^T$ of the problem (1), (2) (or (1), (3)) is said to be oscillatory in the domain $G = \Omega \times [0, \infty)$ if at least one of its nontrivial components

is oscillatory in G . Otherwise, the vector solution $u(x, t)$ is said to be nonoscillatory.

2. Oscillation of the problem (1), (2).

Theorem 2.1. *If the differential inequality*

$$(4) \quad V'(t) + \sum_{h=1}^l Q_h(t)V(\sigma_h(t)) \leq 0, \quad t \geq 0,$$

has no eventually positive solution, then every solution $u(x, t)$ of the problem (1),(2) is oscillatory in G .

Proof. Suppose to the contrary that there is a nonoscillatory solution $u(x, t) = \{u_1(x, t), u_2(x, t), \dots, u_m(x, t)\}^T$ of the problem (1), (2). We assume that $|u_i(x, t)| > 0$ for $t \geq t_0 \geq 0, i \in I_m$. Let $\delta_i = \text{sgn } u_i(x, t), Z_i(x, t) = \delta_i u_i(x, t)$. Then $Z_i(x, t) > 0, (x, t) \in \Omega \times [t_0, \infty), i \in I_m$. From (C3) there exists a number $t_1 \geq t_0$ such that $Z_i(x, t) > 0, Z_k(x, \rho_j(t)) > 0$ and $Z_i(x, \sigma_h(t)) > 0$ in $\Omega \times [t_1, \infty), i, k \in I_m, j \in I_s, h \in I_l$.

Integrating (1) with respect to x over the domain Ω , we have

$$(5) \quad \begin{aligned} \frac{d}{dt} \int_{\Omega} u_i(x, t) dx &= a_i(t) \int_{\Omega} \Delta u_i(x, t) dx \\ &+ \sum_{k=1}^m \sum_{j=1}^s a_{ikj}(t) \int_{\Omega} \Delta u_k(x, \rho_j(t)) dx \\ &- \sum_{k=1}^m \sum_{h=1}^l \int_{\Omega} q_{ikh}(x, t) u_k(x, \sigma_h(t)) dx, \end{aligned}$$

$t \geq t_1, \quad i \in I_m.$

Hence, we have

$$\begin{aligned}
 \frac{d}{dt} \int_{\Omega} Z_i(x, t) dx &= a_i(t) \int_{\Omega} \Delta Z_i(x, t) dx \\
 &+ \sum_{k=1}^m \sum_{j=1}^s a_{ikj}(t) \frac{\delta_i}{\delta_k} \int_{\Omega} \Delta Z_k(x, \rho_j(t)) dx \\
 &- \frac{\delta_i}{\delta_k} \sum_{k=1}^m \sum_{h=1}^l \int_{\Omega} q_{ikh}(x, t) Z_k(x, \sigma_h(t)) dx, \\
 t &\geq t_1, \quad i \in I_m.
 \end{aligned}
 \tag{6}$$

Green's formula and boundary condition (2) yield

$$\begin{aligned}
 \int_{\Omega} \Delta Z_i(x, t) dx &= \int_{\partial\Omega} \frac{\partial Z_i(x, t)}{\partial N} dS \\
 &= - \int_{\partial\Omega} g_i(x, t) Z_i(x, t) dS \leq 0,
 \end{aligned}
 \tag{7}$$

and

$$\begin{aligned}
 \int_{\Omega} \Delta Z_k(x, \rho_j(t)) dx &= \int_{\partial\Omega} \frac{\partial Z_k(x, \rho_j(t))}{\partial N} dS \\
 &= - \int_{\partial\Omega} g_k(x, \rho_j(t)) Z_k(x, \rho_j(t)) dS, \\
 t &\geq t_1, \quad i, k \in I_m, \quad j \in I_s,
 \end{aligned}
 \tag{8}$$

where dS is the surface element on $\partial\Omega$.

