

ON AN INTEGRAL INEQUALITY FOR DIVERGENCE-FREE FUNCTIONS

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1. **Introduction.** Let D be a bounded, two-dimensional domain with smooth boundary ∂D and $\phi_i(x_1, x_2) = \phi_i(x)$ [$i = 1, 2$] any sufficiently smooth vector-valued function which is defined on D , vanishes on ∂D , and satisfies the divergence-free condition, $\phi_{j,j} = 0$ in D . Here the summation convention is used and a comma denotes differentiation; for example,

$$\phi_{j,j} = \frac{\partial \phi_1}{\partial x_1} + \frac{\partial \phi_2}{\partial x_2}.$$

Of interest in this work is the calculation of a positive constant λ such that

$$(1) \quad \int_D \phi_i \phi_i \, dx \leq \frac{1}{\lambda} \int_D \phi_{i,j} \phi_{i,j} \, dx$$

when D can be enclosed in a wedge of angle π/α , $\alpha > \frac{1}{2}$. Ideally we would like to calculate an optimal value for λ ; however, this does not seem possible and we shall, therefore, sharpen known results.

Inequality (1) has been employed in stability and uniqueness studies for the Navier-Stokes equations (see e.g. Serrin [11]) and in an examination of growth properties of solutions for a model of a dusty gas system (see Crooke [2]), among other applications.

It is generally possible to establish these types of inequalities by considering a corresponding variational problem. For inequality (1) we are interested in the following variational problem:

$$(2) \quad \hat{\lambda} = \inf_{\psi_i \in \Gamma(D)} \frac{\int_D \psi_{i,j} \psi_{i,j} \, dx}{\int_D \psi_i \psi_i \, dx}$$

where $\Gamma(D)$ denotes the class of Dirichlet integrable, vector-valued functions which are defined on D , vanish on ∂D and satisfy $\psi_{j,j} = 0$ in D . Hence, if λ is any lower bound for $\hat{\lambda}$ and ϕ_i any function belonging to $\Gamma(D)$, then

$$\lambda \leq \inf_{\psi_i \in \Gamma(D)} \frac{\int_D \psi_{i,j} \psi_{i,j} \, dx}{\int_D \psi_i \psi_i \, dx} \leq \frac{\int_D \phi_{i,j} \phi_{i,j} \, dx}{\int_D \phi_i \phi_i \, dx},$$

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or

$$\int_D \phi_i \phi_i \, dx \leq \frac{1}{\lambda} \int_D \phi_{i,j} \phi_{i,j} \, dx.$$

We note that if

$$\lambda' = \inf_{\psi_i \in \Gamma'(D)} \frac{\int_D \psi_{i,j} \psi_{i,j} \, dx}{\int_D \psi_i \psi_i \, dx}$$

where $\Gamma'(D)$ denotes the space of Dirichlet integrable, vector-valued functions which are defined on D and vanish on ∂D , then $\lambda' \leq \hat{\lambda}$. Lower bounds for λ' abound in the literature. For example, the well-known Faber-Krahn inequality (see [3], [5]) states $\lambda' \geq [j_0]^2/P^2$ where P is the radius of the circle having the same area as D and j_0 is the first zero of the Bessel function J_0 . Payne and Weinberger [10] have obtained a sharper lower bound for λ' when D lies interior to a wedge of angle π/α , $\alpha \geq 1$. The results of this paper will be applicable to similar domains; however, we shall be interested in lower bounds for $\hat{\lambda}$, not λ' . Serrin [11] and Velte [14] have presented lower bounds for $\hat{\lambda}$ which depend on the geometry of D .

2. An eigenvalue inequality. Suppose D is a two-dimensional, bounded domain which can be enclosed in a wedge of angle π/α , $\alpha > \frac{1}{2}$. That is, if r denotes the distance from the apex of the wedge, which is assumed to be at the origin, then

$$D \subset \{(r, \theta) : \theta \in (0, \pi/\alpha), r \in (0, R)\} = D_\alpha.$$

As can readily be seen by its definition, D_α is the sector of a circle of radius R . Noting that $\hat{\lambda}$ is a monotone function of domain, it is sufficient to consider computing a lower bound for the eigenvalue

$$(3) \quad \tilde{\lambda} = \inf_{\psi_i \in \Gamma(D_\alpha)} \frac{\int_{D_\alpha} \psi_{i,j} \psi_{i,j} \, dx}{\int_{D_\alpha} \psi_i \psi_i \, dx},$$

since $\tilde{\lambda} \leq \hat{\lambda}$.