Now combining (6)–(8), we obtain

$$\begin{aligned}
 \frac{d}{dt} \int_{\Omega} Z_i(x, t) dx &+ \sum_{k=1}^m \sum_{j=1}^s a_{ikj}(t) \frac{\delta_i}{\delta_k} \int_{\partial\Omega} g_k(x, \rho_j(t)) Z_k(x, \rho_j(t)) dS \\
 &+ \sum_{h=1}^l q_{iih}(t) \int_{\Omega} Z_i(x, \sigma_h(t)) dx \\
 &- \sum_{h=1}^l \sum_{k=1, k \neq i}^m \bar{q}_{ikh}(t) \int_{\Omega} Z_k(x, \sigma_h(t)) dx \leq 0, \\
 t &\geq t_1, \quad i \in I_m.
 \end{aligned}
 \tag{9}$$

Therefore,

$$\begin{aligned}
 & \frac{d}{dt} \int_{\Omega} Z_i(x, t) dx + \sum_{j=1}^s a_{ij}(t) \int_{\partial\Omega} g_i(x, \rho_j(t)) Z_i(x, \rho_j(t)) dS \\
 & - \sum_{\substack{k=1 \\ k \neq i}}^m \sum_{j=1}^s |a_{ikj}(t)| \int_{\partial\Omega} g_k(x, \rho_j(t)) Z_k(x, \rho_j(t)) dS \\
 (10) \quad & + \sum_{h=1}^l q_{iih}(t) \int_{\Omega} Z_i(x, \sigma_h(t)) dx \\
 & - \sum_{h=1}^l \sum_{k=1, k \neq i}^m \bar{q}_{ikh}(t) \int_{\Omega} Z_k(x, \sigma_h(t)) dx \leq 0, \\
 & t \geq t_1, \quad i \in I_m.
 \end{aligned}$$

Set

$$V_i(t) = \int_{\Omega} Z_i(x, t) dx, U_i(t) = \int_{\partial\Omega} g_i(x, t) Z_i(x, t) dS, \quad t \geq t_1, \quad i \in I_m.$$

From (10) we have

$$\begin{aligned}
 & V_i'(t) + \sum_{j=1}^s [a_{ij}(t) U_i(\rho_j(t)) - \sum_{\substack{k=1 \\ k \neq i}}^m |a_{ikj}(t)| U_k(\rho_j(t))] \\
 (11) \quad & + \sum_{h=1}^l \left[q_{iih}(t) V_i(\sigma_h(t)) - \sum_{k=1, k \neq i}^m \bar{q}_{ikh}(t) V_k(\sigma_h(t)) \right] \leq 0, \\
 & t \geq t_1, \quad i \in I_m.
 \end{aligned}$$

Let

$$V(t) = \sum_{i=1}^m V_i(t), U(t) = \sum_{i=1}^m U_i(t), \quad t \geq t_1.$$

From (11) we have

$$(12) \quad V'(t) + \sum_{j=1}^s \left\{ \sum_{i=1}^m [a_{iij}(t)U_i(\rho_j(t)) - \sum_{\substack{k=1 \\ k \neq i}}^m |a_{ikj}(t)|U_k(\rho_j(t))] \right\} \\ + \sum_{h=1}^l \left\{ \sum_{i=1}^m [q_{iih}(t)V_i(\sigma_h(t)) - \sum_{\substack{k=1 \\ k \neq i}}^m \bar{q}_{ikh}(t)V_k(\sigma_h(t))] \right\} \leq 0, \quad t \geq t_1.$$

Noting that

$$\sum_{i=1}^m \left[q_{iih}(t)V_i(\sigma_h(t)) - \sum_{\substack{k=1 \\ k \neq i}}^m \bar{q}_{ikh}(t)V_k(\sigma_h(t)) \right] \\ = \left[q_{11h}(t)V_1(\sigma_h(t)) - \sum_{\substack{k=1 \\ k \neq 1}}^m \bar{q}_{1kh}(t)V_k(\sigma_h(t)) \right] \\ + \left[q_{22h}(t)V_2(\sigma_h(t)) - \sum_{\substack{k=1 \\ k \neq 2}}^m \bar{q}_{2kh}(t)V_k(\sigma_h(t)) \right] \\ + \dots \\ + \left[q_{mmh}(t)V_m(\sigma_h(t)) - \sum_{\substack{k=1 \\ k \neq m}}^m \bar{q}_{mkh}(t)V_k(\sigma_h(t)) \right] \\ = \left[q_{11h}(t) - \sum_{\substack{k=1 \\ k \neq 1}}^m \bar{q}_{k1h}(t) \right] V_1(\sigma_h(t)) + \left[q_{22h}(t) - \sum_{\substack{k=1 \\ k \neq 2}}^m \bar{q}_{k2h}(t) \right] V_2(\sigma_h(t)) \\ + \dots \\ + \left[q_{mmh}(t) - \sum_{\substack{k=1 \\ k \neq m}}^m \bar{q}_{kmh}(t) \right] V_m(\sigma_h(t)) \\ \geq \min_{1 \leq i \leq m} \left\{ q_{iih}(t) - \sum_{\substack{k=1 \\ k \neq i}}^m \bar{q}_{kih}(t) \right\} \sum_{i=1}^m V_i(\sigma_h(t)) \\ = Q_h(t)V(\sigma_h(t)), \quad t \geq t_1, \quad h \in I_l.$$

Similarly we have

$$\begin{aligned} & \sum_{i=1}^m \left[a_{ii}(t)U_i(\rho_j(t)) - \sum_{\substack{k=1 \\ k \neq i}}^m |a_{ik}(t)|U_k(\rho_j(t)) \right] \\ & \geq \min_{1 \leq i \leq m} \left\{ a_{ii}(t) - \sum_{k=1}^m |a_{ik}(t)| \right\} \sum_{i=1}^m U_i(\rho_j(t)) \\ & = A_j(t)U(\rho_j(t)), \quad t \geq t_1, \quad j \in I_s. \end{aligned}$$

Then from (12), we get

$$(13) \quad V'(t) + \sum_{j=1}^s A_j(t)U(\rho_j(t)) + \sum_{h=1}^l Q_h(t)V(\sigma_h(t)) \leq 0, \quad t \geq t_1.$$

It is easy to see that

$$U(\rho_j(t)) = \sum_{i=1}^m U_i(\rho_j(t)) \geq 0, \quad t \geq t_1, \quad j \in I_s.$$

Therefore,

$$V'(t) + \sum_{h=1}^l Q_h(t)V(\sigma_h(t)) \leq 0, \quad t \geq t_1,$$

which contradicts the assumption that (4) has no eventually positive solutions. This completes the proof. \square

We now give two lemmas which are useful for the proof of the following results.

Lemma 2.1 [7]. *Consider the differential inequality*

$$(14) \quad x'(t) + p(t)x(g(t)) \leq 0.$$

Assume that $p \in C(R; [0, \infty))$, $g \in C(R; R)$, $g(t) \leq t$ and $g(t)$ is nondecreasing, $\lim_{t \rightarrow \infty} g(t) = \infty$ and suppose that

$$(15) \quad \liminf_{t \rightarrow \infty} \int_{g(t)}^t p(s) ds > \frac{1}{e}.$$

Then the inequality (14) has no eventually positive solutions.

Lemma 2.2 [4]. Consider the differential inequality (14). Assume that $p, g \in C([0, \infty); [0, \infty))$, $g(t) \leq t$, $t \geq 0$ and $g(t)$ is nondecreasing, $\lim_{t \rightarrow \infty} g(t) = \infty$, and suppose that when $L < 1$ and $0 < K \leq 1/e$ the following conditions hold

$$(16) \quad L > \frac{\ln \mu_1 + 1}{\mu_1} - \frac{1 - K - \sqrt{1 - 2K - K^2}}{2},$$

where

$$K = \liminf_{t \rightarrow \infty} \int_{g(t)}^t p(s) ds, \quad L = \limsup_{t \rightarrow \infty} \int_{g(t)}^t p(s) ds,$$

and μ_1 is the smaller root of the equation

$$\mu = e^{K\mu}.$$

Then the inequality (14) has no eventually positive solutions.

Theorem 2.2. If there exists $h_0 \in I_l$ such that $\sigma_{h_0}(t) \leq t$, $\sigma_{h_0}(t)$ is nondecreasing in $[0, \infty)$ and

$$(17) \quad \liminf_{t \rightarrow \infty} \int_{\sigma_{h_0}(t)}^t Q_{h_0}(s) ds > \frac{1}{e},$$

then every solution $u(x, t)$ of the problem (1), (2) is oscillatory in G .

Proof. We prove that the inequality (4) has no eventually positive solution if the conditions of Theorem 2.2 hold. Suppose $V(t)$ is an eventually positive solution of the inequality (4). Then there exists a number $t_1 \geq t_0$ such that $V(\sigma_h(t)) > 0$, $t \geq t_1$, $h \in I_l$. Therefore, we have

$$(18) \quad V'(t) + Q_{h_0}(t)V(\sigma_{h_0}(t)) \leq 0, \quad t \geq t_1.$$

By Lemma 2.1 we obtain that the inequality (18) has no eventually positive solutions, which contradicts the fact that $V(t) > 0$ is a solution of the inequality (18).