To compute a lower bound for $\tilde{\lambda}$, we shall use Weinstein's (see [15], [16]) "method of intermediate problems". In order to employ this technique it is necessary to change the form of (3) by introducing a stream-function v such that $\psi_1 = v_{,2}$ and $\psi_2 = -v_{,1}$. It is easily demonstrated that with this definition of $v(x)$ variational problem (3) is transformed into

$$(4) \quad \tilde{\lambda} = \inf_{v \in \Omega(D_\alpha)} \frac{\int_{D_\alpha} (\Delta v)^2 \, dx}{\int_{D_\alpha} (\nabla v)^2 \, dx}$$

where $\Omega(D_\alpha)$ is the space of sufficiently smooth scalar functions which are defined on D_α and which with their normal derivatives vanish on ∂D_α . It might be noted that the positive constant $\tilde{\lambda}$ is the first eigenvalue of the buckling problem for an elastic plate occupying D_α . The corresponding problem for the square was one of the problems originally treated by Weinstein in [15]. Since the normal derivative of v , which we henceforth denote $\partial v/\partial n$, vanishes on ∂D_α , it follows that for any bounded function p defined on ∂D_α we have

$$\int_{\partial D_\alpha} p \frac{\partial v}{\partial n} dS = 0.$$

This leads us to our first intermediate problem:

$$(5) \quad \lambda = \inf_{v \in \Omega'(D_\alpha)} \frac{\int_{D_\alpha} (\Delta v)^2 dx}{\int_{D_\alpha} (\nabla v)^2 dx}$$

where $\Omega'(D_\alpha)$ is the space of sufficiently smooth scalar functions v defined on ∂D_α , satisfying the boundary conditions:

$$(6.a) \quad v = \partial v/\partial n = 0 \quad \text{on } r = R,$$

$$(6.b) \quad v = 0 \quad \text{on } \partial D_\alpha^*,$$

and

$$(6.c) \quad \int_{\partial D_\alpha^*} p \frac{\partial v}{\partial n} dS = 0$$

where ∂D_α^* denotes that portion of ∂D_α for which $\theta = 0, \pi/\alpha$. Using the standard arguments of variational calculus, it follows that $\lambda \leq \tilde{\lambda}$.

The Euler equation and associated boundary conditions for the variational problem (5) can be shown to be:

$$(7.a) \quad \Delta^2 v + \lambda \Delta v = 0 \quad \text{in } D_\alpha,$$

$$(7.b) \quad v = \partial v/\partial n = 0 \quad \text{on } r = R,$$

and

$$(7.c) \quad v = 0, \quad \Delta v = ap \quad \text{on } \partial D_\alpha^*$$

where a is an undetermined constant and $\Delta^2 v = \Delta(\Delta v)$. Let v^j and λ^j ($j = 1, 2, \dots$) denote the eigenfunctions and corresponding eigenvalues of the base problem, i.e., problem (7) with $a = 0$. That is, v^j and λ^j are solutions of

$$\begin{aligned} \Delta^2 v^j + \lambda^j \Delta v^j &= 0 && \text{in } D_\alpha, \\ v^j = \partial v^j / \partial n &= 0 && \text{on } r = R, \end{aligned}$$

and

$$v^j = \Delta(v^j) = 0 \quad \text{on } \partial D_\alpha^*.$$

These eigenfunctions and eigenvalues can be computed explicitly, but as we shall see in the analysis that follows, it is only necessary to explicitly know the first three. They are

$$v^1(r, \theta) = r^\alpha \sin(\alpha \theta) [r^{-\alpha} J_\alpha(\sqrt{\lambda^1} r) - R^{-\alpha} J_\alpha(\sqrt{\lambda^1} R)]$$

and

$$\lambda^1 = \frac{[j_{\alpha+1}^{(1)}]^2}{R^2}$$

$$v^2(r, \theta) = \begin{cases} v_1^2 = r^\alpha \sin(2\alpha \theta) [r^{-2\alpha} J_{2\alpha}(\sqrt{\lambda_1^2} r) - R^{-2\alpha} J_{2\alpha}(\sqrt{\lambda_1^2} R)] \\ \text{or} \\ v_2^2 = r^\alpha \sin(\alpha \theta) [r^{-\alpha} J_\alpha(\sqrt{\lambda_2^2} r) - R^{-\alpha} J_\alpha(\sqrt{\lambda_2^2} R)] \end{cases}$$

and

$$\lambda^2 = \left\{ \lambda_1^2 = \frac{[j_{2\alpha+1}^{(1)}]^2}{R^2} \text{ or } \lambda_2^2 = \frac{[j_{\alpha+1}^{(2)}]^2}{R} \right\},$$