By using Lemma 2.2, the proof of the following theorem is similar to that of Theorem 2.2 and we omit it.

Theorem 2.3. *If there exists $h_0 \in I_l$ such that $\sigma_{h_0}(t) \leq t$, $\sigma_{h_0}(t)$ is nondecreasing in $[0, \infty)$ and suppose that when $\bar{L} < 1$ and $0 < \bar{K} \leq 1/e$ the following conditions hold*

$$(19) \quad \bar{L} > \frac{\ln \lambda_1 + 1}{\lambda_1} - \frac{1 - \bar{K} - \sqrt{1 - 2\bar{K} - \bar{K}^2}}{2},$$

where

$$\bar{K} = \liminf_{t \rightarrow \infty} \int_{\sigma_{h_0}(t)}^t Q_{h_0}(s) ds, \quad \bar{L} = \limsup_{t \rightarrow \infty} \int_{\sigma_{h_0}(t)}^t Q_{h_0}(s) ds,$$

and λ_1 is the smaller root of the equation

$$\lambda = e^{\bar{K}\lambda}.$$

Then every solution $u(x, t)$ of the problem (1), (2) is oscillatory in G .

Theorem 2.4. *If there exists $h_0 \in I_l$ such that $\sigma_{h_0}(t) \leq t$, $\sigma_{h_0}(t)$ is nondecreasing in $[0, \infty)$ and*

$$(20) \quad \limsup_{t \rightarrow \infty} \int_{\sigma_{h_0}(t)}^t Q_{h_0}(s) ds > 1,$$

then every solution $u(x, t)$ of the problem (1), (2) is oscillatory in G .

Proof. As in the proof of Theorem 2.2 we obtain (18). Integrating the inequality (18) from $\sigma_{h_0}(t)$ to t we have

$$(21) \quad V(t) - V(\sigma_{h_0}(t)) + \int_{\sigma_{h_0}(t)}^t Q_{h_0}(s)V(\sigma_{h_0}(s)) ds \leq 0, \quad t \geq t_1.$$

Noting that $V'(t) \leq 0$, $\sigma_{h_0}(t) \leq t$, $\sigma_{h_0}(t)$ is nondecreasing in $[t_1, \infty)$, from (21) we have

$$(22) \quad V(t) - V(\sigma_{h_0}(t)) + V(\sigma_{h_0}(t)) \int_{\sigma_{h_0}(t)}^t Q_{h_0}(s) ds \leq 0, \quad t \geq t_1.$$

Therefore,

$$\int_{\sigma_{h_0}(t)}^t Q_{h_0}(s) ds \leq 1 - \frac{V(t)}{V(\sigma_{h_0}(t))} < 1.$$

And, hence,

$$\limsup_{t \rightarrow \infty} \int_{\sigma_{h_0}(t)}^t Q_{h_0}(s) ds \leq 1,$$

which violates the condition (20). This completes the proof of Theorem 2.4.

3. Oscillation of the problem (1), (3). It is known that the smallest eigenvalue α_0 of the Dirichlet problem

$$\begin{cases} \Delta\omega(x) + \alpha\omega(x) = 0 & \text{in } \Omega, \\ \omega(x) = 0 & \text{on } \partial\Omega, \end{cases}$$

where α is a constant, is positive and the corresponding eigenfunction $\varphi(x)$ is positive in Ω .

Theorem 3.1. *If the differential inequality*

$$(23) \quad V'(t) + \alpha_0 \sum_{j=1}^s A_j(t)V(\rho_j(t)) + \sum_{h=1}^l Q_h(t)V(\sigma_h(t)) \leq 0, \quad t \geq t_1$$

has no eventually positive solutions, then every solution of the problem (1), (3) is oscillatory in G .

Proof. Suppose to the contrary that there is a nonoscillatory solution $u(x, t) = \{u_1(x, t), u_2(x, t), \dots, u_m(x, t)\}^T$ of the problem (1), (3). We assume that $|u_i(x, t)| > 0$ for $t \geq t_0 \geq 0, i \in I_m$. Let $\delta_i = \text{sgn } u_i(x, t), Z_i(x, t) = \delta_i u_i(x, t)$. Then $Z_i(x, t) > 0, (x, t) \in \Omega \times [t_0, \infty), i \in I_m$. From (C3) there exists a number $t_1 \geq t_0$ such that $Z_i(x, t) > 0, Z_k(x, \rho_j(t)) > 0$ and $Z_i(x, \sigma_h(t)) > 0$ in $\Omega \times [t_1, \infty), i, k \in I_m, j \in I_s, h \in I_l$.