$$v^3(r, \theta) = \begin{cases} v_1^3 = r^\alpha \sin(3\alpha \theta) [r^{-3\alpha} J_{3\alpha}(\sqrt{\lambda_1^3} r) - R^{-3\alpha} J_{3\alpha}(\sqrt{\lambda_1^3} R)] & \text{or} \\ v_2^3 = r^\alpha \sin(2\alpha \theta) [r^{-2\alpha} J_{2\alpha}(\sqrt{\lambda_2^3} r) - R^{-2\alpha} J_{2\alpha}(\sqrt{\lambda_2^3} R)] & \text{or} \\ v_3^3 = r^\alpha \sin(\alpha \theta) [r^{-\alpha} J_\alpha(\sqrt{\lambda_3^3} r) - R^{-\alpha} J_\alpha(\sqrt{\lambda_3^3} R)] & \text{or} \\ v_4^3 = r^\alpha \sin(2\alpha \theta) [r^{-2\alpha} J_{2\alpha}(\sqrt{\lambda_4^3} r) - R^{-2\alpha} J_{2\alpha}(\sqrt{\lambda_4^3} R)] & \text{or} \\ v_5^3 = r^\alpha \sin(\alpha \theta) [r^{-\alpha} J_\alpha(\sqrt{\lambda_5^3} r) - R^{-\alpha} J_\alpha(\sqrt{\lambda_5^3} R)] \end{cases}$$

and

$$\lambda^3 = \left\{ \lambda_1^3 = \frac{[j_{3\alpha+1}^{(1)}]^2}{R^2}, \lambda_2^3 = \frac{[j_{2\alpha+1}^{(2)}]^2}{R^2}, \lambda_3^3 = \frac{[j_{\alpha+1}^{(3)}]^2}{R^2}, \right.$$

$$\left. \lambda_4^3 = \frac{[j_{2\alpha+1}^{(1)}]^2}{R^2} \text{ or } \lambda_5^3 = \frac{[j_{\alpha+1}^{(2)}]^2}{R^2} \right\}.$$

In the above expressions $j_\nu^{(n)}$ denotes the n th zero of the Bessel function $J_\nu(\cdot)$. One should note that the superscripts in v_j^i and λ_j^i are to be interpreted as indices and not as powers.

Expanding $v(r, \theta)$ in a series of the eigenfunctions $v^j(r, \theta)$, we have

$$v(r, \theta) = \sum_{i=1}^{\infty} B(v, v^i) \frac{v^i}{k^i}$$

where we have set $B(v, v^i) = \int_{D_\alpha} v, v^i_j dx$ and $k^i = B(v^i, v^i)$. We now develop an expression for $B(v, v^i)$ in terms of λ, λ^i and

$$\oint_{\partial D_\alpha^*} p \frac{\partial v^i}{\partial n} dS.$$

Integrating by parts and using the boundary conditions for v and v^i , one finds that

$$(8) \quad B(v, v^i) = - \int_{D_\alpha} v(\Delta v^i) dx = - \int_{D_\alpha} v^i(\Delta v) dx.$$

Using Green's first identity and the appropriate boundary conditions for v^i , we obtain

$$(9) \quad \int_{D_\alpha} v^i(\Delta^2 v) dx - \int_{D_\alpha} \Delta v(\Delta v^i) dx = - \oint_{\partial D_\alpha} \Delta v \frac{\partial v^i}{\partial n} dS.$$

Integrating the second term in (9) by parts twice, (9) becomes

$$\int_{D_\alpha} v^i(\Delta^2 v) dx - \int_{D_\alpha} v(\Delta^2 v^i) dx = - \oint_{\partial D_\alpha} \Delta v \frac{\partial v^i}{\partial n} dS.$$

Employing the differential equations satisfied by v and v^i , this identity transforms to

$$-\lambda \int_{D_\alpha} v^i(\Delta v) dx + \lambda^i \int_{D_\alpha} v(\Delta v) dx = - \oint_{\partial D_\alpha^*} \Delta v \frac{\partial v^i}{\partial n} dS.$$

With (8), we have then

$$(\lambda - \lambda^i)B(v, v^i) = - \oint_{\partial D_\alpha^*} \Delta v \frac{\partial v^i}{\partial n} dS = - \oint_{\partial D_\alpha^*} ap \frac{\partial v^i}{\partial n} dS,$$

or

$$B(v, v^i) = \frac{a \oint_{\partial D_\alpha^*} p(\partial v^i/\partial n) dS}{\lambda^i - \lambda}.$$

Our infinite series for $v(r, \theta)$ then becomes

$$v(r, \theta) = \sum_{i=1}^{\infty} \frac{\oint_{\partial D_\alpha^*} p(\partial v^i/\partial n) dS}{\lambda^i - \lambda} \frac{v^i}{k^i}.$$

Since $\oint_{\partial D_\alpha^*} p(\partial v/\partial n) dS$ must vanish, we find that λ must satisfy the expression

$$(10) \quad a \sum_{i=1}^{\infty} \frac{[\oint_{\partial D_\alpha^*} p(\partial v^i/\partial n) dS]^2}{k^i(\lambda^i - \lambda)} = 0.$$

At this point we choose our function $p(r)$ which has been, up to this time, arbitrary. Namely, we set $p(r) = \partial v^1/\partial n$ on ∂D_α^* . With respect to equation (10) we have two cases to consider.