Multiplying both sides of (1) by $\varphi(x) > 0$ and integrating with respect to x over the domain Ω , we have

$$\begin{aligned}
 (24) \quad \frac{d}{dt} \int_{\Omega} u_i(x, t) \varphi(x) dx &= a_i(t) \int_{\Omega} \Delta u_i(x, t) \varphi(x) dx \\
 &+ \sum_{k=1}^m \sum_{j=1}^s a_{ikj}(t) \int_{\Omega} \Delta u_k(x, \rho_j(t)) \varphi(x) dx \\
 &- \sum_{k=1}^m \sum_{h=1}^l \int_{\Omega} q_{ikh}(x, t) u_k(x, \sigma_h(t)) \varphi(x) dx, \\
 &t \geq t_1, \quad i \in I_m.
 \end{aligned}$$

Therefore,

$$\begin{aligned}
 (25) \quad \frac{d}{dt} \int_{\Omega} Z_i(x, t) \varphi(x) dx &= a_i(t) \int_{\Omega} \Delta Z_i(x, t) \varphi(x) dx \\
 &+ \sum_{j=1}^s a_{ij}(t) \int_{\Omega} \Delta Z_i(x, \rho_j(t)) \varphi(x) dx \\
 &+ \sum_{\substack{k=1 \\ k \neq i}}^m \sum_{j=1}^s a_{ikj}(t) \int_{\Omega} \Delta Z_k(x, \rho_j(t)) \varphi(x) dx \\
 &- \sum_{h=1}^l \int_{\Omega} q_{iih}(x, t) Z_i(x, \sigma_h(t)) \varphi(x) dx \\
 &- \frac{\delta_i}{\delta_k} \sum_{\substack{k=1 \\ k \neq i}}^m \sum_{h=1}^l \int_{\Omega} q_{ikh}(x, t) Z_k(x, \sigma_h(t)) \varphi(x) dx, \\
 &t \geq t_1, \quad i \in I_m.
 \end{aligned}$$

Green's formula and boundary (3) yield

$$\begin{aligned}
 (26) \quad \int_{\Omega} \Delta Z_i(x, t) \varphi(x) dx &= \int_{\Omega} Z_i(x, t) \Delta \varphi(x) dx \\
 &= -\alpha_0 \int_{\Omega} Z_i(x, t) \varphi(x) dx \leq 0,
 \end{aligned}$$

and

$$\begin{aligned}
 \int_{\Omega} \Delta Z_k(x, \rho_j(t)) \varphi(x) dx &= \int_{\Omega} Z_k(x, \rho_j(t)) \Delta \varphi(x) dx \\
 (27) \qquad \qquad \qquad &= -\alpha_0 \int_{\Omega} Z_k(x, \rho_j(t)) \varphi(x) dx, \\
 &t \geq t_1, \quad i, k \in I_m, \quad j \in I_s.
 \end{aligned}$$

Now from (25), (26) and (27), we have

$$\begin{aligned}
 (28) \qquad \frac{d}{dt} \int_{\Omega} Z_i(x, t) \varphi(x) dx &\leq -\alpha_0 \sum_{j=1}^s a_{ij}(t) \int_{\Omega} Z_i(x, \rho_j(t)) \varphi(x) dx \\
 &+ \alpha_0 \sum_{\substack{k=1 \\ k \neq i}}^m \sum_{j=1}^s |a_{ikj}(t)| \int_{\Omega} Z_k(x, \rho_j(t)) \varphi(x) dx \\
 &- \sum_{h=1}^l q_{iih}(t) \int_{\Omega} Z_i(x, \sigma_h(t)) \varphi(x) dx \\
 &+ \sum_{\substack{k=1 \\ k \neq i}}^m \sum_{h=1}^l \bar{q}_{ikh}(t) \int_{\Omega} Z_k(x, \sigma_h(t)) \varphi(x) dx, \\
 &t \geq t_1, \quad i \in I_m.
 \end{aligned}$$

Setting

$$V_i(t) = \int_{\Omega} Z_i(x, t) \varphi(x) dx, \quad t \geq t_1, i \in I_m,$$

we have

$$\begin{aligned}
 (29) \qquad V_i'(t) + \alpha_0 \sum_{j=1}^s [a_{ij}(t) V_i(\rho_j(t)) - \sum_{\substack{k=1 \\ k \neq i}}^m |a_{ikj}(t)| V_k(\rho_j(t))] \\
 + \sum_{h=1}^l [q_{iih}(t) V_i(\sigma_h(t)) - \sum_{\substack{k=1 \\ k \neq i}}^m \bar{q}_{ikh}(t) V_k(\sigma_h(t))] \leq 0, \\
 t \geq t_1, \quad i \in I_m.
 \end{aligned}$$

Let

$$V(t) = \sum_{i=1}^m V_i(t), t \geq t_1.$$

From (29) we have

$$(30) \quad \begin{aligned} &V'(t) + \alpha_0 \sum_{j=1}^s \left\{ \sum_{i=1}^m \left[a_{ij}(t) V_i(\rho_j(t)) - \sum_{\substack{k=1, k \neq i \\ k=1, k \neq i}}^m |a_{ikj}(t)| V_k(\rho_j(t)) \right] \right\} \\ &+ \sum_{h=1}^l \left\{ \sum_{i=1}^m \left[q_{ih}(t) V_i(\sigma_h(t)) - \sum_{\substack{k=1 \\ k \neq i}}^m \bar{q}_{ikh}(t) V_k(\sigma_h(t)) \right] \right\} \leq 0, \\ &t \geq t_1. \end{aligned}$$

As in the proof of Theorem 2.1, from (30) we obtain

$$V'(t) + \alpha_0 \sum_{j=1}^s A_j(t) V(\rho_j(t)) + \sum_{h=1}^l Q_h(t) V(\sigma_h(t)) \leq 0, \quad t \geq t_1.$$

The above inequality shows that $V(t) = \sum_{i=1}^m V_i(t) > 0$ is an eventually positive solution of the inequality (23), which contradicts the assumption that (23) has no eventually positive solutions. This completes the proof of Theorem 3.1. \square

The proofs of the following theorems are similar to that of Theorem 2.2, Theorem 2.3 and Theorem 2.4.

Theorem 3.2. *If there exists $j_0 \in I_s$ such that $\rho_{j_0}(t) \leq t$, $\rho_{j_0}(t)$ is nondecreasing in $[0, \infty)$ and*

$$(31) \quad \liminf_{t \rightarrow \infty} \alpha_0 \int_{\rho_{j_0}(t)}^t A_{j_0}(s) ds > \frac{1}{e}.$$

Then every solution $u(x, t)$ of the problem (1), (3) is oscillatory in G .

Theorem 3.3. *If there exists $j_0 \in I_s$ such that $\frac{\rho_{j_0}(t)}{L_1} \leq t$, $\rho_{j_0}(t)$ is nondecreasing in $[0, \infty)$ and suppose that when $L_1 < 1$ and*

$0 < \overline{K}_1 \leq 1/e$ the following conditions hold

$$(32) \quad \overline{L}_1 > \frac{\ln \gamma_1 + 1}{\gamma_1} - \frac{1 - \overline{K}_1 - \sqrt{1 - 2\overline{K}_1 - \overline{K}_1^2}}{2},$$

where

$$\overline{K}_1 = \liminf_{t \rightarrow \infty} \alpha_0 \int_{\rho_{j_0}(t)}^t A_{j_0}(s) ds, \quad \overline{L}_1 = \limsup_{t \rightarrow \infty} \alpha_0 \int_{\rho_{j_0}(t)}^t A_{j_0}(s) ds,$$

and γ_1 is the smaller root of the equation

$$\gamma = e^{\overline{K}_1 \gamma};$$

then every solution $u(x, t)$ of the problem (1), (3) is oscillatory in G .

Theorem 3.4. *If there exists $j_0 \in I_s$ such that $\rho_{j_0}(t) \leq t$, $\rho_{j_0}(t)$ is nondecreasing in $[0, \infty)$ and*

$$(33) \quad \limsup_{t \rightarrow \infty} \alpha_0 \int_{\rho_{j_0}(t)}^t A_{j_0}(s) ds > 1,$$

then every solution $u(x, t)$ of the problem (1), (3) is oscillatory in G .