Case I. If $a = 0$, then λ is one of the λ^i 's. Since with the above choice of $p(r)$ we have that

$$\int_{\partial D_\alpha^*} p(r) \frac{\partial v^1}{\partial n} dS \neq 0 \quad \text{and} \quad \int_{\partial D_\alpha^*} p(r) \frac{\partial v_2^2}{\partial n} dS \neq 0,$$

then necessarily $\lambda = \lambda_1^2$.

Case II. Suppose $a \neq 0$. In this case we necessarily have that λ must satisfy

$$(11) \quad \sum_{i=1}^{\infty} \frac{[\oint_{\partial D_\alpha^*} p(\partial v^1/\partial n) dS]^2}{k^i(\lambda^i - \lambda)} = \sum_{i=1}^{\infty} \frac{(c^i)^2}{\lambda^i - \lambda} = 0$$

where we have set

$$c^i = \frac{1}{\sqrt{k^i}} \int_{\partial D_\alpha^*} p \frac{\partial v^i}{\partial n} dS.$$

We now define the auxiliary function ψ such that

$$(12.a) \quad \Delta^2 \psi = 0 \quad \text{in } D_\alpha,$$

$$(12.b) \quad \psi = \frac{\partial \psi}{\partial n} = 0 \quad \text{on } r = R,$$

and

$$(12.c) \quad \psi = 0, \quad \Delta \psi = p \quad \text{on } \partial D_\alpha^*.$$

Using the differential equations for v^i and ψ , together with Green's identity, we find that

$$\begin{aligned} \int_{\partial D_\alpha} p \frac{\partial v^i}{\partial n} dS &= \int_{\partial D_\alpha} \Delta \psi \frac{\partial v^i}{\partial n} dS = \int_{D_\alpha} \psi (\Delta^2 v^i) dx \\ &= -\lambda^i \int_{D_\alpha} \psi \Delta v^i dx = \lambda^i B(v^i, \psi). \end{aligned}$$

Hence, (11) becomes

$$(13) \quad \frac{(c^1)^2}{\lambda - \lambda^1} = \sum_{i=2}^{\infty} \frac{\lambda^i}{\lambda^i - \lambda} \left\{ \frac{\lambda^i}{k^i} [B(v^i, \psi)]^2 \right\}.$$

We now consider two subcases, depending on whether c_2 is zero or not.

Suppose $c_2 = 0$ (which is the case when $v^2 = v_1^2$); then (13) reduces to

$$\frac{(c^1)^2}{\lambda - \lambda^1} = \sum_{i=3}^{\infty} \frac{(\lambda^i)^2}{k^i(\lambda^i - \lambda)} [B(v^i, \psi)]^2.$$

Now either $\lambda \geq \lambda^3$ or $\lambda < \lambda^3$. Since Case I leads to the best possible result, $\lambda = \lambda_1^2$, the only inequality of interest is when $\lambda < \lambda^3$. We then have, noting that for all $i > 3$

$$\lambda^i/(\lambda^i - \lambda) \leq \lambda^3/(\lambda^3 - \lambda),$$

the result

$$\frac{(c^1)^2}{\lambda - \lambda^1} \leq \frac{\lambda^3}{\lambda^3 - \lambda} \sum_{i=3}^{\infty} \frac{\lambda^i}{k^i} [B(v^i, \psi)]^2$$

or

$$\frac{(c^1)^2}{\lambda - \lambda^1} \leq \frac{\lambda^3}{\lambda^3 - \lambda} \left\{ \sum_{i=1}^{\infty} \frac{\lambda^i}{k^i} [B(v^i, \psi)]^2 - \frac{\lambda^1}{k^1} [B(v^1, \psi)]^2 \right\}.$$

One can show by expanding $\psi(r, \theta)$ in a Fourier series,

$$\psi(r, \theta) = \sum_{i=1}^{\infty} B(v^i, \psi) \frac{v^i}{k^i},$$

that

$$\sum_{i=1}^{\infty} \frac{\lambda^i}{k^i} [B(v^i, \psi)]^2 = \int_{D_\alpha} (\Delta\psi)^2 dx.$$

This identity implies that

$$\frac{(c^1)^2}{\lambda - \lambda^1} \leq \frac{\lambda^3}{\lambda^1(\lambda^3 - \lambda^1)} \left\{ \lambda^1 \int_{D_\alpha} (\Delta\psi)^2 dx - (c^1)^2 \right\}.$$

Finally, after considerable algebraic manipulation, one can show that

$$\lambda \geq \lambda^1 [1 + 1/(A - 1)]$$

where

$$A = \frac{\lambda^3 \lambda^1}{(c^1)^2 (\lambda^3 - \lambda^1)} \int_{D_\alpha} (\Delta \psi)^2 dx .$$

This yields a lower bound for λ . However since $\int_{D_\alpha} (\Delta \psi)^2 dx$ is not easily computable, we present two lemmas which afford upper bounds for this quantity in terms of $\oint_{\partial D_\alpha^*} p^2 dS$.

LEMMA 1. *Let ψ satisfy (12). Then*

$$\int_{D_\alpha} (\Delta \psi)^2 dx \leq \gamma^1 \oint_{\partial D_\alpha^*} p^2 dS$$

where γ^1 is a constant which depends on α and D_α and is given by

$$\gamma^1 = \frac{(3)^{3/8}}{(2)^{1/3} \sqrt{\Lambda} \sin(\pi/2\alpha)} .$$

Here Λ is any constant such that

$$\int_{D_\alpha} (\nabla u)^2 dx \leq \frac{1}{\Lambda} \int_{D_\alpha} (\Delta u)^2 dx$$

where u is any sufficiently smooth function which with its normal derivative vanishes on ∂D_α .

PROOF. Integrating by parts twice and using boundary condition (12.c), we find that

$$\int_{D_\alpha} (\Delta \psi)^2 dx = \oint_{\partial D_\alpha^*} p \frac{\partial \psi}{\partial n} dS.$$

An application of the Schwarz inequality yields

$$(14) \quad \left[\int_{D_\alpha} (\Delta \psi)^2 dx \right]^2 \leq \left[\oint_{\partial D_\alpha^*} (p)^2 ds \right] \left[\oint_{\partial D_\alpha^*} \left(\frac{\partial \psi}{\partial n} \right)^2 dS \right] .$$

Let (\bar{x}_1, \bar{x}_2) be an arbitrary point in D and consider

$$(15) \quad \begin{aligned} & \int_{D_\alpha} (x_k - \bar{x}_k) \psi_{,k} \psi_{,ij} dx \\ &= - \int_{D_\alpha} [(x_k - \bar{x}_k) \psi_{,k}]_{,j} \psi_{,j} dx \\ & \quad + \oint_{\partial D_\alpha} (x_k - \bar{x}_k) \psi_{,k} \psi_{,j} n_j dS \end{aligned}$$

where n_j is the j th component of the outward normal vector on ∂D . It can be shown by simple manipulations that (15) collapses to

$$(16) \quad \int_{D_\alpha} (x_k - \bar{x}_k) \psi_{,k} \psi_{,ij} dx = \frac{1}{2} \int_{\partial D_\alpha^*} (x_k - \bar{x}_k) n_k \left(\frac{\partial \psi}{\partial n} \right)^2 dS.$$

We now suppose the point (\bar{x}_1, \bar{x}_2) is chosen to lie on the line $\theta = \pi/2\alpha$. Furthermore, let d be a positive number such that $d \leq 2(x_k - \bar{x}_k)n_k$ for all $x \in \partial D_\alpha^*$. If $q^2 = (x_k - \bar{x}_k)(x_k - \bar{x}_k)$ and $h = (x_k - \bar{x}_k)n_k$, then (16) becomes

$$(17) \quad \int_{\partial D_\alpha^*} h \left(\frac{\partial \psi}{\partial n} \right)^2 dS = 2 \int_{D_\alpha} q \frac{\partial \psi}{\partial q} dx.$$

Employing Schwarz's inequality to (17), we have

$$(18) \quad \left[\int_{\partial D_\alpha^*} h \left(\frac{\partial \psi}{\partial n} \right)^2 dS \right]^2 \leq 4 \left[\int_{D_\alpha} \psi_{,j} \psi_{,j} dx \right] \left[\int_{D_\alpha} q^2 (\psi_{,ij})^2 dx \right].$$