Theorem 3.5. *If the conditions of Theorem 2.2 hold, then every solution $u(x, t)$ of the problem (1), (3) is oscillatory in G .*

Theorem 3.6. *If the conditions of Theorem 2.3 hold, then every solution $u(x, t)$ of the problem (1), (3) is oscillatory in G .*

Theorem 3.7. *If the conditions of Theorem 2.4 hold, then every solution $u(x, t)$ of the problem (1), (3) is oscillatory in G .*

4. Examples.

Example 4.1. Consider the system of parabolic equations

$$(34) \quad \begin{cases} \frac{\partial}{\partial t} u_1(x, t) = \Delta u_1(x, t) + (1 + e^{-t})\Delta u_1(x, t - \frac{\pi}{2}) \\ \qquad \qquad \qquad + e^{-\pi/2}\Delta u_2(x, t - \frac{\pi}{2}) - (1 + e^{-t})u_1(x, t - \pi) \\ \qquad \qquad \qquad - e^{-\pi}u_2(x, t - \pi), \\ \frac{\partial}{\partial t} u_2(x, t) = (1 + e^\pi)\Delta u_2(x, t) + \frac{1}{3}e^{-t}\Delta u_1(x, t - \frac{\pi}{2}) \\ \qquad \qquad \qquad + \frac{4}{3}e^{-\pi/2}\Delta u_2(x, t - \frac{\pi}{2}) - e^{-t}u_1(x, t - \pi) \\ \qquad \qquad \qquad - (1 + e^{-\pi})u_2(x, t - \pi), \quad (x, t) \in (0, \pi) \times [0, \infty), \end{cases}$$

with boundary condition

$$(35) \quad \frac{\partial}{\partial x} u_i(0, t) = \frac{\partial}{\partial x} u_i(\pi, t) = 0, \quad t \geq 0, i = 1, 2.$$

Here $n = 1, m = 2, s = 1, l = 1, a_1(t) = 1, a_{111}(t) = 1 + e^{-t}, a_{121}(t) = e^{-\pi/2}, \rho_1(t) = t - (\pi/2), q_{111}(x, t) = 1 + e^{-t}, q_{121}(x, t) = e^{-\pi}, \sigma_1(t) = t - \pi, a_2(t) = 1 + e^\pi, a_{211}(t) = (1/3)e^{-t}, a_{221} = (4/3)e^{-t}e^{-\pi/2}, q_{211}(x, t) = e^{-t}, q_{221}(x, t) = 1 + e^{-\pi}, \Omega = (0, \pi)$. It is easy to see that the conditions of Theorem 2.2 are verified. Thus all solutions of the problem (34), (35) are oscillatory in $(0, \pi) \times [0, \infty)$. In fact, $u_1(x, t) = \cos x \sin t, u_2(x, t) = -e^{-t} \cos x \sin t$ is such a solution.

Example 4.2. Consider the system of parabolic equations

$$(36) \quad \begin{cases} \frac{\partial}{\partial t} u_1(x, t) = 3\Delta u_1(x, t) + \Delta u_1(x, t - \frac{3\pi}{2}) + \Delta u_2(x, t - \frac{3\pi}{2}) \\ \qquad \qquad \qquad - 4u_1(x, t - \pi) - (-2)u_2(x, t - \pi), \\ \frac{\partial}{\partial t} u_2(x, t) = \frac{9}{2}\Delta u_2(x, t) + \frac{1}{2}\Delta u_1(x, t - \frac{3\pi}{2}) \\ \qquad \qquad \qquad + 2\Delta u_2(x, t - \frac{3\pi}{2}) - 3u_1(x, t - \pi) - 4u_2(x, t - \pi), \\ \qquad \qquad \qquad (x, t) \in (0, \pi) \times [0, \infty), \end{cases}$$

with boundary condition

$$(37) \quad u_i(0, t) = u_i(\pi, t) = 0, \quad t \geq 0, i = 1, 2.$$

It is easy to see that all conditions of Theorem 3.7 are fulfilled. Then every solution of the problem (36), (37) oscillates in $(0, \pi) \times [0, \infty)$. In fact, $u_1(x, t) = \sin x \cos t$, $u_2(x, t) = \sin x \sin t$ is such a solution.

Acknowledgments. The authors thank the referee for his valuable comments on this paper.

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