Integrating by parts and employing (12), one calculates:

$$\int_{D_\alpha} q^2 (\psi_{,ij})^2 dx = \int_{\partial D_\alpha^*} q^2 p \frac{\partial \psi}{\partial n} dS - 2 \int_{\partial D_\alpha^*} h \left(\frac{\partial \psi}{\partial n} \right)^2 dS + 4 \int_{D_\alpha} \psi_{,j} \psi_{,j} dx.$$

Returning to inequality (18), we have with the above identity, for all $\beta > 0$,

$$d^2 \left[\int_{\partial D_\alpha^*} \left(\frac{\partial \psi}{\partial n} \right)^2 dS \right]^2 \leq \left[4 \int_{D_\alpha} \psi_{,j} \psi_{,j} dx \right] \left[\frac{1}{2\beta} \int_{\partial D_\alpha^*} \frac{q^4 p^2}{h} dS + \frac{(\beta - 4)}{2} \int_{\partial D_\alpha^*} h \left(\frac{\partial \psi}{\partial n} \right)^2 dS + 4 \int_{D_\alpha} \psi_{,j} \psi_{,j} dx \right].$$

Choosing $\beta = 4$, the above inequality simplifies to

$$\begin{aligned}
 & d^2 \left[\int_{\partial D_\alpha^*} \left(\frac{\partial \psi}{\partial n} \right)^2 dS \right] \\
 & \leq \frac{1}{2\Lambda d} \left[\int_{D_\alpha} (\Delta \psi)^2 dx \right] \left[\int_{\partial D_\alpha^*} q^4 p^2 dS \right] \\
 & \quad + \frac{16}{\Lambda^2} \left[\int_{D_\alpha} (\Delta \psi)^2 dx \right]^2
 \end{aligned}$$

where we have made use of the inequality

$$\int_{D_\alpha} \psi_{,j} \psi_{,j} dx \leq \frac{1}{\Lambda} \int_{D_\alpha} (\psi_{,jj})^2 dx.$$

Using this upper bound for $\oint_{\partial D_\alpha^*} (\partial \psi / \partial n)^2 dS$, inequality (14) becomes

$$\begin{aligned}
 & \left[\int_{D_\alpha} (\Delta \psi)^2 dx \right]^3 \\
 & \leq \left[\int_{\partial D_\alpha^*} p^2 dS \right]^2 \left[\frac{1}{2\Lambda d^3} \int_{\partial D_\alpha^*} q^4 p^2 dS \right. \\
 & \quad \left. + \frac{16}{\Lambda^2 d^2} \int_{D_\alpha} (\Delta \psi)^2 dx \right].
 \end{aligned}$$

Using a form of the arithmetic-geometric mean inequality, we have for all $\sigma > 0$,

$$\begin{aligned}
 & \left[\int_{D_\alpha} (\Delta \psi)^2 dx \right]^3 \\
 & \leq \frac{3\sigma^2}{(3\sigma^2 - 1)} \left[\frac{d}{2\Lambda [\sin(\pi/2\alpha)]^4} + \frac{128\sigma}{3\Lambda^3 d^3} \right] \\
 & \quad \cdot \left[\int_{\partial D_\alpha^*} p^2 dS \right]^3
 \end{aligned}$$

where we have made use of the fact that

$$\sup_{D_\alpha} (q) = \frac{d}{\sin(\pi/2\alpha)}.$$

Recalling that the two constants d and σ are still at our disposal, we optimize them by the choices

1. $d = 4(\sigma)^{1/4} \sin(\pi/2\alpha) / \sqrt{\Lambda}$,
2. $\sigma = \sqrt{3}$.

This completes the proof of Lemma 1.

We remark that the upper bound for $\int_{D_\alpha} (\Delta\psi)^2 dx$ presented in Lemma 1 deteriorates as α becomes large. For larger α we present the following lemma.

LEMMA 2. *If ψ is a sufficiently smooth function which satisfies (12), then for $\alpha > 1$ we have*

$$\int_{D_\alpha} (\Delta\psi)^2 dx \leq \gamma^2 \int_{\partial D_\alpha^*} p^2 dS$$

where $\gamma^2 = R \sin(\pi/\alpha)/2$.

PROOF. We define the auxiliary function ϕ such that

(19.a) $\Delta^2\phi = 0$ in D_α

(19.b) $\phi = \Delta\phi = 0$ on $r = R$,

and

(19.c) $\phi = 0, \quad \Delta\phi = p$ on ∂D_α^* .

With the above definition of ϕ it is not difficult to show that

$$\int_{D_\alpha} (\Delta\psi)^2 dx \leq \int_{D_\alpha} (\Delta\phi)^2 dx.$$

It can be shown (see Payne [9]) that if $h(x) = h(x_1, x_2)$ is a harmonic function on a bounded domain D whose boundary ∂D has everywhere nonnegative average curvature and if ρ denotes the strip of minimum width that encloses D , then

$$\int_D |h|^q dx \leq \frac{\rho}{2} \int_{\partial D} |h|^q dS, \quad q \geq 1.$$

Since $\Delta\phi$ is a harmonic function in D_α , we have for $q = 2$

$$\int_{D_\alpha} (\Delta\phi)^2 dx \leq \frac{\rho}{2} \int_{\partial D_\alpha} (\Delta\phi)^2 dS.$$

However, $\Delta\phi = p$ on ∂D_α^* and zero on the rest of ∂D ; therefore, since $\rho = R \sin(\pi/\alpha)$, $\alpha > 1$, we conclude that

$$\int_{D_\alpha} (\Delta\phi)^2 dx \leq \frac{R \sin(\pi/\alpha)}{2} \int_{\partial D_\alpha^*} p^2 dS.$$

This completes the proof of Lemma 2.

We remark that it is possible to improve Lemma 2 for specific values of α . In particular, Payne [9] has shown that

$$\int_D |h|^q dx \leq \frac{\sigma_M}{2} \int_{\partial D} |h|^q dS$$

where σ_M is the maximum stress for the torsion problem on D . Saint-Venant (see Timoshenko [12]) has computed σ_M for the domain D_α when $\alpha = 1, 3/2, 3$. In particular, he showed that $\sigma_M = (0.849)R$ when $\alpha = 1$; $\sigma_M = (0.652)R$ when $\alpha = 3/2$; and $\sigma_M = (0.490)R$ when $\alpha = 3$. However, these numbers yield only marginal improvements over the results of Lemma 2.

In comparing the upper bounds for $\int_{D_\alpha} (\Delta\psi)^2 dx$ afforded by Lemmas 1 and 2, we find that if $\gamma = \min[\gamma^1, \gamma^2]$, then $\gamma = \gamma^1$ for $\alpha = 1, 2, 3, 4$ and $\gamma = \gamma^2$ for $\alpha > 4$.

Finally, with the upper bounds for $\int_{D_\alpha} (\Delta\psi)^2 dx$ we obtain the lower bound for λ in the case when $a \neq 0$ and $c_2 = 0$:

$$\lambda \geq \lambda^1 \{1 + 1/(A - 1)\}$$

where

$$A = \frac{\lambda^3 \lambda^1 \gamma}{(c^1)^2 (\lambda^3 - \lambda^1)} \int_{\partial D_\alpha^*} p^2 dS$$

with the understanding that if $\alpha \leq 1$, then $\gamma = \gamma^1$. With our choice of p , one can show (see Luke [6], Abramowitz and Stegun [1], and Tranter [13]) that

$$\begin{aligned} \int_{\partial D_\alpha^*} p(r) \frac{\partial v^1}{\partial n} dS &= \int_{\partial D_\alpha^*} p^2 dS = R^{-1} J_\alpha^2(j_{\alpha+1}^{(1)}) \\ &\cdot \left\{ \frac{4\alpha^2}{4\alpha^2 - 1} [(j_{\alpha+1}^{(1)})^2 + \alpha + \frac{1}{2}] \right. \\ &\quad \left. - \frac{4\alpha^2}{2\alpha - 1} \left[1 + \frac{2^{\alpha-1} \sqrt{\pi} \Gamma(\alpha + \frac{1}{2})}{(j_{\alpha+1}^{(1)})^{\alpha-2}} \right] \right. \\ &\quad \left. \cdot \left(H_{\alpha+1}(j_{\alpha+1}^{(1)}) - \frac{2\alpha}{j_{\alpha+1}^{(1)}} H_\alpha(j_{\alpha+1}^{(1)}) \right) \right] + \frac{2\alpha^2}{2\alpha - 1} \left. \right\} \end{aligned}$$

and

$$k^1 = \frac{\pi [j_{\alpha+1}^{(1)}]^2}{4\alpha} J_\alpha(j_{\alpha+1}^{(1)}),$$

where here $\Gamma(\cdot)$ is the gamma function and $H_\nu(\cdot)$ denotes the Struve function of order ν . Lastly, since $\partial v_2^3/\partial n$ and $\partial v_4^3/\partial n$ are orthogonal to $p(r)$ on ∂D_α^* , and $\lambda_5^3 \leq \lambda_3^3$, we conclude that $\lambda^3 = \min[\lambda_1^3, \lambda_5^3]$.

The subcase when $c_2 \neq 0$ (which is the situation when $v^2 = v_2^2$ and $\lambda^2 = \lambda_2^2$) still remains. Using the same type of analysis as in the subcase when $c_2 = 0$, one can show that

$$\lambda \geq \lambda^1 [1 + 1/(B - 1)]$$

where

$$B = \frac{\lambda^2 \lambda^1 \gamma}{(c^1)^2 (\lambda^2 - \lambda^1)} \int_{\partial D_\alpha^*} p^2 dS, \quad \lambda^2 = \lambda_2^2.$$

Therefore, in any case or subcase we have

$$(20) \quad \lambda \geq R^{-2} \min \{ [j_{2\alpha+1}^{(1)}]^2, [j_{\alpha+1}^{(1)}]^2 [1 + 1/(A - 1)], [j_{\alpha+1}^{(1)}]^2 [1 + 1/(B - 1)] \}.$$

Putting this eigenvalue inequality in the context of our integral inequality, we have shown:

THEOREM 1. *Let ϕ_i ($i = 1, 2$) be any sufficiently smooth, vector-valued function which is defined on a two-dimensional domain D , which can be enclosed in a wedge of angle $\pi\alpha$, $\alpha > \frac{1}{2}$, and side-length R . If in addition ϕ_i vanishes on the boundary of D and satisfies the divergence-free condition $\phi_{i,j} = 0$ in D , then*

$$\int_D \phi_i \phi_i dx \leq \frac{1}{\lambda} \int_D \phi_{i,j} \phi_{i,j} dx$$

where

$$\lambda = R^{-2} \min \{ [j_{2\alpha+1}^{(1)}]^2, [j_{\alpha+1}^{(1)}]^2 [1 + 1/(A - 1)], [j_{\alpha+1}^{(1)}]^2 [1 + 1/(B - 1)] \}.$$

3. Conclusion. Velte [14] has shown that $\lambda = \Lambda^1$ where Λ^1 is the first eigenvalue for the clamped plate problem on a two-dimensional, bounded domain D . Furthermore, Payne and Weinberger (see Payne [8]) have proven that $\Lambda^1 \geq \bar{\lambda}^2$ (an inequality conjectured by Weinstein [15]) where $\bar{\lambda}^2$ is the second eigenvalue for the fixed membrane problem on D . Hence, applying these two results to our wedge domain D_α , the literature affords the lower bound for λ :

$$(21) \quad \lambda \geq \bar{\lambda}^2 = R^{-2} \min \{ [j_{2\alpha}^{(1)}]^2, [j_\alpha^{(2)}]^2 \}.$$

For comparison purposes the lower bounds provided by the Weinstein-Velte result, (21), and our result, (20), have been computed for $\alpha = 1, 2, 3, 4$. This juxtaposition is presented in the following table where we have assumed for the sake of simplicity that $R = 1$.

α	Value of $\lambda_{WV} = \min\{[j_{\alpha}^{(2)}]^2, [j_{2\alpha}^{(1)}]^2\}$	$\lambda_C = \min\{[j_{2\alpha+1}^{(1)}]^2,$
		$[j_{\alpha+1}^{(1)}]^2[1 + 1/(A - 1)],$ $[j_{\alpha+1}^{(1)}]^2[1 + 1/(B - 1)]\}$
1	$[j_2^{(1)}]^2 = 26.37$	$1.3[j_2^{(1)}]^2 = 35.29$
2	$[j_4^{(1)}]^2 = 57.58$	$1.7[j_3^{(1)}]^2 = 70.77$
3	$[j_3^{(2)}]^2 = 95.27$	$2.1[j_4^{(1)}]^2 = 122.32$
4	$[j_4^{(2)}]^2 = 122.42$	$2.2[j_5^{(1)}]^2 = 168.68$

In the above calculations we have let $\Lambda = \min\{[j_{\alpha}^{(2)}]^2, [j_{2\alpha}^{(1)}]^2\}$ and the values of the various Struve functions have been taken from [4]. Calculations of λ_C and λ_{WV} when $\alpha > 4$ seem to indicate that

$$\lambda_C > \frac{[j_{\alpha+1}^{(2)}]^2}{R^2} \cong \frac{[j_{\alpha}^{(2)}]^2}{R^2} = \lambda_{WV}.$$

Finally, to show how our lower bound is sensitive to the positioning of the origin, let D be a right isosceles triangular region with equal sides of unit length. If the origin is taken at the midpoint of the hypotenuse, then we obtain from (20) with $\alpha = 1$,

$$\lambda \cong 70.58.$$

Placing the origin at the right-angled corner, we have with $\alpha = 2$,

$$\lambda \cong 70.77.$$

Finally, if we choose the origin at once of the acute-angled corners and letting $\alpha = 4$ in (20), we find

$$\lambda \cong 84.34.$$

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